

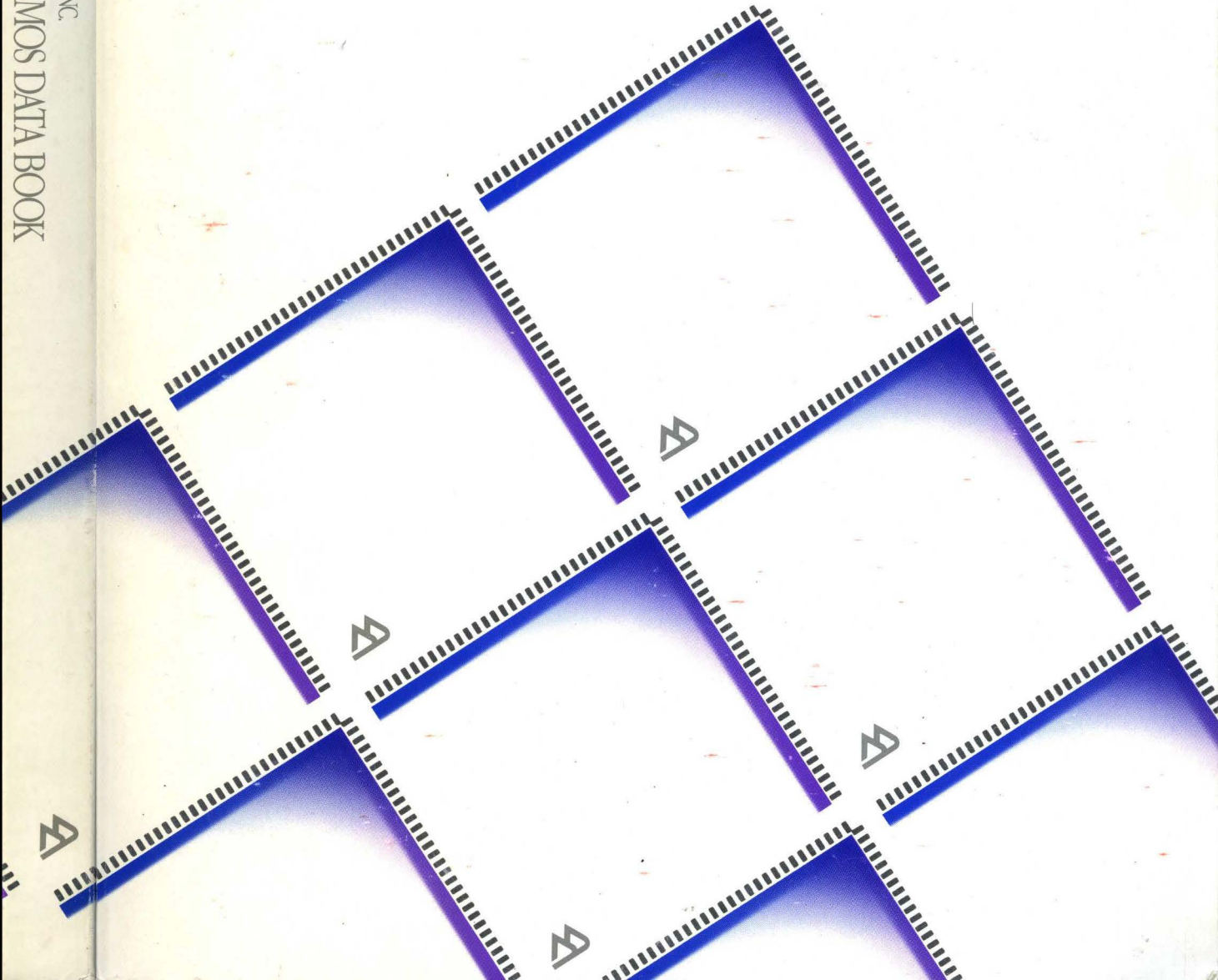
1988/1989 CMOS  
DATA BOOK

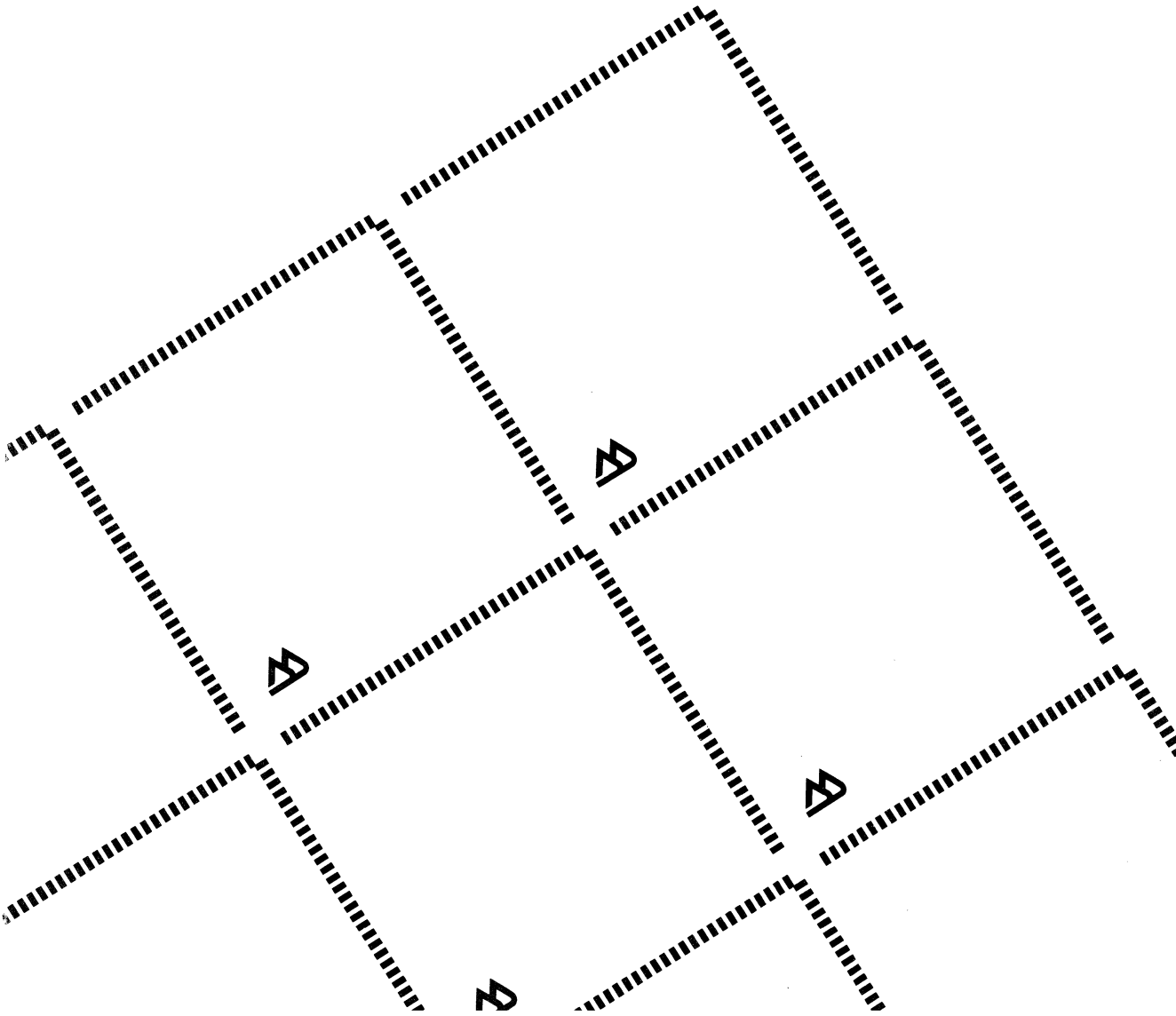
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SMOS SYSTEMS, INC.

1988/1989 CMOS DATA BOOK







## High-Performance CMOS Products for the Low-Power CMOS System

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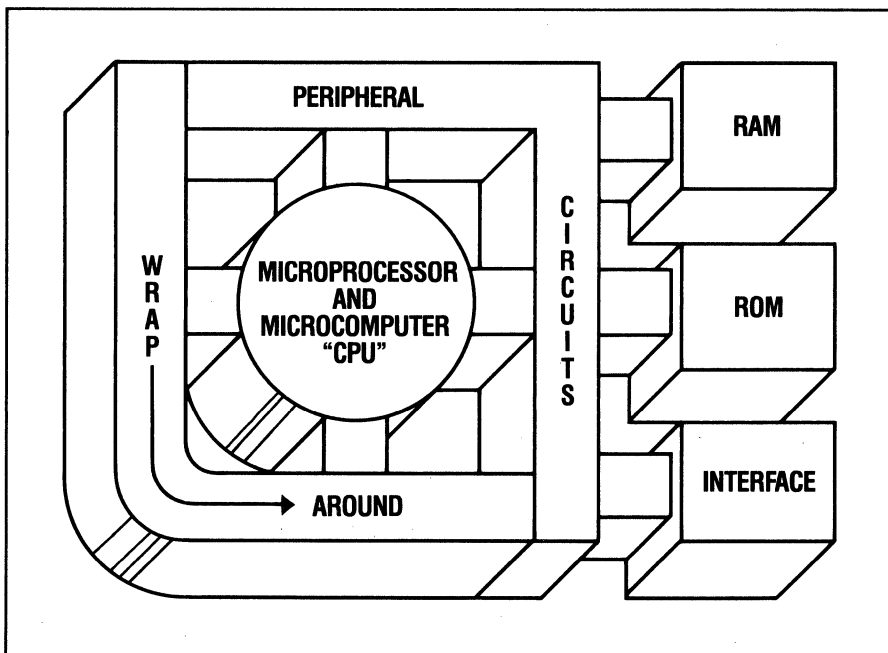
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**S-MOS takes a system approach to CMOS technology, providing the building blocks for a 100% CMOS system.**



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# 1988/1989 CMOS DATA BOOK

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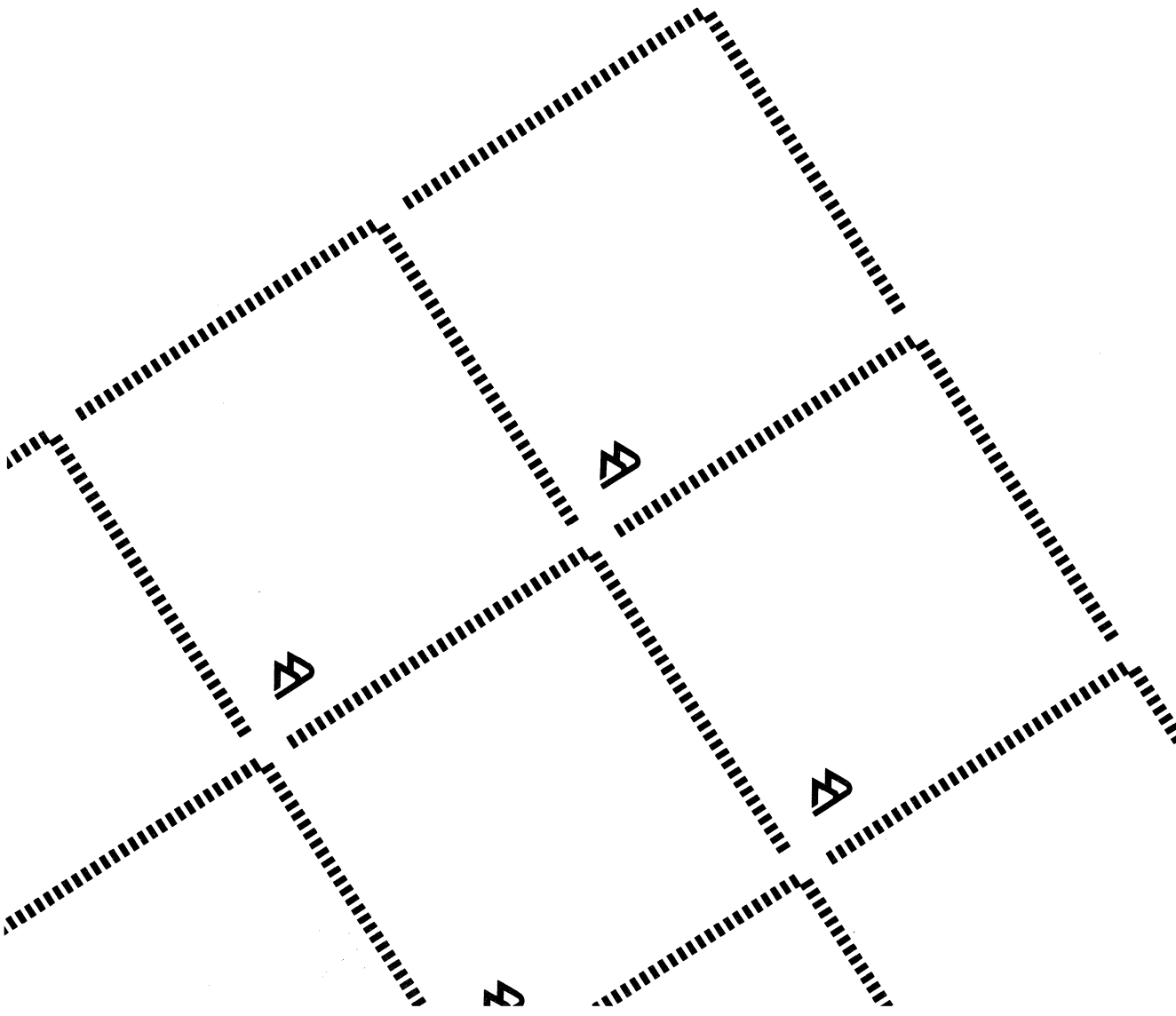
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I. APPLICATION  
INFORMATION

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# 1. OUTLINE OF PRODUCTS

## 1.1 Product Code

The name assigned to each product is coded to indicate its function and package type.

Example : SRM2016C00

S    R M    2 0 1 6    C    0 0

S-MOS SYSTEMS, INC.

Abbreviation of Function

(RM means RAM)

(Please refer to Item 1.2)

Product Number

Package Code :

C : Plastic DIP

D : Die Form (Chip)

F : Plastic QFP

L : Ceramic QFP

H : CERDIP, Ceramic DIP

M : Plastic SOP

J : PLCC, SOJ

G : Plastic PGA

P : Ceramic PGA

S : Plastic Shrink DIP

N : Plastic Skinny DIP

Y : SOT

Sub-Code :

The Sub-Code can be used in any of three different ways :

- (a) As the User Code for Semi-Custom LSIs
- (b) As a Number to Distinguish Between Different Versions of the Same Product [i. e. 12, 15, or 20 to represent 120, 150 and 200 ns respectively] .
- (c) Revision of Product Features

## 1.2 S-MOS Product Prefix Guide

### 1.2.1 Standard & Semi Custom CMOS LSIs for Industry

— Gate Array	— Logic Array	.....	SLA Series
— Standard Cell	— Standard Cell	.....	SSC Series
— Static RAM	— Random Access Memory	.....	SRM Series
— Mask ROM	— Mask Programmed Memory	.....	SMM Series
— Single-chip Microcomputer	— Microcomputer, CPU & Peripheral	.....	SMC Series
— Microprocessor			
— Peripheral			
— LCD Driver	— Electric Driver	.....	SED Series
— Thermal Head Driver			
— VFD/PDP Driver			
— Control LSI of Equipment			
— Converter IC	— Converter IC	.....	SCI Series
— Telecommunication LSIs	— Telecommunications	.....	STC Series
— Image Sensor	— Sensor	.....	SEA Series
— Hybrid IC	— Hybrid IC	.....	SHB Series
— Module IC	— Module	.....	SEK Series

### 1.2.2 Standard CMOS LSI for Consumers

— IC for Watch and Clock	— Time Piece	.....	STP Series
— Single-chip Microcomputer	— Microcomputer	.....	SMC Series
— Melody IC	— Melody	.....	SVM Series

### 1.2.3 Custom CMOS LSI

— Low Voltage Operation IC	— Device for Battery Operation
— CMOS Linear IC	— A/D • D/A Converter, PLL, VFO, SCF, etc.
— High Voltage Operation IC	— VFD/PDP Driver etc.
— High Density Mounted IC	— Hybrid LSI etc.

---

## 2. SPECIFICATIONS AND CHARACTERISTICS

### 2.1 Electrical Characteristics

To fully utilize the CMOS IC it is important to understand the circuit, its characteristics and its specifications. This chapter discusses the Absolute Maximum Ratings, the Recommended Operating Conditions and the Electrical Characteristics of CMOS integrated circuits.

Please note that the voltage value is based on a high level power supply ( $V_{DD}$ ) or on a low level power supply ( $V_{SS}$ ).

#### 2.1.1 Absolute Maximum Ratings

The Absolute Maximum Ratings of a specification are the highest levels at which the circuit will safely operate. Exceeding this level may result in damage to, or destruction of, the circuit. It is, therefore, necessary to monitor such things as supply voltage, input voltage and the ambient temperature.

(1) Operating Voltage

This is the maximum voltage allowed at the power supply terminals. It is important not to let the voltage exceed the specification, not only in the stationary state, but also in the transient state, during power supply turn on, and includes noise on the power supply line. When the voltage exceeds the specification, it may cause some damage to the IC and may adversely effect its reliability.

(2) Input Voltage

This is the maximum voltage allowed into the input terminal. When voltage exceeding the specification is applied, the IC may lose functions because of damage to the input protection resistors or diodes.

(3) Output Current

This is the maximum value of current flow to or from the output. Generally, this is not specified for devices which have small output capacity. This value is provided for ICs, such as drivers which requires a large amount of current.

(4) Power Dissipation

This value shows the allowable dissipation for the device. It depends on the thermal characteristics of its package. For devices which must supply large amounts of output, this specifies the limitation of the output current.

(5) Operating Temperature

The ambient temperature range at which the IC will function reliably.

(6) Storage Temperature

The range of storage temperatures when no voltage is being applied on the IC. This is a very important factor, especially during air transportation.

(7) Soldering Temperature and Time

Maximum temperature and time allowed for soldering.

## 2.1.2 Recommended Operating Conditions

The Recommended Operating Conditions, such as supply voltage, input conditions, and external components, are the conditions necessary for the IC to function properly to meet the electrical characteristics. The operating conditions may be in the same column as the electrical characteristics.

## 2.1.3 Electrical Characteristics

AC and DC electrical characteristics are provided for each input pin and power supply pin. These characteristics are measured at either the ambient temperature specified or in the range of the operating temperatures specified under the worst conditions.

## 2.2 Symbol Definitions

SYMBOLS	PARAMETERS	EXPLANATION
$C_D$	Drain Capacitance	Static capacitance between output terminal and power supply terminal on the oscillation circuit.
$C_G$	Gate Capacitance	Static capacitance between input terminal and power supply terminal on the oscillation circuit.
$C_I$	Input Capacitance	Static capacitance between the input terminal and the power supply terminal.
$C_{I/O}$	Input/Output Capacitance	Static capacitance between the I/O terminal and the power supply terminal.
$C_L$	Loading Capacitance	Loading static capacitance for the external components
$C_O$	Output Capacitance	Static capacitance between the output terminal and the power supply terminal
$f_{XXX}$	XXX Frequency	XXX indicates either the function or the terminal name
$f_{max}$	Maximum Clock Frequency	Maximum Frequency input to the IC from an external pin
$f_{CLK}$	Clock Frequency	Clock Frequency input to the IC from an external pin
$f_{osc}$	Oscillation Frequency	Oscillation Frequency
H	High level	Logical "H" level
$I_{DD}$	( $V_{DD}$ ) Supply Current	Supply current flows into the IC from the $V_{DD}$ external terminal
$I_{DDA}$	Average Operating Current	Average supply current flows into the IC from the $V_{DD}$ external terminal
$I_{DDO}$	Operating Supply Current	$V_{DD}$ supply current while operating
$I_{DDs}$	Standby Supply Current	$V_{DD}$ supply current while standby
$I_I$	Input Current	Current which flows to the input terminal
$I_{LI}$	Input Leakage Current	Leakage current which flows to the input terminal
$I_{IH}$	High Level Input Current	The input current at the "H" level input
$I_{IL}$	Low Level Input Current	The input current at the "L" level input
$I_O$	Output Current	Current which flows through the output terminal
$I_{OH}$	High Level Output Current	Output current when the output terminal voltage is $V_{OH}$
$I_{OL}$	Low Level Output Current	Output current when the output terminal voltage is $V_{OL}$
$I_{LO}$	Output Leakage Current	Leak current flowed when the power voltage is applied to the output terminal when in the 'off (high impedance)' condition
$I_{SS}$	( $V_{SS}$ ) Supply Current	Current flowed out of the $V_{SS}$ terminal
L	Low Level	Logical "L" level
$P_D$	Power Dissipation	Allowable consumption of the electric power
$R_I$	Input Resistance	Built-in resistance for pulling up and pulling down the input
$R_L$	Loading Resistance	Loading resistance for the external components
$T_a$	Ambient Temperature	Ambient temperature of the IC
$T_j$	Junction Temperature	Junction temperature of the IC
$T_{opr}$	Operating Temperature	Surrounding temperature of the IC in operation
$T_{stg}$	Storage Temperature	Temperature of storage area the IC
$T_{sol}$	Soldering Temperature and Time	Soldering temperature and time

## 2.2 Symbol Definitions (cont.)

SYMBOLS	PARAMETERS	EXPLANATION
V <sub>DD</sub>	(V <sub>DD</sub> ) Supply Voltage	Supply voltage or the operating voltage applied to the V <sub>DD</sub> terminal
V <sub>I</sub>	Input Voltage	Voltage applied to the input terminal
V <sub>I/O</sub>	Input/Output Voltage	Voltage applied to the I/O terminal
V <sub>IH</sub>	High Level Input Voltage	Input voltage which can be judged as "H" level
V <sub>IL</sub>	Low Level Input Voltage	Input voltage which can be judged as "L" Level
V <sub>O</sub>	Output Voltage	Voltage generated from or applied to the output terminal
V <sub>OH</sub>	High Level Output Voltage	Voltage at the "H" level output
V <sub>OL</sub>	Low Level Output Voltage	Voltage at the "L" level output
V <sub>rip</sub>	Ripple Voltage	Ripple voltage Amplitude
V <sub>SS</sub>	(V <sub>SS</sub> ) Supply Voltage	Supply voltage applied to the V <sub>SS</sub> terminal
V <sub>SSn</sub>	V <sub>SSn</sub> Supply Voltage	N times pressurized power supply terminal or its voltage level
V <sub>STA</sub>	Oscillation Start Voltage	Voltage for automatic starting
V <sub>STP</sub>	Oscillation Stop Voltage	Voltage when oscillation stops
—	"H", "L" or High Impedance	Unfixed or unprovided level or high impedance
X	"H" or "L"	Unfixed or unprovided level
Z	High Impedance	High impedance condition in three states
t <sub>a</sub>	Access Time	Time between the input of prescription and the output of the valid data
t <sub>ACC</sub>	Address Access Time	Time required for obtaining the output of valid data after the address is given
t <sub>ACE</sub>	Chip Enable Access Time	Time required for obtaining the output of the valid data after the chip enable signal is given
t <sub>ACS</sub>	Chip Select Access Time	Time required for obtaining the output of the valid data after chip select signal is given
t <sub>c</sub>	Cycle Time	Time from the start point of a complete operation to the start point of the next operation
t <sub>RC</sub>	Read Cycle Time	Time required for one read cycle
t <sub>WC</sub>	Write Cycle Time	Time required for one write cycle
t <sub>f</sub>	Fall Time	Time required for the signal changed from "H" to "L"
t <sub>h</sub>	Hold Time	Time required for the synchronous input to be held stable after the active clock edge
t <sub>DH</sub>	Data Hold Time	Time required for the data input to be held stable after the active clock edge
t <sub>AH</sub>	Address Hold Time	Time required for the address input to be held stable after the active clock edge
t <sub>OE</sub>	Output Enable Delay Time	Time required for obtaining a valid output data after the output enable signal is given
t <sub>OH</sub>	Output Hold Time	Time required for the output data to be held stable after the active clock edge
t <sub>pd</sub>	Propagation Delay Time	Delay time between the active clock edge and the output change
t <sub>pHL</sub>	Low Level Propagation Time	Delay time between the active clock edge and the output change from High to Low
t <sub>pLH</sub>	High Level Propagation Time	Delay time between the active clock edge and the output change from Low to High
t <sub>r</sub>	Rise Time	Time for changing the signal from Low to High
t <sub>su</sub>	Set-up Time	Time required for the synchronous input remained stable before the next clock edge
t <sub>AS</sub>	Address Set-up Time	Time required for the address input remained stable before the next clock edge
t <sub>DS</sub>	Data Set-up Time	Time required for the data input remained stable before the next clock edge
t <sub>PW</sub>	Pulse Width	Pulse width
t <sub>RP</sub>	Read Pulse Width	Pulse width of the read signal
t <sub>WP</sub>	Write Pulse Width	Pulse width of the write signal
t <sub>WR</sub>	Write Recovery Time	Same as the address hold time t <sub>AH</sub>

### 3. QUALITY ASSURANCE

S-MOS Systems, Inc. supported by the foundation of results acquired through experience in the adoption of low-power CMOS LSI for SEIKO quartz watches, has been providing highly reliable products that have set new standards in the industry.

Today extremely high reliability is demanded of our customers' products. In step with this trend, extremely high reliability is demanded of semiconductor components.

To meet this demand in the market, we utilize a product quality assurance program which guarantees the highest quality in our products.

Our quality assurance program is as follows:

#### 3.1 Quality Assurance System for Development of New Products

Our quality assurance efforts begin with a market survey to determine the user's specific needs. After the survey is completed, an analysis is made. Based on this analysis, an initial design is made. Next the initial design goes through prototype production and quality evaluation stages. Once these steps are completed, a new product, made according to the user's specifications is created. Fig. 3-1 shows the typical stages of new product development from initial planning to commercial production.

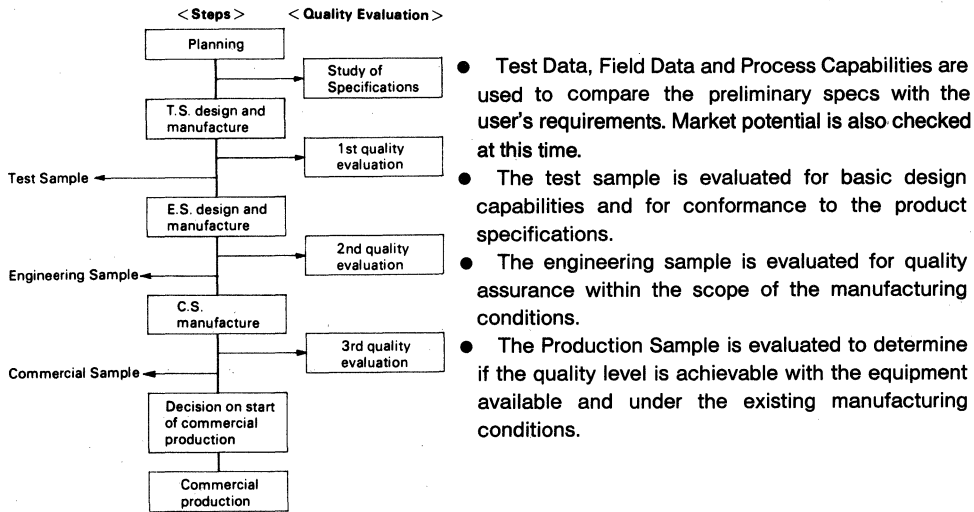


Fig. 3-1 New Product Development Flow

### **3.1.1 Design**

Market surveys are done so the designers know the exact specifications required by the user. Based on the information received, designs for the projected product are made. A "reliability" design is made using the data from reliability tests, field quality studies, past problems and available quality or reliability related information. Design staffs are given the purpose, environment and other factors relating to the application of a product to aid in its design.

### **3.1.2 Quality Evaluation**

The quality evaluation is in two parts, the design evaluation and the reliability evaluation. The design evaluation determines if the target functions and performance level have been reached. The reliability evaluation verifies that long term quality is assured.

The reliability evaluation is done based on the particular objectives of the product. The evaluation is carried out under pre-established guidelines. It is performed according to EIAJ-IC-121 (Electronics Industries Association) standards and with MIL-STD-750B/883C and JIS-C7021 (Japanese Industrial Standards) where applicable. The application, environment and uniqueness of the manufacturing process are also taken into consideration.

### **3.1.3 Decision to Start Commercial Production**

The decision is made whether or not to start commercial production after the sample or prototype production and quality evaluation are completed. This decision is based upon production capabilities, data verification on yield, reliability test results and the user's evaluation of the engineering sample.

## **3.2 Quality Assurance Systems for Commercial Production**

Quality and reliability are assured by design checks in the Engineering and Manufacturing Departments and with verification of the finished product. Once in commercial production, quality control checks are made at various stages. Quality control begins at the assembly line. Inspections follow during the intermediate and final processes, ending with the shipping inspection. A quality assurance flow chart is shown in Fig. 3-2.

### **3.2.1 Manufacturing Environment Control**

Due to the sensitive nature of semiconductor devices, extreme care must be used during the manufacturing process. The manufacturing is done in a "clean room" where the temperature, humidity and dust are carefully monitored and controlled.

### **3.2.2 Control of Manufacturing and Measuring Equipment**

Important elements of building reliability into a product are maintaining and controlling the manufacturing and measuring equipment. This equipment is used to monitor and control line conditions and/or to do intermediate inspections. With the evolution of devices to higher integrations and improved reliability, the production process must be controlled at a higher level. Routine checks and periodic inspections insure that we achieve these high standards.

### **3.2.3 Process Inspection**

Quality Assurance is based on the theory that quality is built into the product. The inspection at each processing stage assures high quality. The inspection results are fed back into each process in order to stabilize the entire operation. These inspections also prevent defective parts from moving to the next process stage.

Fig. 3-3 and 3-4 show typical wafer process and assembly flow.

### **3.2.4 Shipping Inspection**

The final inspection is performed when the product is ready to ship to reverify that the product meets our high standards. The electrical characteristics are 100% tested, and the environmental characteristics are tested on a lot sample basis. External visual inspection is also performed.

The shipping inspection is performed according to the category of the product. An example of the inspection process is shown in Table 3-1.



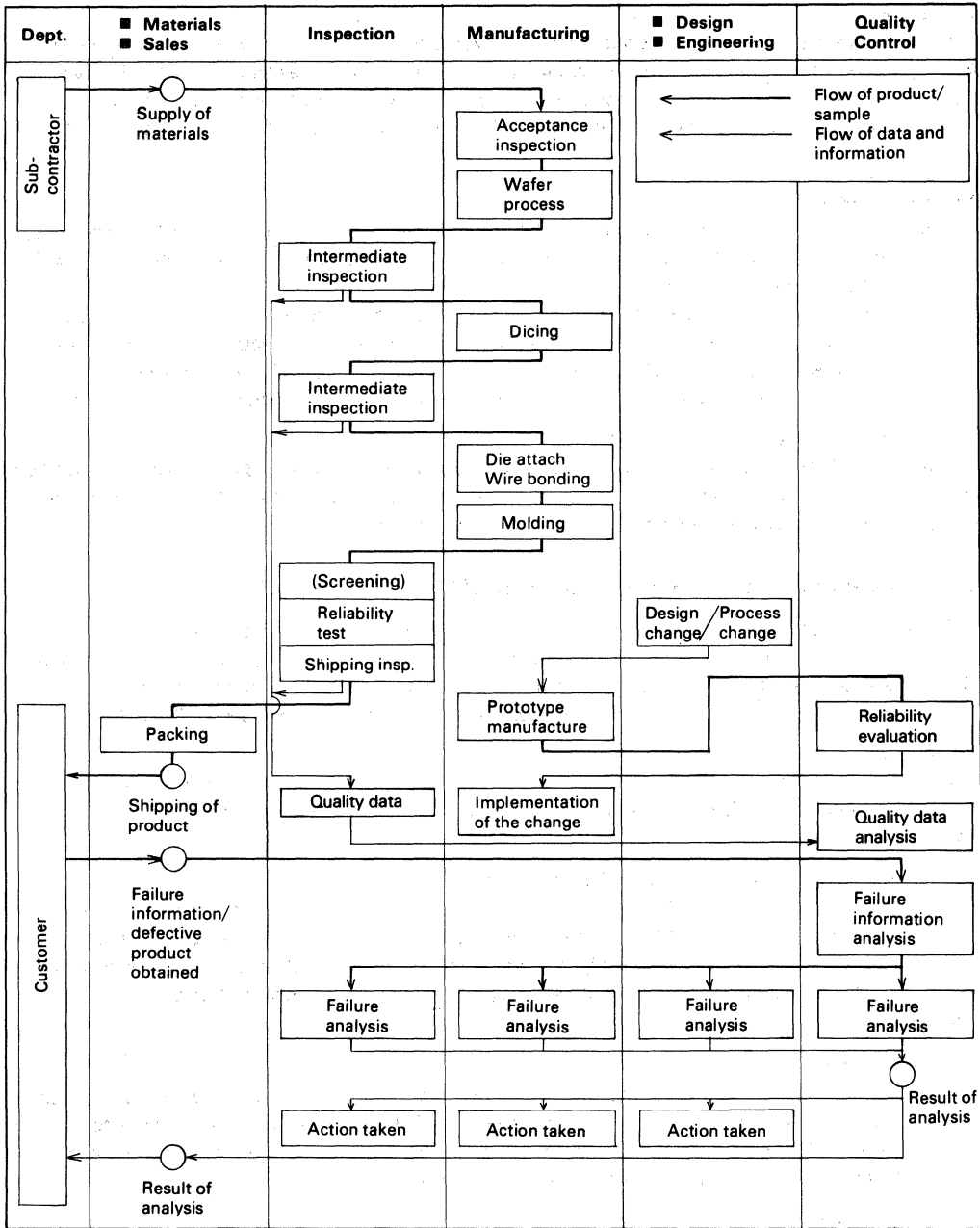
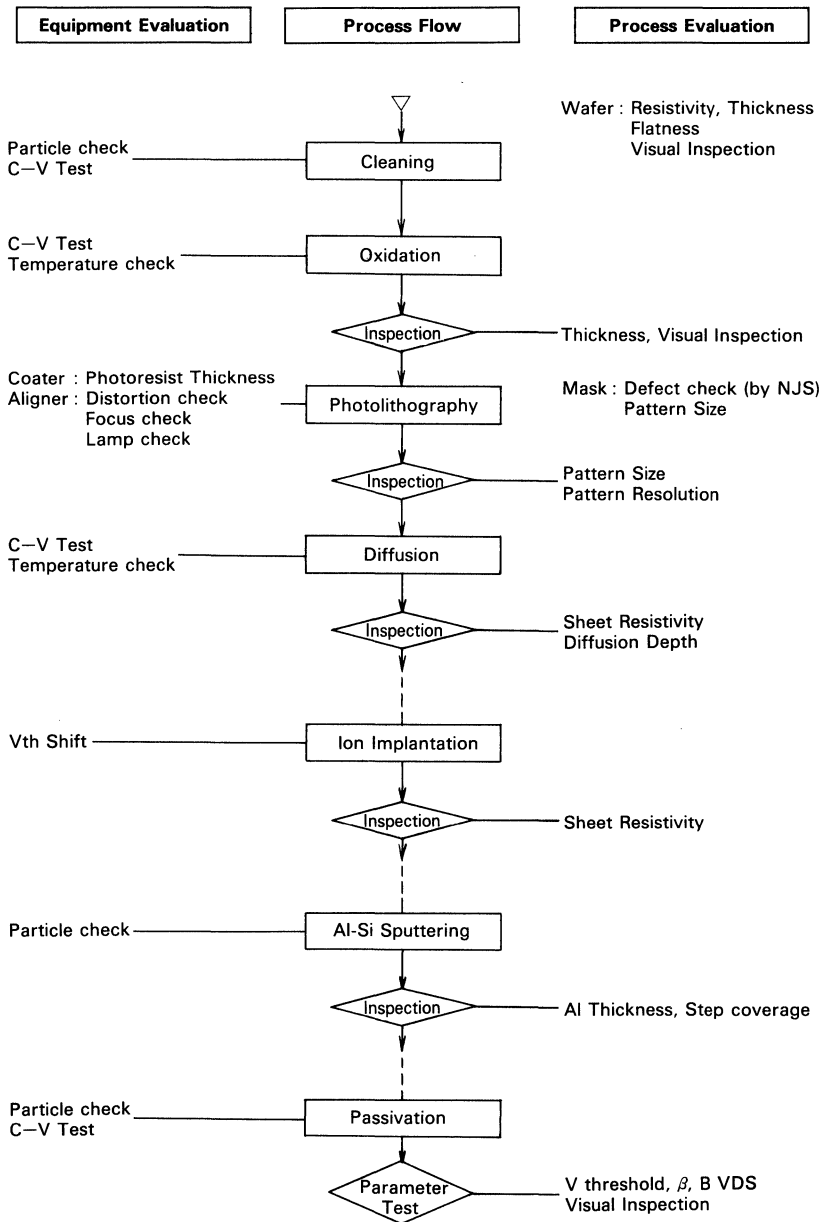


Fig. 3-2 Flow of Quality Assurance Activities in Commercial Production



**Fig. 3-3 Quality Assurance System for Wafer Production**

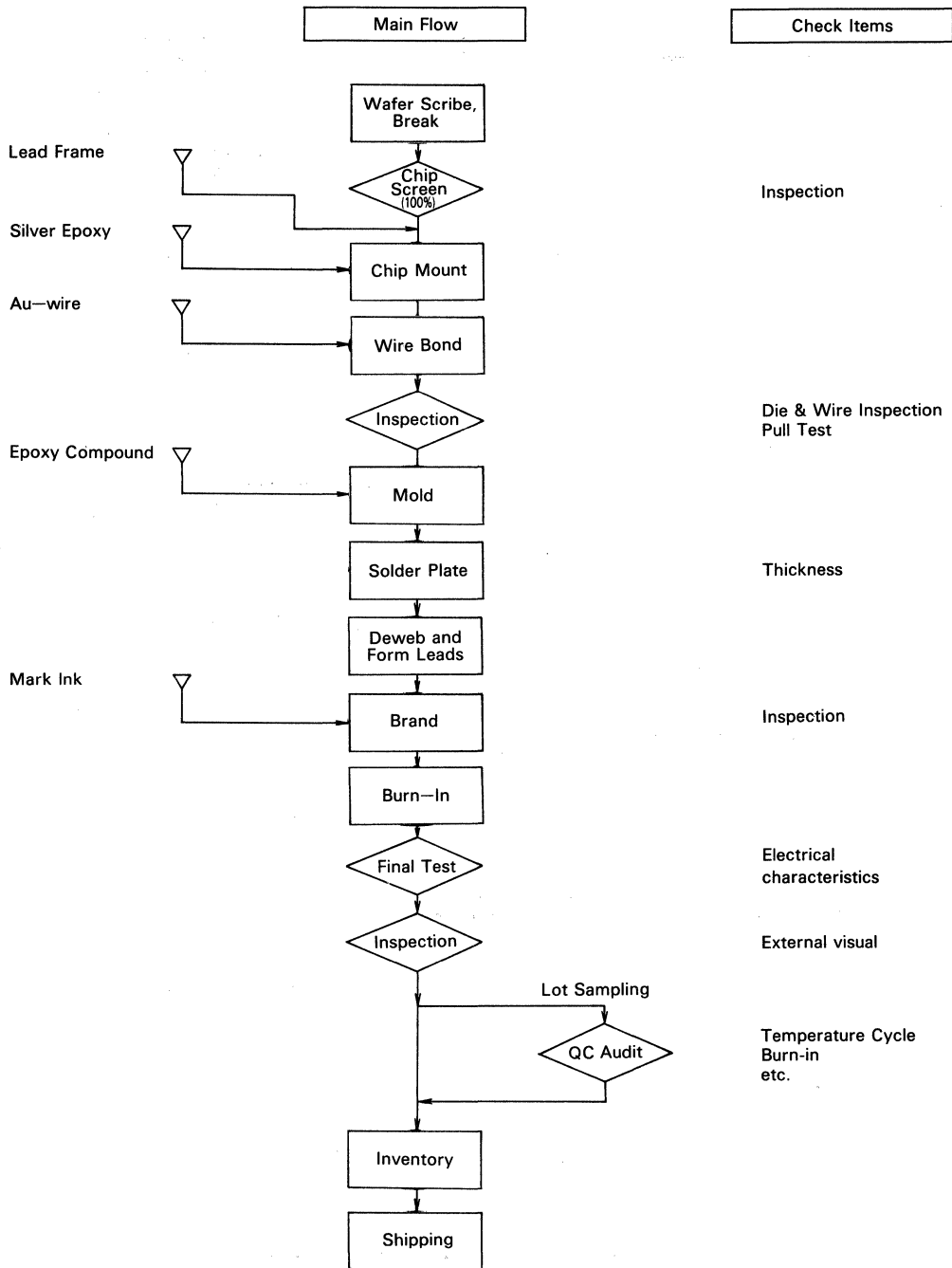
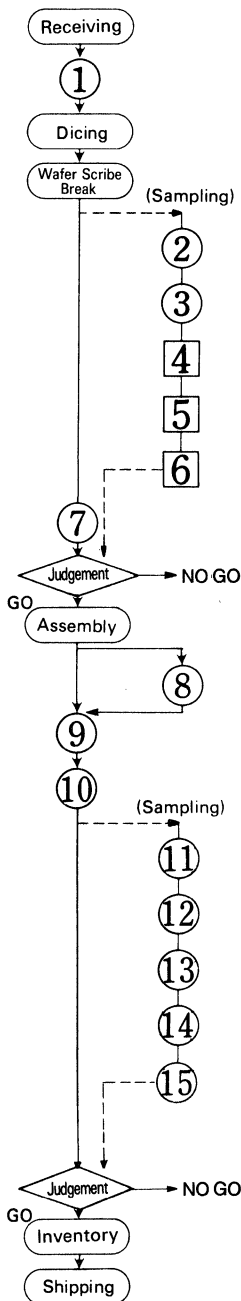


Fig. 3-4 Plastic Package Assembly Flowchart

**Table 3-1 Example of Shipping Inspection**

- : Each lot is inspected for quality assurance.
- : Specific lot is inspected to understand process levels.



**Shipping Inspection for Pellet**

No.	Process	Control point	Standard condition (method)
1	Electrical characteristics (100%)	Wafer process	Determined by product type
2	Resistance to heat	↑	Exposed to high temperature for short time
3	Bondability	↑	Wire pull Die shear strength
4	Electrical characteristics/	↑	Determined by product types
5	Temperature cycle	↑	-55°C to 125°C (for 30 Min. at each temperature)
6	High temperature with bias	↑	125°C with Max. rated voltage applied
7	Visual inspection	Wafer process/ inspection process	Microscope

**Shipping Inspection for Plastic package**

8	Screening	Wafer process/ Assembling process	Burn-in Determined by product type
9	Electrical characteristics (100%)	↑	Determined by product type
10	Visual inspection (100%)	Assembling process	Visually checked
11	Temperature cycle	↑	-55°C to 125°C (for 30 minutes at each temperature)
12	Electrical characteristics/ Visual inspection	Wafer process/ Assembling process	Determined by product types/visually checked
13	High temperature with bias	↑	125°C with Max. rated voltage applied
14	Pressure cooking	Assembling process	2 atmospheric (vapor) pressure (at 121°C)
15	Moisture resistance (with bias)	Wafer process/ Assembling process	85°C, 85% RH with Max. rated voltage applied

### 3.3 Reliability Testing

The reliability test includes environmental testing, life testing and mechanical testing. These tests are made in accordance with EIAJ-IC-121 as the prime standard, and with MIL-STD-750B/883C and JIS where applicable. The way the product is used, the application and the environment in which the product is operated are some of the factors taken into consideration when the conditions are set for the reliability test. It is important to conduct tests of new products under conditions that simulate how the product is to be used. In addition, standard tests are performed.

Table 3-2 summarizes the reliability test items and the factors associated with defects. Table 3-3 gives an example of typical conditions for reliability testing.

**Table 3-2 Reliability Test Items and Factors Associated with Defects**

Reliability test items \ Factors associated with defects	Junction isolation	Oxides	Metallization	Passivation	Die bonding	Wire bonding	Seal	Lead integrity	Solderability	Marking
High temperature bias	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>			
High temperature storage	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>		<input type="checkbox"/>	<input type="checkbox"/>			
Low temperature storage						<input type="checkbox"/>	<input type="checkbox"/>			
Boil	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>			
Temperature cycle	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>			
Mechanical shock						<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>		
Salt atmosphere							<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
Thermal shock		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>			
Vibration variable frequency			<input type="checkbox"/>		<input type="checkbox"/>	<input type="checkbox"/>				
Vibration constant frequency			<input type="checkbox"/>		<input type="checkbox"/>	<input type="checkbox"/>				
Lead integrity								<input type="checkbox"/>		
Bond strength			<input type="checkbox"/>		<input type="checkbox"/>	<input type="checkbox"/>				
Resistance to solvents							<input type="checkbox"/>			<input type="checkbox"/>

**Table 3-3 Typical Conditions for Reliability Test**

Test items		Test method		Purpose of test
		Reference standard	Test conditions	
Environmental test	Temperature cycle	EIAJ-IC-121 04 MIL-STD-883C 1010.5	-65°C to 150°C 100 cycles	Checks resistance to high and low temperatures, and varying temperatures
	Thermal shock	EIAJ-IC-121 03 MIL-STD-883C 1011.4	0°C to 100°C 10 cycles	Checks resistance to rapid temperature changes
	High temperature storage	EIAJ-IC-121 15 MIL-STD-883C 1008.2	Ta = 150°C 1,000 hours	Checks resistance to heat when exposed to high temperature
	Low temperature storage	EIAJ-IC-121 16	Ta = -65°C 1,000 hours	Checks resistance to cold when exposed to low temperature
	Moisture resistance	EIAJ-IC-121 17	Ta = 85°C, 85% RH 1,000 hours	Checks resistance to long-time operation and storage in the environment with high relative humidity
	Salt atmosphere	JIS-C7021 A-12 MIL-STD-202E 101D	35°C, 5% brine spray, 48 hours	Checks resistance to corrosion through acceleration test with coastal environment simulated atmosphere
	Pressure cooker	EIAJ-IC-121 18	2 atmospheric pressures (121°C) 96 hours	Checks resistance to accelerated humidity changes
	Resistance to soldering heat	EIAJ-IC-121 01	260°C, 10 seconds (solder bath)	Checks resistance to heat during soldering
	Resistance to solvents	EIAJ-IC-121 14 MIL-STD-883C 2015.4	Freon Trichloroethylene 10 minutes	Checks resistance of printed marking to solvent
Life test	High temperature steady state	EIAJ-IC-121 51 MIL-STD-883C 1005.4	Ta = 125°C (steady operation) 1,000 hours	Checks resistance to electrical stress and thermal stress applied for extended time periods
	Moisture resistance (with bias)	EIAJ-IC-121 17	Ta = 85°C, 85% RH (rated voltage applied) 1,000 hours	Checks resistance to long-time use with high relative humidity

(Continue)

### Typical Conditions for Reliability Test (cont.)

Test items		Test method		Purpose of test
		Reference standard	Test conditions	
Mechanical test	Vibration variable frequency	EIAJ-IC-121 10 MIL-STD-883C 2007-1	100 Hz to 2,000 Hz 4 minutes/back and forth 4 times each for X, Y and Z (at 20G)	Checks resistance to vibration during transportation or operation
	Vibration fatigue	EIAJ-IC-121 10 MIL-STD-883C 2005-1	60 Hz 20G 32 hours each for X, Y and Z	Checks resistance to vibration during transportation or operation
	Mechanical shock	EIAJ-IC-121 08	1,500G 3 falls each for X, Y and Z	Checks resistance to shocks applied when the product is being handled, transported or operated
	Lead integrity	EIAJ-IC-121 11 MIL-STD-883C 2004-4	Tension 1.0 kg 10 seconds (DIP) Tension 0.3 kg 10 seconds (FP)	Checks resistance to forces to which the lead is subject during installation or operation
		EIAJ-IC-121 11 MIL-STD-883C 2004-4	Bend 90° 2 cycles : 42 Alloy	
Solderability	EIAJ-IC-121 02 MIL-STD-202E 208C	230°C, 5 seconds flux used	Checks solderability to leads	

### 3.4 Defective Product Policy

S-MOS Systems requests the user to return defective products. It is important to S-MOS that when a problem arises it be brought to our attention. Any product information, positive or negative, is valuable data which enables us to improve the quality of our product.

We will make a thorough investigation of the problem with the user's assistance. Where the problem occurred, how it developed and any other related information will be reviewed. The product's manufacturing process and reliability test data will also be reviewed.

The Quality Control Department will check all available information for solutions to prevent the problem from happening in the future. Quality Control will report the results of the investigation to the user through the Sales Department. The Manufacturing Department will be given the report so corrective action can be taken as necessary.

Fig. 3-5 shows that RMA (Returned Material Authorization) process.

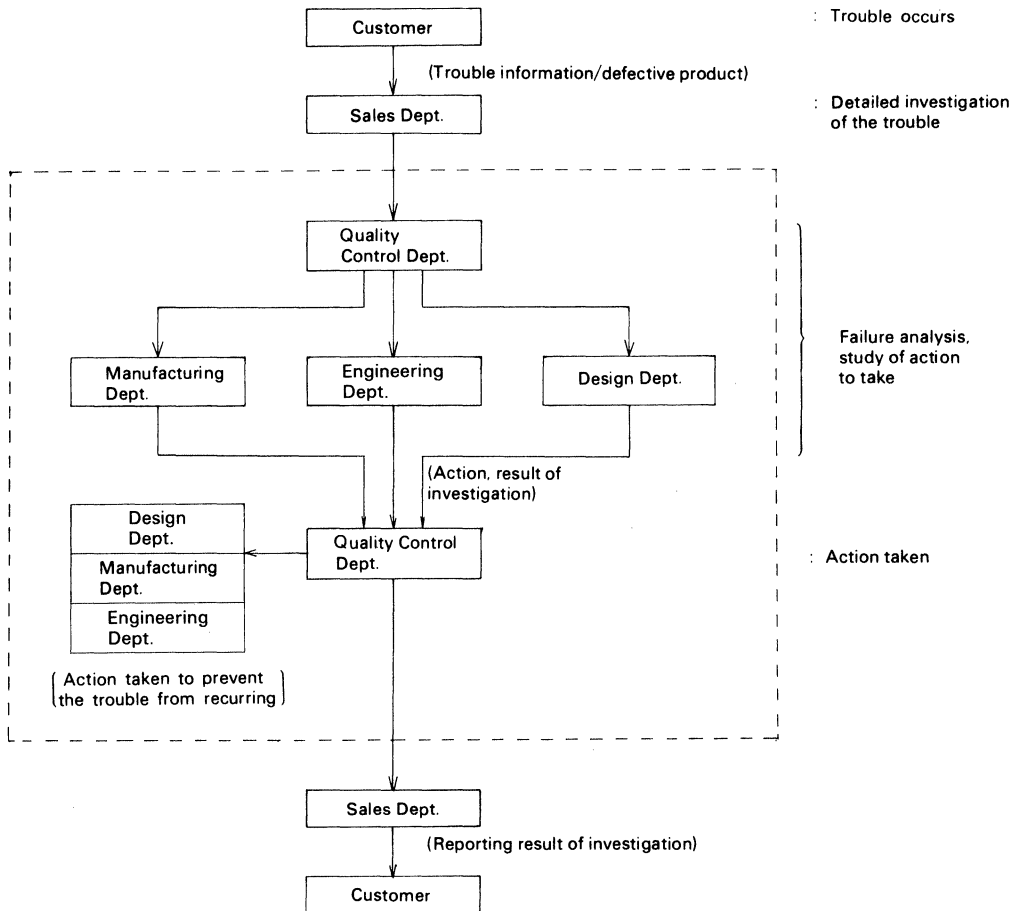


Fig. 3-5 Route of Actions against Trouble Occuring outside the Company



### **3.5 Operating Precautions**

S-MOS System's plastic molded CMOS LSI devices are designed and manufactured for trouble free operation when used under normal operating conditions. Our products are subjected to stringent electrostatic, mechanical strength, and environmental tests for assured reliability. When working with our product the user should observe the following precautions:

- (1) Use the product in the range of rated operating voltage, operating temperature, operating input/output voltage and input/output current. If the product is used outside these operating parameters, the user may experience high failure rates.
- (2) Excessive electrical noise applied to the power or input pin of the device could cause it to latch up, resulting in malfunction or damage. If this occurs, turn the power off immediately, isolate the problem and turn the power on again.
- (3) Do not expose the product to excessive mechanical vibration, repetitive shock stress, rapid or cyclic temperature changes. These factors can cause the wires in the plastic package to break.
- (4) Although all terminals have electrostatic protection, damage may still occur if very high electrostatic potentials are applied. Use of a conductive container or aluminum foil for packaging and transportation is recommended. (Untreated plastic containers are NOT recommended.) Use grounded soldering tools and test equipment.

### **3.6 Solder-reflow Process of Plastic Flat Packages**

During the solder-reflow process, the plastic flat package is exposed to high temperatures (such as far-infrared) inside the reflow furnace. Therefore, the following precautions should be observed when packages are in the solder-reflow process :

- (1) Maintain the maximum temperature of the resin of the package at 245°C for not more than 10 seconds.
- (2) Maintain the outer surface of the reflow furnace temperature (resin surface temperature) at the curve shown in Fig. 3-6.
- (3) The resin on plastic flat packages is prone to absorb moisture. Even at room temperature, the amount of moisture absorbed increases with time. If a wet package is put in the solder-reflow furnace, the resin may crack or the adhesiveness of the resin to the frame may be decreased.
- (4) Items (1) through (3) are intended as a guideline based on our laboratory experience and are for reference only since packages will be stored in different environments and different types of reflow furnaces will be used. Thus, it is important that packages be checked for quality at the solder-reflow process before entering mass production.

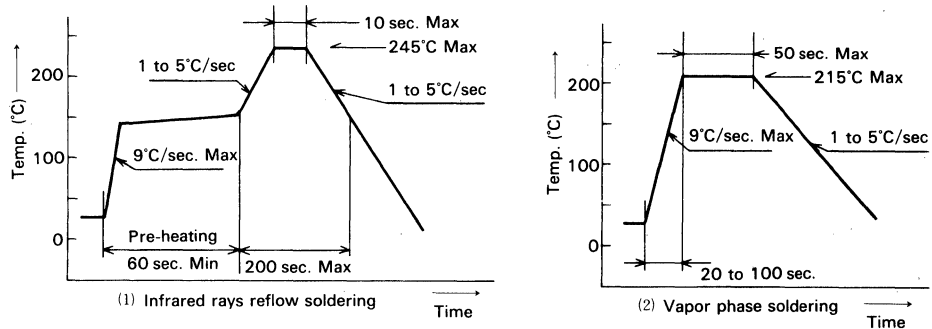


Fig. 3-6 Reflow Furnace Temperature Curve

### 3.7 Package Storage Guidelines

- (1) Packages should be stored in the recommended environment. Maximum storage conditions for temperature and humidity are shown in Table 3.6.
- (2) Packages which exceed the storage limits specified in Table 3.6, or which have absorbed too much moisture due to high temperature or high humidity, should be baked before the reflow process. The recommended procedures for drying the packages are shown in Table 3.7. This drying process will prevent the resin from cracking during the reflow process.

**Table 3-6 Maximum Storage Conditions for Surface Mount Component (SMC)**

**PLASTIC FLAT PACKAGE & SOP**

Storage Conditions		Allowable period
Before open dry-pack ( $\leq 35^{\circ}\text{C}$ )		6 month
After open dry-pack	25°C. 60%	1.5 month
	30°C. 80%	12 day
	35°C. 90%	3 day (72 hour)

**PLASTIC PLCC**

Storage Conditions		Allowable period
Before open dry-pack ( $\leq 35^{\circ}\text{C}$ )		6 month
After open dry-pack	25°C. 60%	2 month
	30°C. 80%	12 day
	35°C. 90%	3 day (72 hour)

**Table 3-7 Dryout conditions for SMC**

Package type	Temperature	125°C	150°C
	PLASTIC QFP, SOP		5 hour
PLASTIC PLCC		20 hour	8 hour

## 4. PACKAGE INFORMATION

Package	Pin	Name	Package	Pin	Name
Plastic DIP	8 pin	C 8	Plastic QFP	18pin	F18-4
	14pin	C14		44pin	F44-2
	16pin	C16		46pin	F46
	18pin	C18		46pin	F46-5
	20pin	C20		60pin	F60
	22pin	C22		60pin	F60-2
	24pin	C24		60pin	F60-5
	28pin	C28		80pin	F80
	40pin	C40		80pin	F80-5
	42pin	C42		100pin	F100-5
	CERDIP	16pin		H16	Ceramic QFP
18pin		H18	Plastic SOP	14pin	
20pin		H20		16pin	M16
24pin		H24		24pin	M24
28pin		H28		24pin	M24-2
40pin		H40	28pin	M28-2	
Plastic Shrink DIP	28pin	S28	Ceramic PGA	64pin	P64
	64pin	S64		72pin	P72
Plastic Skinny DIP	24pin	N24		132pin	P132
			Plastic PGA	89pin	G89
Plastic Skinny DIP	24pin	N24	PLCC	28pin	J28
				44pin	J44
				68pin	J68
				84pin	J84
			SOT89	3pin	Y3

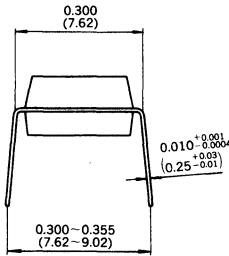
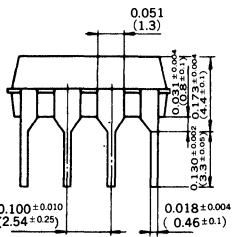
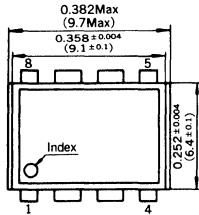
NOTE: Exact dimensions may vary slightly with use of different assembly lines.

## Package Dimension Drawings

Page	Code	Package Type	Page	Code	Package Type
21	C8	8-pin DIP	29	F60	60-pin QFP
	C14	14-pin DIP		F60-2	60-pin QFP
	C16	16-pin DIP		F60-5	60-pin QFP
	C18	18-pin DIP		F80	80-pin QFP
22	C20	20-pin DIP	30	F80-5	80-pin QFP
	C22	22-pin DIP		F100-5	100-pin QFP
	C24	24-pin DIP		F128-8	128-pin QFP
	C28	28-pin DIP		F144-8	144-pin QFP
23	C40	40-pin DIP	31	F160-8	160-pin QFP
	C42	42-pin DIP	32	L148	148-pin QFP
24	H16	16-pin CERDIP	33	M14	14-pin SOP
	H18	18-pin CERDIP		M16	16-pin SOP
	H20	20-pin CERDIP		M24	24-pin SOP
	H24	24-pin CERDIP		M24-2	24-pin SOP
C25	H28	28-pin CERDIP	34	M28-2	28-pin SOP
	H40	40-pin CERDIP	35	P64	64-pin PGA
26	S28	28-pin Shrink DIP		P72	72-pin PGA
	S64	64-pin Shrink DIP		P132	132-pin PGA
27	N24	24-pin Skinny DIP		36	G89
28	F18-4	18-pin QFP	37	J28	28-pin PLCC
	F44-2	44-pin QFP		J44	44-pin PLCC
	F46	46-pin QFP		J68	68-pin PLCC
	F46-5	46-pin QFP		J84	84-pin PLCC
			38	Y3	3-pin SOT89

C8

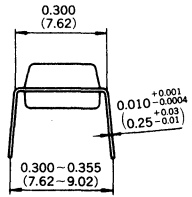
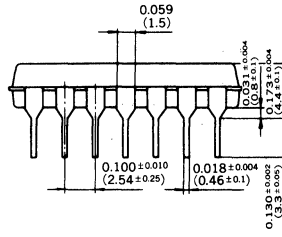
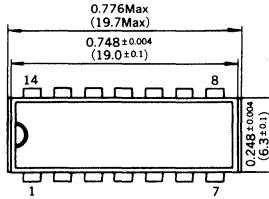
8-pin DIP



unit : inch  
(mm)

C14

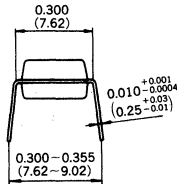
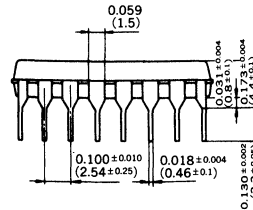
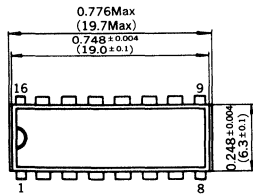
14-pin DIP



unit : inch  
(mm)

C16

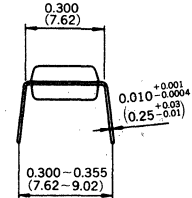
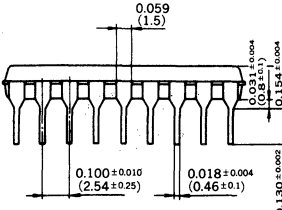
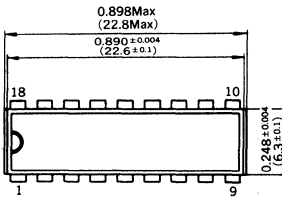
16-pin DIP



unit : inch  
(mm)

C18

18-pin DIP

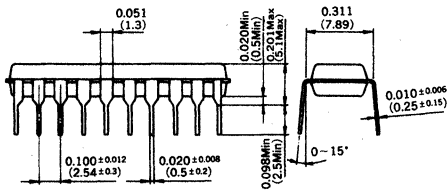
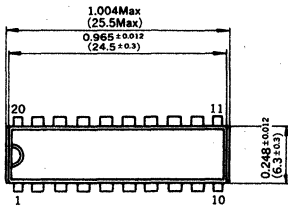


unit : inch  
(mm)

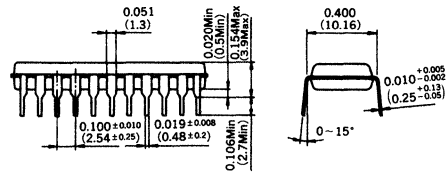
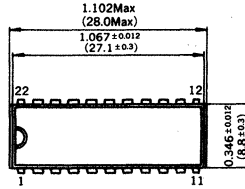
NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.

**C20**

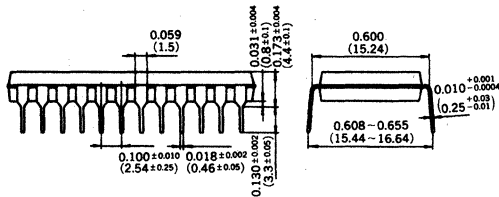
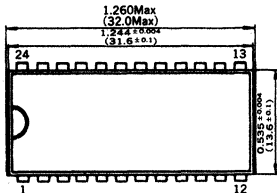
20-pin DIP

unit : inch  
(mm)**C22**

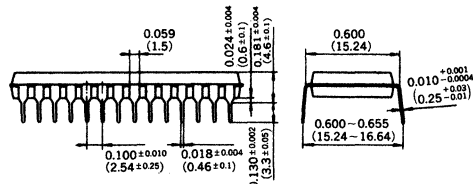
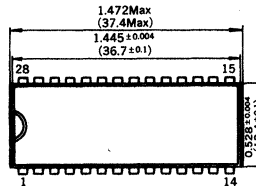
22-pin DIP

unit : inch  
(mm)**C24**

24-pin DIP

unit : inch  
(mm)**C28**

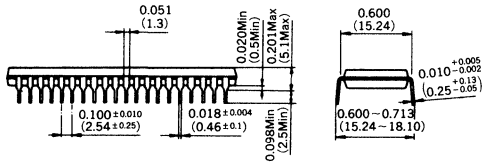
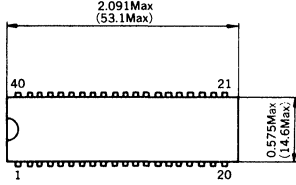
28-pin DIP

unit : inch  
(mm)

NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.

C40

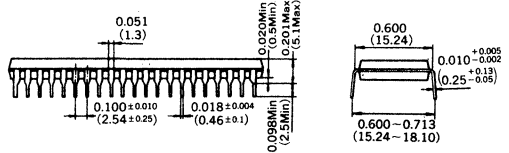
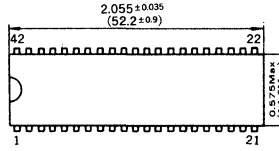
40-pin DIP



unit : inch  
(mm)

C42

42-pin DIP



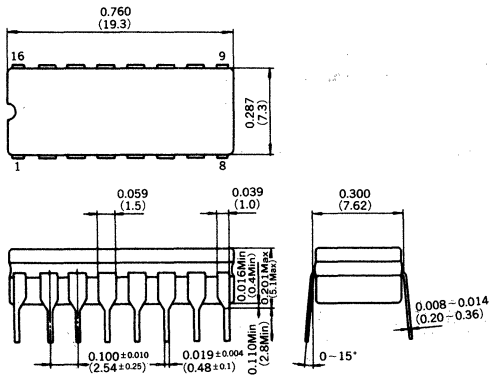
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NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.

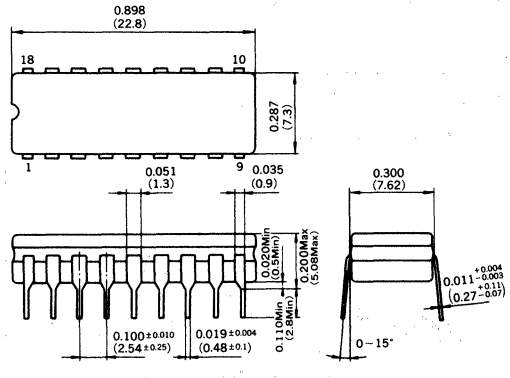


**H16**

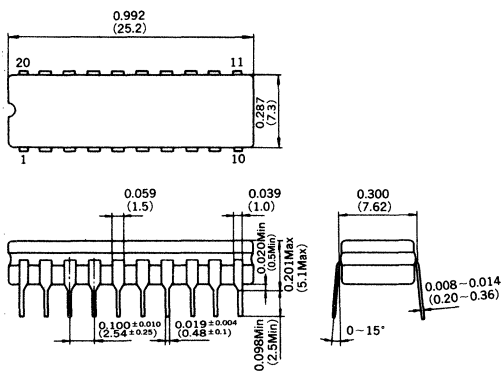
16-pin CERPDP

unit : inch  
(mm)**H18**

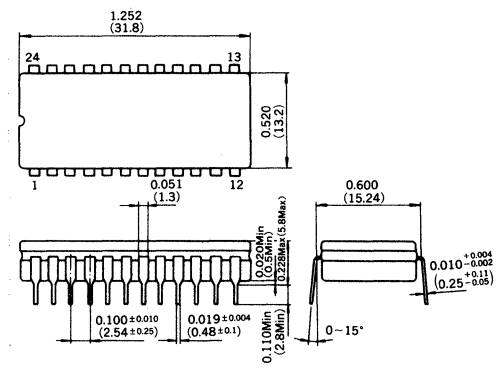
18-pin CERPDP

unit : inch  
(mm)**H20**

20-pin CERPDP

unit : inch  
(mm)**H24**

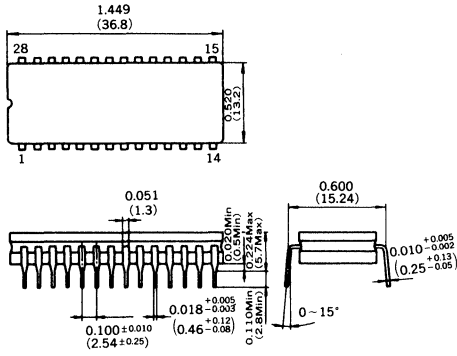
24-pin CERPDP

unit : inch  
(mm)

NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.

H28

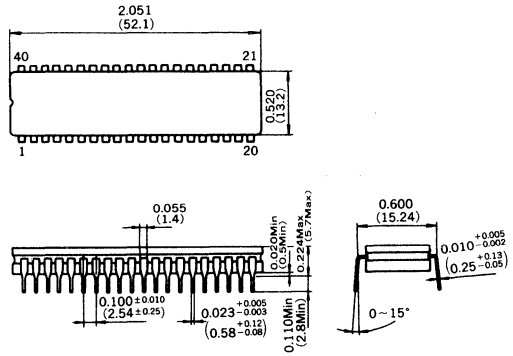
28-pin Cerdip



unit : inch  
(mm)

H40

40-pin Cerdip

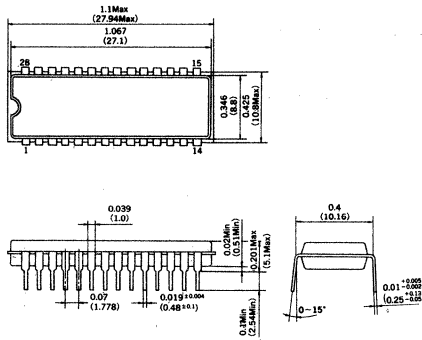


unit : inch  
(mm)

NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.

S28

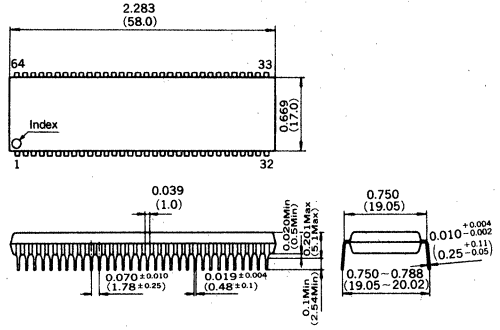
28-pin Shrink DIP



unit : inch  
(mm)

S64

64-pin Shrink DIP

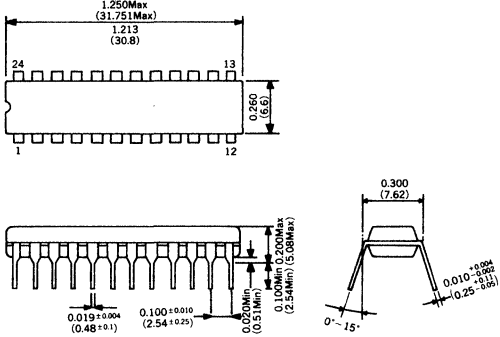


unit : inch  
(mm)

NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.

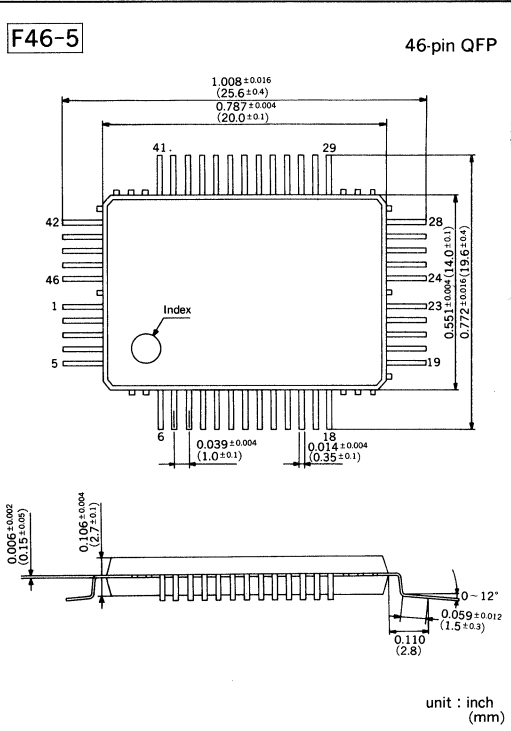
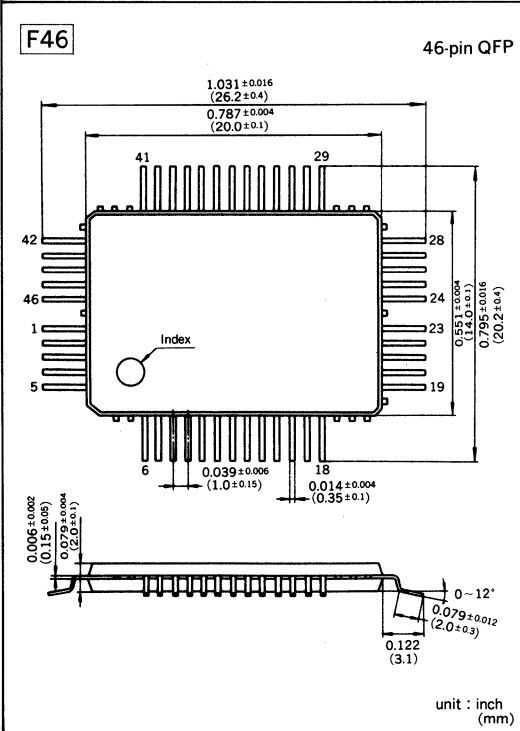
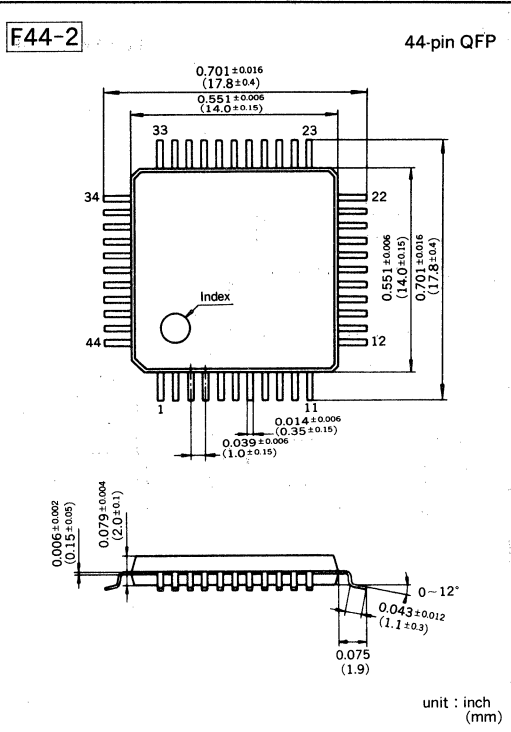
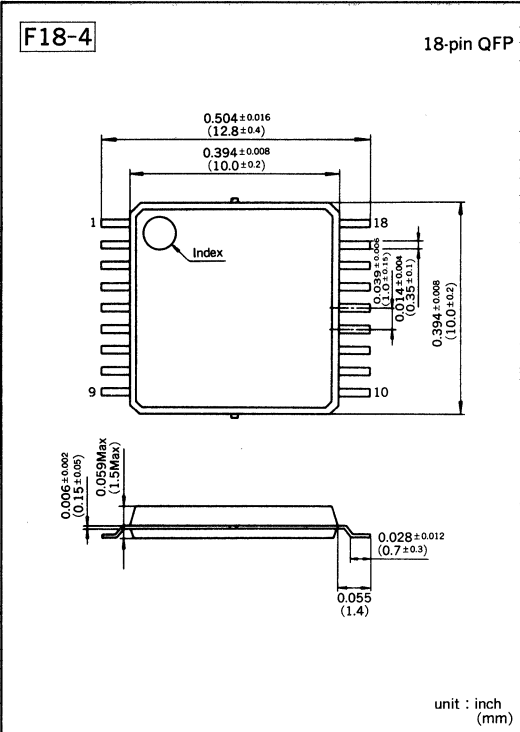
**N24**

24-pin Skinny DIP

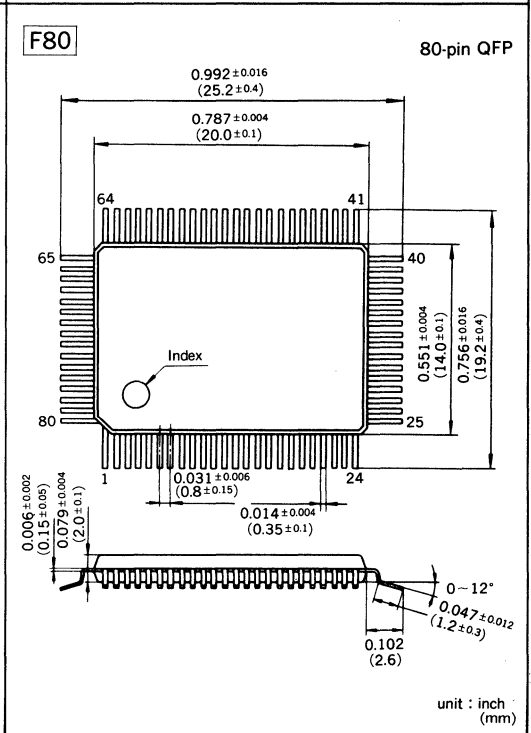
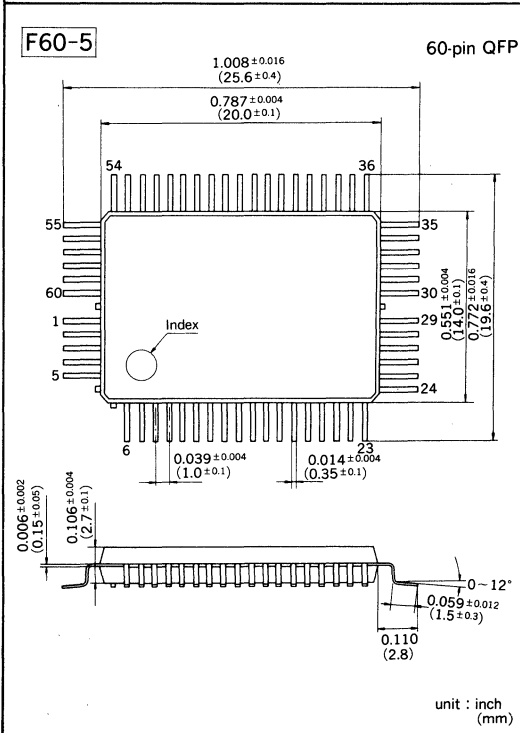
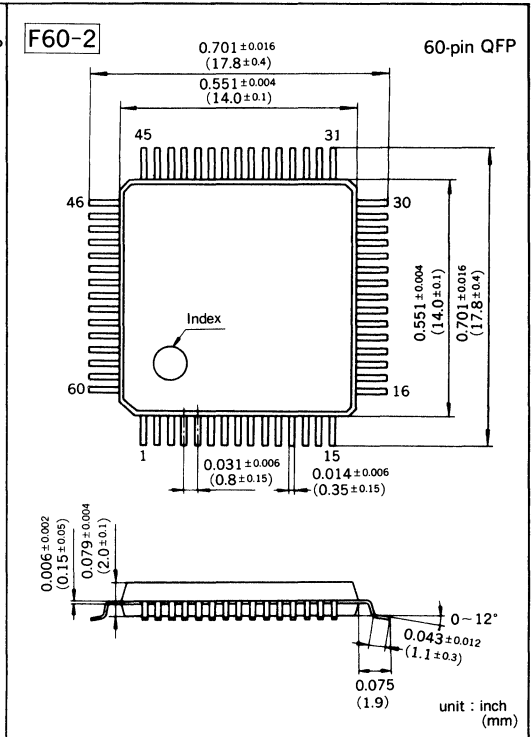
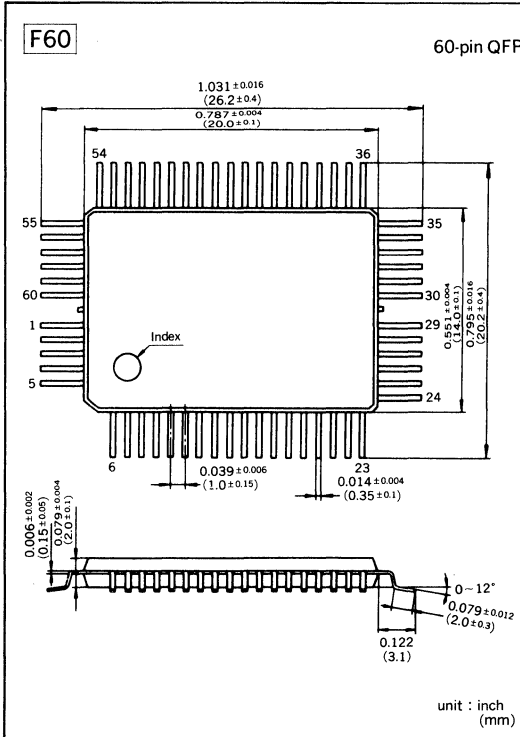


unit : inch  
(mm)

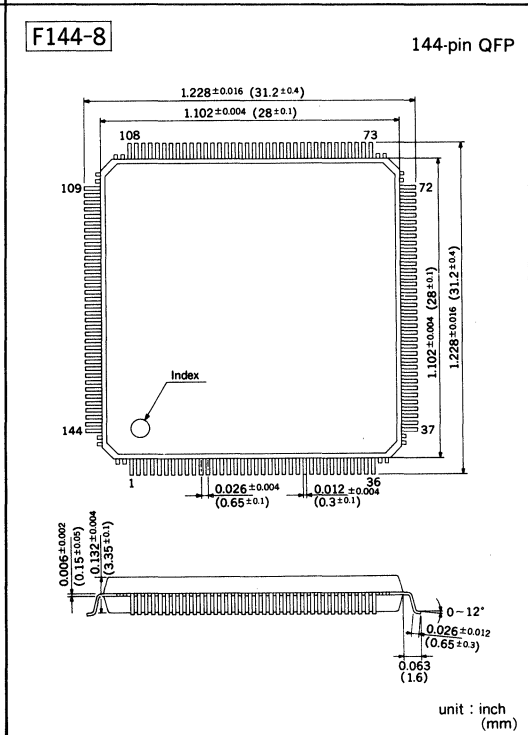
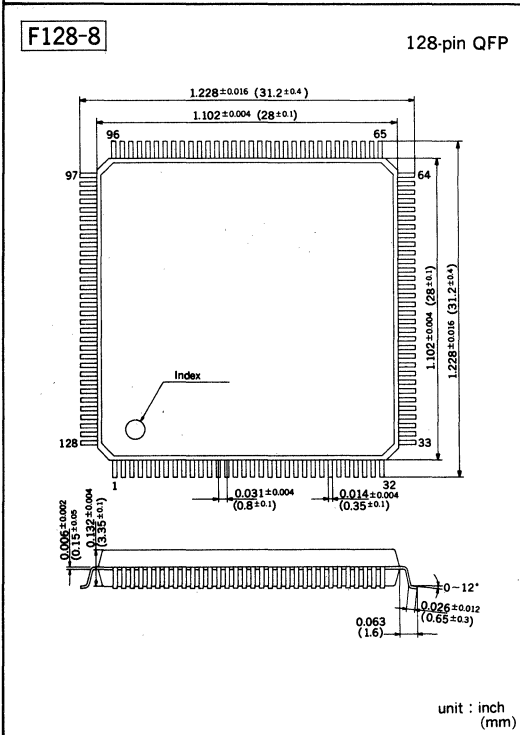
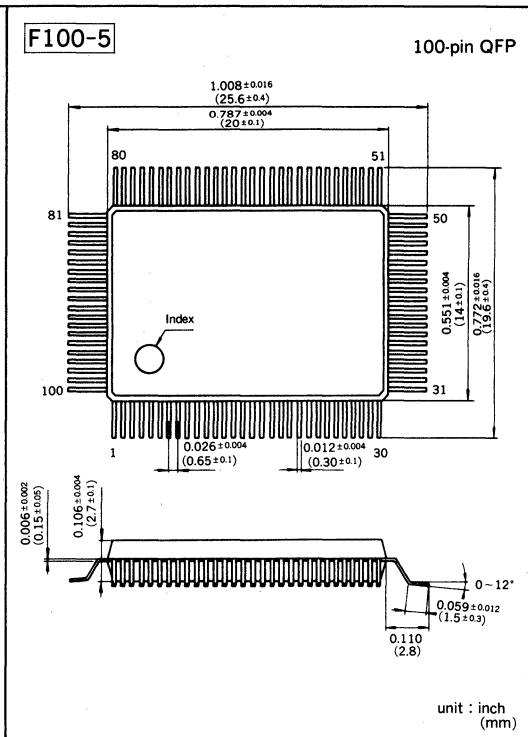
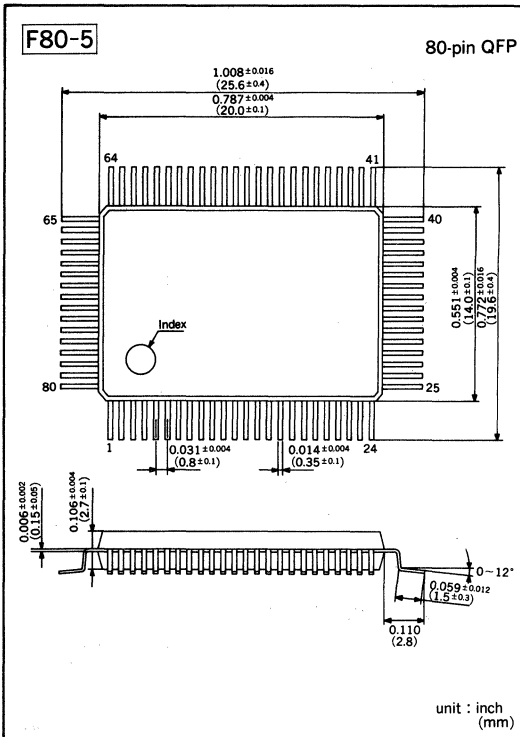
NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.



NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.



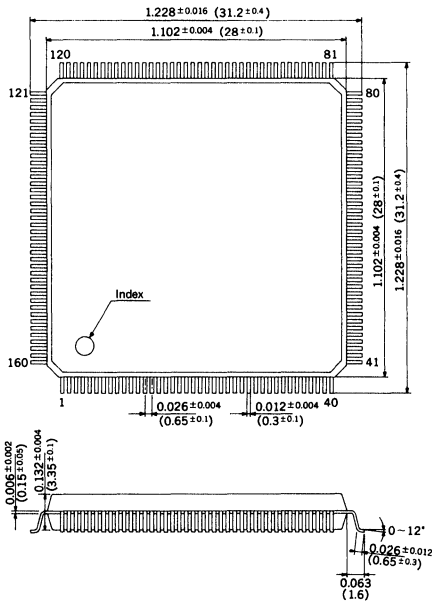
NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.



NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.

F160-8

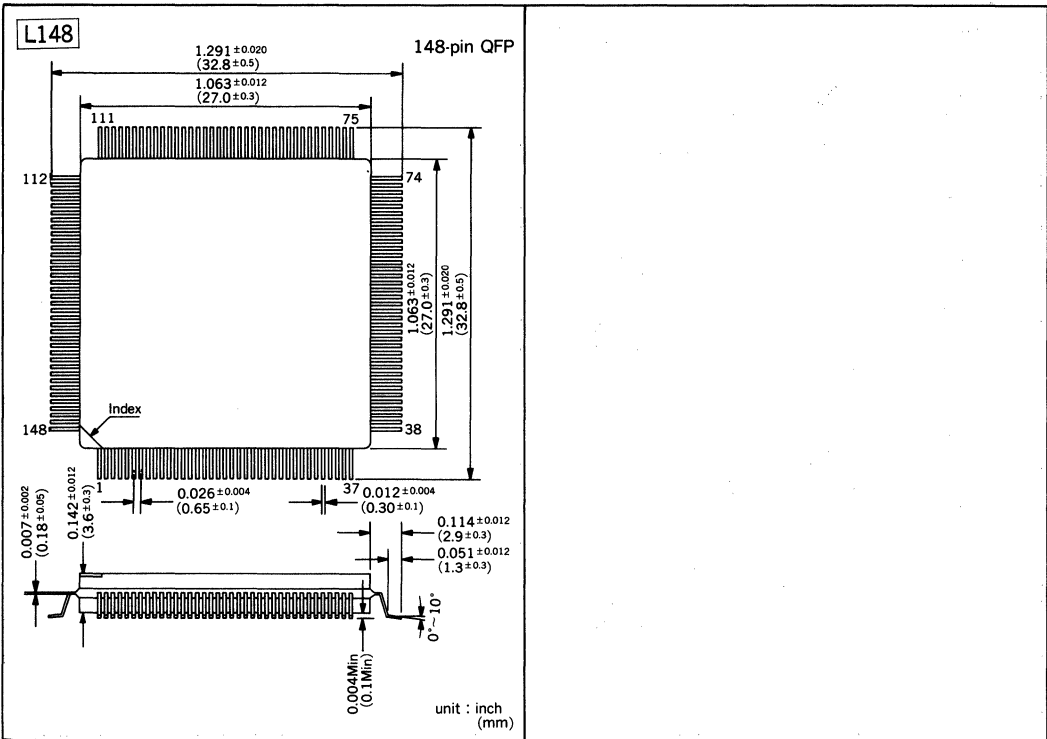
160-pin QFP



unit : inch  
(mm)

NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.

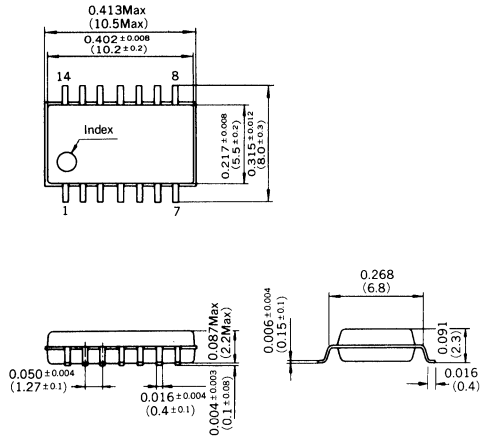




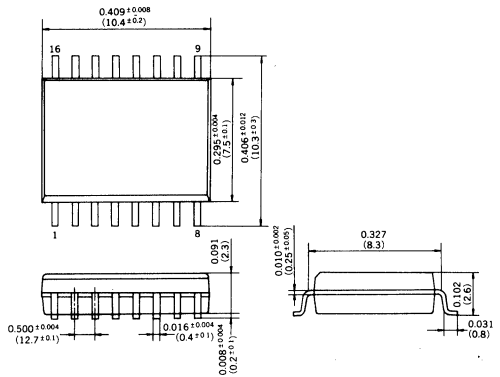
NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.

**M14**

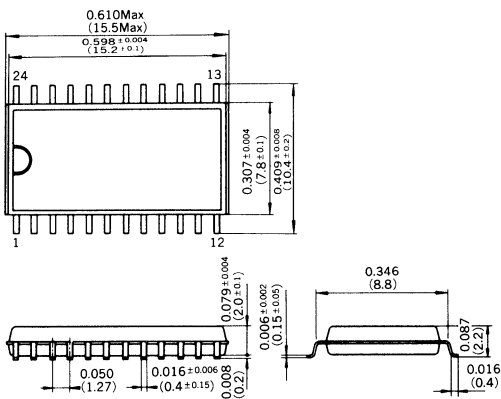
14-pin SOP

unit : inch  
(mm)**M16**

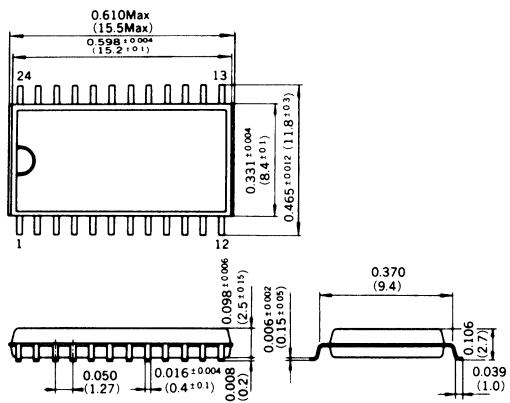
16-pin SOP

unit : inch  
(mm)**M24**

24-pin SOP

unit : inch  
(mm)**M24-2**

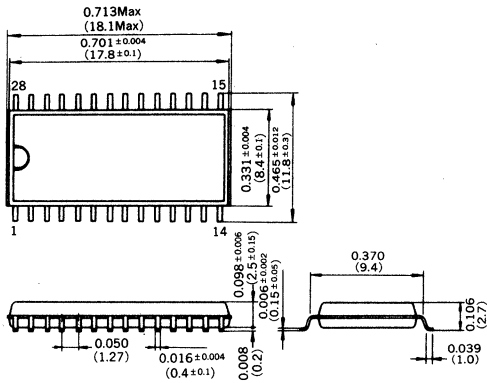
24-pin SOP

unit : inch  
(mm)

NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.

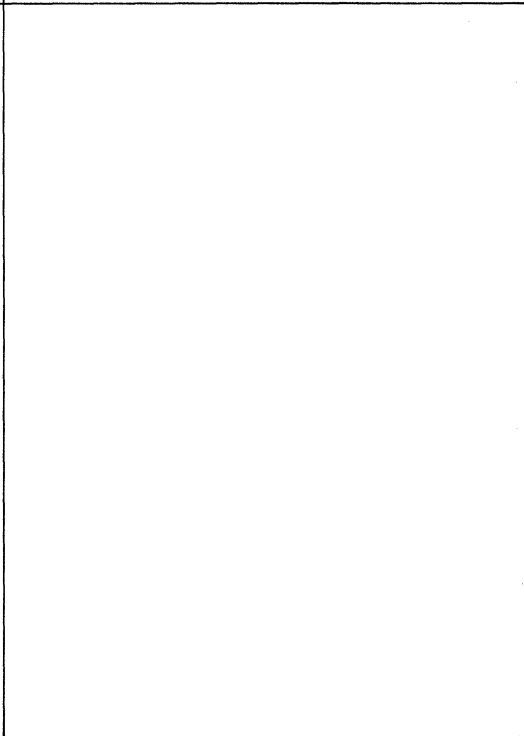
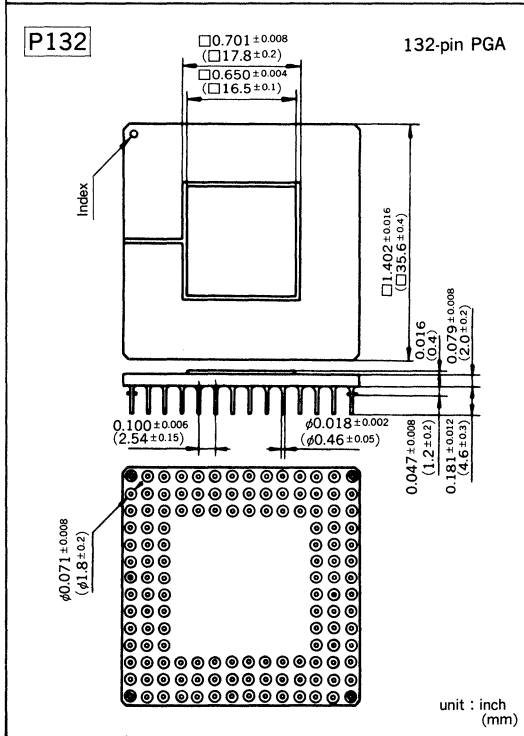
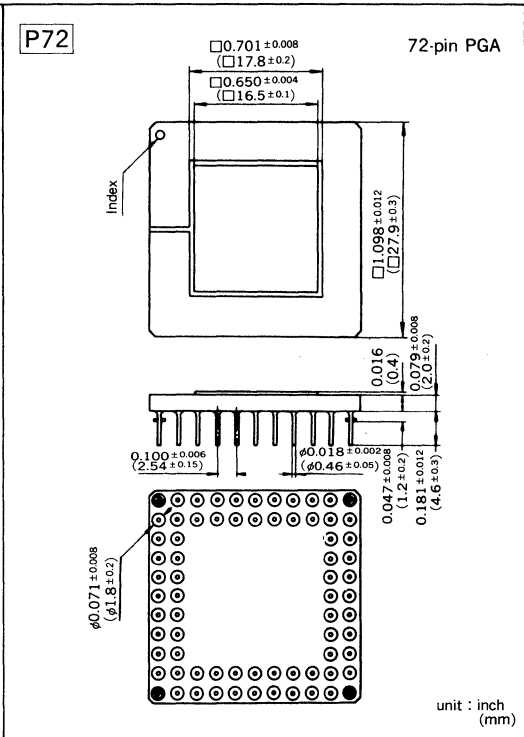
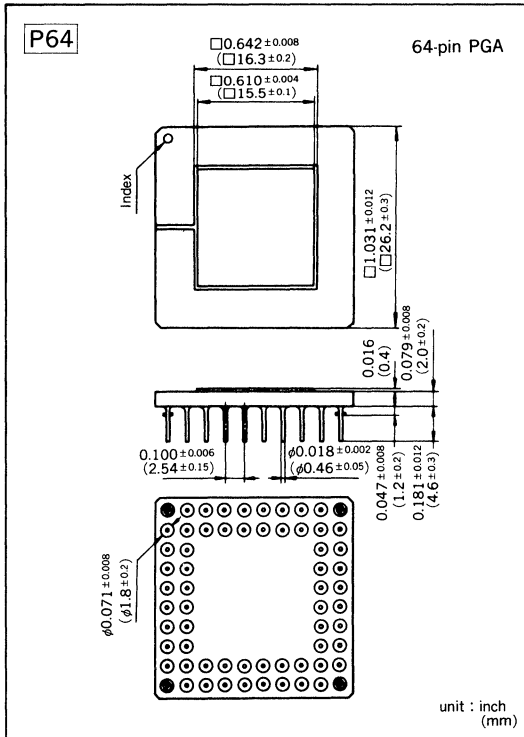
M28-2

28-pin SOP



unit : inch  
(mm)

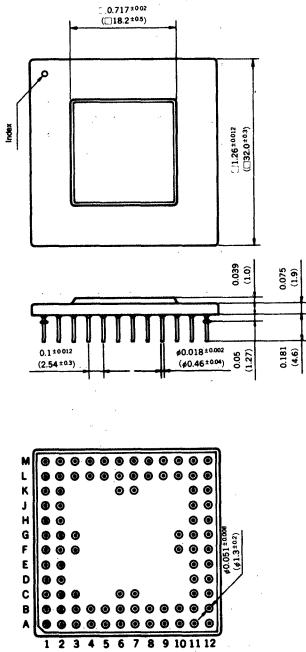
NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.



NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.

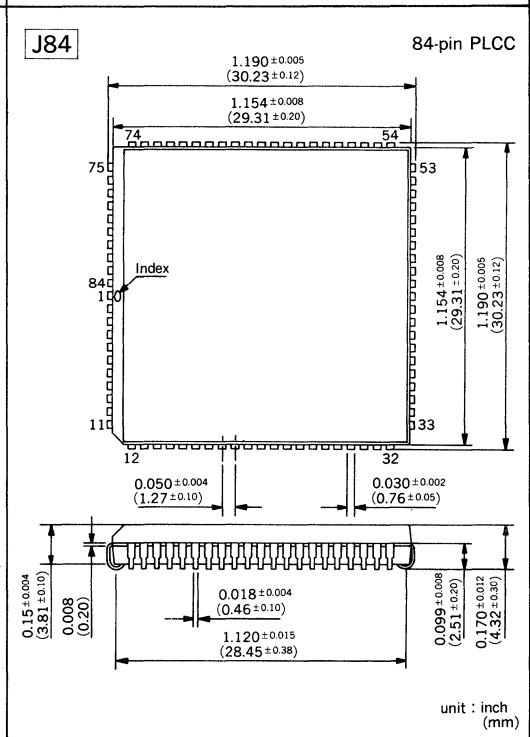
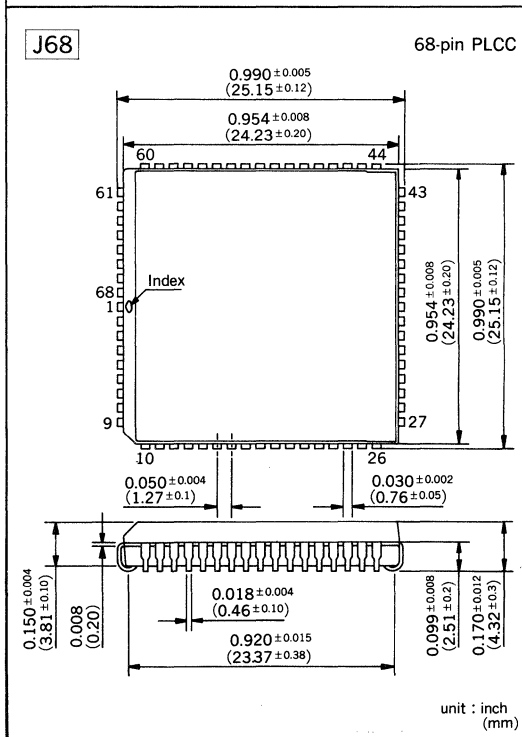
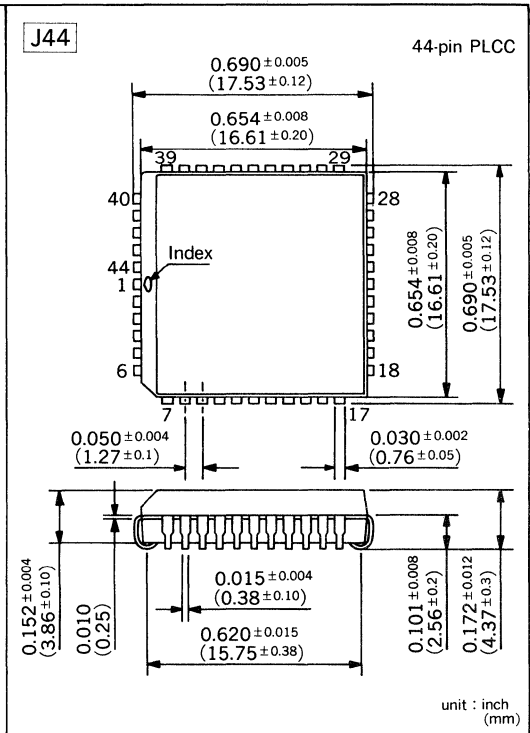
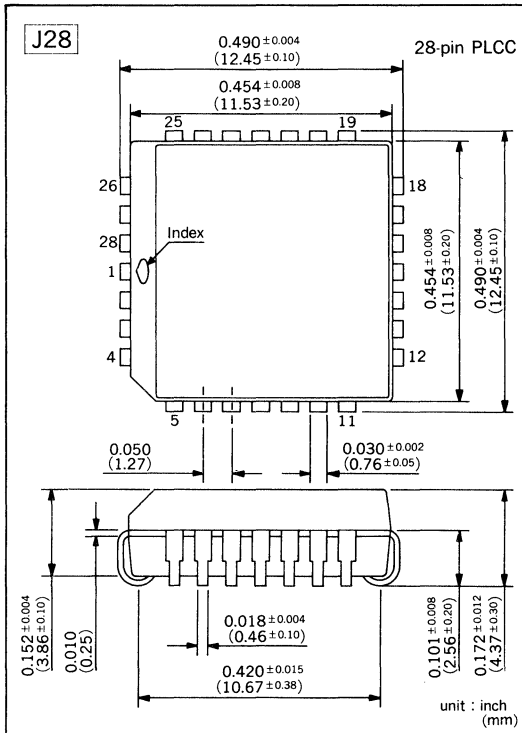
G89

89-pin PGA



unit : inch  
(mm)

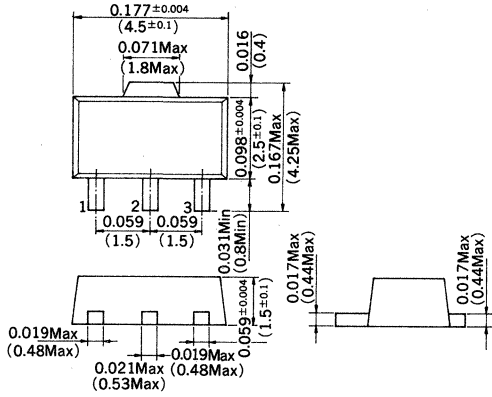
NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.



NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.

Y3

3-pin SOT89



unit : inch  
(mm)

NOTE : Dimensions shown in inches and are derived from their metric equivalents. Please use metric dimensions for board layouts.

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## 5. DEVELOPMENT OF SEMI-CUSTOM CIRCUITS

### 5.1 Development of the Mask ROM and the Single Chip Microcomputer ROM

#### 5.1.1 Mask ROM Customer Code Pattern

Customer code is entered into the Mask ROM using CAD. The ROM code data should be submitted by EPROM or magnetic tape in accordance with the following specifications. The chip enable and the chip select are assigned by completing the "Mask ROM Order Sheet" attached to the ROM code data. Consult S-MOS when using media other than the EPROM or magnetic tape.

- (1) EPROM Requirements
  - (a) Most EPROMs are acceptable.
  - (b) The product name of the EPROM must be written on the "Mask ROM Order Sheet"
  - (c) Submit two sets of EPROM data and data list when placing an order.
- (2) Magnetic Tape Requirements
  - (a) Magnetic tape must be compatible with IBM's magnetic tape device:
    - Number of Tracks: 9
    - Magnetic Recording Density: 800 BPI or 1600 BPI  
(The density should be specified on the "Mask ROM Order Sheet")
  - (b) Magnetic Tape Code: EBCDIC
  - (c) Format of the Magnetic Tape:
    - Without tape mark at the head
    - Without label
    - Record Size: 80 byte/record
    - Block Size: 10 records/block
    - Two continuous tape marks at the end of the file
  - (d) When writing the ROM code data of multiple chips on a single magnetic tape, there should be one tape mark at the end of each file and two tape marks at the end of the last file. Separate magnetic tapes should be used for each semicustom LSI.
- (3) Data Form
  - (a) Divide the eight bit code in half; the upper four bits and the lower four bits. Each four bits should be converted into a hexadecimal.
  - (b) The data form is shown in Fig. 5-1. Data is written on the tape in ASCII hexadecimal code.
    - Record Mark — Colon ":" indicates the beginning of a record.
    - Number of Codes — Number of object codes stored in one record will be indicated in two hexadecimal digits.
    - Location Address — The head address for each record should be written in four hexadecimal digits. The number should start from 0000 in ascending order.
    - Record Type — Should be in two hexadecimal digits, 01 for the last record and 00 for all others.
    - Code — One eight bit word is written in two hexadecimal digits.
    - Check Sum — The number of codes, the location address, the record type and the codes are subtracted in order from the primary value 00. The results are written in two hexadecimal digits.
    - Last Record — Indicated by 00000001FF RETURN.



(4) Check Sum Calculation

The subtraction is made on the assumption that the binary subtracting device is used and borrowing is ignored.

Example:

The number of codes (10) is subtracted from the primary value.

```

0000 0000
- ) 0001 0000
-----
1111 0000
  
```

The upper 8 bits of the location address (00) is then subtracted.

```

1111 0000
- ) 0000 0000
-----
1111 0000
  
```

The lower 8 bits (00), the record type (00) and the code (7D) are subtracted in sequence.

```

1111 0000
- ) 0111 1101
-----
0111 0011
  
```

next the code (FE) is subtracted.

```

0111 0011
- ) 1111 1110
-----
0111 0101
  
```

This procedure is repeated until the last code is subtracted.

```

0111 0101
- ) 0010 0000
-----
0101 0101
  
```

The check sum will be 66.

```

1110 0100
- ) 0111 1110
-----
0110 0110
  
```

(5) ROM Code Revisions

After the EPROM or magnetic tape has been submitted, ROM code revisions due to a design change will be accepted before Mask manufacturing begins only. A revised EPROM or magnetic tape must be submitted also.

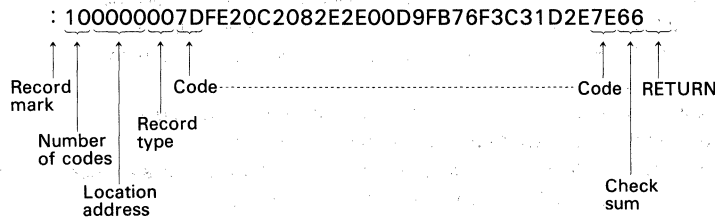
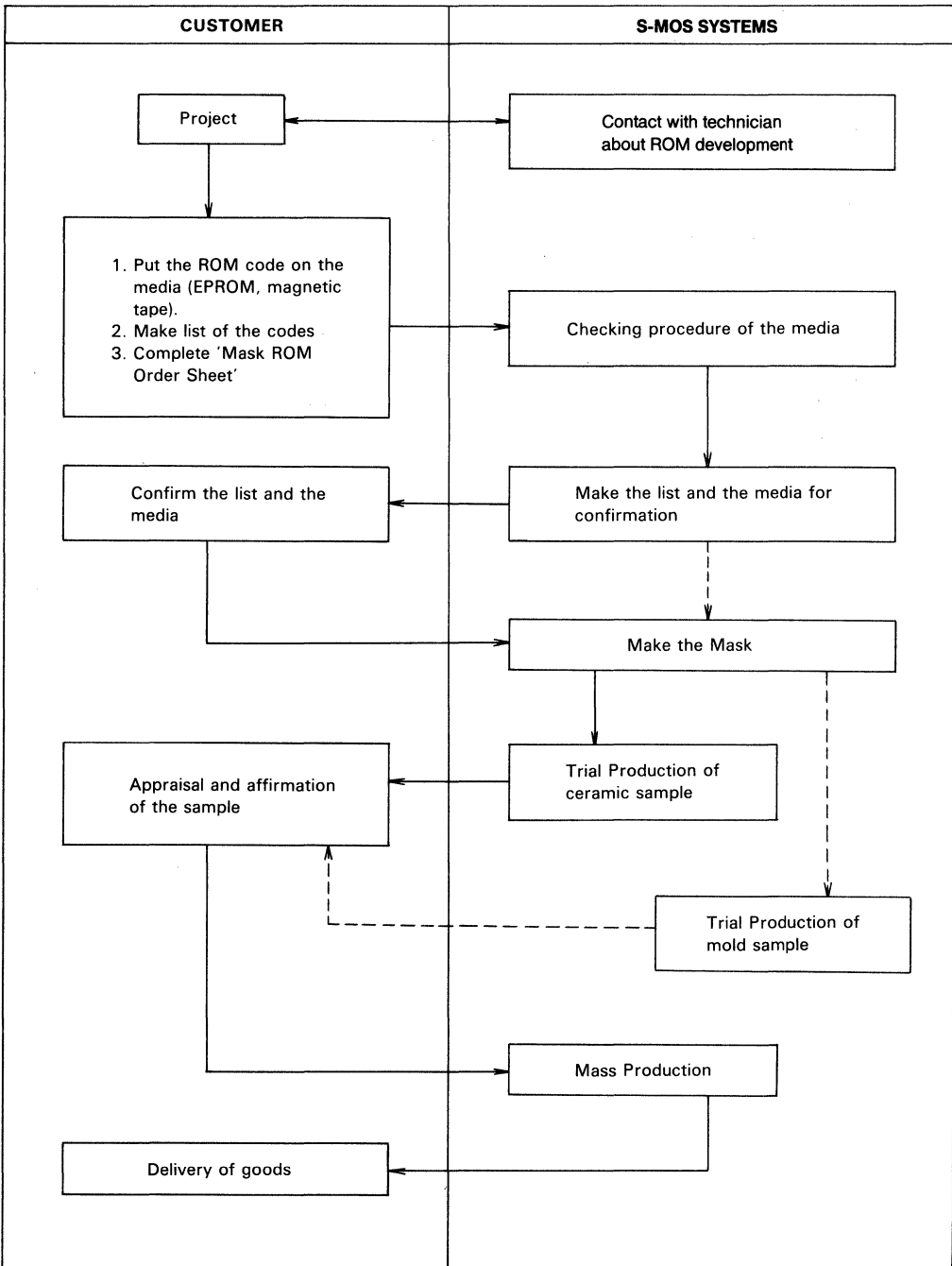


Fig. 5-1 Data Format

### 5.1.2 Flow Chart of Mask ROM Development



---

#### Development Routine

- (1) The solid line indicates the standard development procedure.
- (2) The dotted line indicates the procedure at customer's request.

#### Schedule

- (1) Five weeks (standard) — from list confirmation to ceramic sample
- (2) Six weeks (standard) — from list confirmation to mold sample
- (3) Six weeks (standard) — from sample confirmation to the delivery of goods

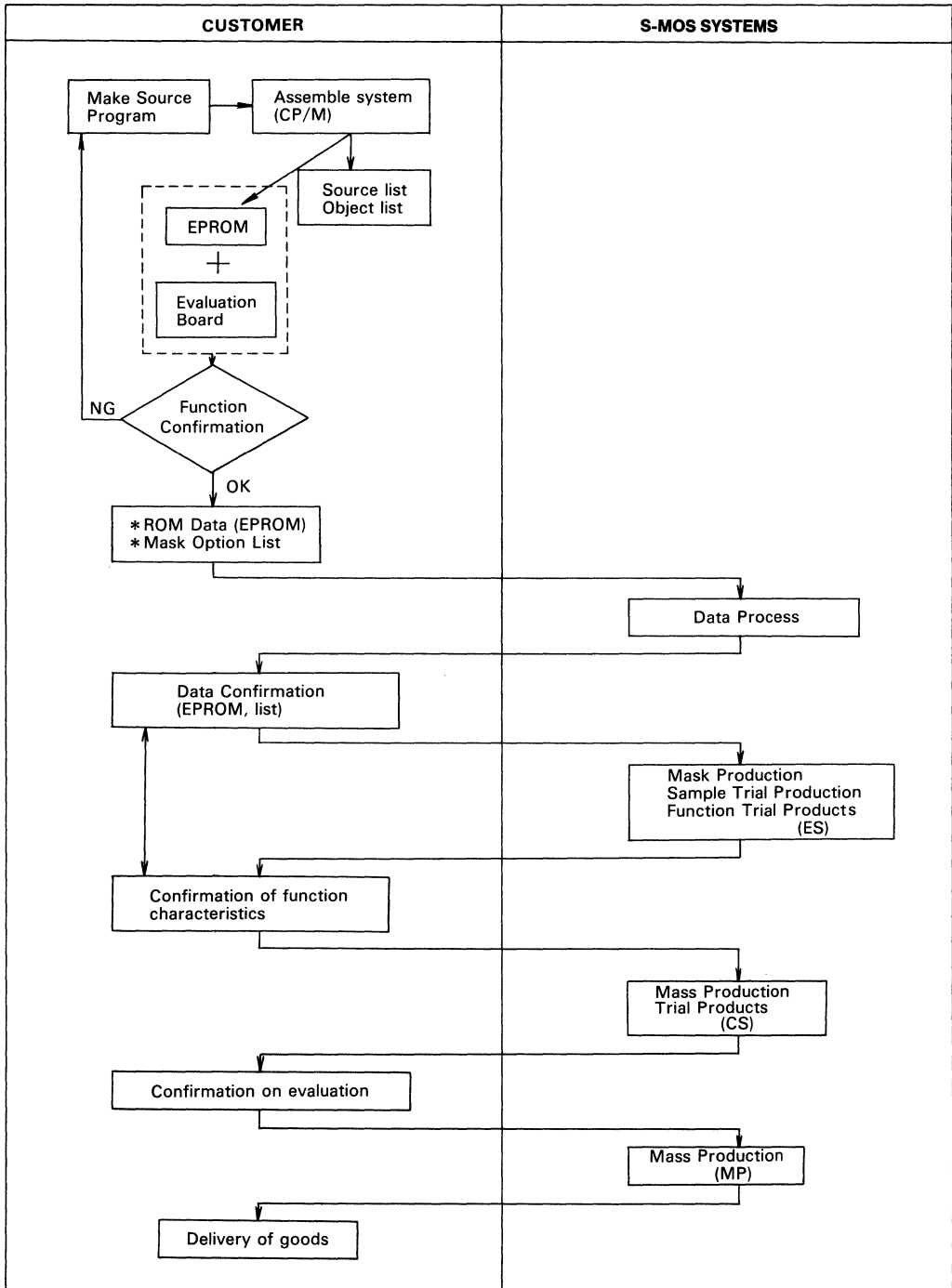
#### Quantity

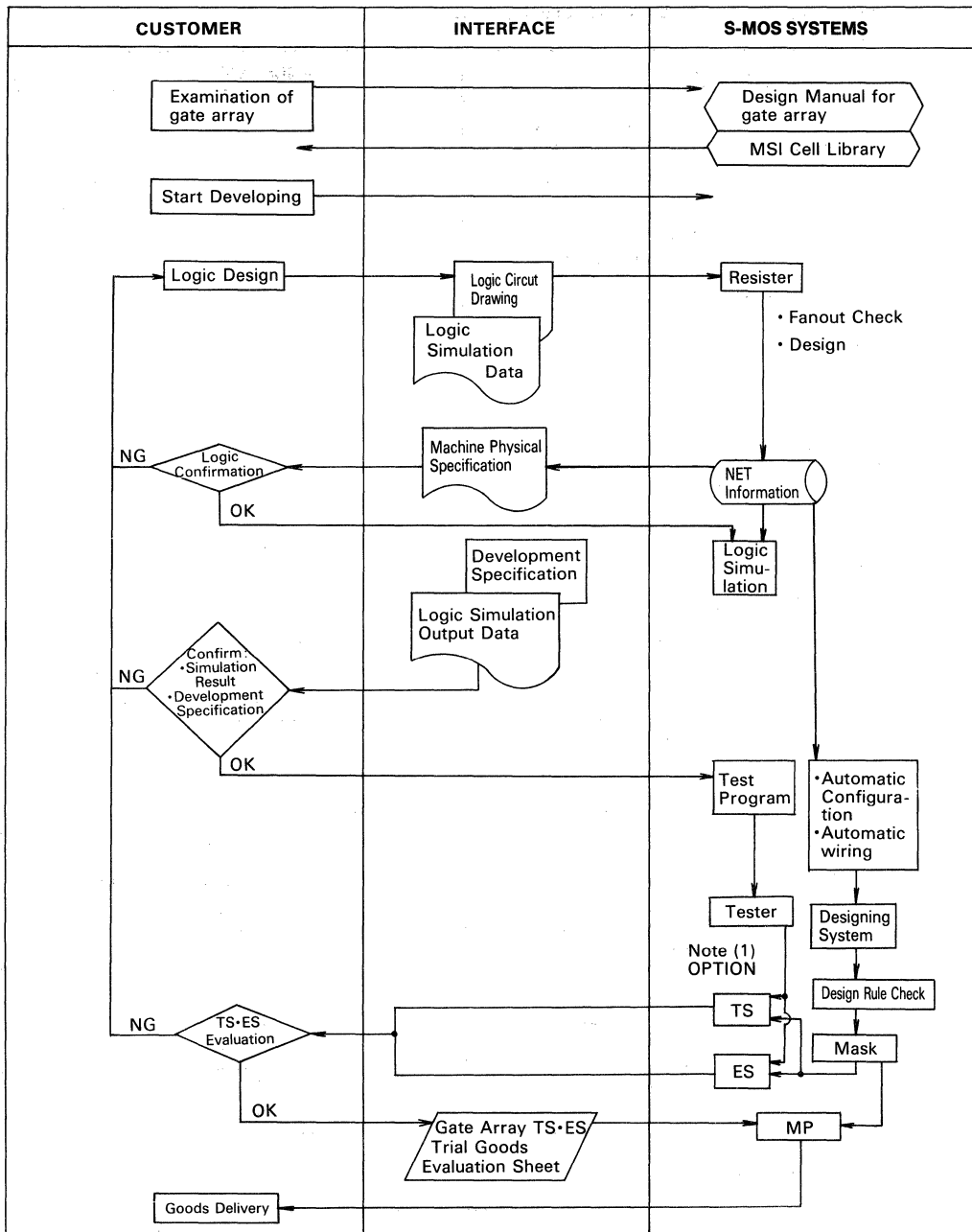
- (1) Normally, five ceramic samples are included in the mask charge.
- (2) Normally, less than one hundred mold samples are available with the charge.

#### Flow Chart of Single-chip Microcomputer ROM Development (Table 5.1.3)

- (1) Please refer to the "Order of Mask ROM custom code pattern" for making the ROM data (EPROM).
- (2) CS may be omitted by mutual agreement of the customer and S-MOS Systems.
- (3) If S-MOS Systems develops the software, the evaluation instruments for the LCD Panel and its Objective System must be prepared by the customer for S-MOS Systems.

### 5.1.3 Flow Chart of Single-chip Microcomputer ROM Development

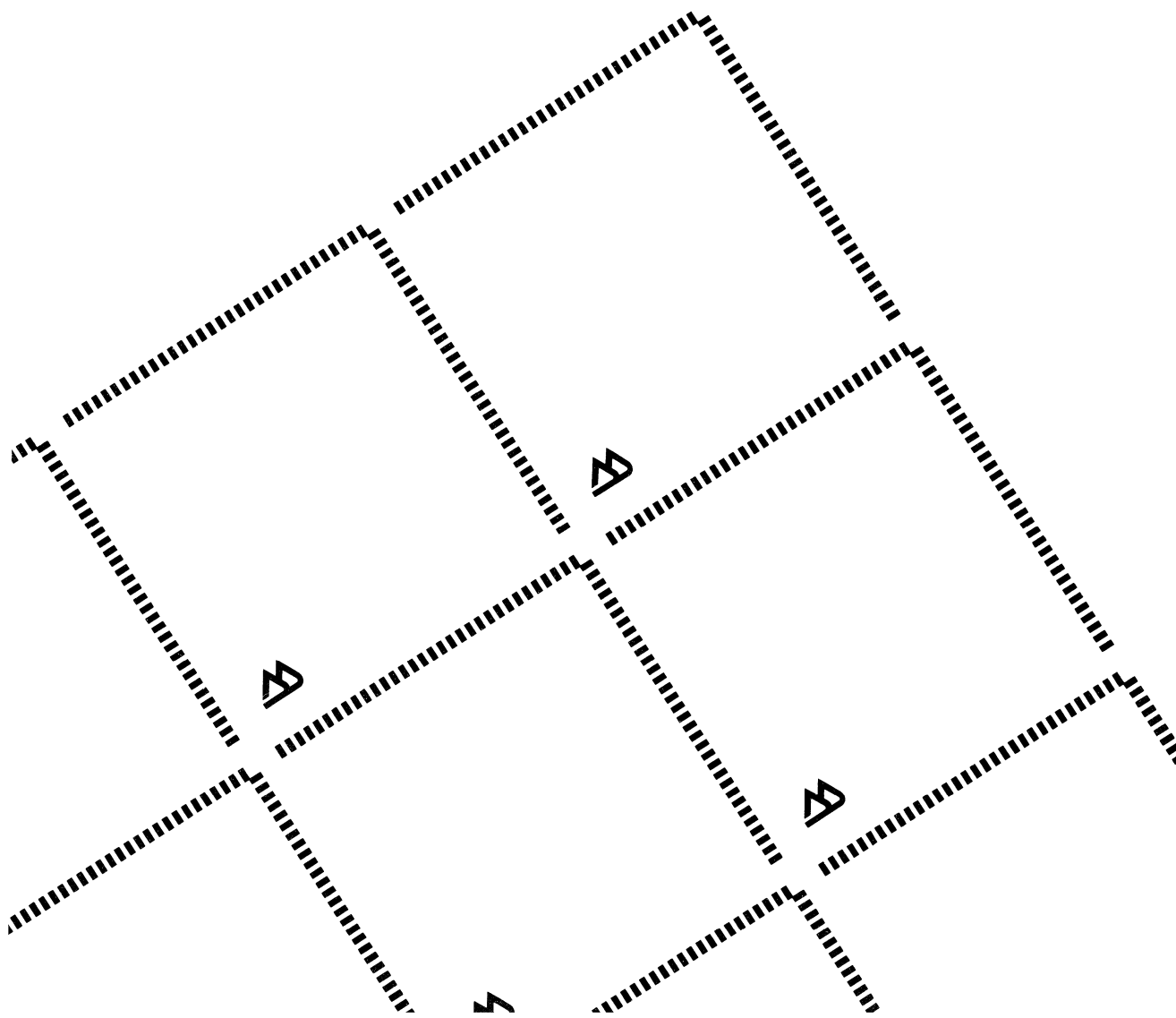




- NOTE) 1. TS is available upon request. Its packaging form is different from that of mass production.  
 2. Since the time for delivery is based on the standard, there may be some small differences between the scheduled date and the actual delivery date.  
 3. Twenty ESs are included in the cost for development.

A. MEMORIES

1988/1989 CMOS  
DATA BOOK





# SRM2114C<sub>25/L7</sub>

## CMOS 4K-BIT STATIC RAM

- Low Supply Current
- Access Time 250ns/700ns
- 1,024 Words × 4 Bits

### DESCRIPTION

The SRM2114C<sub>25/L7</sub> is a 1,024 words × 4 bits asynchronous, static, random access memory on a monolithic CMOS chip. Its very low standby current consumption makes it ideal for applications requiring non-volatile storage with back-up batteries. The static nature of the memory requires no external clock or refreshing circuit.

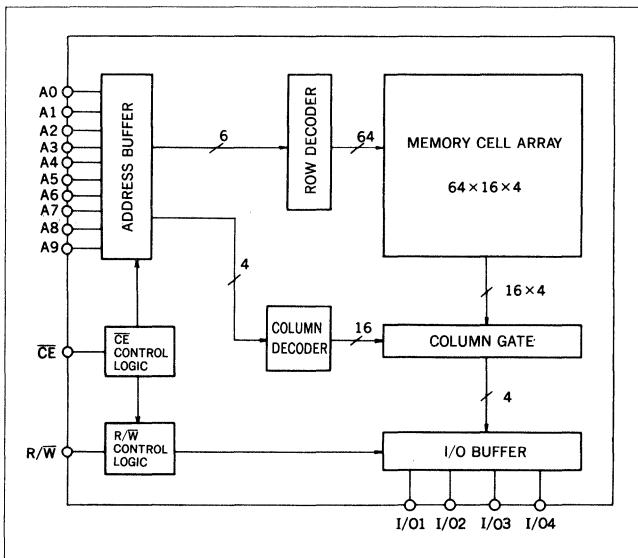
Both the input and output ports are TTL compatible; and the three-state output allows easy expansion of memory capacity. These features make the SRM2114C<sub>25/L7</sub> usable for widerange of applications from microprocessor systems to terminal devices.

The SRM2114C<sub>L7</sub> is a low power variation of SRM2114C<sub>25</sub>.

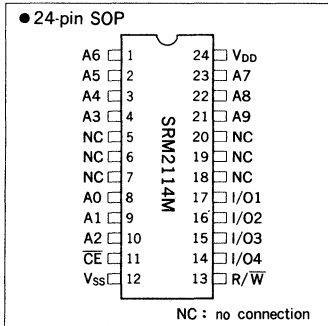
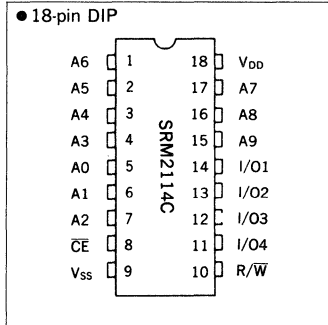
### FEATURES

- Access time ..... 250ns (Max) / 700ns (Max)
- Single power supply ..... 5V ± 10% / 3 to 5V
- Low supply current ..... Standby : 0.1μA (Typ) / 0.1μA (Typ)  
Operation : 14mA (Typ) / 9mA (Typ)
- Completely static operation
- TTL compatible inputs and outputs
- 3-state output with wired-OR capability
- Operation with back-up batteries
- Package ..... 18-pin DIP (plastic)  
24-pin SOP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A9	Address Input
R/W	Read/Write
CE	Chip Enable
I/O1 to 4	Data Input/Output
VDD	Power Supply (+)
VSS	Power Supply (-)



## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5 to 7.0	V
I/O voltage	V <sub>I/O</sub>	-0.5 to V <sub>DD</sub> +0.3	V
Power dissipation	P <sub>D</sub>	1.0	W
Operating temperature	T <sub>opr</sub>	-40 to 85 [-10 to 70]	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

[ ]: SRM2114CL7

## ■ RECOMMENDED DC OPERATING CONDITIONS

Parameter	Symbol	SRM2114C25			SRM2114CL7			Unit
		Min	Typ	Max	Min	Typ	Max	
Supply voltage	V <sub>DD</sub>	4.5	5.0	5.5	3.0	4.5	5.0	V
	V <sub>SS</sub>	—	0	—	—	0	—	
Input voltage	V <sub>IH</sub>	2.2	—	V <sub>DD</sub> +0.3	V <sub>DD</sub> -0.4	—	V <sub>DD</sub> +0.3	V
	V <sub>IL</sub>	-0.3	—	0.8	-0.3	—	0.4	

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

(SRM2114C25.....V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, Ta = -40 to 85°C)  
 (SRM2114CL7.....V<sub>DD</sub> = 3 to 5V, V<sub>SS</sub> = 0V, Ta = -10 to 70°C)

Parameter	Symbol	SRM2114C25				SRM2114CL7				Unit
		Conditions	Min	Typ	Max	Conditions	Min	Typ	Max	
Input leakage Current	I <sub>LI</sub>	V <sub>I</sub> = 0 to V <sub>DD</sub>	-1.0	—	1.0	V <sub>I</sub> = 0 to V <sub>DD</sub>	-1.0	—	1.0	μA
Standby supply current	I <sub>DDS</sub>	CE = V <sub>DD</sub> - 0.2V	—	0.1	5	CE = V <sub>DD</sub> - 0.2V	—	0.1	5	μA
Operating supply current	I <sub>DDO</sub>	CE = V <sub>IL</sub> * C <sub>L</sub> = 100pF	—	* 14	* 35	CE = V <sub>IL</sub> I <sub>0</sub> = 0mA	—	6	10	mA
						t <sub>RC</sub> = 1000ns t <sub>RC</sub> = 700ns	—	9	15	
Output leakage current	I <sub>LO</sub>	V <sub>O</sub> = 0 to V <sub>DD</sub>	-1.0	—	1.0	V <sub>O</sub> = 0 to V <sub>DD</sub>	-1.0	—	1.0	μA
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -1.0mA	2.4	—	—	I <sub>OH</sub> = -100μA	V <sub>DD</sub> -0.2	—	—	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2.0mA	—	—	0.4	I <sub>OL</sub> = 100μA	—	—	0.2	V

\* C<sub>L</sub> = 0pF Typ7 Max25

### ● Terminal Capacitance

(f = 1MHz, SRM2114C25.....V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, Ta = -40 to 85°C)  
 (SRM2114CL7.....V<sub>DD</sub> = 3 to 5V, V<sub>SS</sub> = 0V, Ta = -10 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input capacitance	C <sub>I</sub>	V <sub>I</sub> = 0V	—	—	7	pF
I/O capacitance	C <sub>I/O</sub>	V <sub>I/O</sub> = 0V	—	—	10	pF

### ● AC Electrical Characteristics

#### ○ Read Cycle

(SRM2114C25.....V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, Ta = -40 to 85°C)  
 (SRM2114CL7.....V<sub>DD</sub> = 3 to 5V, V<sub>SS</sub> = 0V, Ta = -10 to 70°C)

Parameter	Symbol	Conditions	SRM2114C25		SRM2114CL7		Unit
			Min	Max	Min	Max	
Read cycle time	t <sub>RC</sub>	* 1	250	—	700	—	ns
Address access time	t <sub>ACC</sub>		—	250	—	700	ns
CE access time	t <sub>ACE</sub>		—	250	—	700	ns
CE output set time	t <sub>CLZ</sub>	* 2	0	—	0	—	ns
CE output floating	t <sub>CHZ</sub>		—	120	—	140	ns
Output hold time	t <sub>OH</sub>	* 1	10	—	10	—	ns

### ○ Write Cycle

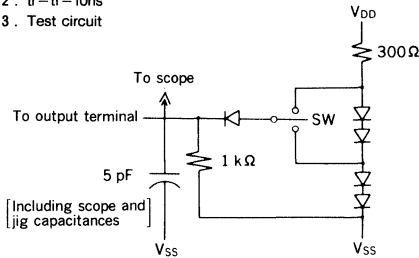
Parameter	Symbol	Conditions	SRM2114C <sub>25</sub>		SRM2114C <sub>L7</sub>		Unit
			Min	Max	Min	Max	
Write cycle time	$t_{WC}$	* 1	250	—	700	—	ns
Address setup time	$t_{AS}$		0	—	0	—	ns
Write pulse width	$t_{WP}$		150	—	420	—	ns
Address hold time	$t_{WR}$		0	—	0	—	ns
Input data setup time	$t_{DW}$		100	—	280	—	ns
Input data hold time	$t_{DH}$		0	—	0	—	ns
R/ $\bar{W}$ Output floating	$t_{WHZ}$	* 3	—	120	—	140	ns

#### \* 1 Test conditions. [( ):SRM2114C<sub>L7</sub>]

- Input pulse level : 0.8 to 2.2V ( $V_{DD}-0.4V$  to 0.4V)
- $t_r = t_f = 10ns$
- Output load :  $I_{TL} + C_L = 100pF$  [including scope and jig capacitances] ( $C_L = 100pF$ )
- Timing reference level : 1.5V ( $V_{DD}/2$ )

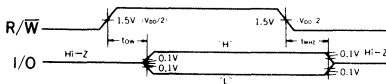
#### \* 3 Test conditions

- Input pulse level : 0.8 to 2.2V ( $V_{DD}-0.4V$  to 0.4V)
- $t_r = t_f = 10ns$
- Test circuit



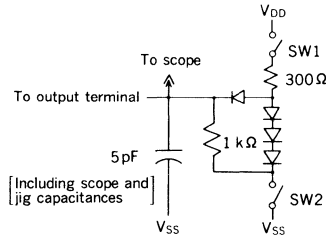
- SW is set to the  $V_{DD}$  side when measuring Hi-Z→"High" and "High"→Hi-Z of  $t_{ow}$  or  $t_{whz}$ .
- SW is set to the  $V_{SS}$  side when measuring Hi-Z→"Low" and "Low"→Hi-Z of  $t_{oz}$  or  $t_{whz}$ .

#### Output turn-on turn-off times



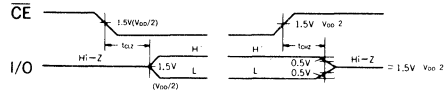
#### \* 2 Test conditions

- Input pulse level : 0.8 to 2.2V ( $V_{DD}-0.4V$  to 0.4V)
- $t_r = t_f = 10ns$
- Test circuit



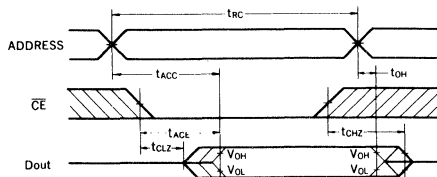
- SW1, SW2 are closed when measuring  $t_{chz}$ .
- SW1 is open, SW2 is closed when measuring Hi-Z→"High" of  $t_{oz}$ .
- SW1 is closed, SW2 is open when measuring Hi-Z→"Low" of  $t_{oz}$ .

#### Output turn-on turn-off times



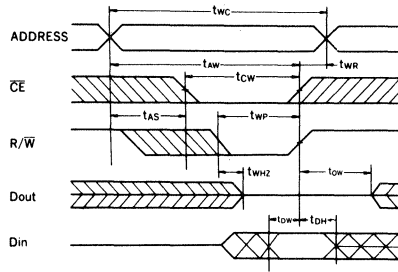
### ● Timing Chart

#### ○ Read Cycle



\* R/ $\bar{W}$  is "High" during read cycle.

○ Write Cycle



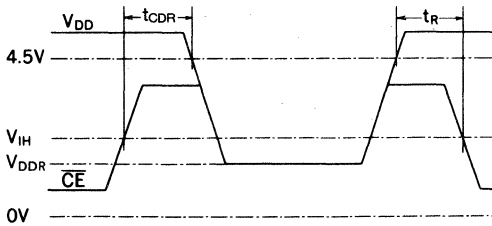
■ DATA RETENTION CHARACTERISTICS WITH LOW SUPPLY VOLTAGE

(SRM2114C<sub>25</sub>.....Ta = -40 to 85°C)  
 (SRM2114C<sub>L7</sub>.....Ta = -10 to 70°C)

Parameter	Symbol	Conditions		SRM2114C <sub>25</sub>			SRM2114C <sub>L7</sub>			Unit
		SRM2114C <sub>25</sub>	SRM2114C <sub>L7</sub>	Min	Typ	Max	Min	Typ	Max	
Data retention supply voltage	V <sub>DDR</sub>	V <sub>I</sub> = 0 or V <sub>DD</sub> , $\overline{CE} = V_{DD}$		2.0	—	5.5	2.0	—	5.0	V
Data retention supply current	I <sub>DDR</sub>	V <sub>DD</sub> = 2.0V, 25°C	V <sub>DD</sub> = 3.0V, 25°C	—	—	2	—	—	2.5	μA
$\overline{CE}$ setup time	t <sub>CDR</sub>	Refer to the figure below		0	—	—	0	—	—	ns
$\overline{CE}$ recovery time	t <sub>R</sub>			t <sub>RC</sub> *	—	—	t <sub>RC</sub> *	—	—	ns

\*t<sub>RC</sub>: Read cycle time

Data retention timing



\* When retaining data in standby mode, supply voltage can be lowered within a certain range. But read or write cycle cannot be performed while the supply voltage is low.

## FUNCTIONS

### Truth Table

$\overline{CE}$	R/ $\overline{W}$	A0 to A9	DATA I/O	MODE
H	X	X	Hi-Z	Unselected
L	L	Stable	Input data	Write
L	H	Stable	Output data	Read

X: "H" or "L"

### Reading Data

Data can be read out if an address is set while  $\overline{CE}$  is "Low", and R/ $\overline{W}$  is "High".

### Writing Data

There are the following two ways of writing data into the memory.

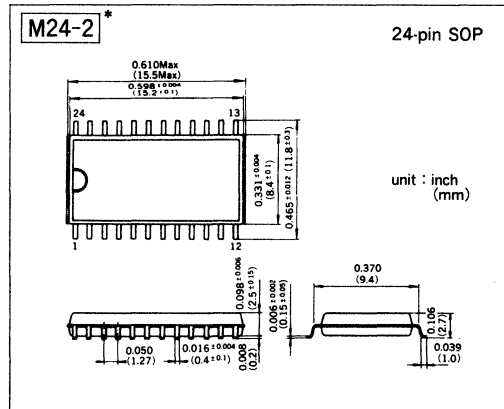
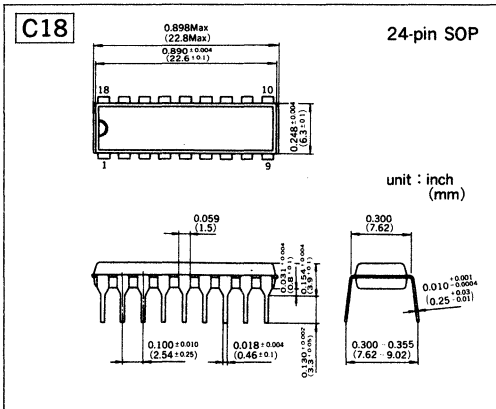
- (1) Hold  $\overline{CE}$  "L", set the address, and apply low level pulse to R/ $\overline{W}$ .
- (2) Set the address and apply Low level pulse to  $\overline{CE}$  and R/ $\overline{W}$ .

In each case, data from the DATA I/O terminal is latched at the positive transition of "L" pulse of  $\overline{CE}$  or R/ $\overline{W}$ . The DATA I/O terminal is in high-impedance state when  $\overline{CE}$  is "H" or R/ $\overline{W}$  is "L", so competition of data driver and memory output can be avoided.

### Standby Mode

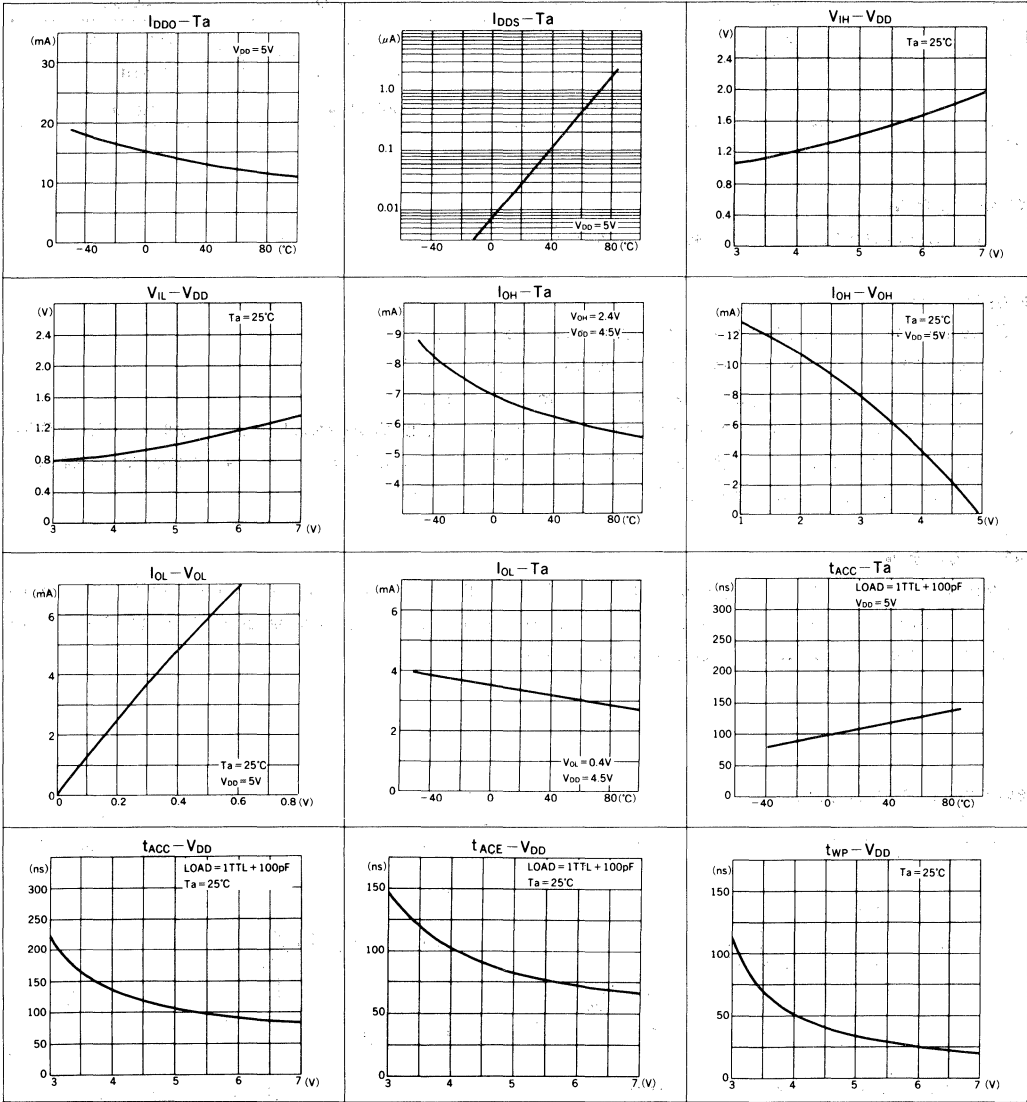
When  $\overline{CE}$  is "H", SRM2114C<sub>25/L7</sub> is in standby mode and only retains the data. In this mode, DATA I/O terminals are in high-impedance state, and all inputs of addresses, R/ $\overline{W}$ , or data can be any "H" or "L". The current flowing in the SRM2114C<sub>25/L7</sub> is only leakage current.

## PACKAGE DIMENSIONS



\*Represents model SRM2114M<sub>25/L7</sub> that has the same electrical characteristics as model SRM2114C<sub>25/L7</sub>.

# CHARACTERISTICS CURVES



# SRM2016C<sub>10/12</sub>

## CMOS 16K-BIT STATIC RAM

- **Low Supply Current**
- **Access Time 100ns/120ns**
- **2,048 Words × 8 Bits Asynchronous**

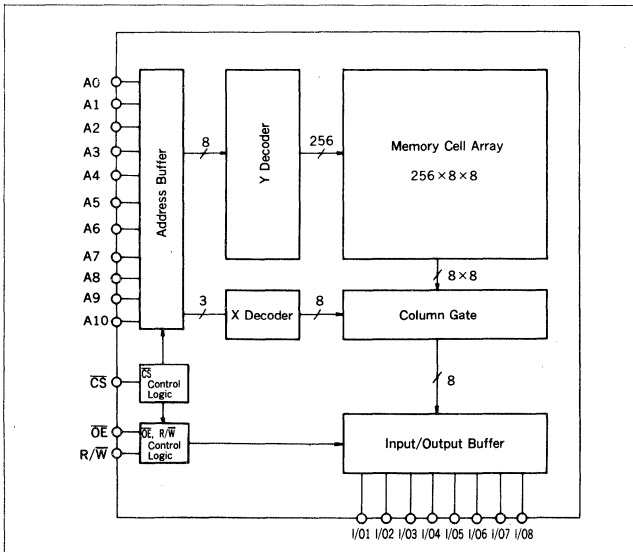
### DESCRIPTION

The SRM2016C<sub>10/12</sub> is a 2,048 words × 8 bits asynchronous, static, random access memory on a monolithic CMOS chip. Its very low standby power requirement makes it ideal for applications requiring non-volatile storage with back-up batteries. The asynchronous and static nature of the memory requires no external clock or refreshing circuit. Both the input and output ports are TTL compatible and the 3-state output allows easy expansion of memory capacity.

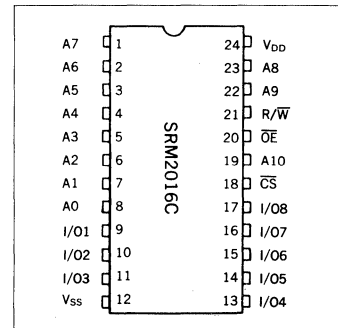
### FEATURES

- Access time .....SRM2016C<sub>10</sub> 100ns (Max)  
SRM2016C<sub>12</sub> 120ns (Max)
- Low supply current .....standby : 1 $\mu$ A (Typ)  
operation : SRM2016C<sub>10</sub> 30mA (Typ)  
SRM2016C<sub>12</sub> 25mA (Typ)
- Complete static operation
- Single power supply .....5V  $\pm$ 10%
- TTL compatible inputs and outputs
- 3-state output with wired-OR capability
- Non-volatile storage with back-up batteries
- Package .....SRM2016C<sub>10/12</sub> 24-pin DIP (plastic)  
SRM2016M<sub>10/12</sub> 24-pin SOP (plastic)  
SRM2016N<sub>10/12</sub> 24-pin Skinny DIP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A10	Address Input
R/W	Read/Write
OE	Output Enable
CS	Chip Select
I/O1 to 8	Data Input/Output
V <sub>DD</sub>	Power Supply (+5V)
V <sub>SS</sub>	Power Supply (0V)

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage*	V <sub>I</sub>	-0.5 to 7.0	V
Input/output voltage*	V <sub>I/O</sub>	-0.5 to V <sub>DD</sub> +0.3	V
Power dissipation	P <sub>D</sub>	1.0	W
Operating temperature	T <sub>opr</sub>	0 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temp. & time	T <sub>sol</sub>	260°C, 10s (at lead)	—

\*V<sub>I</sub>, V<sub>I/O</sub> = -1.0V when pulse width is 50 ns

## ■ RECOMMENDED OPERATING CONDITIONS

(Ta=0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
	V <sub>SS</sub>		0	0	0	V
Input voltage	V <sub>IH</sub>		2.2	3.5	V <sub>DD</sub> +0.3	V
	V <sub>IL</sub>		-0.3*	—	0.8	V

\*V<sub>IL</sub>(Min) = -1.0V when pulse width is 50ns

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

(V<sub>DD</sub>=5V±10%, V<sub>SS</sub>=0V, Ta=0 to 70°C)

Parameter	Symbol	Conditions	SRM2016C <sub>10</sub>			SRM2016C <sub>12</sub>			Unit
			Min	Typ*	Max	Min	Typ*	Max	
Input leakage current	I <sub>LI</sub>	V <sub>DD</sub> =5.5V, V <sub>I</sub> =0 to V <sub>DD</sub>	-1	—	1	-1	—	1	μA
Output leakage current	I <sub>LO</sub>	$\overline{CS}$ =V <sub>IH</sub> , or $\overline{OE}$ =V <sub>IH</sub> , V <sub>I/O</sub> =0 to V <sub>DD</sub>	-1	—	1	-1	—	1	μA
Operating supply current	I <sub>DDO</sub>	$\overline{CS}$ =V <sub>IL</sub> , I <sub>I/O</sub> =0mA	—	30	60	—	25	50	mA
	I <sub>DDO1</sub>	V <sub>IH</sub> =3.5V, V <sub>IL</sub> =0.6V, I <sub>I/O</sub> =0mA	—	16	—	—	16	—	mA
Average operating current	I <sub>DDA</sub>	Min. cycle, duty=100%, I <sub>I/O</sub> =0mA	—	30	60	—	25	50	mA
Standby supply current	I <sub>DDS</sub>	$\overline{CS}$ =V <sub>IH</sub>	—	1.5	3.0	—	1.5	3.0	mA
	I <sub>DDS1</sub>	$\overline{CS}$ =V <sub>DD</sub> -0.2V	—	1	50	—	1	50	μA
Output voltage	V <sub>OL</sub>	I <sub>OL</sub> =4.0mA	—	—	0.4	—	—	0.4	V
	V <sub>OH</sub>	I <sub>OH</sub> =-1.0mA	2.4	—	—	2.4	—	—	V

\* Typical values are for reference, with V<sub>DD</sub>=5V and Ta=25°C assumed

### ● Terminal Capacitance

(f=1MHz, Ta=25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input capacitance	C <sub>I</sub>	V <sub>I</sub> =0V	—	4	6	pF
I/O capacitance	C <sub>I/O</sub>	V <sub>I/O</sub> =0V	—	6	8	pF

### ● AC Electrical Characteristics

#### ○ Read Cycle

(V<sub>DD</sub>=5V±10%, V<sub>SS</sub>=0V, Ta=0 to 70°C)

Parameter	Symbol	Conditions	SRM2016C <sub>10</sub>		SRM2016C <sub>12</sub>		Unit
			Min	Max	Min	Max	
Read cycle time	t <sub>RC</sub>	*1	100	—	120	—	ns
Address access time	t <sub>ACC</sub>		—	100	—	120	ns
$\overline{CS}$ access time	t <sub>ACS</sub>		—	100	—	120	ns
$\overline{CS}$ output setup time	t <sub>CLZ</sub>	*2	10	—	10	—	ns
$\overline{OE}$ access time	t <sub>OE</sub>	*1	—	55	—	60	ns
$\overline{OE}$ output setup time	t <sub>OLZ</sub>	*2	5	—	10	—	ns
$\overline{CS}$ output floating	t <sub>CHZ</sub>		0	40	0	40	ns
$\overline{OE}$ output floating	t <sub>OHZ</sub>		0	40	0	40	ns
Output hold time	t <sub>OH</sub>		*1	10	—	10	—

○ Write Cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=0$  to  $70^\circ C$ )

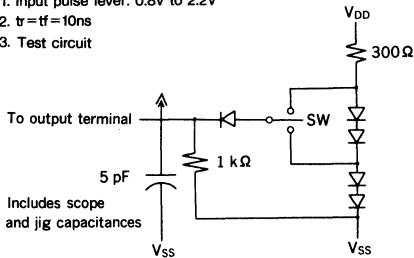
Parameter	Symbol	Conditions	SRM2016C <sub>10</sub>		SRM2016C <sub>12</sub>		Unit
			Min	Max	Min	Max	
Write cycle time	$t_{WC}$	*1	100	—	120	—	ns
Chip select time (CS)	$t_{CW}$		80	—	85	—	ns
Address enable time	$t_{AW}$		80	—	85	—	ns
Address setup time	$t_{AS}$		0	—	0	—	ns
Write pulse width	$t_{WP}$		65	—	70	—	ns
$\overline{OE}$ output floating	$t_{OHZ}$	*2	0	40	0	40	ns
R/ $\overline{W}$ output floating	$t_{WHZ}$	*3	0	45	0	50	ns
Input data setup time	$t_{DW}$	*1	45	—	50	—	ns
Address hold time	$t_{WR}$		5	—	5	—	ns
Input data hold time	$t_{DH}$		0	—	0	—	ns
R/ $\overline{W}$ output setup time	$t_{OW}$	*3	5	—	10	—	ns

\*1 Test conditions.

1. Input pulse level: 0.8V to 2.2V
2.  $t_r = t_f = 10ns$
3. Input/output timing reference level: 1.5V
4. Output load:  $I_{TL} + C_L = 100pF$

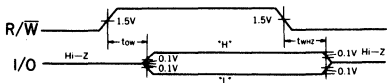
\*3 Test conditions.

1. Input pulse level: 0.8V to 2.2V
2.  $t_r = t_f = 10ns$
3. Test circuit



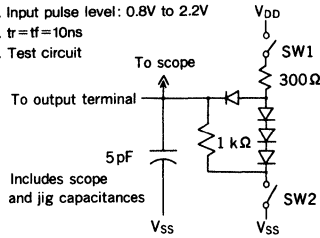
- SW is set to the  $V_{DD}$  side when measuring Hi-z-high and high-Hi-z of  $t_{OW}$  or  $t_{WHZ}$ .
- SW is set to the  $V_{SS}$  side when measuring Hi-z-low and low-Hi-z of  $t_{OW}$  or  $t_{WHZ}$ .

Output turn-on turn-off times



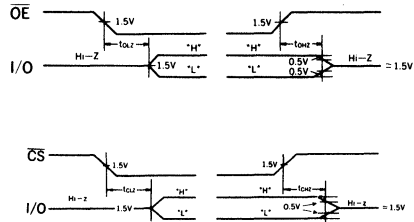
\*2 Test conditions.

1. Input pulse level: 0.8V to 2.2V
2.  $t_r = t_f = 10ns$
3. Test circuit



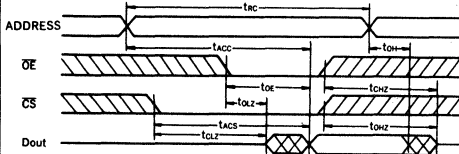
- Both SW1 and SW2 are closed when measuring  $t_{OHZ}$  or  $t_{WHZ}$ .
- SW1 is open and SW2 is closed when measuring Hi-z-high of  $t_{OZ}$  or  $t_{OZ}$ .
- SW1 is closed and SW2 is open when measuring Hi-z-low of  $t_{OZ}$  or  $t_{OZ}$ .

Output turn-on turn-off times

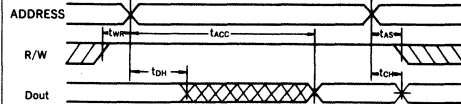


● Timing Chart

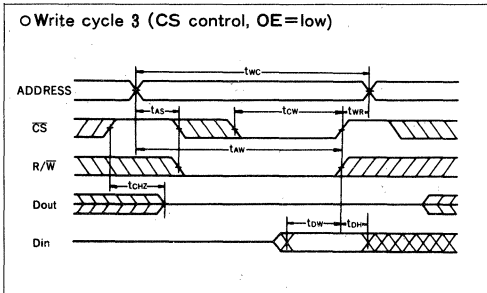
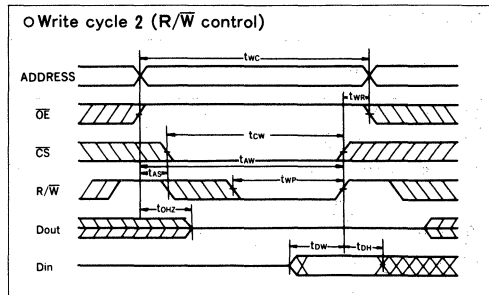
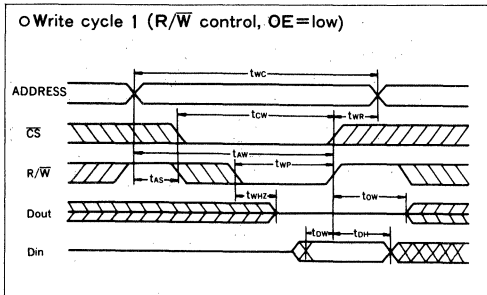
○ Read cycle 1 ( $\overline{OE}$ , CS control, R/ $\overline{W}$ =high)



○ Read cycle 2 (R/ $\overline{W}$  control,  $\overline{OE}$ =low, CS=low)







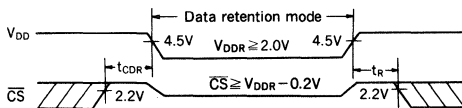
■ DATA RETENTION CHARACTERISTICS WITH LOW VOLTAGE POWER SUPPLY

( $T_a = 0$  to  $70^\circ\text{C}$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Data retention supply voltage	$V_{DD}$	$\overline{CS} \geq V_{DD} - 0.2\text{V}$	2.0	—	5.5	V
Data retention current	$I_{DDR}$	$V_{DD} = 3.0\text{V}$ , $\overline{CS} \geq 2.8\text{V}$	—	—	25	$\mu\text{A}$
Chip select data hold time	$t_{CDR}$	Refer to the figure below.	0	—	—	ns
Operation recovery time	$t_R$		$t_{RC}^*$	—	—	ns

\*  $t_{RC}$  : read cycle time

■ Data retention timing



**Note:** When retaining data in standby mode, supply voltage can be lowered within a certain range. Read or write cycle cannot be performed while the supply voltage is low.

■ FUNCTIONS

● Truth Table

CS	OE	R/W	A0 to A10	DATA I/O	Mode	$I_{DD}$
H	—	—	—	Hi-Z	Unselected	$I_{DDs}$ , $I_{DDs1}$
L	L	H	Stable	Output data	Read	$I_{DD0}$
L	H	L	Stable	Input data	Write	$I_{DD0}$
L	L	L	Stable	Input data	Write	$I_{DD0}$

X: "H" or "L" —: "H", "L" or "Hi"

● Reading Data

Data can be read out if an address is set while  $\overline{CS}$  and  $\overline{OE}$  are held low, and R/W is held high.

## ● Writing Data

There are the following three ways of writing data into the memory.

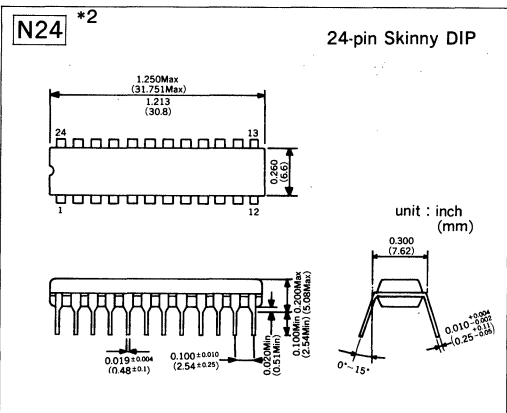
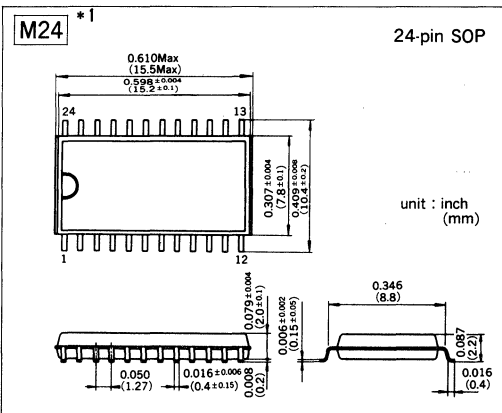
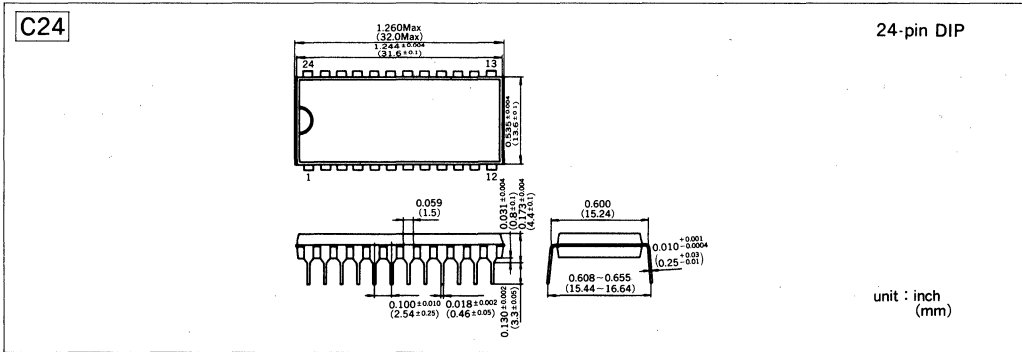
- (1) Hold  $\overline{CS}$  low, set the address, and apply a low pulse to  $R/\overline{W}$ .
- (2) Hold  $R/\overline{W}$  low, set the address, and apply a low pulse to  $\overline{CS}$ .
- (3) Set the address, then apply low pulses to both  $\overline{CS}$  and  $R/\overline{W}$ .

In each case, data from the DATA I/O terminal is fetched into the SRM2016C<sub>10/12</sub> at the last transition of a section in which both  $\overline{CS}$  and  $R/\overline{W}$  are low. Because the DATA I/O terminal is in high-impedance state when  $\overline{CS}$  or  $\overline{OE}$  is high, or  $R/\overline{W}$  is low, contention of the data driver on the bus and memory output is avoided.

## ● Standby Mode

When  $\overline{CS}$  is high, SRM2016C<sub>10/12</sub> is in the stand-by mode and only retains the data. At this time the DATA I/O terminal is in high-impedance state and input of an address,  $R/\overline{W}$  signal, or data is prohibited. When  $\overline{CS}$  is above  $V_{DD}-0.2V$ , current flowing within the SRM2016C<sub>10/12</sub> chip is only that in the high-resistance portion of the memory cells and leakage current.

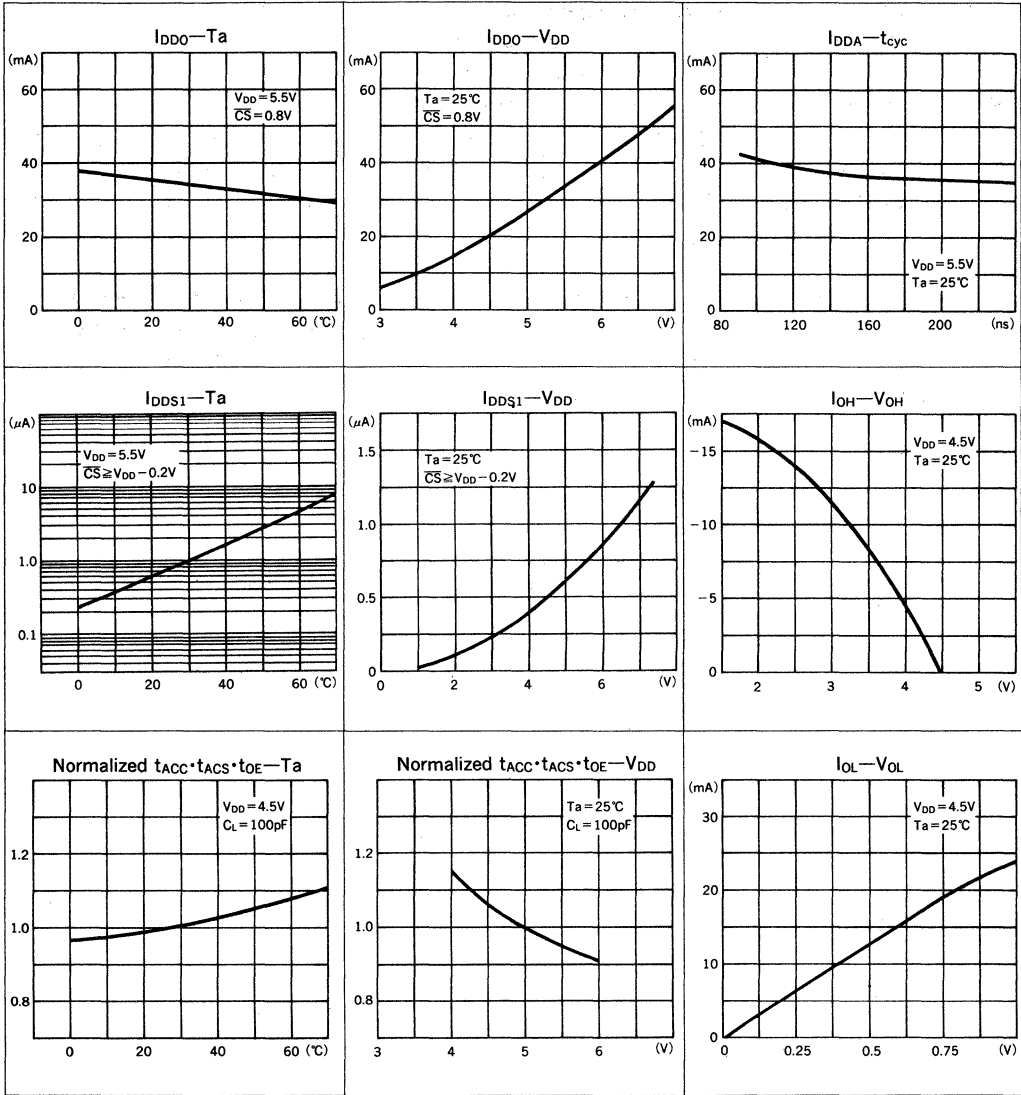
## ■ PACKAGE DIMENSIONS



\*1 Represents model SRM2016M<sub>10/12</sub> that has the same electrical characteristics as model SRM2016C<sub>10/12</sub>.

\*2 Represents model SRM2016N<sub>10/12</sub> that has the same electrical characteristics as model SRM2016C<sub>10/12</sub>.

# CHARACTERISTICS CURVES



# SRM2017C<sub>10/12</sub>

## CMOS 16K-BIT STATIC RAM

- Low Supply Current
- Access Time 100ns/120ns
- 2,048 Words × 8 Bits Asynchronous

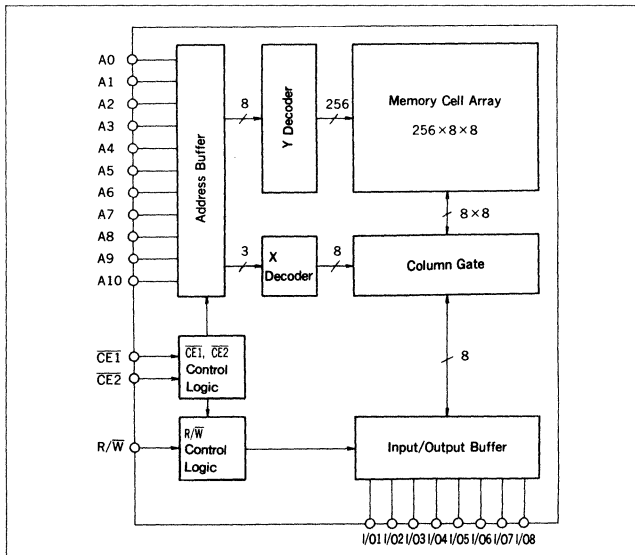
### DESCRIPTION

The SRM2017C<sub>10/12</sub> is a 2,048 words × 8 bits asynchronous, static, random access memory on a monolithic CMOS chip. Its very low standby power requirement makes it ideal for applications requiring non-volatile storage with back-up batteries. The asynchronous and static nature of the memory requires no external clock or refreshing circuit. Both the input and output ports are TTL compatible and the 3-state output allows easy expansion of memory capacity.

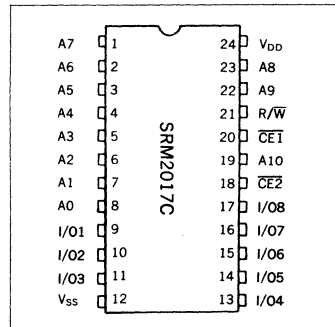
### FEATURES

- Access time ..... SRM2017C<sub>10</sub> 100ns (Max)  
SRM2017C<sub>12</sub> 120ns (Max)
- Low supply current ..... standby : 1μA (Typ)  
operation : SRM2017C<sub>10</sub> 30mA (Typ)  
SRM2017C<sub>12</sub> 25mA (Typ)
- Complete static operation
- Single power supply ..... 5V ± 10%
- TTL compatible inputs and outputs
- 3-state output with wired-OR capability
- Non-volatile storage with back-up batteries
- Package ..... SRM2017C<sub>10/12</sub> 24-pin DIP (plastic)  
SRM2017M<sub>10/12</sub> 24-pin SOP (plastic)  
SRM2017N<sub>10/12</sub> 24-pin Skinny DIP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A10	Address Input
R/W	Read/Write
CE1	Chip Enable 1
CE2	Chip Enable 2
I/O1 to 8	Data Input/Output
VDD	Power Supply (+5V)
Vss	Power Supply (0V)

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage*	V <sub>I</sub>	-0.5 to 7.0	V
Input/output voltage*	V <sub>I/O</sub>	-0.5 to V <sub>DD</sub> +0.3	V
Power dissipation	P <sub>D</sub>	1.0	W
Operating temperature	T <sub>opr</sub>	0 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temp. & time	T <sub>sol</sub>	260°C, 10s (at lead)	—

\*V<sub>I</sub>, V<sub>I/O</sub> = -1.0V when pulse width is 50 ns

## ■ RECOMMENDED OPERATING CONDITIONS

(T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
	V <sub>SS</sub>		0	0	0	V
Input voltage	V <sub>IH</sub>		2.2	3.5	V <sub>DD</sub> +0.3	V
	V <sub>IL</sub>		-0.3*	—	0.8	V

\*V<sub>IL</sub>(Min) = -1.0V when pulse width is 50ns

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	SRM2017C <sub>10</sub>			SRM2017C <sub>12</sub>			Unit
			Min	Typ*	Max	Min	Typ*	Max	
Input leakage current	I <sub>LI</sub>	V <sub>DD</sub> = 5.5V, V <sub>I</sub> = 0 to V <sub>DD</sub>	-1	—	1	-1	—	1	μA
Output leakage current	I <sub>LO</sub>	CE1 or CE2 = V <sub>IH</sub> , V <sub>I/O</sub> = 0 to V <sub>DD</sub>	-1	—	1	-1	—	1	μA
Operating supply current	I <sub>DDO</sub>	CE2 = V <sub>IL</sub> , I <sub>I/O</sub> = 0mA	—	30	60	—	25	50	mA
	I <sub>DDO1</sub>	V <sub>IH</sub> = 3.5V, V <sub>IL</sub> = 0.6V, I <sub>I/O</sub> = 0mA	—	16	—	—	16	—	mA
Average operating current	I <sub>DDA</sub>	Min. cycle, duty = 100%, I <sub>I/O</sub> = 0mA	—	30	60	—	25	50	mA
Standby supply current	I <sub>DDS</sub>	CE2 = V <sub>IH</sub>	—	1.5	3.0	—	1.5	3.0	mA
	I <sub>DDs1</sub>	CE2 = V <sub>DD</sub> - 0.2V	—	1	50	—	1	50	μA
Output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 4.0mA	—	—	0.4	—	—	0.4	V
	V <sub>OH</sub>	I <sub>OH</sub> = -1.0mA	2.4	—	—	2.4	—	—	V

\*Typical values are for reference, with V<sub>DD</sub> = 5V and T<sub>a</sub> = 25°C assumed.

### ● Terminal Capacitance

(f = 1MHz, T<sub>a</sub> = 25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input capacitance	C <sub>I</sub>	V <sub>I</sub> = 0V	—	4	6	pF
I/O capacitance	C <sub>I/O</sub>	V <sub>I/O</sub> = 0V	—	6	8	pF

### ● AC Electrical Characteristics

#### ○ Read Cycle

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	SRM2017C <sub>10</sub>		SRM2017C <sub>12</sub>		Unit
			Min	Max	Min	Max	
Read cycle time	t <sub>RC</sub>	*1	100	—	120	—	ns
Address access time	t <sub>ACC</sub>		—	100	—	120	ns
CE1 access time	t <sub>ACE1</sub>		—	55	—	55	ns
CE2 access time	t <sub>ACE2</sub>		—	100	—	120	ns
CE1 output setup time	t <sub>CLZ1</sub>	*2	10	—	10	—	ns
CE1 output floating	t <sub>CHZ1</sub>		0	40	0	40	ns
CE2 output setup time	t <sub>CLZ2</sub>		10	—	10	—	ns
CE2 output floating	t <sub>CHZ2</sub>		0	40	0	40	ns
Output hold time	t <sub>OH</sub>	*1	10	—	10	—	ns

○ Write Cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=0$  to  $70^\circ C$ )

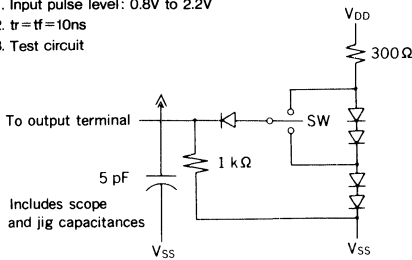
Parameter	Symbol	Conditions	SRM2017C <sub>10</sub>		SRM2017C <sub>12</sub>		Unit
			Min	Max	Min	Max	
Write cycle time	$t_{WC}$	* 1	100	—	120	—	ns
Chip select time ( $\overline{CE1}$ )	$t_{CW1}$		80	—	85	—	ns
Chip select time ( $\overline{CE2}$ )	$t_{CW2}$		80	—	85	—	ns
Address enable time	$t_{AW}$		80	—	85	—	ns
Address setup time	$t_{AS}$		0	—	0	—	ns
Write pulse width	$t_{WP}$		65	—	70	—	ns
Input data setup time	$t_{DW}$		45	—	50	—	ns
Address hold time	$t_{WR}$		5	—	5	—	ns
Input data hold time	$t_{DH}$		0	—	0	—	ns
R/W output setup time	$t_{OW}$		* 3	5	—	10	—
R/W output floating	$t_{WHZ}$	0		45	0	50	ns

\*1 Test conditions.

1. Input pulse level: 0.8V to 2.2V
2.  $t_r = t_f = 10ns$
3. Input/output timing reference level: 1.5V
4. Output load:  $I_{TL} + C_L = 100pF$

\*3 Test conditions.

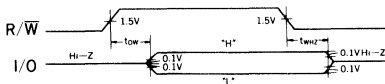
1. Input pulse level: 0.8V to 2.2V
2.  $t_r = t_f = 10ns$
3. Test circuit



○ SW is set to the  $V_{DD}$  side when measuring Hi-z-high and high-Hi-z of  $t_{OW}$  or  $t_{WHZ}$ .

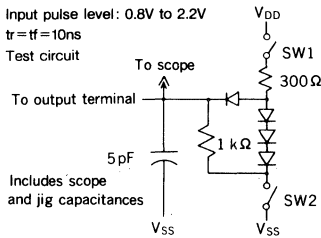
○ SW is set to the  $V_{SS}$  side when measuring Hi-z-low and low-Hi-z of  $t_{OW}$  or  $t_{WHZ}$ .

Output turn-on turn-off times



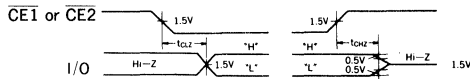
\*2 Test conditions.

1. Input pulse level: 0.8V to 2.2V
2.  $t_r = t_f = 10ns$
3. Test circuit



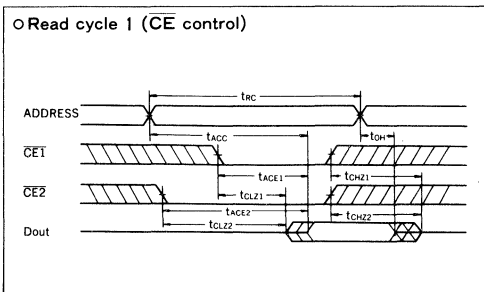
- Both SW1 and SW2 are closed when measuring  $t_{CHZ}$  or  $t_{OHZ}$ .
- SW1 is open and SW2 is closed when measuring Hi-z-high of  $t_{OZ}$  or  $t_{LZ}$ .
- SW1 is closed and SW2 is open when measuring Hi-z-low of  $t_{OZ}$  or  $t_{LZ}$ .

Output turn-on turn-off times

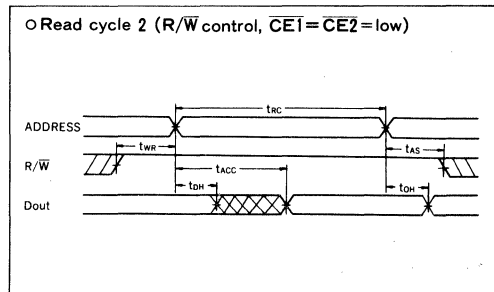


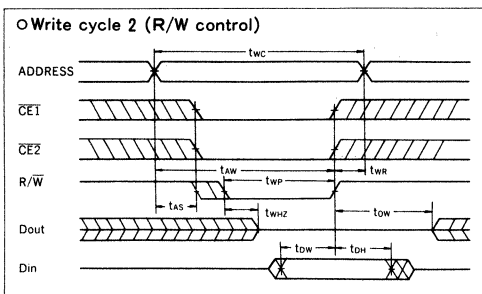
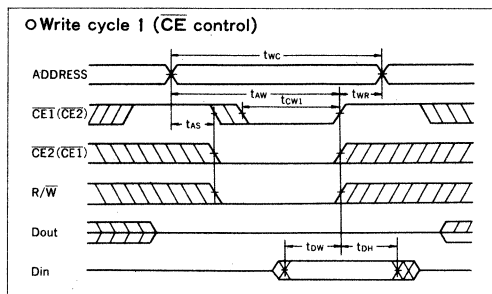
● Timing Chart

○ Read cycle 1 ( $\overline{CE}$  control)



○ Read cycle 2 ( $\overline{R/W}$  control,  $\overline{CE1} = \overline{CE2} = \text{low}$ )





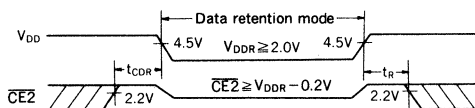
**DATA RETENTION CHARACTERISTICS WITH LOW SUPPLY VOLTAGE**

( $T_a = 0$  to  $70^\circ\text{C}$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Data retention supply voltage	$V_{\text{DDR}}$	$\overline{\text{CE2}} \geq V_{\text{DDR}} - 0.2\text{V}$	2.0	—	5.5	V
Data retention current	$I_{\text{DDR}}$	$V_{\text{DD}} = 3.0\text{V}, \overline{\text{CE2}} \geq 2.8\text{V}$	—	—	25	$\mu\text{A}$
Chip select data hold time	$t_{\text{CDR}}$	Refer to the figure below.	0	—	—	ns
Operation recovery time	$t_{\text{R}}$		$t_{\text{RC}}^*$	—	—	ns

\*  $t_{\text{RC}}$ : read cycle time

**Data retention timing**



**Note:** When retaining data in the stand-by mode, supply voltage can be lowered within a certain range. Read or write cycle cannot be performed while the supply voltage is low.

**FUNCTIONS**

**Truth Table**

CE1	CE2	R/W	A0 to A10	DATA I/O	Mode	$I_{\text{DD}}$
—	H	—	—	Hi-Z	Unselected	$I_{\text{DDs}}, I_{\text{DDs1}}$
H	L	X	X	Hi-Z	Unselected	$I_{\text{DD0}}$
L	L	H	Stable	Output data	Read	$I_{\text{DD0}}$
L	L	L	Stable	Input data	Write	$I_{\text{DD0}}$

X: "H" or "L" —: "H", "L" or "Hi-Z"

**Reading Data**

Data can be read out if an address is set while  $\overline{\text{CE1}}$  is held low, and  $\overline{\text{R/W}}$  is held high.

## ● Writing Data

There are the following three ways of writing data into the memory.

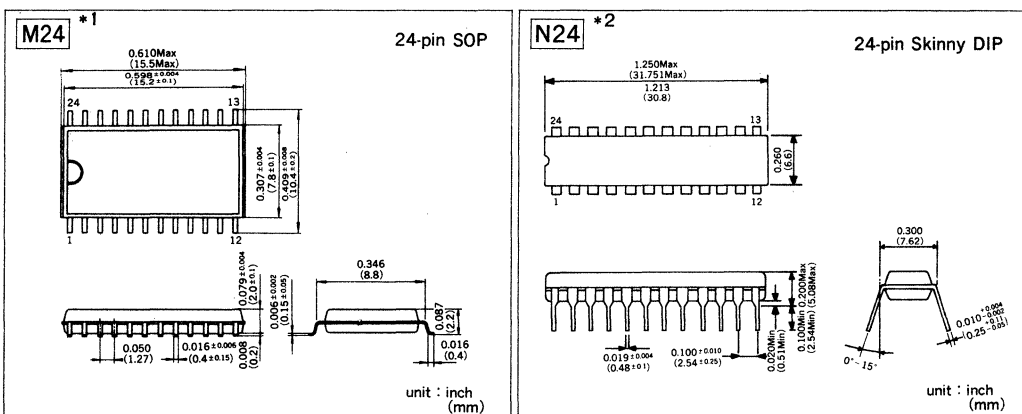
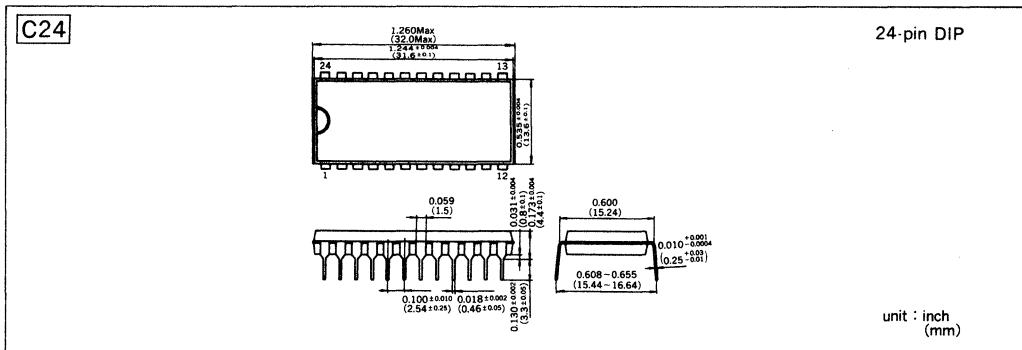
- (1) Hold  $\overline{CE1}$  and  $\overline{CE2}$  low, set the address, and apply a low pulse to  $R/\overline{W}$ .
- (2) Hold  $R/\overline{W}$  low and hold  $\overline{CE1}$  or  $\overline{CE2}$  low, set the address, and apply a low pulse to  $\overline{CE2}$  or  $\overline{CE1}$ .
- (3) Set the address, then apply low pulses to  $\overline{CE1}$ ,  $\overline{CE2}$ , and  $R/\overline{W}$ .

In each case, data from the DATA I/O terminal is fetched into the SRM2017C<sub>10/12</sub> at the last transition of a section in which  $\overline{CE1}$ ,  $\overline{CE2}$ , and  $R/\overline{W}$  are low. Because the DATA I/O terminal is in high-impedance state when both  $\overline{CE1}$  and  $\overline{CE2}$  are high or  $R/\overline{W}$  is low, competition of data driver and memory output is avoided.

## ● Standby Mode

When  $\overline{CE2}$  is high, SRM2017C<sub>10/12</sub> is in the stand-by mode and only retains the data. At this time the DATA I/O terminal is in high-impedance state and input of an address,  $R/\overline{W}$  signal, or data is prohibited. When  $\overline{CE2}$  is above  $V_{DD}-0.2V$ , current flowing within the SRM2017C<sub>10/12</sub> chip is only that in the high-resistance portion of the memory cells and leakage current.

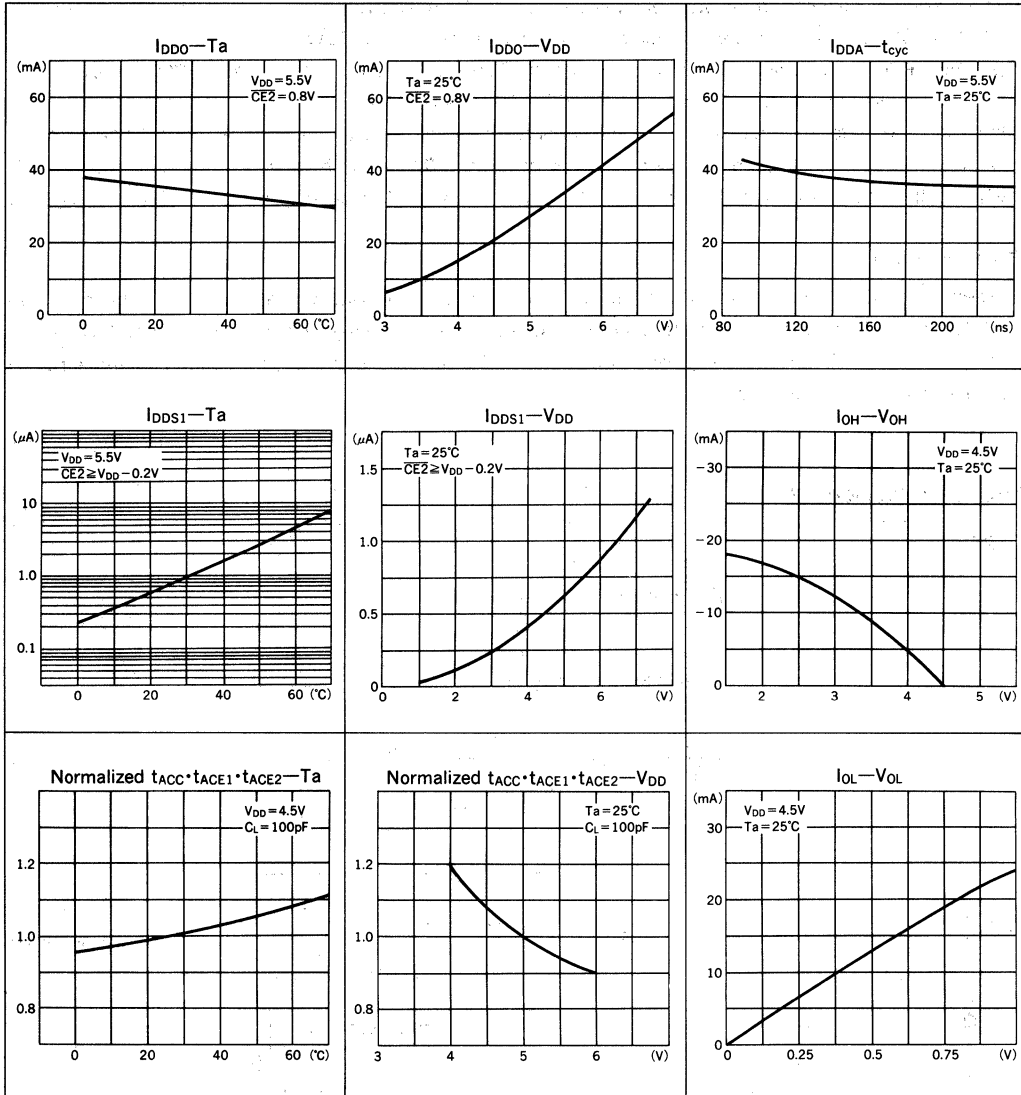
## ■ PACKAGE DIMENSIONS



- \*1 Represents model SRM2017M<sub>10/12</sub> that has the same electrical characteristics as model SRM2017C<sub>10/12</sub>.  
 \*2 Represents model SRM2017N<sub>10/12</sub> that has the same electrical characteristics as model SRM2017C<sub>10/12</sub>.



# CHARACTERISTICS CURVES



# SRM2018C<sub>10/12</sub>

## CMOS 16K-BIT STATIC RAM

- Low Supply Current
- Access Time 100ns/120ns
- 2,048 Words × 8 Bits Asynchronous

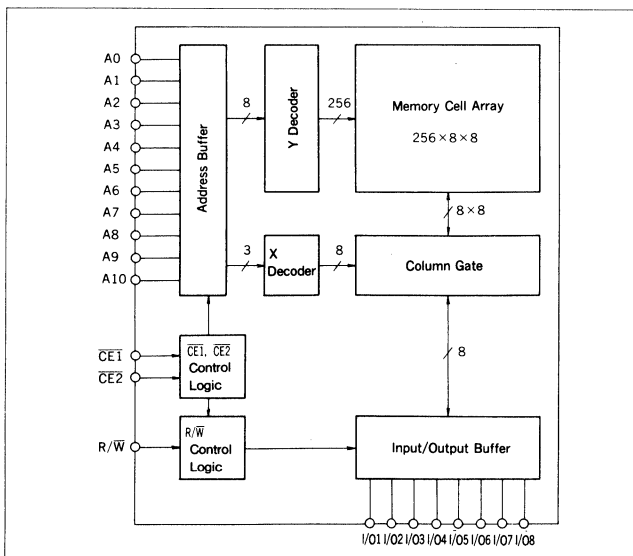
### DESCRIPTION

The SRM2018C<sub>10/12</sub> is a 2,048 words × 8 bits asynchronous, static, random access memory on a monolithic CMOS chip. Its very low standby power requirement makes it ideal for applications requiring non-volatile storage with back-up batteries. The asynchronous and static nature of the memory requires no external clock or refreshing circuit. Both the input and output ports are TTL compatible and the 3-state output allows easy expansion of memory capacity.

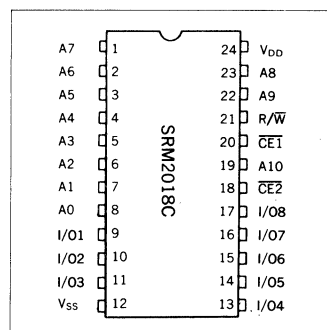
### FEATURES

- Access time ..... SRM2018C<sub>10</sub> 100ns (Max)  
SRM2018C<sub>12</sub> 120ns (Max)
- Low supply current ..... standby : 1μA (Typ)  
operation : SRM2018C<sub>10</sub> 30mA (Typ)  
SRM2018C<sub>12</sub> 25mA (Typ)
- Complete static operation
- Single power supply ..... 5V ± 10%
- TTL compatible inputs and outputs
- 3-state output with wired-OR capability
- Non-volatile storage with back-up batteries
- Package ..... SRM2018C<sub>10/12</sub> 24-pin DIP (plastic)  
SRM2018M<sub>10/12</sub> 24-pin SOP (plastic)  
SRM2018N<sub>10/12</sub> 24-pin Skinny DIP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A10	Address Input
R/W	Read/Write
CE1	Chip Enable 1
CE2	Chip Enable 2
I/O1 to 8	Data Input/Output
VDD	Power Supply (+5V)
Vss	Power Supply (0V)

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage*	V <sub>I</sub>	-0.5 to 7.0	V
Input/output voltage*	V <sub>I/O</sub>	-0.5 to V <sub>DD</sub> +0.3	V
Power dissipation	P <sub>D</sub>	1.0	W
Operating temperature	T <sub>opr</sub>	0 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temp. & time	T <sub>sol</sub>	260°C, 10s (at lead)	—

\*V<sub>I</sub>, V<sub>I/O</sub> = -1.0V when pulse width is 50ns

## ■ RECOMMENDED OPERATING CONDITIONS

(T<sub>a</sub>=0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
	V <sub>SS</sub>		0	0	0	V
Input voltage	V <sub>IH</sub>		2.2	3.5	V <sub>DD</sub> +0.3	V
	V <sub>IL</sub>		-0.3*	—	0.8	V

\*V<sub>IL</sub>(Min) = -1.0V when pulse width is 50ns

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

(V<sub>DD</sub>=5V±10%, V<sub>SS</sub>=0V, T<sub>a</sub>=0 to 70°C)

Parameter	Symbol	Conditions	SRM2018C <sub>10</sub>			SRM2018C <sub>12</sub>			Unit
			Min	Typ <sup>†</sup>	Max	Min	Typ <sup>†</sup>	Max	
Input leakage current	I <sub>LI</sub>	V <sub>DD</sub> =5.5V, V <sub>I</sub> =0 to V <sub>DD</sub>	-1	—	1	-1	—	1	μA
Output leakage current	I <sub>LO</sub>	CE1 or CE2=V <sub>IH</sub> , V <sub>I/O</sub> =0 to V <sub>DD</sub>	-1	—	1	-1	—	1	μA
Operating supply current	I <sub>DDO</sub>	CE1 and CE2=V <sub>IL</sub> , I <sub>I/O</sub> =0mA	—	30	60	—	25	50	mA
	I <sub>DDO1</sub>	V <sub>IH</sub> =3.5V, V <sub>IL</sub> =0.6V, I <sub>I/O</sub> =0mA	—	16	—	—	16	—	mA
Average operating current	I <sub>DDA</sub>	Min. cycle, duty=100%, I <sub>I/O</sub> =0mA	—	30	60	—	25	50	mA
Standby supply current	I <sub>DDS</sub>	CE1 or CE2=V <sub>IH</sub>	—	1.5	3.0	—	1.5	3.0	mA
	I <sub>DDS1</sub>	CE1 or CE2=V <sub>DD</sub> -0.2V *2	—	1	50	—	1	50	μA
Output voltage	V <sub>OL</sub>	I <sub>OL</sub> =4.0mA	—	—	0.4	—	—	0.4	V
	V <sub>OH</sub>	I <sub>OH</sub> =-1.0mA	2.4	—	—	2.4	—	—	V

\*1 Typical values are for reference, with V<sub>DD</sub>=5V and T<sub>a</sub>=25°C assumed.

\*2 CE1=V<sub>DD</sub>-0.2V and CE2=0.2V or V<sub>DD</sub>-0.2V, CE2=V<sub>DD</sub>-0.2V and CE1=0.2V or V<sub>DD</sub>-0.2V

### ● Terminal Capacitance

(f=1MHz, T<sub>a</sub>=25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input capacitance	C <sub>I</sub>	V <sub>I</sub> =0V	—	4	6	pF
I/O capacitance	C <sub>I/O</sub>	V <sub>I/O</sub> =0V	—	6	8	pF

### ● AC Electrical Characteristics

#### ○ Read Cycle

(V<sub>DD</sub>=5V±10%, V<sub>SS</sub>=0V, T<sub>a</sub>=0 to 70°C)

Parameter	Symbol	Conditions	SRM2018C <sub>10</sub>		SRM2018C <sub>12</sub>		Unit
			Min	Max	Min	Max	
Read cycle time	t <sub>RC</sub>	*1	100	—	120	—	ns
Address access time	t <sub>ACC</sub>		—	100	—	120	ns
CE1 access time	t <sub>ACE1</sub>		—	100	—	120	ns
CE2 access time	t <sub>ACE2</sub>		—	100	—	120	ns
CE1 output setup time	t <sub>CLZ1</sub>	*2	10	—	10	—	ns
CE1 output floating	t <sub>CHZ1</sub>		0	40	0	40	ns
CE2 output setup time	t <sub>CLZ2</sub>		10	—	10	—	ns
CE2 output floating	t <sub>CHZ2</sub>		0	40	0	40	ns
Output hold time	t <sub>OH</sub>	*1	10	—	10	—	ns

○ Write Cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=0$  to  $70^\circ C$ )

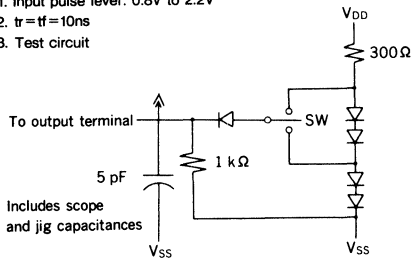
Parameter	Symbol	Conditions	SRM2018C <sub>10</sub>		SRM2018C <sub>12</sub>		Unit
			Min	Max	Min	Max	
Write cycle time	$t_{WC}$	* 1	100	—	120	—	ns
Chip select time (CE1)	$t_{CW1}$		80	—	85	—	ns
Chip select time (CE2)	$t_{CW2}$		80	—	85	—	ns
Address enable time	$t_{AW}$		80	—	85	—	ns
Address setup time	$t_{AS}$		0	—	0	—	ns
Write pulse width	$t_{WP}$		65	—	70	—	ns
Input data setup time	$t_{DW}$		45	—	50	—	ns
Address hold time	$t_{WR}$		5	—	5	—	ns
Input data hold time	$t_{DH}$		0	—	0	—	ns
R/ $\bar{W}$ output setup time	$t_{OW}$	* 3	5	—	10	—	ns
R/ $\bar{W}$ output floating	$t_{WHZ}$		0	45	0	50	ns

\* 1 Test conditions.

1. Input pulse level: 0.8V to 2.2V
2.  $t_r=t_f=10ns$
3. Input/output timing reference level: 1.5V
4. Output load:  $1mL+CL=100pF$

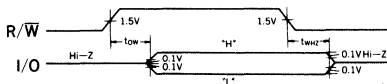
\* 3 Test conditions.

1. Input pulse level: 0.8V to 2.2V
2.  $t_r=t_f=10ns$
3. Test circuit



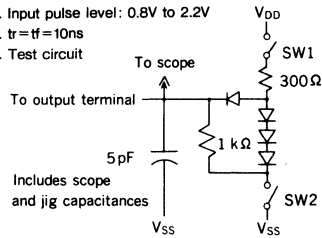
- SW is set to the  $V_{DD}$  side when measuring Hi-z-high and high-Hi-z of  $t_{ow}$  or  $t_{whz}$ .
- SW is set to the  $V_{SS}$  side when measuring Hi-z-low and low-Hi-z of  $t_{ow}$  or  $t_{whz}$ .

Output turn-on turn-off times



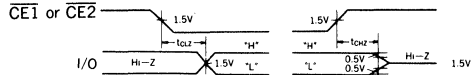
\* 2 Test conditions.

1. Input pulse level: 0.8V to 2.2V
2.  $t_r=t_f=10ns$
3. Test circuit



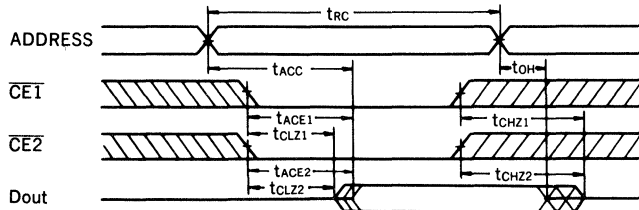
- Both SW1 and SW2 are closed when measuring  $t_{chz}$  or  $t_{ohz}$ .
- SW1 is open and SW2 is closed when measuring Hi-z-high of  $t_{oz}$  or  $t_{oz}$ .
- SW1 is closed and SW2 is open when measuring Hi-z-low of  $t_{oz}$  or  $t_{oz}$ .

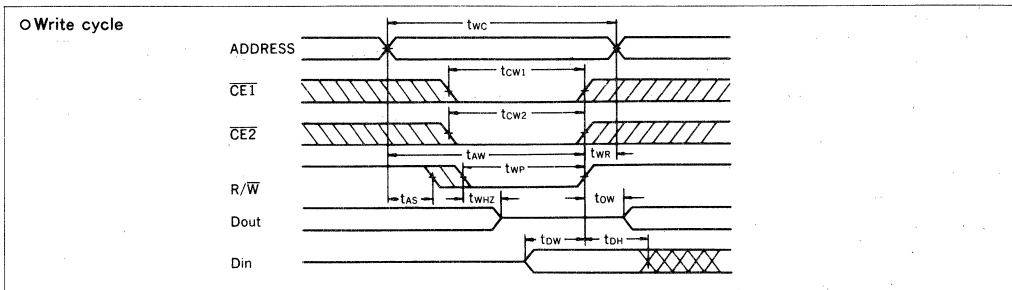
Output turn-on turn-off times



● Timing Chart

○ Read cycle





### ■ DATA RETENTION CHARACTERISTICS WITH LOW VOLTAGE POWER SUPPLY

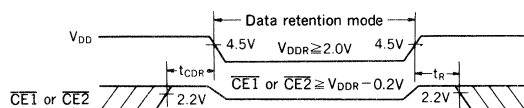
( $T_a = 0$  to  $70^\circ\text{C}$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Data retention supply voltage	$V_{DDR}$	$\overline{\text{CE1}}$ or $\overline{\text{CE2}} \geq V_{DDR} - 0.2\text{V}$	2.0	—	5.5	V
Data retention current	$I_{DDR}$	$V_{DD} = 3.0\text{V}$ , $\overline{\text{CE1}}$ or $\overline{\text{CE2}} \geq 2.8\text{V}^{*2}$	—	—	25	$\mu\text{A}$
Chip select data hold time	$t_{CDR}$	Refer to the figure below.	0	—	—	ns
Operation recovery time	$t_R$		$t_{RC}^{*1}$	—	—	ns

\*1  $t_{RC}$ : read cycle time

\*2  $\overline{\text{CE1}} \geq 2.8\text{V}$  and  $\overline{\text{CE2}} \geq 2.8\text{V}$  or  $\overline{\text{CE2}} \leq 0.2\text{V}$ ,  $\overline{\text{CE2}} \geq 2.8\text{V}$  and  $\overline{\text{CE1}} \geq 2.8\text{V}$  or  $\overline{\text{CE1}} \leq 0.2\text{V}$

### Data retention timing



**Note:** When retaining data in the stand-by mode, supply voltage can be lowered within a certain range. Read or write cycle cannot be performed while the supply voltage is low.

### ■ FUNCTIONS

#### ● Truth Table

$\overline{\text{CE1}}$	$\overline{\text{CE2}}$	R/W	A0 to A10	DATA I/O	Mode	$I_{DD}$
H	X	—	—	Hi-Z	Unselected	$I_{DDs}$ , $I_{DDs1}$
X	H	—	—	Hi-Z	Unselected	$I_{DDs}$ , $I_{DDs1}$
L	L	H	Stable	Output data	Read	$I_{DDo}$
L	L	L	Stable	Input data	Write	$I_{DDo}$

X: "H" or "L", —: "H", "L" or "Hi-Z"

#### ● Reading Data

Data can be read out if an address is set while  $\overline{\text{CE1}}$  and  $\overline{\text{CE2}}$  are held low and  $\overline{\text{R/W}}$  is held high.

## ● Writing Data

There are the following three ways of writing data into the memory.

- (1) Hold  $\overline{CE1}$  and  $\overline{CE2}$  low, set the address, and apply a low pulse to  $R/\overline{W}$ .
- (2) Hold  $R/\overline{W}$  low and hold  $\overline{CE1}$  or  $\overline{CE2}$  low, set the address, and apply a low pulse to  $\overline{CE2}$  or  $\overline{CE1}$ .
- (3) Set the address, then apply low pulses to  $\overline{CE1}$ ,  $\overline{CE2}$ , and  $R/\overline{W}$ .

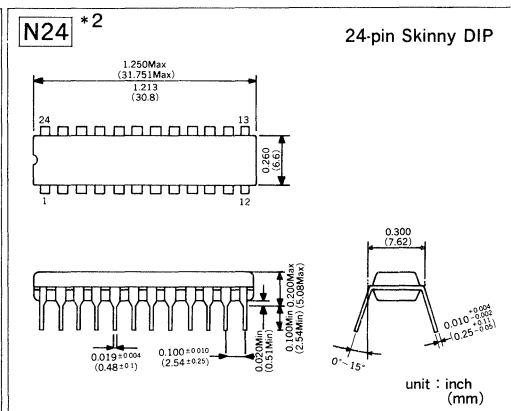
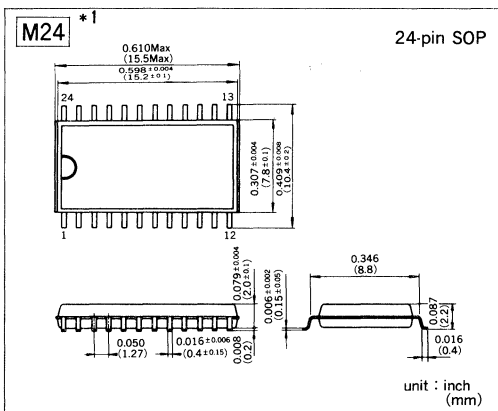
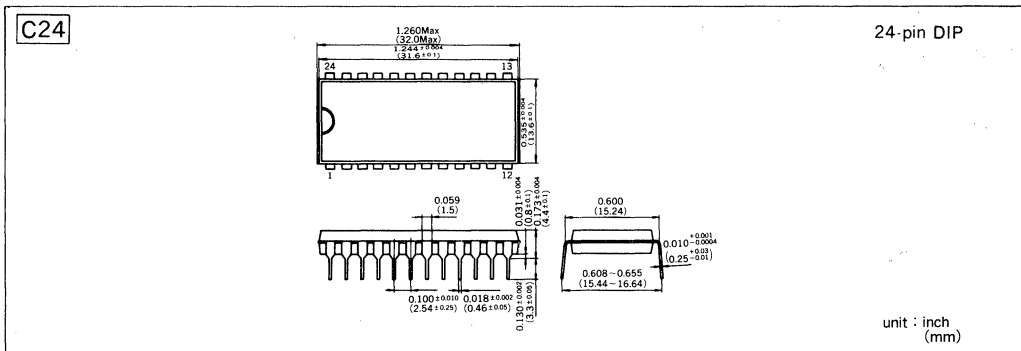
In each case, data from the DATA I/O terminal is fetched into the SRM2018C<sub>10/12</sub> at the last transition of a section in which  $\overline{CE1}$ ,  $\overline{CE2}$ , and  $R/\overline{W}$  are low. Because the DATA I/O terminal is in high-impedance state when both  $\overline{CE1}$  and  $\overline{CE2}$  are high or  $R/\overline{W}$  is low, competition of data driver and memory output is avoided.

## ● Standby Mode

When  $\overline{CE1}$  or  $\overline{CE2}$  is high, SRM2018C<sub>10/12</sub> is in the stand-by mode and only retains the data. At this time the DATA I/O terminal is in a high-impedance state and input of an address,  $R/\overline{W}$  signal, or data is prohibited. When  $\overline{CE1}$  or  $\overline{CE2}$  is above  $V_{DD}-0.2V$ ,\* current flowing within the SRM2018C<sub>10/12</sub> chip is only that in the high-resistance portion of the memory cells and leakage current.

\*  $\overline{CE1} = V_{DD} - 0.2V$  and  $\overline{CE2} = 0.2V$  or  $V_{DD} - 0.2V$   
 $\overline{CE2} = V_{DD} - 0.2V$  and  $\overline{CE1} = 0.2V$  or  $V_{DD} - 0.2V$

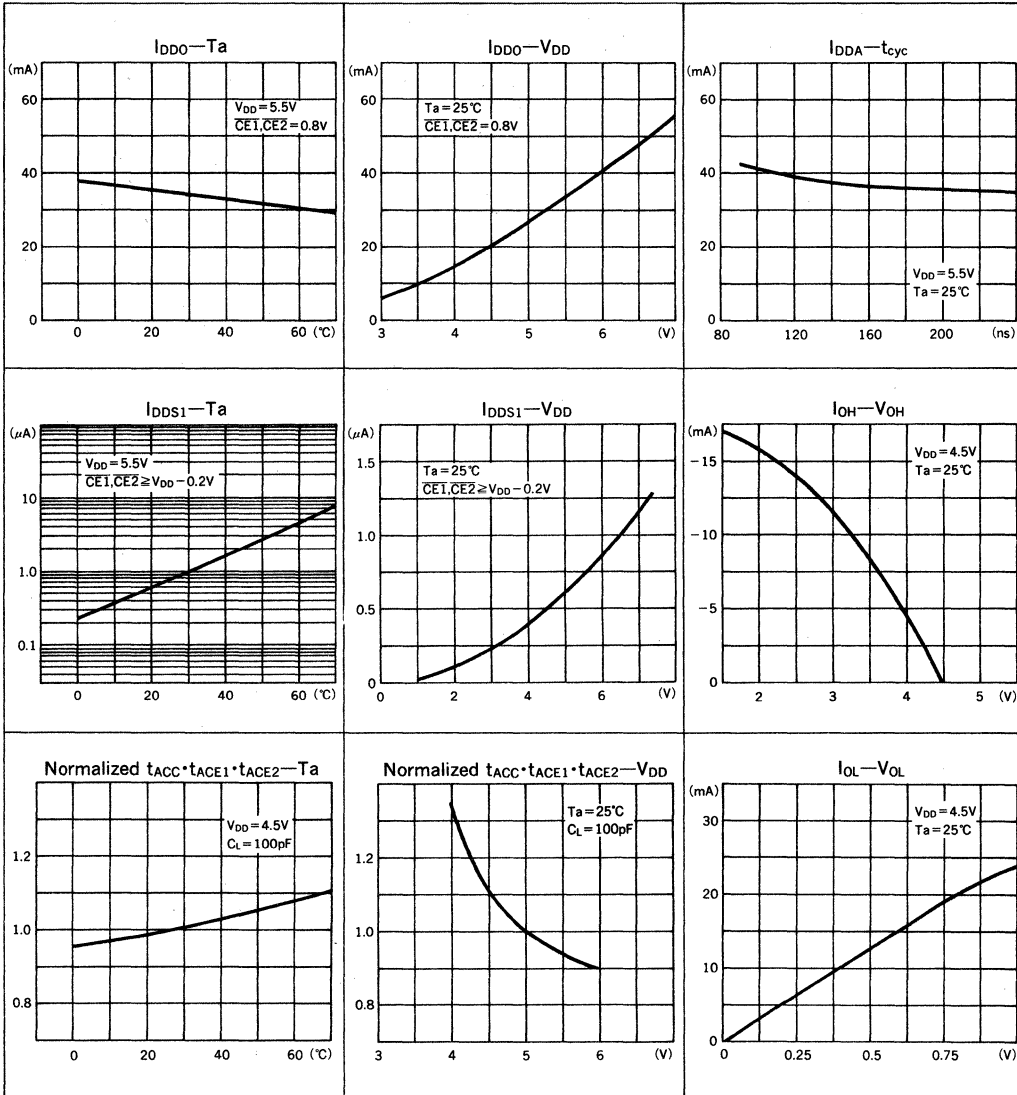
## ■ PACKAGE DIMENSIONS



\*1 Represents model SRM2018M<sub>10/12</sub> that has the same electrical characteristics as model SRM2018C<sub>10/12</sub>.

\*2 Represents model SRM2018N<sub>10/12</sub> that has the same electrical characteristics as model SRM2018C<sub>10/12</sub>.

# CHARACTERISTICS CURVES



# SRM2264LC<sub>90/10/12</sub>

## HIGH SPEED CMOS 64K-BIT STATIC RAM

- Low Supply Current
- Access Time 90ns/100ns/120ns
- 8,192 Words × 8 Bits Asynchronous

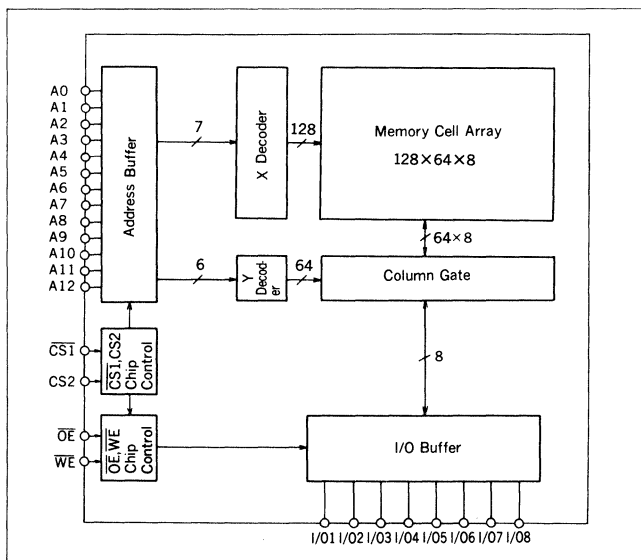
### DESCRIPTION

The SRM2264LC<sub>90/10/12</sub> is an 8,192 words × 8 bits asynchronous, static, random access memory on a monolithic CMOS chip. Its very low standby power requirement makes it ideal for applications requiring non-volatile storage with back-up batteries. The asynchronous and static nature of the memory requires no external clock or refreshing circuit. Both the input and output ports are TTL compatible and the 3-state output allows easy expansion of memory capacity.

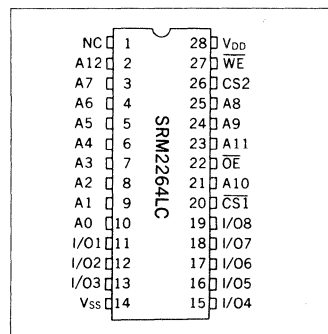
### FEATURES

- Fast Access time.....SRM2264LC<sub>90</sub> 90ns (Max)  
SRM2264LC<sub>10</sub> 100ns (Max)  
SRM2264LC<sub>12</sub> 120ns (Max)
- Low supply current.....standby : 0.5μA (Typ)  
operation: 50mA (Typ)..... 90ns  
47mA (Typ).....100ns  
45mA (Typ).....120ns
- Completely static.....No clock required
- Single power supply.....5V ± 10%
- TTL compatible inputs and outputs
- 3-state output with wired-OR capability
- Non-volatile storage with back-up batteries
- Package.....SRM2264LC<sub>90/10/12</sub> 28-pin DIP(plastic)  
SRM2264LM<sub>90/10/12</sub> 28-pin SOP(plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A12	Address Input
WE	Write Enable
OE	Output Enable
CS1, CS2	Chip Select
I/O1 to I/O8	Data I/O
V <sub>DD</sub>	Power Supply(+ 5V)
V <sub>SS</sub>	Power Supply( 0V)
NC	No connection



## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage*	V <sub>I</sub>	-0.5 to 7.0	V
Input/Output voltage*	V <sub>I/O</sub>	-0.5 to V <sub>DD</sub> + 0.3	V
Power dissipation	P <sub>D</sub>	1.0	W
Operating temperature	T <sub>opr</sub>	0 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

\* V<sub>I</sub>, V<sub>I/O</sub> (Min) = -1.0V (Pulse width is 50ns)

## ■ DC RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub> = 0V, T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>	—	4.5	5.0	5.5	V
	V <sub>SS</sub>	—	0	0	0	V
Input voltage	V <sub>IH</sub>	—	2.2	3.5	V <sub>DD</sub> + 0.3	V
	V <sub>IL</sub>	—	-0.3*	0	0.8	V

\* If pulse width is less than 50ns, it is -1.0V

## ■ ELECTRICAL CHARACTERISTICS

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = 0 to 70°C)

### ● DC Electrical Characteristics

Parameter	Symbol	Conditions	SRM2264LC <sub>90</sub>			SRM2264LC <sub>10</sub>			SRM2264LC <sub>12</sub>			Unit
			Min	Typ*	Max	Min	Typ*	Max	Min	Typ*	Max	
Input leakage	I <sub>LI</sub>	V <sub>I</sub> = 0 to V <sub>DD</sub>	-1	—	1	-1	—	1	-1	—	1	μA
Standby supply current	I <sub>DSS</sub>	CS1 = V <sub>IH</sub> or CS2 = V <sub>IL</sub>	-0.5	1.0	—	-0.5	1.0	—	-0.5	1.0	—	mA
	I <sub>DSS1</sub>	CS1 = CS2 ≥ V <sub>DD</sub> - 0.2V or CS2 ≤ 0.2V	-0.5	20	—	-0.5	20	—	-0.5	20	—	μA
Average operating current	I <sub>DDA</sub>	V <sub>I</sub> = V <sub>IL</sub> , V <sub>IH</sub> I <sub>I/O</sub> = 0mA t <sub>cyc</sub> = Min	—	50	85	—	47	82	—	45	80	mA
Operating supply current	I <sub>DDO</sub>	V <sub>I</sub> = V <sub>IL</sub> , V <sub>IH</sub> I <sub>I/O</sub> = 0mA	—	35	60	—	35	60	—	35	60	mA
Output leakage	I <sub>LO</sub>	CS1 = V <sub>IH</sub> or CS2 = V <sub>IL</sub> or WE = V <sub>IL</sub> or OE = V <sub>IH</sub> V <sub>I</sub> = 0 to V <sub>DD</sub>	-1	—	1	-1	—	1	-1	—	1	μA
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -1.0mA	2.4	V <sub>DD</sub> - 0.1	—	2.4	V <sub>DD</sub> - 0.1	—	2.4	V <sub>DD</sub> - 0.1	—	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 4.0mA	-0.2	0.4	—	-0.2	0.4	—	-0.2	0.4	—	V

\*1 Typical values are measured at T<sub>a</sub> = 25°C and V<sub>DD</sub> = 5.0V

### ● Terminal Capacitance

(f = 1MHz, T<sub>a</sub> = 25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Address Capacitance	C <sub>ADD</sub>	V <sub>ADD</sub> = 0V	—	3	5	pF
Input Capacitance	C <sub>I</sub>	V <sub>I</sub> = 0V	—	5	6	pF
I/O Capacitance	C <sub>I/O</sub>	V <sub>I/O</sub> = 0V	—	6	7	pF

### ● AC Electrical Characteristics

#### ○ Read Cycle

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	SRM2264LC <sub>90</sub>		SRM2264LC <sub>10</sub>		SRM2264LC <sub>12</sub>		Unit	
			Min	Max	Min	Max	Min	Max		
Read cycle time	t <sub>RC</sub>	*1	90	—	100	—	120	—	ns	
Address access time	t <sub>ACC</sub>		—	90	—	100	—	120	ns	
Chip select 1 access time	t <sub>ACS1</sub>		—	90	—	100	—	120	ns	
Chip select 2 access time	t <sub>ACS2</sub>		—	90	—	100	—	120	ns	
Output enable access time	t <sub>OE</sub>		—	50	—	50	—	60	ns	
Chip select 1 output set time	t <sub>CLZ1</sub>		*2	10	—	10	—	10	—	ns
Chip select 1 output floating	t <sub>CHZ1</sub>			—	35	—	35	—	40	ns
Chip select 2 output set time	t <sub>CLZ2</sub>			10	—	10	—	10	—	ns
Chip select 2 output floating	t <sub>CHZ2</sub>			—	35	—	35	—	40	ns
Output enable output set time	t <sub>OLZ</sub>			5	—	5	—	5	—	ns
Output enable output floating	t <sub>OHZ</sub>	—		35	—	35	—	40	ns	
Output hold time	t <sub>OH</sub>	*1		10	—	10	—	10	—	ns

○ Write Cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=0$  to  $70^\circ C$ )

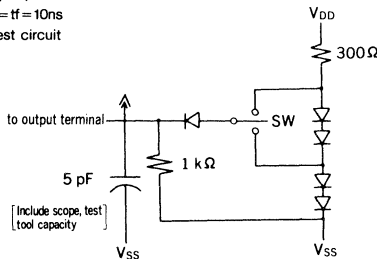
Parameter	Symbol	Conditions	SRM2264LC <sub>90</sub>		SRM2264LC <sub>10</sub>		SRM2264LC <sub>12</sub>		Unit
			Min	Max	Min	Max	Min	Max	
Write cycle time	$t_{WC}$	* 1	90	—	100	—	120	—	ns
Chip select time 1	$t_{CW1}$		75	—	80	—	85	—	ns
Chip select time 2	$t_{CW2}$		75	—	80	—	85	—	ns
Address enable time	$t_{AW}$		75	—	80	—	85	—	ns
Address setup time	$t_{AS}$		0	—	0	—	0	—	ns
Write pulse width	$t_{WP}$		60	—	60	—	70	—	ns
Address hold time	$t_{WR}$		0	—	0	—	0	—	ns
Input data setup time	$t_{DW}$		50	—	50	—	50	—	ns
Input data hold time	$t_{DH}$		0	—	0	—	0	—	ns
$\overline{WE}$ Output floating	$t_{WHZ}$	* 3	—	35	—	35	—	40	ns
$\overline{WE}$ Output setup time	$t_{OW}$		5	—	5	—	5	—	ns

\* 1 Test Conditions

- Input pulse level : 0.8V to 2.4V
- $t_r = t_f = 10ns$
- Input and output timing reference levels : 1.5V
- Output load  $I_{TL} + C_L = 100pF$

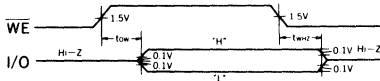
\* 3 Test Conditions

- Input pulse level : 0.8V to 2.4V
- $t_r = t_f = 10ns$
- Test circuit



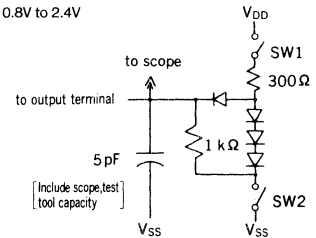
Test :  $t_{ow}, t_{whz}$  Hi-Z → "H" and "H" → Hi-Z SW is  $V_{DD}$  side  
 Test :  $t_{ow}, t_{whz}$  Hi-Z → "L" and "L" → Hi-Z SW is  $V_{SS}$  side

Output turnon turnoff time



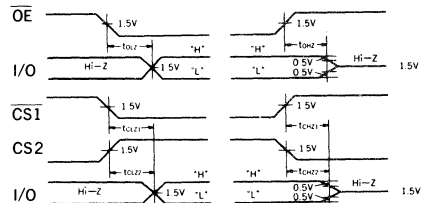
\* 2 Test Conditions

- Input pulse level : 0.8V to 2.4V
- $t_r = t_f = 10ns$
- Test circuit



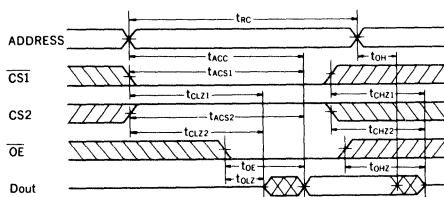
Test :  $t_{chz1}, t_{chz2}, t_{ohz}$  Both SW1 and SW2 are close  
 Test :  $t_{clz1}, t_{clz2}, t_{olz}$  Hi-Z → "H" SW1 is open, SW2 is close.  
 Test :  $t_{clz1}, t_{clz2}, t_{olz}$  Hi-Z → "L" SW1 is close, SW2 is open.

Output turnon turnoff time

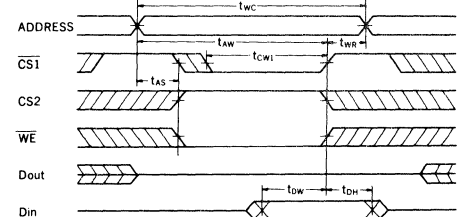


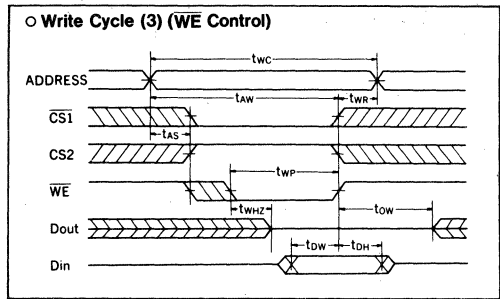
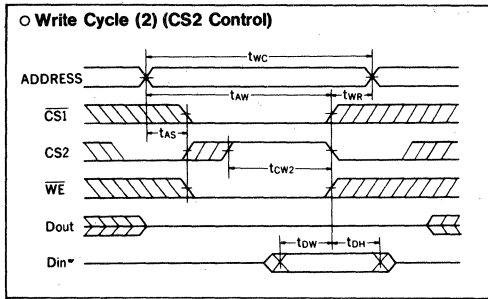
● Timing Chart

○ Read Cycle



○ Write Cycle (1) (CS1 Control)





- Note : 1. During read cycle time,  $\overline{WE}$  is to be "H" level.  
 2. During write cycle time that is controlled by  $\overline{CS1}$  or  $\overline{CS2}$ , Output Buffer is in high impedance state whether  $\overline{OE}$  level is "H" or "L".  
 3. During write cycle time that is controlled by  $\overline{WE}$ , Output Buffer is high impedance state if  $\overline{OE}$  is "H" level.

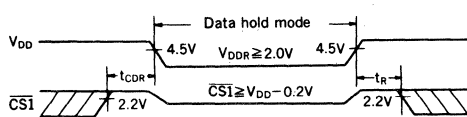
■ DATA RETENTION CHARACTERISTIC WITH LOW VOLTAGE POWER SUPPLY

( $T_a = 0$  to  $70^\circ\text{C}$ )

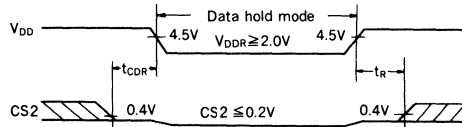
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Data retention supply voltage	$V_{\text{DDR}}$		2.0	—	5.5	V
Data retention current	$I_{\text{DDR}}$	$V_{\text{DD}} = 3\text{V}$ $\overline{CS1} = \overline{CS2} \geq V_{\text{DD}} - 0.2\text{V}$ or $\overline{CS2} \leq 0.2\text{V}$	—	—	10	$\mu\text{A}$
Chip select · data hold time	$t_{\text{CDR}}$		0	—	—	ns
Operation recovery time	$t_{\text{R}}$		$t_{\text{RC}}^*$	—	—	ns

\* $t_{\text{RC}}$  = Read cycle time

Data retention timing ( $\overline{CS1}$  Control)



Data retention timing ( $\overline{CS2}$  Control)



■ FUNCTIONS

● Truth Table

$\overline{CS1}$	$\overline{CS2}$	$\overline{OE}$	$\overline{WE}$	A0 to A12	DATA I/O	Mode	$I_{\text{DD}}$
H	X	—	—	—	Hi-Z	Unselected	$I_{\text{DDS}}, I_{\text{DDSI}}$
—	L	—	—	—	Hi-Z	Unselected	$I_{\text{DDS}}, I_{\text{DDSI}}$
L	H	X	L	Stable	Input data	Write	$I_{\text{DDO}}$
L	H	L	H	Stable	Output data	Read	$I_{\text{DDO}}$
L	H	H	H	Stable	Hi-Z	Output disable	$I_{\text{DDO}}$

X: "H" or "L", —: "H", "L" or "Hi-Z"

● Reading data

Data is able to be read when the address is setted while holding  $\overline{CS1} = "L"$ ,  $\overline{CS2} = "H"$ ,  $\overline{OE} = "L"$  and  $\overline{WE} = "H"$ . Since Data I/O terminals are in high impedance state when  $\overline{OE} = "H"$ , the data bus line can be used for any other objective, then access time apparently is able to be cut down.

● Writing data

There are the following four ways of writing data into the memory.

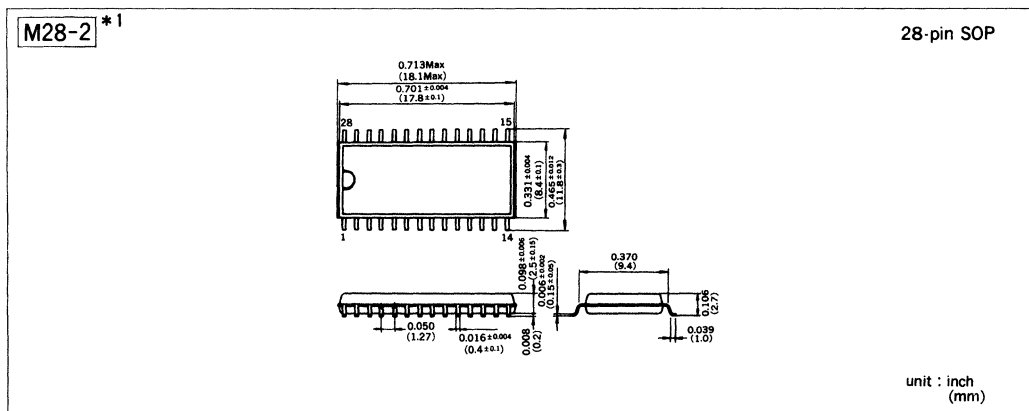
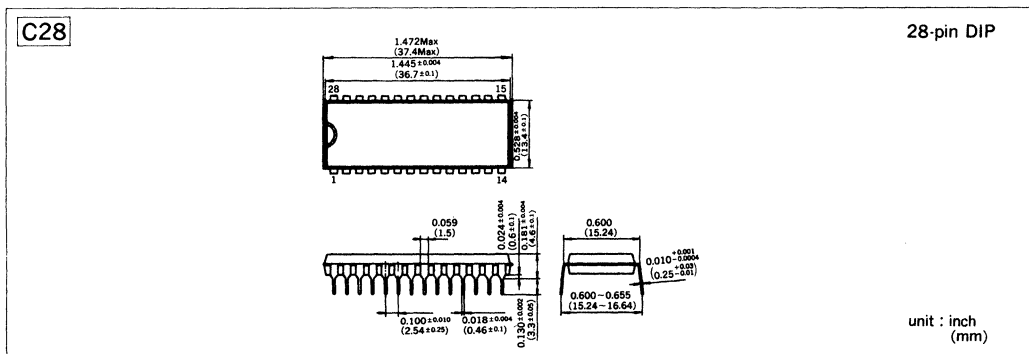
- (1) Hold CS2="H",  $\overline{WE}$ ="L" set addresses and give "L" pulse to  $\overline{CS1}$ .
- (2) Hold  $\overline{CS1}$ ="L",  $\overline{WE}$ ="L", set addresses and give "H" pulse to CS2.
- (3) Hold  $\overline{CS1}$ ="L", CS2="H", set addresses and give "L" pulse to  $\overline{WE}$ .
- (4) After setting addresses, give "L" pulse to  $\overline{CS1}$ ,  $\overline{WE}$  and give "H" pulse to CS2.

Anyway, data on the Data I/O terminals are latched up into the SRM2264LC<sub>90/10/12</sub> at the end of the period that  $\overline{CS1}$ ,  $\overline{WE}$  are "L" level, and CS2 is "H" level. As Data I/O terminals are in high impedance state when any of  $\overline{CS1}$ ,  $\overline{OE}$ ="H", or CS2="L", the contention on the data bus can be avoided.

● Standby mode

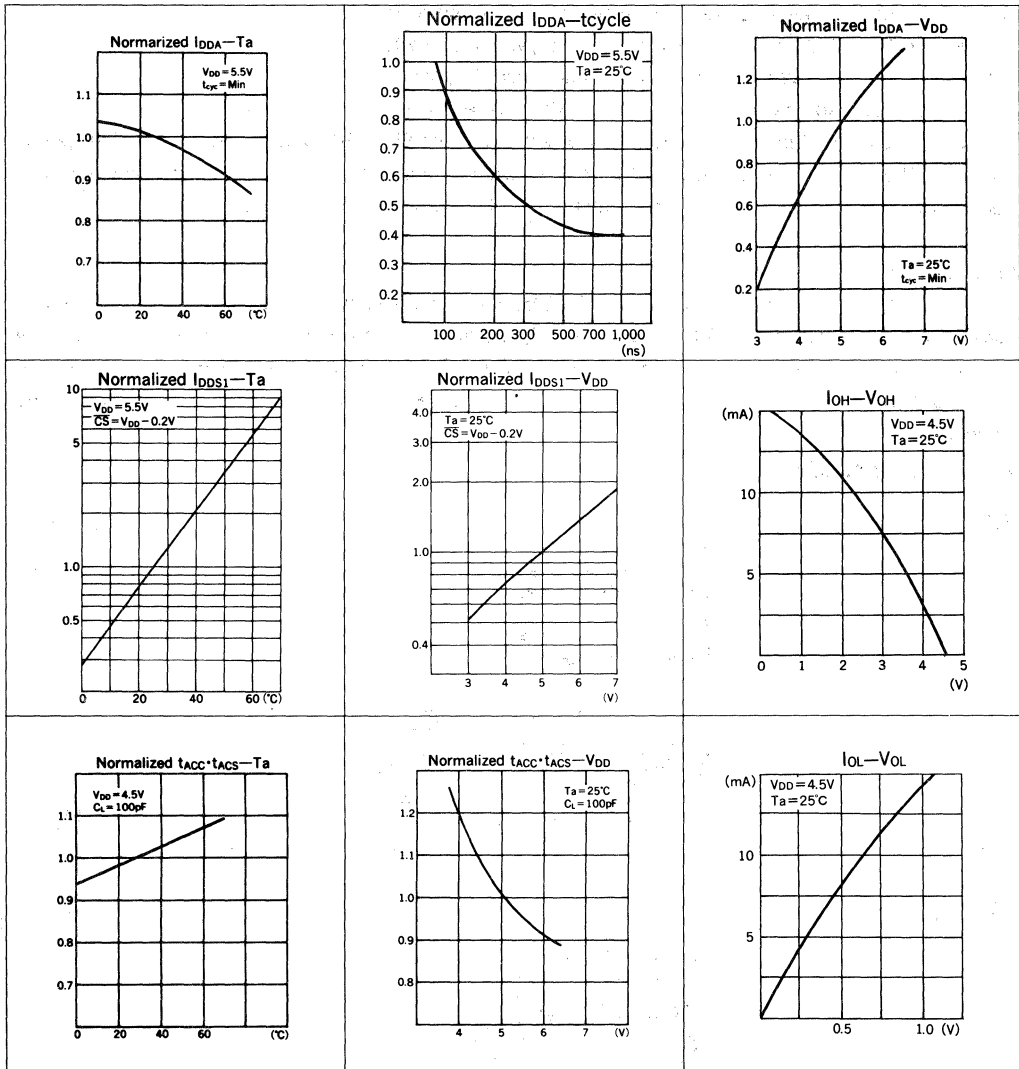
When  $\overline{CS1}$  is "H" or CS2 is "L" level, the SRM2264<sub>90/10/12</sub> is in the standby mode which has retaining date operation. In this case Data I/O terminals are Hi-Z, and all inputs of addresses,  $\overline{WE}$  and data can be any "H" or "L". When  $\overline{CS1}$  and CS2 level are in the range over  $V_{DD}-0.2V$ , or CS2 level is in the range under 0.2V, in the SRM2264LC<sub>90/10/12</sub> there is almost no current flow except through the high resistance parts of the memory.

■ PACKAGE DIMENSIONS



\*1 SRM2264LM<sub>90/10/12</sub> has the same characteristics as SRM2264LC<sub>90/10/12</sub>.

# CHARACTERISTICS CURVES



# SRM20256LC<sub>10/12</sub>

## CMOS 256K-BIT STATIC RAM

- **Low Supply Current**
- **Access Time 100ns/120ns**
- **32,768 Words × 8 Bits Asynchronous**

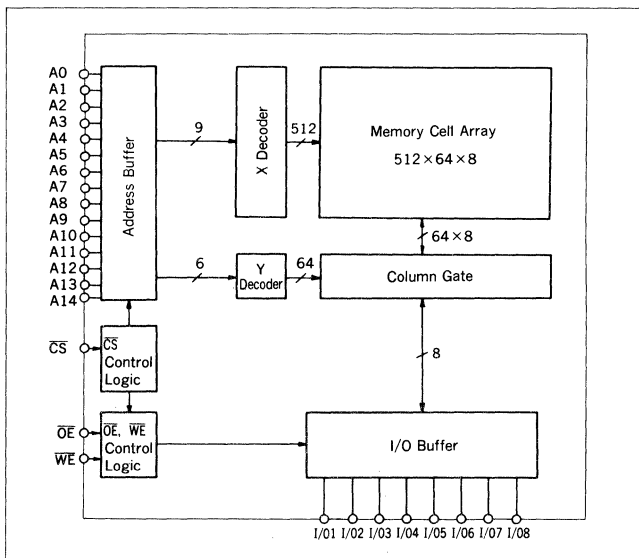
### DESCRIPTION

The SRM20256LC<sub>10/12</sub> is a 32,768 word × 8 bits asynchronous, static, random access memory fabricated using an advanced CMOS technology. Its very low standby power requirement makes it ideal for applications requiring non-volatile storage with back-up batteries. The asynchronous and static nature of the memory requires no external clock or refresh circuit. Input and output ports are TTL compatible and the 3-state output allows easy expansion of memory capacity.

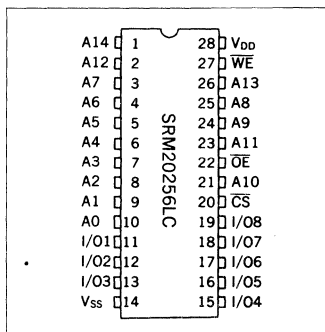
### FEATURES

- **Fast access time** ..... SRM20256LC<sub>10</sub> 100ns (Max)  
SRM20256LC<sub>12</sub> 120ns (Max)
- **Low supply current** ..... standby : 2μA (Typ)  
operation : 13mA/1MHz (Typ)
- **Completely static** ..... no clock required
- **Single power supply** ..... 5V ± 10%
- **TTL compatible inputs and outputs**
- **3-state output**
- **Battery back-up operation**
- **Package** ..... SRM20256LC<sub>10/12</sub> 28-pin DIP (plastic)  
SRM20256LM<sub>10/12</sub> 28-pin SOP (plastic)  
SRM20256LS<sub>10/12</sub> 28-pin Shrink DIP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A14	Address Input
WE	Write Enable
OE	Output Enable
CS	Chip Select
I/O1 to 8	Data Input/Output
V <sub>DD</sub>	Power Supply (+5V)
V <sub>SS</sub>	Power Supply (0V)

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5* to 7.0	V
Input/Output voltage	V <sub>I/O</sub>	-0.5* to V <sub>DD</sub> +0.3	V
Power dissipation	P <sub>D</sub>	1.0	W
Operating temperature	T <sub>opr</sub>	0 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (Lead only)	—

\*V<sub>I</sub>, V<sub>I/O</sub>(Min) = -1.0V when pulse width is less or equal to 50ns

## ■ DC RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub>=0V, Ta=0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
	V <sub>SS</sub>		0	0	0	V
Input voltage	V <sub>IH</sub>		2.2	3.5	V <sub>DD</sub> +0.3	V
	V <sub>IL</sub>		-0.3*	0	0.8	V

\*V<sub>IL</sub>(Min) = -1.0V when pulse width is less or equal to 50ns

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

(V<sub>DD</sub>=5V±10%, V<sub>SS</sub>=0V, Ta=0 to 70°C)

Parameter	Symbol	Conditions	SRM20256LC <sub>10</sub>			SRM20256LC <sub>12</sub>			Unit
			Min	Typ*	Max	Min	Typ*	Max	
Input leakage	I <sub>LI</sub>	V <sub>I</sub> =0 to V <sub>DD</sub>	-1	—	1	-1	—	1	μA
Standby supply current	I <sub>DDS</sub>	CS = V <sub>IH</sub>	—	1.5	3.0	—	1.5	3.0	mA
	I <sub>DDSI</sub>	CS ≥ V <sub>DD</sub> - 0.2V	—	2	100	—	2	100	μA
Average operating current	I <sub>DDA</sub>	V <sub>I</sub> =V <sub>IL</sub> , V <sub>IH</sub> I <sub>I/O</sub> =0mA t <sub>cyc</sub> =Min	—	40	70	—	37	70	mA
	I <sub>DDA1</sub>	V <sub>I</sub> =V <sub>IL</sub> , V <sub>IH</sub> I <sub>I/O</sub> =0mA t <sub>cyc</sub> =1μs	—	13	—	—	13	—	mA
Operating supply current	I <sub>DDO</sub>	V <sub>I</sub> =V <sub>IL</sub> , V <sub>IH</sub> I <sub>I/O</sub> =0mA	—	35	65	—	35	65	mA
Output leakage	I <sub>LO</sub>	CS = V <sub>IH</sub> or WE = V <sub>IL</sub> or OE = V <sub>IH</sub> V <sub>I/O</sub> =0 to V <sub>DD</sub>	-1	—	1	-1	—	1	μA
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -1.0mA	2.4	V <sub>DD</sub> -0.1	—	2.4	V <sub>DD</sub> -0.1	—	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2.1mA	—	0.2	0.4	—	0.2	0.4	V

\*Typical values are measured at Ta=25°C and V<sub>DD</sub>=5.0V

### ● Terminal Capacitance

(f=1MHz, Ta=25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Address Capacitance	C <sub>ADD</sub>	V <sub>ADD</sub> =0V	—	—	10	pF
Input Capacitance	C <sub>I</sub>	V <sub>I</sub> =0V	—	—	10	pF
I/O Capacitance	C <sub>I/O</sub>	V <sub>I/O</sub> =0V	—	—	10	pF

### ● AC Electrical Characteristics

#### ○ Read Cycle

(V<sub>DD</sub>=5V±10%, V<sub>SS</sub>=0V, Ta=0 to 70°C)

Parameter	Symbol	Conditions	SRM20256LC <sub>10</sub>		SRM20256LC <sub>12</sub>		Unit
			Min	Max	Min	Max	
Read cycle time	t <sub>RC</sub>	* 1	100	—	120	—	ns
Address access time	t <sub>ACC</sub>		—	100	—	120	ns
CS access time	t <sub>ACS</sub>		—	100	—	120	ns
OE access time	t <sub>OE</sub>		—	50	—	60	ns
CS output set time	t <sub>CLZ</sub>	* 2	10	—	10	—	ns
CS output floating	t <sub>CHZ</sub>		—	35	—	40	ns
OE output set time	t <sub>OLZ</sub>		5	—	5	—	ns
OE output floating	t <sub>OHZ</sub>		—	35	—	40	ns
Output hold time	t <sub>OH</sub>	* 1	10	—	10	—	ns

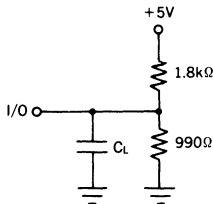
### ○ Write Cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=0$  to  $70^\circ C$ )

Parameter	Symbol	Conditions	SRM20256LC <sub>10</sub>		SRM20256LC <sub>12</sub>		Unit
			Min	Max	Min	Max	
Write cycle time	$t_{wc}$	*1	100	—	120	—	ns
Chip select time	$t_{cw}$		80	—	85	—	ns
Address valid to end of write	$t_{aw}$		80	—	85	—	ns
Address setup time	$t_{as}$		0	—	0	—	ns
Write pulse width	$t_{wp}$		75	—	80	—	ns
Address hold time	$t_{wr}$		0	—	0	—	ns
Input data set time	$t_{dw}$		45	—	50	—	ns
Input data hold time	$t_{dh}$		0	—	0	—	ns
Write to Output floating	$t_{whz}$	*2	—	35	—	40	ns
Output Active from end of write	$t_{ow}$		10	—	10	—	ns

#### \*1 Test Conditions

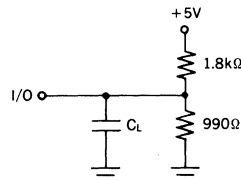
1. Input pulse level : 0.6V to 2.4V
2.  $t_r = t_f = 5ns$
3. Input and output timing reference levels : 1.5V
4. Output load  $C_L = 100pF$



$C_L = 100pF$  (Includes Jig Capacitance)

#### \*2 Test Conditions

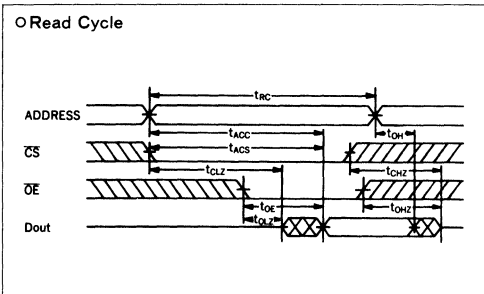
1. Input pulse level : 0.6V to 2.4V
2.  $t_r = t_f = 5ns$
3. Input timing reference levels : 1.5V
4. Output timing reference levels :  $\pm 200mV$  (the level displaced from stable output voltage level)
5. Output load  $C_L = 5pF$



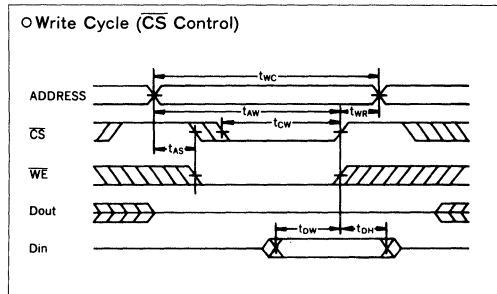
$C_L = 5pF$  (Includes Jig Capacitance)

### ● Timing Chart

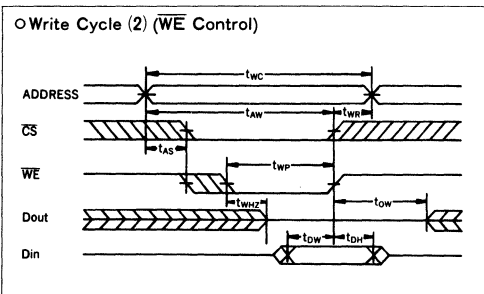
#### ○ Read Cycle



#### ○ Write Cycle ( $\overline{CS}$ Control)



#### ○ Write Cycle (2) ( $\overline{WE}$ Control)



#### Note :

1. During read cycle time,  $\overline{WE}$  is to be "H" level.
2. During write cycle time that is controlled by  $\overline{CS}$ , Output Buffer is in high impedance state, whether  $\overline{OE}$  level is "H" or "L".
3. During write cycle time that is controlled by  $\overline{WE}$ , Output Buffer is in high impedance state if  $\overline{OE}$  is "H" level.



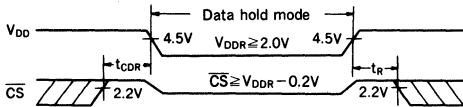
## DATA RETENTION CHARACTERISTIC WITH LOW VOLTAGE POWER SUPPLY

( $V_{SS}=0V$ ,  $T_a=0$  to  $70^{\circ}C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Data retention supply voltage	$V_{DDR}$		2.0	—	5.5	V
Data retention current	$I_{DDR}$	$V_{DD}=3V$ , $\overline{CS} \geq V_{DDR} - 0.2V$	—	1	50	$\mu A$
Chip select data hold time	$t_{CDR}$		0	—	—	ns
Operation recovery time	$t_R$		$t_{RC}^*$	—	—	ns

\* $t_{RC}$ =Read cycle time

### Data retention timing



## FUNCTIONS

### Truth Table

$\overline{CS}$	$\overline{OE}$	$\overline{WE}$	A0 to A14	DATA I/O	Mode	$I_{DD}$
H	—	—	—	Hi-Z	Standby	$I_{DDs}$ , $I_{DDs1}$
L	X	L	Stable	$D_{IN}$	Write	$I_{DDA}$ , $I_{DDA1}$
L	L	H	Stable	$D_{OUT}$	Read	$I_{DDA}$ , $I_{DDA1}$
L	H	H	Stable	Hi-Z	Output disable	$I_{DDA}$ , $I_{DDA1}$

### Read Mode

The Data appear when the address is setted while holding  $\overline{CS} = "L"$ ,  $\overline{OE} = "L"$  and  $\overline{WE} = "H"$ . When  $\overline{OE} = "H"$ , Data I/O terminals are in high impedance state, that makes circuit design and bus control easy.

### Write Mode

There are the following 3 ways of writing data into memory.

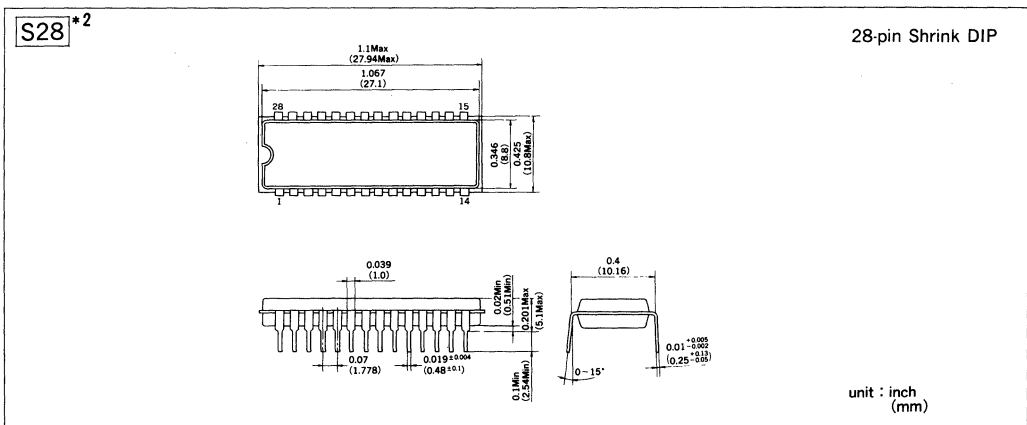
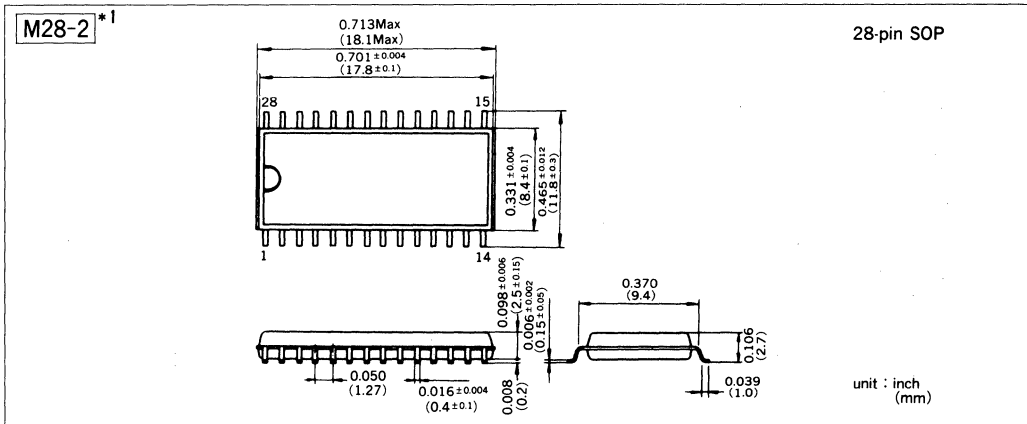
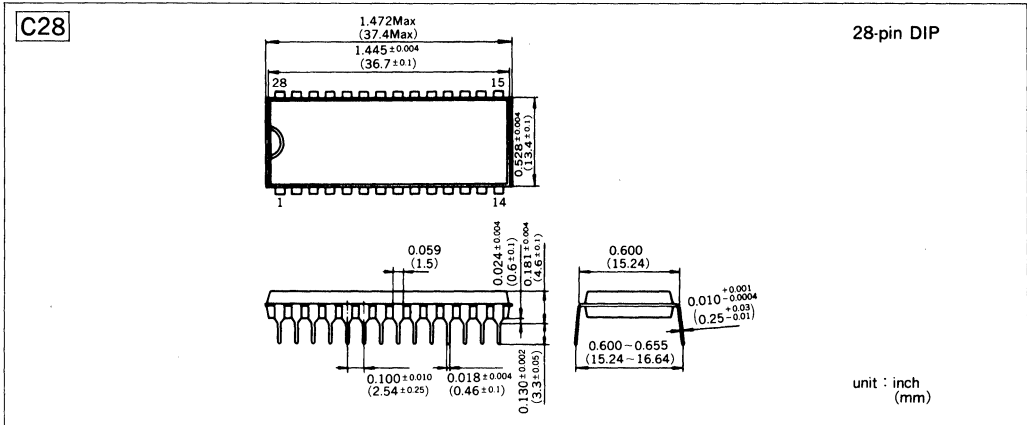
- (1) Hold  $\overline{CS} = "L"$  and  $\overline{WE} = "L"$ , set address.
- (2) Hold  $\overline{CS} = "L"$  then set address and give "L" pulse to  $\overline{WE}$ .
- (3) After setting addresses, give "L" pulse to both  $\overline{CS}$  and  $\overline{WE}$ .

In above any case data on the DATA I/O terminals are latched up into the SRM20256LC<sub>10/12</sub> when  $\overline{CS}$  or  $\overline{WE}$  is in positive-going. Since DATA I/O terminals are high impedance when  $\overline{CS}$  or  $\overline{OE} = "H"$ , bus contention between data driver and memory outputs can be avoided.

### Standby Mode

When  $\overline{CS}$  is "H" the SRM20256LC<sub>10/12</sub> become in the stand-by mode. In this mode, data I/O terminals are Hi-Z, and all inputs of addresses,  $\overline{WE}$  and data can be any "H" or "L". When  $\overline{CS}$  is over than  $V_{DD} - 0.2V$ , the SRM20256LC<sub>10/12</sub> is in the data retention battery back-up mode, in this case, there is a small current in the SRM20256LC<sub>10/12</sub> which flow through the high resistances of the memory cells.

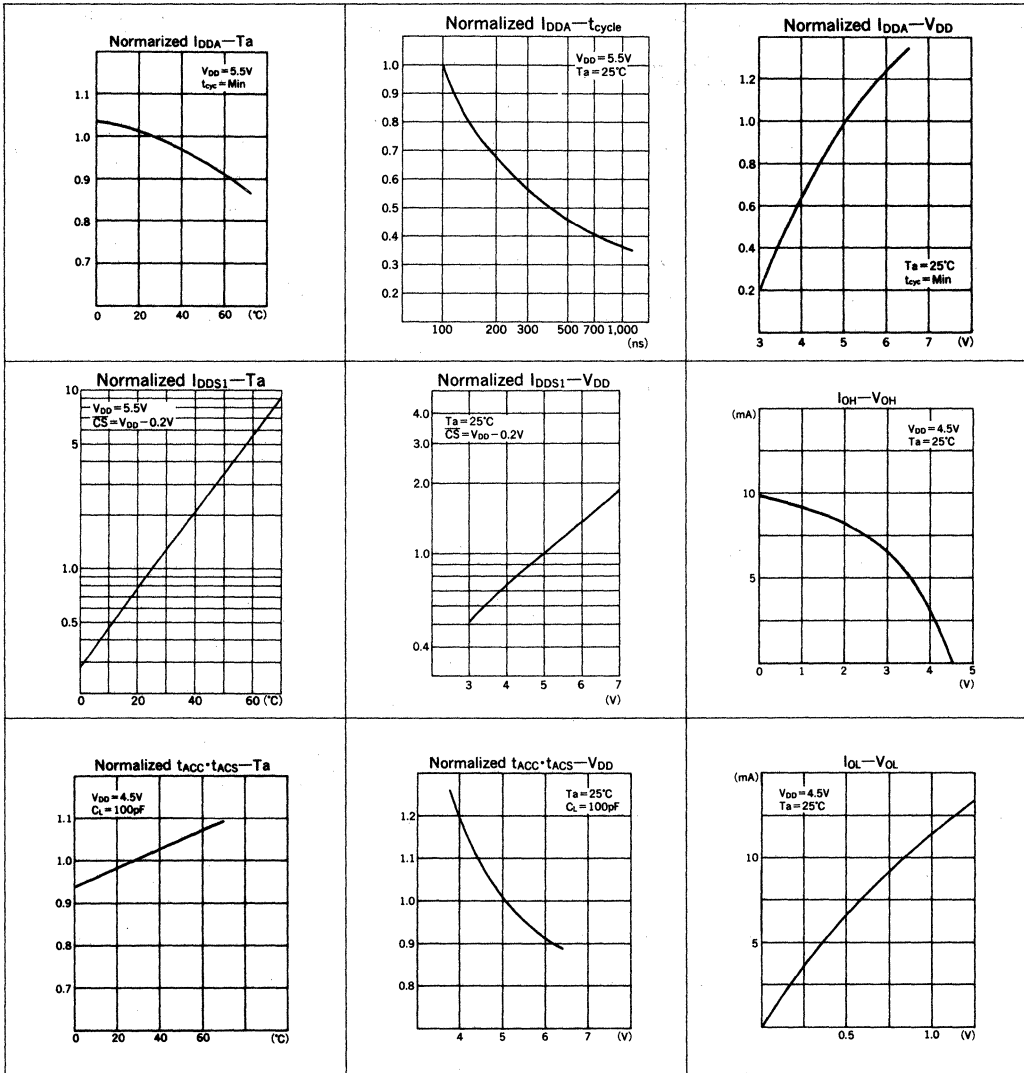
**PACKAGE DIMENSIONS**



\*1 Represents SRM20256LM10/12 that has the same electrical characteristics as SRM20256LC10/12.

\*2 Represents SRM20256LS10/12 that has the same electrical characteristics as SRM20256LC10/12.

■ CHARACTERISTICS CURVES



# SRM20256LCT<sub>10/12</sub>

## CMOS 256K-BIT STATIC RAM

- Industrial Temperature Range
- Low Supply Current
- Access Time 100ns/120ns
- 32,768 Words × 8 Bits Asynchronous

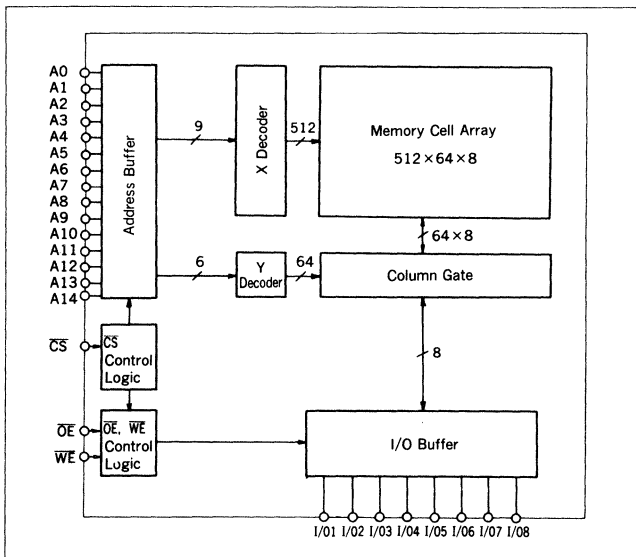
### DESCRIPTION

The SRM20256LCT<sub>10/12</sub> is a 32,768 word × 8 bits asynchronous, static, random access memory fabricated using advanced CMOS technology. Its very low stand-by power feature makes it ideal for applications requiring non-volatile storage with back-up batteries. And -40 to 85°C operating temperature range makes it ideal for industrial use. The asynchronous and static nature of the memory requires no external clock of refresh circuit. Input and output ports are TTL compatible and the 3-state output allows easy expansion of memory capacity.

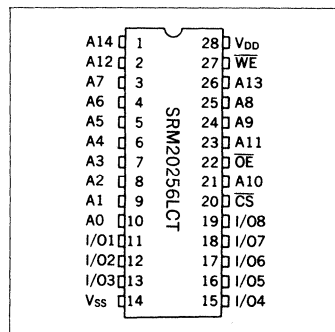
### FEATURES

- Industrial temperature range ..... -40 to 85°C
- Fast access time ..... SRM20256LCT<sub>10</sub> 100ns (Max)  
SRM20256LCT<sub>12</sub> 120ns (Max)
- Low supply current ..... standby : 2μA (Typ)  
operation : 13mA/1MHz (Typ)
- Completely static ..... no clock required
- Single power supply ..... 5V ± 10%
- TTL compatible inputs and outputs
- 3-state output
- Battery back-up operation
- Package ..... SRM20256LCT<sub>10/12</sub> 28-pin DIP (plastic)  
SRM20256LMT<sub>10/12</sub> 28-pin SOP (plastic)  
SRM20256LST<sub>10/12</sub> 28-pin Shrink DIP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A14	Address Input
WE	Write Enable
OE	Output Enable
CS	Chip Select
I/01 to 8	Data Input/Output
VDD	Power Supply (+5V)
Vss	Power Supply (0V)

### ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5* to 7.0	V
Input/Output voltage	V <sub>I/O</sub>	-0.5* to V <sub>DD</sub> +0.3	V
Power dissipation	P <sub>D</sub>	1.0	W
Operating temperature	T <sub>opr</sub>	-40 to 85	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (Lead only)	—

\*V<sub>I</sub>, V<sub>I/O</sub>(Min) = -1.0V when pulse width is less or equal to 50ns

### ■ DC RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub> = 0V, T<sub>a</sub> = -40 to 85°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
	V <sub>SS</sub>		0	0	0	V
Input voltage	V <sub>IH</sub>		2.2	3.5	V <sub>DD</sub> +0.3	V
	V <sub>IL</sub>		-0.3*	0	0.8	V

\*V<sub>IL</sub>(Min) = -1.0V when pulse width is less or equal to 50ns

### ■ ELECTRICAL CHARACTERISTICS

#### ● DC Electrical Characteristics

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -40 to 85°C)

Parameter	Symbol	Conditions	SRM20256LCT <sub>10</sub>			SRM20256LCT <sub>12</sub>			Unit
			Min	Typ*	Max	Min	Typ*	Max	
Input leakage	I <sub>LI</sub>	V <sub>I</sub> = 0 to V <sub>DD</sub>	-1	—	1	-1	—	1	μA
Standby supply current	I <sub>DDSI</sub>	CS = V <sub>IH</sub>	—	1.5	3.0	—	1.5	3.0	mA
	I <sub>DDSI1</sub>	CS ≥ V <sub>DD</sub> - 0.2V	—	2	200	—	2	200	μA
Average operating current	I <sub>DDA</sub>	V <sub>I</sub> = V <sub>IL</sub> , V <sub>IH</sub> I <sub>I/O</sub> = 0mA t <sub>cyc</sub> = Min	—	40	70	—	37	70	mA
	I <sub>DDA1</sub>	V <sub>I</sub> = V <sub>IL</sub> , V <sub>IH</sub> I <sub>I/O</sub> = 0mA t <sub>cyc</sub> = 1μs	—	13	—	—	13	—	mA
Operating supply current	I <sub>DDO</sub>	V <sub>I</sub> = V <sub>IL</sub> , V <sub>IH</sub> I <sub>I/O</sub> = 0mA	—	35	65	—	35	65	mA
Output leakage	I <sub>LO</sub>	CS = V <sub>IH</sub> or WE = V <sub>IL</sub> or OE = V <sub>IH</sub> V <sub>I/O</sub> = 0 to V <sub>DD</sub>	-1	—	1	-1	—	1	μA
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -1.0mA	2.4	V <sub>DD</sub> -0.1	—	2.4	V <sub>DD</sub> -0.1	—	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2.1mA	—	0.2	0.4	—	0.2	0.4	V

\*Typical values are measured at T<sub>a</sub> = 25°C and V<sub>DD</sub> = 5.0V

#### ● Terminal Capacitance

(f = 1MHz, T<sub>a</sub> = 25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Address Capacitance	C <sub>ADD</sub>	V <sub>ADD</sub> = 0V	—	—	10	pF
Input Capacitance	C <sub>I</sub>	V <sub>I</sub> = 0V	—	—	10	pF
I/O Capacitance	C <sub>I/O</sub>	V <sub>I/O</sub> = 0V	—	—	10	pF

#### ● AC Electrical Characteristics

##### ○ Read Cycle

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -40 to 85°C)

Parameter	Symbol	Conditions	SRM20256LCT <sub>10</sub>		SRM20256LCT <sub>12</sub>		Unit
			Min	Max	Min	Max	
Read cycle time	t <sub>RC</sub>		100	—	120	—	ns
Address access time	t <sub>ACC</sub>	*1	—	100	—	120	ns
CS access time	t <sub>ACS</sub>		—	100	—	120	ns
OE access time	t <sub>OE</sub>		—	50	—	60	ns
CS output set time	t <sub>CLZ</sub>	*2	10	—	10	—	ns
CS output floating	t <sub>CHZ</sub>		—	35	—	40	ns
OE output set time	t <sub>OLZ</sub>		5	—	5	—	ns
OE output floating	t <sub>OHZ</sub>		—	35	—	40	ns
Output hold time	t <sub>OH</sub>	*1	10	—	10	—	ns

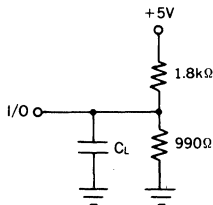
○ Write Cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a = -40$  to  $85^\circ C$ )

Parameter	Symbol	Conditions	SRM20256LCT <sub>10</sub>		SRM20256LCT <sub>12</sub>		Unit
			Min	Max	Min	Max	
Write cycle time	$t_{WC}$	*1	100	—	120	—	ns
Chip select time	$t_{CW}$		80	—	85	—	ns
Address valid to end of write	$t_{AW}$		80	—	85	—	ns
Address setup time	$t_{AS}$		0	—	0	—	ns
Write pulse width	$t_{WP}$		75	—	80	—	ns
Address hold time	$t_{WR}$		5	—	5	—	ns
Input data set time	$t_{DW}$		45	—	50	—	ns
Input data hold time	$t_{DH}$		0	—	0	—	ns
Write to Output floating	$t_{WHZ}$	*2	—	35	—	40	ns
Output Active from end of write	$t_{OW}$		5	—	5	—	ns

\*1 Test Conditions

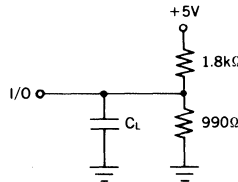
1. Input pulse level : 0.6V to 2.4V
2.  $t_r = t_f = 5ns$
3. Input and output timing reference levels : 1.5V
4. Output load  $C_L = 100pF$



$C_L = 100pF$  (Includes Jig Capacitance)

\*2 Test Conditions

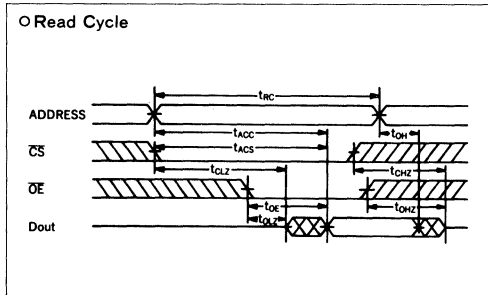
1. Input pulse level : 0.6V to 2.4V
2.  $t_r = t_f = 5ns$
3. Input timing reference levels : 1.5V
4. Output timing reference levels :  $\pm 200mV$  (the level displaced from stable output voltage level)
5. Output load  $C_L = 5pF$



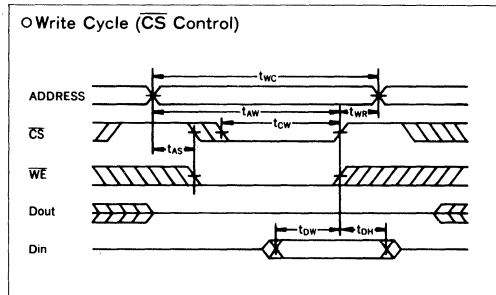
$C_L = 5pF$  (Includes Jig Capacitance)

● Timing Chart

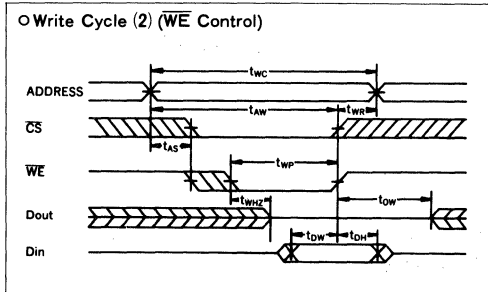
○ Read Cycle



○ Write Cycle ( $\overline{CS}$  Control)



○ Write Cycle (2) ( $\overline{WE}$  Control)



Note :

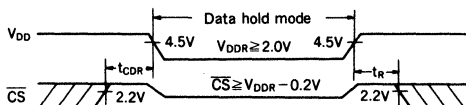
1. During read cycle time,  $\overline{WE}$  is to be "H" level.
2. During write cycle time that is controlled by  $\overline{CS}$ , Output Buffer is in high impedance state, whether  $\overline{OE}$  level is "H" or "L".
3. During write cycle time that is controlled by  $\overline{WE}$ , Output Buffer is in high impedance state if  $\overline{OE}$  is "H" level.

## DATA RETENTION CHARACTERISTIC WITH LOW VOLTAGE POWER SUPPLY (V<sub>SS</sub>=0V, T<sub>a</sub>= -40 to 85°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Data retention supply voltage	V <sub>DDR</sub>		2.0	—	5.5	V
Data retention current	I <sub>DDR</sub>	V <sub>DD</sub> =3V, $\overline{CS} \geq V_{DDR} - 0.2V$	—	1	100	$\mu A$
Chip select data hold time	t <sub>CDR</sub>		0	—	—	ns
Operation recovery time	t <sub>r</sub>		t <sub>rc</sub> *	—	—	ns

\*t<sub>rc</sub>=Read cycle time

### Data retention timing



## FUNCTIONS

### Truth Table

$\overline{CS}$	$\overline{OE}$	$\overline{WE}$	A0 to A14	DATA I/O	Mode	I <sub>DD</sub>
H	—	—	—	Hi-Z	Standby	I <sub>DDs</sub> , I <sub>DDs1</sub>
L	X	L	Stable	D <sub>IN</sub>	Write	I <sub>DDA</sub> , I <sub>DDA1</sub>
L	L	H	Stable	D <sub>OUT</sub>	Read	I <sub>DDA</sub> , I <sub>DDA1</sub>
L	H	H	Stable	Hi-Z	Output disable	I <sub>DDA</sub> , I <sub>DDA1</sub>

### Read Mode

The Data appear when the addresses is setted while holding  $\overline{CS} = "L"$ ,  $\overline{OE} = "L"$  and  $\overline{WE} = "H"$ . When  $\overline{OE} = "H"$ , Data I/O terminals are in high impedance state, that makes it easy for circuit design and bus control.

### Write Mode

There are following 3ways of writing data into the memory.

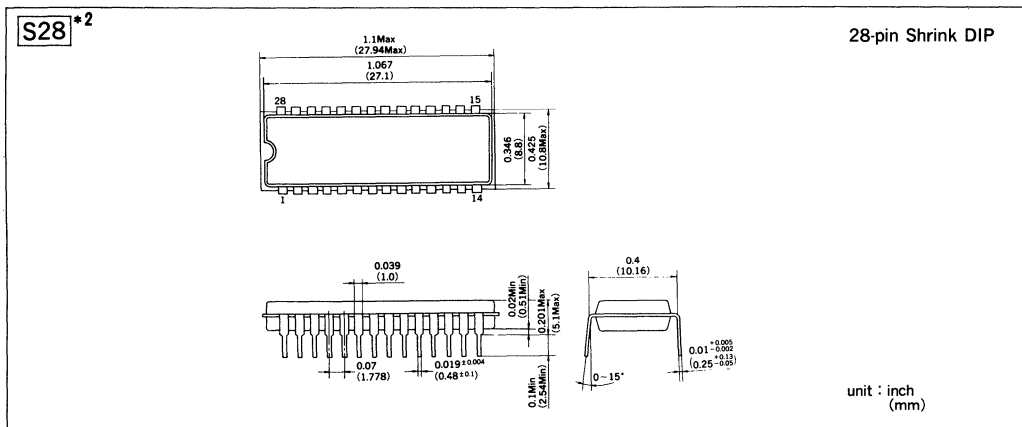
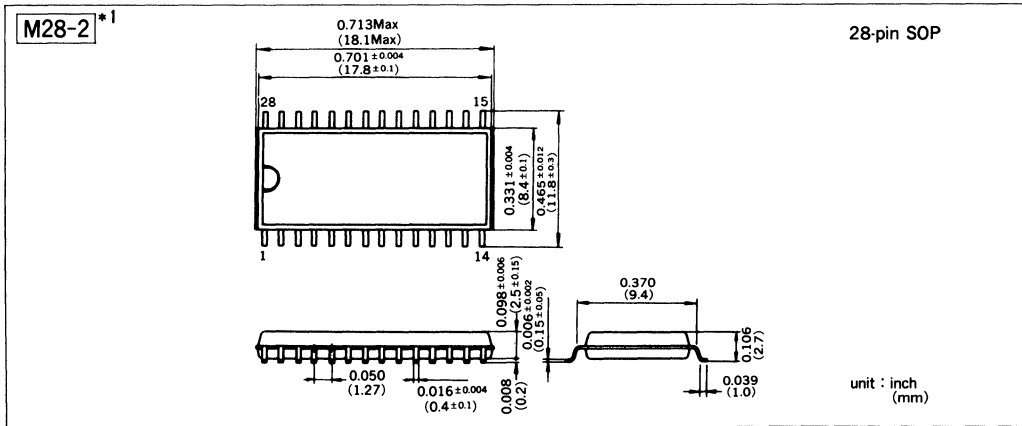
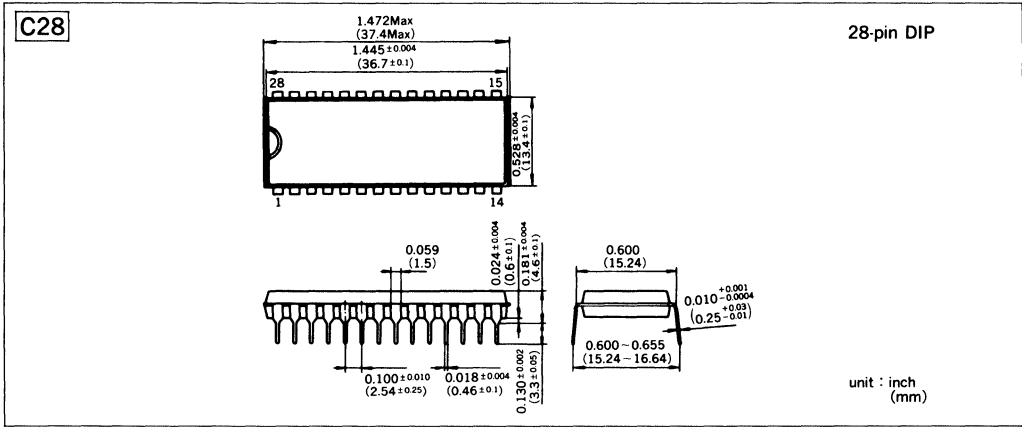
- (1) Hold  $\overline{CS} = "L"$ ,  $\overline{WE} = "L"$ , set address.
- (2) Hold  $\overline{CS} = "L"$ , set address and give "L" pulse to  $\overline{WE}$ .
- (3) After setting addresses, "L" pulse to both  $\overline{CS}$  and  $\overline{WE}$ .

In above any case, Data on the DATA I/O terminals are latched up into the SRM20256LCT<sub>10/12</sub> when  $\overline{CS}$  or  $\overline{WE}$  is in positive-going. Since DATA I/O terminals are in high impedance state when  $\overline{CS}$  or  $\overline{OE} = "H"$ , the contention on the data bus can be aboided.

### Standby Mode

When  $\overline{CS}$  is "H" the SRM20256LCT<sub>10/12</sub> is in the standby mode. In this case Data I/O terminals are in Hi-Z, so that all inputs of addresses,  $\overline{WE}$  and data can be any "H" or "L". When  $\overline{CS}$  is over than V<sub>DD</sub>-0.2V, the SRM20256LCT<sub>10/12</sub> is in the data retention battery back-up mode, in this mode, there is a small current in the SRM20256LCT<sub>10/12</sub> which flow through the high resistances of the memory cells.

■ PACKAGE DIMENSIONS



\*1 Represents SRM20256LMT<sub>10/12</sub> that has the same electrical characteristics as SRM20256LCT<sub>10/12</sub>.  
 \*2 Represents SRM20256LST<sub>10/12</sub> that has the same electrical characteristics as SRM20256LCT<sub>10/12</sub>.



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**CHARACTERISTICS CURVES**

Under measurement

# SRM21256N<sub>35/45/55</sub>

## CMOS 256K-BIT STATIC RAM

preliminary

- Low Supply Current
- Access Time 35ns/45ns/55ns
- 65,536 Words × 4 Bits Asynchronous

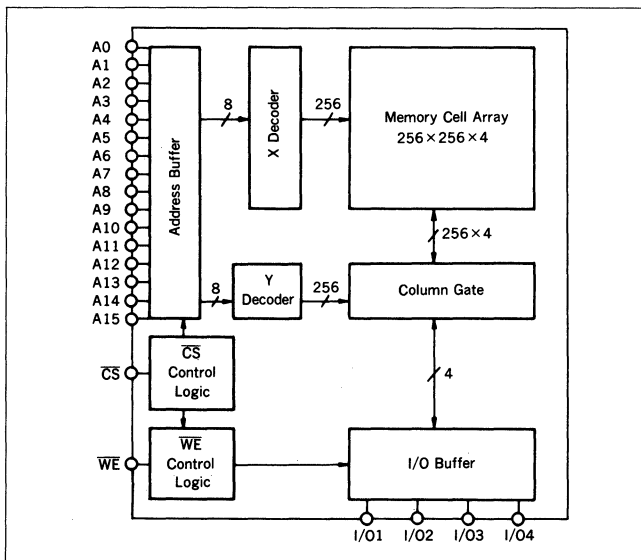
### DESCRIPTION

The SRM21256N<sub>35/45/55</sub> is a 65,536-word × 4 bits asynchronous, static random access memory fabricated using advanced CMOS technology. Since it is asynchronous and static, the memory does not require an external clock or refresh circuitry. Input and output ports are TTL compatible and the 3-state output allows easy expansion of memory capacity.

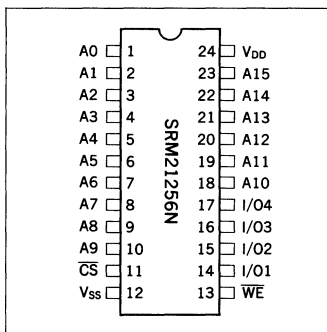
### FEATURES

- Fast access time.....SRM21256N<sub>35</sub> 35ns(Max)  
SRM21256N<sub>45</sub> 45ns(Max)  
SRM21256N<sub>55</sub> 55ns(Max)
- Low supply current.....stand-by : 3mA(Max)  
operation : 120mA(Max)
- Completely static .....no clock required
- Single power supply .....5V ±10%
- TTL compatible inputs and outputs
- 3-state output
- Package .....SRM21256N<sub>35/45/55</sub> 24-pin Skinny DIP (300 mil plastic package)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A15	Address Input
WE	Write Enable
CS	Chip Select
I/O1 to 4	Data Input/Output
V <sub>DD</sub>	Power Supply (+5V)
V <sub>SS</sub>	Power Supply (0V)

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5* to 7.0	V
Input/Output voltage	V <sub>I/O</sub>	-0.5* to V <sub>DD</sub> +0.3	V
Power dissipation	P <sub>D</sub>	1.0	W
Operating temperature	T <sub>opr</sub>	0 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (Lead only)	—

\*V<sub>I</sub>, V<sub>I/O</sub>(Min) = -3.0V when pulse width is ≤20ns

## ■ DC RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub>=0V, T<sub>a</sub>=0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
	V <sub>SS</sub>		0	0	0	V
Input voltage	V <sub>IH</sub>		2.2	—	V <sub>DD</sub> +0.3	V
	V <sub>IL</sub>		-0.3*	—	0.8	V

\*V<sub>IL</sub>(Min) = -3.0V when pulse width is ≤20ns

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

(V<sub>DD</sub>=5V±10%, V<sub>SS</sub>=0V, T<sub>a</sub>=0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input leakage	I <sub>LI</sub>	V <sub>I</sub> =0 to V <sub>DD</sub>	-1	—	1	μA
Standby supply current	I <sub>DDS</sub>	$\overline{CS}=V_{IH}$	—	—	10	mA
	I <sub>DDSI</sub>	$\overline{CS} \geq V_{DD} - 0.2V$	—	—	2	mA
Average operating current	I <sub>DDA</sub>	V <sub>I</sub> =V <sub>IL</sub> , V <sub>IH</sub> I <sub>I/O</sub> =0mA t <sub>cycle</sub> =Min	—	—	120	mA
Output leakage	I <sub>LO</sub>	$\overline{CS}=V_{IH}$ or $\overline{WE}=V_{IL}$ V <sub>I/O</sub> =0 to V <sub>DD</sub>	-1	—	1	μA
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -4.0mA	2.4	—	—	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 8.0mA	—	—	0.4	V

### ● Terminal Capacitance

(f=1MHz, T<sub>a</sub>=25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Address Capacitance	C <sub>ADD</sub>		—	—	10	pF
Input Capacitance	C <sub>I</sub>		—	—	10	pF
I/O Capacitance	C <sub>I/O</sub>		—	—	10	pF

### ● AC Electrical Characteristics

#### ○ Read Cycle

(V<sub>DD</sub>=5V±10%, V<sub>SS</sub>=0V, T<sub>a</sub>=0 to 70°C)

Parameter	Symbol	Conditions	SRM21256N <sub>35</sub>		SRM21256N <sub>45</sub>		SRM21256N <sub>55</sub>		Unit
			Min	Max	Min	Max	Min	Max	
Read cycle time	t <sub>RC</sub>	*1	35	—	45	—	55	—	ns
Address access time	t <sub>ACC</sub>		—	35	—	45	—	55	ns
$\overline{CS}$ access time	t <sub>ACS</sub>		—	35	—	45	—	55	ns
$\overline{CS}$ output set time	t <sub>CLZ</sub>	*2	5	—	5	—	5	—	ns
$\overline{CS}$ output floating	t <sub>CHZ</sub>		0	15	0	20	0	25	ns
Output hold time	t <sub>OH</sub>	*1	5	—	5	—	5	—	ns

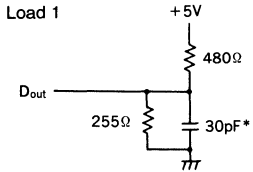
○ Write Cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=0$  to  $70^\circ C$ )

Parameter	Symbol	Conditions	SRM21256N <sub>85</sub>		SRM21256N <sub>45</sub>		SRM21256N <sub>55</sub>		Unit
			Min	Max	Min	Max	Min	Max	
Write cycle time	$t_{WC}$	* 1	35	—	45	—	55	—	ns
Chip select time	$t_{CW}$		30	—	40	—	50	—	ns
Address valid to end of write	$t_{AW}$		30	—	40	—	50	—	ns
Address setup time	$t_{AS}$		0	—	0	—	0	—	ns
Write pulse width	$t_{WP}$		25	—	35	—	45	—	ns
Address hold time	$t_{WR}$		0	—	0	—	0	—	ns
Input data set time	$t_{DW}$		15	—	20	—	25	—	ns
Input data hold time	$t_{DH}$		0	—	0	—	0	—	ns
Write to Output floating	$t_{WHZ}$		0	15	0	20	0	25	ns
Output Active from end of write	$t_{OW}$	* 2	0	—	0	—	10	—	ns

\* 1 Test Conditions

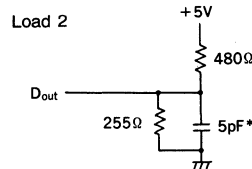
1. Input pulse level:  $V_{SS}$  to 3.0V
2.  $t_r = t_f = 5ns$
3. Input and output timing reference levels: 1.5V
4. Output load  $C_L = 30pF$



\* Including scope and jig.

\* 2 Test Conditions

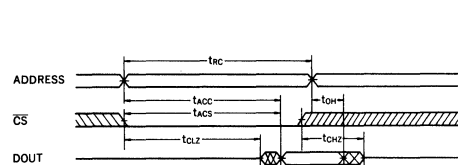
1. Input pulse level:  $V_{SS}$  to 3.0V
2.  $t_r = t_f = 5ns$
3. Input timing reference levels: 1.5V
4. Output timing reference levels:  $\pm 200mV$  (the level displaced from stable output voltage level)
5. Output load  $C_L = 5pF$



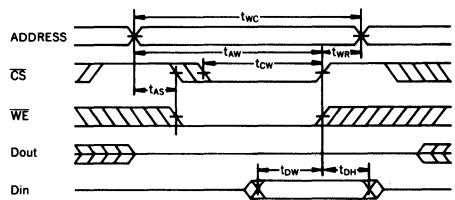
\* Including scope and jig.

● Timing Chart

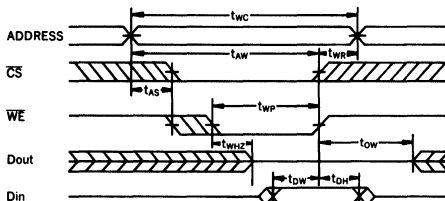
○ Read Cycle



○ Write Cycle (1) ( $\overline{CS}$  Control)



○ Write Cycle (2) ( $\overline{WE}$  Control)



Note : During read cycle time,  $\overline{WE}$  should be "H" level.

## FUNCTIONS

### Truth Table

$\overline{CS}$	$\overline{WE}$	A0 to A15	DATA I/O	Mode	$I_{DD}$
H	*	*	Hi-Z	Standby	$I_{DDs}, I_{DDs1}$
L	L	Stable	DIN	Write	$I_{DDA}$
L	H	Stable	DOUT	Read	$I_{DDA}$

\*: "H" or "L"

### Read Mode

The Data appear when the address is setted while holding  $\overline{CS}="L"$ , and  $\overline{WE}="H"$ .

### Write Mode

There are following 3 ways of writing data into memory.

- (1) Hold  $\overline{WE}="L"$ , set address and give "L" pulse to  $\overline{CS}$ .
- (2) Hold  $\overline{CS}="L"$ , set address and give "L" pulse to  $\overline{WE}$ .
- (3) After setting addresses, give "L" pulse to both  $\overline{CS}$  and  $\overline{WE}$ .

In above any case, data on the DATA I/O terminals are latched up into the SRM21256N when  $\overline{CS}$  or  $\overline{WE}$  is in positive-going. Since DATA I/O terminals are high impedance when  $\overline{CS}="H"$ , the contention on the data bus can be avoided.

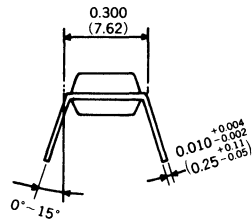
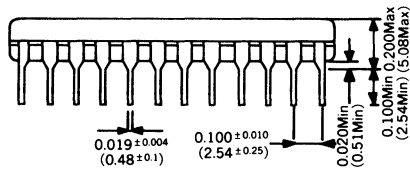
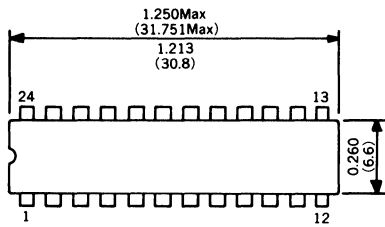
### Standby Mode

When  $\overline{CS}$  is "H" the SRM21256N is in the stand-by mode. In this case, Data I/O terminals are in Hi-Z, so that all inputs of addresses,  $\overline{WE}$  and data can be any "H" or "L".

■ PACKAGE DIMENSIONS

N24

24-pin DIP



unit : inch  
(mm)

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■ CHARACTERISTICS CURVES

Under measurement

# SMM2364C

## CMOS 64K-BIT MASK ROM

- Low Supply Current
- Access Time 350ns/450ns
- 8,192 Words × 8 Bits Asynchronous

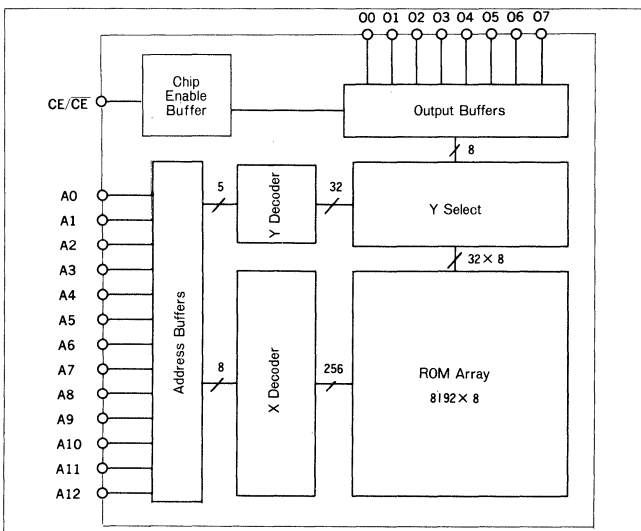
### DESCRIPTION

The SMM2364C is an 8,192 words × 8 bits asynchronous, static, mask programmable ROM on a monolithic CMOS chip and is characterized by fast access time and very low power dissipation. The nature "static" of the memory eliminates the need of an external clock. Both the input and output are TTL compatible. The 3-state output and mask programmable chip enable provide easy system design and easy expansion of the memory capacity. These features make the SMM2364C usable for wide-ranged applications, especially as a memory for low power dissipation devices using microprocessors.

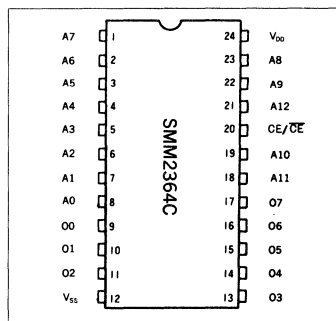
### FEATURES

- Access time .....350/450ns
- Low supply current .....standby : 0.1μA (Typ)  
operation: 15mA/12mA (Typ)
- Completely static
- Single power supply .....5V ±10%
- TTL compatible inputs and outputs
- 3-state output with wired-OR capability
- Package .....24-pin DIP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A12	Address Inputs
CE/CE	Chip Enable
O0 to O7	Data Outputs
V <sub>DD</sub>	Power Supply (+5V)
V <sub>SS</sub>	Power Supply (0V)



## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.3 to 7.0	V
Input voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Power dissipation	P <sub>D</sub>	1.0	W
DC output current	I <sub>O</sub>	10	mA
Operating temperature	T <sub>opr</sub>	-65 to 150	°C
Storage temperature	T <sub>stg</sub>	-10 to 70	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10 s (at lead)	—

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Characteristics

(V<sub>DD</sub> = +5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -10 to +70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
High level input voltage	V <sub>IH</sub>		2.2	—	V <sub>DD</sub> +0.3	V
Low level input voltage	V <sub>IL</sub>		-0.3	—	0.8	V
Input leakage current	I <sub>LI</sub>	0 ≤ V <sub>I</sub> ≤ V <sub>DD</sub>	-1.0	—	1.0	μA
Standby supply current	I <sub>DDS</sub>	CE = V <sub>SS</sub> +0.2 or CE = V <sub>DD</sub> -0.2	—	—	40	μA
Operating supply current	I <sub>DDO</sub>	with output open	—	15*/12	40*/30	mA
Output leakage current	I <sub>LO</sub>	0 ≤ V <sub>O</sub> ≤ V <sub>DD</sub>	-1.0	—	1.0	μA
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -1.0mA	2.4	—	—	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2.0mA	—	—	0.4	V
Input capacitance	C <sub>I</sub>	f = 1 MHz	—	—	7	pF
Output capacitance	C <sub>O</sub>	f = 1 MHz	—	—	10	pF

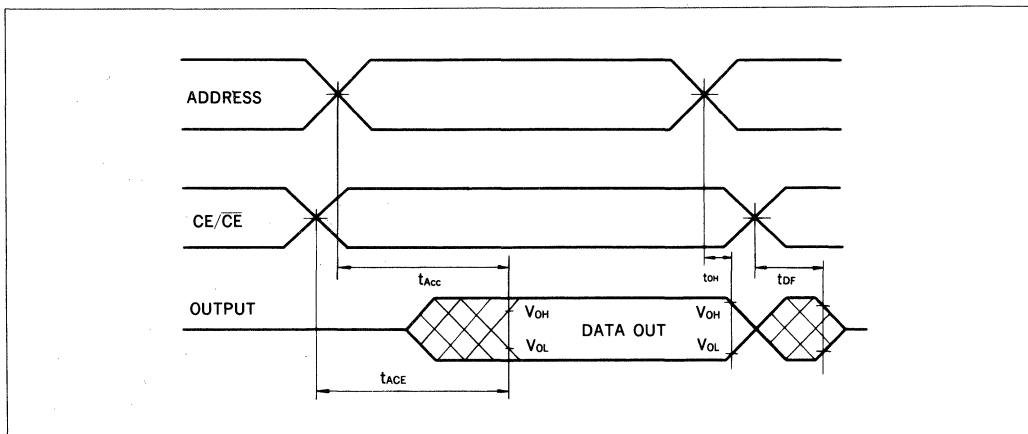
\*at access time 350ns

### ● AC Characteristics

(V<sub>DD</sub> = +5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -10 to +70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Address access time	t <sub>ACC</sub>	C <sub>L</sub> = 1TTL + 100pF	—	—	350/450	ns
CE access time	t <sub>ACE</sub>	V <sub>IH</sub> = 2.2V, V <sub>IL</sub> = 0.8V	—	—	350/450	ns
Output floating	t <sub>DF</sub>	V <sub>OH</sub> = 2.2V, V <sub>OL</sub> = 0.8V	—	—	150	ns
Output hold time	t <sub>OH</sub>	t <sub>r</sub> = t <sub>f</sub> = 10ns	0	—	—	ns

### ● Timing Chart



## FUNCTIONS

### Truth Table

CE	$\overline{\text{CE}}$	A0 to A12	O0 to O7	MODE
L	H	X	Hi-Z	Standby
H	L	Stable	Output data	Read

(X : H or L)

### Read mode

Data can be read by simply setting an address with CE held at "H" or  $\overline{\text{CE}}$  at "L".

### Standby mode

Setting CE at "L" or  $\overline{\text{CE}}$  at "H" initiates the standby mode. In this mode, the output impedance goes high and all address inputs are disabled. Within the chip, no circuit allows current flow and only the leakage current exists.

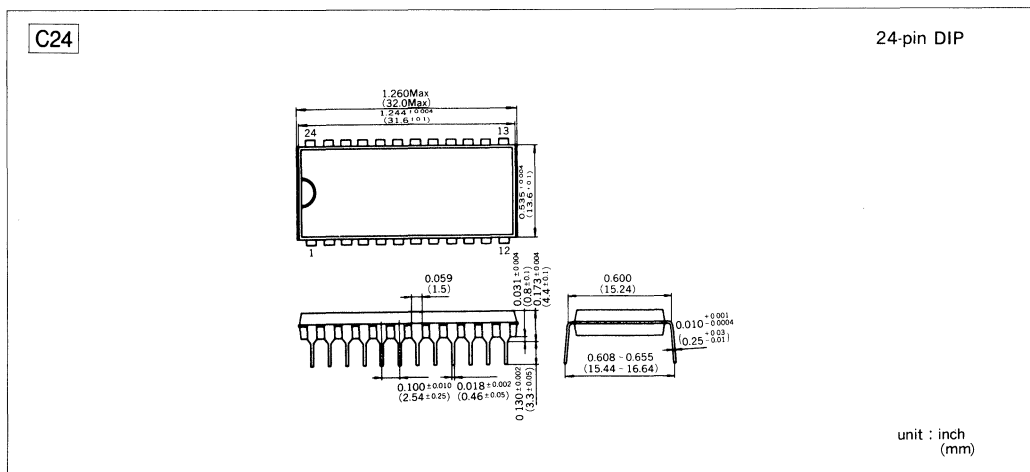
### Specifying CE/ $\overline{\text{CE}}$

CE/ $\overline{\text{CE}}$  is mask programmable and may be selected for either active level. When ordering, specify the active level of CE/ $\overline{\text{CE}}$ .

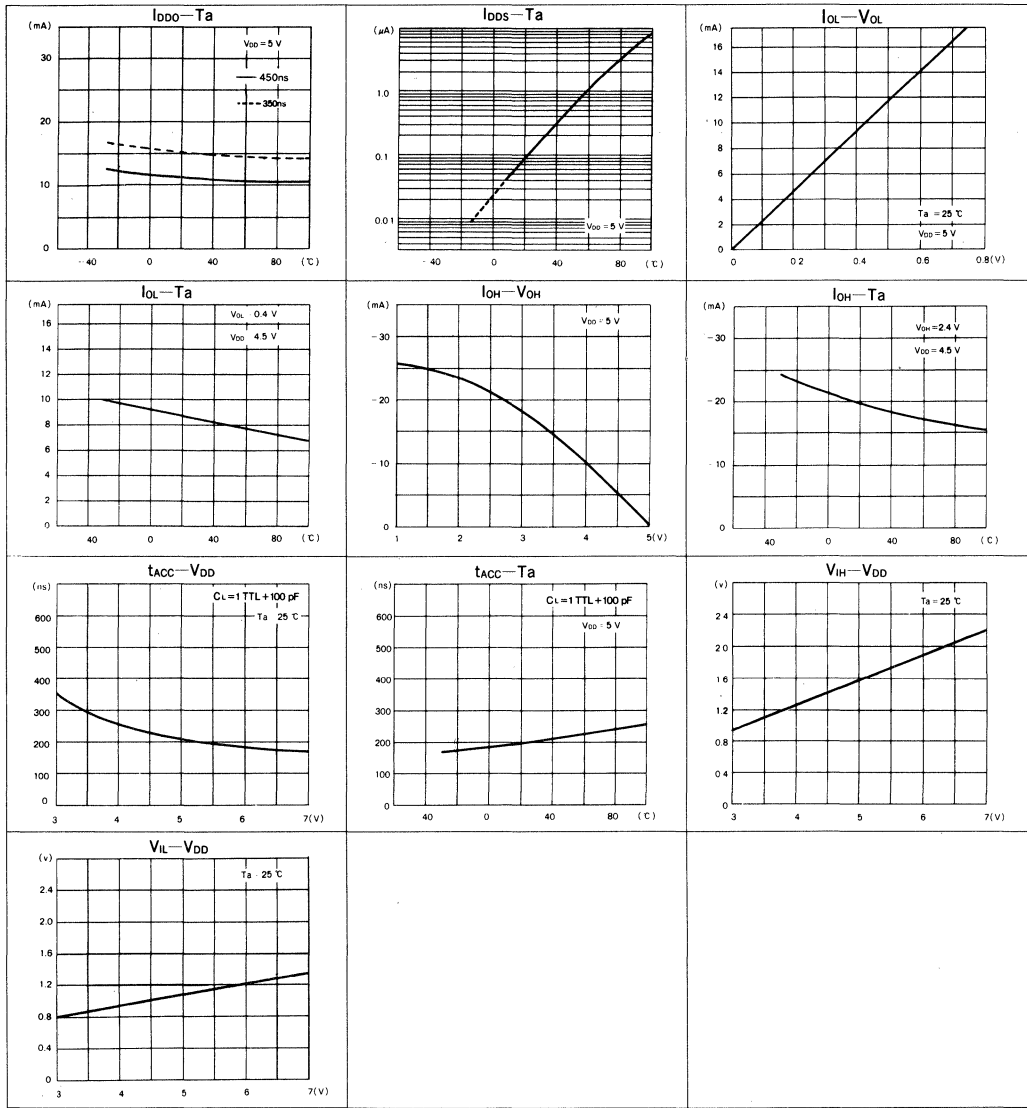
### [NOTE] RECOMMENDATIONS

- The SMM2364C is a mask programmable ROM on a CMOS chip. In the data read mode, transient current will flow in the chip at the time of transistor transition. For protection of such transients, it is recommended to connect a high-frequency capacitor and an electrolytic capacitor between the power supplies  $V_{DD}$  and  $V_{SS}$ .
- The input and output of the SMM2364C are TTL compatible. It is recommended that, when the chip is connected to TTL, pull-up resistors be connected to the CE/ $\overline{\text{CE}}$  and address input terminal.

## PACKAGE DIMENSIONS



# CHARACTERISTICS CURVES



# SMM2365C

## CMOS 64K-BIT MASK ROM

- Low Supply Current
- Access Time 350ns/450ns
- 8,192 Words × 8 Bits Asynchronous

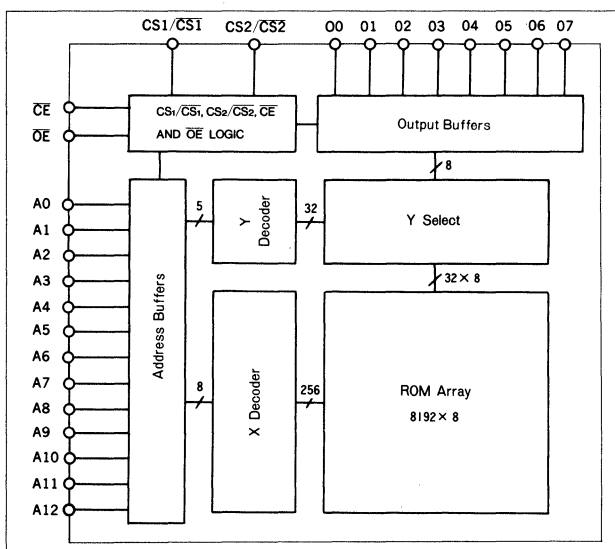
### DESCRIPTION

The SMM2365C is an 8,192 words × 8 bits asynchronous, static, mask programmable ROM on a monolithic CMOS chip and is characterized by fast access time and very low power dissipation. The nature "static" of the memory eliminates the need of an external clock. Both the input and output are TTL compatible. The 3-state output and mask programmable chip select allow for easy system design and easy expansion of the memory capacity. These features make the SMM2365C usable for a widerange of applications, especially as a memory for low power dissipation devices using microprocessors.

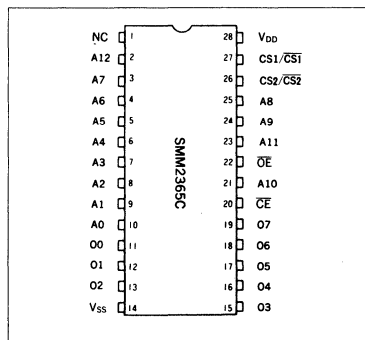
### FEATURES

- Access time.....350/450ns
- Low supply current.....standby: 0.1  $\mu$ A Typ  
operation: 15mA/12mA
- Completely static
- Single power supply .....5 V  $\pm$  10%
- TTL compatible inputs and outputs
- 3-state output with wired-OR capability
- Package.....28-pin DIP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A12	Address Input
OE	Output Enable
CE	Chip Enable
CS1/CS1, CS2/CS2	Chip Select
O0 to O7	Data Output
V <sub>DD</sub>	Power Supply (+5V)
V <sub>SS</sub>	Power Supply (0V)
NC	No Connection

## ■ ABSOLUTE MAXIMUM RATINGS

( $V_{SS}=0V$ )

Parameter	Symbol	Ratings	Unit
Supply voltage	$V_{DD}$	-0.3 to 7.0	V
Input voltage	$V_I$	-0.3 to $V_{DD}+0.3$	V
Output voltage	$V_O$	-0.3 to $V_{DD}+0.3$	V
Power dissipation	$P_D$	1.0	W
DC output current	$I_O$	10	mA
Operating temperature	$T_{opr}$	-10 to 70	°C
Storage temperature	$T_{stg}$	-65 to 150	°C
Soldering temperature and time	$T_{sol}$	260°C, 10 s (at lead)	—

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Characteristics

( $V_{DD}=+5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=-10$  to  $+70^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
High level input voltage	$V_{IH}$		2.2	—	$V_{DD}+0.3$	V
Low level input voltage	$V_{IL}$		-0.3	—	0.8	V
Input leakage current	$I_{LI}$	$0 \leq V_I \leq V_{DD}$	-1.0	—	1.0	$\mu A$
Standby supply current	$I_{DDS}$	$\overline{CE}=V_{DD}-0.2$	—	0.1	40	$\mu A$
Operating supply current	$I_{DDO}$	with output open	—	15*/12	40*/30	mA
Output leakage current	$I_{LO}$	$0 \leq V_O \leq V_{DD}$	-1.0	—	1.0	$\mu A$
High level output voltage	$V_{OH}$	$I_{OH}=-1.0mA$	2.4	—	—	V
Low level output voltage	$V_{OL}$	$I_{OL}=2.0mA$	—	—	0.4	V
Input capacitance	$C_I$	$f=1$ MHz	—	—	7	pF
Output capacitance	$C_O$	$f=1$ MHz	—	—	10	pF

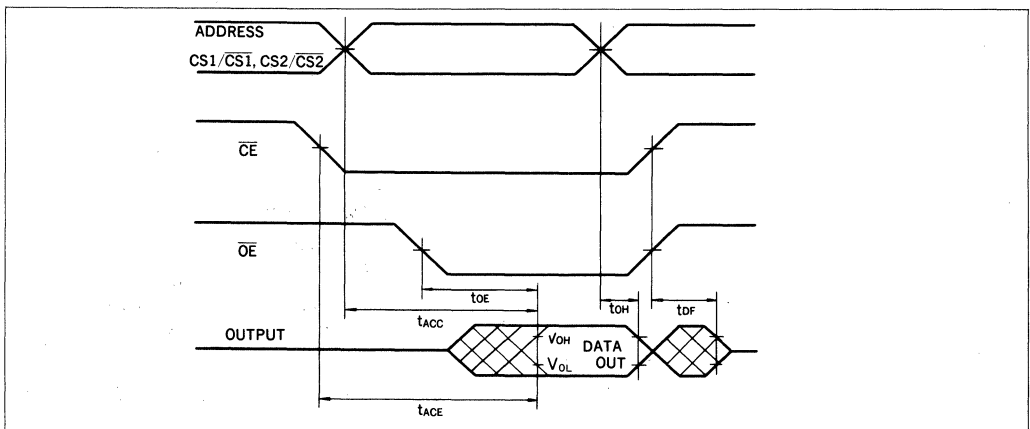
\* at access time 350 ns

### ● AC Characteristics

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=-10$  to  $+70^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Address access time	$t_{ACC}$	$C_L=1$ TTL + 100 pF $V_{IH}=2.2V$ , $V_{IL}=0.8V$ $V_{OH}=2.2V$ , $V_{OL}=0.8V$ $t_r=t_f=10$ ns	—	—	350/450	ns
$\overline{CE}$ access time	$t_{ACE}$		—	—	350/450	ns
$\overline{OE}$ access time	$t_{OE}$		—	—	150	ns
Output floating	$t_{DF}$		—	—	150	ns
Output hold time	$t_{OH}$		0	—	—	ns

### ● Timing Chart



## FUNCTIONS

### Truth Table

$\overline{CE}$	$CS1/\overline{CS1}$ , $CS2/\overline{CS2}$ , A0 to A12	$\overline{OE}$	O0 to O7	MODE
H	X	X	Hi-Z	Standby
L	Stable	H	Hi-Z	Output disable
L	Stable	L	Output data	Read

X: "H" or "L"

### Read mode

Data can be read by simply setting an address with  $\overline{CE}$  held at "L",  $\overline{OE}$  at "L",  $CS1/\overline{CS1}$ ,  $CS2/\overline{CS2}$  at each active level.

### Standby mode

Setting  $\overline{CE}$  at "H" initiates the standby mode. In this mode, the output impedance goes high and all chip select and address inputs are disabled. Within the chip, no circuit allows current flow and only the leakage current exists.

### Output disable

When  $\overline{OE}$  is set at "H", the output impedance goes high.

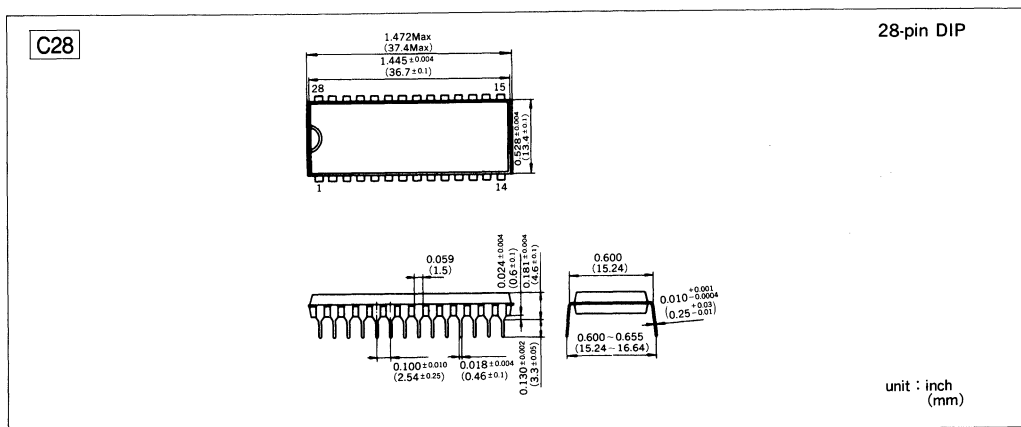
### Specifying $CS1/\overline{CS1}$ , $CS2/\overline{CS2}$

$CS1/\overline{CS1}$ ,  $CS2/\overline{CS2}$  is mask programmable and may be selected for either active level. When ordering, specify the active level of  $CS1/\overline{CS1}$ ,  $CS2/\overline{CS2}$ .

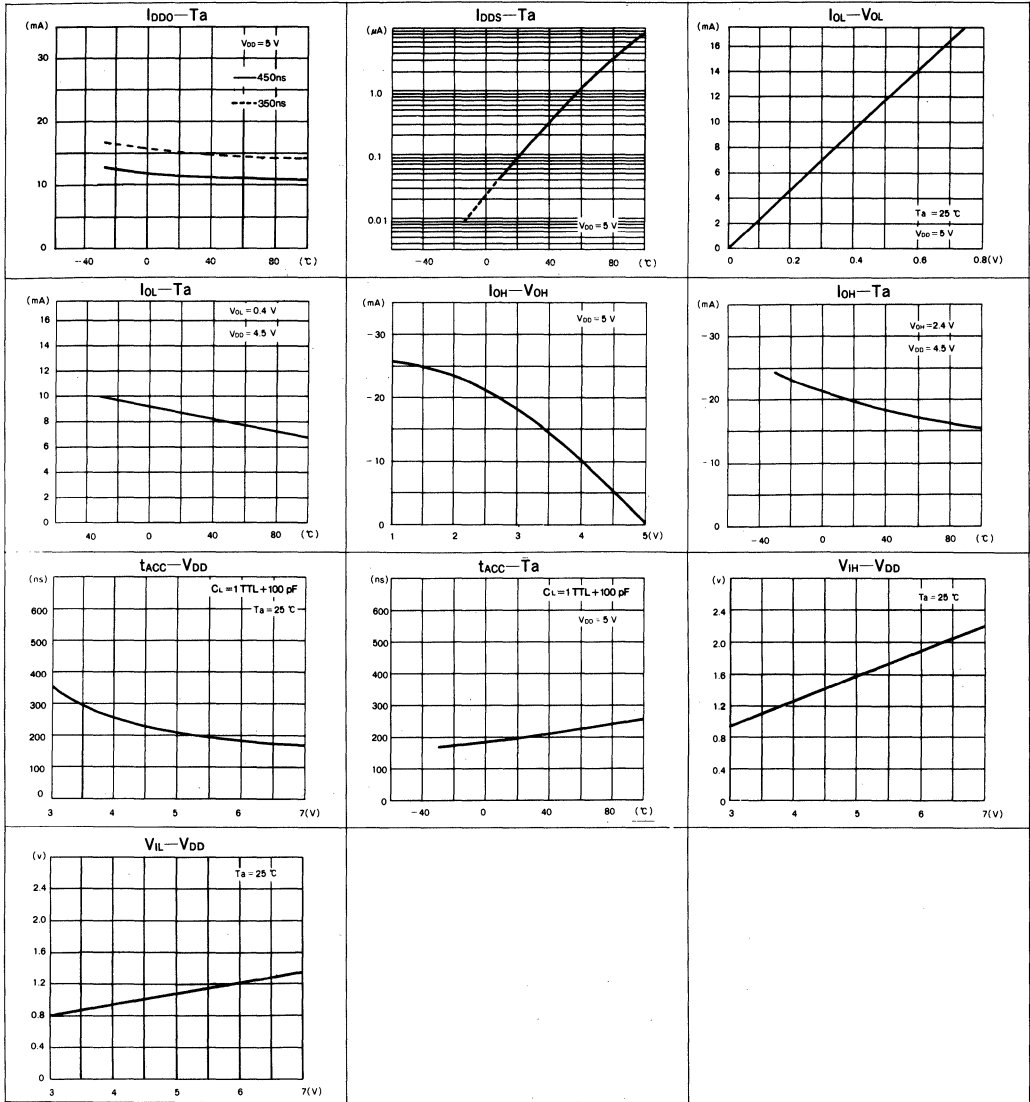
### NOTE RECOMMENDATIONS

1. The SMM2365C is a mask programmable ROM on a CMOS chip. In the data read mode, transient current will flow in the chip at the time of transistor transition. For protection of such transients, it is recommended to connect a high-frequency capacitor and an electrolytic capacitor between the power supplies  $V_{DD}$  and  $V_{SS}$ .
2. The input and output of the SMM2365C are TTL compatible. It is recommended that, when the chip is connected to TTL, pull-up resistors be connected to the  $\overline{CE}$ ,  $\overline{OE}$ , chip select and address input terminal.

## PACKAGE DIMENSIONS



# CHARACTERISTICS CURVES



# SMM6365C

## CMOS 64K-BIT MASK ROM

- Low Power Dissipation
- Access Time 250ns
- 8,192 Words × 8 Bits Asynchronous

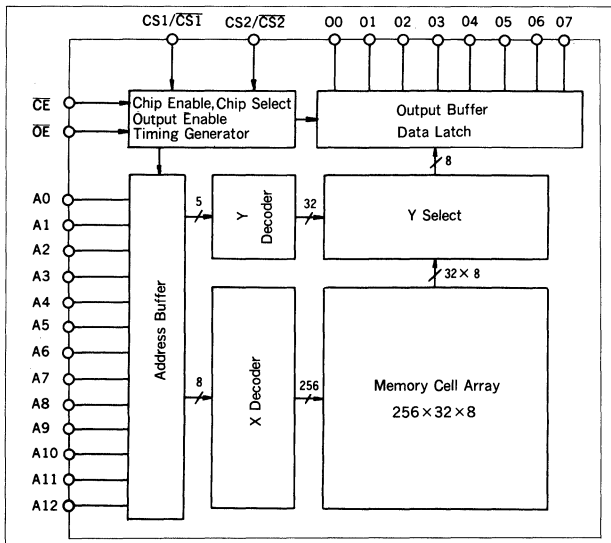
### DESCRIPTION

The SMM6365C is an 8,192 words × 8 bits asynchronous CMOS mask programmable ROM. This device operates on a single power supply, its input and output levels are TTL compatible and the outputs are 3-state types. The device does not require clock circuit; it has a detection circuit which detects the difference of address, CS1/ $\overline{CS1}$ , CS2/ $\overline{CS2}$  and  $\overline{CE}$  input. With the detected signal, the timing signal is generated (internal synchronous type). With such a significant performance, power dissipation is low, processing speed is high and it can be used for various applications.

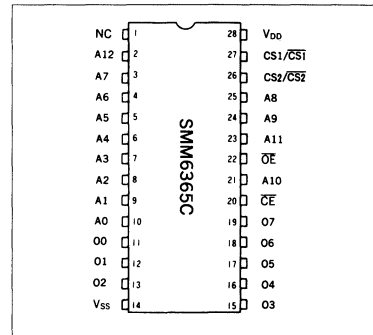
### FEATURES

- Access time ..... 250ns
- Low supply current ..... Standby: 0.1  $\mu$ A (Typ)  
Operation: 16 mA (Typ)
- Internal synchronous type
- Single power supply ..... 5V  $\pm$  10%
- TTL compatible inputs and outputs
- 3-state output with wired – OR Capability
- Package ..... 28-pin DIP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A12	Address Input
$\overline{CE}$	Chip Enable
CS1/ $\overline{CS1}$ , CS2/ $\overline{CS2}$	Chip Select
OE	Output Enable
00 to 07	Data Output
V <sub>DD</sub>	Power Supply (+5V)
V <sub>SS</sub>	Power Supply (0V)
NC	No connection



## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5 to V <sub>DD</sub> + 0.3	V
Output voltage	V <sub>O</sub>	-0.5 to V <sub>DD</sub> + 0.3	V
Power dissipation	P <sub>D</sub>	1.0	W
DC output current	I <sub>O</sub>	10	mA
Operating temperature	T <sub>opr</sub>	-10 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10 s (at lead)	—

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Characteristics

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -10 to +70°C)

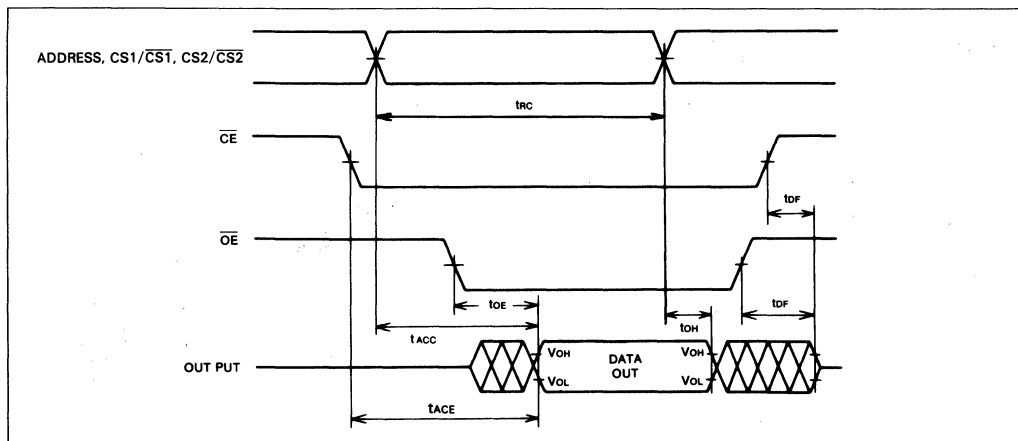
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
High level input voltage	V <sub>IH</sub>		2.2	—	V <sub>DD</sub> + 0.3	V
Low level input voltage	V <sub>IL</sub>		-0.5	—	0.8	V
Input leakage current	I <sub>LI</sub>	0 ≤ V <sub>I</sub> ≤ V <sub>DD</sub>	-2.0	—	2.0	μA
Standby supply current	I <sub>DDS</sub>	$\overline{CE} = V_{DD} - 0.2$	—	0.1	40	μA
Operating supply current	I <sub>DDO</sub>	with output open	—	16	30	mA
Output leakage current	I <sub>LO</sub>	0 ≤ V <sub>O</sub> ≤ V <sub>DD</sub>	-10.0	—	10.0	μA
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -1.0mA	2.4	—	—	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 3.2mA	—	—	0.4	V
Input capacitance	C <sub>I</sub>	f = 1 MHz	—	—	10	pF
Output capacitance	C <sub>O</sub>	f = 1 MHz	—	—	15	pF

### ● AC Characteristics

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -10 to +70°C)

Parameter	Symbol	Conditions	Min	Max	Unit
Read cycle time	t <sub>rc</sub>	C <sub>L</sub> = 1TTL + 100pF	250	—	ns
Address access time	t <sub>acc</sub>	V <sub>IH</sub> = 2.2V	—	250	ns
$\overline{CE}$ access time	t <sub>ACE</sub>	V <sub>IL</sub> = 0.8V	—	250	ns
$\overline{OE}$ access time	t <sub>OE</sub>	V <sub>OH</sub> = 1.5V	—	80	ns
Output floating	t <sub>DF</sub>	V <sub>OL</sub> = 1.5V	—	80	ns
Output hold time	t <sub>OH</sub>	t <sub>r</sub> = t <sub>f</sub> = 10ns	0	—	ns

### ● Timing Chart



## FUNCTIONS

### Truth Table

$\overline{CE}$	CS1/ $\overline{CS1}$ , CS2/ $\overline{CS2}$ , A0 to A12	$\overline{OE}$	O0 to O7	MODE
H	X	X	Hi-Z	Standby
L	Stable	H	Hi-Z	Output Disable
L	Stable	L	Data out	Read

X: "H" or "L"

### Read mode

Data can be read by simply setting an address with  $\overline{CE}$  held at "L",  $\overline{OE}$  held at "L" and CS1/ $\overline{CS1}$ , CS2/ $\overline{CS2}$  held at active level. At the time of power-on, the initial state cannot be determined because of the operation of internal clock circuit. If the power is on in the mode of holding  $\overline{CE}$  = "L" and a certain address is fixed, the data related to the address may not appear. Data should be read after the supply voltage becomes stable, and  $\overline{CE}$  is set at "H" or the address input is changed in the mode of  $\overline{CE}$  = "L".

### Standby mode

Setting  $\overline{CE}$  at "H" initiates the standby mode. In this mode, the output impedance goes high and all address input is disabled. Within the chip, no circuit allows current flow and only the leakage current exists.

### Output disable

When  $\overline{OE}$  is set at "H", the output impedance goes high.

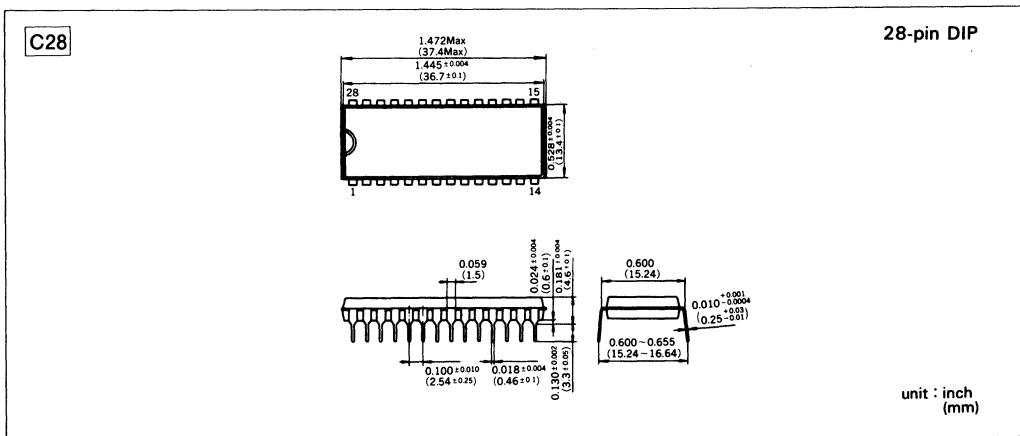
### Specifying CS1/ $\overline{CS1}$ , CS2/ $\overline{CS2}$

CS1/ $\overline{CS1}$ , CS2/ $\overline{CS2}$  is mask programmable and may be selected for either active level. When ordering, specify the active level of CS1/ $\overline{CS1}$ , CS2/ $\overline{CS2}$ .

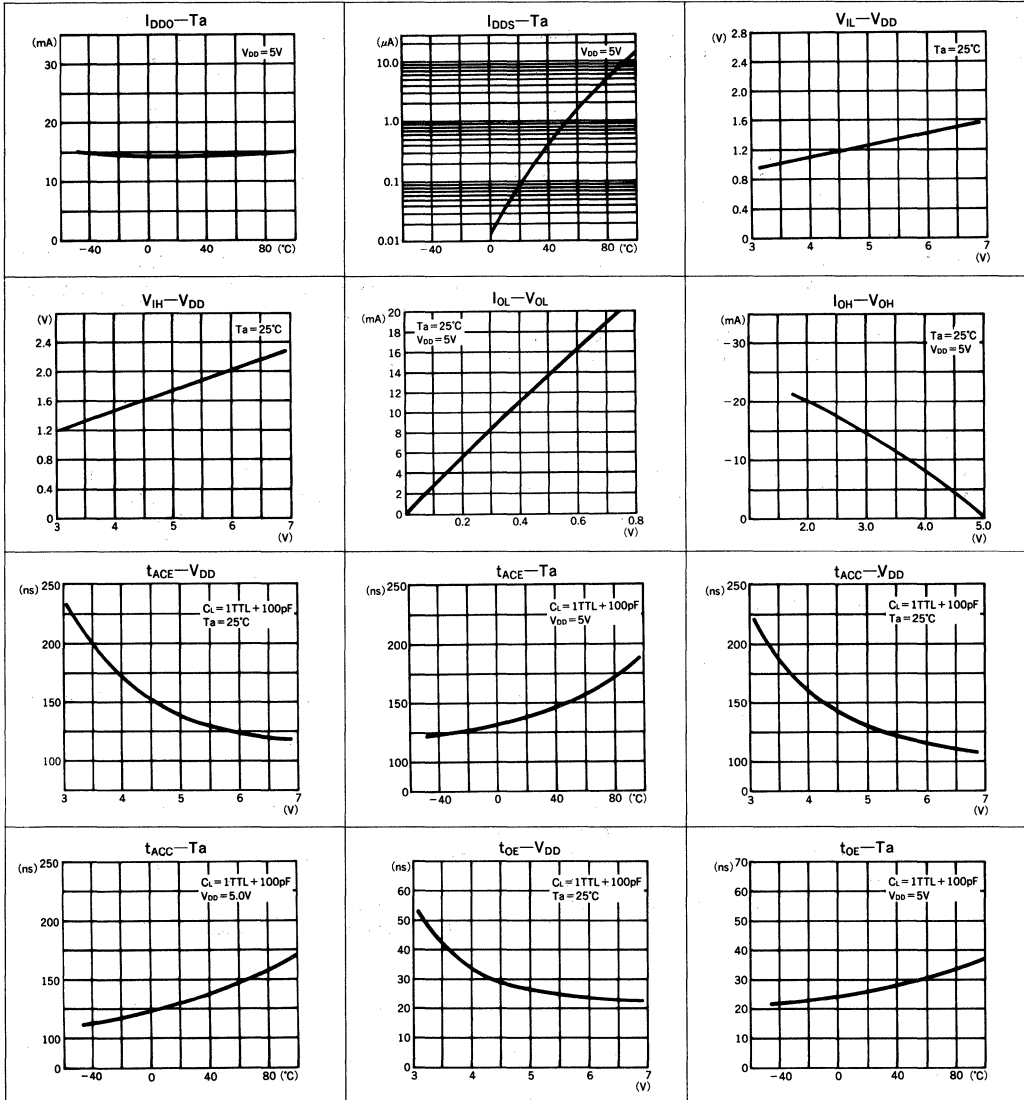
## [NOTE] RECOMMENDATIONS

- The SMM6365C is a mask programmable ROM on a CMOS chip. In the data read mode, transient current will flow in the chip at the time of transistor switching transition. For protection of such transients, it is recommended to connect a high-frequency capacitor and an electrolytic capacitor between the power supplies  $V_{DD}$  and  $V_{SS}$ .
- The input and output of the SMM6365C are TTL compatible. It is recommended that, when the chip is connected to TTL, pull-up resistors be connected to the  $\overline{CE}$ , CS1/ $\overline{CS1}$ , CS2/ $\overline{CS2}$ ,  $\overline{OE}$  and address input terminal.

## PACKAGE DIMENSIONS



## CHARACTERISTICS CURVES



# SMM6312C

## CMOS 128K-BIT MASK ROM

- Low Supply Current
- Access Time 250ns
- 16,384 Words × 8 Bits Asynchronous

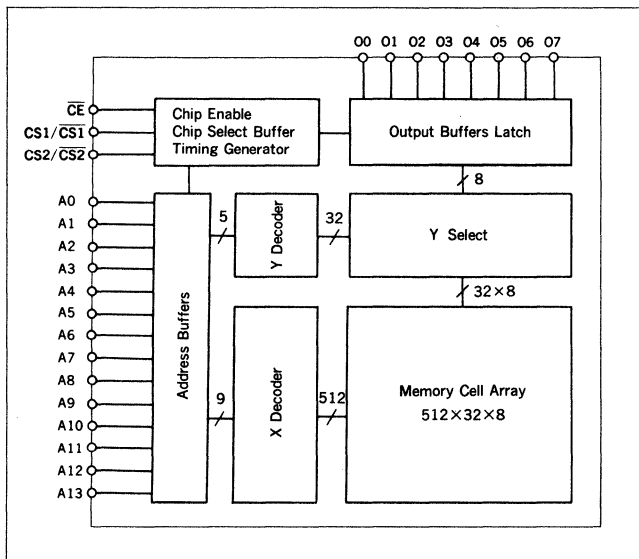
### DESCRIPTION

The SMM6312C is a 16,384 words × 8 bits asynchronous CMOS mask programmable ROM. This device operates on a single power supply, its input and output levels are TTL compatible and the outputs are 3 state types. This device does not require clock circuit ; it has a detection circuit which detects the difference of address, CS1/ $\overline{CS1}$ , CS2/ $\overline{CS2}$  and  $\overline{CE}$  input. With the detected signal, the timing signal is generated (internal synchronous type). With such a significant performance, power dissipation is low, processing speed is high and it can be used for various applications.

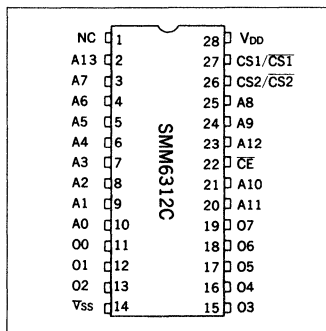
### FEATURES

- Access time .....250ns
- Low supply current .....standby : 0.1 $\mu$ A (Typ)  
operation : 16mA (Typ)
- Single power supply .....5V $\pm$ 10%
- Internal synchronous type
- TTL compatible inputs and outputs
- 3-state output with wired-OR capability
- Package .....28-pin DIP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A13	Address Input
CE	Chip Enable
CS1/ $\overline{CS1}$ , CS2/ $\overline{CS2}$	Chip Select
O0 to O7	Data Output
V <sub>DD</sub>	Power Supply (+5V)
V <sub>SS</sub>	Power Supply (0V)
NC	No connection

## ■ ABSOLUTE MAXIMUM RATINGS

( $V_{SS}=0V$ )

Parameter	Symbol	Ratings	Unit
Supply voltage	$V_{DD}$	-0.5 to 7.0	V
Input voltage	$V_I$	-0.5 to $V_{DD}+0.3$	V
Output voltage	$V_O$	-0.5 to $V_{DD}+0.3$	V
Power dissipation	$P_D$	1.0	W
DC output current	$I_O$	10	mA
Operating temperature	$T_{opr}$	-10 to 70	°C
Storage temperature	$T_{stg}$	-65 to 150	°C
Soldering temperature and time	$T_{sol}$	260°C, 10s (at lead)	—

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Characteristics

( $V_{DD}=+5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a = -10$  to  $+70^\circ C$ )

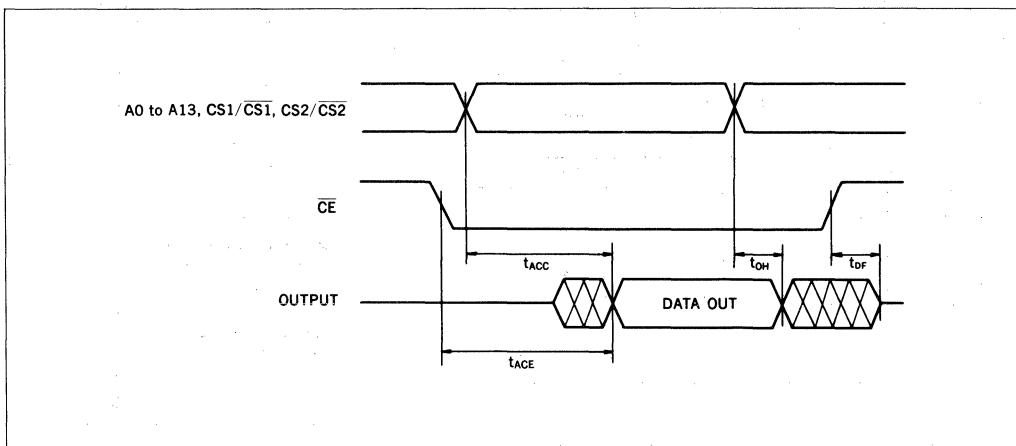
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
High level input voltage	$V_{IH}$		2.2	—	$V_{DD}+0.3$	V
Low level input voltage	$V_{IL}$		-0.5	—	0.8	V
Input leakage current	$I_{LI}$	$0 \leq V_I \leq V_{DD}$	-2.0	—	2.0	$\mu A$
Standby supply current	$I_{DDS}$	$CE = V_{DD} - 0.2V$	—	0.1	40	$\mu A$
Operating supply current	$I_{DDO}$	with output open	—	16	30	mA
Output leakage current	$I_{LO}$	$0 \leq V_O \leq V_{DD}$	-10.0	—	10.0	$\mu A$
High level output voltage	$V_{OH}$	$I_{OH} = -1.0mA$	2.4	—	—	V
Low level output voltage	$V_{OL}$	$I_{OL} = 3.2mA$	—	—	0.4	V
Input capacitance	$C_I$	$f = 1MHz$	—	—	10	pF
Output capacitance	$C_O$	$f = 1MHz$	—	—	15	pF

### ● AC Characteristics

( $V_{DD}=+5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a = -10$  to  $+70^\circ C$ )

Parameter	Symbol	Conditions	Min	Max	Unit
Read cycle time	$t_{RC}$	$C_L = 1TTL + 100pF$	250	—	ns
Address access time	$t_{ACC}$	$V_{IH} = 2.2V$	—	250	ns
CE access time	$t_{ACE}$	$V_{IL} = 0.8V$	—	250	ns
Output floating	$t_{DF}$	$V_{OH} = 1.5V$	—	80	ns
Output hold time	$t_{OH}$	$V_{OL} = 1.5V$	0	—	ns
		$t_r = t_f = 10ns$			

### ● Timing Chart



## FUNCTIONS

### Truth Table

$\overline{CE}$	$\overline{CS1}/\overline{CS1}, \overline{CS2}/\overline{CS2}, A0$ to $A13$	$O0$ to $O7$	MODE
H	X	Hi-Z	Standby
L	Stable	Output data	Read

X: "H" or "L"

### Read mode

Data can be read by simply setting an address with  $\overline{CE}$  held at "L",  $\overline{CS1}/\overline{CS1}, \overline{CS2}/\overline{CS2}$  at each active level. At the time of power-on the initial state cannot be determined because of the operation of the internal clock circuit. If the power is on in the mode of holding  $\overline{CE}$  "L" and a certain address is fixed, the data related to the address may not appear. Data should be read after the supply voltage becomes stable, and  $\overline{CE}$  is set at "H" or the address input is changed in the mode of  $\overline{CE}$  "L".

### Standby mode

Setting  $\overline{CE}$  at "H" initiates the standby mode. In this mode, the output impedance goes high and all address input is disabled.

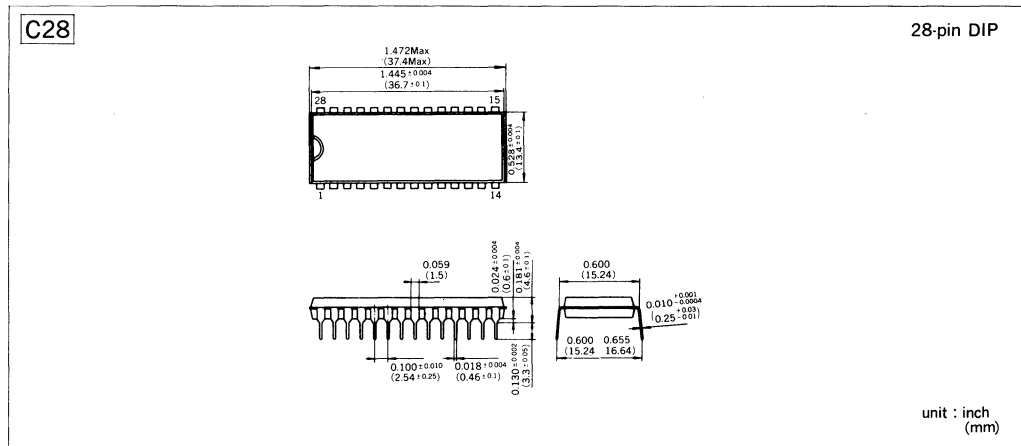
### Specifying $\overline{CS1}/\overline{CS1}, \overline{CS2}/\overline{CS2}$

$\overline{CS1}/\overline{CS1}, \overline{CS2}/\overline{CS2}$  is mask programmable and may be selected for either active level. When ordering, specify the active level.

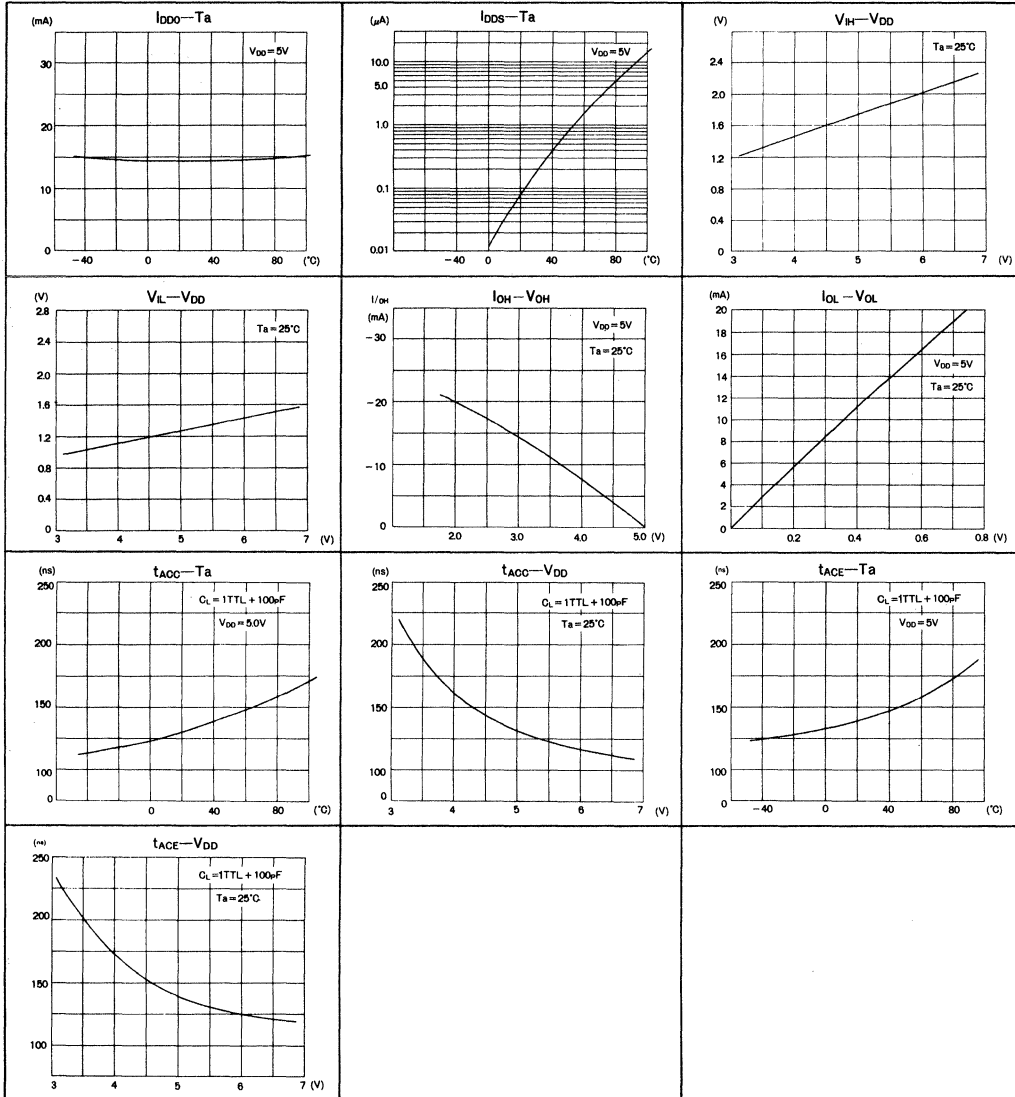
### [NOTE] RECOMMENDATIONS

- The SMM6312C is a mask programmable ROM on a CMOS chip. In the data read mode, transient current will flow in the chip at the time of transistor transition. For protection of such transients, it is recommended to connect a high-frequency capacitor and an electrolytic capacitor between the power supplies  $V_{DD}$  and  $V_{SS}$ .
- The input and output of SMM6312C are TTL compatible. It is recommended that, when the chip is connected to TTL, pull up resistors be connected to the  $\overline{CE}, \overline{CS1}/\overline{CS1}, \overline{CS2}/\overline{CS2}$  and address input terminal.

## PACKAGE DIMENSIONS



# CHARACTERISTICS CURVES



# SMM6313C

## CMOS 128K-BIT MASK ROM

- Low Supply Current
- Access Time 250ns
- 16,384 Words × 8 Bits Asynchronous

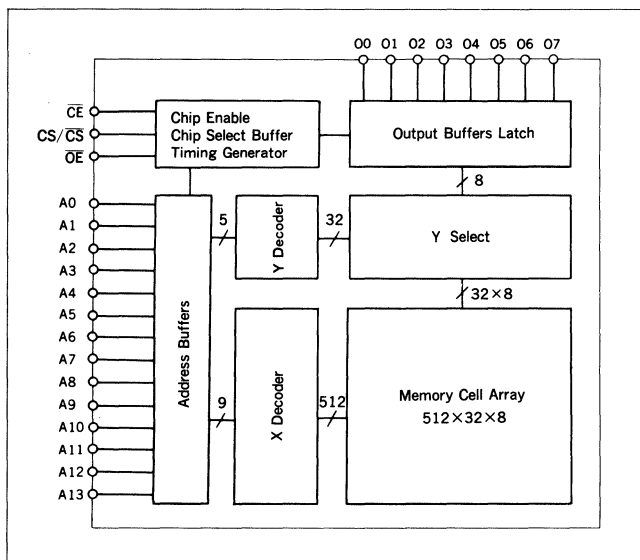
### DESCRIPTION

The SMM6313C is a 16,384 words × 8 bits asynchronous CMOS mask programmable ROM. This device operates on a single power supply, its input and output levels are TTL compatible and the outputs are 3 state types. This device does not require clock circuit ; it has a detection circuit which detects the difference of address, CS/CS and CE input. With the detected signal, the timing signal is generated (internal synchronous type). With such a significant performance, power dissipation is low, processing speed is high and it can be used for various applications.

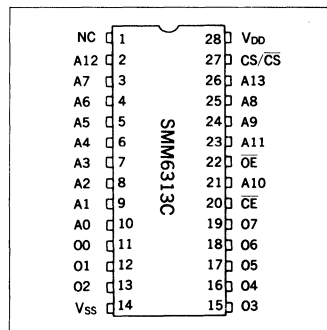
### FEATURES

- Access time .....250ns
- Low supply current .....standby : 0.1μA (Typ)  
operation : 16mA (Typ)
- Single power supply .....5V ± 10%
- Internal synchronous type
- TTL compatible inputs and outputs
- 3-state output with wired-OR capability
- Package .....28-pin DIP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A13	Address Input
CE	Chip Enable
CS/CS	Chip Select
OE	Output Enable
O0 to O7	Data Output
V <sub>DD</sub>	Power Supply (+5V)
V <sub>SS</sub>	Power Supply (0V)
NC	No connection



## ■ ABSOLUTE MAXIMUM RATINGS

( $V_{SS}=0V$ )

Parameter	Symbol	Ratings	Unit
Supply voltage	$V_{DD}$	-0.5 to 7.0	V
Input voltage	$V_I$	-0.5 to $V_{DD}+0.3$	V
Output voltage	$V_O$	-0.5 to $V_{DD}+0.3$	V
Power dissipation	$P_D$	1.0	W
DC output current	$I_O$	10	mA
Operating temperature	$T_{opr}$	-10 to 70	°C
Storage temperature	$T_{stg}$	-65 to 150	°C
Soldering temperature and time	$T_{sol}$	260°C, 10s (at lead)	—

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Characteristics

( $V_{DD}=+5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a = -10$  to  $+70^\circ C$ )

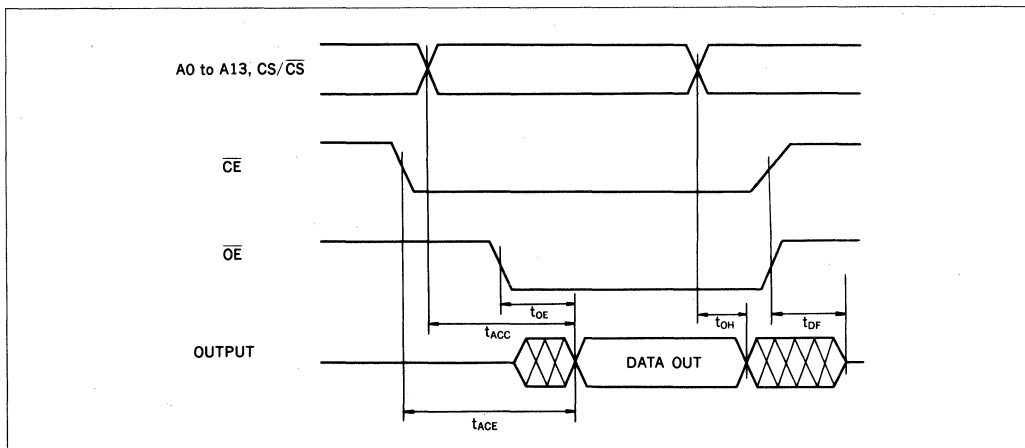
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
High level input voltage	$V_{IH}$		2.2	—	$V_{DD}+0.3$	V
Low level input voltage	$V_{IL}$		-0.5	—	0.8	V
Input leakage current	$I_{LI}$	$0 \leq V_I \leq V_{DD}$	-2.0	—	2.0	$\mu A$
Standby supply current	$I_{DDS}$	$\overline{CE} = V_{DD} - 0.2V$	—	0.1	40	$\mu A$
Operating supply current	$I_{DDO}$	with output open	—	16	30	mA
Output leakage current	$I_{LO}$	$0 \leq V_O \leq V_{DD}$	-10.0	—	10.0	$\mu A$
High level output voltage	$V_{OH}$	$I_{OH} = -1.0mA$	2.4	—	—	V
Low level output voltage	$V_{OL}$	$I_{OL} = 3.2mA$	—	—	0.4	V
Input capacitance	$C_i$	$f = 1MHz$	—	—	10	pF
Output capacitance	$C_o$	$f = 1MHz$	—	—	15	pF

### ● AC Characteristics

( $V_{DD}=+5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a = -10$  to  $+70^\circ C$ )

Parameter	Symbol	Conditions	Min	Max	Unit
Read cycle time	$t_{RC}$	$C_L = 1TTL + 100pF$	250	—	ns
Address access time	$t_{ACC}$	$V_{IH} = 2.2V$	—	250	ns
$\overline{CE}$ access time	$t_{ACE}$	$V_{IL} = 0.8V$	—	250	ns
$\overline{OE}$ access time	$t_{OE}$	$V_{OH} = 1.5V$	—	80	ns
Output floating	$t_{DF}$	$V_{OL} = 1.5V$	—	80	ns
Output hold time	$t_{OH}$	$t_r = t_f = 10ns$	0	—	ns

### ● Timing Chart



## FUNCTIONS

### Truth Table

$\overline{CE}$	CS/ $\overline{CS}$ , A0 to A13	$\overline{OE}$	O0 to O7	MODE
H	X	X	Hi-Z	Standby
L	Stable	H	Hi-Z	Output disable
L	Stable	L	Output data	Read

X: "H" or "L"

### Read mode

Data can be read by simply setting an address with  $\overline{CE}$  held at "L",  $\overline{OE}$  at "L", CS/ $\overline{CS}$  at each active level. At the time of power-on the initial state cannot be determined because of the operation of the internal clock circuit. If the power is on in the mode of holding  $\overline{CE}$  "L" and a certain address is fixed, the data related to the address may not appear. Data should be read after the supply voltage becomes stable, and  $\overline{CE}$  is set at "H" or the address input is changed in the mode of  $\overline{CE}$  "L".

### Standby mode

Setting  $\overline{CE}$  at "H" initiates the standby mode. In this mode, the output impedance goes high and all address input is disabled.

### Output disable

When  $\overline{OE}$  is set at "H", the output impedance goes high.

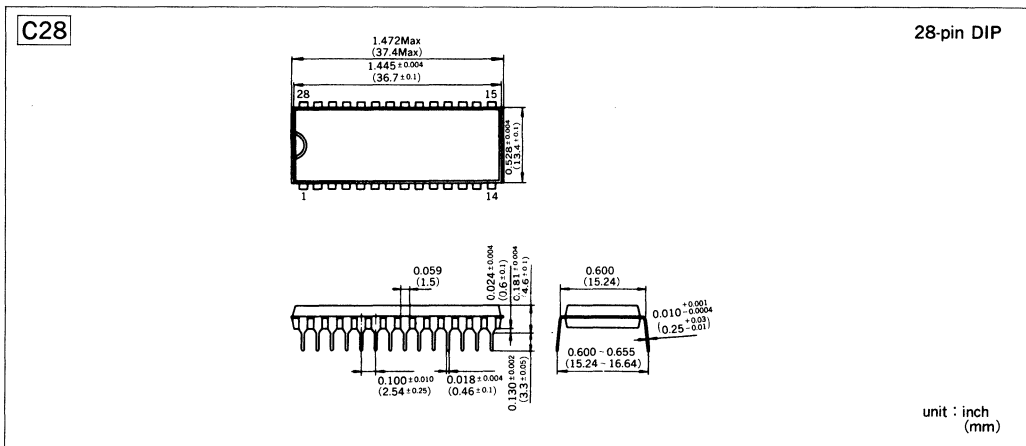
### Specifying CS/ $\overline{CS}$

CS/ $\overline{CS}$  is mask programmable and may be selected for either active level. When ordering, specify the active level.

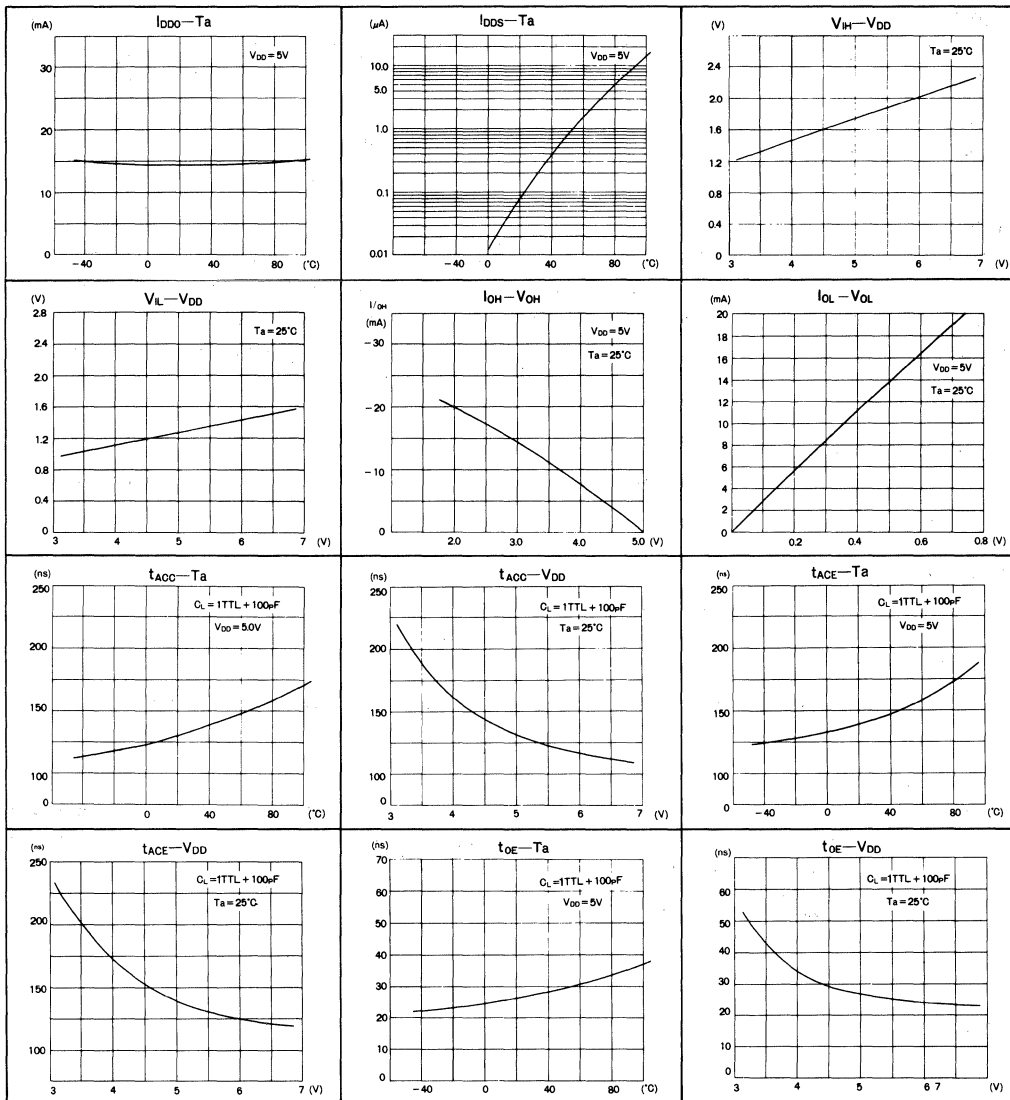
### [NOTE] RECOMMENDATIONS

- The SMM6313C is a mask programmable ROM on a CMOS chip. In the data read mode, transient current will flow in the chip at the time of transistor transition. For protection of such transients, it is recommended to connect a high-frequency capacitor and an electrolytic capacitor between the power supplies  $V_{DD}$  and  $V_{SS}$ .
- The input and output of SMM6313C are TTL compatible. It is recommended that, when the chip is connected to TTL, pull up resistors be connected to the  $\overline{CE}$ , CS/ $\overline{CS}$  and address input terminal.

## PACKAGE DIMENSIONS



# CHARACTERISTICS CURVES



# SMM6325C

## CMOS 256K-BIT MASK ROM

- Low Supply Current
- Access Time 250 ns
- 32,768 Words × 8 Bits Asynchronous

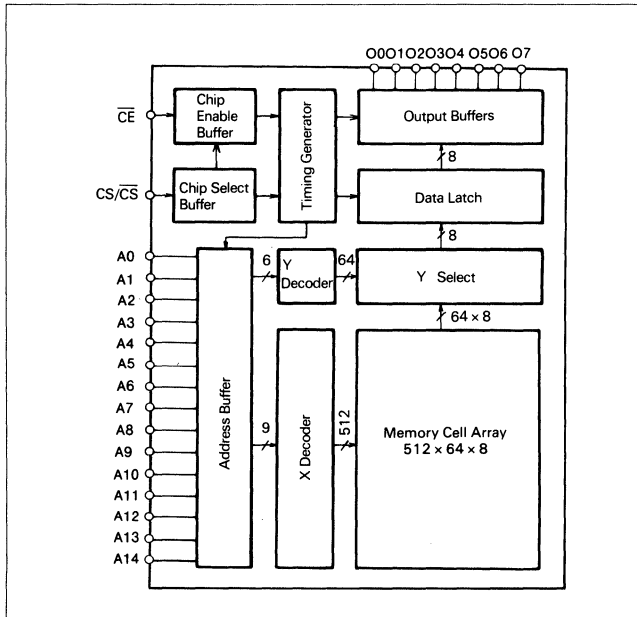
### DESCRIPTION

The SMM6325C is a 32,768 words × 8 bits asynchronous CMOS mask programmable ROM. This device operates on a single power supply, its input and output levels are TTL compatible and the outputs are 3-state types. The device does not require clock circuit; it has a detection circuit which detects the difference of address, CS/ $\overline{CS}$  and  $\overline{CE}$  input. With the detected signal, the timing signal is generated (internal synchronous type). With such a significant performance, supply current is low, processing speed is high and it can be used for various applications.

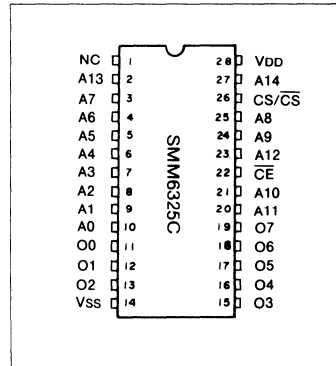
### FEATURES

- Access time ..... 250 ns
- Low supply current ..... Standby : 0.1  $\mu$ A (Typ)  
Operation: 16mA (Typ)
- Internal synchronous type
- Single power supply ..... 5V  $\pm$  10%
- TTL compatible inputs and outputs
- 3-state output with wired – OR capability
- Package ..... 28-pin DIP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A14	Address Input
$\overline{CE}$	Chip Enable
CS/ $\overline{CS}$	Chip Select
O0 to O7	Data Output
VDD	Power Supply (+5V)
VSS	Power Supply (0V)
NC	No connection

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5 to V <sub>DD</sub> + 0.3	V
Output voltage	V <sub>O</sub>	-0.5 to V <sub>DD</sub> + 0.3	V
Power dissipation	P <sub>d</sub>	1.0	W
DC output current	I <sub>O</sub>	10	mA
Operating temperature	T <sub>opr</sub>	-10 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10 s (at lead)	—

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Characteristics

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -10 to 70°C)

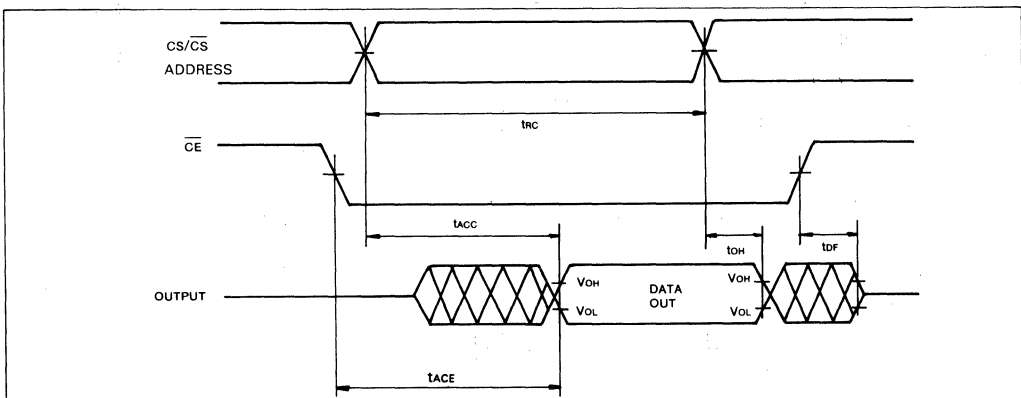
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
High level input voltage	V <sub>IH</sub>		2.2	—	V <sub>DD</sub> + 0.3	V
Low level input voltage	V <sub>IL</sub>		-0.5	—	0.8	V
Input leakage current	I <sub>LI</sub>	0 ≤ V <sub>I</sub> ≤ V <sub>DD</sub>	2.0	—	2.0	μA
Standby supply current	I <sub>DDS</sub>	$\overline{CE} = V_{DD} - 0.2$	—	0.1	40	μA
Operating supply current	I <sub>DDO</sub>	with output open	—	16	30	mA
Output leakage current	I <sub>LO</sub>	0 ≤ V <sub>O</sub> ≤ V <sub>DD</sub>	-10.0	—	10.0	μA
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -1.0 mA	2.4	—	—	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 3.2 mA	—	—	0.4	V
Input capacitance	C <sub>I</sub>	f = 1 MHz	—	—	10	pF
Output capacitance	C <sub>O</sub>	f = 1 MHz	—	—	15	pF

### ● AC Characteristics

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -10 to +70°C)

Parameter	Symbol	Conditions	Min	Max	Unit
Read cycle time	t <sub>RC</sub>	CL = 1TTL + 100 pF	250	—	ns
Address access time	t <sub>ACC</sub>	V <sub>IH</sub> = 2.2V V <sub>IL</sub> = 0.8V	—	250	ns
$\overline{CE}$ access time	t <sub>ACE</sub>	V <sub>OH</sub> = 1.5V V <sub>OL</sub> = 1.5V	—	250	ns
Output floating	t <sub>DF</sub>	V <sub>OL</sub> = 1.5V	—	80	ns
Output hold time	t <sub>OH</sub>	t <sub>r</sub> = t <sub>f</sub> = 10ns	0	—	ns

### ● Timing Chart



■ FUNCTIONS

● Truth Table

$\overline{CE}$	CS/ $\overline{CS}$ , A0 to A14	O0 to O7	MODE
H	X	Hi-Z	Standby
L	Stable	Output data	Read

X: H or L

● Read mode

Data can be read by simply setting an address and CS/ $\overline{CS}$  with  $\overline{CE}$  held at "L". At the time of power-on, the initial state cannot be determined because of the operation of the internal clock circuit. If the power is on in the mode of  $\overline{CE}$  = "L" and a certain address is fixed, the data related to the address may not appear. Data should be read after the supply voltage becomes stable, and  $\overline{CE}$  is set at "H" or the address input is changed in the mode of  $\overline{CE}$  = "L".

● Standby mode

Setting  $\overline{CE}$  at "H" initiates the standby mode. In this mode, the output impedance goes high and all address input is disabled. Within the chip, no circuit allows current flow.

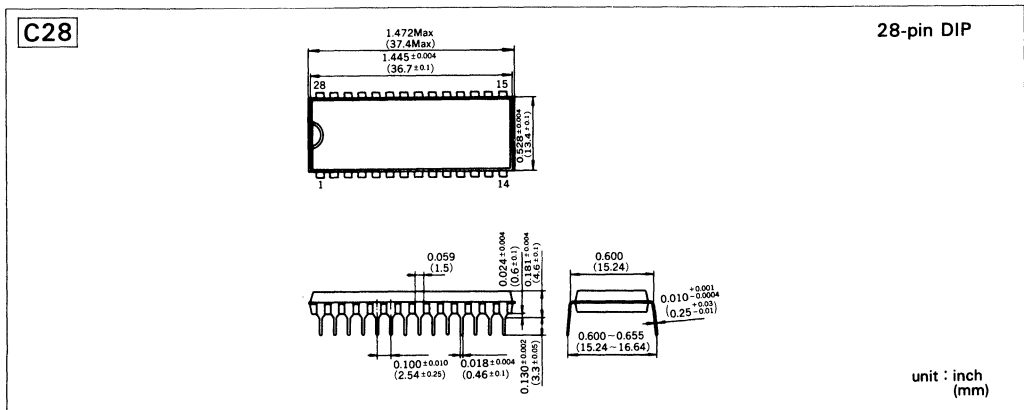
● Specifying CS/ $\overline{CS}$

CS/ $\overline{CS}$  is mask programmable and may be selected for either active level. When ordering, specify the active level CS/ $\overline{CS}$ .

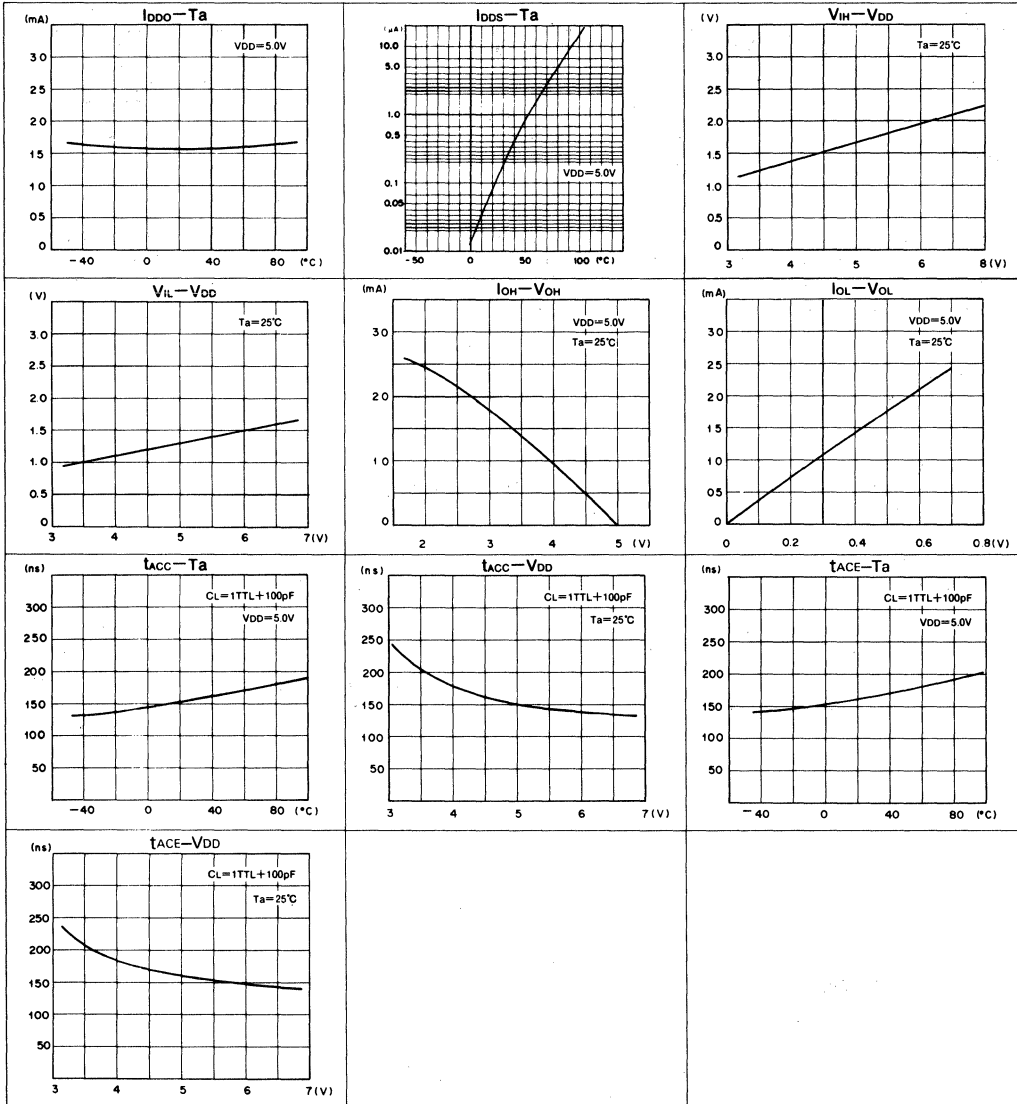
[NOTE] RECOMMENDATIONS

- The SMM6325C is a mask programmable ROM on a CMOS chip. In the data read mode, transient current will flow in the chip at the time of transistor transition. For protection of such transients, it is recommended to connect a high-frequency capacitor and onelectrolytic capacitor between the power supplies VDD and VSS.
- The input and output of the SMM6325C are TTL compatible. It is recommended that, when the chip is connected to TTL, pull-up resistors be connected to the  $\overline{CE}$ , CS/ $\overline{CS}$  and address input terminal.

■ PACKAGE DIMENSIONS



# CHARACTERISTICS CURVES



# SMM6326C

## CMOS 256K-BIT MASK ROM

- Low Supply Current
- Access Time 250 ns
- 32,768 Words × 8 Bits Asynchronous

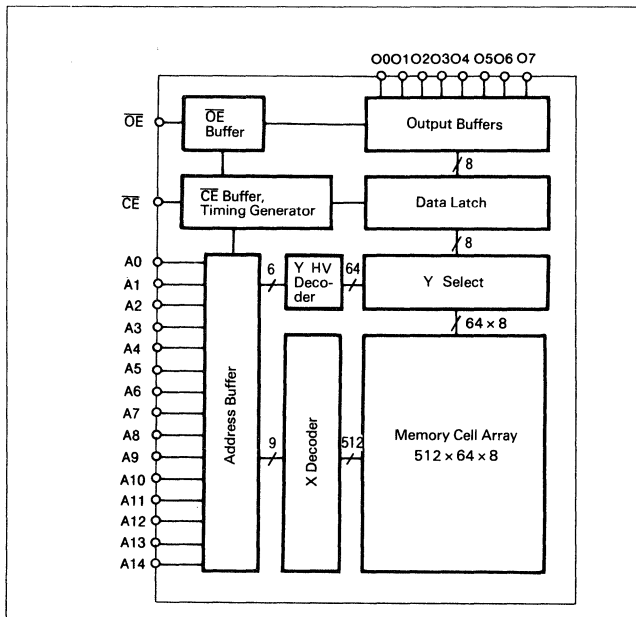
### DESCRIPTION

The SMM6326C is a 32,768 words × 8 bits asynchronous CMOS mask programmable ROM. This device operates on a signal power supply, its input and output levels are TTL compatible and the outputs are 3-state types. The device does not require clock circuit; it has a detection circuit which detects the difference of address and CE input. With the detected signal, the timing signal is generated (internal synchronous type). With such a significant performance, supply current is low, processing speed is high and it can be used for various applications.

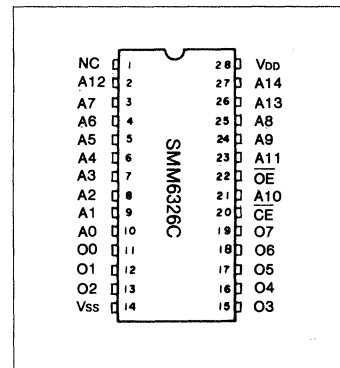
### FEATURES

- Access time ..... 250ns
- Low supply current ..... Standby: 0.1 μA (Typ)  
Operation: 16 mA (Typ)
- Internal synchronous type
- Single power supply ..... 5V ± 10%
- TTL compatible inputs and outputs
- 3-state output with wired – OR Capability
- Package..... 28-pin DIP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A14	Address Input
CE	Chip Enable
OE	Output Enable
O0 to O7	Data Output
V <sub>DD</sub>	Power Supply (+5V)
V <sub>SS</sub>	Power Supply (0V)
NC	No connection



## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5 to V <sub>DD</sub> + 0.3	V
Output voltage	V <sub>O</sub>	-0.5 to V <sub>DD</sub> + 0.3	V
Power dissipation	P <sub>D</sub>	1.0	W
DC output current	I <sub>O</sub>	10	mA
Operating temperature	T <sub>opr</sub>	-10 to 70	°C
Storage temperature	T <sub>stg</sub>	-55 to 125	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10 s (at lead)	—

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Characteristics

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -10 to +70°C)

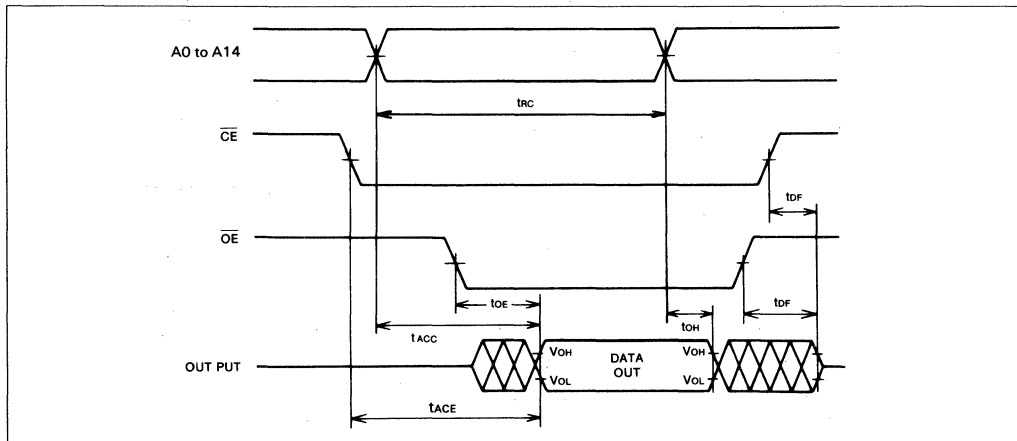
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
High level input voltage	V <sub>IH</sub>		2.2	—	V <sub>DD</sub> + 0.3	V
Low level input voltage	V <sub>IL</sub>		-0.5	—	0.8	V
Input leakage current	I <sub>LI</sub>	0 ≤ V <sub>I</sub> ≤ V <sub>DD</sub>	-2.0	—	2.0	μA
Standby supply current	I <sub>DDS</sub>	$\overline{CE} = V_{DD} - 0.2$	—	0.1	40	μA
Operating supply current	I <sub>DDO</sub>	with output open	—	16	30	mA
Output leakage current	I <sub>LO</sub>	0 ≤ V <sub>O</sub> ≤ V <sub>DD</sub>	-10.0	—	10.0	μA
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -1.0mA	2.4	—	—	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 3.2mA	—	—	0.4	V
Input capacitance	C <sub>I</sub>	f = 1 MHz	—	—	10	pF
Output capacitance	C <sub>O</sub>	f = 1 MHz	—	—	15	pF

### ● AC Characteristics

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -10 to +70°C)

Parameter	Symbol	Conditions	Min	Max	Unit
Read cycle time	t <sub>RC</sub>	C <sub>L</sub> = ITTL + 100pF	250	—	ns
Address access time	t <sub>ACC</sub>	V <sub>IH</sub> = 2.2V	—	250	ns
$\overline{CE}$ access time	t <sub>ACE</sub>	V <sub>IL</sub> = 0.8V	—	250	ns
$\overline{OE}$ access time	t <sub>OE</sub>	V <sub>OH</sub> = 1.5V	—	80	ns
Output floating	t <sub>DF</sub>	V <sub>OL</sub> = 1.5V	—	80	ns
Output hold time	t <sub>OH</sub>	t <sub>r</sub> = t <sub>f</sub> = 10ns	0	—	ns

### ● Timing Chart



## ■ FUNCTIONS

### ● Truth Table

$\overline{CE}$	A0 to A14	$\overline{OE}$	O0 to O7	MODE
H	X	X	Hi-Z	Standby
L	Stable	H	Hi-Z	Output disable
L	Stable	L	Output data	Read

X: "H" or "L"

### ● Read mode

Data can be read by simply setting an address with  $\overline{CE}$  held at "L". At the time of power-on, the initial state cannot be determined because of the operation of the internal clock circuit. If the power is on in the mode of holding  $\overline{CE} = "L"$  and a certain address is fixed, the data related to the address may not appear. Data should be read after the supply voltage becomes stable, and  $\overline{CE}$  is set at "H" or the address input is changed in the mode of  $\overline{CE} = "L"$ .

### ● Standby mode

Setting  $\overline{CE}$  at "H" initiates the standby mode. In this mode, the output impedance goes high and all address input is disabled. Within the chip, no circuit allows current flow and only the leakage current exists.

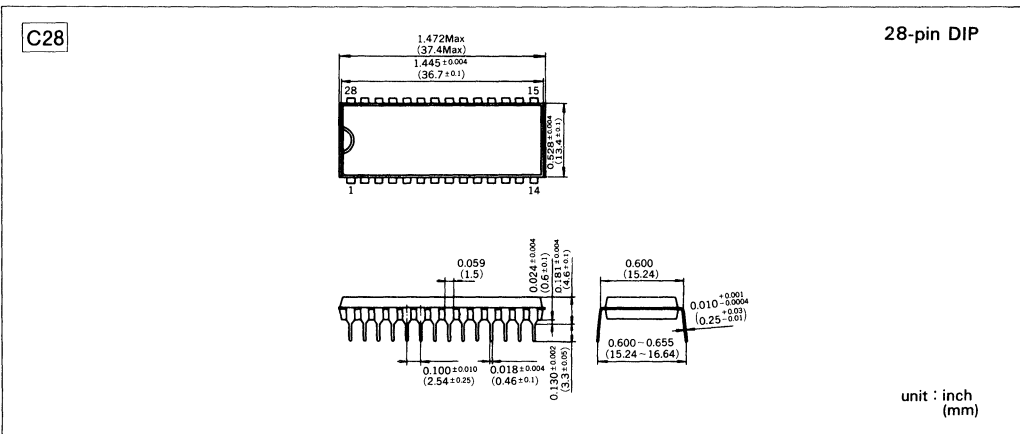
### ● Output disable

When  $\overline{OE}$  is set at "H", the output impedance goes high.

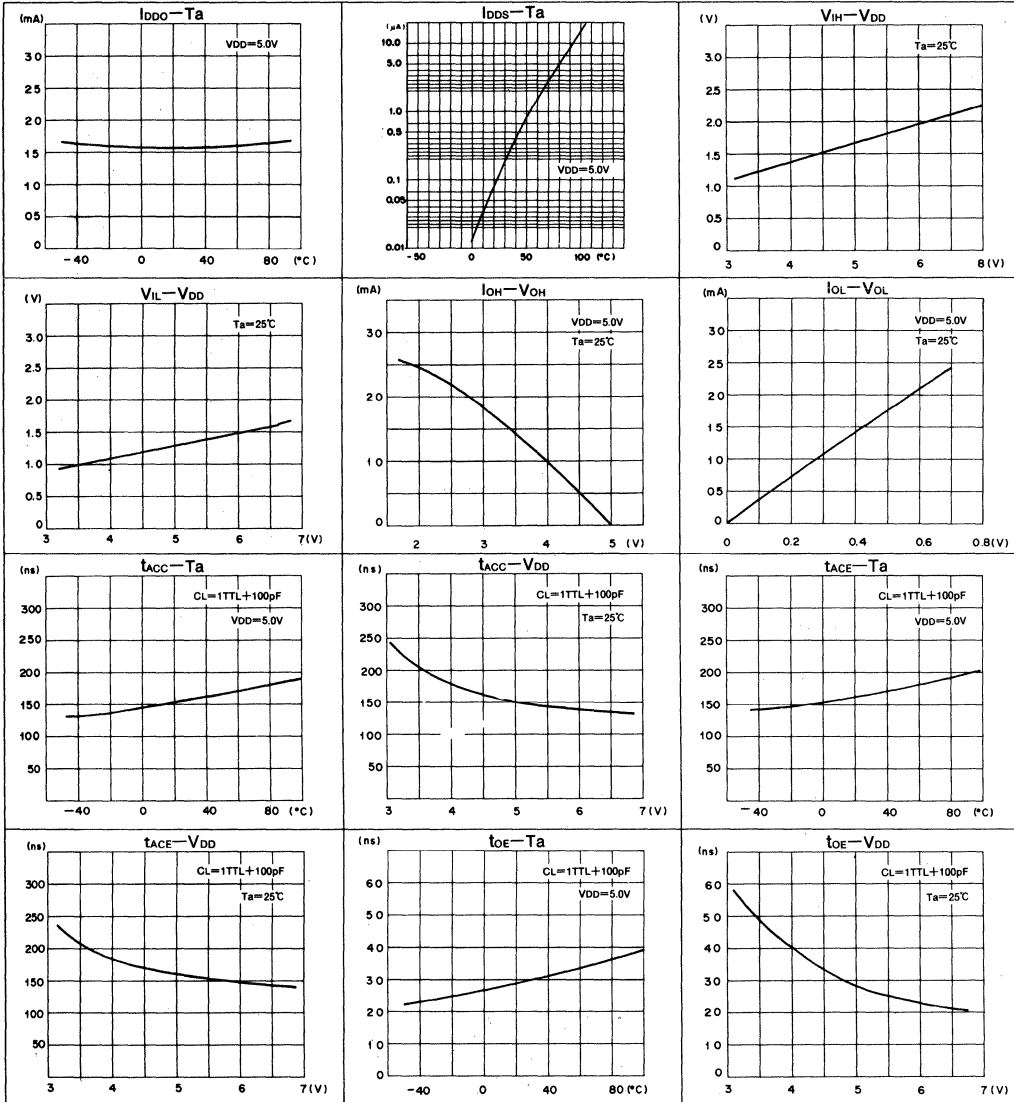
## [NOTE] RECOMMENDATIONS

- The SMM6326C is a mask programmable ROM on a CMOS chip. In the data read mode, transient current will flow in the chip at the time of transistor transition.  
For protection of such transients, it is recommended to connect a high-frequency capacitor and an electrolytic capacitor between the power supplies VDD and VSS.
- The input and output of the SMM6326C are TTL compatible. It is recommended that, when the chip is connected to TTL, pull-up resistors be connected to the  $\overline{CE}$ ,  $\overline{OE}$  and address input terminal.

## ■ PACKAGE DIMENSIONS



# CHARACTERISTICS CURVES



# SMM43100C

## CMOS 1M-BIT MASK ROM

*Preliminary*  
Under Development

- Low supply current
- Access time 100ns
- 131,072 words × 8 bits asynchronous

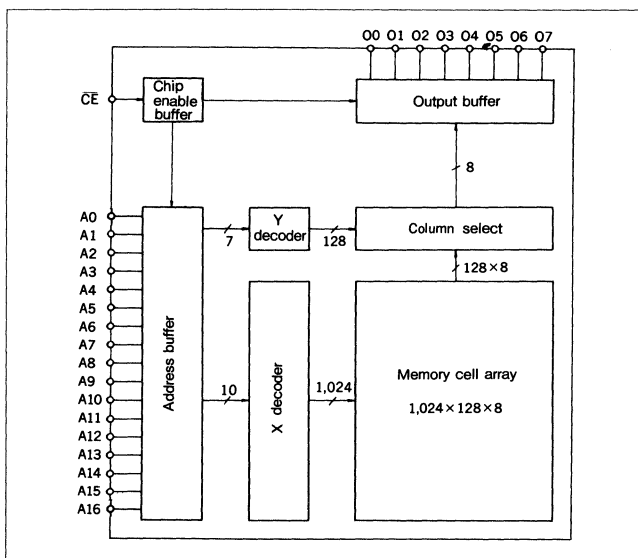
### DESCRIPTION

The SMM43100C is a 131,072 words × 8 bits mask programmable asynchronous CMOS read-only memory (ROM) and operates on a single power source. Both the input and output ports are TTL compatible with 3-state output. This memory requires no external clock, since it has perfect static operation.

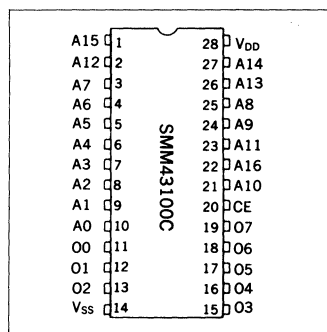
### FEATURES

- Access time .....100ns
- Low supply current .....Standby : 0.1 $\mu$ A (Typ)  
Operation : 30mA (Typ)
- Asynchronous type
- Single power supply .....5V $\pm$ 10%
- TTL-compatible input and output
- 3-state output with wired-OR capability
- Package .....28-pin DIP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

A0 to A16	Address input
CE	Chip enable
00 to 07	Data output
VDD	Power supply(+ 5V)
VSS	Power supply(0V)

## ■ ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Ratings	Unit
Supply voltage	$V_{DD}$	-0.3 to 7.0	V
Input voltage	$V_I$	-0.3 to $V_{DD}+0.3$	V
Output voltage	$V_O$	-0.3 to $V_{DD}+0.3$	V
Power dissipation	$P_D$	1.0	W
Output current	$I_O$	10	mA
Operating temperature	$T_{opr}$	-10 to 70	°C
Storage temperature	$T_{stg}$	-65 to 150	°C
Soldering temperature and time	$T_{sol}$	260°C, 10s (at lead)	—

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

( $V_{DD}=5V \pm 10\%$ ,  $T_a = -10^\circ$  to  $70^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ*	Max	Unit
High level input voltage	$V_{IH}$	—	2.2	—	$V_{DD}+0.3$	V
Low level input voltage	$V_{IL}$	—	-0.3	—	0.8	V
Input leakage current	$I_{LI}$	$0 \leq V_I \leq V_{DD}$	-2.0	—	2.0	$\mu A$
Standby supply current	$I_{DDs}$	$CE = V_{DD}-0.2$	—	0.1	40	$\mu A$
Operating supply current	$I_{DDO}$	with output pin open	—	30	50	mA
Output leakage current	$I_{LO}$	$0 \leq V_O \leq V_{DD}$	-10.0	—	10.0	$\mu A$
High level output voltage	$V_{OH}$	$I_{OH} = -1.0mA$	2.4	—	—	V
Low level output voltage	$V_{OL}$	$I_{OL} = 3.2mA$	—	—	0.4	V
Input terminal capacitance	$C_I$	$f = 1MHz$	—	—	10	pF
Output terminal capacitance	$C_O$	$f = 1MHz$	—	—	15	pF

\*Typical values are measured at  $V_{DD}=5V$  and  $T_a = 25^\circ C$

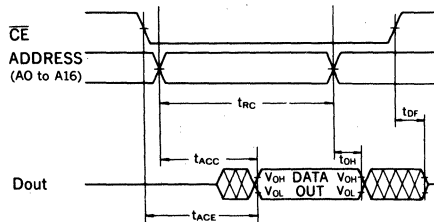
### ● AC Electrical Characteristics

( $V_{DD}=5V \pm 10\%$ ,  $T_a = -10^\circ$  to  $70^\circ C$ )

Parameter	Symbol	Conditions	Min	Max	Unit
Read cycle time	$t_{RC}$	<ul style="list-style-type: none"> <li>Input pulse level : <math>V_{IH}=2.4V</math> <math>V_{IL}=0.6V</math></li> <li><math>C_L = 1TTL + 100pF</math></li> <li>Input/Output Reference level : 1.5V</li> <li><math>t_r = t_f = 10ns</math></li> </ul>	100	—	ns
Address access time	$t_{ACC}$		—	100	ns
CE access time	$t_{ACE}$		—	100	ns
Output floating time	$t_{DF}$		—	40	ns
Output hold time	$t_{OH}$		0	—	ns

### ● Timing Chart

#### ○ Read Cycle



## FUNCTIONS

### Truth table

$\overline{CE}$	A0 to A16	O0 to O7	Mode
H	X	High impedance	Standby
L	Stable	Output data	Read

X: "H" or "L"

### Reading data

Data can be read by setting addresses while holding  $\overline{CE} = "L"$ .

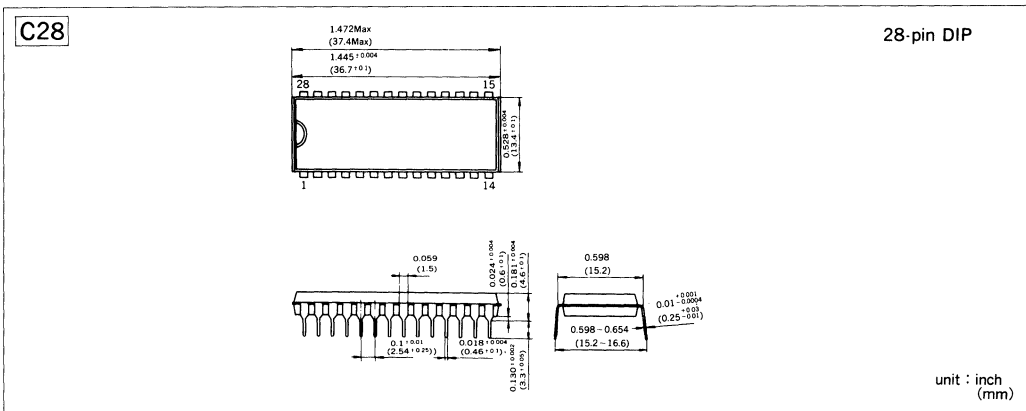
### Standby mode

When  $\overline{CE}$  is "H", the memory is in the standby mode. In this mode, the output terminals are in the high impedance state and any input of address is prohibited. There will be no current flow except for leakage in the chip.

### [Note] Recommendations

- Although the SMM43100C is a CMOS mask ROM, transient current will flow at the time of transistors transition in data read operation. For protection of such transient current, it is recommended to connect a high-frequency capacitor and an electrolytic capacitor between power supply lines  $V_{DD}$  and  $V_{SS}$ .
- Although the input and output ports of the SMM43100C are TTL compatible, when it is connected to TTL ICs, it is advisable to connect a pull-up resistor to each of the  $\overline{CE}$  and the address input terminals.

## PACKAGE DIMENSIONS



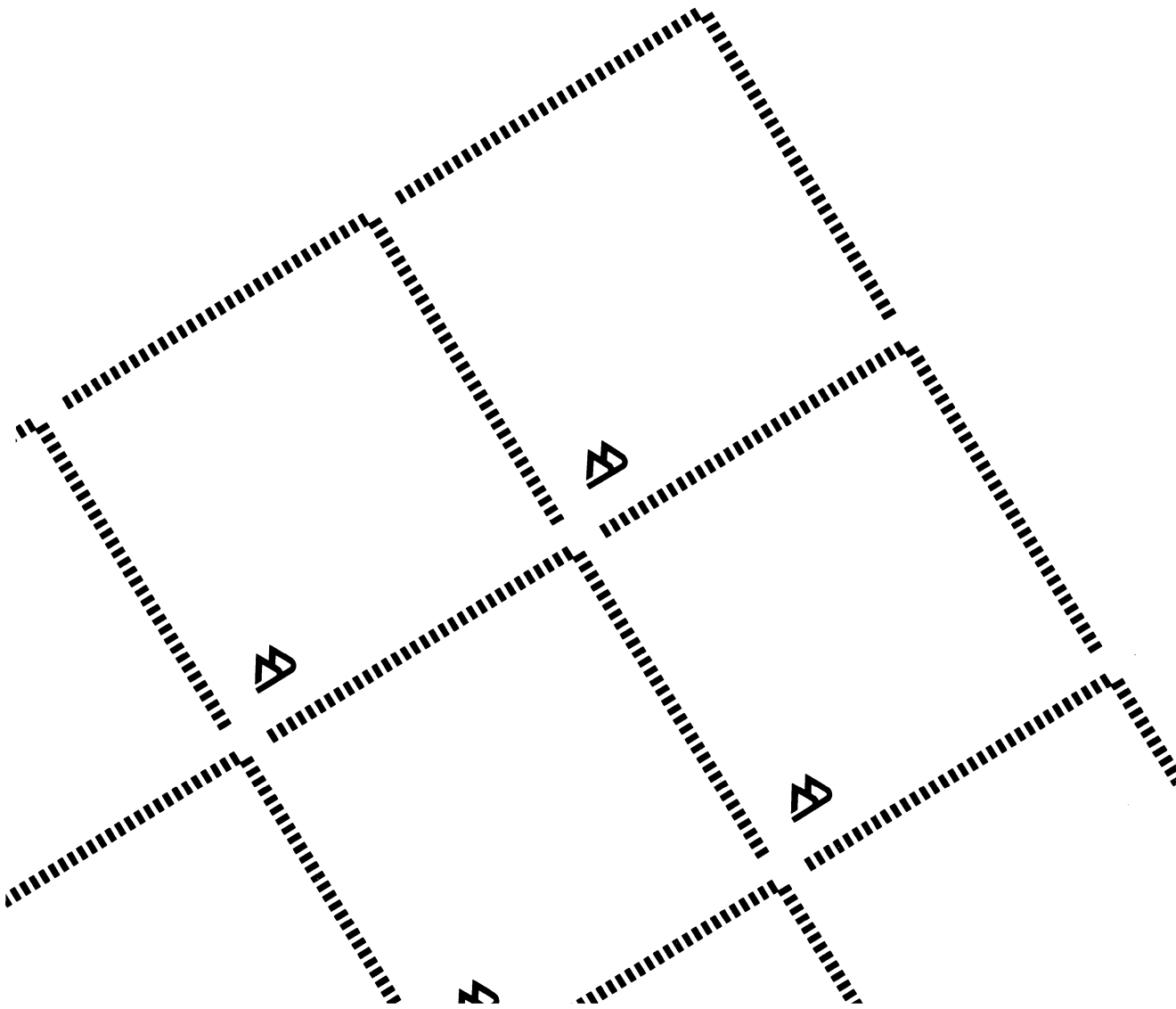
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■ CHARACTERISTICS CURVES

Under measurment

B. MICROCOMPUTERS

1988/1989 CMOS  
DATA BOOK







# SMC112F

## CMOS 4 BIT SINGLE CHIP MICROCOMPUTER

- Built-in LCD Driver
- Single Chip
- Low Supply Current

### ■ DESCRIPTION

The SMC112F is a 4-bit CMOS microcomputer which integrates 2K bytes ROM, 128 words RAM, 4 bits input port, 8 bits output port, and 32 × 4 segments LCD driver, 4 bits Timer, etc. on the chip. This provides low power systems for many kinds of applications.

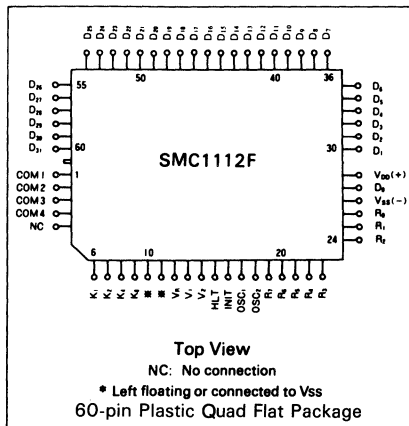
### ■ FEATURES

- Monolithic ..... CMOS LSI
- 4 bit parallel operation
- Low power dissipation ..... Typ 30  $\mu$ A
- Clock frequency ..... 32.768 kHz
- Instruction execution time ..... 122  $\mu$ sec
- Instruction set ..... 54 kinds
- Mask programmable ROM ..... 1920 × 8 bits  
(Max 2048 × 8 bits)
- Internal RAM ..... 128 × 4 bits
- Input port K input ..... 4 bits  
(with pull down resistors)
- Output port R output ..... 8 bits  
Bit manipulate instruction
- LCD driving output ..... V-3V, 1/4 duty  
4 common outputs  
32 segment outputs
- Built-in LCD segment memory ..... 32 × 4 bits
- Built-in Timer
- Subroutine nesting ..... 4 levels  
(commonly used for interrupt operation)
- Interrupt operation ..... Timer interrupt or K input  
Interrupt can be selected by programs
- Built-in oscillator ..... Crystal and capacitor external
- Power supply ..... VDD — VSS Typ 3V (Logic)  
VDD — VR Typ 3V (LCD driver)
- Package ..... 60-pin QFP(plastic)

### ■ APPLICATION

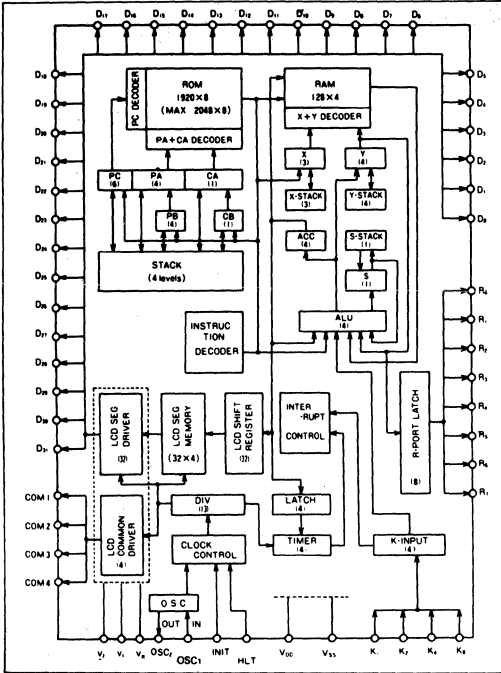
Applicable for LCD game, cash register, POS terminal device, portable measuring equipment, automatic vending machine, electric appliance, audio system controller and multi-purpose timer, etc.

### ■ PIN CONFIGURATION



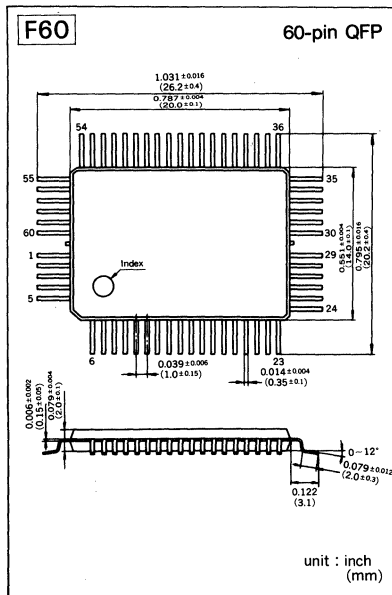
Name	Description
D <sub>0</sub> — D <sub>31</sub>	LCD driver's segment outputs
COM1 — COM4	LCD driver's common outputs
OSC <sub>1</sub>	Oscillator terminal (input)
OSC <sub>2</sub>	Oscillator terminal (output)
INIT	Active high input is used to initialize the SMC112.
HLT	Halt (Hi — stop, Lo — re-start)
K <sub>1</sub> , K <sub>2</sub> , K <sub>4</sub> , K <sub>8</sub>	K inputs
R <sub>0</sub> — R <sub>7</sub>	R outputs
VDD	Power supply (+)
VSS	Power supply for logic (-)
V <sub>R</sub> , V <sub>1</sub> , V <sub>2</sub>	Power supply for LCD driver (-)

## ■ BLOCK DIAGRAM



Symbol	Description
ALU	Arithmetic and logic unit
ACC	Accumulator
S	Status register
X	X-register
Y	Y-register
S-STACK	Status stack
X-STACK	X-stack
Y-STACK	Y-stack
PC	Program counter
PA	Page address register
CA	Chapter address register
PB	Page buffer register
CB	Chapter buffer register
STACK	ROM address stack
DIV	13-stage divider

## ■ PACKAGE DIMENSIONS



## ■ ELECTRICAL CHARACTERISTICS

### 1. Absolute maximum ratings

Parameter	Symbol	Min	Max	Unit
Supply voltage	V <sub>SS</sub>	-4.5	0.2	V
	V <sub>R</sub>	V <sub>SS</sub>	0.2	V
Input terminal voltage	V <sub>I</sub>	V <sub>SS</sub> -0.2	0.2	V
Operating temperature	T <sub>opr</sub>	-10	65	°C
Storage temperature	T <sub>stg</sub>	-40	125	°C

Note: Ground is V<sub>DD</sub> (= 0V).

### 2. Operating conditions (f<sub>osc</sub> = 32.768 kHz)

Parameter	Symbol	Min	Max	Unit
Supply voltage (Logic)	V <sub>SS</sub>	-3.5	-2.5	V
Supply voltage (LCD driver)	V <sub>R</sub>	V <sub>SS</sub>	-2.5	V
External capacitor for oscillation	C <sub>D</sub>	5	30	pF
	C <sub>G</sub>	5	30	pF

Note: Ground is V<sub>DD</sub> (= 0V).

### 3. Electrical characteristics (V<sub>SS</sub> = V<sub>R</sub> = -3.0V, T<sub>a</sub> = 25°C)

Parameter	Symbol	Min	Typ	Max	Unit	Test conditions	Terminal
"H" level input voltage	V <sub>IH</sub>	-0.5			V		K <sub>8</sub> , K <sub>4</sub> , K <sub>2</sub> , K <sub>1</sub> , HLT INIT, OSC <sub>1</sub>
"L" level input voltage	V <sub>IL</sub>			V <sub>SS</sub> + 0.5	V		
"H" level output current	I <sub>OH</sub>			-100	μA	V <sub>OH</sub> = -0.6V	R <sub>0</sub> - R <sub>7</sub>
"L" level output current	I <sub>OL</sub>	200			μA	V <sub>OL</sub> = V <sub>SS</sub> + 0.5V	
LCD common output voltage	V <sub>CO1</sub>	-0.2		0	V	R <sub>L</sub> = 5 MΩ	COM1 - COM4
	V <sub>CO2</sub>	-1.2	-1.0	-0.8	V		
	V <sub>CO3</sub>	-2.2	-2.0	-1.8	V		
	V <sub>CO4</sub>	V <sub>R</sub>		-2.8	V		
LCD segment output voltage	V <sub>DO1</sub>	-0.2		0	V	R <sub>L</sub> = 5 MΩ	D <sub>0</sub> - D <sub>31</sub>
	V <sub>DO2</sub>	-1.2	-1.0	-0.8	V		
	V <sub>DO3</sub>	-2.2	-2.0	-1.8	V		
	V <sub>DO4</sub>	V <sub>R</sub>		-2.8	V		
"H" level input current	I <sub>K</sub>	0.5	1.0	3.0	μA		K <sub>8</sub> , K <sub>4</sub> , K <sub>2</sub> , K <sub>1</sub> HLT INIT
	I <sub>HLT</sub>	0.5	1.2	5.0	μA		
	I <sub>INIT</sub>	5	15	25	μA		
Operating current (Crystal oscillation)	I <sub>SS1</sub>		20	30	μA	f <sub>osc</sub> = 32.768 kHz	V <sub>SS</sub>
	I <sub>IR</sub>	4	10	20	μA	No-load	V <sub>R</sub>

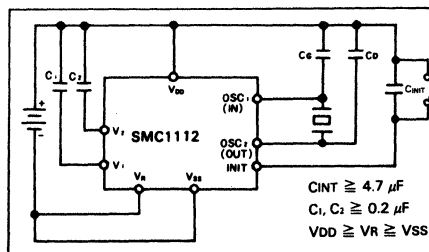
#### Note:

\* Ground is V<sub>DD</sub> (= 0V).

\* Current flowing into IC is positive and flowing out of IC is negative.

## ■ FUNDAMENTAL EXTERNAL CONNECTION

For power supply V<sub>DD</sub> must be common line to V<sub>SS</sub> and V<sub>R</sub>. V<sub>R</sub> is adjustable to the optimum voltage to drive Liquid Crystal Display (LCD). Set V<sub>DD</sub> ≥ V<sub>R</sub> ≥ V<sub>SS</sub> without fail.



## ■ INSTRUCTION TABLE

Function	Mnemonic	OP code	Status effect		Operation	Function	Mnemonic	OP code	Status effect		Operation		
			C	N					C	N			
Register to Register	TAY TYA CLA	20 23 7F			ACC→Y Y→ACC 0→ACC	ROM Addressing	BR	80-8F			1 STATUS = 1 CB→CA,PB→PA,I(W)→PC 2 STATUS = 0 PC+1→PC,1→STATUS		
Register to Memory	TAM TAMIYC TAMDYN TAMZA	27 25 24 26	Y Y		ACC→M(X,Y) ACC→M(X,Y), Y+1→Y ACC→M(X,Y), Y-1→Y ACC→M(X,Y), 0→ACC		CALL	CO-FF			1 STATUS = 1 CA,PA,PC+1→STACK, SP+1→SP CB→CA,PB→PA,I(W)→PC 2 STATUS = 0 PC+1→PC,1→STATUS		
Memory to Register	TMA TMY XMA	21 22 03			M(X,Y)→ACC M(X,Y)→Y M(X,Y)←ACC		RETN	0F			STACK→CA,PA,PC,PB SP-1→SP		
Arithmetic	AMAAC	06	Y		M(X,Y)+ACC→ACC		LCD Operation	TASR	0A			ACC→LCD S/R,S/R SHIFT	
	SAMAN	3C	Y		M(X,Y)-ACC→ACC			TSG1	7C			LCD S/R→ SEG.MEMORY (COM1)	
	IMAC	3E	Y		M(X,Y)+1→ACC			TSG2	7D			LCD S/R→ SEG.MEMORY (COM2)	
	DMAN	07	Y		M(X,Y)-1→ACC			TSG3	72			LCD S/R→ SEG.MEMORY (COM3)	
	IAC	70	Y		ACC+1→ACC			TSG4	73			LCD S/R→ SEG.MEMORY (COM4)	
	DAN	77	Y		ACC-1→ACC			Halt	HALT	71			CPU Stop Restart when "HLT" input goes down to "L" level.
	ABAAC	7A	Y		ACC+6→ACC				Timer	TMSET	7B		
	ABAAC	7E	Y		ACC+8→ACC	INTEN				74			Enable interrupt after an instruction.
	A10AAC	79	Y		ACC+10→ACC	INTDIS				75			Disable interrupt
	IYC	05	Y		Y+1→Y	SELIN		78				ACC <sub>n-1</sub> → Flip-flop of interrupt selector	
DYN	04	Y		Y-1→Y	Interrupt Control					1 ACC <sub>n</sub> = '1'→ Timer interrupt ACC <sub>n</sub> = '0'→ K-input interrupt			
CPAIZ	3D	Y		ACC+1→ACC						2 ACC <sub>0</sub> = '1'→ Timer clock input (fosc/2 <sup>2</sup> ) ACC <sub>0</sub> = '0'→ Timer clock input (fosc/2 <sup>13</sup> )			
Arithmetic Compare	ALEM	01	Y										
Logical Compare	MNEA MNEZ YNEA YNEC	00 3F 02 50-5F	Y Y Y Y			M(X,Y)≠ACC→STATUS=1 M(X,Y)≠0→STATUS=1 Y≠ACC→STATUS=1 Y≠I(C)→STATUS=1							
Bits in Memory	SBIT RBIT TBIT1	30-33 34-37 38-3B			1→M(X,Y,I(B)) 0→M(X,Y,I(B)) M(X,Y,I(B))=1→STATUS=1								
Constants	TCY TCMIY	40-4F 60-6F			I(C)→Y I(C)→M(X,Y), Y+1→Y								
Input	TKA KNEZ	08 0E		Y	K <sub>4,2,1</sub> →ACC K <sub>4,2,1</sub> ≠0→STATUS=1								
Output	SETR RSTR	0D 0C			1→R(Y) 0→R(Y)								
RAM 'X' Addressing	LDX COMX	28-2F 09			I(F)→X X <sub>M58</sub> →X <sub>M58</sub>								
ROM Addressing	LDP COMC	10-1F 0B			I(C)→PB CB→CB								

# SMC4040C Series

## CMOS 4 BIT SINGLE CHIP MICROCOMPUTER

- Minimum Instruction Cycle Time :  $1\mu\text{s}$
- 512 Byte ROM
- Low Supply Current

### DESCRIPTION

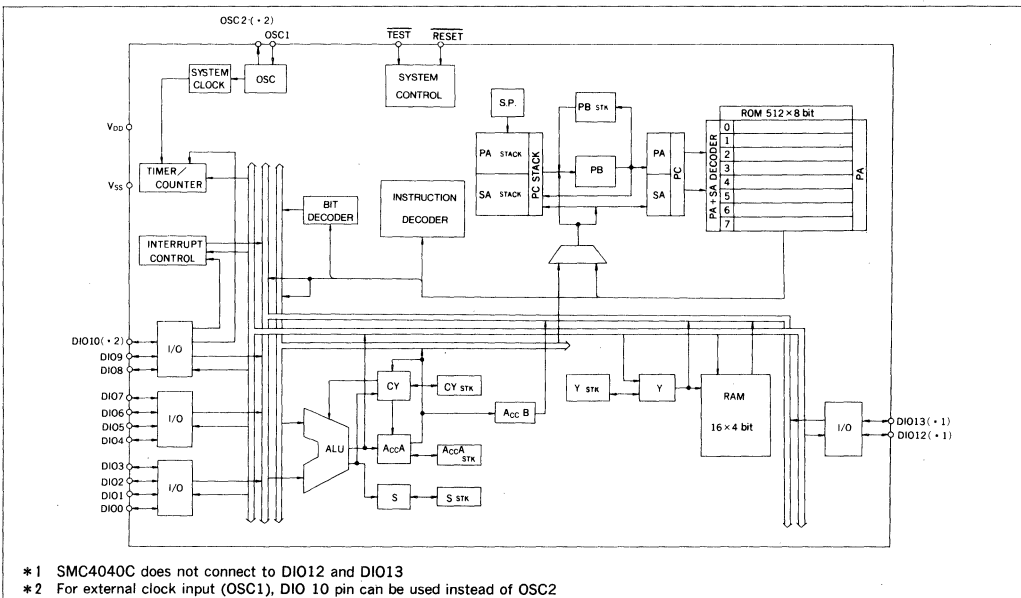
The SMC4040C Series is a low supply current type CMOS 4 bit single chip microcomputer featuring high-speed operation (minimum instruction cycle time :  $1\mu\text{s}$ ) with a wide voltage range (4 to 6V). It incorporates a RAM, I/O ports, a timer/event counter with a prescaler, and an interrupt control on a single chip. The SMC4040C Series can be flexibly applied to a variety of control systems.

(The SMC4040C Series includes the SMC4040C, SMC4041C)

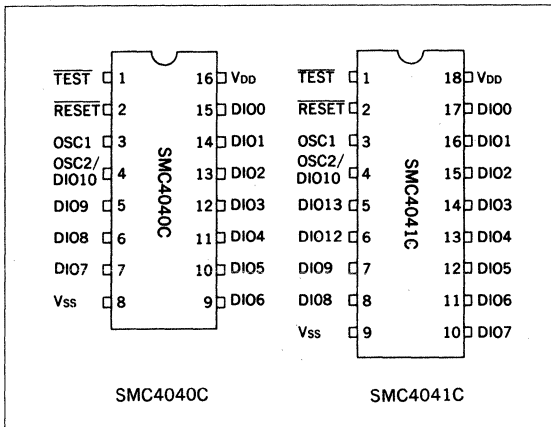
### FEATURES

- CMOS LSI 4 bits parallel processing
- Clock frequency ..... 400kHz to 6MHz
- On-chip oscillator circuit : ceramic oscillator (CR oscillation also available as option)
- Instruction cycle time .....  $1\mu\text{s}$  Min
- Instruction set containing 44 instructions
- 512 x 8 bits ROM
- 16 x 4 bits RAM
- 10(SMC4040C) or 12(SMC4041C) I/O ports
- Timer/event counter equipped with 5 bit prescaler/4 bit preset counter
- Interrupt : 1 level (with register stack) ... interrupt by timer/event counter or external input
- Two subroutine nesting levels (common to interrupt)
- Single power supply .....  $5\text{V} \pm 20\%$
- Package ..... SMC4040C 16-pin DIP (plastic)  
SMC4041C 18-pin DIP (plastic)

### BLOCK DIAGRAM



## PIN CONFIGURATION



## PIN NAMES AND FUNCTIONS

$\overline{\text{TEST}}$	Test input
$\overline{\text{RESET}}$	Reset input
OSC1	Oscillation input
OSC2/DIO10*1	Oscillation output
DIO0 to DIO9	Data input/output
DIO12, DIO13**2	Data input/output
V <sub>DD</sub>	Power supply (+)
V <sub>SS</sub>	Power supply (0V)

\*1 For external clock input (OSC1), data I/O pin DIO10 can be used instead of OSC2 (by mask option).

\*2 SMC4041C

## ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5 to V <sub>DD</sub> +0.3	V
I/O pin voltage	V <sub>I/O</sub>	-0.5 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	-0.5 to V <sub>DD</sub> +0.3	V
Power dissipation	P <sub>D</sub>	0.3	W
Operating temperature	T <sub>opr</sub>	-40 to 85	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

\* When the internal oscillator circuit is used, the operating temperature range is -20°C to 70°C because of the characteristics of the ceramic oscillator.

## RECOMMENDED OPERATING CONDITIONS

(T<sub>a</sub> = -40 to 85°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4	5	6	V
	V <sub>SS</sub>		—	0	—	V
Clock frequency	f <sub>OSC</sub>	V <sub>DD</sub> =4 to 6V	400	—	6000	kHz
Low level peak output current	I <sub>OL PEAK</sub>	DIO(OUTPUT)	—	—	10	mA
Low level mean output current	I <sub>OL AVG</sub>	DIO(OUTPUT)	—	—	5	mA

## ELECTRICAL CHARACTERISTICS

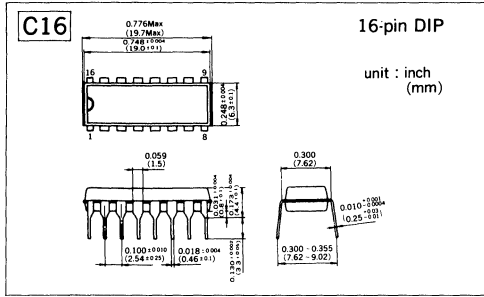
### DC Characteristics

(V<sub>DD</sub> = 5V ± 20%, V<sub>SS</sub> = 0V, f<sub>OSC</sub> = 6MHz, T<sub>a</sub> = -40 to 85°C)

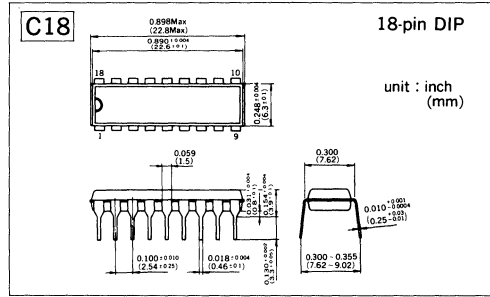
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Low level input current	I <sub>IL1</sub>	OSC1	-1	—	—	μA
	I <sub>IL2</sub>	RESET, TEST, DIO(INPUT)	-120	—	-10	μA
Low level input voltage	V <sub>IL1</sub>	OSC1	0	—	0.05V <sub>DD</sub>	V
	V <sub>IL2</sub>		0	—	0.2V <sub>DD</sub>	V
High level input voltage	V <sub>IH1</sub>	OSC1	0.95V <sub>DD</sub>	—	V <sub>DD</sub>	V
	V <sub>IH2</sub>		0.7V <sub>DD</sub>	—	V <sub>DD</sub>	V
Low level output current	I <sub>OL</sub>	V <sub>O</sub> =0.1V <sub>DD</sub> , DIO(OUTPUT)	1.6	—	—	mA
High level output current	I <sub>OH</sub>	V <sub>O</sub> =0.9V <sub>DD</sub> , DIO(OUTPUT)	—	—	-2	μA
Input leakage current	I <sub>LI</sub>	V <sub>I</sub> =V <sub>DD</sub>	—	—	1	μA
Operating current	I <sub>DDO</sub>	f <sub>OSC</sub> =6MHz, External clock	—	3	—	mA

## PACKAGE DIMENSIONS

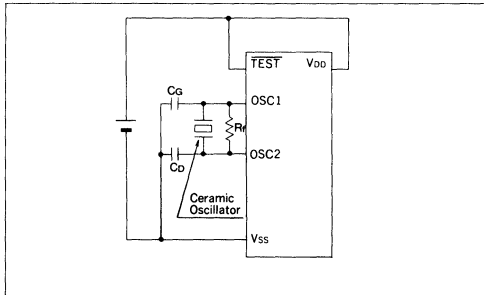
### SMC4040C



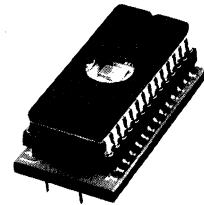
### SMC4041C



## EXAMPLE OF APPLICATION



Power supply is based on  $V_{SS}$ .  
 Example of oscillator constants  
 Ceramic oscillator: 6MHz (5V)  
 $R_f$  : 1M ohm  
 $C_g$  : 30pF  
 $C_d$  : 30pF



<Piggy-back package>

## SUPPORT TOOLS

The following support tools are available to the SMC4040C Series for efficient programming and debugging.

- Cross assembler : Operates in the CP/M®
- Software simulator : Operates in the CP/M®
- Evaluation chip : Piggy-back package allowing easy on board debugging. Can also be used for debugging small-volume products.

Used the CMOS type 27C32, or 27C64 EPROM.

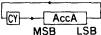
## SMC4040C SERIES

Type No.	Number of I/O pins	Package
SMC4040C	10 (11)*	16-pin DIP
SMC4041C	12 (13)*	18-pin DIP

\* The parenthesized number applies to the case where the DIO pin is used instead of OSC2 (by mask option) when external clock is applied.



## INSTRUCTION SETS

Function	Mnemonic	Machine code								Status	Operation	Function	Mnemonic	Machine code								Status	Operation
		7	6	5	4	3	2	1	0					7	6	5	4	3	2	1	0		
ALU	ADC A, M	0	0	0	0	0	1	0	0	(NC)	AccA, CY ← AccA + M(Y) + CY	BRANCH	LD PA, p	0	1	0	0	0	p2	p1	p0	SET	PB ← p
	ADD A, i	0	1	1	1	i3	i2	i1	i0	(NC)	AccA ← AccA + i		JP S, s	1	1	s3	s4	s3	s2	s1	s0	SET	if S = 1 PA ← PB SA ← s if S = 0 SA ← SA + 1
	ADD A, B	0	0	0	0	0	0	1	1	(NC)	AccA ← AccA + AccB		JPA S, j	0	1	0	0	1	0	j1	j0	SET	if S = 1 PA ← PB SA5,4 ← j SA3-0 ← AccA if S = 0 SA ← SA + 1
	ADD A, M	0	0	0	0	0	0	1	0	(NC)	AccA ← AccA + M(Y)		CALL S, s	1	0	s3	s4	s3	s2	s1	s0	SET	if S = 1 PA <sub>STACK</sub> ← PA SA <sub>STACK</sub> ← SA + 1 PA ← PB SA ← s SP ← SP + 1 if S = 0 SA ← SA + 1
	AND A, B	0	0	0	1	0	0	1	1	(Z)	AccA ← AccA ∧ AccB		RET	0	0	0	0	1	1	0	0	SET	SP ← SP - 1 PA ← PB ← PA <sub>STACK</sub> SA ← SA <sub>STACK</sub>
	AND A, M	0	0	0	1	0	0	1	0	(Z)	AccA ← AccA ∧ M(Y)		RETI	0	0	0	1	1	1	0	0	SSTK	SP ← SP - 1 PA ← PA <sub>STACK</sub> SA ← SA <sub>STACK</sub> PB ← PB <sub>STK</sub> AccA ← AccA <sub>STK</sub> S ← S <sub>STK</sub> Y ← Y <sub>STK</sub> CY ← CY <sub>STK</sub>
	AND S, M, j	0	1	0	0	1	1	j1	j0	(Z)	Mj(Y) ∧ 1		SYSTEM EI	0	0	0	0	1	1	0	1	SET	Interrupt enable
	INC Y	0	0	0	1	0	0	0	0	(NC)	M(Y) ← M(Y) + 1		DI	0	0	0	1	1	1	0	1	SET	Interrupt disable
	OR A, B	0	0	1	0	0	0	1	1	SET	AccA ← AccA ∨ AccB		NOP	0	1	1	1	0	0	0	0	SET	No operation
	OR A, M	0	0	1	0	0	0	1	0	SET	AccA ← AccA ∨ M(Y)		HALT	0	0	0	1	0	0	0	0	SET	SYSTEM Clock Stop
	XOR S, A, M	0	0	0	1	0	1	0	1	(Z)	AccA ← M(Y)											Restart when interrupt occur	
ACC	CPL A	0	0	0	0	1	1	1	1	(Z)	AccA ← AccA												
	EX	0	0	0	1	1	0	0	0	SET	AccA ← AccB												
	RRA	0	0	0	1	1	1	1	1	(CY)													
LOAD	LD A, i	0	1	1	0	i3	i2	i1	i0	SET	AccA ← i												
	LD A, M	0	0	0	1	1	0	0	1	SET	AccA ← M(Y)												
	LD A, O	0	0	1	0	0	0	0	0	SET	AccA ← OUT(Y)												
	LD A, Y	0	0	0	1	0	1	1	1	SET	AccA ← Y												
	LD B, A	0	0	0	0	1	0	0	0	SET	AccB ← AccA												
	LD M, A	0	0	0	0	1	0	0	1	SET	M(Y) ← AccA												
	LD Y, i	0	1	0	1	i3	i2	i1	i0	SET	Y ← i												
	LD Y, A	0	0	0	0	1	1	1	1	SET	Y ← AccA												
	SET CY	0	0	0	0	0	1	1	0	SET	CY ← 1												
RES CY	0	0	0	1	0	1	1	0	SET	CY ← 0													
BIT	SET M, j	0	0	1	1	1	0	j1	j0	SET	Mj(Y) ← 1												
	RES M, j	0	0	1	1	1	1	j1	j0	SET	Mj(Y) ← 0												
I/O	IN A	0	0	0	0	1	0	1	0	SET	AccA ← IN(Y)												
	IN M	0	0	0	1	1	0	1	0	SET	M(Y) ← IN(Y)												
	OUT A	0	0	0	0	1	0	1	1	SET	OUT(Y) ← AccA												
	OUT M	0	0	0	1	1	0	1	1	SET	OUT(Y) ← M(Y)												
	SET O, j	0	0	1	1	0	0	j1	j0	SET	OUTj(Y) ← 1												
RES O, j	0	0	1	1	0	1	j1	j0	SET	OUTj(Y) ← 0													

# SMC4050C Series

## CMOS 4 BIT SINGLE CHIP MICROCOMPUTERS

- Minimum Instruction Cycle Time : 1  $\mu$ s
- 1,024 Byte ROM
- Low Supply Current

### DESCRIPTION

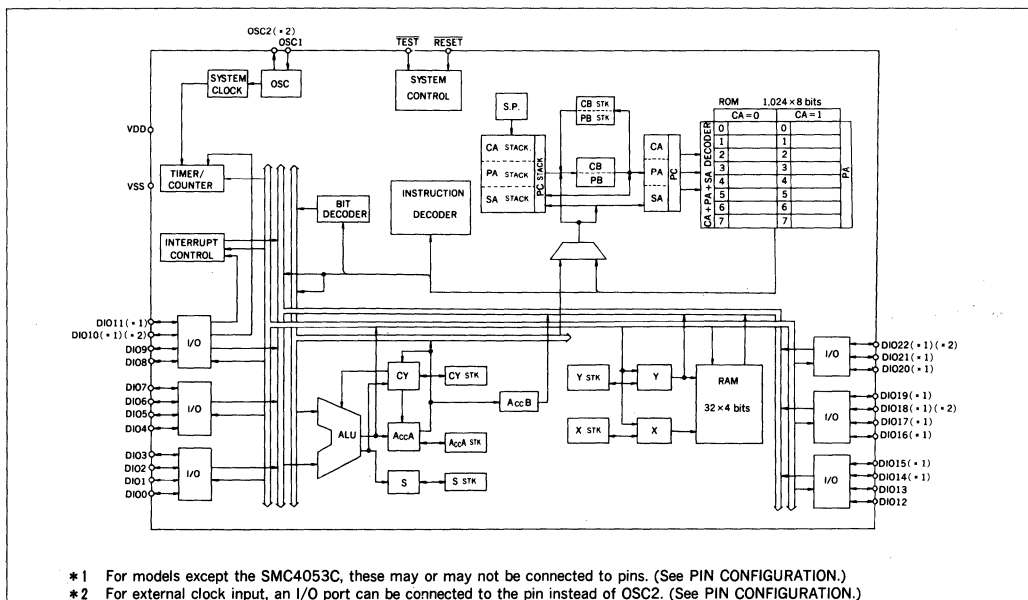
The SMC4050C Series is a low supply current type CMOS 4 bit single chip microcomputer featuring high-speed operation (minimum instruction cycle time : 1  $\mu$ s) with a wide voltage range (4 to 6V). It incorporates a RAM, a ROM, I/O ports, a timer/event counter with a prescaler and an interrupt control on a single chip. The SMC4050C Series can be flexibly applied to a variety of control systems.

(The SMC4050C Series includes the SMC4051C, SMC4052C/M, and SMC4053C.)

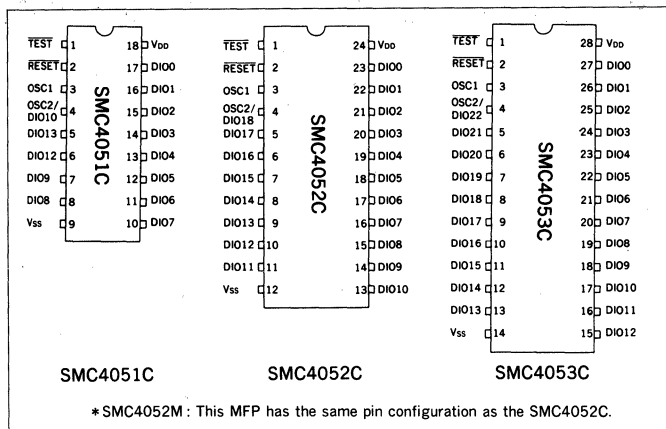
### FEATURES

- CMOS LSI 4 bits parallel processing
- Clock frequency ..... 400kHz to 6MHz
- On-chip oscillator circuit...ceramic oscillator (CR oscillation also available as option)
- Instruction cycle time ..... 1  $\mu$ s Min
- Instruction set containing 46 instructions
- 1024 x 8 bits ROM
- 32 x 4 bits RAM
- 12(SMC4051C), 18(SMC4052C/M) or 22(SMC4053C) I/O ports
- Timer/event counter equipped with 5 bit prescaler/4 bit preset counter
- Interrupt .....1 level(with register stack) interrupt by timer/event counter or external input
- Two subroutine nesting levels (common to interrupt)
- Single power supply .....5V  $\pm$ 20%
- Package.....18-pin DIP (SMC4051C), 24-pin DIP (SMC4052C), 24-pin SOP (SMC4052M), or 28-pin DIP (SMC4053C)

### BLOCK DIAGRAM



## PIN CONFIGURATION



## PIN NAMES AND FUNCTIONS

TEST	Test input
RESET	Reset input
OSC1	Oscillation input
OSC2/DIOXX*1	Oscillation output
DIO0toDIO13**2	Data input/output
DIO0toDIO17**3	Data input/output
DIO0toDIO21**4	Data input/output
VDD	Power supply (+)
VSS	Power supply (0V)

\*1 For external clock input (OSC1), data I/O pin DIOXX can be used instead of OSC2 (by mask option).

\*2 SMC4051C  
\*3 SMC4052C/M  
\*4 SMC4053C

## ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5 to V <sub>DD</sub> +0.3	V
I/O pin voltage	V <sub>I/O</sub>	-0.5 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	-0.5 to V <sub>DD</sub> +0.3	V
Power dissipation	P <sub>D</sub>	0.3	W
Operating temperature *	T <sub>opr</sub>	-40 to 85	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

\*When the internal oscillator circuit is used, the operating temperature range is -20°C to 70°C because of the characteristics of the ceramic oscillator.

## RECOMMENDED OPERATING CONDITIONS

(T<sub>a</sub> = -40 to 85°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4	5	6	V
	V <sub>SS</sub>		—	0	—	V
Clock frequency	f <sub>OSC</sub>	V <sub>DD</sub> =4 to 6V	400	—	6000	kHz
Low level peak output current	I <sub>OL PEAK</sub>	DIO(OUTPUT)	—	—	10	mA
Low level mean output current	I <sub>OL AVG</sub>	DIO(OUTPUT)	—	—	5	mA

## ELECTRICAL CHARACTERISTICS

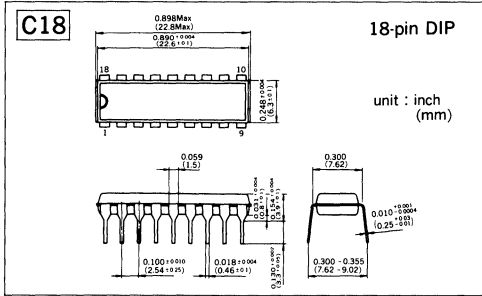
### DC Characteristics

(V<sub>DD</sub> = 5V ± 20%, V<sub>SS</sub> = 0V, f<sub>osc</sub> = 6MHz, T<sub>a</sub> = -40 to 85°C)

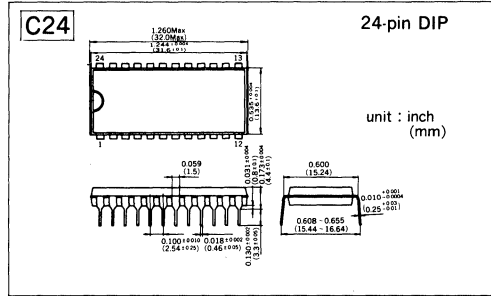
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Low level input current	I <sub>IL1</sub>	OSC1	-1	—	—	μA
	I <sub>IL2</sub>	RESET, TEST, DIO(INPUT)	-120	—	-10	μA
Low level input voltage	V <sub>IL1</sub>	OSC1	0	—	0.05V <sub>DD</sub>	V
	V <sub>IL2</sub>		0	—	0.2V <sub>DD</sub>	V
High level input voltage	V <sub>IH1</sub>	OSC1	0.95V <sub>DD</sub>	—	V <sub>DD</sub>	V
	V <sub>IH2</sub>		0.7V <sub>DD</sub>	—	V <sub>DD</sub>	V
Low level output current	I <sub>OL</sub>	V <sub>O</sub> =0.1V <sub>DD</sub> , DIO(OUTPUT)	1.6	—	—	mA
High level output current	I <sub>OH</sub>	V <sub>O</sub> =0.9V <sub>DD</sub> , DIO(OUTPUT)	—	—	-2	μA
Input leakage current	I <sub>LI</sub>	V <sub>I</sub> =V <sub>DD</sub>	—	—	1	μA
Operating current	I <sub>DDO</sub>	f <sub>osc</sub> =6MHz, External clock	—	5	—	mA

## PACKAGE DIMENSIONS

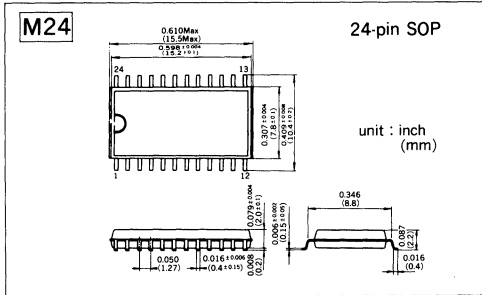
### SMC4051C



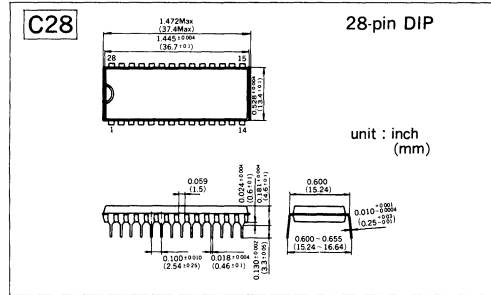
### SMC4052C



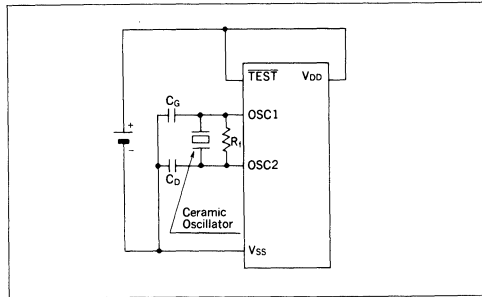
### SMC4052M



### SMC4053C

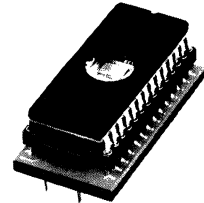


## EXAMPLE OF APPLICATION



Power supply is based on V<sub>DD</sub>.  
 Example of oscillator constants  
 Ceramic oscillator : 6MHz (5V)

R<sub>f</sub> : 1M ohm  
 C<sub>g</sub> : 30pF  
 C<sub>d</sub> : 30pF



[Piggy-back package]

## SUPPORT TOOLS

The following support tools are available to the SMC4050C Series for efficient programming and debugging :

- Cross assembler ..... Operates in the CP/M®
- Software simulator .. Operates in the CP/M®
- Evaluation chip ..... Piggy-back package allowing easy on-board debugging. Can also be used for debugging small-volume products.

Used the CMOS type 27C32, or 27C64 EPROM.

## SMC4050C SERIES

Model	Number of I/O pins	Package
SMC4051C	12 (13) *	18-pin DIP
SMC4052C/M	18 (19) *	24-pin DIP, or 24-pin SOP
SMC4053C	22 (23) *	28-pin DIP

\*The parenthesized number applies to the case where the DIO pin is used instead of OSC2 (by mask option) when external clock is applied.

## INSTRUCTION SETS

Function	Mnemonic	Machine code						Status	Function	Function	Function	Status	Function					
		7	6	5	4	3	2							1	0			
ALU	ADC	A, M	0	0	0	0	0	1	0	0	(NC)	$AccA, CY \leftarrow AccA + M(X, Y) + CY$						
	ADD	A, i	0	1	1	1	3	i	2	i	1	i	0	(NC)	$AccA \leftarrow AccA + i$			
	ADD	A, B	0	0	0	0	0	0	1	1	(NC)	$AccA \leftarrow AccA + AccB$						
	ADD	A, M	0	0	0	0	0	0	1	0	(NC)	$AccA \leftarrow AccA + M(X, Y)$						
	AND	A, B	0	0	0	1	0	0	1	1	(Z)	$AccA \leftarrow AccA \wedge AccB$						
	AND	A, M	0	0	0	1	0	0	1	0	(Z)	$AccA \leftarrow AccA \wedge M(X, Y)$						
	AND	S, M, j	0	1	0	0	1	1	j	1	j	0	(Z)	$Mj(X, Y) \wedge 1$				
	INC	M	0	0	0	1	0	0	0	0	(NC)	$M(X, Y) \leftarrow M(X, Y) + 1$						
	INC	Y	0	0	0	0	0	0	0	1	(NC)	$Y \leftarrow Y + 1$						
	OR	A, B	0	0	1	0	0	0	1	1	SET	$AccA \leftarrow AccA \vee AccB$						
	OR	A, M	0	0	1	0	0	0	1	0	SET	$AccA \leftarrow AccA \vee M(X, Y)$						
	ACC	CPL	A	0	0	0	0	1	1	1	1	(Z)	$AccA \leftarrow \bar{AccA}$					
EX			0	0	0	1	1	0	0	0	SET	$AccA \leftrightarrow AccB$						
RRA			0	0	0	1	1	1	1	1	(CY)	$  \begin{array}{c}  \text{AccA} \\  \hline  \text{MSB} \quad \text{LSB}  \end{array}  $						
LOAD		LD	A, i	0	1	1	0	i	3	i	2	i	1	i	0	SET	$AccA \leftarrow i$	
	LD	A, M	0	0	0	1	1	0	0	1	SET	$AccA \leftarrow M(X, Y)$						
	LD	A, O	0	0	1	0	0	0	0	0	SET	$AccA \leftarrow OUT(Y)$						
	LD	A, Y	0	0	0	1	0	1	1	1	SET	$AccA \leftarrow Y$						
	LD	B, A	0	0	0	0	1	0	0	0	SET	$AccB \leftarrow AccA$						
	LD	M, A	0	0	0	0	1	0	0	1	SET	$M(X, Y) \leftarrow AccA$						
	LD	X, b	0	0	1	0	0	1	0	b	SET	$X \leftarrow b$						
	LD	Y, i	0	1	0	1	i	3	i	2	i	1	i	0	SET	$Y \leftarrow i$		
	LD	Y, A	0	0	0	0	0	1	1	1	SET	$Y \leftarrow AccA$						
	SET	CY	0	0	0	0	0	1	1	0	SET	$CY \leftarrow 1$						
	RES	CY	0	0	0	1	0	1	1	0	SET	$CY \leftarrow 0$						
BIT	SET	M, j	0	0	1	1	0	j	1	j	0	SET	$Mj(X, Y) \leftarrow 1$					
	RES	M, j	0	0	1	1	1	1	j	1	j	0	SET	$Mj(X, Y) \leftarrow 0$				
I/O	IN	A	0	0	0	0	1	0	1	0	SET	$AccA \leftarrow IN(Y)$						
	IN	M	0	0	0	1	1	0	1	0	SET	$M(X, Y) \leftarrow IN(Y)$						
	OUT	A	0	0	0	0	1	0	1	1	SET	$OUT(Y) \leftarrow AccA$						
	OUT	M	0	0	0	1	1	0	1	1	SET	$OUT(Y) \leftarrow M(X, Y)$						
	SET	O, j	0	0	1	1	0	0	j	1	j	0	SET	$OUTj(Y) \leftarrow 1$				
	RES	O, j	0	0	1	1	0	1	j	1	j	0	SET	$OUTj(Y) \leftarrow 0$				
BRANCH	LD	CA, b	0	0	1	0	1	0	0	0	b	SET	$CB \leftarrow b$					
	LD	PA, p	0	1	0	0	0	0	p	2	p	1	p	0	SET	$PB \leftarrow p$		
	JP	S, s	1	1	s	5	s	4	s	3	s	2	s	1	s	0	SET	if S = 1 CA $\leftarrow$ CB, PA $\leftarrow$ PB SA $\leftarrow$ s
																	if S = 0 SA $\leftarrow$ SA + 1	
	JPA	S, j	0	1	0	0	1	0	j	1	j	0	SET	if S = 1 CA $\leftarrow$ CB, PA $\leftarrow$ PB SA5,4 $\leftarrow$ j				
																	SA3-0 $\leftarrow$ AccA	
																	if S = 0 SA $\leftarrow$ SA + 1	
	CALL	S, s	1	0	s	5	s	4	s	3	s	2	s	1	s	0	SET	if S = 1 CASTACK $\leftarrow$ CA PASTACK $\leftarrow$ PA SASTACK $\leftarrow$ SA + 1 CA $\leftarrow$ CB, PA $\leftarrow$ PB SA $\leftarrow$ s, SP $\leftarrow$ SP + 1
																		if S = 0 SA $\leftarrow$ SA + 1
	RET			0	0	0	0	1	1	0	0	SET	SP $\leftarrow$ SP - 1 CA $\leftarrow$ CB $\leftarrow$ CASTACK PA $\leftarrow$ PB $\leftarrow$ PASTACK SA $\leftarrow$ SASTACK					
RETI			0	0	0	1	1	1	0	0	SSTK	SP $\leftarrow$ SP - 1 CA $\leftarrow$ CASTACK, PA $\leftarrow$ PASTACK SA $\leftarrow$ SASTACK, CB $\leftarrow$ CBSTK PB $\leftarrow$ PBSTK AccA $\leftarrow$ AccASTK S $\leftarrow$ SSTK, Y $\leftarrow$ YSTK X $\leftarrow$ XSTK, CY $\leftarrow$ CYSTK						
SYSTEM	EI		0	0	0	0	1	1	0	1	SET	Interrupt enable						
	DI		0	0	0	1	1	1	0	1	SET	Interrupt disable						
	NOP		0	1	1	1	0	0	0	0	SET	No operation						
	HALT		0	0	0	1	0	0	0	0	SET	SYSTEM Clock Stop Restart when interrupt occur						

# SMC4055C Series

## CMOS 4BIT SINGLE CHIP MICROCOMPUTER

- IR-remote-controller Use
- 1,024 Byte ROM
- Low Supply Current

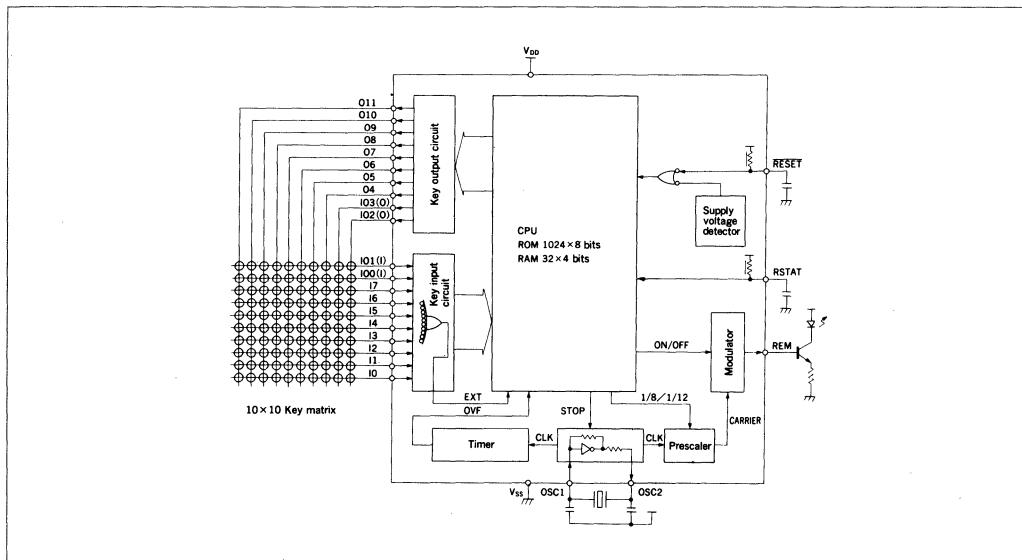
### DESCRIPTION

SMC4055C Series is a low supply current type CMOS 4bit single chip microcomputer for use IR-remote-controller. It incorporates a ROM, RAM, I ports, O ports, timer, carrier modulator with a prescaler and an interrupt controller on a single chip. So several key function types or code types can be flexibly designed by using such functions. Furthermore, it enters a standby mode when the oscillation is stopped by "STOP" instruction. Then, it can return to an operation mode by key interrupt.

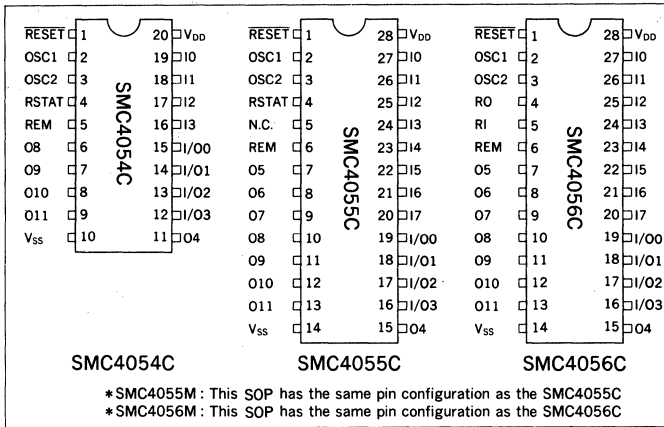
### FEATURES

- CMOS LSI 4bits parallel processing
- Clock frequency ..... 400 to 500kHz (Ceramic oscillator)
- Instruction cycle time.....12 $\mu$ s (Min)
- On chip prescaler .....1/8, 1/12
  - Each modulation output is selected by instruction control.
  - Instruction control modulation output
  - 1/2 duty or 1/3 duty is optional in 1/12 prescaling
- Timer .....8bits
- Key matrix .....10 $\times$ 10 or 5 $\times$ 8 (with LCD 6seg output): 28 pin package 5 $\times$ 8: 20 pin package
- Standby mode ..... "STOP" and key interrupt control
- ROM .....1,024 $\times$ 8bits
- RAM .....32 $\times$ 4bits
- Instruction sets .....48
- Interrupt level .....1 (Timer or key input)
- Subroutine nesting level .....3 (Common to interrupt)
- Single power supply .....2.0 to 3.5V
- Low supply current ..... Operating (No load): 0.3mA (Typ) Standby: 1 $\mu$ A (Typ)
- Operating temperature.....-20 to 80 $^{\circ}$ C
- Package .....20-pin DIP (plastic) 28-pin DIP (plastic) 28-pin SOP (plastic)

### BLOCK DIAGRAM



## PIN CONFIGURATION



## PIN DESCRIPTION

RESET	Reset input
OSC1	Oscillation input
OSC2	Oscillation output
RSTAT	Restart control
O5 to O11	Data output (LCD drive available)
O4	Data output
I/O0 to I/O3	Key input/output
I0 to I7	Key input
RI, RO	CR oscillation input/output
V <sub>DD</sub>	Power supply (+)
V <sub>SS</sub>	Power supply (0V)
REM	Remote control signal output

## ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5 to V <sub>DD</sub> +0.3	V
I/O pin voltage	V <sub>I/O</sub>	-0.5 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	-0.5 to V <sub>DD</sub> +0.3	V
Power dissipation	P <sub>D</sub>	0.3	W
Operating temperature	T <sub>opr</sub>	-20 to 80	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

## RECOMMENDED OPERATING CONDITIONS

(T<sub>a</sub> = -20 to 80°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		2.0	3.0	3.5	V
	V <sub>SS</sub>		—	0	—	V
Clock frequency	f <sub>osc</sub>	V <sub>DD</sub> =2.0 to 3.5V	400	—	500	kHz

## ELECTRICAL CHARACTERISTICS

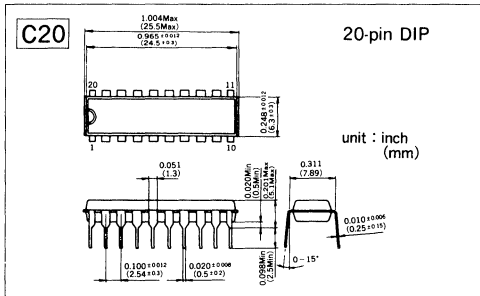
### DC Characteristics

(V<sub>DD</sub>=2.0 to 3.5V, V<sub>SS</sub>=0V, f<sub>osc</sub>=400 to 500kHz, T<sub>a</sub>=-20 to 80°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Low level input current	I <sub>IL1</sub>	OSC1	-6.5	—	—	μA
	I <sub>IL2</sub>	I0 to I7, I/O (INPUT)	-35	-12	-3	μA
Low level input voltage	V <sub>IL1</sub>	OSC1	0	—	0.05V <sub>DD</sub>	V
	V <sub>IL2</sub>	I0 to I7, I/O (INPUT)	0	—	0.3V <sub>DD</sub>	V
High level input voltage	V <sub>IH1</sub>	OSC1	0.95V <sub>DD</sub>	—	V <sub>DD</sub>	V
	V <sub>IH2</sub>	I0 to I7, I/O (INPUT)	0.7V <sub>DD</sub>	—	V <sub>DD</sub>	V
Key ON resistance	R <sub>K(ON)</sub>		—	—	10	kΩ
Key OFF resistance	R <sub>K(OFF)</sub>		400	—	—	kΩ
Low level output current	I <sub>OL</sub>	V <sub>O</sub> =0.1V <sub>DD</sub>	0.5	—	—	mA
High level output current	I <sub>OH</sub>	V <sub>O</sub> =0.5V <sub>DD</sub> , REM	—	—	-1.2	mA
Input leakage current	I <sub>LI</sub>	V <sub>I</sub> =V <sub>DD</sub>	—	—	1	μA
Operating current	I <sub>DD0</sub>	Operation (No load)	—	0.3	—	mA
	I <sub>DD5</sub>	Standby (STOP)	—	1	15	μA

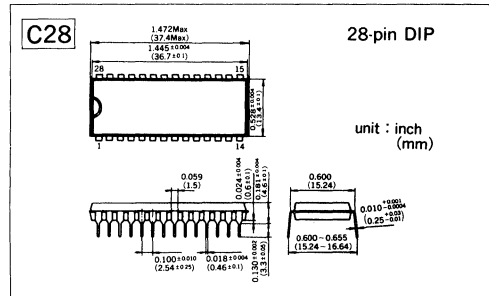
## PACKAGE DIMENSIONS

### SMC4054C

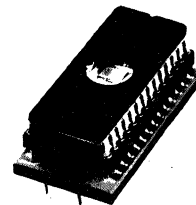
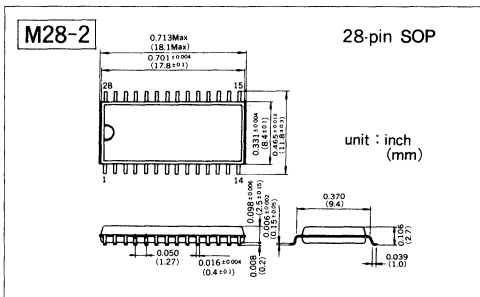


### SMC4055C, SMC4056C

(under developing)

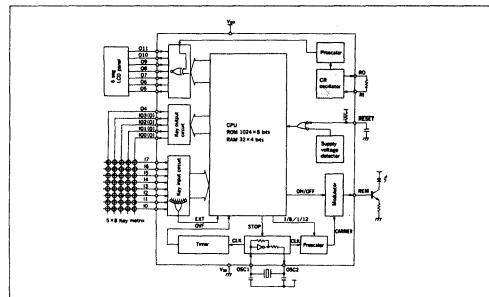
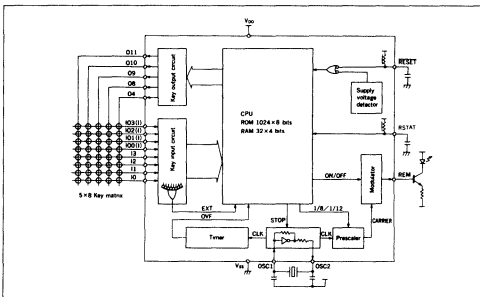


### SMC4055M, SMC4056M



[Piggy-back package]

## EXAMPLE OF APPLICATIONS



## SUPPORT TOOLS

The following support tools are available to the SMC4054C, SMC4055C/M, SMC4056C/M for efficient programming and debugging.

- Cross assembler ..... Operates in the CP/M®
- Software simulator ..... Operates in the CP/M®
- Evaluation chip ..... Piggy-back package allowing easy on-board debugging. Can also be used for debugging small-volume products.

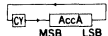
Used the CMOS type 27C32, or 27C64 EPROM.

## SMC4055C SERIES

Model	Number of I/O pins	Package
SMC4054C	5(O) × 8(I)	20-pin DIP
SMC4055C/M	10(O) × 10(I)	28-pin DIP, 28-pin SOP
SMC4056C/M	5(O) × 8(I), 6(seg) × 1(COM)	28-pin DIP, 28-pin SOP



## INSTRUCTION SETS

Function	Mnemonic	Machine code								Status	Operation	Function	Mnemonic	Machine code								Status	Operation																					
		7	6	5	4	3	2	1	0					7	6	5	4	3	2	1	0																							
ALU	ADC	A, M	0	0	0	0	0	1	0	0	(NC)	AccA, CY ← AccA + M(X, Y) + CY	BRANCH	LD	CA, b	0	0	1	0	1	0	0	b	SET	CB ← b																			
	ADD	A, i	0	1	1	1	1	1	0	0	(NC)	AccA ← AccA + i		LD	PA, p	0	1	0	0	0	p2	p1	p0	SET	PB ← p																			
	ADD	A, B	0	0	0	0	0	0	1	1	(NC)	AccA ← AccA + AccB		JP	S, s	1	1	s5	s4	s3	s2	s1	s0	SET	if S = 1 CA ← CB, PA ← PB SA ← s																			
	ADD	A, M	0	0	0	0	0	0	1	0	(NC)	AccA ← AccA + M(X, Y)		JPA	S, j	0	1	0	0	1	0	j1	j0	SET	if S = 0 SA ← SA + 1																			
	AND	A, B	0	0	0	1	0	0	1	1	(Z)	AccA ← AccA ∧ AccB												SET	if S = 1 CA ← CB, PA ← PB SA5,4 ← j																			
	AND	A, M	0	0	0	1	0	0	1	0	(Z)	AccA ← AccA ∧ M(X, Y)												SET	SA3-0 ← AccA																			
	AND S, M, j	0	1	0	0	1	1	j1	j0	(Z)	Mj(X, Y) ∧ 1	SET												if S = 0 SA ← SA + 1																				
	INC	M	0	0	0	1	0	0	0	1	(NC)	M(X, Y) ← M(X, Y) + 1												CALL	S, s	1	0	s5	s4	s3	s2	s1	s0	SET	if S = 1 CASTACK ← CA PASTACK ← PA SASTACK ← SA + 1 CA ← CB, PA ← PB SA ← s, SP ← SP + 1									
	INC	Y	0	0	0	0	0	0	0	1	(NC)	Y ← Y + 1																						SET	if S = 0 SA ← SA + 1									
	INC	B	0	0	1	0	0	0	0	1	(NC)	B ← B + 1																						SET	if S = 1 CASTACK ← CA PASTACK ← PA SASTACK ← SA + 1 CA ← CB, PA ← PB SA ← s, SP ← SP + 1									
	OR	A, B	0	0	1	0	0	0	1	1	SET	AccA ← AccA ∨ AccB																						RET	0	0	0	0	1	1	0	0	SET	if S = 0 SA ← SA + 1
	OR	A, M	0	0	1	0	0	0	1	0	SET	AccA ← AccA ∨ M(X, Y)																															SET	SP ← SP - 1
	XOR	S, A, B	0	0	0	0	0	1	0	1	(Z)	AccA ⊕ AccB																															SET	CA ← CB - CASTACK PA ← PB - PASTACK SA ← SASTACK
	XOR	S, A, M	0	0	0	1	0	1	0	1	(Z)	AccA ⊕ M(X, Y)		SET	SA ← SASTACK PB ← PBSTK AccA ← AccASTK S ← Sstk, Y ← Ystk X ← Xstk, CY ← CYstk																													
ACC	CPL	A	0	0	0	0	1	1	1	1	(Z)	AccA ← AccA	RETI	0	0	0	0	1	1	0	0	SET	SP ← SP - 1 CA ← CB - CASTACK PA ← PB - PASTACK SA ← SASTACK																					
	EX	0	0	0	1	1	0	0	1	SET	AccA ↔ AccB	SET										SA ← SASTACK PB ← PBSTK AccA ← AccASTK S ← Sstk, Y ← Ystk X ← Xstk, CY ← CYstk																						
	RRA	0	0	0	1	1	1	1	1	(CY)		SET										SA ← SASTACK PB ← PBSTK AccA ← AccASTK S ← Sstk, Y ← Ystk X ← Xstk, CY ← CYstk																						
LOAD	LD	A, i	0	1	1	0	1	1	0	0	SET	AccA ← i	SYSTEM	EI	0	0	0	0	1	1	0	1	SET	Interrupt enable																				
	LD	A, M	0	0	0	1	1	0	0	1	SET	AccA ← M(X, Y)											SET	Interrupt disable																				
	LD	A, O	0	0	1	0	0	0	0	0	SET	AccA ← OUT(Y)											SET	No operation																				
	LD	A, Y	0	0	0	1	0	1	1	1	SET	AccA ← Y											SET	SYSTEM Clock Stop																				
	LD	B, A	0	0	0	0	1	0	0	0	SET	AccB ← AccA											SET	Restart when interrupt occur																				
	LD	M, A	0	0	0	0	1	0	0	1	SET	M(X, Y) ← AccA											SET	OSC Stop																				
	LD	X, b	0	0	1	0	0	0	1	b	SET	X ← b											SET	Restart when interrupt occur																				
	LD	Y, i	0	1	0	1	1	1	0	i	SET	Y ← i											SET	Restart when interrupt occur																				
	LD	Y, A	0	0	0	0	1	1	1	1	SET	Y ← AccA											SET																					
	SET	CY	0	0	0	1	0	1	1	0	SET	CY ← 1											SET																					
	RES	CY	0	0	0	0	1	1	0	0	SET	CY ← 0											SET																					
BIT	SET	M, j	0	0	1	1	1	0	j1	j0	SET	Mj(X, Y) ← 1	STOP	0	0	0	0	1	1	1	0	SET	Restart when interrupt occur																					
	RES	M, j	0	0	1	1	1	1	j1	j0	SET	Mj(X, Y) ← 0										SET	Restart when interrupt occur																					
I/O	IN	A	0	0	0	0	1	0	1	0	SET	AccA ← IN(Y)																																
	IN	M	0	0	0	1	1	0	1	0	SET	M(X, Y) ← IN(Y)																																
	OUT	A	0	0	0	0	1	0	1	1	SET	OUT(Y) ← AccA																																
	OUT	M	0	0	0	1	1	0	1	1	SET	OUT(Y) ← M(X, Y)																																
	SET	O, j	0	0	1	1	0	0	j1	j0	SET	OUTj(Y) ← 1																																
	RES	O, j	0	0	1	1	0	1	j1	j0	SET	OUTj(Y) ← 0																																

# SMC6110F Series

## CMOS 4BIT SINGLE CHIP MICROCOMPUTER

- ROM 1K WORD
- LCD driver confined
- Low power dissipation

### ■DESCRIPTION

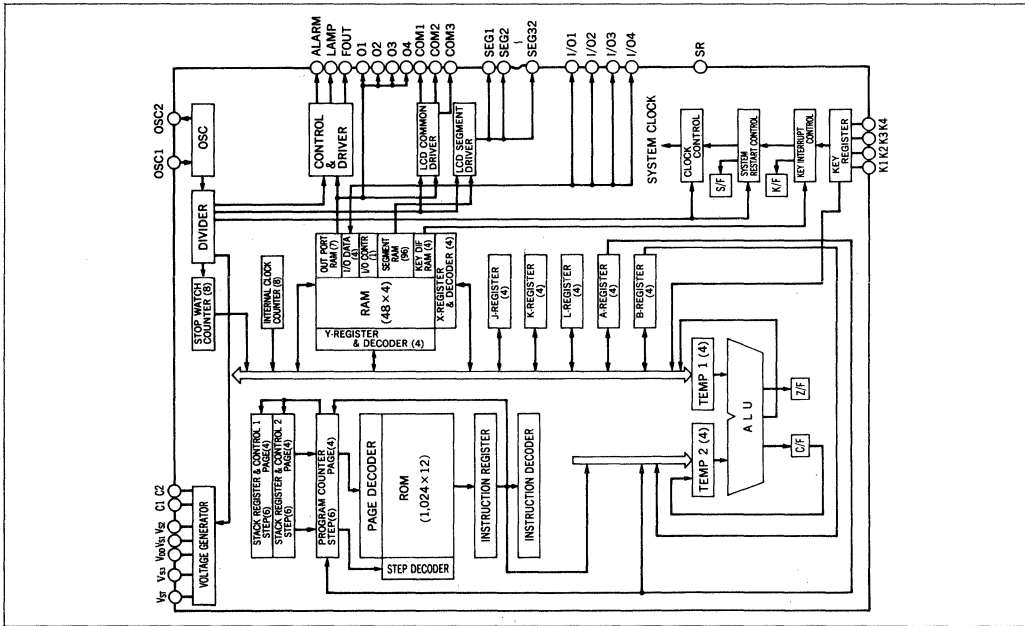
The SMC6110F Series is a CMOS 4-bit single chip microcomputer. It incorporates a 1,024×12 bits ROM, a 48×4 bits RAM, a 96 segment LCD driver, restart with timer and key, and interrupt by key. The SMC6110F series applies to a variety of appliances with using LCD, low power dissipation; such as timepieces.

### ■FEATURES

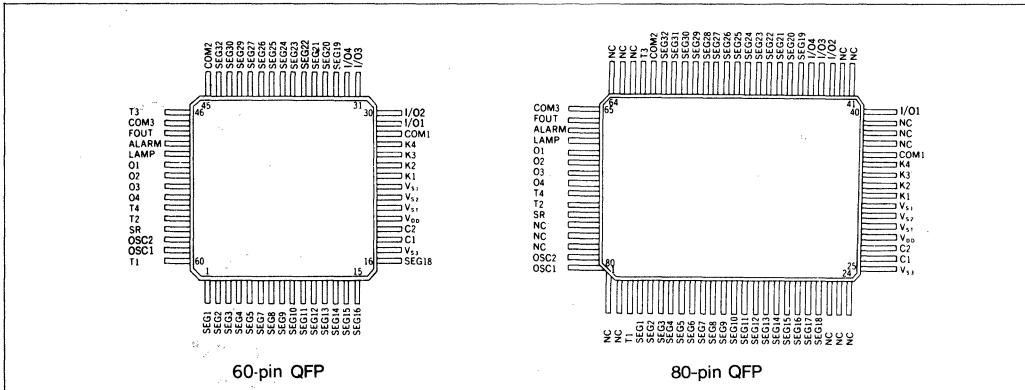
- CMOS LSI 4 bits parallel processing
- Clock frequency ( $f_{osc}$ ) ..... SMC6115F/6117F 32.768kHz
- Instruction cycle time ..... SMC6115F/6117F 122 $\mu$ s
- Instruction set ..... 78 instructions
- ROM ..... 1,024×12 bits
- RAM ..... 48×4 bits
- Input port ..... 4 bits\*
- Output port ..... 4 bits, 1 bit (for Alarm), 1 bit (for Lamp)
- I/O port ..... 4 bits parallel processing\*
- FOUT ..... Internal divided frequency output  
SMC6115F/6117F 512Hz to 32kHz
- Key input ..... 16 keys available (I/O matrix method)
- LCD driver ..... Common : 3 terminals  
Segment : 32 terminals  
SMC6115F/6117F 1/2V-V-3/2V, 1/3 duty
- On-chip LCD segment memory ..... 96 bits
- Timer ..... Chronograph counter  
Internal clock counter
- Subroutine nesting levels ..... 2 levels
- Interrupt ..... Key input interrupt
- Programmed restart ..... Timer restart :  
SMC6115F/6117F 1 sec, 1/10 sec  
Key input restart
- LCD power supply circuit ..... Built-in :  
SMC6115F 1/2V halver, 3/2V booster  
SMC6117F Doubler, Tripler
- Supply voltage ..... SMC6115F 3.0V  
SMC6117F 1.5V
- Current consumption ..... SMC6115F 1.5 $\mu$ A (Typ)  
SMC6117F 3.0 $\mu$ A (Typ)
- Package ..... 60-pin QFP/80-pin QFP

\*pull-down resistor attachable

## ■ BLOCK DIAGRAM



## ■ PIN CONFIGURATION



## ■ PIN DESCRIPTION

V <sub>DD</sub>	Supply voltage (0V)	K1 to K4	Input
V <sub>S1</sub>	Supply voltage (-1.5V) Dropped voltage	O1 to O4	Output
V <sub>S2</sub>	Supply voltage (-3.0V) Boosted voltage	COM1, COM2, COM3	LCD common driving output
V <sub>S3</sub>	Boosted voltage (-4.5V)	SEG1 to SEG32	LCD segment driving output
V <sub>ST</sub>	Stabilized voltage	ALARM	Alarm output
OSC1	Oscillation terminal (Input)	LAMP	Lamp output
OSC2	Oscillation terminal (Output)	FOUT	Internal divided frequency output (512Hz to 32kHz)
SR	System reset input	I/O1 to I/O4	Input/Output
C1, C2	Capacitor connection terminal for booster and regulator	TEST1 to TEST4	Test input

## ■ ABSOLUTE MAXIMUM RATINGS

### SMC6115F

Parameter	Symbol	Ratings	Unit
Supply voltage	$V_{S2}$	- 5.0 to 0.5	V
Input voltage	$V_I$	$V_{S2} - 0.3$ to 0.5	V
Output voltage	$V_O$	$V_{S2} - 0.3$ to 0.5	V
Operating temperature	$T_{opr}$	- 20 to 80	°C
Storage temperature	$T_{stg}$	- 65 to 150	°C
Soldering temperature and time	$T_{sol}$	260°C, 10s (at lead)	—

### SMC6117F

Parameter	Symbol	Ratings	Unit
Supply voltage	$V_{S1}$	- 3.0 to 0.5	V
Input voltage	$V_I$	$V_{S1} - 0.3$ to 0.5	V
Output voltage	$V_O$	$V_{S1} - 0.3$ to 0.5	V
Operating temperature	$T_{opr}$	- 20 to 80	°C
Storage temperature	$T_{stg}$	- 65 to 150	°C
Soldering temperature and time	$T_{sol}$	260°C, 10s (at lead)	—

## ■ RECOMMENDED OPERATING CONDITIONS

### SMC6115F

( $T_a = -20^\circ\text{C}$  to  $80^\circ\text{C}$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	$V_{DD}$	$V_{DD} - V_{S2}$	2.0	—	3.5	V
Oscillation frequency	$f_{osc}$		—	32.768	—	kHz
Capacitor for booster	CE		0.047	—	—	$\mu\text{F}$
Capacitor for $V_{DD} - V_{S1}$	CA		0.047	—	—	$\mu\text{F}$
Capacitor for $V_{DD} - V_{S3}$	CC		0.047	—	—	$\mu\text{F}$
Capacitor for $V_{DD} - V_{ST}$	CD		0.047	—	—	$\mu\text{F}$

### SMC6117F

( $T_a = -20^\circ\text{C}$  to  $80^\circ\text{C}$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	$V_{DD}$	$V_{DD} - V_{S1}$	1.45	—	1.7	V
Oscillation frequency	$f_{osc}$		—	32.768	—	kHz
Capacitor for booster	CE		0.047	—	—	$\mu\text{F}$
Capacitor for $V_{DD} - V_{S2}$	CB		0.047	—	—	$\mu\text{F}$
Capacitor for $V_{DD} - V_{S3}$	CC		0.047	—	—	$\mu\text{F}$

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

SMC6115F

( $V_{S1} = -1.5V, V_{S2} = -3.0V, V_{S3} = -4.5V, f_{OSC} = 32.768kHz, CA = CC = CD = CE = 0.047\mu F, T_a = 25^\circ C$ )

Parameter	Symbol	Conditions		Min	Typ	Max	Unit
High level input voltage	$V_{IH1}$		K1 to K4	-0.2	—	0	V
Low level input voltage	$V_{IL1}$		I/O1 to I/O4	$V_{S2}$	—	$V_{S2} + 0.2$	V
High level input current	$I_{IH1}$	$V_{IH1} = 0V$	K1 to K4, I/O1 to I/O4	—	—	0.5	$\mu A$
			K1 to K4, I/O1 to I/O4 with pull down resistor	2	—	10	$\mu A$
	$I_{IH2}$	$V_{IH2} = 0V$	SR	5	—	25	$\mu A$
Low level input current	$I_{IL}$	$V_{IL} = -3.0V$	K1 to K4, I/O1 to I/O4	-0.5	—	—	$\mu A$
High level output current (1)	$I_{OH1}$	$V_{OH1} = -0.5V$	ALARM			-500	$\mu A$
Low level output current (1)	$I_{OL1}$	$V_{OL1} = -2.5V$	LAMP	500			$\mu A$
High level output current (2)	$I_{OH2}$	$V_{OH2} = -0.5V$	O1 to O4			-60	$\mu A$
Low level output current (2)	$I_{OL2}$	$V_{OL2} = -2.5V$		60			$\mu A$
High level output current (3)	$I_{OH3}$	$V_{OH3} = -0.5V$	FOUT			-60	$\mu A$
Low level output current (3)	$I_{OL3}$	$V_{OL3} = -2.5V$		60			$\mu A$
High level output current (4)	$I_{OH4}$	$V_{OH4} = -0.5V$	I/O port			-60	$\mu A$
Low level output current (4)	$I_{OL4}$	$V_{OL4} = -2.5V$		60			$\mu A$
Common output current	$I_{OH5}$	$V_{OH5} = -0.05V$	COM1, COM2, COM3			-3.0	$\mu A$
	$I_{OL5}$	$V_{OL5} = -2.95V$		3.0			$\mu A$
Segment output current	$I_{OH6}$	$V_{OH6} = -0.05V$	SEG1 to 32			-0.15	$\mu A$
	$I_{OL6}$	$V_{OL6} = -2.95V$		0.15			$\mu A$
Dropped output voltage	$V_{S1}$	$1M\Omega$ loading connected between $V_{DD}$ and $V_{S1}$	$V_{S1}$			-1.45	V
Dropped ripple voltage	$V_{rip1}$						0.1
Boosted output voltage	$V_{S3}$	$1M\Omega$ loading connected between $V_{DD}$ and $V_{S3}$				-4.2	V
Boosted ripple voltage	$V_{rip3}$						0.3
Current consumption	$I_{S2}$	No Load, Base Time Mode			0.40	0.70	$\mu A$
		No Load, Executing			1.50	2.50	
Operating voltage range	$V_{DD} - V_{S2}$	Normal		2.50	3.00	3.50	V
		Heavy Load		2.00	—	3.50	

SMC6117F

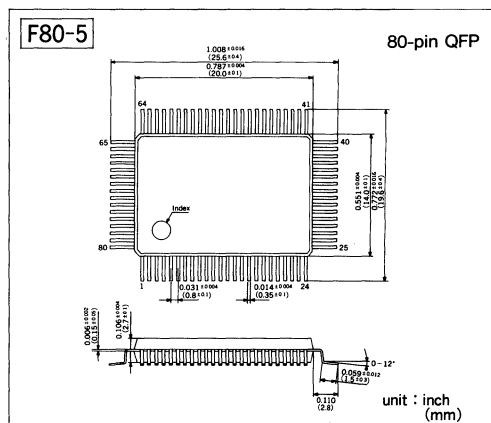
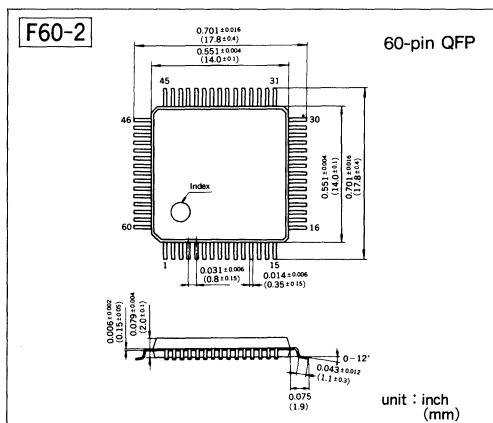
( $V_{S1} = -1.5V, V_{S2} = -3.0V, V_{S3} = -4.5V, f_{OSC} = 32.768kHz, CB = CC = CE = 0.047\mu F, T_a = 25^\circ C$ )

Parameter	Symbol	Conditions		Min	Typ	Max	Unit
High level input voltage	$V_{IH1}$		K1 to K4	-0.2		0	V
Low level input voltage	$V_{IL1}$		I/O1 to I/O4	$V_{S1}$		$V_{S1} + 0.2$	V
High level input current	$I_{IH1}$	$V_{IH1} = 0V$	K1 to K4, I/O1 to I/O4	—	—	0.5	$\mu A$
			K1 to K4, I/O1 to I/O4 with pull down resistor	2	—	10	$\mu A$
	$I_{IH2}$	$V_{IH2} = 0V$	SR	5	—	25	$\mu A$
Low level input current	$I_{IL}$	$V_{IL} = -1.5V$	K1 to K4, I/O1 to I/O4	-0.5			$\mu A$
High level output current (1)	$I_{OH1}$	$V_{OH1} = -0.5V$	ALARM			-250	$\mu A$
Low level output current (1)	$I_{OL1}$	$V_{OL1} = -1.0V$	LAMP	250			$\mu A$
High level output current (2)	$I_{OH2}$	$V_{OH2} = -0.5V$	O1 to O4			-30	$\mu A$
Low level output current (2)	$I_{OL2}$	$V_{OL2} = -1.0V$		30			$\mu A$
High level output current (3)	$I_{OH3}$	$V_{OH3} = -0.5V$	FOUT			-30	$\mu A$
Low level output current (3)	$I_{OL3}$	$V_{OL3} = -1.0V$		30			$\mu A$
High level output current (4)	$I_{OH4}$	$V_{OH4} = -0.5V$	I/O port			-30	$\mu A$
Low level output current (4)	$I_{OL4}$	$V_{OL4} = -1.0V$		30			$\mu A$
Common output current	$I_{OH5}$	$V_{OH5} = -0.05V$	COM1, COM2, COM3			-3.0	$\mu A$
	$I_{OL5}$	$V_{OL5} = -1.45V$		3.0			$\mu A$

SMC6117 (continued)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Segment output current	$I_{OH6}$	$V_{OH6} = -0.05V$	SEG1 to 32		-0.15	$\mu A$
	$I_{OL6}$	$V_{OL6} = -1.45V$		0.15		$\mu A$
Boosted output voltage	$V_{S2}$	1M $\Omega$ loading connected between $V_{DD}$ and $V_{S2}$	$V_{S2}$		-2.90	V
Boosted ripple voltage	$V_{rip2}$			0.1	V	
Boosted output voltage	$V_{S3}$	1M $\Omega$ loading connected between $V_{DD}$ and $V_{S3}$			-4.1	V
Boosted ripple voltage	$V_{rip3}$			0.3	V	
Current consumption	$I_{S1}$	No Load, Base Time Mode		0.80	1.40	$\mu A$
		No Load, Executing		3.0	5.0	
Operating voltage range	$V_{DD} - V_{S1}$		1.35	1.50	1.70	V

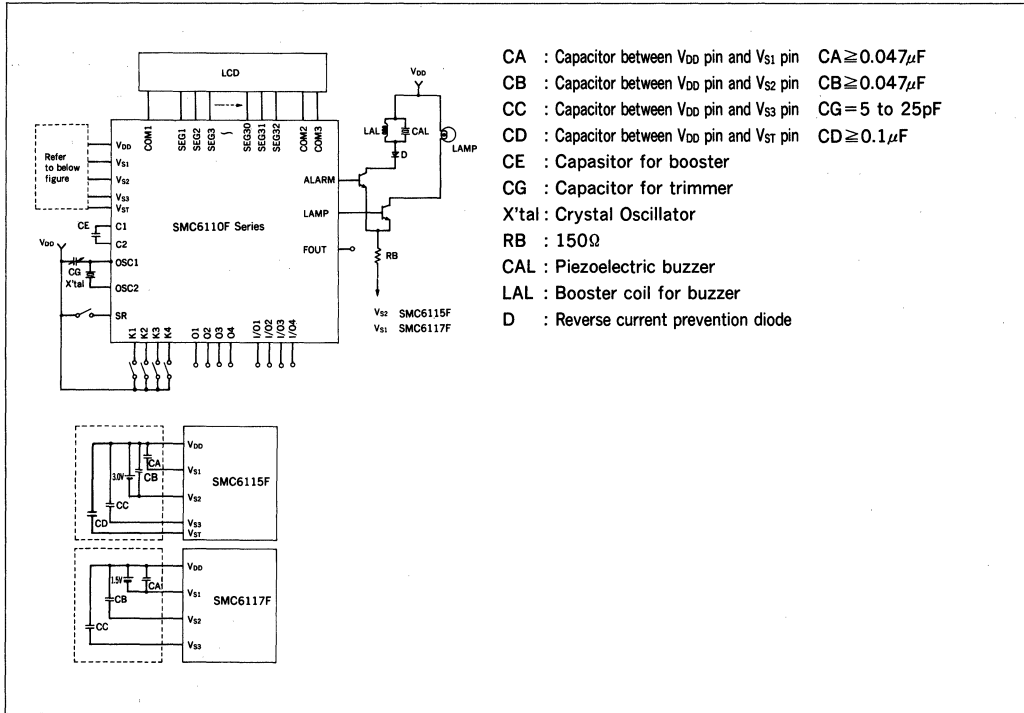
■ PACKAGE DIMENSIONS



■ SMC6110F SERIES

Type No.	Power Supply	Instruction Cycle	Package
SMC6115F	3.0V Li battery	122 $\mu s$	60-pin QFP
SMC6117F	1.5V Ag battery	122 $\mu s$	80-pin QFP

## EXAMPLE OF APPLICATION



## INSTRUCTION SET

Function	Mnemonic	Machine Code										Flag				Operation		
		B	A	9	8	7	6	5	4	3	2	1	0	C	Z		K	S
System	NOP	1	1	1	1	1	1	1	1	1	1	1	1					No Operation
	HLT b	1	1	1	1	1	1	1	0	1	1	1	b					Clock stop b=0 : 1s Restart b=1 : 1/10s Restart
	EI	1	1	1	1	1	1	0	1	1	1	1	1					Enable Key Interrupt
	DI	1	1	1	1	1	1	0	1	1	1	1	0					Disable Key Interrupt
	RESW	1	1	1	1	1	1	0	0	1	1	1	1					Reset Stop Watch Counter
	CFC b	1	1	1	1	1	0	1	1	1	1	1	b	↓				Carry Flag Control b=0 reset : b=1 set
	ZFC b	1	1	1	1	1	0	1	0	1	1	1	b		↓			Zero Flag Control b=0 reset : b=1 set
ALU	ADD A, i	1	1	1	1	0	0	0	0	i3	i2	i1	i0	↓	↓			A ← A+i
	ADC A, i	1	1	1	1	0	0	0	1	i3	i2	i1	i0	↓	↓			A ← A+i+C
	AND A, i	1	1	1	1	0	0	1	0	i3	i2	i1	i0	↓				A ← A∧i
	OR A, i	1	1	1	1	0	0	1	1	i3	i2	i1	i0		↓			A ← A∨i
	ADD B, i	1	1	1	1	0	1	0	0	i3	i2	i1	i0	↓	↓			B ← B+i
	ADC B, i	1	1	1	1	0	1	0	1	i3	i2	i1	i0	↓	↓			B ← B+i+C
	AND B, i	1	1	1	1	0	1	1	0	i3	i2	i1	i0		↓			B ← B∧i
	OR B, i	1	1	1	1	0	1	1	1	i3	i2	i1	i0		↓			B ← B∨i
	CP r, i	1	1	1	0	0	r2	r1	r0	i3	i2	i1	i0	↓	↓			r ← i
	FAN r, i	1	1	1	0	1	r2	r1	r0	i3	i2	i1	i0		↓			r ← i
	ADD r, A	1	0	0	1	0	r2	r1	r0	0	0	0	0	↓	↓			r ← r+A
	ADC r, A	1	0	0	1	0	r2	r1	r0	0	0	0	1	↓	↓			r ← r+A+C

INSTRUCTION SET (continued)

Function	Mnemonic	Machine Code										Flag				Operation					
		B	A	9	8	7	6	5	4	3	2	1	0	C	Z		K	S			
ALU	SUB	r	,	A	1	0	0	1	0	r2	r1	r0	0	0	1	0	↓	↓			r←r-A
	SBC	r	,	A	1	0	0	1	0	r2	r1	r0	0	0	1	1	↓	↓			r←r-A-C
	AND	r	,	A	1	0	0	1	0	r2	r1	r0	0	1	0	0		↓			r←r∧A
	OR	r	,	A	1	0	0	1	0	r2	r1	r0	0	1	0	1		↓			r←r∨A
	CP	r	,	A	1	0	0	1	0	r2	r1	r0	0	1	1	0	↓	↓			r-A
	FAN	r	,	A	1	0	0	1	0	r2	r1	r0	0	1	1	1		↓			r∧A
	ADD	r	,	B	1	0	0	1	0	r2	r1	r0	1	0	0	0	↓	↓			r←r+B
	ADC	r	,	B	1	0	0	1	0	r2	r1	r0	1	0	0	1	↓	↓			r←r+B+C
	SUB	r	,	B	1	0	0	1	0	r2	r1	r0	1	0	1	0	↓	↓			r←r-B
	SBC	r	,	B	1	0	0	1	0	r2	r1	r0	1	0	1	1	↓	↓			r←r-B-C
	AND	r	,	B	1	0	0	1	0	r2	r1	r0	1	1	0	0		↓			r←r∧B
	OR	r	,	B	1	0	0	1	0	r2	r1	r0	1	1	0	1		↓			r←r∨B
	CP	r	,	B	1	0	0	1	0	r2	r1	r0	1	1	1	0	↓	↓			r-B
	FAN	r	,	B	1	0	0	1	0	r2	r1	r0	1	1	1	1		↓			r∧B
	ADD	A	,	r	1	0	1	0	0	r2	r1	r0	0	0	0	0	↓	↓			A←r+A
	ADC	A	,	r	1	0	1	0	0	r2	r1	r0	0	0	0	1	↓	↓			A←r+A+C
	SUBR	A	,	r	1	0	1	0	0	r2	r1	r0	0	0	1	0	↓	↓			A←r-A
	SBCR	A	,	r	1	0	1	0	0	r2	r1	r0	0	0	1	1	↓	↓			A←r-A-C
	AND	A	,	r	1	0	1	0	0	r2	r1	r0	0	1	0	0		↓			A←r∧A
	OR	A	,	r	1	0	1	0	0	r2	r1	r0	0	1	0	1		↓			A←r∨A
	ADD	B	,	r	1	0	1	0	0	r2	r1	r0	1	0	0	0	↓	↓			B←r+B
	ADC	B	,	r	1	0	1	0	0	r2	r1	r0	1	0	0	1	↓	↓			B←r+B+C
	SUBR	B	,	r	1	0	1	0	0	r2	r1	r0	1	0	1	0	↓	↓			B←r-B
	SBCR	B	,	r	1	0	1	0	0	r2	r1	r0	1	0	1	1	↓	↓			B←r-B-C
	AND	B	,	r	1	0	1	0	0	r2	r1	r0	1	1	0	0		↓			B←r∧B
	OR	B	,	r	1	0	1	0	0	r2	r1	r0	1	1	0	1		↓			B←r∨B
	ADDP	r	,	A	1	0	0	1	1	r2	r1	r0	0	0	0	0	↓	↓			r←r+A Y←Y+1
	ADCP	r	,	A	1	0	0	1	1	r2	r1	r0	0	0	0	1	↓	↓			r←r+A+C Y←Y+1
	SUBP	r	,	A	1	0	0	1	1	r2	r1	r0	0	0	1	0	↓	↓			r←r-A Y←Y+1
	SBCP	r	,	A	1	0	0	1	1	r2	r1	r0	0	0	1	1	↓	↓			r←r-A-C Y←Y+1
	ANDP	r	,	A	1	0	0	1	1	r2	r1	r0	0	1	0	0		↓			r←r∧A Y←Y+1
	ORP	r	,	A	1	0	0	1	1	r2	r1	r0	0	1	0	1		↓			r←r∨A Y←Y+1
ADDP	r	,	B	1	0	0	1	1	r2	r1	r0	1	0	0	0	↓	↓			r←r+B Y←Y+1	
ADCP	r	,	B	1	0	0	1	1	r2	r1	r0	1	0	0	1	↓	↓			r←r+B+C Y←Y+1	
SUBP	r	,	B	1	0	0	1	1	r2	r1	r0	1	0	1	0	↓	↓			r←r-B Y←Y+1	
SBCP	r	,	B	1	0	0	1	1	r2	r1	r0	1	0	1	1	↓	↓			r←r-B-C Y←Y+1	
ANDP	r	,	B	1	0	0	1	1	r2	r1	r0	1	1	0	0		↓			r←r∧B Y←Y+1	
ORP	r	,	B	1	0	0	1	1	r2	r1	r0	1	1	0	1		↓			r←r∨B Y←Y+1	



**INSTRUCTION SET (continued)**

Function	Mnemonic	Machine Code										Flag			Operation			
		B	A	9	8	7	6	5	4	3	2	1	0	C		Z	K	S
LOAD	LD r, i	1	1	0	0	0	r2	r1	r0	i3	i2	i1	i0					r←i
	LXDY x, y	1	1	0	1	x3	x2	x1	x0	y3	y2	y1	y0					X←x, Y←y
	LDP M, i	1	1	1	1	1	0	0	1	i3	i2	i1	i0					M(X, Y)←i Y←Y+1
	LD r, r'	1	0	0	0	0	r2	r1	r0	0	r'2	r'1	r'0					r←r'
	LDP r, r'	1	0	0	0	0	r2	r1	r0	1	r'2	r'1	r'0					r←r', Y←Y+1
	LD r, SW0	1	0	0	0	1	r2	r1	r0	0	1	0	0					r←SW0
	LD r, SW1	1	0	0	0	1	r2	r1	r0	0	1	0	1					r←SW1
IN	IN r	1	0	0	0	1	r2	r1	r0	0	1	1	1					r←IN
Branch	CALL ps	0	1	p3	p2	p1	p0	s5	s4	s3	s2	s1	s0					Subroutine Call PC5+1→PCS, SF→SP, then [SP=0: PCP→STP1, PCS→STS1] [SP=1: PCP→STP2, PCS→STS2] then p→PCP, s→PCS
	RET	1	1	0	0	1	1	0	0	1	1	1	1					Return [SP=0: STP1→PCP, STS1→PCS] [SP=1: STP2→PCP, STS2→PCS] then, SP→SP
	RET LM, i	1	1	0	0	1	1	0	1	i3	i2	i1	i0					M(X, Y)←i, then, Return
	RET AM, i	1	1	0	0	1	1	1	0	i3	i2	i1	i0		↓			M(X, Y)←M(X, Y)∧i then, Return
	RET OM, i	1	1	0	0	1	1	1	1	i3	i2	i1	i0		↓			M(X, Y)←M(X, Y)∨i then, Return
	JP ps	0	0	p3	p2	p1	p0	s5	s4	s3	s2	s1	s0					Jump p→PCP, s→PCS
	JP C, s	1	0	1	1	0	0	s5	s4	s3	s2	s1	s0					Jump Condition IF C=1 s→PCS
	JP NC, s	1	0	1	1	0	1	s5	s4	s3	s2	s1	s0					Jump Condition IF C=0 s→PCS
	JP Z, s	1	0	1	1	1	0	s5	s4	s3	s2	s1	s0					Jump Condition IF Z=1 s→PCS
	JP NZ, s	1	0	1	1	1	1	s5	s4	s3	s2	s1	s0					Jump Condition IF Z=0 s→PCS
	JP K, s	1	0	1	0	1	0	s5	s4	s3	s2	s1	s0			↓		Jump Condition IF K=1 s→PCS Reset K
	JP S, s	1	0	1	0	1	1	s5	s4	s3	s2	s1	s0				↓	Jump Condition IF S=1 s→PCS Reset S
	JP A, j	1	1	0	0	1	0	j5	j4	1	1	1	1					Jump Indirect by A PCS5, 4←j5, 4 PCS3to0←A

NOTE: 1 r and r' correspond to register A, B, J, K, L, X, Y, and M (X, Y). The following table shows the relationship between code and register.

Register	CODE			Register	CODE			Register	CODE		
	r2	r1	r0		r2	r1	r		r2	r1	r0
A	0	0	0	K	0	1	1	Y	1	1	0
B	0	0	1	L	1	0	0	M (X, Y)	1	1	1
J	0	1	0	X	1	0	1				

- 2 i refers to 4 bits Immediate Data. Co refers to 1 bit Immediate Data. P refers to 4 bits Immediate Data. S refers to 6 bits Immediate Data.
- 3 PCP: Program Counter Page. PCS: Program Counter Step. STP: Stack Page. STS: Stack Step. SW: Stop Watch Counter. C: Carry Flag. Z: Zero Flag. K: Key Flag. S: Second Flag.

# SMC6214F

## CMOS 4 BIT SINGLE CHIP MICROCOMPUTER

- Core CPU Architecture
- 32 KHz/455 KHz Twin Clock Operation
- Built-in BLD and Analog Comparator
- Built-in Watchdog Timer

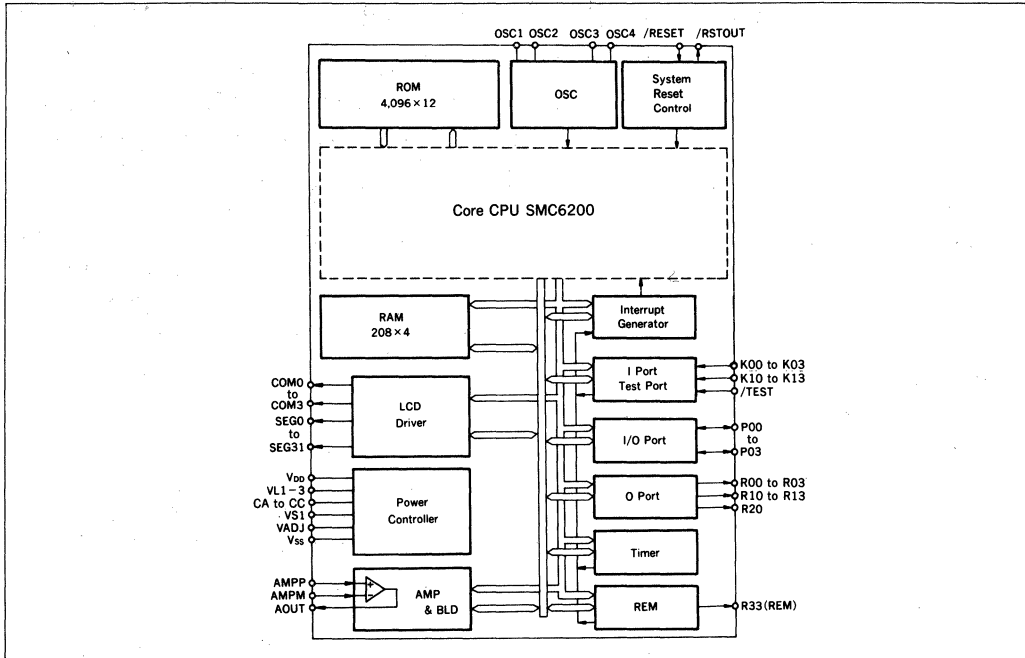
### ■ DESCRIPTION

The SMC6214F is a CMOS 4-bit microcomputer using an SMC6200 as its core processors. It contains ROM, RAM, an LCD driver circuit, remote-control carrier output circuit, time base counter, analog comparator, watchdog timer, and other functions on a single chip. The SMC6214F provides an excellent solution for low-power system applications such as an infrared remote controller with a clock function.

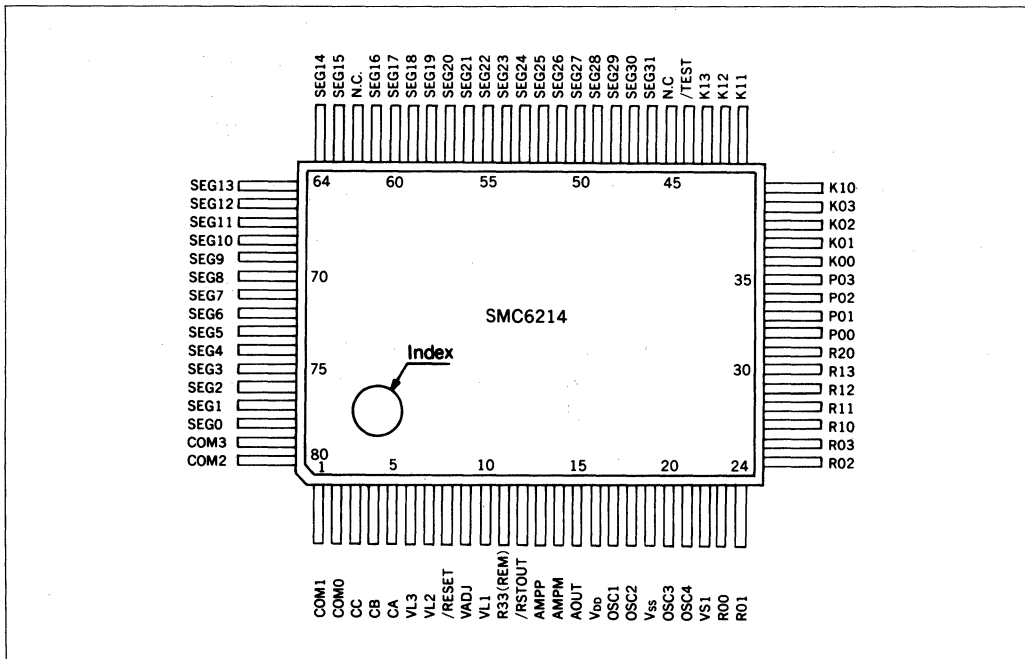
### ■ FEATURES

- CMOS LSI 4-bit parallel processing
- Clocks .....32.768 kHz (typ.) or 455 kHz (typ.), selectable by software
- Instruction set .....100 instructions
- Instruction cycle time ..... 32kHz clock mode : 153  $\mu$ sec, 214  $\mu$ sec or 366  $\mu$ sec  
455kHz clock mode : 11  $\mu$ sec, 15  $\mu$ sec or 26  $\mu$ sec
- ROM size .....4,096 $\times$ 12 bits
- RAM size .....208 $\times$ 4 bits
- Input port .....8 bits (pull-up resistors available by using a mask option)
- Output port .....9 bits (clock, buzzer output available by using a mask option)
- I/O port .....4 bits
- REM output .....1 bit (hardware timer or software timer selectable by software)
- LCD driver .....32 segments $\times$ 3 commons or 32 segments $\times$ 4 commons  
(1/3 or 1/4 duty selectable by using a mask option)
- Built-in LCD power supplies .....Voltage regulator, voltage doubler, and voltage tripler
- Built-in BLD circuit .....2.3V (battery life detector)
- Built-in amplifier .....Operational amplifier for MOS input analog comparator
- Built-in watchdog timer
- Interrupts .....External : two input interrupts  
Internal : three timer interrupts (32Hz, 8Hz, 2Hz)  
one REM interrupt
- Supply voltage .....3V (2.2 to 3.5V)
- Current dissipation ..... 32kHz clock mode : 5 $\mu$ A (typ.) (basic clock mode)  
455kHz clock mode : 300 $\mu$ A (typ.)
- Package .....80-pin QFP (plastic)  
also available in chip form

## ■ BLOCK DIAGRAM



## ■ PIN CONFIGURATION



## ■PIN DESCRIPTION

Pin name	Functions	Pin name	Functions
V <sub>DD</sub>	Power supply (+)	AMPP	Analog comparator non-reverse input pin
V <sub>SS</sub>	Power supply (-)	AMPM	Analog comparator reverse input pin
V <sub>S1</sub>	Power supply for oscillator (generated internally)	AOUT	Analog comparator output pin
V <sub>L1</sub>	Power supply for LCD driver (generated internally)	/TEST	Test input pin
V <sub>L2</sub>	Power supply for LCD driver (doubled V <sub>L1</sub> )	/RESET	System reset input pin
V <sub>L3</sub>	Power supply for LCD driver (tripled V <sub>L1</sub> )	K00 to 03	Input ports
CA to CC	Capacitor connection pins for LCD booster	K10 to 13	Input ports
VADJ	VL adjusting input pin	P00 to 03	Input/Output ports
OSC1	Crystal oscillation input pin	R00 to 03	Output ports (R12: selectable for DC output, FOUT output or/BZ output by using mask option) (R13: selectable for DC output or BZ output by using mask option)
OSC2	Crystal oscillation output pin (containing CD)	R10 to 13	
OSC3	Ceramic or CR oscillation input pin (selectable by using mask option)	R20	
OSC4	Ceramic or CR oscillation output pin (selectable by using mask option)	R33 (REM)	Remote-control output pin
COM0 to 3	LCD common output (1/3 or 1/4 duty selectable by using mask option)	/RSTOUT	System reset output pin
SEG0 to 31	LCD segment output (DC output available by using mask option)		

## ■ABSOLUTE MAXIMUM RATINGS

(V<sub>DD</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>SS</sub>	-5.2 to 0.5	V
Input voltage	V <sub>I</sub>	V <sub>SS</sub> -0.3 to 0.3	V
	V <sub>IOSC</sub>	V <sub>S1</sub> -0.3 to 0.3	V
Operating temperature	T <sub>opr</sub>	-20 to 60	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at leads)	—
Power dissipation	P <sub>D</sub>	250	mW

## ■RECOMMENDED OPERATING CONDITIONS

(T<sub>a</sub> = -20°C to 60°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>SS</sub>	V <sub>DD</sub> =0V	-3.5	-3.0	-2.2	V
Oscillation frequency	f <sub>osc1</sub>		—	32.768	—	kHz
	f <sub>osc3</sub>	duty : 50 ± 5%	50	455	500	kHz
Power supply voltage for LCD driver	V <sub>L1</sub>		-1.6	-1.05	—	V

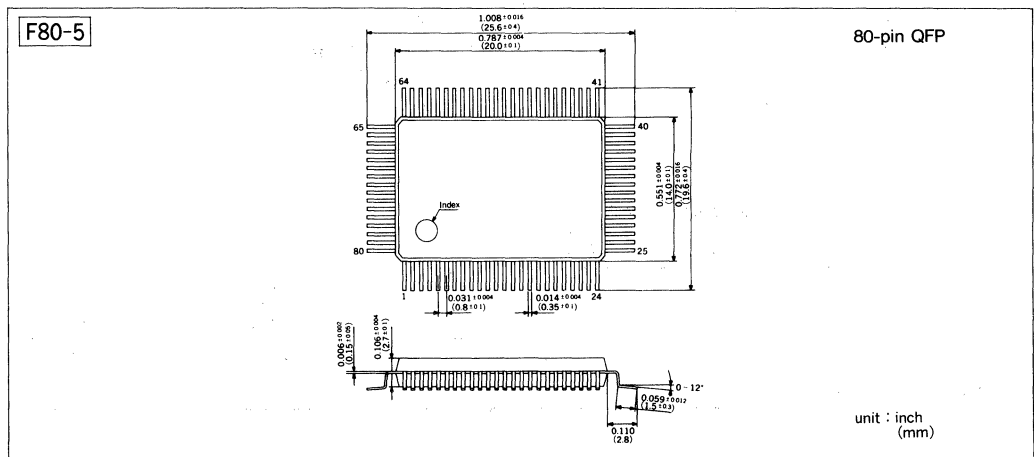
## ELECTRICAL CHARACTERISTICS

( $V_{DD}=0V$ ,  $V_{SS}=-2.2$  to  $-3.5V$ ,  $V_{L3}=-3.0V$ ,  $T_a=-20$  to  $60^{\circ}C$ )

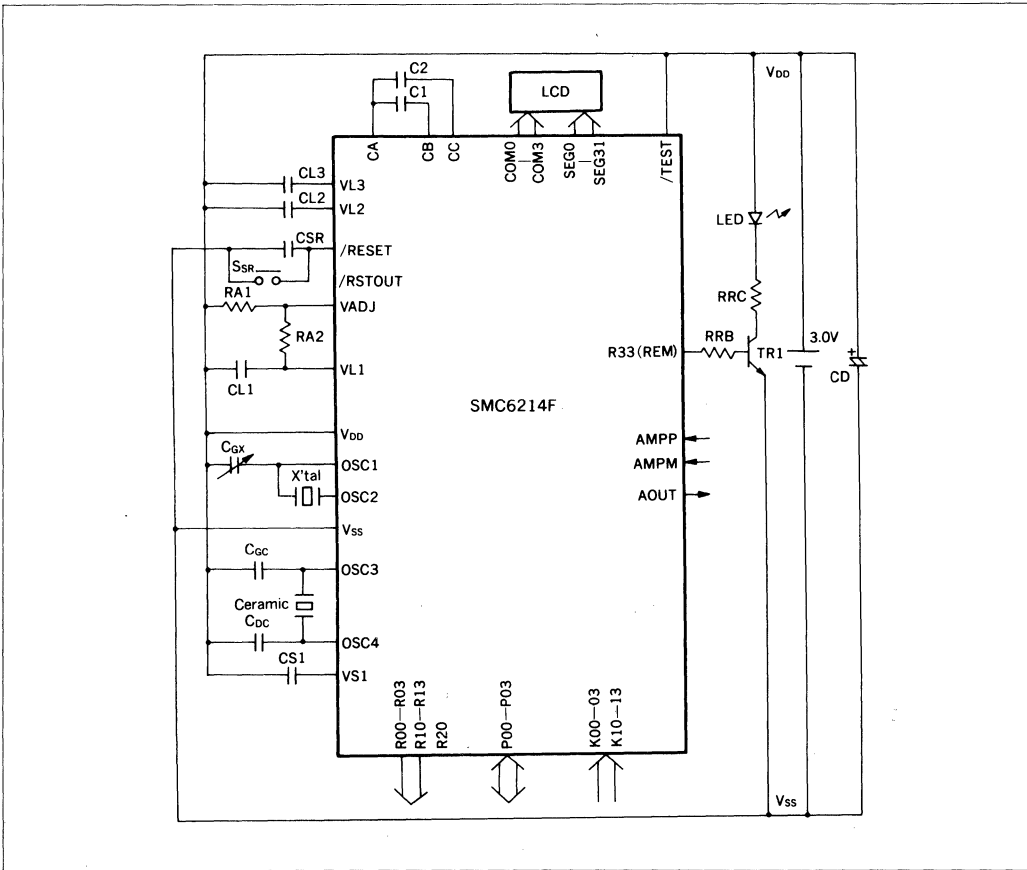
Parameter	Symbol	Conditions	Min	Typ	Max	Unit	
High-level input voltage (1)	$V_{IH1}$	K00 to K13 P00 to P03	$0.2V_{SS}$	—	0	V	
Low-level input voltage (1)	$V_{IL1}$		$V_{SS}$	—	$0.8V_{SS}$	V	
High-level input current (2)	$V_{IH2}$	/RESET	$0.1V_{SS}$	—	0	V	
Low-level input voltage (2)	$V_{IL2}$		$V_{SS}$	—	$0.9V_{SS}$	V	
Low-level input current	$I_{IL1}$	$V_{IL1}=V_{SS}$ , Without pull-up resistor	K00 to K13	-1	—	$\mu A$	
	$I_{IL2}$	$V_{IL2}=V_{SS}$ , With pull-up resistor	K00 to K13	-5	—	$\mu A$	
	$I_{IL3}$	$V_{IL3}=0.2V_{SS}$	/RESET	-30	—	$\mu A$	
	$I_{IL4}$	$V_{IL4}=V_{SS}$	P00 to P03 (at read mode) (with a built-in program)	-15	—	$\mu A$	
High-level input current	$I_{IH1}$	$V_{IH1}=0V$	—	—	1	$\mu A$	
High-level output current (1)	$I_{OH1}$	$V_{OH1}=0.1V_{SS}$	R00 to R03 R10 to R13	—	-250	$\mu A$	
Low-level output current (1)	$I_{OL1}$	$V_{OL1}=0.9V_{SS}$	/RSTOUT	1.0	—	mA	
High-level output current (2)	$I_{OH2}$	$V_{OH2}=0.1V_{SS}$	R20	—	—	-1.8	mA
Low level output current (2)	$I_{OL2}$	$V_{OL2}=0.9V_{SS}$		1.0	—	—	mA
High-level output current (3)	$I_{OH3}$	$V_{OH3}=0.1V_{SS}$	P00 to P03	—	—	-100	$\mu A$
Low-level output current (3)	$I_{OL3}$	$V_{OL3}=0.9V_{SS}$		140	—	—	$\mu A$
High level output current (4)	$I_{OH4}$	$V_{OH4}=0.5V_{SS}$	R33 (REM)	—	—	-1.0	mA
Low-level output current (4)	$I_{OL4}$	$V_{OL4}=0.9V_{SS}$		1.0	—	—	mA
Common output current	$I_{OH5}$	$V_{OH5}=-0.05V$	COM0 to 3 $V_{SS}=-3.0V$	—	—	-3.0	$\mu A$
	$I_{OL5}$	$V_{OL5}=-2.95V$		3.0	—	—	$\mu A$
Segment output current	$I_{OH6}$	$V_{OH6}=-0.05V$	SEG0 to 31 $V_{SS}=-3.0V$	—	—	-3.0	$\mu A$
	$I_{OL6}$	$V_{OL6}=-2.95V$		3.0	—	—	$\mu A$
Internal voltages	$V_{L1}$	$V_{ADJ}=V_{L1}$ , $I_{L1}=5\mu A$ with $1M\Omega$ loads between $V_{DD}$ and $V_{L2}$ and between $V_{DD}$ and $V_{L3}$	-1.13	-1.05	-0.98	V	
	$V_{L2}$		$2 \cdot V_{L1}$	$2V_{L1}$	$2 \cdot V_{L1} + 0.1$	V	
	$V_{L3}$		$3 \cdot V_{L1}$	$3V_{L1}$	$3 \cdot V_{L1} + 0.3$	V	
BLD voltage	$V_{BLD}$	$T_a=25^{\circ}C$	-2.4	-2.3	-2.2	V	
Current dissipation	$I_{opr}$	At halt	OSCC=0, $T_a=25^{\circ}C$ $V_{ADJ}=V_{L1}$ No panel load	—	3	8	$\mu A$
		In Basic clock mode*	—	5	12	$\mu A$	
		In 455KHz clock mode	$V_{ADJ}=V_{L1}$ No panel load $T_a=25^{\circ}C$	—	300	450	$\mu A$

\*Basic clock mode: duty cycle 10%

## PACKAGE DIMENSIONS



## EXAMPLE OF APPLICATION



## INSTRUCTION SET

Group	Mnemonic	Operand	OP code																Flag			Clock	Operation		
			B	A	9	8	7	6	5	4	3	2	1	0	p3	p2	p1	p0	I	D	Z			C	
Branch	PSET	P	1	1	1	0	0	1	0	p4	p3	p2	p1	p0									5	NPB-p4, NPP-p3-0	
		s	0	0	0	0	s7	s6	s5	s4	s3	s2	s1	s0									5	PCB-NPB, PCP-NPP, PCS-s7-0	
		C, s	0	0	1	0	s7	s6	s5	s4	s3	s2	s1	s0									5	PCB-NPB, PCP-NPP, PCS-s7-0 if C=1	
		NC, s	0	0	1	1	s7	s6	s5	s4	s3	s2	s1	s0									5	PCB-NPB, PCP-NPP, PCS-s7-0 if C=0	
		Z, s	0	1	1	0	s7	s6	s5	s4	s3	s2	s1	s0									5	PCB-NPB, PCP-NPP, PCS-s7-0 if Z=1	
	JP	NZ, s	0	1	1	1	s7	s6	s5	s4	s3	s2	s1	s0									5	PCB-NPB, PCP-NPP, PCS-s7-0 if Z=0	
		JPBA	1	1	1	1	1	1	1	0	1	0	0	0									5	PCB-NPB, PCP-NPP, PCSH-B, PCSL-A	
		CALL	s	0	1	0	0	s7	s6	s5	s4	s3	s2	s1	s0									7	M(SP-1)-PCP, M(SP-2)-PCSH, M(SP-3)-PCSL+1 SP-SP-3, PCP-NPP, PCS-s7-0
		CALZ	s	0	1	0	1	s7	s6	s5	s4	s3	s2	s1	s0									7	M(SP-1)-PCP, M(SP-2)-PCSH, M(SP-3)-PCSL+1 SP-SP-3, PCP-0, PCS-s7-0
		RET		1	1	1	1	1	0	1	1	1	1	1	1									7	PCSL-M(SP), PCSH-M(SP+1), PCP-M(SP+2), SP-SP+3
System Control	RETS		1	1	1	1	1	0	1	1	1	1	0									12	PCSL-M(SP), PCSH-M(SP+1), PCP-M(SP+2), SP-SP+3 PC-PC+1		
	RETD	I	0	0	0	1	17	16	15	14	13	12	11	10									12	PCSL-M(SP), PCSH-M(SP+1), PCP-M(SP+2), SP-SP+3 M(X)-13-0, M(X+1)-17-4, X-X+2	
	NOP5		1	1	1	1	1	1	1	1	1	0	1	1									5	No Operation (3 clocks)	
Flag Operation	NOP7		1	1	1	1	1	1	1	1	1	1	1									7	No Operation (7 clocks)		
	HALT		1	1	1	1	1	1	1	1	0	0	0									5	Half (stop clock)		
	SET	F, i	1	1	1	0	1	0	0	13	12	11	10									7	F←F∨i3-0		
	RST	F, i	1	1	1	0	1	0	0	13	12	11	10									7	F←F∧i3-0		
	SCF		1	1	1	0	1	0	0	0	0	0	1									7	C←1		
	RCF		1	1	1	0	1	0	1	1	1	1	0									7	C←0		
	SZF		1	1	1	0	1	0	0	0	0	0	1	0									7	Z←1	
	RZF		1	1	1	0	1	0	1	1	1	0	1									7	Z←0		
	SDF		1	1	1	0	1	0	0	0	0	1	0	0									7	D←1 (Decimal Adjust ON)	
	RDF		1	1	1	0	1	0	1	1	0	1	1									7	D←0 (Decimal Adjust OFF)		
Flag Operation	EI		1	1	1	0	1	0	0	1	0	0	0									7	I←1 (Enable Interrupt)		
	DI		1	1	1	0	1	0	1	0	1	1	1									7	I←0 (Disable Interrupt)		

Group	Mnemonic	Operand	OP code										Flag			Clock	Operation						
			B	A	9	8	7	6	5	4	3	2	1	0	i			D	Z	C			
Stack Operation	INC	SP	1	1	1	1	1	1	0	1	1	0	1	1				5	SP←SP+1				
	DEC	SP	1	1	1	1	1	1	0	0	1	0	1	1				5	SP←SP-1				
	PUSH	r	r	1	1	1	1	1	1	0	0	0	r1	r0				5	M(SP-1)←r, SP←SP-1				
		XH	XH	1	1	1	1	1	1	0	0	0	1	0	1				5	M(SP-1)←XH, SP←SP-1			
		XL	XL	1	1	1	1	1	1	0	0	0	1	1	0				5	M(SP-1)←XL, SP←SP-1			
		YH	YH	1	1	1	1	1	1	0	0	1	0	0	0				5	M(SP-1)←YH, SP←SP-1			
		YL	YL	1	1	1	1	1	1	0	0	1	0	0	1				5	M(SP-1)←YL, SP←SP-1			
		F	F	1	1	1	1	1	1	0	0	1	0	1	0				5	M(SP-1)←F, SP←SP-1			
	POP	r	r	1	1	1	1	1	1	0	1	0	0	r1	r0				5	r←M(SP), SP←SP+1			
		XH	XH	1	1	1	1	1	1	0	1	0	1	0	1				5	XH←M(SP), SP←SP+1			
		XL	XL	1	1	1	1	1	1	0	1	0	1	1	0				5	XL←M(SP), SP←SP+1			
		YH	YH	1	1	1	1	1	1	0	1	0	1	0	0				5	YH←M(SP), SP←SP+1			
		YL	YL	1	1	1	1	1	1	0	1	1	0	0	1				5	YL←M(SP), SP←SP+1			
		F	F	1	1	1	1	1	1	0	1	1	0	1	0	1	1	1	5	F←M(SP), SP←SP+1			
	LD	SPH, r	r	1	1	1	1	1	1	1	0	0	r1	r0				5	SPH←r				
		SPL, r	r	1	1	1	1	1	1	1	0	0	r1	r0				5	SPL←r				
		r, SPH	r	1	1	1	1	1	1	1	0	0	r1	r0				5	r←SPH				
		r, SPL	r	1	1	1	1	1	1	1	0	1	r1	r0				5	r←SPL				
	Index Operation	INC	X	1	1	1	0	1	1	1	0	0	0	0	0				5	X←X+1			
			Y	1	1	1	0	1	1	1	1	0	0	0	0				5	Y←Y+1			
r			1	1	1	0	1	1	1	1	0	0	0	0				5	r←r+1				
LD		X, x	x	1	0	1	0	1	x7	x8	x5	x4	x3	x2	x1	x0				5	XH←x7-4, XL←x3-0		
		Y, y	y	1	0	0	0	y7	y8	y5	y4	y3	y2	y1	y0				5	YH←y7-4, YL←y3-0			
		XH, r	r	1	1	1	0	1	0	0	0	1	r1	r0				5	XH←r				
		XL, r	r	1	1	1	0	1	0	0	0	1	0	r1	r0				5	XL←r			
		YH, r	r	1	1	1	0	1	0	0	1	0	r1	r0				5	YH←r				
		YL, r	r	1	1	1	0	1	0	0	1	1	0	r1	r0				5	YL←r			
		r, XH	r	1	1	1	0	1	0	1	0	0	1	r1	r0				5	r←XH			
		r, XL	r	1	1	1	0	1	0	1	0	0	1	0	r1	r0				5	r←XL		
		r, YH	r	1	1	1	0	1	0	1	1	0	1	r1	r0				5	r←YH			
		r, YL	r	1	1	1	0	1	0	1	1	1	0	r1	r0				5	r←YL			
ADC		XH, i	i	1	0	1	0	0	0	0	0	0	0	0	0	1	1	1	7	XH←XH+i3-0+C			
		XL, i	i	1	0	0	0	0	0	1	0	0	0	0	0	1	1	1	7	XL←XL+i3-0+C			
		YH, i	i	1	0	1	0	0	0	1	0	0	0	0	0	1	1	1	7	YH←YH+i3-0+C			
		YL, i	i	1	0	1	0	0	0	1	1	0	0	0	0	1	1	1	7	YL←YL+i3-0+C			
CP		XH, i	i	1	0	1	0	0	1	0	0	0	0	0	0	1	1	1	7	XH-i3-0			
		XL, i	i	1	0	1	0	0	1	0	1	0	0	0	0	1	1	1	7	XL-i3-0			
		YH, i	i	1	0	1	0	0	1	1	0	0	0	0	0	1	1	1	7	YH-i3-0			
	YL, i	i	1	0	1	0	0	1	1	1	0	0	0	0	1	1	1	7	YL-i3-0				
Data Transfer	LD	r, i	1	1	1	0	0	0	r1	r0	0	0	0	0				5	r←i3-0				
		r, q	1	1	1	0	1	1	0	0	r1	r0	q1	q0				5	r←q				
		A, Mn	1	1	1	1	1	0	1	0	0	n3	n2	n1	n0				5	A←M(n3-0)			
		B, Mn	1	1	1	1	1	0	1	0	0	0	n3	n2	n1	n0				5	B←M(n3-0)		
		Mn, A	1	1	1	1	1	0	0	0	0	n3	n2	n1	n0				5	M(n3-0)←A			
		Mn, B	1	1	1	1	1	0	0	0	1	n3	n2	n1	n0				5	M(n3-0)←B			
	LDPX	MX, i	i	1	1	1	0	0	1	1	0	0	0	0	0				5	M(X)-i3-0, X←X+1			
		r, q	r	1	1	1	0	1	1	1	0	r1	r0	q1	q0				5	r←q, X←X+1			
	LDPY	MY, i	i	1	1	1	0	0	1	1	1	0	0	0	0				5	M(Y)-i3-0, Y←Y+1			
		r, q	r	1	1	1	0	1	1	1	1	r1	r0	q1	q0				5	r←q, Y←Y+1			
	LBPX	MX, i	1	0	0	1	0	1	7	1	6	1	5	4	3	2	1	0				5	M(X)-i3-0, M(X+1)-i7-4, X←X+2
	Calculation	ADD	r, i	1	1	0	0	0	0	0	r1	r0	0	0	0	*	1	1	7	r←r+i3-0			
r, q			1	1	0	0	1	0	0	0	r1	r0	q1	q0	*	1	1	7	r←r+q				
r, i		1	1	0	0	0	1	r1	r0	0	0	0	0	0	*	1	1	7	r←r+i3-0+C				
r, q		1	1	0	0	1	0	0	1	r1	r0	q1	q0	*	1	1	7	r←r+q+C					
SUB		r, q	1	0	1	0	1	0	1	0	r1	r0	q1	q0	*	1	1	7	r←r-q				
SBC		r, i	1	0	1	0	1	0	1	r1	r0	0	0	0	*	1	1	7	r←r-i3-0-C				
		r, q	1	0	1	0	1	0	1	1	r1	r0	q1	q0	*	1	1	7	r←r-q-C				
AND		r, i	1	1	0	0	1	0	r1	r0	0	0	0	0	1	1	1	7	r←r∧i3-0				
		r, q	1	1	0	0	1	1	0	0	r1	r0	q1	q0	1	1	1	7	r←r∧q				
OR		r, i	1	1	0	0	1	1	r1	r0	0	0	0	0	1	1	1	7	r←r∨i3-0				
		r, q	1	1	0	0	1	1	0	1	r1	r0	q1	q0	1	1	1	7	r←r∨q				
XOR		r, i	1	1	0	1	0	0	r1	r0	0	0	0	0	1	1	1	7	r←r∨i3-0				
		r, q	1	1	0	1	0	1	1	0	r1	r0	q1	q0	1	1	1	7	r←r∨q				
CP		r, i	1	1	0	1	1	r1	r0	0	0	0	0	0	1	1	1	7	r-i3-0				
		r, q	1	1	1	1	0	0	0	0	r1	r0	q1	q0	1	1	1	7	r-q				
FAN		r, i	1	1	0	1	1	0	r1	r0	0	0	0	0	1	1	1	7	r∧i3-0				
		r, q	1	1	1	0	0	0	1	r1	r0	q1	q0	1	1	1	7	r∧q					
RLC		r	1	0	1	0	1	1	1	r1	r0	r1	r0	1	1	1	7	d3←d2, d2←d1, d1←d0, d0←C, C←d3					
RRC		r	1	1	0	1	0	1	0	0	1	1	r1	r0	1	1	1	5	d3←C, d2←d3, d1←d2, d0←d1, C←d0				
INC		Mn	1	1	1	1	0	1	1	0	n3	n2	n1	n0	1	1	1	7	M(n3-0)←M(n3-0)+1				
DEC	Mn	1	1	1	1	0	1	1	1	n3	n2	n1	n0	1	1	1	7	M(n3-0)←M(n3-0)-1					
ACPX	MX, r	r	1	1	1	1	0	0	1	0	r1	r0	*	1	1	7	M(X)←M(X)+r+C, X←X+1						
ACPY	MY, r	r	1	1	1	1	0	0	1	1	r1	r0	*	1	1	7	M(Y)←M(Y)+r+C, Y←Y+1						
SCPX	MX, r	r	1	1	1	1	0	0	1	1	0	r1	r0	*	1	1	7	M(X)←M(X)-r-C, X←X+1					
SCPY	MY, r	r	1	1	1	1	0	0	1	1	1	r1	r0	*	1	1	7	M(Y)←M(Y)-r-C, Y←Y+1					
NOT	r	r	1	1	0	1	0	0	r1	r0	1	1	1	1	1	1	1	7	r←r				

# SMC8360F Series

## CMOS 8 BIT SINGLE CHIP MICROCOMPUTER

- Minimum Instruction Cycle Time : 1  $\mu$ s
- On-chip Gate Array
- 4KB ROM

### DESCRIPTION

The SMC8360F Series is a high-performance low power CMOS 8 bit single chip microcomputer (minimum machine cycle time: 1  $\mu$ s). It contains a ROM, a RAM, I/O ports, a timer/counter, and a gate array (SMC8362/SMC8367 : 2 input NAND  $\times$  848 gates).

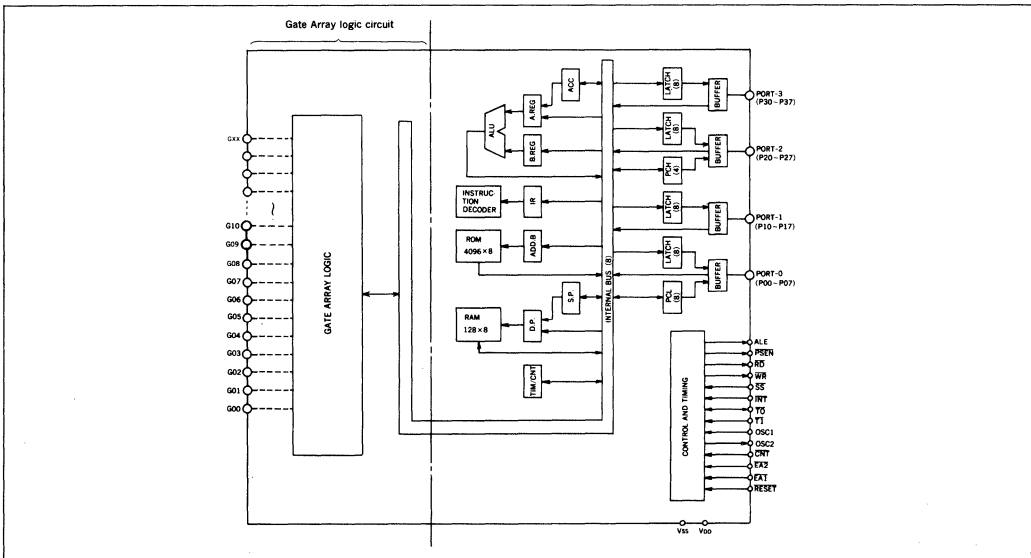
The major features include :

- High flexibility due to built-in gate array
- Reduce software overhead and faster processing.
- The capability of implementing a general-purpose controller for peripherals of the processor, by implementing a bus interface circuit.

### FEATURES

- CPU .....CMOS LSI 8 bits
- On-chip oscillator circuit .....50kHz to 4MHz
- Instruction cycle time .....1  $\mu$ s (Min)
- Instruction set .....104 sets
- ROM .....4k  $\times$  8 bits
- RAM .....128  $\times$  8 bits
- Built-in gate array  
SMC8362/SMC8367 : 2 input NAND  $\times$  848 gates
- Gate array .....SLA6000 series Equivalent
- I/O ports .....4 ports  $\times$  8 bits  
Gate array SMC8362/SMC8367 : 33 I/O (Max)
- Extension of external program ROM (Gate array option)
- Release from STOP mode circuit (Gate array option)
- Interrupts : External interrupt .....  
INT, T1, and T0 OR logic  
Internal interrupt .....  
timer/counter overflow
- Nesting levels ..... 8 subroutines (Max)
- Operational modes .....RUN, HALT, and STOP
- Single power supply .....5V  $\pm$  10% or 2.5 to 6.0V
- Package .....80-pin QFP (plastic)

### BLOCK DIAGRAM

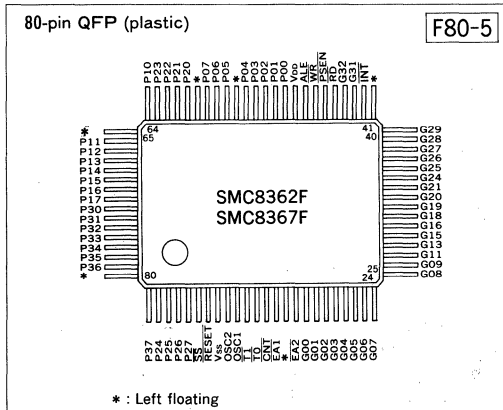




## ■ SMC8360F SERIES

Model	Gate	PORT-1(P10-P17)	Max gate array I/O	Package
SMC8362	848 gates	Input port or Output port	33	80-pin QFP (plastic)
SMC8367	848 gates	Address bus	33	80-pin QFP (plastic)

## ■ PIN CONFIGURATION



## ■ PIN DESCRIPTION

P00-P07	Bus interface bi-directional port
P10-P17	I/O port or 8 bit address bus
P20-P27	I/O port
P30-P37	I/O port
ALE	Address latch enable
WR	Write
RD	Read
EA1,EA2	Control mode pin
CNT	Counter input
RESET	System reset
SS	Single step
OSC1	Crystal oscillator input pin
OSC2	Crystal oscillator output pin
INT	Interrupt input
T1	Interrupt input
T0	Interrupt input/clock output
G00-GXX	Gate array I/O pin

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = GND)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	V <sub>SS</sub> -0.3 to 7.0	V
Input voltage	V <sub>I</sub>	V <sub>SS</sub> -0.3 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	V <sub>SS</sub> -0.3 to V <sub>DD</sub> +0.3	V
Output current/pin	I <sub>O</sub>	±10	mA
Power dissipation	P <sub>D</sub>	0.5	W
Operating temperature	T <sub>opr</sub>	-40 to 85	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10sec (Lead only)	—

## ■ RECOMMENDED OPERATING CONDITIONS

(T<sub>a</sub> = -40~85°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>	f <sub>osc</sub> = 50kHz to 1MHz	2.5	—	6.0	V
		f <sub>osc</sub> = 50kHz to 4MHz	4.5	5	5.5	V
	V <sub>SS</sub>		0	—	0	V
Input voltage	V <sub>I</sub>		V <sub>SS</sub>	—	V <sub>DD</sub>	V
Operating frequency	f <sub>osc</sub>	V <sub>DD</sub> = 5V ± 10%	50	—	4000	kHz

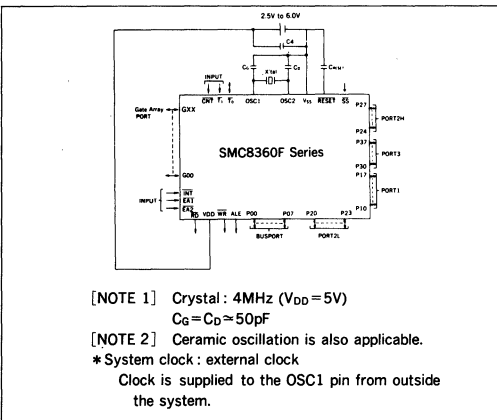
## ELECTRICAL CHARACTERISTICS

### DC Characteristics (CPU)

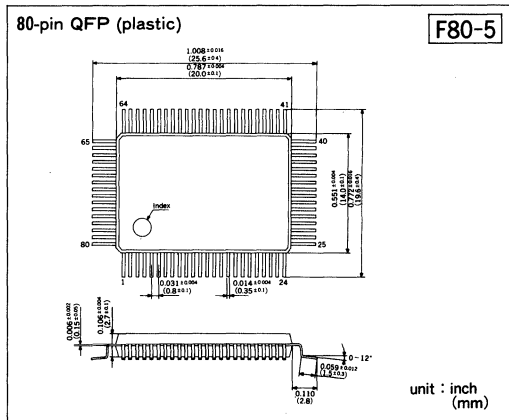
(V<sub>SS</sub>=GND, T<sub>a</sub> = -40 to 85°C)

Parameter	Symbol	Conditions	V <sub>DD</sub> = 5V ± 10%			V <sub>DD</sub> = 2.5 to 6.0V			Unit	
			Min	Typ	Max	Min	Typ	Max		
Low level input voltage	V <sub>IL</sub>		V <sub>SS</sub>	—	0.8	V <sub>SS</sub>	—	0.18V <sub>DD</sub>	V	
High level input voltage	V <sub>IH</sub>	Except RESET, SS, OSC1	2.0	—	V <sub>DD</sub>	0.6V <sub>DD</sub>	—	V <sub>DD</sub>	V	
	V <sub>IH1</sub>	RESET, SS, OSC1	V <sub>DD</sub> -1	—	V <sub>DD</sub>	0.8V <sub>DD</sub>	—	V <sub>DD</sub>	V	
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2.0mA	—	—	0.45	—	—	—	V	
		I <sub>OL</sub> = 1.0mA	—	—	—	—	—	0.45	V	
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -1.0mA	2.4	—	—	—	—	—	V	
		I <sub>OH</sub> = -100μA	—	—	—	0.8V <sub>DD</sub>	—	—	V	
Input current	I <sub>IP</sub>	V <sub>I</sub> = V <sub>SS</sub> Input pin with pull-up resistor	-250	-100	-30	-300	—	-6	μA	
	I <sub>IL</sub>	V <sub>I</sub> = V <sub>SS</sub> Latch input pin	-3	—	3	-3	—	3	μA	
	I <sub>IP2</sub>	V <sub>I</sub> = V <sub>SS</sub> SS pin	RUN mode -125 STOP mode -3	-50 0	-15 3	-150 -3	— —	-3 3	μA	
Input leakage current	I <sub>LI1</sub>	V <sub>I</sub> = V <sub>DD</sub>	-3	—	3	-3	—	3	μA	
	I <sub>LI2</sub>	V <sub>I</sub> = V <sub>DD</sub> SS pin	RUN mode 60 STOP mode 500	3 1500	3 12	-3 1800	— —	3 3	μA	
Output leakage current	I <sub>LOP</sub>	When at high impedance V <sub>O</sub> = V <sub>SS</sub> (with pull-up resistor)	-250	-100	-30	-300	—	-6	μA	
	I <sub>LOL</sub>	When at high impedance V <sub>O</sub> = V <sub>SS</sub> (with latch input)	-3	—	3	-3	—	3	μA	
	I <sub>LOH</sub>	When at high impedance V <sub>O</sub> = V <sub>DD</sub>	-3	—	3	-3	—	3	μA	
Standby current	I <sub>DDS1</sub>	HALT mode V <sub>DD</sub> = 5V ± 10% (f = 4MHz, T <sub>cy</sub> = 1μs)	—	2	10	—	—	—	mA	
		V <sub>DD</sub> = 6V (f = 4MHz, T <sub>cy</sub> = 1μs)	—	—	—	—	—	2.4	11	mA
		V <sub>DD</sub> = 3V (f = 1MHz, T <sub>cy</sub> = 4μs)	—	—	—	—	—	0.3	1.4	mA
	I <sub>DDS2</sub>	STOP mode V <sub>DD</sub> = 5V ± 10%	—	—	20	—	—	—	—	μA
		V <sub>DD</sub> = 6V	—	—	—	—	—	—	50	μA
		V <sub>DD</sub> = 3V	—	—	—	—	—	—	20	μA
Operating current	I <sub>DDO</sub>	RUN mode V <sub>DD</sub> = 5V ± 10% (f = 4MHz, T <sub>cy</sub> = 1μs)	—	6	20	—	—	—	—	mA
		V <sub>DD</sub> = 6V (f = 4MHz, T <sub>cy</sub> = 1μs)	—	—	—	—	—	7	22	mA
		V <sub>DD</sub> = 3V (f = 1MHz, T <sub>cy</sub> = 4μs)	—	—	—	—	—	0.9	3	mA
Data holding voltage	V <sub>DDR</sub>	STOP mode (no rapid voltage change allowed)	3.0	—	—	—	—	—	V	

## TYPICAL CIRCUIT

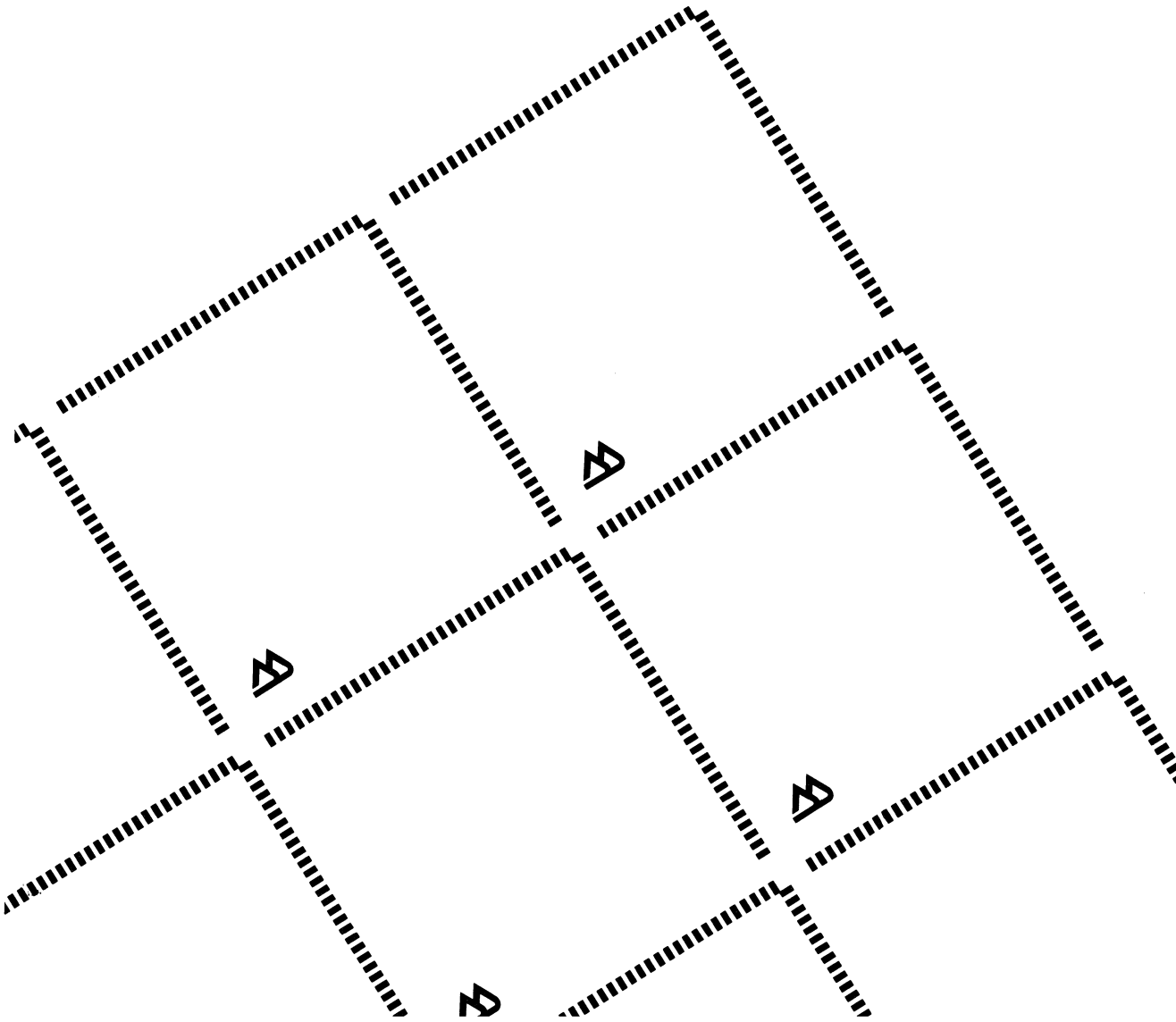


## PACKAGE DIMENSIONS



# INSTRUCTION SET

No.	Function	Mnemonic	Bytes	Machine cycle	Operation	No.	Function	Mnemonic	Bytes	Machine cycle	Operation	
1	Operational instructions	ADD A,Rr	1	1	A ← A + Rr r=0 to 7	56	Branch instructions	JP n	2	2	PC11 ← MR, PC10 to 8 ← n10 to 8 PC7 to 0 ← n7 to 0	
2		ADD A,(Rr)	1	1	A ← A + (Rr) r=0, 1	57		JP A	1	2	PC7 to 0 ← A	
3		ADD A, #n	2	2	A ← A + n7 to 0	58		DJNZ Rr, n	2	2	Rr ← Rr - 1 if Rr ≠ 0 r=0 to 7	
4		ADC A,Rr	1	1	A ← A + Rr + CY r=0 to 7	59		JP C, n	2	2	if CY = 1 JUMP	
5		ADC A, (Rr)	1	1	A ← A + (Rr) + CY r=0, 1	60		JP NC, n	2	2	if CY = 0 JUMP	
6		ADC A, #n	2	2	A ← A + n7 to 0 + CY	61		JP Z, n	2	2	if A = 0 JUMP	
7		AND A,Rr	1	1	A ← A ∧ Rr r=0 to 7	62		JP NZ, n	2	2	if A ≠ 0 JUMP	
8		AND, A,(Rr)	1	1	A ← A ∧ (Rr) r=0, 1	63		JBT Ab, n	2	2	if Ab = 1 JUMP b=7 to 0	
9		AND A, #n	2	2	A ← A ∧ n7 to 0	64		JP F1, n	2	2	if F1 = 1 JUMP	
10		OR A,Rr	1	1	A ← A ∨ Rr r=0 to 7	65		JP F0, n	2	2	if F0 = 1 JUMP	
11		OR A,(Rr)	1	1	A ← A ∨ (Rr) r=0, 1	66		JP TF, n	2	2	if TF = 1 JUMP & TF ← 0	
12		OR A, #n	2	2	A ← A ∨ n7 to 0	67		JP INTF, n	2	2	if INTF = 1 JUMP & INTF ← 0	
13		XOR A,Rr	1	1	A ← A ⊕ Rr r=0 to 7	68		JP T1F, n	2	2	if T1F = 1 JUMP & T1F ← 0	
14		XOR A,(Rr)	1	1	A ← A ⊕ (Rr) r=0, 1	69		JP T1, n	2	2	if T1 = 'H' JUMP	
15		XOR A, #n	2	2	A ← A ⊕ n7 to 0	70	JP T0, n	2	2	if T0 = 'H' JUMP		
16		ADD (Rr),A	1	1	(Rr) ← (Rr) + A r=0, 1	71	JP NT0, n	2	2	if T0 = 'L' JUMP		
17		ADC (Rr),A	1	1	(Rr) ← (Rr) + A + CY r=0, 1	72	JBT Mb, n	2	2	if Mb = 1 JUMP b=7 to 0		
18		AND (Rr),A	1	1	(Rr) ← (Rr) ∧ A r=0, 1	73	Subroutine call instructions	CALL n	2	2	(SP) ← PC, SRG, SP ← SP + 1	
19		OR (Rr),A	1	1	(Rr) ← (Rr) ∨ A r=0, 1	74		RET	1	2	PC11 ← MR, PC10 to 8 ← n10 to 8, PC7 to 0 ← n7 to 0 SP ← SP - 1, PC ← (SP)	
20		INC A	1	1	A ← A + 1	75		RETR	1	2	SP ← SP - 1, PC ← (SP), SRG ← (SP)	
21		DEC A	1	1	A ← A - 1	76		I/O instructions	IN A, Pp	1	2	A ← Pp p=0 to 3
22		CLR A	1	1	A ← 0	77	OUT Pp, A		1	2	Pp ← A p=0 to 3	
23		CPL A	1	1	A ← $\bar{A}$	78	AND Pp, #n		2	2	Pp ← Pp ∧ n7 to 0 p=0 to 3	
24		DA A	1	1	Converts accumulator data into 2-digit BCD	79	OR Pp, #n		2	2	Pp ← Pp ∨ n7 to 0 p=0 to 3	
25		SWAP A	1	1	A7 to 4 ↔ A3 to 0	80	IN A, P0		1	2	A ← P0	
26		RL A	1	1	An+1 ← An, An ← A7 n=0 to 6	81	OUT P0, A		1	2	P0 ← A	
27		RLC A	1	1	An+1 ← An, An ← CY, CY ← A7 n=0 to 6	82	AND P0, #n		2	2	P0 ← P0 ∧ n7 to 0	
28		RR A	1	1	An ← An+1, A7 ← A0 n=0 to 6	83	OR P0, #n		2	2	P0 ← P0 ∨ n7 to 0	
29		RRC A	1	1	An ← An+1, A7 ← CY, CY ← A0 n=0 to 6	84	Timer/counter instructions		LD A, TC	1	1	A ← TC
30		INC Rr	1	1	Rr ← Rr + 1 r=0 to 7	85			LD TC, A	1	1	TC ← A
31		INC (Rr)	1	1	(Rr) ← (Rr) + 1 r=0, 1	86		STRT T	1	1	Start timer	
32		DEC Rr	1	1	Rr ← Rr - 1 r=0 to 7	87		STRT C	1	1	Start Event Counter	
33		DEC (Rr)	1	1	(Rr) ← (Rr) - 1 r=0, 1	88		STOP TC	1	1	Stop timer/Counter	
34	RES C	1	1	CY ← 0	89	EI TC		1	1	Internal interrupt enable		
35	CPL C	1	1	CY ← $\bar{C}Y$	90	DI TC		1	1	Internal interrupt disable		
36	RES F0	1	1	F0 ← 0	91	Control instructions		EI EXT	1	1	External interrupt enable	
37	CPL F0	1	1	F0 ← $\bar{F}0$	92			DI EXT	1	1	External interrupt disable	
38	RES F1	1	1	F1 ← 0	93			CHG ALT0	1	1	ALT ← 0	
39	CPL F1	1	1	F1 ← $\bar{F}1$	94		CHG ALT1	1	1	ALT ← 1		
40	LD A,Rr	1	1	A ← Rr r=0 to 7	95		CHG MRO	1	1	MR ← 0		
41	LD A,(Rr)	1	1	A ← (Rr) r=0, 1	96		CHG MR1	1	1	MR ← 1		
42	LD A, #n	2	2	A ← n7 to 0	97		OUTTO CLK	1	1	CLOCK is supplied from $\bar{T}0$		
43	LD Rr,A	1	1	Rr ← A r=0 to 7	98		HALT	1	1	CPU Halt		
44	LD (Rr),A	1	1	(Rr) ← A r=0, 1	99		STOP	1	1	Stop CPU		
45	LD Rr, #n	2	2	Rr ← n7 to 0 r=0 to 7	100		NOP	1	1	NO OPERATION		
46	LD (Rr), #n	2	2	(Rr) ← n7 to 0 r=0, 1	101	Gate array control instructions	LD Gn, A	1	1	Gn ← A n=0 to 3		
47	LD A,SRG	1	1	A ← SRG	102		LD A, Gn	1	1	A ← Gn n=0 to 3		
48	LD SRG,A	1	1	SRG ← A	103		GST Xn	1	1	Timing signal n=0 to 3		
49	LDX A,(Rr)	1	2	A ← (Rr) r=0, 1	104		GST Yn	1	1	Timing signal n=0 to 3		
50	LDX (Rr),A	1	2	(Rr) ← A r=0, 1								
51	LDP R A,(A)	1	2	A ← (PC11 - 8, A)								
52	LDP3 A,(A)	1	2	A ← (0011, A)								
53	EX A,Rr	1	1	A ← Rr r=0 to 7								
54	EX A,(Rr)	1	1	A ← (Rr) r=0, 1								
55	EXN A,(Rr)	1	1	A3 to 0 ↔ (Rr)3 to 0 r=0, 1								





# SMC82C37AC/-4/-5

## CMOS PROGRAMMABLE DMA CONTROLLER

- Four DMA Channels
- Low Supply Current

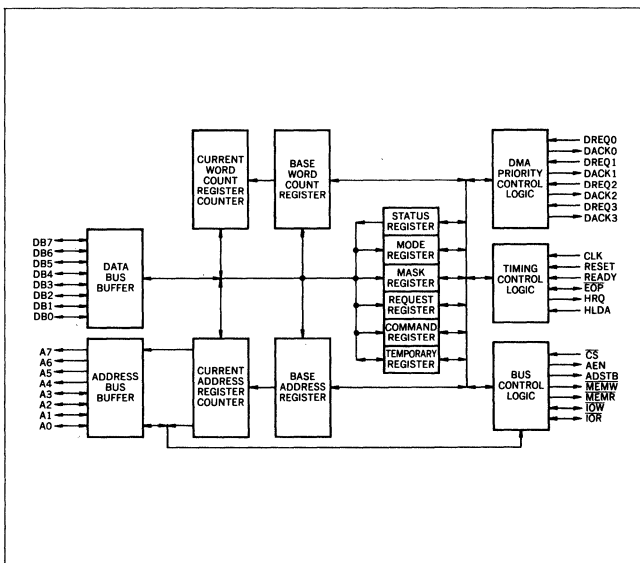
### DESCRIPTION

The SMC82C37AC/-4/-5 is an enhanced CMOS version of a programmable 4-channel Direct Memory Access (DMA) controller. The device is designed to improve system performance by permitting the CPU to off-load the task of moving blocks of data to and from memory via one of the DMA channels.

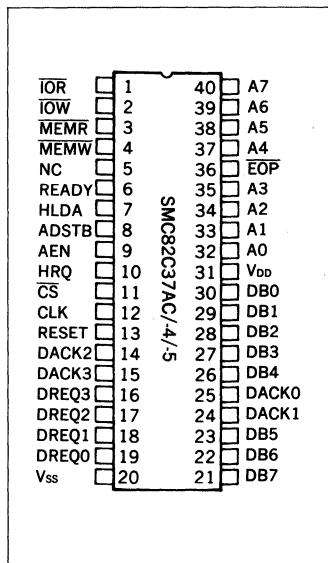
### FEATURES

- Four DMA channels
- High data transfer rates ; up to 1.6M bytes/second
- Enable/disable control of DMA request
- Programmable features
  - ..... Logic polarity of DREQ and DACK
  - Fixed or rotating priority
  - Address increment or decrement
- Automatic features
  - ..... Channel initialization
- External DMA termination
- Single power supply
  - ..... 5V ± 10%
- Package
  - ..... 40-pin DIP (plastic)
- Clock frequency
  - SMC82C37AC : 3.1MHz
  - SMC82C37AC-4 : 4MHz
  - SMC82C37AC-5\* : 5MHz
  - \* Under development

### BLOCK DIAGRAM



### PIN CONFIGURATION



## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.3 to 7	V
Input voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Operating free-air temperature range	T <sub>opr</sub>	0 to 70	°C
Storage temperature range	T <sub>stg</sub>	-65 to 150	°C

## ■ RECOMMENDED OPERATING CONDITIONS

(T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>	—	4.5	5	5.5	V
Supply voltage	V <sub>SS</sub>	—	—	0	—	V

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Low level input voltage	V <sub>IL</sub>	—	-0.3	—	0.8	V
High level input voltage	V <sub>IH</sub>	—	2.0	—	V <sub>CC</sub> +0.3	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2.0mA (data bus) I <sub>OL</sub> = 3.2mA (other outputs)	—	—	0.45	V
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -200μA	2.4	—	—	V
		I <sub>OH</sub> = -100μA (HRQ only)	3.2	—	—	V
Input current	I <sub>I</sub>	V <sub>I</sub> = 0 to V <sub>DD</sub>	-10	—	10	μA
Off state output current	I <sub>OZ</sub>	V <sub>I</sub> = 0 to V <sub>DD</sub>	-10	—	10	μA
Supply current from V <sub>DD</sub>	I <sub>DD</sub>	V <sub>IH</sub> = V <sub>DD</sub> , V <sub>IL</sub> = V <sub>SS</sub> , f <sub>CLK</sub> = 1/t <sub>cy</sub> Min	—	—	15	mA

### ● AC Electrical Characteristics

#### ○ Slave mode

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	SMC82C37AC		SMC82C37AC-4		SMC82C37AC-5		Unit
			Min	Max	Min	Max	Min	Max	
Address or $\overline{CS}$ setup time before read	t <sub>AR</sub>	—	0	—	0	—	0	—	ns
$\overline{CS}$ setup time before write rising edge	t <sub>CW</sub>	—	200	—	150	—	150	—	ns
Address setup time before write rising edge	t <sub>AW</sub>	—	200	—	150	—	150	—	ns
Data setup time before write rising edge	t <sub>DW</sub>	—	200	—	150	—	100	—	ns
Address or $\overline{CS}$ hold time after read	t <sub>RA</sub>	—	0	—	0	—	0	—	ns
$\overline{CS}$ hold time after write	t <sub>WC</sub>	—	0	—	0	—	0	—	ns
Address hold time after write	t <sub>WA</sub>	—	0	—	0	—	0	—	ns
Data hold time after write	t <sub>WD</sub>	—	0	—	0	—	0	—	ns
Read pulse width	t <sub>RW</sub>	—	300	—	250	—	200	—	ns
Write pulse width	t <sub>WWS</sub>	—	200	—	200	—	160	—	ns
Reset pulse width	t <sub>RSTW</sub>	—	300	—	300	—	300	—	ns
Supply voltage setup time before reset	t <sub>RSTD</sub>	—	500	—	500	—	500	—	ns
Reset setup time before read or write	t <sub>RSTS</sub>	—	2t <sub>cy</sub>	—	2t <sub>cy</sub>	—	2t <sub>cy</sub>	—	ns
Data output enable after read	t <sub>RDE</sub>	—	—	200	—	200	—	140	ns
Data output disable after read	t <sub>RDF</sub>	—	0	100	0	100	0	70	ns

○DMA mode

(V<sub>DD</sub>=5V±10%, V<sub>SS</sub>=0V, T<sub>a</sub>=0 to 70°C)

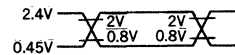
Parameter	Symbol	Conditions	SMC82C37AC		SMC82C37AC-4		SMC82C37AC-5		Unit
			Min	Max	Min	Max	Min	Max	
Propagation time from clock to AEN	t <sub>AEL</sub>	—	—	300	—	225	—	200	ns
Propagation time from clock to AEN	t <sub>AET</sub>	—	—	200	—	150	—	130	ns
Propagation time from clock to address active	t <sub>FAAB</sub>	—	—	250	—	190	—	170	ns
Propagation time from clock to address stable	t <sub>ASM</sub>	—	—	250	—	190	—	170	ns
Propagation time from clock to address floating	t <sub>AFAB</sub>	—	—	150	—	120	—	90	ns
Propagation time from clock to data active	t <sub>FADB</sub>	—	—	300	—	225	—	200	ns
Propagation time from clock to data floating	t <sub>AFDB</sub>	—	—	250	—	190	—	170	ns
Propagation time from clock to ADSTB	t <sub>STL</sub>	—	—	200	—	150	—	130	ns
Propagation time from clock to ADSTB	t <sub>STT</sub>	—	—	140	—	110	—	90	ns
Data setup time before ADSTB	t <sub>ASS</sub>	—	100	—	100	—	100	—	ns
Data hold time after ADSTB	t <sub>AHS</sub>	—	50	—	40	—	30	—	ns
Propagation time from clock to read or write active	t <sub>FAC</sub>	—	—	200	—	150	—	150	ns
Propagation time from clock to read or write	t <sub>DCL</sub>	—	—	270	—	200	—	190	ns
Propagation time from clock to read	t <sub>DCTR</sub>	—	—	270	—	210	—	190	ns
Propagation time from clock to write	t <sub>DCTW</sub>	—	—	200	—	150	—	130	ns
Propagation time from clock to read or write floating	t <sub>AFC</sub>	—	—	150	—	120	—	120	ns
Address hold time after read	t <sub>AHR</sub>	—	t <sub>cy</sub> -100	—	t <sub>cy</sub> -100	—	t <sub>cy</sub> -100	—	ns
Address hold time after write	t <sub>AHW</sub>	—	t <sub>cy</sub> -50	—	t <sub>cy</sub> -50	—	t <sub>cy</sub> -50	—	ns
Data setup time before MEMW	t <sub>ODV</sub>	—	200	—	125	—	125	—	ns
Data hold time after MEMW	t <sub>ODH</sub>	—	20	—	20	—	10	—	ns
Propagation time from clock to DACK	t <sub>AK</sub>	—	—	250	—	220	—	170	ns
Propagation time from clock to EOP output		—	—	250	—	190	—	170	ns
Propagation time from clock to HRQ	"H" 2.0V	—	—	160	—	120	—	120	ns
	"H" 3.3V	—	—	250	—	190	—	120	
Clock high width	t <sub>CH</sub>	—	120	—	100	—	80	—	ns
Clock low width	t <sub>CL</sub>	—	150	—	110	—	68	—	ns
Clock period	t <sub>cy</sub>	—	320	—	250	—	200	—	ns
External EOP setup time before clock	t <sub>EPS</sub>	—	60	—	45	—	40	—	ns
External EOP pulse width	t <sub>EPW</sub>	—	300	—	225	—	220	—	ns
DREQ setup time before clock	t <sub>OS</sub>	—	0	—	0	—	0	—	ns
Ready setup time before clock	t <sub>RS</sub>	—	100	—	60	—	60	—	ns
Ready hold time after clock	t <sub>RH</sub>	—	20	—	20	—	20	—	ns
HLDA setup time before clock	t <sub>HS</sub>	—	100	—	75	—	75	—	ns
Data setup time before MEMR	t <sub>DS</sub>	—	250	—	190	—	170	—	ns
Data hold time after MEMR	t <sub>IDH</sub>	—	0	—	0	—	0	—	ns

Notes : AC testing waveform

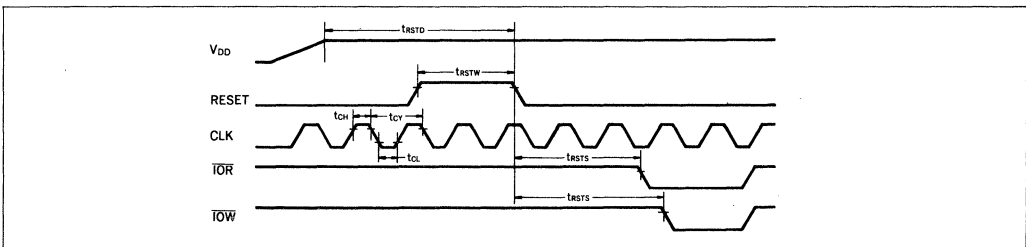
Input pulse level 0.45V to 2.4V  
 Input pulse rise time 10ns  
 Input pulse fall time 10ns

Reference level

input V<sub>IH</sub>=2V, V<sub>IL</sub>=0.8V  
 output V<sub>OH</sub>=2V, V<sub>OL</sub>=0.8V

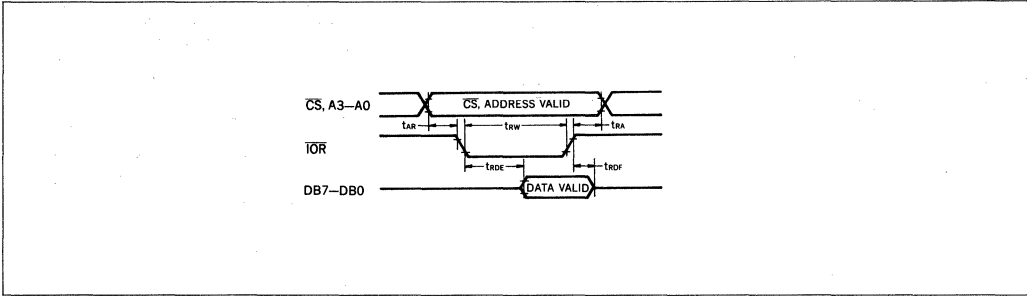


●Timing Chart  
 Reset Timing

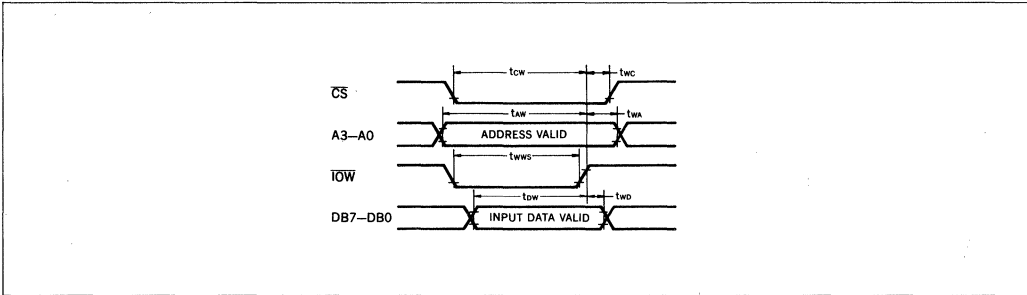




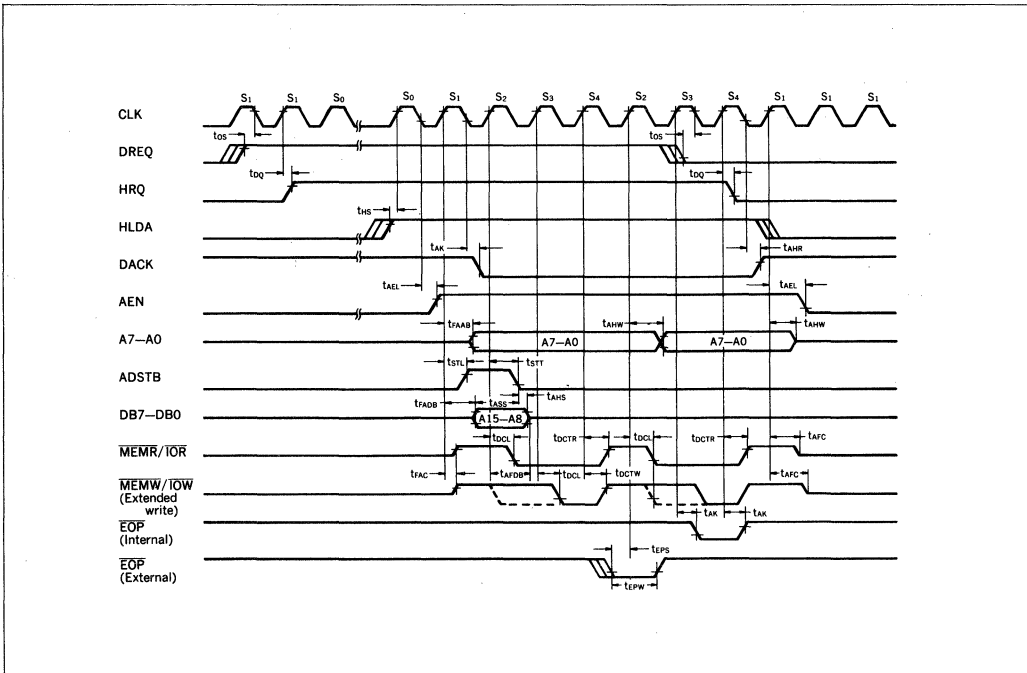
### Slave Mode Timing (READ)



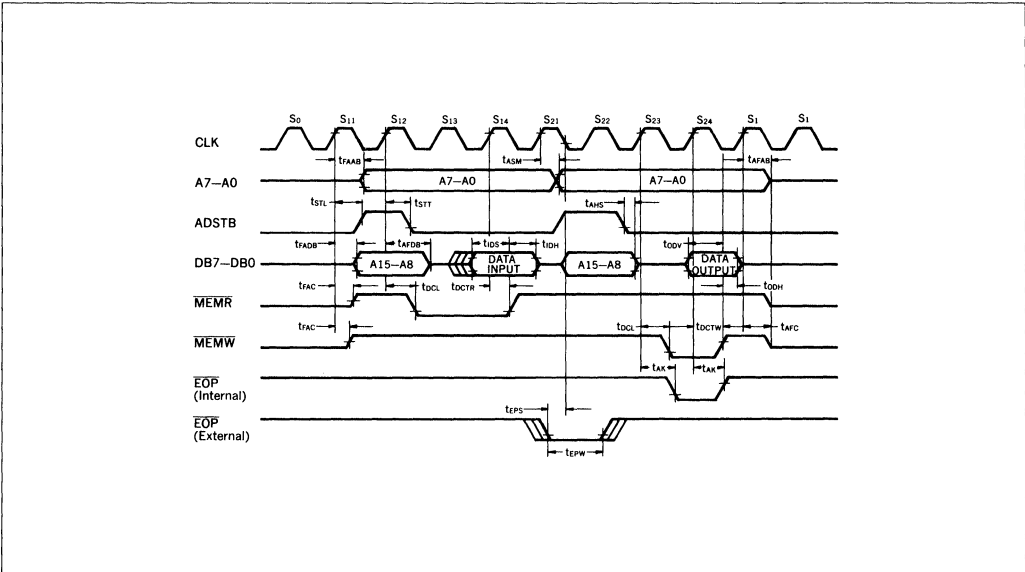
### Slave Mode Timing (WRITE)



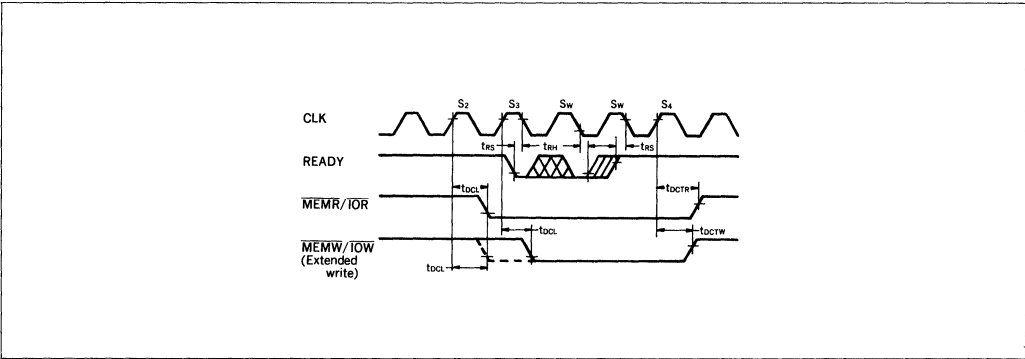
### DMA Transfer



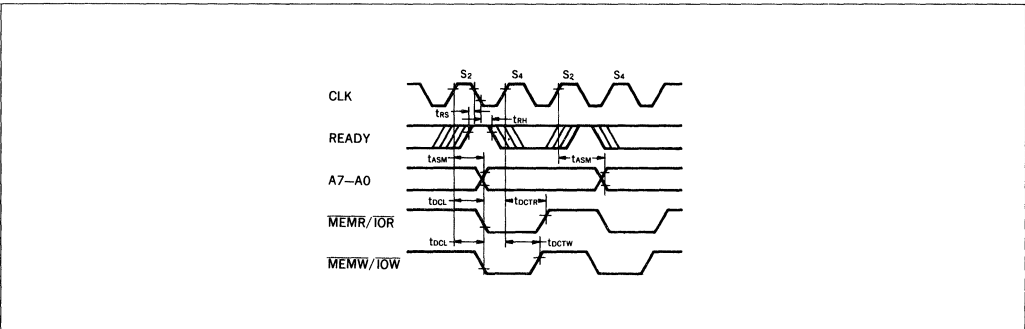
### Memory to Memory Transfer



### Ready Input Timing



### Compressed Transfer Timing



## FUNCTIONS

The SMC82C37AC/-4/-5 is a programmable 4-channel DMA controller. The device offers a variety of programmable control features that can be dynamically reconfigured under program control. There are three programmable transfer modes: single, block and demand. There is also a full 64K address and word count capability per channel.

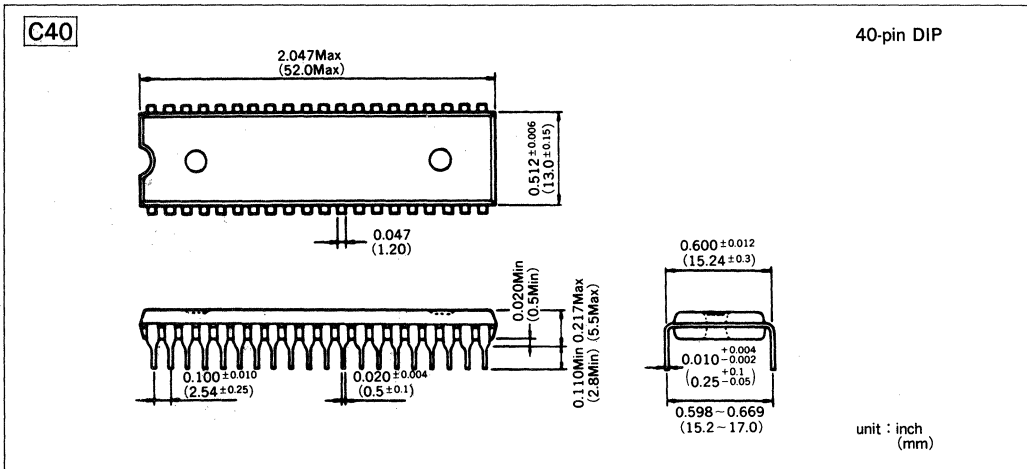
The device consists of three basic control blocks: the timing control block, the program command control block and the priority encoder block. To start a DMA operation, set a start address, an end address, a mode, and commands. The device requests control of the system bus when  $HRQ=1$  is valid. The CPU acknowledges that it has relinquished control of the system bus via the hold acknowledge pin ( $HLDA=1$ ) to the SMC 82C37AC/-4/-5. A  $DACK$  signal is then sent to the highest priority channel and DMA operation begins.

In the process of the DMA operation, addressing is performed in two bytes. The low byte is outputs A7-A0 and the high byte is outputs DB7-DB0; the high byte is sent to an external address latch. After the address is transmitted, the read/write control signals are sent to memory ( $\overline{MEMR}/\overline{MEMW}$ ) or to a peripheral ( $\overline{IOR}/\overline{IOW}$ ).

## APPLICATIONS

DMA control of peripheral equipment such as floppy disks and CRT terminals that require high-speed data transfer.

## PACKAGE DIMENSIONS



# SMC82C51AC

## CMOS PROGRAMMABLE COMMUNICATION INTERFACE

- Synchronous/Asynchronous Receiver/Transmitter
- Baud Rate -- DC to 64Kbps
- Low Power

### DESCRIPTION

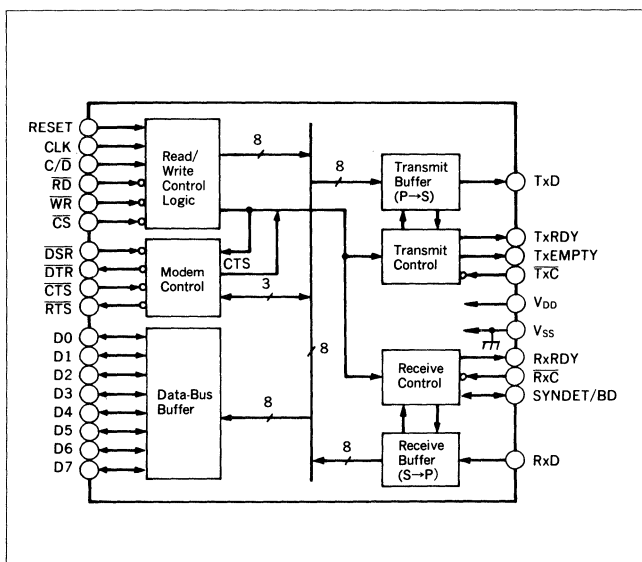
The SMC82C51AC is the enhanced CMOS version of the industry standard Universal Synchronous/Asynchronous Receiver/Transmitter (USART) designed for data communications.

### FEATURES

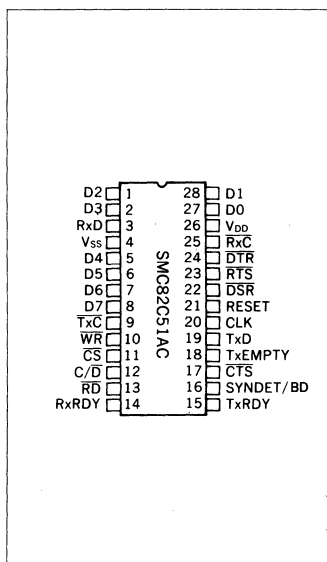
- Synchronous 5 to 8-bit character operation
  - Internal or external character synchronization
  - Automatic SYNC character insertion
  - Synchronous baud rate: DC to 64K baud
- Asynchronous 5 to 8-bit character operation
  - Clock rate of 1, 16, or 64 times baud rate
  - 1, 1.5 or 2 stop bits
  - False start bit detection
  - Automatic break detection and handling
- Baud rate: DC to 64K Baud
- Full-duplex, double-buffered transmitter and receiver
- Error detection: parity, overrun and framing
- Single 5V (±10%) power supply
- Package: .....28-pin DIP  
28-pin SOP\*

\* Under development

### BLOCK DIAGRAM



### PIN CONFIGURATION



### ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V, T<sub>a</sub> = 25°C)

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V <sub>DD</sub>	With respect to V <sub>SS</sub>	-0.3 to 7	V
Input voltage	V <sub>I</sub>		-0.3 to V <sub>DD</sub> + 0.3	V
Output voltage	V <sub>O</sub>		-0.3 to V <sub>DD</sub> + 0.3	V
Operating temperature	T <sub>opr</sub>	—	-20 to 75	°C
Storage temperature	T <sub>stg</sub>	—	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	—	260°C, 10s (at lead)	—

### ■ RECOMMENDED OPERATING CONDITIONS

(T<sub>a</sub> = -20 to 75°C, unless otherwise noted.)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>	—	4.5	5	5.5	V
Power-supply voltage	V <sub>SS</sub>	—	—	0	—	V

### ■ ELECTRICAL CHARACTERISTICS

#### ● DC Electrical Characteristics

(T<sub>a</sub> = -20 to 75°C, V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, unless otherwise noted.)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
High-level input voltage	V <sub>IH</sub>	—	2	—	V <sub>DD</sub> + 0.3	V
Low-level input voltage	V <sub>IL</sub>	—	-0.3	—	0.8	V
High-level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -400μA	2.4	—	—	V
Low-level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2.2mA	—	—	0.45	V
Supply current from V <sub>DD</sub>	I <sub>DD</sub>	—	—	—	5	mA
High-level input current	I <sub>IH</sub>	V <sub>I</sub> = V <sub>DD</sub>	-10	—	10	μA
Low-level input current	I <sub>IL</sub>	V <sub>I</sub> = 0V	-10	—	10	μA
Off-state input current	I <sub>OZ</sub>	V <sub>SS</sub> = 0V, V <sub>I</sub> = 0V to V <sub>DD</sub>	-10	—	10	μA
Input capacitance	C <sub>I</sub>	V <sub>DD</sub> = V <sub>SS</sub> , f = 1MHz, 25mV <sub>rms</sub> , T <sub>a</sub> = 25°C	—	—	10	pF
Input/output capacitance	C <sub>I/O</sub>	V <sub>DD</sub> = V <sub>SS</sub> , f = 1MHz, 25mV <sub>rms</sub> , T <sub>a</sub> = 25°C	—	—	20	pF

#### ● AC Electrical Characteristics

##### ○ Timing Requirements

(T<sub>a</sub> = -20 to 75°C, V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, unless otherwise noted.)

Parameter	Symbol	Alternative Symbol	Conditions	Min	Typ	Max	Unit
Clock cycle time * 1, 2	t <sub>C(φ)</sub>	t <sub>CY</sub>		320	—	1350	ns
Clock high pulse width	t <sub>W(φ)</sub>	t <sub>φ</sub>		120	—	t <sub>C(φ)</sub> - 90	ns
Clock low pulse width	t <sub>W(φ̄)</sub>	t <sub>φ̄</sub>		90	—	—	ns
Clock rise time	t <sub>r</sub>	t <sub>R</sub>		—	—	20	ns
Clock fall time	t <sub>f</sub>	t <sub>F</sub>		—	—	20	ns
Transmitter input clock frequency	1X baud rate	f <sub>TX</sub>	f <sub>TX</sub>	DC	—	64	kHz
	16X baud rate		f <sub>TX</sub>	DC	—	310	kHz
	64X baud rate		f <sub>TX</sub>	DC	—	615	kHz
Transmitter input clock low pulse width	1X baud rate	t <sub>W(TPWL)</sub>	t <sub>TPW</sub>	12	—	—	t <sub>C(φ)</sub>
	16X, 64X baud rate		t <sub>TPW</sub>	1	—	—	t <sub>C(φ)</sub>
Transmitter input clock high pulse width	1X baud rate	t <sub>W(TPWH)</sub>	t <sub>TPD</sub>	15	—	—	t <sub>C(φ)</sub>
	16X, 64X baud rate		t <sub>TPD</sub>	3	—	—	t <sub>C(φ)</sub>
Receiver input clock frequency	1X baud rate	f <sub>RX</sub>	f <sub>RX</sub>	DC	—	64	kHz
	16X baud rate		f <sub>RX</sub>	DC	—	310	kHz
	64X baud rate		f <sub>RX</sub>	DC	—	615	kHz
Receiver input clock low pulse width	1X baud rate	t <sub>W(RPWL)</sub>	t <sub>RPW</sub>	12	—	—	t <sub>C(φ)</sub>
	16X, 64X baud rate		t <sub>RPW</sub>	1	—	—	t <sub>C(φ)</sub>
Receiver input clock high pulse width	1X baud rate	t <sub>W(RPWH)</sub>	t <sub>RPO</sub>	15	—	—	t <sub>C(φ)</sub>
	16X, 64X baud rate		t <sub>RPO</sub>	3	—	—	t <sub>C(φ)</sub>
Address setup time before read (CS, C/D) * 3		t <sub>SU(A-R)</sub>	t <sub>AR</sub>	0	—	—	ns
Address hold time after read (CS, C/D) * 3		t <sub>H(R-A)</sub>	t <sub>RA</sub>	0	—	—	ns

Parameter	Symbol	Alternative Symbol	Conditions	Min	Typ	Max	Unit
Read pulse width	$t_{W(R)}$	$t_{RR}$		200	—	—	ns
Address setup time before write	$t_{SU(A-W)}$	$t_{AW}$		0	—	—	ns
Address hold time after write	$t_{h(W-A)}$	$t_{WA}$		0	—	—	ns
Write pulse width	$t_{W(W)}$	$t_{WW}$		200	—	—	ns
Data setup time before write	$t_{SU(DQ-W)}$	$t_{DW}$		100	—	—	ns
Data hold time after write	$t_{h(W-DQ)}$	$t_{WO}$		0	—	—	ns
E-SYNDET setup time before $\overline{RxC}$	$t_{SU(ESD-RxC)}$	$t_{ES}$		18	—	—	$t_{C(\phi)}$
Control setup time before read	$t_{SU(C-R)}$	$t_{CR}$		20	—	—	$t_{C(\phi)}$
Write recovery time between writes *4	$t_{RV}$	$t_{RV}$		6	—	—	$t_{C(\phi)}$
RxD setup time before internal sampling pulse	$t_{SU(RxD-IS)}$	$t_{SRx}$		2	—	—	$\mu s$
RxD hold time after internal sampling pulse	$t_{h(IS-RxD)}$	$t_{HRx}$		2	—	—	$\mu s$

\*1 The  $\overline{TxC}$  and  $\overline{RxC}$  frequencies have the following limitations with respect to CLK.

For 1X baud rate  $f_{TX}$ ,  $f_{RX} \leq 1/(30t_{C(\phi)})$ . For 16X, 64X baud rate  $f_{TX}$ ,  $f_{RX} \leq 1/(4.5t_{C(\phi)})$

\*2 Reset pulse width =  $6t_{C(\phi)}$  minimum. System clock must be running during reset.

\*3  $\overline{CS}, C/D$  are considered as address.

\*4 This recovery time is for mode initialization only. Write data is allowed only when  $TxRDY=1$ . Recovery time between writes for asynchronous mode is  $8t_{C(\phi)}$ , and that for synchronous mode is  $16t_{C(\phi)}$ .

### Switching Characteristics

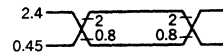
( $T_a = -20$  to  $75^\circ C$ ,  $V_{DD} = 5V \pm 10\%$ ,  $V_{SS} = 0V$ , unless otherwise noted.)

Parameter	Symbol	Alternative symbol	Conditions *7	Min	Typ	Max	Unit
Output data enable time after read *5	$t_{PZV(R-DQ)}$	$t_{RD}$	$C_L = 150pF$	—	—	170	ns
Output data disable time after read	$t_{PVZ(R-DQ)}$	$t_{DF}$		10	—	100	ns
TxD enable time after falling edge of $\overline{TxC}$	$t_{PZV(TxC-TxD)}$	$t_{CTx}$		—	—	1	$\mu s$
Propagation time from center of last bit to $TxRDY$ clear *6	$t_{PLH(CLB-TxR)}$	$t_{TxRDY}$		—	—	8	$t_{C(\phi)}$
Propagation time from write data to $TxRDY$ *6	$t_{PHL(W-TxR)}$	$t_{TxRDY CLEAR}$		—	—	400	ns
Propagation time from center of last bit to $RxRDY$ *6	$t_{PLH(CLB-RxR)}$	$t_{RxRDY}$		—	—	26	$t_{C(\phi)}$
Propagation time from read data to $RxRDY$ clear *6	$t_{PHL(R-RxR)}$	$t_{RxRDY CLEAR}$		—	—	400	ns
Propagation time from rising edge of $\overline{RxC}$ to internal SYNDET *6	$t_{PLH(RxC-SYD)}$	$t_{IS}$		—	—	26	$t_{C(\phi)}$
Propagation time from center of last bit to $TxEMPTY$ *6	$t_{PLH(CLB-TxE)}$	$t_{TxEMPTY}$		20	—	—	$t_{C(\phi)}$
Propagation time from rising edge of $\overline{WR}$ to control *6	$t_{PHL(W-C)}$	$t_{WC}$		8	—	—	$t_{C(\phi)}$

\*5 Assumes that address is valid before falling edge of  $\overline{RD}$ .

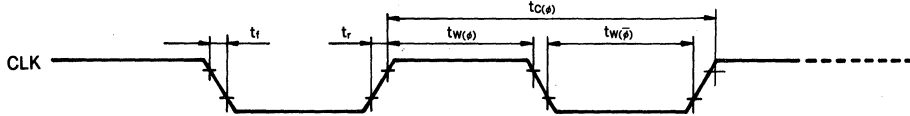
\*6 Status-up data can have a maximum delay of 28 clock periods from the event affecting the status.

\*7 Input pulse level 0.45 to 2.4V Reference level Input  $V_{IH} = 2V$ ,  $V_{IL} = 0.8V$   
 Input pulse rise time 20ns Output  $V_{OH} = 2V$ ,  $V_{OL} = 0.8V$   
 Input pulse fall time 20ns

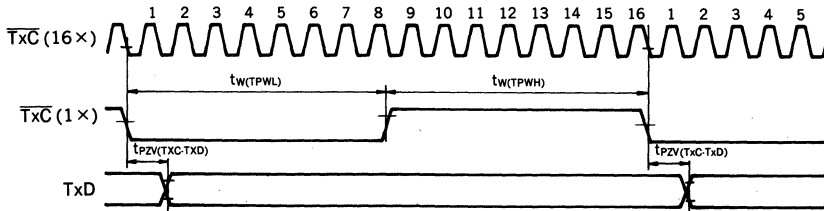


● Timing Chart

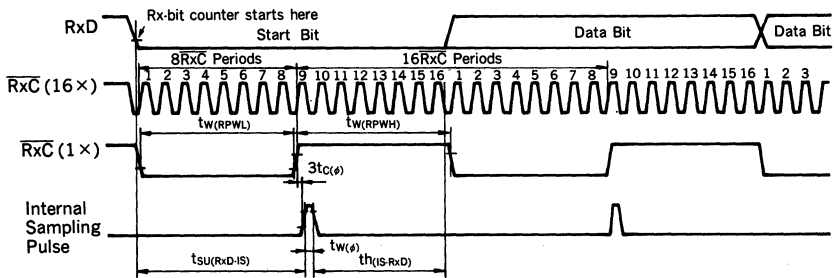
○ System clock (CLK)



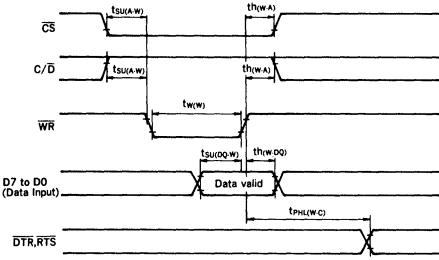
○ Transmitter clock & data



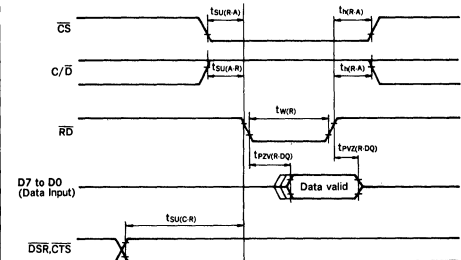
○ Receiver clock & data



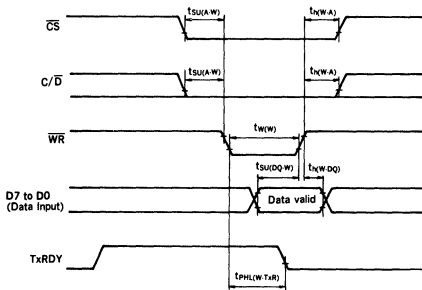
○ Write control cycle (CPU → USART)



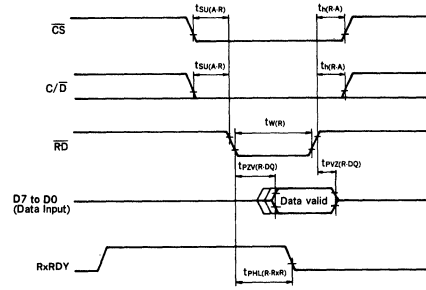
○ Read control cycle (USART → CPU)



○ Write data cycle (CPU → USART)

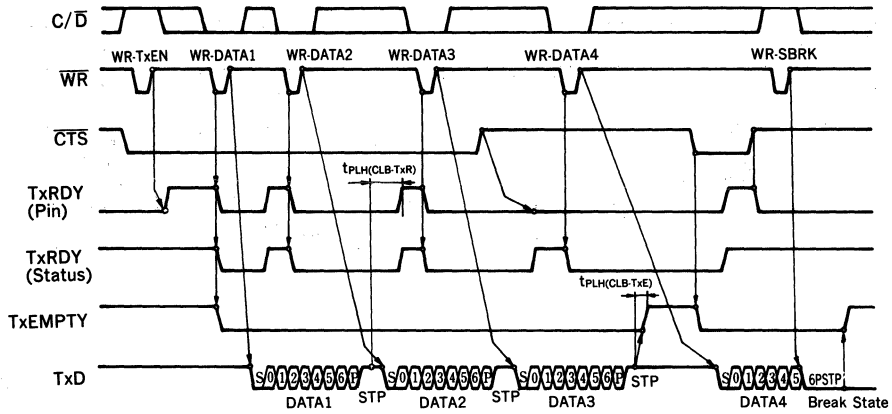


○ Read data cycle (USART → CPU)



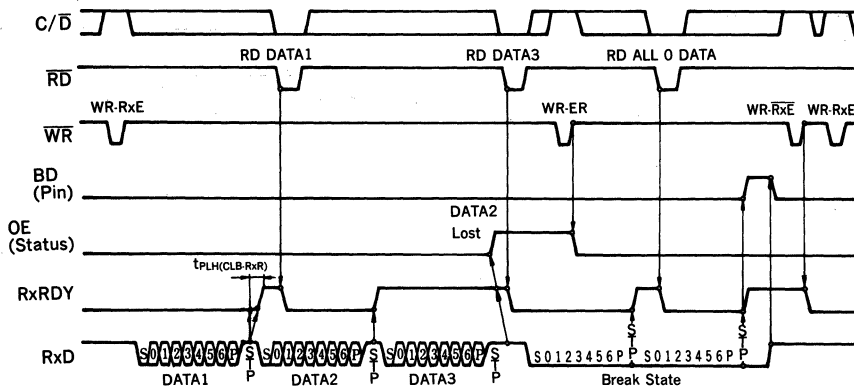


○ Transmitter control & flag timing (async mode)



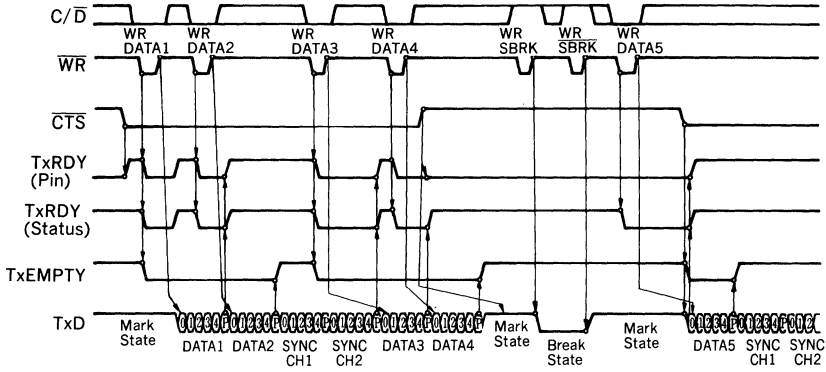
- \* 8 Example format = 7 bits/character with parity & 2 stop bits
- \* 9  $TxRDY(pin) = 1 \leftarrow (Transmit-data\ buffer\ is\ empty) \cdot (TxEN = 1) \cdot (CTS = L) = 1$
- \* 10  $TxRDY(status) = 1 \leftarrow (Transmit-data\ buffer\ is\ empty) = 1$

○ Receiver control & flag timing (async mode)



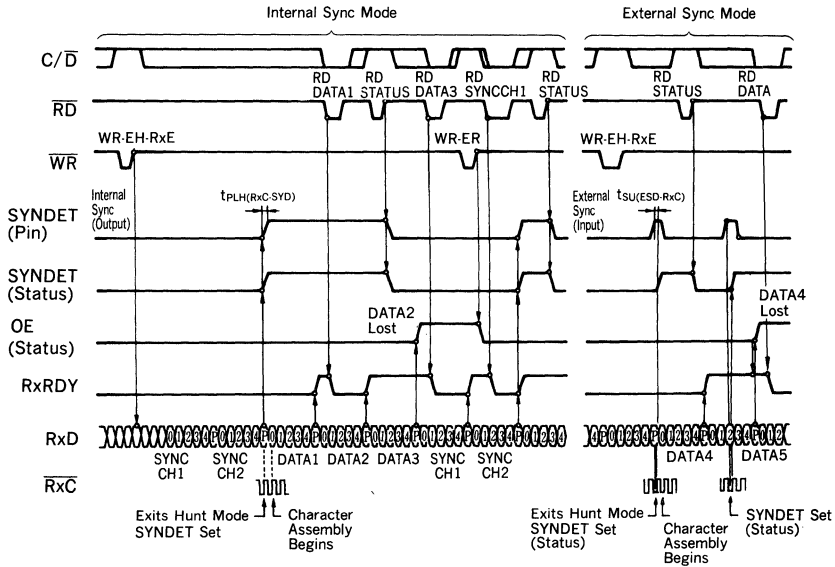
- \* 11 Example format = 7 bits/character with parity

○ Transmitter control & flag timing (sync mode)



\* Example format = 5 bits/character with parity, bi-sync characters.

○ Receiver control & flag timing (sync mode)



\* Example format = 5 bits/character with parity, bi-sync characters.

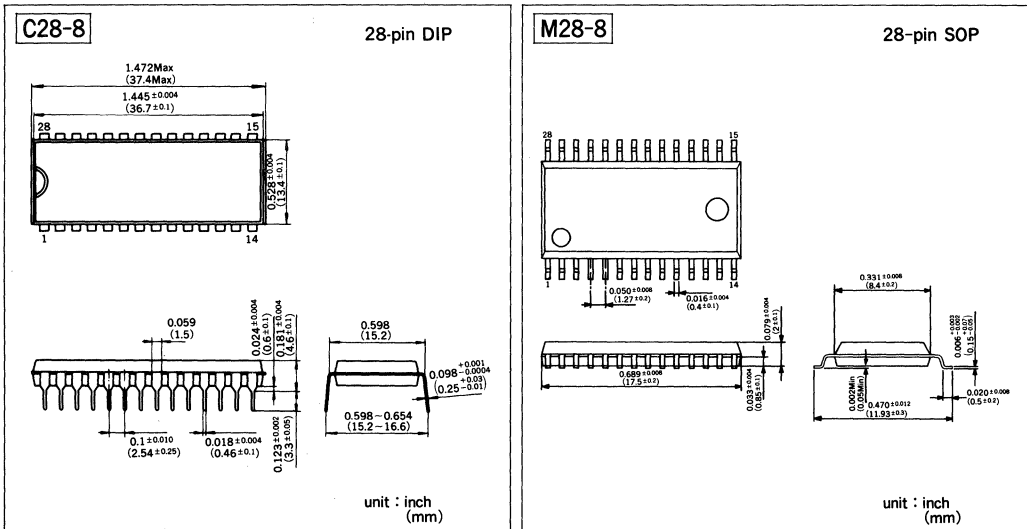
## FUNCTIONS

The SMC 82C51AC is used as a peripheral device and programmed to interface a CPU with virtually all serial data transmission techniques presently in use. Including IBM's "bi-sync". The SMC82C51AC can accept data characteristics from the CPU in parallel format, convert the data into a serial stream and transmit the data via the TxD pin. It can also receive data in a serial stream via the RxD pin, convert the data into a parallel format and transmit the data to the CPU. The SMC82C51AC, upon receipt of parallel or serial data, will flag the CPU using the TxRDY or RxRDY signals. The CPU can also poll the SMC82C51AC status with  $C/\bar{D}=1$ . The status which may be read contains Information such as data transmission error, parity error, overrun error or frame error.

## APPLICATIONS

In 8-bit microcomputer applications, modem control of data communications.  
Control of CRT, TTY and other terminal equipment.

## PACKAGE DIMENSIONS



# SMC82C54C/-6

## CMOS PROGRAMMABLE INTERVAL TIMER

- **3 Independent 18-bit Counters**
- **6 Programmable Counter Modes**
- **Low Power**

### DESCRIPTION

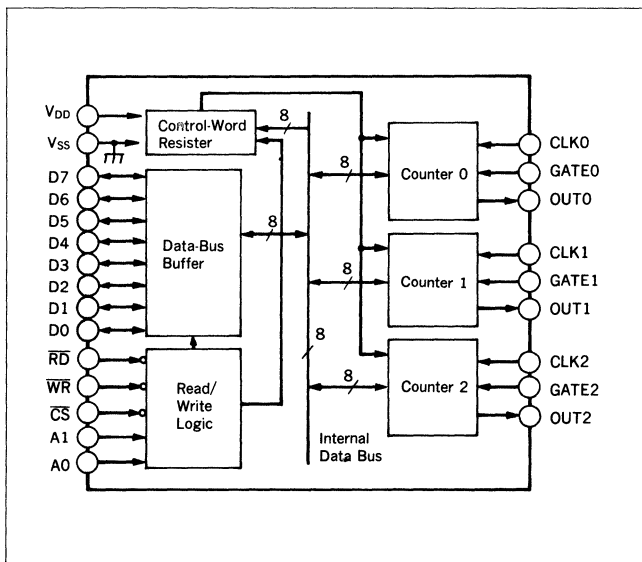
The SMC82C54C\*1/-6 is a CMOS Programmable Timer/Counter. It is designed to provide a flexible solution to Timer/Counter requirements in microcomputer systems. The device provides three independent 18-bit counters. Each counter is capable of handling clock inputs up to 8 MHz. This Timer/Counter has six programmable modes.

### FEATURES

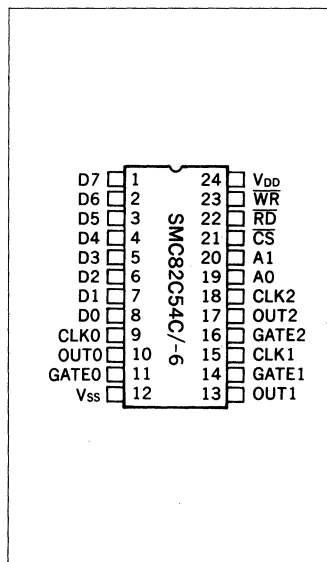
- Compatible with most 8-bit microprocessors
- Three independent 16-bit counters
- Clock input .....SMC82C54C\*1   DC to 8MHz  
  SMC82C54C-6   DC to 6MHz
- Binary or decimal counter
- Six programmable counter modes
- Status poll feature
- Single 5V (±10%) power supply
- Package.....24-pin DIP  
  24-pin SOP\*2

\*1 SMC82C54C: Under development  
\*2 Under development

### BLOCK DIAGRAM



### PIN CONFIGURATION



## ■ ABSOLUTE MAXIMUM RATINGS

( $V_{SS}=0V$ ,  $T_a=25^{\circ}C$ )

Parameter	Symbol	Ratings	Unit
Power supply voltage	$V_{DD}$	-0.3 to 7	V
Input voltage	$V_I$	-0.3 to $V_{DD}+0.3$	V
Output voltage	$V_O$	-0.3 to $V_{DD}+0.3$	V
Operating temperature	$T_{opr}$	-20 to 75	$^{\circ}C$
Storage temperature	$T_{stg}$	-65 to 150	$^{\circ}C$
Soldering temperature and time	$T_{sol}$	260 $^{\circ}C$ , 10s (at lead)	—

## ■ RECOMMENDED OPERATING CONDITIONS

( $T_a = -20$  to  $75^{\circ}C$ , unless otherwise noted)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Power supply voltage	$V_{DD}$	—	4.50	5	5.50	V
Supply voltage (GND)	$V_{SS}$	—	—	0	—	V

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

( $T_a = -20$  to  $75^{\circ}C$ ,  $V_{DD}=5V \pm 10\%$ , unless otherwise noted)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
High-level input voltage	$V_{IH}$	—	2.0	—	$V_{DD}+0.3$	V
Low-level input voltage	$V_{IL}$	—	-0.3	—	0.8	V
High-level output voltage	$V_{OH}$	$V_{SS}=0V$ , $I_{OH} = -400\mu A$	2.4	—	—	V
Low-level output voltage	$V_{OL}$	$V_{SS}=0V$ , $I_{OL}=2.0mA$	—	—	0.45	V
High-level input current	$I_{IH}$	$V_{SS}=0V$ , $V_I=5.50V$	—	—	$\pm 10$	$\mu A$
Low-level input current	$I_{IL}$	$V_{SS}=0V$ , $V_I=0V$	—	—	$\pm 10$	$\mu A$
Off-state output current	$I_{OZ}$	$V_{SS}=0V$ , $V_I=0$ to $V_{DD}$	—	—	$\pm 10$	$\mu A$
Power supply Current	$I_{DD}$	SMC82C54C $V_{SS}=0V$ , $f=8MHz$	—	—	10	mA
		SMC82C54C-6 $V_{SS}=0V$ , $f=6MHz$	—	—	10	mA
Power supply current during STAND BY	$I_{DDS}$	$V_{SS}=0V$ , other inputs are $V_{SS}$ or $V_{DD}$	—	—	10	$\mu A$
Input capacitance	$C_I$	$V_{IL}=V_{SS}$ , $f=1MHz$ , $25mVrms$ , $T_a=25^{\circ}C$	—	—	10	pF
Input/output capacitance	$C_{I/O}$	$V_{I/O}=V_{SS}$ , $f=1MHz$ , $25mVrms$ , $T_a=25^{\circ}C$	—	—	20	pF

### ● AC Electrical Characteristics

#### ○ Timing Requirements

( $T_a = -20$  to  $75^{\circ}C$ ,  $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ , unless otherwise noted)

##### Read cycle

Parameter	Symbol	Alternative symbol	Conditions	Min	Typ	Max	Unit
Read pulse width	$t_{W(R)}$	$t_{RR}$	$C_L = 150pF$	150	—	—	ns
$\overline{CS}$ setup time before read	$t_{SU(S-R)}$	$t_{SR}$		0	—	—	ns
Address setup time before read	$t_{SU(A-R)}$	$t_{AR}$		45	—	—	ns
Address hold time after read	$t_{H(R-A)}$	$t_{RA}$		0	—	—	ns
Read recovery time	$t_{rec(R)}$	$t_{RV}$		200	—	—	ns

##### Write cycle

Parameter	Symbol	Alternative Symbol	Conditions	Min	Typ	Max	Unit
Write pulse width	$t_{W(W)}$	$t_{WW}$	$C_L = 150pF$	150	—	—	ns
$\overline{CS}$ setup time before write	$t_{SU(S-W)}$	$t_{SW}$		0	—	—	ns
Address setup time before write	$t_{SU(A-W)}$	$t_{AW}$		0	—	—	ns
Address hold time after write	$t_{H(W-A)}$	$t_{WA}$		0	—	—	ns
Data setup time before write	$t_{SU(D-W)}$	$t_{DW}$		100	—	—	ns
Data hold time after write	$t_{H(W-D)}$	$t_{WD}$		0	—	—	ns
Write recovery time	$t_{rec(W)}$	$t_{RV}$		200	—	—	ns

○ Clock and gate timing

Parameter	Symbol	Alternative symbol	Conditions	Min	Typ	Max	Unit
Clock high pulse width	SMC82C54C	$t_{W(\phi H)}$	$C_L = 150\text{pF}$	60	—	—	ns
	SMC82C54C-6			55	—	—	
Clock low pulse width	SMC82C54C	$t_{W(\phi L)}$		60	—	—	ns
	SMC82C54C-6			110	—	—	
Clock cycle time	SMC82C54C	$t_{C(\phi)}$		125	—	—	ns
	SMC82C54C-6			165	—	—	
Clock rise time	$t_{r(\phi)}$	$t_R$		—	—	100	ns
Clock fall time	$t_{f(\phi)}$	$t_F$		—	—	100	ns
Gate high pulse width	$t_{W(GH)}$	$t_{GW}$		50	—	—	ns
Gate low pulse width	$t_{W(GL)}$	$t_{GL}$		50	—	—	ns
Gate setup time before clock	$t_{SU(G-\phi)}$	$t_{GS}$		50	—	—	ns
Gate hold time after clock	$t_{H(\phi-G)}$	$t_{GH}$		50	—	—	ns

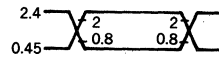
○ Switching Characteristics

( $T_a = -20$  to  $75^\circ\text{C}$ ,  $V_{DD} = 5\text{V} \pm 10\%$ ,  $V_{SS} = 0\text{V}$ , unless otherwise noted)\*

Parameter	Symbol	Alternative symbol	Conditions	Min	Typ	Max	Unit
Propagation time from address to output	$t_{PZV(A-Q)}$	$t_{AD}$	$C_L = 150\text{pF}$	—	—	220	ns
Propagation time from read to output	SMC82C54C	$t_{PZV(R-Q)}$		—	—	120	ns
	SMC82C54C-6			—	—	170	
Propagation time from read to output floating	$t_{PVZ(R-Q)}$	$t_{DF}$		5	—	90	ns
Propagation time from gate to output	$t_{PXV(G-Q)}$	$t_{ODG}$		—	—	120	ns
Propagation time from clock to output	$t_{PXV(\phi-Q)}$	$t_{OD}$		—	—	150	ns

\* A.C Testing waveform

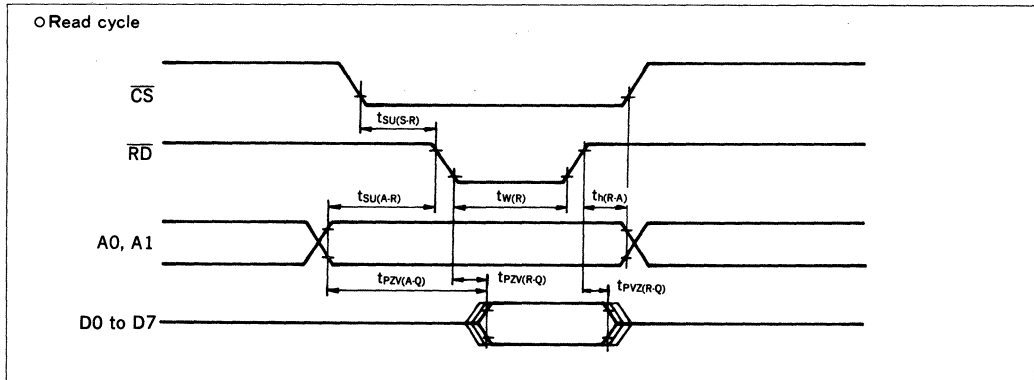
Input pulse level 0.45 to 2.4V  
 Input pulse rise time 10ns  
 Input pulse fall time 10ns  
 Reference level input  $V_{IH} = 2\text{V}$ ,  $V_{IL} = 0.8\text{V}$   
 Output  $V_{OH} = 2\text{V}$ ,  $V_{OL} = 0.8\text{V}$

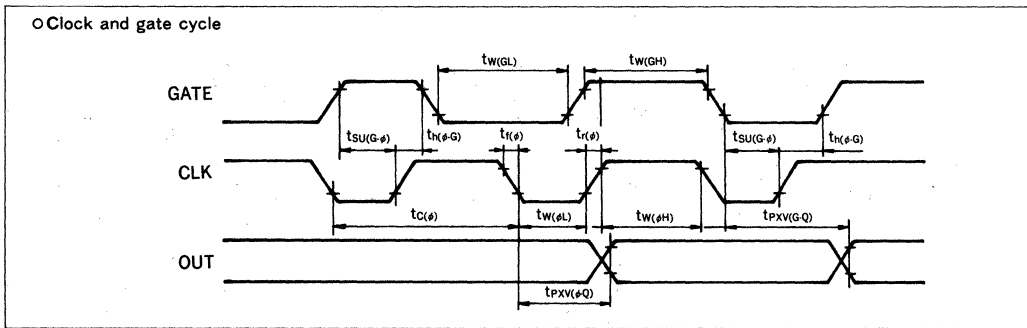
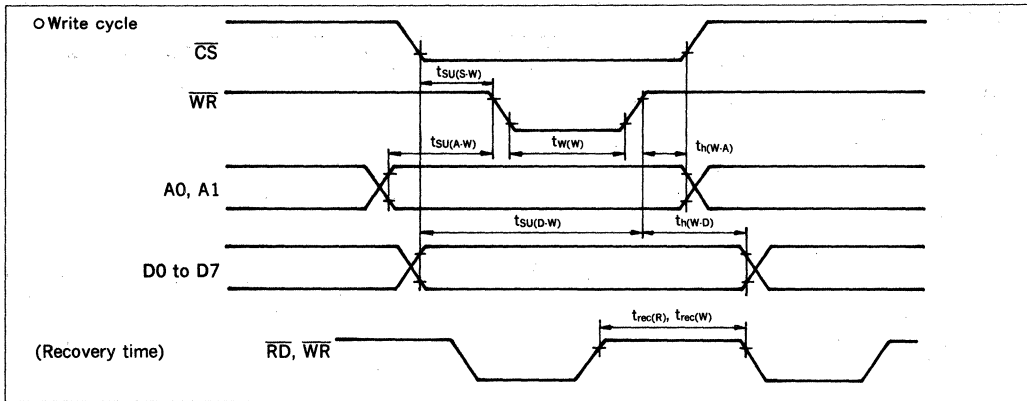


■ FUNCTIONS

There are three independent programmable 16-bit counters. Each counter can operate in any of the six programmable counter modes. Mode 0 (Interrupt on Terminal Count) is typically used for event counting. Mode 1 is a retriggerable one shot. Modes 2 and 3 are typically used as rate generators. Modes 4 and 5 are used as triggered strobes. With software and hardware triggered, respectively. Each counter's status can be monitored by polling via the read back command.

■ TIMING CHART (Reference voltage : High = 2.0V Low = 0.8V)

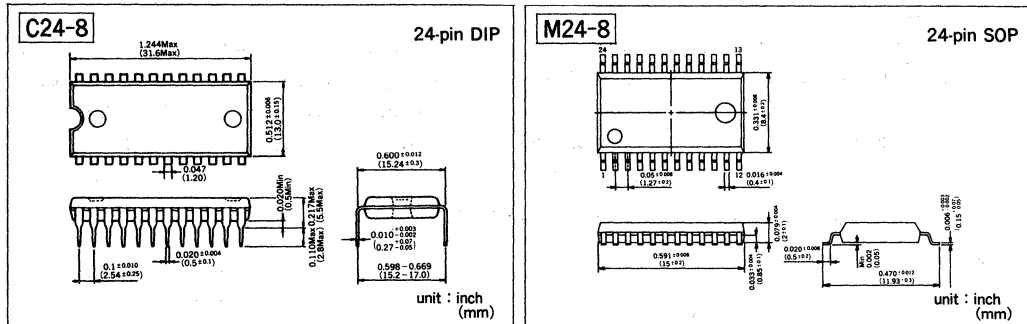




■ APPLICATION

Delayed time setting, pulse counting and rate generation in microcomputers.

■ PACKAGE DIMENSIONS



# SMC82C55AC-5

## CMOS PROGRAMMABLE PERIPHERAL INTERFACE

- 24 Bit Input/Output
- Improved DC Driving Capability
- Low Power

### DESCRIPTION

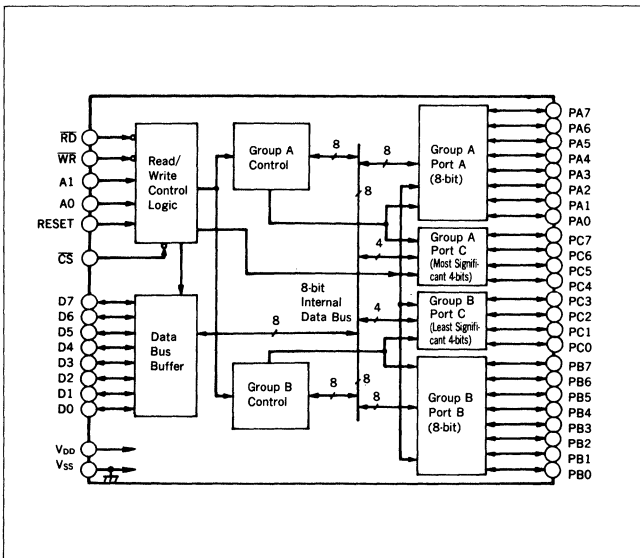
The SMC82C55AC-5 is a CMOS General Purpose Programmable I/O device designed for use with an 8/16 bit CPU. The device has 24 programmable I/O pins that can be individually programmed in two groups of 12.

### FEATURES

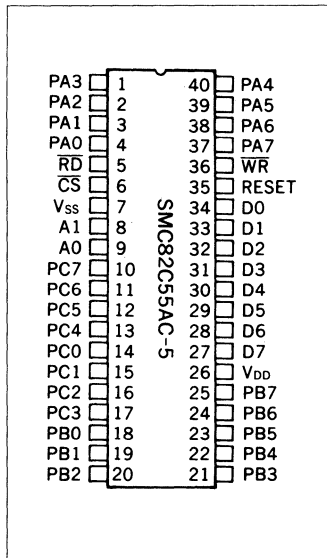
- 24 programmable I/O pins
- Compatible with 80XX series of microprocessors
- Direct bit set/reset capability
- Improved DC driving capability
- Single 5V ( $\pm 10\%$ ) power supply
- TTL compatible
- Package.....40-pin DIP  
40-pin SOP\*

\*Under development

### BLOCK DIAGRAM



### PIN CONFIGURATION





### ■ ABSOLUTE MAXIMUM RATINGS

( $V_{SS} = 0V$ ,  $T_a = 25^\circ C$ )

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	$V_{DD}$	With respect to $V_{SS}$	-0.3 to 7	V
Input voltage	$V_I$		-0.3 to $V_{DD} + 0.3$	V
Output voltage	$V_O$		-0.3 to $V_{DD} + 0.3$	V
Operating temperature	$T_{opr}$	—	-20 to 75	$^\circ C$
Storage temperature	$T_{stg}$	—	-65 to 150	$^\circ C$
Soldering temperature and time	$T_{sol}$	—	260 $^\circ C$ , 10s (lead)	—

### ■ RECOMMENDED OPERATING CONDITIONS

( $T_a = -20$  to  $75^\circ C$ , unless otherwise noted)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	$V_{DD}$	—	4.5	5	5.5	V
Supply voltage	$V_{SS}$	—	—	0	—	V

### ■ ELECTRICAL CHARACTERISTICS

#### ● DC Electrical Characteristics

( $T_a = -20$  to  $75^\circ C$ ,  $V_{DD} = 5V \pm 10\%$ ,  $V_{SS} = 0V$ , unless otherwise noted)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
High-level input voltage	$V_{IH}$	—	2.0	—	$V_{DD} + 0.3$	V
Low-level input voltage	$V_{IL}$	—	-0.3	—	0.8	V
Output high voltage*2	$V_{OH}$	$I_{OH} = -400\mu A$	2.4	—	—	V
Output low voltage	$V_{OL}$	$I_{OL} = 2.5mA$	—	—	0.45	V
Supply current from $V_{DD}$	$I_{DD}$	$V_{SS} = 0V$ . All input mode. RESET = 0V. Other pins = $V_{DD}$	—	—	10	$\mu A$
Input leak current	$I_{LI}$	$V_{SS} = 0V$ , $V_I = 0V$ , $V_{DD}$	—	—	$\pm 10$	$\mu A$
Off-state output current	$I_{OZ}$	$V_{SS} = 0V$ , $V_I = 0V$ , $V_{DD}$	—	—	$\pm 10$	$\mu A$
Input capacitance	$C_I$	$V_{IL} = V_{SS}$ , $f = 1MHz$ , 25mVrms, $T_a = 25^\circ C$	—	—	10	pF
Input/output terminal capacitance	$C_{I/O}$	$V_{I/OL} = V_{SS}$ , $f = 1MHz$ , 25mVrms, $T_a = 25^\circ C$	—	—	20	pF

\*1 Current flowing into an IC is positive, out is negative.

\*2 The sum total  $I_{OH}$  current must be less than -64mA on port B, C, and -32mA on Port A.

#### ● AC Electrical Characteristics

##### ○ Timing Requirements

( $T_a = -20$  to  $75^\circ C$ ,  $V_{DD} = 5V \pm 10\%$ ,  $V_{SS} = 0V$ , unless otherwise noted)

Parameter	Symbol	Alternative symbol	Conditions	Min	Typ	Max	Unit
Read pulse width	$t_{W(R)}$	$t_{RR}$		200	—	—	ns
Peripheral setup time before read	$t_{SU(PE-R)}$	$t_{IR}$		0	—	—	ns
Peripheral hold time after read	$t_{H(R-PE)}$	$t_{HR}$		0	—	—	ns
Address setup time before read	$t_{SU(A-R)}$	$t_{AR}$		0	—	—	ns
Address hold time after read	$t_{H(RA)}$	$t_{RA}$		0	—	—	ns
Write pulse width	$t_{W(W)}$	$t_{WW}$		200	—	—	ns
Data setup time before write	$t_{SU(DQ-W)}$	$t_{DW}$		100	—	—	ns
Data hold time after write	$t_{H(W-DQ)}$	$t_{WD}$		0	—	—	ns
Address setup time before write	$t_{SU(A-W)}$	$t_{AW}$		0	—	—	ns
Address hold time after write	$t_{H(WA)}$	$t_{WA}$		0	—	—	ns
Acknowledge pulse width	$t_{W(ACK)}$	$t_{AK}$		300	—	—	ns
Strobe pulse width	$t_{W(STB)}$	$t_{ST}$		350	—	—	ns
Peripheral setup time before strobe	$t_{SU(PE-STB)}$	$t_{PS}$		0	—	—	ns
Peripheral hold time after strobe	$t_{H(STB-PE)}$	$t_{PH}$		150	—	—	ns
Read/write cycle time	$t_{C(RW)}$	$t_{RV}$		850	—	—	ns

## ● Switching Characteristics

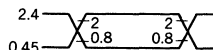
( $T_a = -20$  to  $75^\circ\text{C}$ ,  $V_{DD} = 5\text{V} \pm 10\%$ , unless otherwise noted)

Parameter	Symbol	Alternative symbol	Conditions	Min	Typ	Max	Unit
Propagation time from read to data output	$t_{PZX(R-DQ)}$	$t_{RD}$	$C_L = 150\text{pF}$			170	ns
Propagation time from read to data floating *3	$t_{PXZ(R-DQ)}$	$t_{DF}$		10		100	ns
Propagation time from write to output	$t_{PHL(W-PE)}$ $t_{PLH(W-PE)}$	$t_{WB}$				350	ns
Propagation time from strobe to IBF flag	$t_{PLH(STB-IBF)}$	$t_{SIB}$				300	ns
Propagation time from strobe to interrupt	$t_{PLH(STB-INTR)}$	$t_{SIT}$				300	ns
Propagation time from read to interrupt	$t_{PHL(R-INTR)}$	$t_{RIT}$				400	ns
Propagation time from read to IBF flag	$t_{PHL(R-IBF)}$	$t_{RIB}$				300	ns
Propagation time from write to interrupt	$t_{PHL(W-INTR)}$	$t_{WIT}$				450	ns
Propagation time from write to OBF flag	$t_{PHL(W-OBF)}$	$t_{WOB}$				650	ns
Propagation time from acknowledge to OBF flag	$t_{PLH(ACK-OBF)}$	$t_{AOB}$				350	ns
Propagation time from acknowledge to interrupt	$t_{PLH(ACK-INTR)}$	$t_{AIT}$				350	ns
Propagation time from acknowledge to data output	$t_{PZX(ACK-PE)}$	$t_{AD}$				300	ns
Propagation time from acknowledge to data floating *3	$t_{PXZ(ACK-PE)}$	$t_{KD}$		20		250	ns

\*3 Test conditions are not applied.

\*4 A.C Testing waveform

Input pulse level 0.45 to 2.4V  
 Input pulse rise time 10ns  
 Input pulse fall time 10ns  
 Reference level input  $V_{IH} = 2\text{V}$ ,  $V_{IL} = 0.8\text{V}$   
 Output  $V_{OH} = 2\text{V}$ ,  $V_{OL} = 0.8\text{V}$



## ■ FUNCTIONS

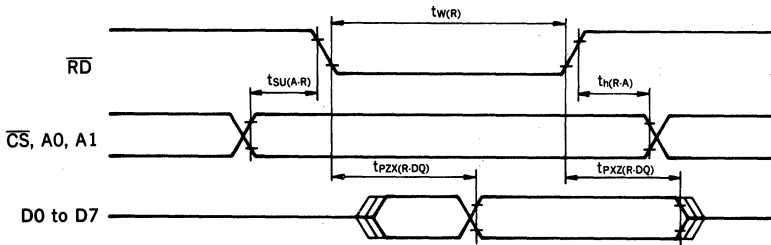
The SMC82C55AC-5 has programmable I/O pins that interface peripheral equipment to the CPU. The system software programs the functional configuration of the device.

The 24 programmable I/O pins may be individually configured in two groups of 12. Each group has three major modes of operation: 0, 1 and 2. In mode 0, each group of 12 I/O pins may be programmed in sets of four inputs or outputs. In mode 1, each group of 12 I/O pins may be grouped as one 8-bit I/O data port and one 4-bit control/status port. Mode 2 is used in Group A only, as one 8-bit bidirectional port and one 5-bit control/status port.

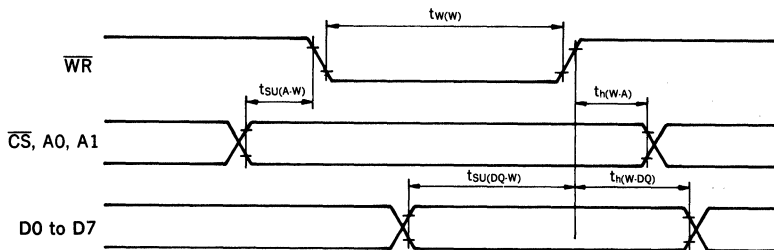
In mode 1 or 2, the control/status port bits can be set or reset by the CPU. A RESET pin is provided to clear all internal registers and set all ports to an input mode.

● Timing Chart

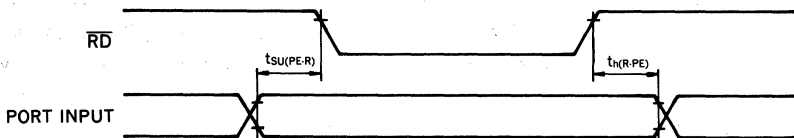
○ Data bus read operation



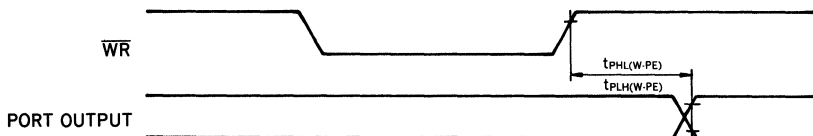
○ Data bus write operation



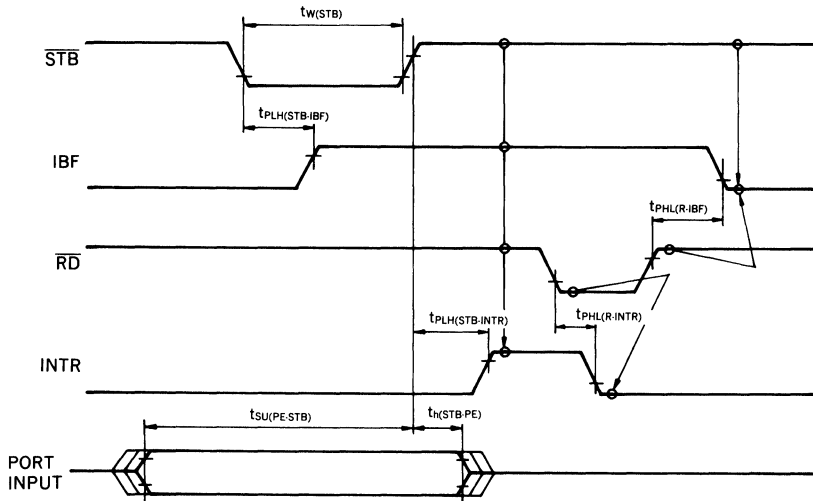
○ Mode 0 Port input



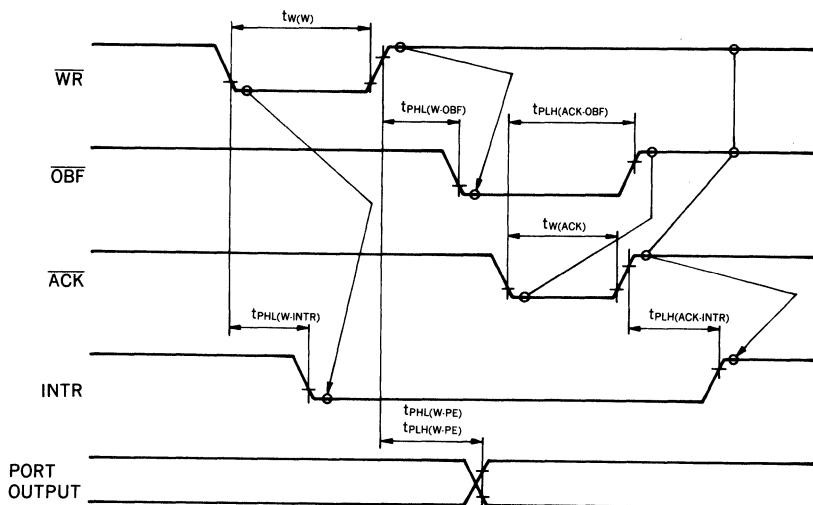
○ Mode 0, 1 Port output



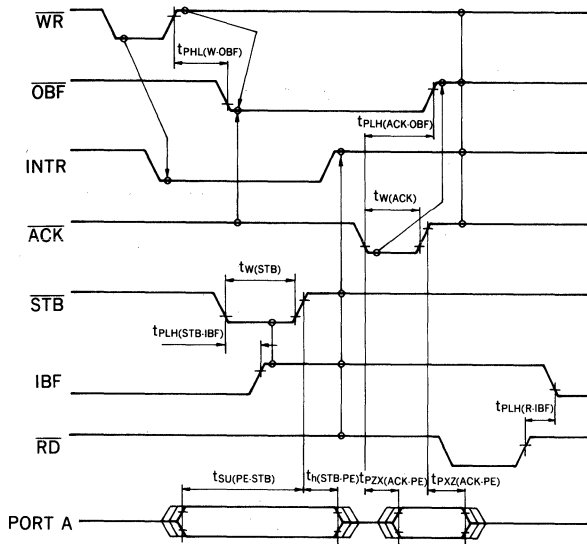
Mode 1 Strobed input



Mode 1 Strobed output



○ Mode 2 Bidirectional

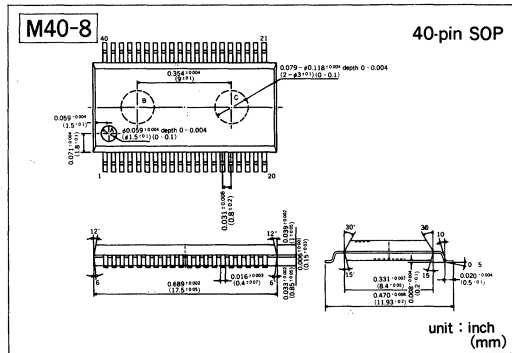
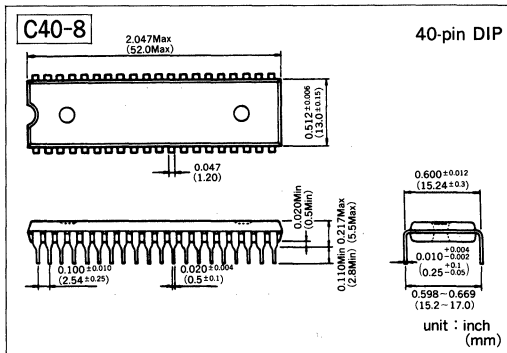


\*5  $INTR = \overline{IBF} \cdot \overline{MASK} \cdot \overline{STB} \cdot \overline{RD} + \overline{OBF} \cdot \overline{MASK} \cdot \overline{ACK} \cdot \overline{WR}$

■ APPLICATION

The SMC 82C55AC-5 is used as a general purpose programmable I/O device designed to interface peripheral equipment to the 80XX series of microprocessors.

■ PACKAGE DIMENSIONS



# SMC82C59AC

## CMOS PROGRAMMABLE INTERRUPT CONTROLLER

- Supports 8 Levels of Interrupt
- Many Functions for Interrupt
- Low Power

### DESCRIPTION

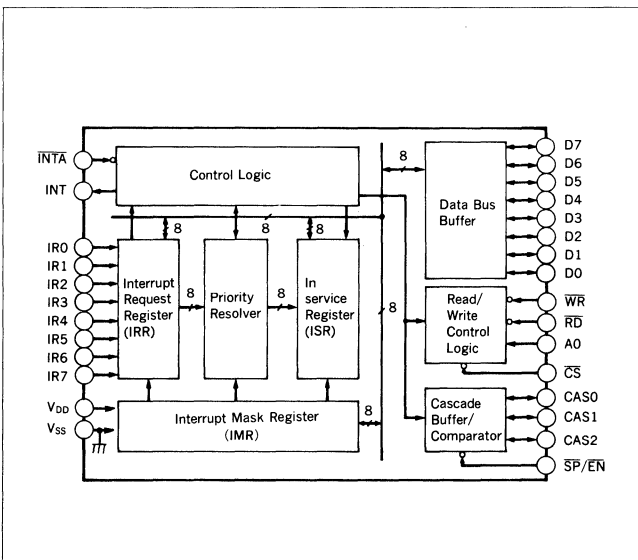
The SMC82C59AC is a CMOS Programmable Interrupt Controller. The device is designed to minimize the system software overhead required to handle multi-level interrupts. The device requires no clock inputs.

### FEATURES

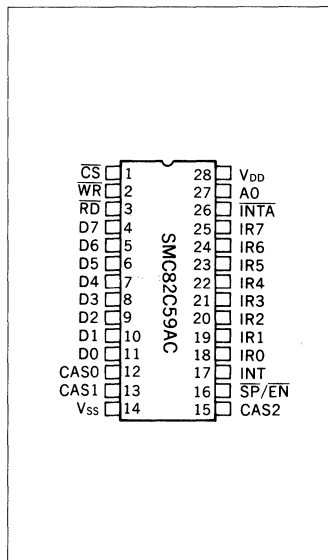
- Supports eight levels of interrupt
- Cascadable up to 64 levels
- Programmable
  - Priority
  - Mask Capability
  - Vectored Address
- Single 5V (±10%) power supply
- Package.....28-pin DIP  
28-pin SOP\*

\*Under development

### BLOCK DIAGRAM



### PIN CONFIGURATION



## ■ ABSOLUTE MAXIMUM RATINGS

( $V_{SS}=0V$ ,  $T_a=25^\circ C$ )

Parameter	Symbol	Conditions	Ratings	Unit
Power-supply voltage	$V_{DD}$	With respect to $V_{SS}$	-0.3 to 7	V
Input voltage	$V_I$		-0.3 to $V_{DD}+0.3$	V
Output voltage	$V_O$		-0.3 to $V_{DD}+0.3$	V
Operating temperature	$T_{opr}$	—	-20 to 75	$^\circ C$
Storage temperature	$T_{stg}$	—	-65 to 150	$^\circ C$
Soldering temperature and time	$T_{sol}$	—	260 $^\circ C$ , 10s (lead)	—

## ■ RECOMMENDED OPERATING CONDITIONS

( $T_a = -20$  to  $75^\circ C$ , unless otherwise noted)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	$V_{DD}$	—	4.5	5	5.5	V
Supply voltage	$V_{SS}$	—	—	0	—	V

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

( $T_a = -20$  to  $75^\circ C$ ,  $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ , unless otherwise noted)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
High-level input voltage	$V_{IH}$	—	2	—	$V_{DD}+0.3$	V
Low-level input voltage	$V_{IL}$	—	-0.3	—	0.8	V
High-level output voltage	$V_{OH}$	$I_{OH} = -400\mu A$	2.4	—	—	V
High-level output voltage, interrupt request output	$V_{OH(INT)}$	$I_{OH} = -100\mu A$	3.5	—	—	V
Low-level output voltage	$V_{OL}$	$I_{OL} = 2.2mA$	—	—	0.45	V
Standby supply current from $V_{DD}$	$I_{DDs}$	$V_{DD}=5.5V$ , $V_I=V_{DD}$ or GND output open	—	—	10	$\mu A$
High-level input current	$I_{IH}$	$V_I=V_{DD}$	-10	—	10	$\mu A$
Low-level input current	$I_{IL}$	$V_I=0V$	-10	—	10	$\mu A$
Off-state output current	$I_{OZ}$	$V_{SS}=0$ , $V_I=0.45$ to $5.5V$	-10	—	10	$\mu A$
High-level input current, interrupt request inputs	$I_{IH(IR)}$	$V_I=V_{DD}$	—	—	10	$\mu A$
Low-level input current, interrupt request inputs	$I_{IL(IR)}$	$V_I=0V$	-300	—	—	$\mu A$
Input capacitance	$C_I$	$V_{DD}=V_{SS}$ , $f=1MHz$ , $25mVrms$ , $T_a=25^\circ C$	—	—	10	pF
Input/output capacitance	$C_{I/O}$	$V_{DD}=V_{SS}$ , $f=1MHz$ , $25mVrms$ , $T_a=25^\circ C$	—	—	20	pF

### ● AC Electrical Characteristics

#### ○ Timing Requirements

( $T_a = -20$  to  $75^\circ C$ ,  $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ , unless otherwise noted)

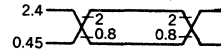
Parameter	Symbol	Alternative symbol	Conditions	Min	Typ	Max	Unit
Write pulse width	$t_{W(W)}$	$t_{WLWH}$		200	—	—	ns
Address setup time before write	$t_{SU(A-W)}$	$t_{AHWL}$		0	—	—	ns
Address hold time after write	$t_{H(W-A)}$	$t_{WHAX}$		0	—	—	ns
Data setup time before write	$t_{SU(DQ-W)}$	$t_{DVWH}$		100	—	—	ns
Data hold time after write	$t_{H(W-DQ)}$	$t_{WHDX}$		0	—	—	ns
Read pulse width	$t_{W(R)}$	$t_{RLRH}$		200	—	—	ns
Address setup time before read	$t_{SU(A-R)}$	$t_{AHRL}$		0	—	—	ns
Address hold time after read	$t_{H(R-A)}$	$t_{RHAX}$		0	—	—	ns
Interrupt request input width, low-level time, edge triggered mode	$t_{W(IR)}$	$t_{JLJH}$		100	—	—	ns
Cascade setup time before INTA (slave)	$t_{SU(CAS-INTA)}$	$t_{CVIAL}$		55	—	—	ns
Write recovery time	$t_{rec(W)}$	$t_{WHRL}$		190	—	—	ns
Read recovery time	$t_{rec(R)}$	$t_{RHRL}$		160	—	—	ns

## ● Switching Characteristics

( $T_a = -20$  to  $75^\circ\text{C}$ ,  $V_{DD} = 5\text{V} \pm 10\%$ ,  $V_{SS} = 0\text{V}$ , unless otherwise noted)

Parameter	Symbol	Alternative symbol	Conditions	Min	Typ	Max	Unit
Data output enable time after read	$t_{PZV(R-DQ)}$	$t_{RLDV}$		—	—	170	ns
Data output disable time after read	$t_{PVZ(R-DQ)}$	$t_{RHDZ}$		10	—	100	ns
Data output enable time after address	$t_{PZV(A-DQ)}$	$t_{AHDV}$		—	—	200	ns
Propagation time from read to enable signal output	$t_{PHL(R-EN)}$	$t_{RLEL}$		—	—	125	ns
Propagation time from read to disable signal output	$t_{PLH(R-EN)}$	$t_{RHEH}$		—	—	150	ns
Propagation time from interrupt request input to interrupt request output	$t_{PLH(IR-INT)}$	$t_{JHIH}$		—	—	350	ns
Propagation time from INTA to cascade output (master)	$t_{PLV(INTA-CAS)}$	$t_{IALCV}$		—	—	565	ns
Data output enable time after cascade output (slave)	$t_{PZV(CAS-DQ)}$	$t_{CVDV}$		—	—	300	ns

- \* 1 INTA signal is considered read signal  
 CS signal is considered address signal  
 Input pulse level 0.45 to 2.4V  
 Input pulse rise time 10ns  
 Input pulse fall time 10ns  
 Reference level Input  $V_{IH} = 2\text{V}$ ,  $V_{IL} = 0.8\text{V}$   
 Output  $V_{OH} = 2\text{V}$ ,  $V_{OL} = 0.8\text{V}$   
 Load capacitance  $C_L = 100\text{pF}$ , where SP/EN pin is 15pF

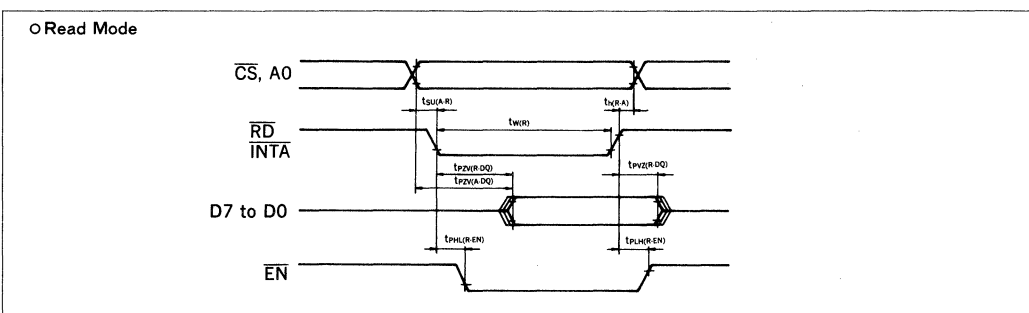
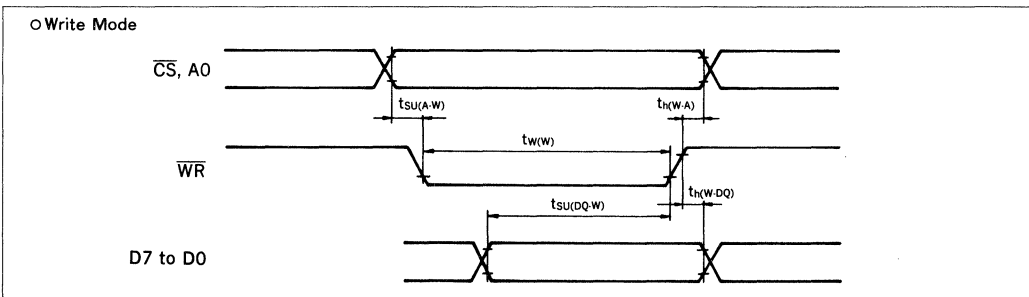


## ■ FUNCTIONS

The SMC82C59AC is able to handle up to eight vectored priority interrupts for a CPU. The device is designed for real time use and thus reduces system software overhead. The priority and interrupt mask can be reconfigured as required by the system software.

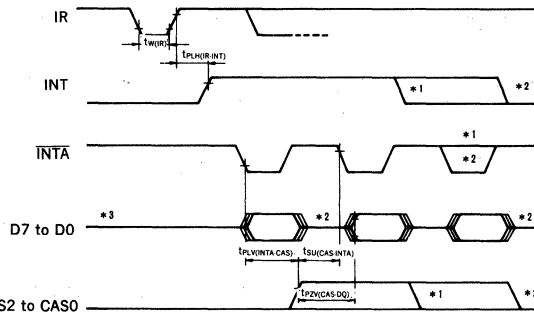
When a peripheral requires servicing an interrupt is generated by the peripheral. The SMC82C59AC based on the mask and the priority of the interrupt will issue an interrupt request (INT) to the CPU. After the CPU acknowledges ( $\overline{\text{INTA}}$ ) the interrupt; the SMC82C59AC can "point" the Program Counter to the service routine associated with the peripheral interrupt request. This "pointer" is a programmed vector address in the device and is released via the data bus.

## ● Timing Chart



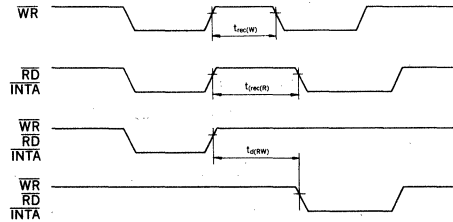


### ○ Interrupt Sequence



- \*1 8086 mode
- \*2 8085 mode
- \*3 8086 mode is in high-impedance state, pointer is released during the next INTA. When in single 8085 mode, data is released by all INTAs. When master, CALL instruction is released during the first INTA, high impedance state during the second and third INTA. When slave, high impedance state during the first INTA, vectored address is released during the second and third INTA.

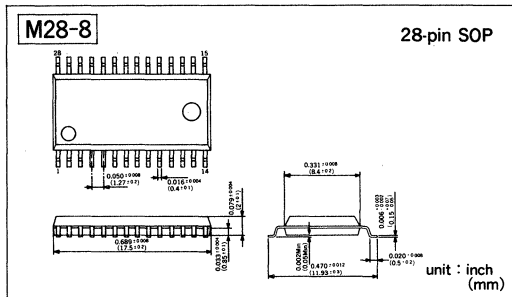
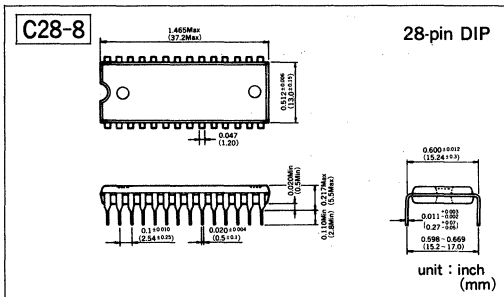
### ○ Other Timing



### ■ APPLICATION

The SMC82C59AC can be used as an interrupt controller for most CPUs and specifically the 80XX series microcomputers.

### ■ PACKAGE DIMENSIONS



# SMC5242C

## CMOS REAL TIME CLOCK

- Microprocessor Direct Bus Connection
- Function of Hours, Minutes, Seconds, Days of Month, Months, Years, Days of Week
- Low Supply Current (Power Down Mode)

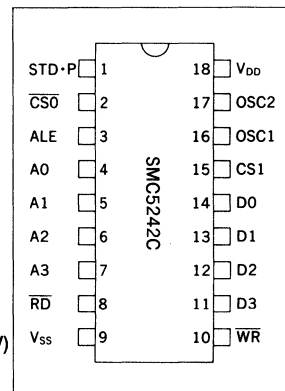
### DESCRIPTION

The SMC5242C is a CMOS real time clock IC with calendar information designed to operate in bus oriented microprocessor applications. Standard quartz crystal (32.768kHz) is applicable.

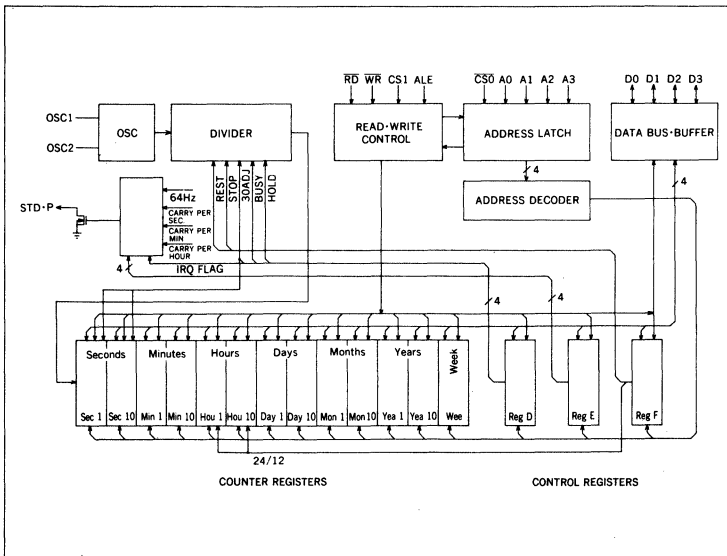
### FEATURES

- 4 bit bi-directional DATA BUS and 4bit ADDRESS BUS
- 12-hour/24-hour operation (selective)
- BCD format code from seconds to years
- ±30 seconds error correction with software
- Selective interrupt output/periodical clock output
- Start/stop function
- Automatic distinction of Leap year
- ALE input pin for 8048 8051 8085CPU
- Low supply current .....5μA MAX at V<sub>DD</sub>=2V (Power Down Mode)  
10μA MAX at V<sub>DD</sub>=5V
- Power .....V<sub>DD</sub>=5V±20%, (Power down mode V<sub>DD</sub>=2~6V)
- Package .....18-pin DIP (plastic)

### PIN CONFIGURATION



### BLOCK DIAGRAM



### PIN DESCRIPTION

D0 to D3	DATA BUS
A0 to A3	ADDRESS BUS
ALE	ADD. LATCH ENABLE
WR	WRITE
RD	READ
CS0	CHIP SELECT 0
CS1	CHIP SELECT 1
STD-P	STANDARD PULSE OUTPUT
OSC1, OSC2	CRYSTAL OSC
V <sub>DD</sub>	POWER SUPPLY (+5V)
V <sub>SS</sub>	POWER SUPPLY (0V)

## FUNCTION OF TERMINALS

Pin Name	Pin No.	Direction	Function
D0 to D3	11 to 14	Bi-direction	(4 bit Data Bus) Bi-directional data bus pins, are connected to microprocessor data bus lines. Using this bus, any data is read from or written to the internal counter-register.
A0 to A3	4 to 7	Input	(4 bit Address Bus) Input pins for address, are connected to microprocessor address bus lines. Address information select the internal register. (This bus is also used with ALE.)
ALE	3	Input	(Address Latch Enable) This is input pin for reading address data and $\overline{CS0}$ . When ALE = H, the address data and $\overline{CS0}$ are read into the IC. The address data and $\overline{CS0}$ are latched at negative-going of ALE. For microprocessors that don't have ALE output, this pin should be "H".
$\overline{WR}$	10	Input	(Write) At $\overline{WR}$ = L, the data on data bus (D0 to D3) is written into the register appointed by address lines (A0 to A3).
$\overline{RD}$	8	Input	(Read) At $\overline{RD}$ = L, the data from the register appointed by address lines (A0 to A3) is outputted to data bus (D0 to D3).
$\overline{CS0}$	2	Input	(Chip Select 0) $\overline{CS0}$ = L makes this IC active, and this pin is able to be used with ALE also.
CS1	15	Input	(Chip Select 1) Input pin, makes this IC stand-by or operating. When CS1 = H this pin makes this IC active. (When CS1 = L this pin makes IC stand-by.)
STD·P	1	Output	(Standard Pulse) STD·p is output pin of N-ch open drain. This pin outputs periodical interrupt wave or periodical pulse wave. When STD·P = L, this is active. $\overline{CS0}$ , CS1 don't inhibit this output.
OSC1	16	Input	(Oscillation) Terminals for 32.768kHz quartz crystal oscillation.
OSC2	17		
V <sub>DD</sub>	18	—	(Power) V <sub>DD</sub> supply terminal (+5V), V <sub>SS</sub> supply terminal (0V-GND).
V <sub>SS</sub>	9		

## TRUTH TABLE

$\overline{CS0}$	CS1	$\overline{RD}$	$\overline{WR}$	Mode	D0 to D3
L	H	L	H	Output Mode	Read Data
L	H	H	L	Input Mode	Write Data
—	—	L	L	Inhibit	—
H	—	—	—	Not Selected	Hi-Z
—	L	—	—	Not Selected	Hi-Z

Note 1) — : "H" or "L"

Note 2) Upper table is at ALE = H

## ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V <sub>DD</sub>	GND = 0V	-0.3 to 7	V
Input voltage	V <sub>I</sub>		GND - 0.3 to V <sub>DD</sub> + 0.3	V
Output voltage	V <sub>O</sub>		GND - 0.3 to V <sub>DD</sub> + 0.3	V
Operating temperature	T <sub>opr</sub>		-30 to 85	°C
Storage temperature	T <sub>stg</sub>		-55 to 150	°C

## RECOMMENDED OPERATING CONDITIONS

( $T_a = -30$  to  $85^\circ\text{C}$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	$V_{DD}$	—	4.5	5.0	5.5	V
Input voltage (ex. CS1)	$V_{IH}$	—	2.2	—	$V_{DD} + 0.3$	V
	$V_{IL}$	—	-0.3	—	0.8	V
Input voltage (CS1)	$V_{IH}$	—	$V_{DD} \times 0.8$	—	$V_{DD} + 0.3$	V
	$V_{IL}$	—	-0.3	—	$V_{DD} \times 0.2$	V
Time keeping source voltage	$V_{CLK}$	—	2.0	—	6.0	V
Crystal frequency	$f_{OSC}$	—	—	32.768	—	kHz

Note : Time keeping source voltage guarantee crystal oscillation and time counting.

## ELECTRICAL CHARACTERISTICS

### DC Electrical Characteristics

( $T_a = -30$  to  $85^\circ\text{C}$ ,  $V_{DD} = 5V \pm 10\%$ )

Parameter	Symbol	Conditions	Applicable pin	Min	Typ	Max	Unit
Input leakage current	$I_{LI}$	$V_i = 0$ to $V_{DD}$	except D0 to D3	-1	—	1	$\mu\text{A}$
Input leakage current	$I_{LI}$		D0 to D3	-10	—	10	$\mu\text{A}$
Low level output voltage	$V_{OL}$	$I_{OL} = 2.5\text{mA}$ $I_{OH} = -400\mu\text{A}$	D0 to D3	—	—	0.4	V
High level output voltage	$V_{OH}$			2.4	—	—	V
Low level output voltage	$V_{OL}$	$I_{OL} = 2.5\text{mA}$	STD·P	—	—	0.4	V
Off state output current	$I_{OZ}$	$V_O = 0$ to $V_{DD}$		-10	—	10	$\mu\text{A}$
Operating supply current	$I_{DDO}$	$V_{DD} = 5V$ , $f = 32\text{kHz}$	$V_{DD}$	—	—	10	$\mu\text{A}$

### Terminal Capacitance

( $T_a = 25^\circ\text{C}$ )

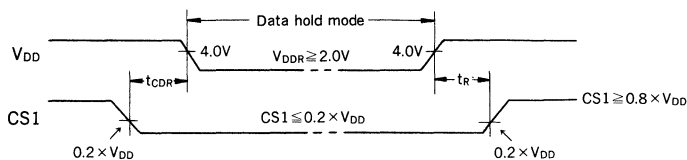
Parameter	Symbol	Conditions	Applicable pin	Min	Typ	Max	Unit
Input Capacitance	$C_i$	$f = 1\text{MHz}$	except D0 to D3	—	—	10	pF
I/O Capacitance	$C_{i/o}$	$f = 1\text{MHz}$	D0 to D3, STD·P	—	—	20	pF

### Data Retention Characteristic with Low Voltage Power Supply

( $T_a = -30$  to  $85^\circ\text{C}$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Data retention supply voltage	$V_{DDR}$	$CS1 \leq 0.2 \times V_{DD}$	2.0	—	6.0	V
Data retention current	$I_{DDR}$	$V_{DD} = 2V$ , $CS1 \leq 0.2 \times V_{DD}$	—	—	5	$\mu\text{A}$
Chip select data hold time	$t_{CDR}$	See following figure	2	—	—	$\mu\text{s}$
Operation recovery time	$t_R$		2	—	—	$\mu\text{s}$

### Data retention timing



Note : When retaining data in the stand-by mode, supply voltage can be lowered within a certain range. Read or write cycle cannot be performed while the supply voltage is low.

## ● AC Electrical Characteristics

○ Read Mode (ALE = V<sub>DD</sub> Connect)

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -30 to 85°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
CS1 setup time	t <sub>SU(CS1)</sub>	—	1000	—	—	ns
CS1 hold time	t <sub>H(CS1)</sub>	—	1000	—	—	ns
Address setup time before read	t <sub>SU(A-R)</sub>	—	50	—	—	ns
Address hold time after read	t <sub>H(R-A)</sub>	—	10	—	—	ns
RD access time	t <sub>PZV(R-Q)</sub>	C <sub>L</sub> = 150pF	—	—	120	ns
Output floating time after read	t <sub>PVZ(R-Q)</sub>	—	0	—	70	ns
Read recovery time	t <sub>rec(R)</sub>	—	200	—	—	ns

○ Read Mode (ALE use)

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -30 to 85°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
CS1 setup time	t <sub>SU(CS1)</sub>	—	1000	—	—	ns
Address setup time before ALE	t <sub>SU(A-ALE)</sub>	—	50	—	—	ns
Address hold time after ALE	t <sub>H(ALE-A)</sub>	—	50	—	—	ns
ALE pulse width	t <sub>W(ALE)</sub>	—	80	—	—	ns
ALE setup time before read	t <sub>SU(ALE-R)</sub>	—	0	—	—	ns
ALE setup time after read	t <sub>SU(R-ALE)</sub>	—	50	—	—	ns
RD access time	t <sub>PZV(R-Q)</sub>	C <sub>L</sub> = 150pF	—	—	120	ns
Output floating time after read	t <sub>PVZ(R-Q)</sub>	—	0	—	70	ns
Read recovery time	t <sub>rec(R)</sub>	—	200	—	—	ns
CS1 hold time	t <sub>H(CS1)</sub>	—	1000	—	—	ns

○ Write Mode (ALE = V<sub>DD</sub> Connect)

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -30 to 85°C)

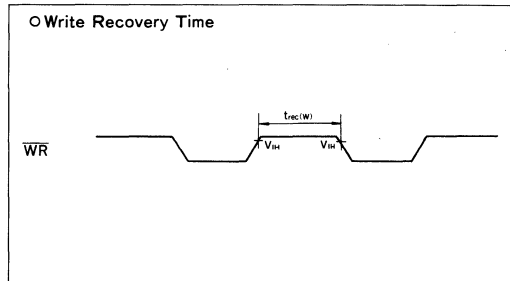
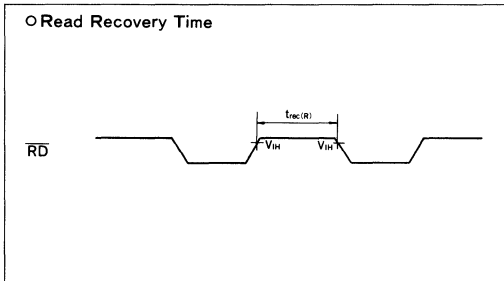
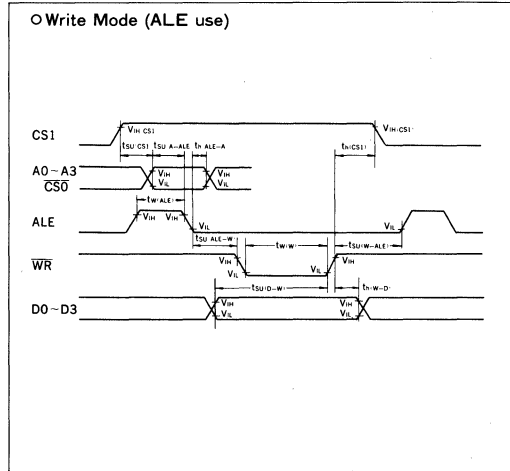
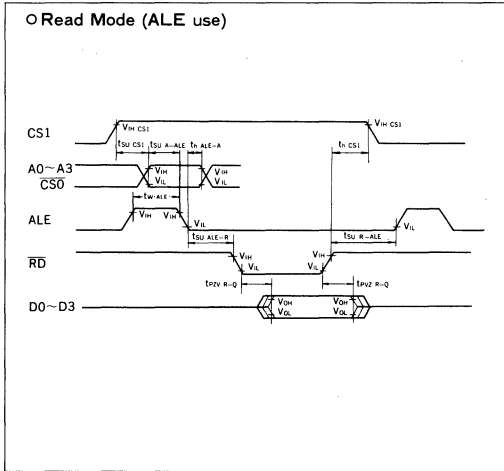
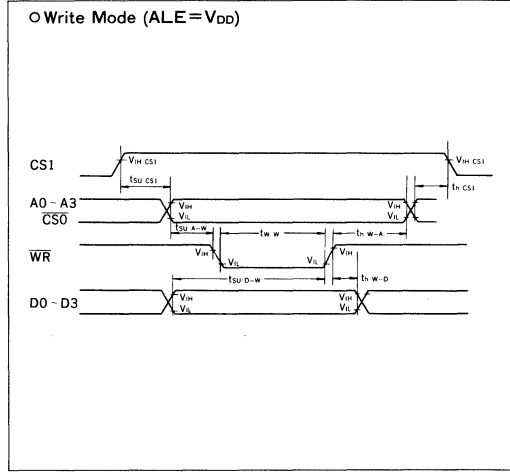
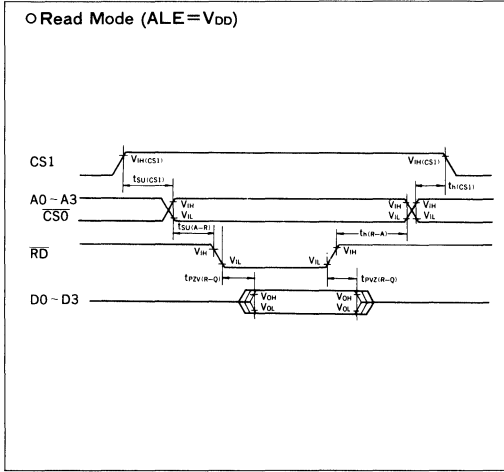
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
CS1 setup time	t <sub>SU(CS1)</sub>	—	1000	—	—	ns
CS1 hold time	t <sub>H(CS1)</sub>	—	1000	—	—	ns
Address setup time before write	t <sub>SU(A-W)</sub>	—	50	—	—	ns
Address hold time after write	t <sub>H(W-A)</sub>	—	10	—	—	ns
Write pulse width	t <sub>W(W)</sub>	—	120	—	—	ns
Data input setup time before write	t <sub>SU(D-W)</sub>	—	80	—	—	ns
Data input hold time after write	t <sub>H(W-D)</sub>	—	10	—	—	ns
Write recovery time	t <sub>rec(W)</sub>	—	200	—	—	ns

○ Write Mode (ALE use)

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -30 to 85°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
CS1 setup time	t <sub>SU(CS1)</sub>	—	1000	—	—	ns
Address setup time before ALE	t <sub>SU(A-ALE)</sub>	—	50	—	—	ns
Address hold time after ALE	t <sub>H(ALE-A)</sub>	—	50	—	—	ns
ALE pulse width	t <sub>W(ALE)</sub>	—	80	—	—	ns
ALE setup time before write	t <sub>SU(ALE-W)</sub>	—	0	—	—	ns
Write pulse width	t <sub>W(W)</sub>	—	120	—	—	ns
ALE setup time after write	t <sub>SU(W-ALE)</sub>	—	50	—	—	ns
Data input setup time before write	t <sub>SU(D-W)</sub>	—	80	—	—	ns
Data input hold time after write	t <sub>H(W-D)</sub>	—	10	—	—	ns
CS1 hold time	t <sub>H(CS1)</sub>	—	1000	—	—	ns
Write recovery time	t <sub>rec(W)</sub>	—	200	—	—	ns

● Timing Chart



Note : Conditions of V<sub>IH</sub>, V<sub>IL</sub>, V<sub>OH</sub>, V<sub>OL</sub> (READ MODE)  
 V<sub>IH</sub> = 2.2V (ex. CS1), V<sub>IH</sub>(CS1) =  $\frac{4}{5}V_{DD}$ , V<sub>OH</sub> = 2.4V  
 V<sub>IL</sub> = 0.8V (ex. CS1), V<sub>IL</sub>(CS1) =  $\frac{1}{5}V_{DD}$ , V<sub>OL</sub> = 0.4V

Note : Conditions of V<sub>IH</sub>, V<sub>IL</sub> (WRITE MODE)  
 V<sub>IH</sub> = 2.2V (ex. CS1), V<sub>IH</sub>(CS1) =  $\frac{4}{5}V_{DD}$   
 V<sub>IL</sub> = 0.8V (ex. CS1), V<sub>IL</sub>(CS1) =  $\frac{1}{5}V_{DD}$

## FUNCTION EXPLANATION

### Register's Function Table

Address of Registers and bit-content

Address	A3	A2	A1	A0	Name of Registers	Data				Count	Comment
						D3	D2	D1	D0		
0	0	0	0	0	Sec 1	S <sub>8</sub>	S <sub>4</sub>	S <sub>2</sub>	S <sub>1</sub>	0 to 9	1 second register
1	0	0	0	1	Sec 10	*	S <sub>40</sub>	S <sub>20</sub>	S <sub>10</sub>	0 to 5	10 seconds register
2	0	0	1	0	Min 1	Mi <sub>8</sub>	Mi <sub>4</sub>	Mi <sub>2</sub>	Mi <sub>1</sub>	0 to 9	1 minute register
3	0	0	1	1	Min 10	*	Mi <sub>40</sub>	Mi <sub>20</sub>	Mi <sub>10</sub>	0 to 5	10 minutes register
4	0	1	0	0	Hou 1	H <sub>8</sub>	H <sub>4</sub>	H <sub>2</sub>	H <sub>1</sub>	0 to 9	1 hour register
5	0	1	0	1	Hou 10	*	PM/AM	H <sub>20</sub>	H <sub>10</sub>	0 to 2 or 0 to 1	PM/AM, 10 hours register
6	0	1	1	0	Day 1	D <sub>8</sub>	D <sub>4</sub>	D <sub>2</sub>	D <sub>1</sub>	0 to 9	1 day register
7	0	1	1	1	Day 10	*	*	D <sub>20</sub>	D <sub>10</sub>	0 to 3	10 days register
8	1	0	0	0	Mon 1	Mo <sub>8</sub>	Mo <sub>4</sub>	Mo <sub>2</sub>	Mo <sub>1</sub>	0 to 9	1 month register
9	1	0	0	1	Mon 10	*	*	*	Mo <sub>10</sub>	0 to 1	10 months register
A	1	0	1	0	Yea 1	Y <sub>8</sub>	Y <sub>4</sub>	Y <sub>2</sub>	Y <sub>1</sub>	0 to 9	1 year register
B	1	0	1	1	Yea 10	Y <sub>80</sub>	Y <sub>40</sub>	Y <sub>20</sub>	Y <sub>10</sub>	0 to 9	10 years register
C	1	1	0	0	Wee	*	W <sub>4</sub>	W <sub>2</sub>	W <sub>1</sub>	0 to 6	Week Register
D	1	1	0	1	Reg D	<sup>30sec</sup> ADJ	IRQ FLAG	BUSY	HOLD	—	Control Register D
E	1	1	1	0	Reg E	t <sub>1</sub>	t <sub>0</sub>	ITRPT STND	MASK	—	Control Register E
F	1	1	1	1	Reg F	TEST	24/12	STOP	RESET	—	Control Register F

Note 1) \*bit : "H", "L" is writable but when read state "L" is valid only.

Note 2) BUSY bit : Output only.

Note 3) IRQ FLAG : "H", "L" is writable but "L" is valid only, when read state "H" or "L" is valid.

Data (=D0 to D3) of counter-register (=address 0 to C) has BCD code.

SMC5242C has read pin ( $\overline{RD}$ ), write pin ( $\overline{WR}$ ), chip selects ( $\overline{CS0}$ ,  $\overline{CS1}$ ), address bus and data bus, therefore usage of this IC is similar to normal RAMs.

Data bits of each register indicate the data as positive logic.

PM/AM, ITRPT/STND, 24/12, these data bits have the following table format.

	PM/AM	ITRPT/STND	24/12
H	PM	ITRPT	24
L	AM	STND	12

● **Functions of Registers** (See Block Diagram and Register's Function Table)

○ Counter-Register

The counter-register consists of a total of 13 registers with addresses from 0 to C.

Functions of these Registers are timekeeping (seconds, minutes, hours) and calendar (days of month, months, years, days of week).

Each counter uses BCD notation. The registers use positive logic for writing and reading on the data bus.

1) Hour·Hour Register (1 hour, 10 hours, PM/AM register)

These registers are used for counting hours, and are also used for operating the 12/24 hours format counting. The [24/12] use of Reg F (control register F) selects this operation.

- 24-hour operation : 0 to 23 hours counting
- 12-hour operation : AM12 to AM11 hours counting  
PM12 to PM11 hours counting

2) Year Register and Leap Year Distinction

This register is for counting years and distinguishing leap years automatically until 2,099 A. D.

- Example 80, 84, 88.....00 are leap years

3) Wee Register (Week Register)

This counter is constructed with limits of 0 to 6. User can set the contents of the week-register related with days of week freely.

- Setting Examples

	Sun.	Mon.	Tue.	Wed.	Thu.	Fri.	Sat.
W <sub>1</sub>	L	H	L	H	L	H	L
W <sub>2</sub>	L	L	H	H	L	L	H
W <sub>4</sub>	L	L	L	L	H	H	H

○ Control-Registers

The addresses of these registers are D, E, F and these functions monitor the internal condition, such as the 30 seconds error adjustment.

1) Reg D (Register D)

a. HOLD, BUSY

HOLD bit is used with BUSY bit when data is read from and written to control-register.

BUSY is a status bit which indicate that carry is occurring or not to second-counter when HOLD bit is set to logical "H".

BUSY bit is only used for reading.

- Procedure for reading and writing data to counter or control register (except Reg. D)

HOLD bit	Status of BUSY bit	WRITE, READ	Register
H setting	H	inhibit	carry occurring
	L	able	carry not occurring*

Note : \* Carry occurring to second-counter during HOLD=H, it can be corrected once automatically when HOLD bit is set "L". Be careful to set HOLD bit to "L" immediately after writing/reading operation.



b. IRQ FLAG

This is the status bit which corresponds to the STD·P output. It is used to indicate that a request of the interrupt to the microprocessor is occurring.

- STD·P Output with IRQ FLAG (When IRQ FLAG is read)

ITRPT/STND Mode	STD·P Output	IRQ FLAG Status
H (Interrupt Mode)	L	H
	H (OPEN)	L
L (Constant-Period Output Mode)	L	H (during 7.8125ms)
	H (OPEN)	L

Note. "L" can be written to IRQ FLAG from outside and at this time STD·P output "H" (OPEN), "L" is same as upper table too.

c. 30 sec ADJ.

This bit is used for second adjusting.

- When 30 sec ADJ bit is set to "H"  
Seconds=at 30 to 59 sec. ....Occurring carry to minute, Seconds become 00  
Seconds=at 01 to 29 sec. ....Not occurring carry to minute, Seconds become 00
- Automatic Return of 30 sec ADJ bit  
After writing "H", this bit hold "H" during 76.3μs, then it will automatically return to "L".  
While holding "H", writing "L" and operating other registers is inhibited.

2) Reg E (Register E)

a. MASK

The MASK bit control the STD·P output

- STD·P Output with MASK bit (When "H", "L" is written to MASK bit)

ITRPT/STND Mode	MASK	STD·P Output
H (Interrupt Mode)	H	Not Become "L" (Inhibit interrupt output)
	L	Cancel MASK Operation
L (Constant-Period Output Mode)	H	Not Become "L" (7.8125ms pulse not output)
	L	Cancel MASK Operation

Note : In Interrupt mode and at IRQ FLAG=H (STD·P=L), if MASK is set to "H", STD·P will be "H" while MASK=H.

In Constant-Period Output mode, at IRQ FLAG=H (STD·P=L), if MASK is set to "H", but STD·P will not be "H", moreover 7.8125ms pulse output.

b. ITRPT/STND

This bit is used for mode selection of the STD·P output.

- STD·P output mode with ITRPT/STND bit

ITRPT/STND Writing	STD·P Output Mode	Remarks
H	Interrupt mode	—
L	Constant-period output mode	Pulse width : 7.8125ms

Note: Output period is selected by  $t_0$ ,  $t_1$  (Both mode).

c.  $t_0$ ,  $t_1$

These bits select the output period from STD·P output terminal.

- Selecting Period with  $t_0$ ,  $t_1$

$t_1$	$t_0$	period	Pulse width	
			periodical output mode	interrupt mode
L	L	1/64 second	7.8125ms	depend on usage
L	H	1 second	7.8125ms	depend on usage
H	L	1 minute	7.8125ms	depend on usage
H	H	1 hour	7.8125ms	depend on usage

Note: Output-timing at 1 second, 1 minute or 1 hour period is carry occurring timing of its counter.

### 3) Reg F (Register F)

a. REST

Bit for resetting that reset divider counter from 256Hz to under a second.

While "H", resetting is continual. When it is set to "L", resetting is canceled.

If CS1 is "L", this REST bit will also be "L" automatically.

b. STOP

This bit inhibits the counting into the 8,192Hz divider stage and after.

"H" write : STOP "L" write : restart

c. 24/12

"H" write : 24 hours Operation

"L" write : 12 hours Operation (with AM, PM)

Should a user changes this bit, then the data of the upper register from the hour counter will be interrupted, therefore, it will be necessary to rewrite.

d. TEST

Please convert this terminal to "L".

## ■ OSCILLATION CIRCUIT

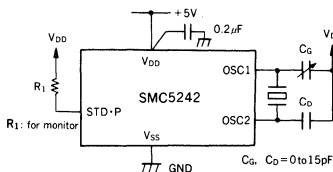
Use only a quartz crystal (32.768kHz, impedance : under 30k $\Omega$ ) and connect crystal to OSC1, OSC2.

In order to adjust frequency,  $C_G$  and  $C_D$  are needed as shown in the following figure, and also setting the control register is needed as shown in the following table.

$C_G$  is used for regulating frequency.

The STD·P terminal is used for monitor purposes.

### ● Circuit Construction



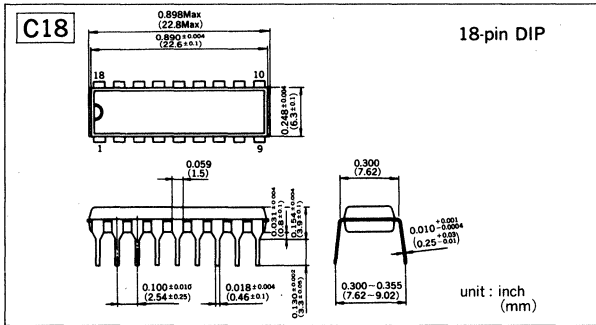
Note : If  $C_G$ ,  $C_D$  are too large, when power is on at a lower temperature, the oscillation may be impossible.

### ● Control-Register Setting for Adjusting Frequency

	D3	D2	D1	D0
Reg D	L	L	—	L
Reg E	$t_1$	$t_0$	L	L
Reg F	L	L	L	L

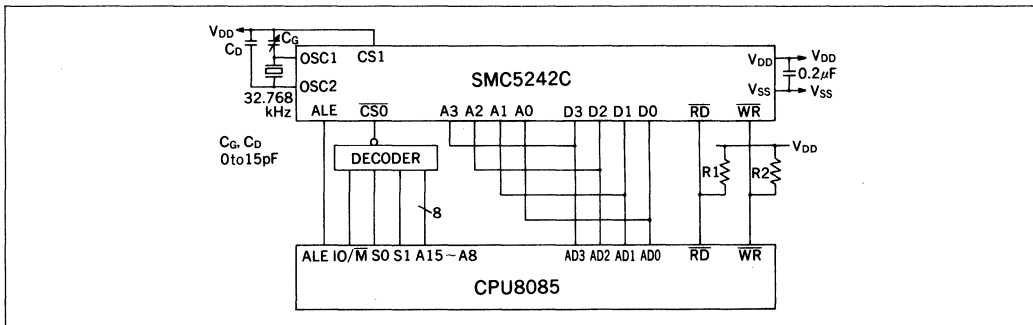
$t_0$ ,  $t_1$  select period.

## PACKAGE DIMENSIONS

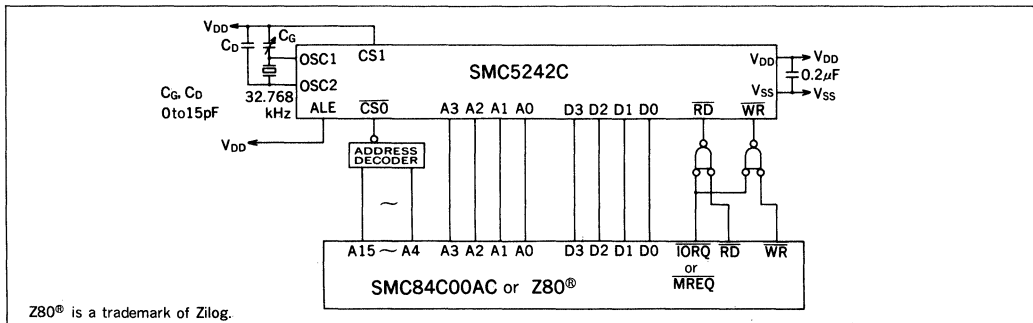


## EXAMPLE OF APPLICATION

### Using CPU 8085

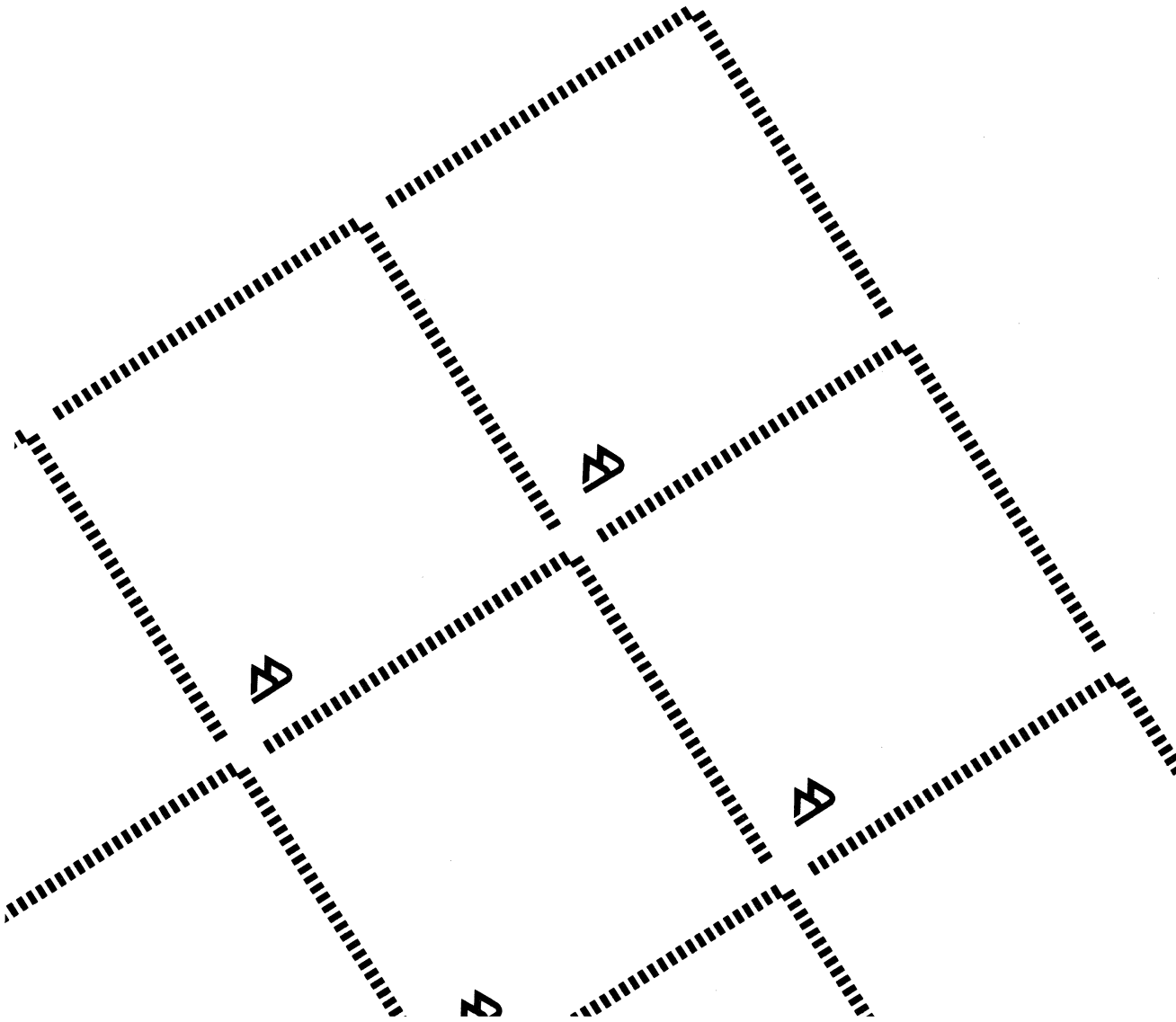


### Using SMC84C00AC or Z80®



D. GATE ARRAYS/STANDARD CELLS

1988/1989 CMOS  
DATA BOOK



1000  
1000

1000



# SLA100L Series

## CMOS LOW VOLTAGE GATE ARRAY

- Low Voltage Operation · · 0.9V Min to 6.0V Max
- CMOS I/O Compatible
- Gate Densities From 1,600 to 8,000 Gates

### ■ DESCRIPTION

The SLA100L series is a CMOS master slice, low voltage gate array fabricated using a low threshold process. It includes six models, with a gate capacity range of 1,600 to 8,000 gates.

The low voltage design enables this series to operate from a single 1.5V or 3V battery. It is well suited for portable products and standard 5V applications.

The SLA100L Series is also available with MSI cell libraries and can be designed with the same tools as the SLA6000 and SLA7000 series.

### ■ FEATURES

- Low voltage operation ······ 0.9V Min (Operating voltage: 0.9 to 6.0V)
- Six models covering a gate capacity of 1,600 to 8,000 gates
- Suitable for portable product applications
- Short turn-around time

### ■ SLA100L SERIES

Series		Parameter					
		SLA116L	SLA122L	SLA134L	SLA149L	SLA162L	SLA180L
Gates (2-input NAND)		1,632	2,232	3,432	4,900	6,210	8,000
Technology		SILICON GATE CMOS 2 LAYER METALLIZATION					
I/O level		CMOS					
Delay time	Internal gate	8.5ns (1.5V Standard)		3.0ns (3.0V Standard)			
	Input buffer	12.0ns (1.5V Standard)		4.0ns (3.0V Standard)			
	Output buffer	40.0ns (1.5V Standard)		14.0ns (3.0V Standard)		C <sub>L</sub> = 15pF	
Coefficient of delay		For the SLA100L Series, the coefficient of delay is the typical value with V <sub>DD</sub> = 1.5V in the MSI cell library, multiplied by the maximum and minimum coefficients at the minimum and maximum operating voltages. For the applicable coefficient, contact us.					
Total ports for I/O		70	82	104	128	150	170
Total ports for Power/GND (Max)		8	8	8	8	8	8
Output mode		Normal, Open-drain, 3-state, Bi-directional					

□: Under development

### ■ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.3 to 6.5	V
Input voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Storage temperature	T <sub>stg</sub>	-65 to 150	°C

### ■RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>	1.5V (Standard)	1.35	1.50	1.65	V
	V <sub>DD</sub>	3V (Standard)	2.70	3.00	3.30	V
Operating voltage	V <sub>DD</sub>		0.90	—	6.00	V
Operating temperature	T <sub>opr</sub>		0	—	70	°C

### ■ELECTRICAL CHARACTERISTICS

(T<sub>a</sub>=0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply current	I <sub>DD</sub>	Stand-by, V <sub>DD</sub> =1.5V	—	—	2.0	μA
	I <sub>DD</sub>	Stand-by, V <sub>DD</sub> =3.0V	—	—	2.0	μA
High level output voltage	V <sub>OH</sub>	V <sub>DD</sub> =1.5V, I <sub>OH</sub> =-0.23mA	1.3	—	—	V
	V <sub>OH</sub>	V <sub>DD</sub> =3.0V, I <sub>OH</sub> =-0.6mA	2.7	—	—	V
Low level output voltage	V <sub>OL</sub>	V <sub>DD</sub> =1.5V, I <sub>OL</sub> =0.7mA	—	—	0.2	V
	V <sub>OL</sub>	V <sub>DD</sub> =3.0V, I <sub>OL</sub> =1.7mA	—	—	0.3	V
High level input voltage	V <sub>IH</sub>	V <sub>DD</sub> =1.5V	1.1	—	—	V
	V <sub>IH</sub>	V <sub>DD</sub> =3.0V	2.0	—	—	V
Low level input voltage	V <sub>IL</sub>	V <sub>DD</sub> =1.5V	—	—	0.4	V
	V <sub>IL</sub>	V <sub>DD</sub> =3.0V	—	—	1.0	V
Input leakage current	I <sub>LI</sub>		-200	—	200	nA

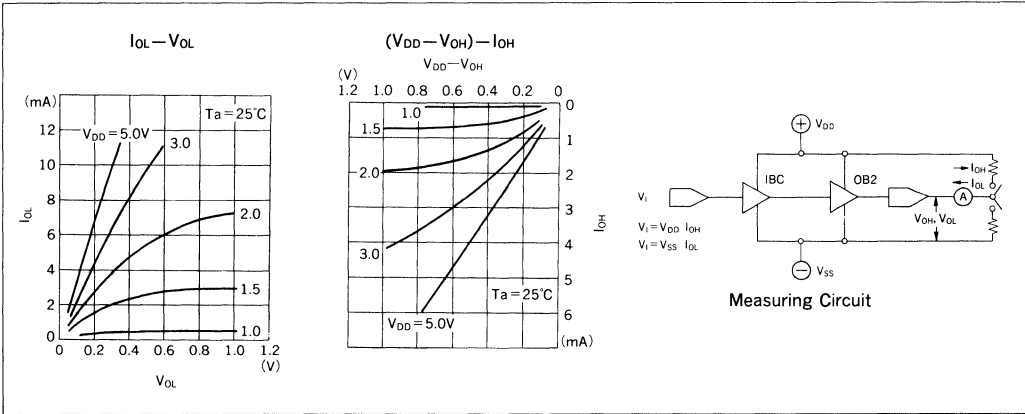
### ■PACKAGE LIST

Type	Pin No.	Package name	SLA116L	SLA122L	SLA134L	SLA149L	SLA162L	SLA180L
Plastic DIP	28pin	C28	○	○	○	□		
	40pin	C40	○	○	□	□		
	42pin	C42	□	○	○	□		
Plastic shrink DIP	64pin	S64	○	○	○	○	○	
	44pin	F44-2	○	○	○			
Plastic QFP	60pin	F60-2	□	○	○	○	○	
	60pin	F60-5	○	□	○	○	□	
	64pin	F64-5	□	□	□	□	□	
	80pin	F80-5	○	○	○	○	○	
	100pin	F100-5		○	○	○	○	
	128pin	F128-8			○	○	○	○
	144pin	F144-8					○	○
	160pin	F160-8				○	○	○
Plastic PGA	89pin	G89		□	□	□	□	
	132pin	G132		□	□	□	□	□
	176pin	G176					□	□
	208pin	G208						□
PLCC	44pin	J44	□	○	○	○	○	
	68pin	J68	□	○	○	○	○	
	84pin	J84				○	○	○
Ceramic PGA	72pin	P72		□	○	○	○	
	132pin	P132		□	○	○	○	○
	176pin	P176					□	□
	208pin	P208						□

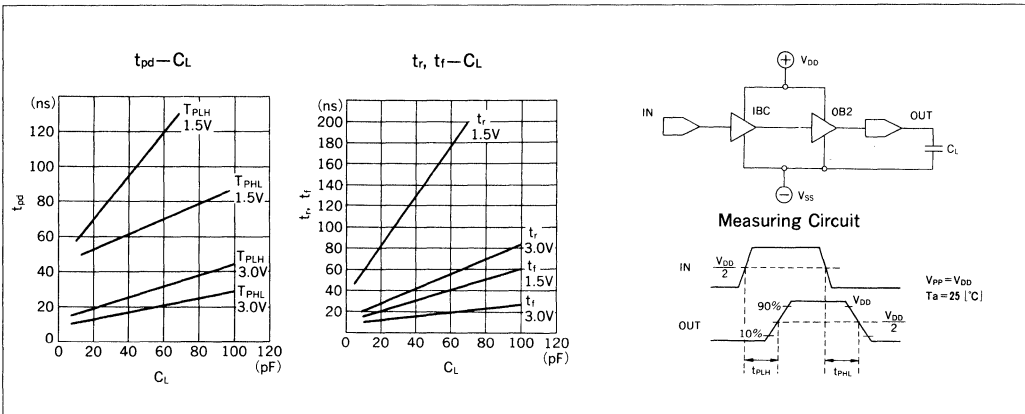
○: Available, □: Under development

## ■ PERFORMANCE CURVES

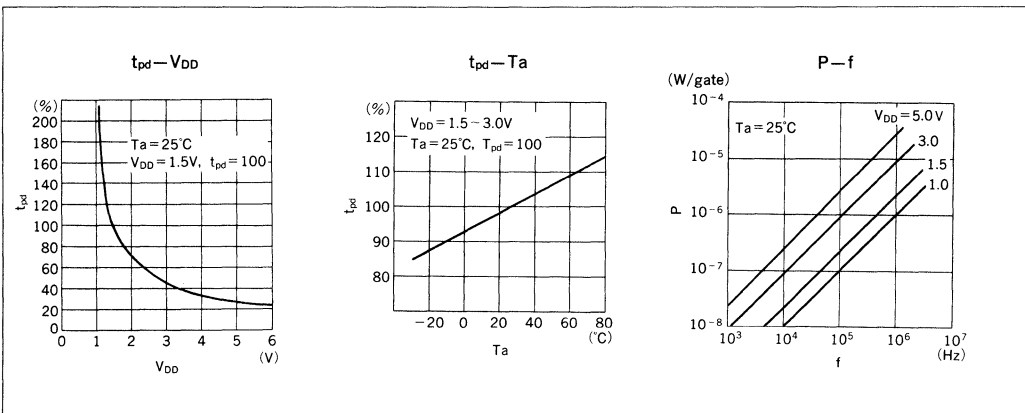
### ● Output Current



### ● $t_{pd}$ , $t_r$ , $t_f - C_L$

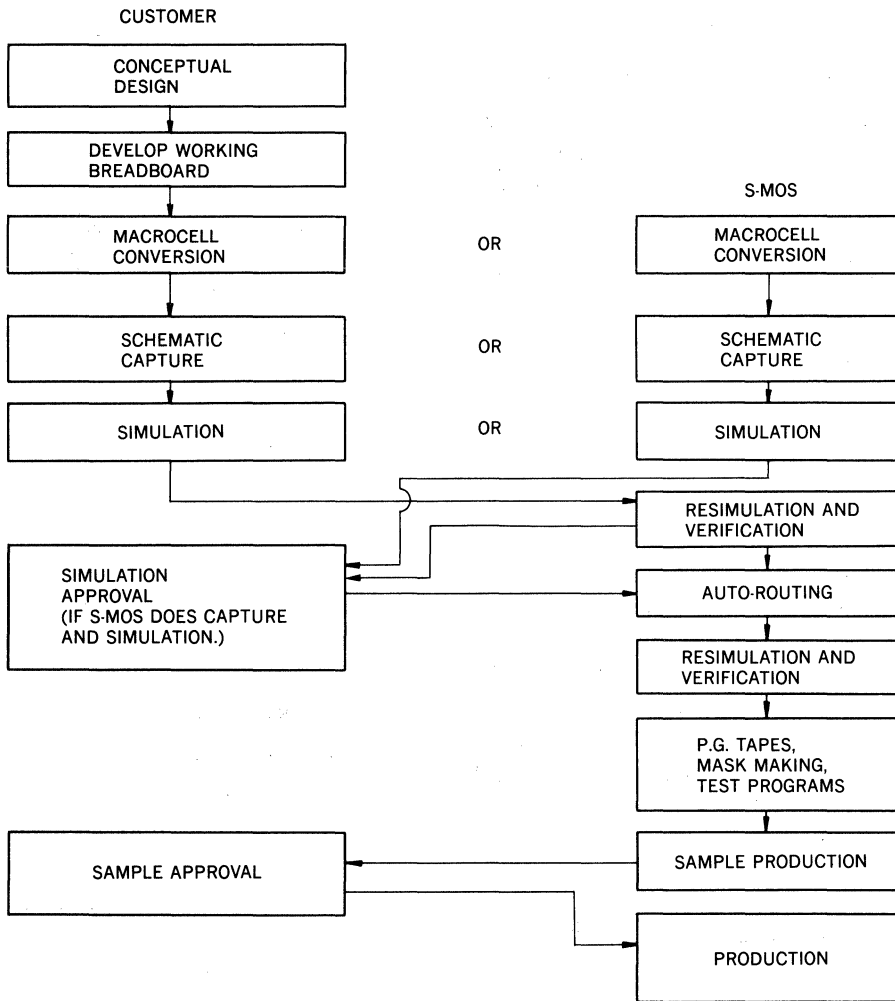


### ● Delay Time, Power Dissipation





# ■ GATE ARRAY DESIGN FLOW



# SLA6000 Series

## CMOS HIGH SPEED GATE ARRAY

- 2 Micron Dual Layer Metal
- 8 Sizes
- Fast Design Cycle

■ DESCRIPTION

The SLA6000 Series consists of a group of 8 CMOS Gate arrays with gate counts from 513 to 6,206 gates. The series is fabricated utilizing our 2 micron high speed CMOS silicon gate technology to achieve propagation delays of 1.8ns for the internal gates and 3ns-8ns for the I/O buffers. All I/O buffers are TTL and CMOS compatible which make this series an ideal choice for replacing existing discrete logic as well as for new designs.

■ FEATURES

- High speed silicon gate CMOS technology
- TTL and CMOS I/O compatible
- High output driver capability
- Gate densities from 513 to 6,206 gates
- "Hard" MSI macrocells for superior AC performance
- Cell libraries, software, and documentation available for IBM® PC compatibles with Future Net or OrCAD and Daisy and Mentor systems

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■ SLA 6000

Series		SLA6050	SLA6080	SLA6140	SLA6170	SLA6270	SLA6330	SLA6430	SLA6620
		Parameter							
Gates (2-input NAND)		513	820	1,394	1,746	2,667	3,312	4,342	6,206
Technology		SILICON GATE CMOS 2 LAYER METALLIZATION							
I/O level		TTL, CMOS							
Delay time	Internal gate <sup>*1</sup>	1.8ns (standard)							
	Input buffer <sup>*1, *2</sup>	t <sub>PLH</sub> = 3 ns, t <sub>PHL</sub> = 4 ns (standard)							
	Output buffer <sup>*2</sup>	t <sub>PLH</sub> = 6 ns, t <sub>PHL</sub> = 8 ns (standard) C <sub>L</sub> = 30pF							
Total ports for I/O (Terminals only for input port)		48 ( 6 )	60 ( 6 )	74 ( 6 )	82 ( 6 )	100 ( 6 )	110 ( 6 )	126 ( 6 )	154 ( 8 )
Output mode		Normal, Open-drain, 3-state, Bi-directional							

\*1 Typical fanout 2, 1 mm of interconnect  
 \*2 Standard I/O cell

### ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply Voltage	V <sub>DD</sub>	-0.3 to 7.0	V
Input Voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output Voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Storage Temperature	T <sub>stg</sub>	-65 to 150	°C

### ■ RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply Voltage	V <sub>DD</sub>	—	4.75	5.00	5.25	V
Operating Temperature	T <sub>opr</sub>	—	0	—	70	°C

### ■ ELECTRICAL CHARACTERISTICS

(V<sub>DD</sub>=5V±5%, V<sub>SS</sub>=0V, T<sub>a</sub>=0 to 70 °C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply Current	I <sub>DD</sub>	Standby	—	2	—	μA
High level output voltage	V <sub>OH</sub>	V <sub>DD</sub> =4.75 V I <sub>OH</sub> =-6 mA	2.4	—	—	V
Low level output voltage	V <sub>OL</sub>	V <sub>DD</sub> =4.75 V I <sub>OL</sub> =6 mA	—	—	0.4	V
High level input voltage	V <sub>IH</sub>	V <sub>DD</sub> =5.25 V	2.0	—	—	V
Low level input voltage	V <sub>IL</sub>	V <sub>DD</sub> =4.75 V	—	—	0.8	V
Input leakage current	I <sub>I</sub>	—	-1	—	1	μA

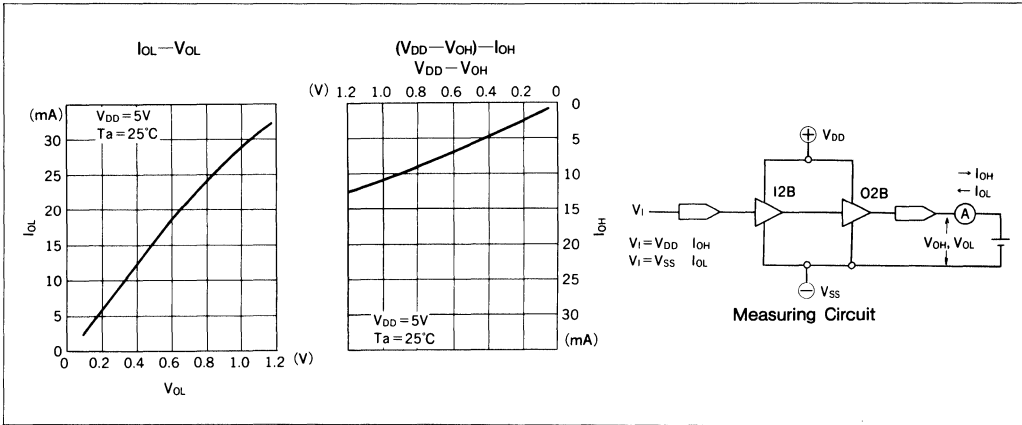
### ■ PACKAGE LIST

Type	Pin No.	Package name	SLA6050	SLA6080	SLA6140	SLA6170	SLA6270	SLA6330	SLA6430	SLA6620
Plastic DIP	14pin	C14	○	○						
	16pin	C16	○	○						
	18pin	C18	○	○						
	24pin	C24	○	○	○	○				
	28pin	C28	○	○	○	○	○			
	40pin	C40	○	○	○	○	○			
	42pin	C42	○	○	○	○	○			
Plastic QFP	44pin	F44-2		○	○	○	○			
	46pin	F46-5	○	○	○	○	○	○	○	
	60pin	F60-2	○	○	○	○	○	○		
	60pin	F60-5	○	○	○	○	○	○	○	
	80pin	F80-5			○	○	○	○	○	
	100pin	F100-5				○	○	○	○	
Ceramic QFP	148pin	H148						○	○	○
Plastic SOP	24pin	M24	○	○	○					
	28pin	M28-2		○	○					
Shrink DIP	28pin	S28		○						
	42pin	S42								
	64pin	S64			○	○	○			
Ceramic PGA	64pin	P64			○	○	○	○		
	72pin	P72				○	○	○		
	132pin	P132							○	○
PLCC	44pin	J44	○	○	○	○	○	○	○	
	68pin	J68			○	○	○	○	○	○
	84pin	J84				○	○	○	○	○

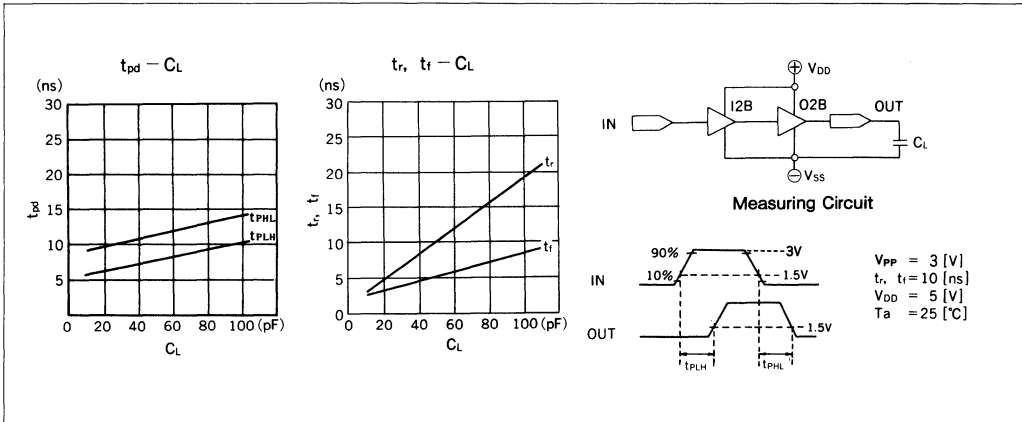
○ : Available

## PERFORMANCE CURVES

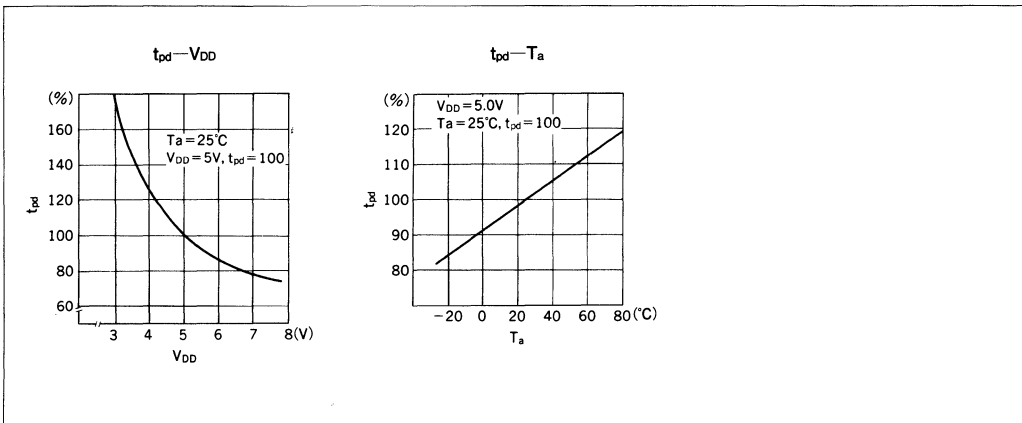
### Output Current



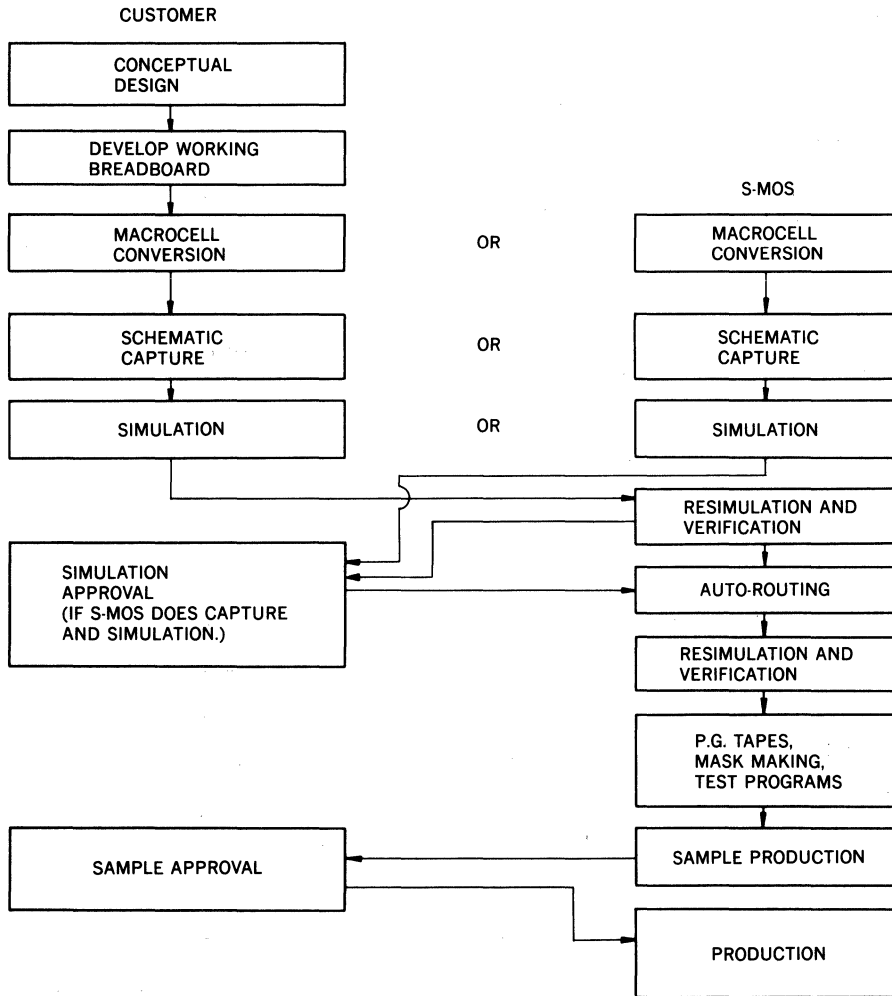
### $t_{pd}$ , $t_r$ , $t_f - C_L$



### Delay Time



**■ GATE ARRAY DESIGN FLOW**



# SLA7000 Series

## CMOS HIGH SPEED GATE ARRAY

- 1.5 Micron Dual Layer Metal
- 7 Sizes
- Fast Design Cycle
- Bipolar Speeds

### DESCRIPTION

The SLA7000 series consists of a group of 6 CMOS gate arrays with gate counts from 1,632 to 16,250 gates. The series is fabricated utilizing our 1.5 micron high speed CMOS silicon gate technology to achieve propagation delays of 1.0ns for the internal gates. All I/O buffers are TTL and CMOS compatible which makes this series an ideal choice for replacing existing discrete logic as well as for new designs requiring very high speed and/or high gate counts.

### FEATURES

- Very high speed silicon gate CMOS technology
- TTL and CMOS I/O compatible
- High output driver capability
- Gate densities from 1,632 to 16,250 gates
- "Hard" MSI macrocells for superior AC performance
- Cell libraries, software, and documentation available for IBM® PC compatibles with Future Net or OrCAD and Daisy and Mentor systems

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### SLA7000 SERIES

Series		SLA7160	SLA7220	SLA7340	SLA7490	SLA7620	SLA7800	SLA790S*3
		Parameter						
Gates (2-input NAND)		1,632	2,232	3,432	4,900	6,210	8,000	16,250
Technology		SILICON GATE CMOS 2 LAYER METALLIZATION						
I/O level		TTL, CMOS						
Delay time	Internal gate*1	1.0ns						
	Input buffer*1,*2	tp <sub>LH</sub> = 1.9ns, tp <sub>HL</sub> = 3.4ns						
	Output buffer*2	tp <sub>LH</sub> = 5.5ns, tp <sub>HL</sub> = 4.7ns, C <sub>L</sub> = 30pF						
Total ports for I/O		70	82	104	128	150	170	188
Total ports for Power/GND (Max)		8	8	8	8	8	8	8
Output mode		Normal, Open-drain, 3-state, Bi-directional						

\*1 Typical fanout of 2, 1mm of interconnect.

\*2 Standard I/O cell.

\*3 Sea of Gates (approx 8K usable gates.)

### ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.3 to 7.0	V
Input voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Storage temperature	T <sub>stg</sub>	-65 to 150	°C

### ■ RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>	—	4.75	5.00	5.25	V
Operating temperature	T <sub>opr</sub>	—	0	—	70	°C

### ■ ELECTRICAL CHARACTERISTICS

(V<sub>DD</sub>=5V±5%, T<sub>a</sub>=0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply current	I <sub>DD</sub>	Standby	—	2	—	μA
High level output voltage	V <sub>OH</sub>	V <sub>DD</sub> =4.75V I <sub>OH</sub> =-6mA	2.4	—	—	V
Low level output voltage	V <sub>OL</sub>	V <sub>DD</sub> =4.75V I <sub>OL</sub> =6mA	—	—	0.4	V
High level input voltage	V <sub>IH</sub>	V <sub>DD</sub> =5.25V	2.0	—	—	V
Low level input voltage	V <sub>IL</sub>	V <sub>DD</sub> =4.75V	—	—	0.8	V
Input leakage current	I <sub>LI</sub>	—	-1	—	1	μA

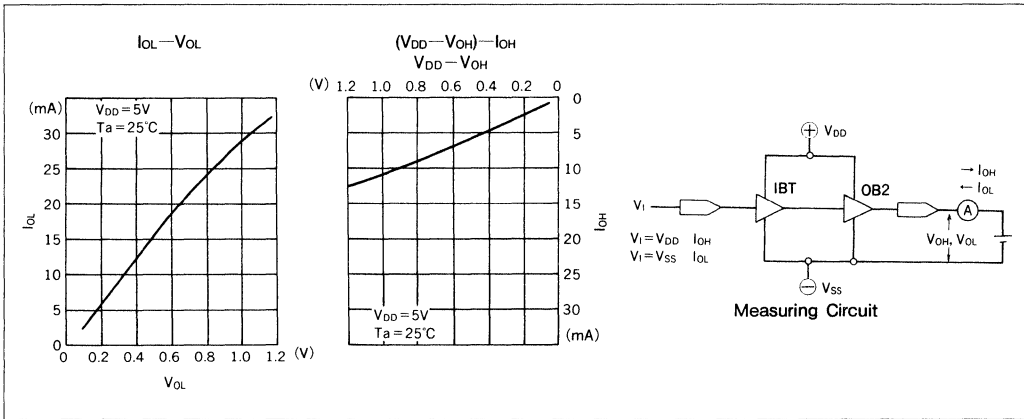
### ■ PACKAGE TYPES

Type	Pin No.	Package name	SLA7160	SLA7220	SLA7340	SLA7490	SLA7620	SLA7800	SLA790S
Plastic DIP	28pin	C28	○	○	○	□			
	40pin	C40	○	○	□	□			
	42pin	C42	□	○	○	□			
Plastic shrink DIP	64pin	S64	○	○	○	○	○		
Plastic QFP	44pin	F44-2	○	○	○				
	60pin	F60-2	□	○	○	○	○		
	60pin	F60-5	○	□	○	○	□		
	64pin	F64-5	□	□	□	□	□		
	80pin	F80-5	○	○	○	○			
	100pin	F100-5		○	○	○	○		
	128pin	F128-8			○	○	○	○	○
	144pin	F144-8					○	○	○
Plastic PGA	160pin	F160-8				○	○	○	○
	89pin	G89		□	□	□	□		
	132pin	G132		□	□	□	□	□	□
	176pin	G176					□	□	□
PLCC	208pin	G208					□	□	□
	44pin	J44	□	○	○	○	○		
	68pin	J68	□	○	○	○	○		
Ceramic PGA	84pin	J84				○	○	○	○
	72pin	P72		□	○	○	○		
	132pin	P132		□	○	○	○	○	○
	176pin	P176					□	□	□
	208pin	P208					□	□	□

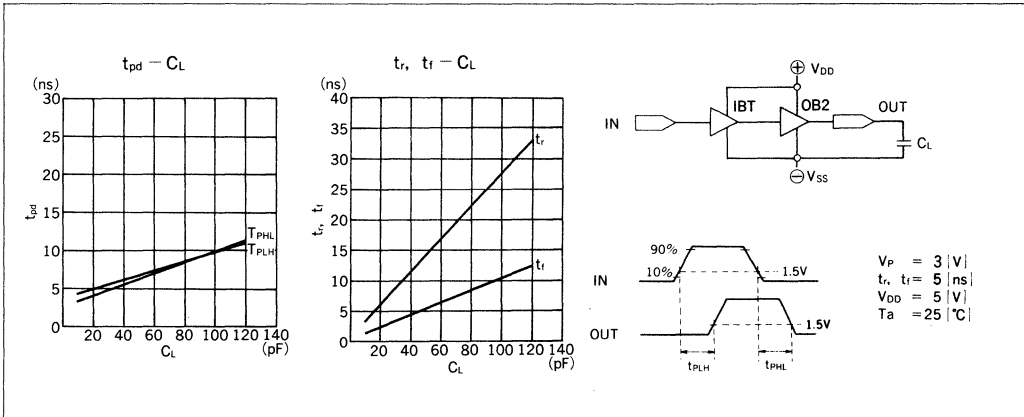
○ : Available    □ : Under Development

## PERFORMANCE CURVES

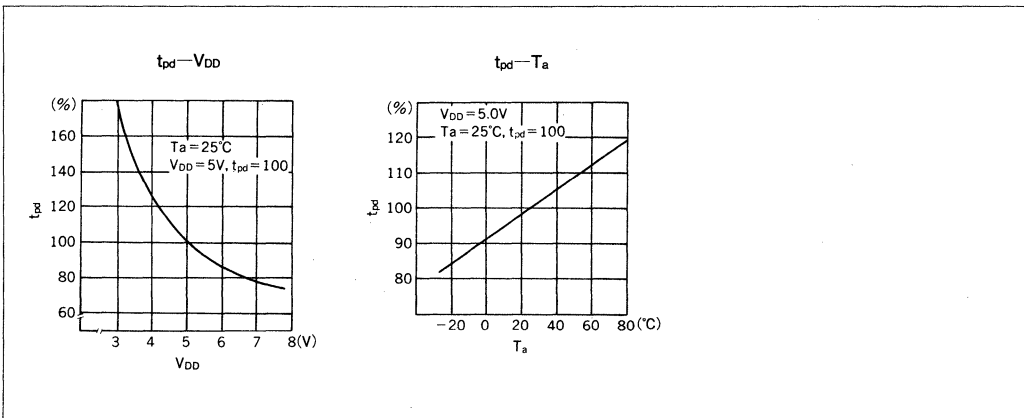
### Output Current



### $t_{pd}$ , $t_r$ , $t_f - C_L$

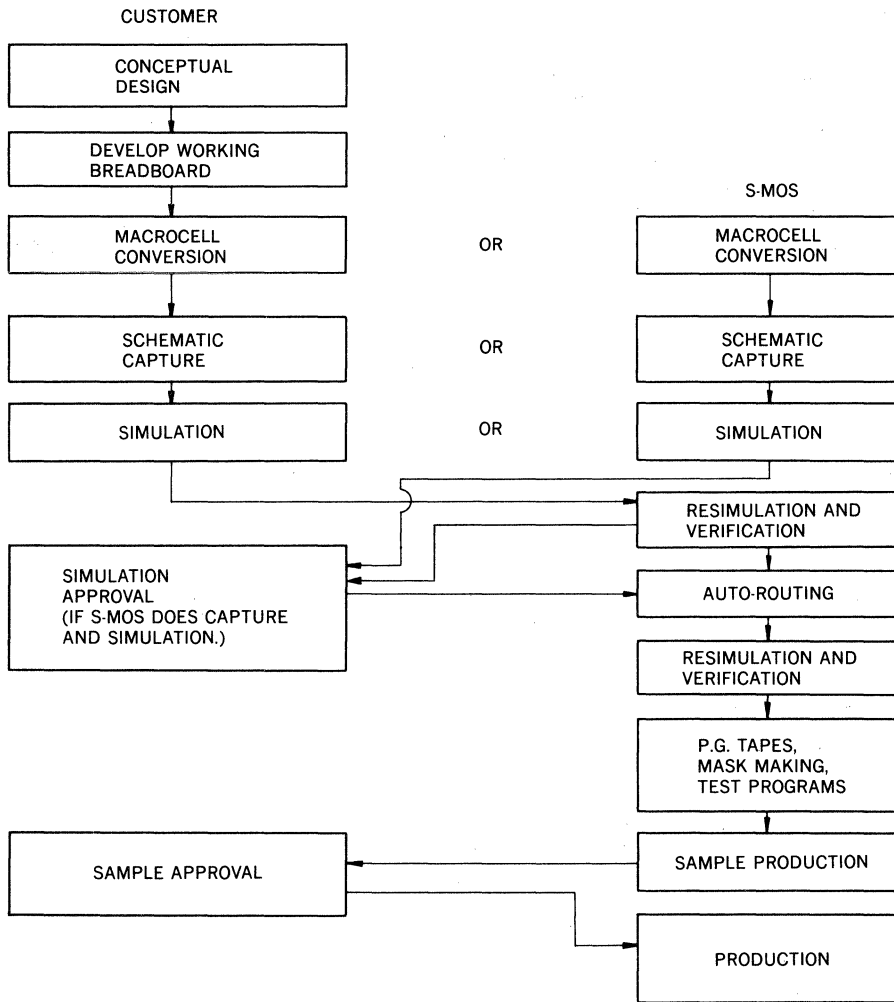


### Delay Time





■ GATE ARRAY DESIGN FLOW



# SLA700B Series

## CMOS HIGH SPEED & HIGH OUTPUT GATE ARRAY

- High Output Drive Capability
- Adaptable to CMOS and STTL Applications
- TTL and CMOS I/O Compatible
- Gate Densities from 800 to 2,400 Gates

### DESCRIPTION

The SLA700B series is a multi-pin, high output CMOS gate array, an enhanced version of the SLA7000 series. The series is fabricated using our advanced 1.5 micron CMOS technology and can deliver up to 24mA  $I_{OL}$ .

### FEATURES

- Multiple I/O pin configuration
- High output drive capability ( $I_{OL} = 24mA$ )
- Very high speed operation (typical delay time: 1.0ns)
- Adaptable to CMOS and STTL applications
- Library compatibility with our SLA7000 series
- Cell libraries, software, and documentation available for IBM® PC compatibles with Future Net or OrCAD and Daisy and Mentor systems

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### SLA700B SERIES

Series		SLA708B	SLA715B	SLA724B
Parameter				
Gates (2-input NAND)		825	1,500	2,482
Technology		SILICON GATE CMOS 2 LAYER METALLIZATION		
I/O level		TTL, CMOS		
Delay time	Internal gate <sup>*1</sup>	1.0ns		
	Input buffer <sup>*1,*2</sup>	$t_{PLH} = 1.9ns, t_{PHL} = 3.4ns$		
	Output buffer <sup>*2</sup>	$t_{PLH} = 5.5ns, t_{PHL} = 4.7ns \quad C_L = 30pF$		
Total ports for I/O		84	100	122
Total ports for Power/GND (Max)		8 (16)	8 (16)	8 (16)
Output mode		Normal, Open-drain, 3-state, Bi-directional		

\*1 Typical fanout 2, 1mm of interconnect

\*2 Standard I/O cell

### ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.3 to 7.0	V
Input voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Storage temperature	T <sub>stg</sub>	-65 to 150	°C

### ■ RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>	—	4.75	5.00	5.25	V
Operating temperature	T <sub>opr</sub>	—	0	—	70	°C

### ■ ELECTRICAL CHARACTERISTICS

(V<sub>DD</sub> = 5V ± 5%, T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply current	I <sub>DD</sub>	Standby	—	2	—	μA
High level output voltage	V <sub>OH</sub>	V <sub>DD</sub> = 4.75V I <sub>OH</sub> = -24mA	2.4	—	—	V
Low level output voltage	V <sub>OL</sub>	V <sub>DD</sub> = 4.75V I <sub>OL</sub> = 24mA	—	—	0.4	V
High level input voltage	V <sub>IH</sub>	V <sub>DD</sub> = 5.25V	2.0	—	—	V
Low level input voltage	V <sub>IL</sub>	V <sub>DD</sub> = 4.75V	—	—	0.8	V
Input leakage current	I <sub>LI</sub>	—	-1	—	1	μA

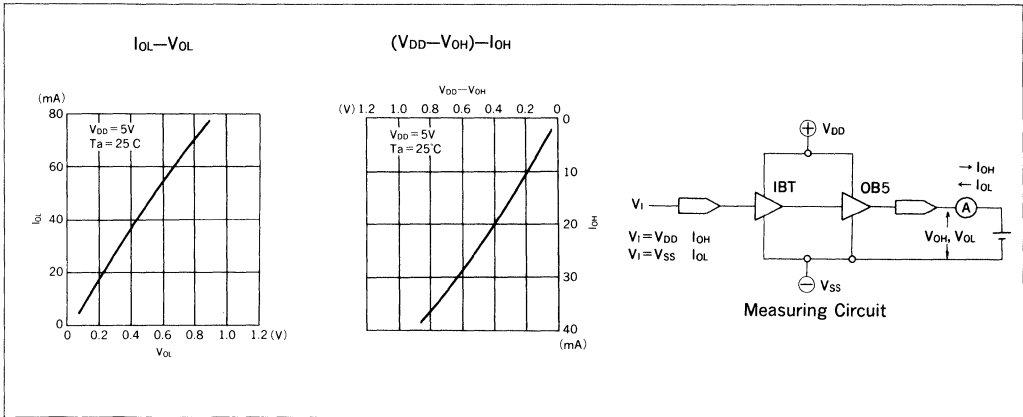
### ■ PACKAGE LIST

Type	Pin No.	Package name	SLA708B	SLA715B	SLA724B
Plastic DIP	28pin	C28			
	40pin	C40			
	42pin	C42			
Plastic shrink DIP	64pin	S64	○	○	○
	44pin	F44-2			
Plastic QFP	60pin	F60-2			
	60pin	F60-5			
	64pin	F64-5			
	80pin	F80-5	○	○	○
	100pin	F100-5	○	○	○
	128pin	F128-8		○	□
	144pin	F144-8			□
	160pin	F160-8			
Plastic PGA	89pin	G89	□	□	□
	132pin	G132	□	□	□
	176pin	G176			
	208pin	G208			
PLCC	44pin	J44			
	68pin	J68	○	○	○
	84pin	J84	○	○	○
Ceramic PGA	72pin	P72	□	□	□
	132pin	P132	○	○	○
	176pin	P176			
	208pin	P208			

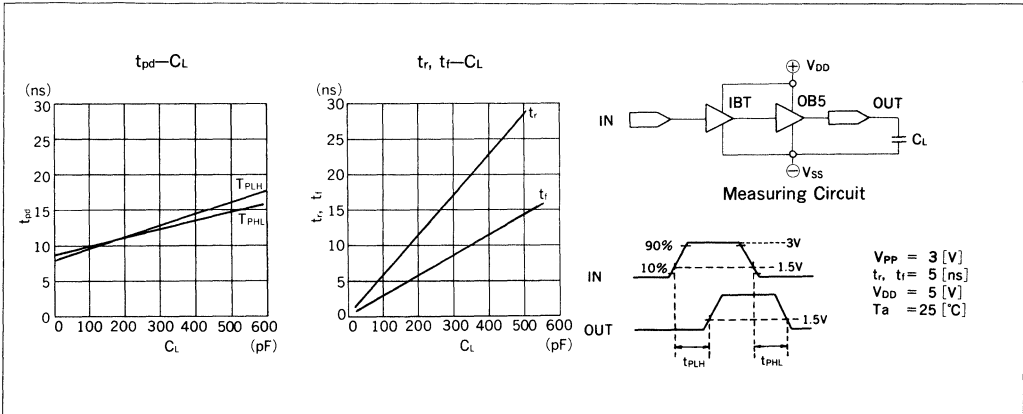
○: Available □: Under development

## PERFORMANCE CURVES

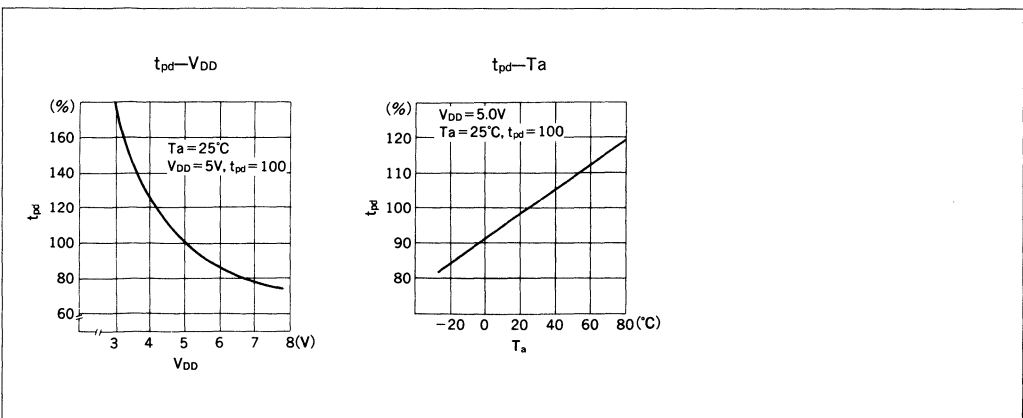
### Output Current



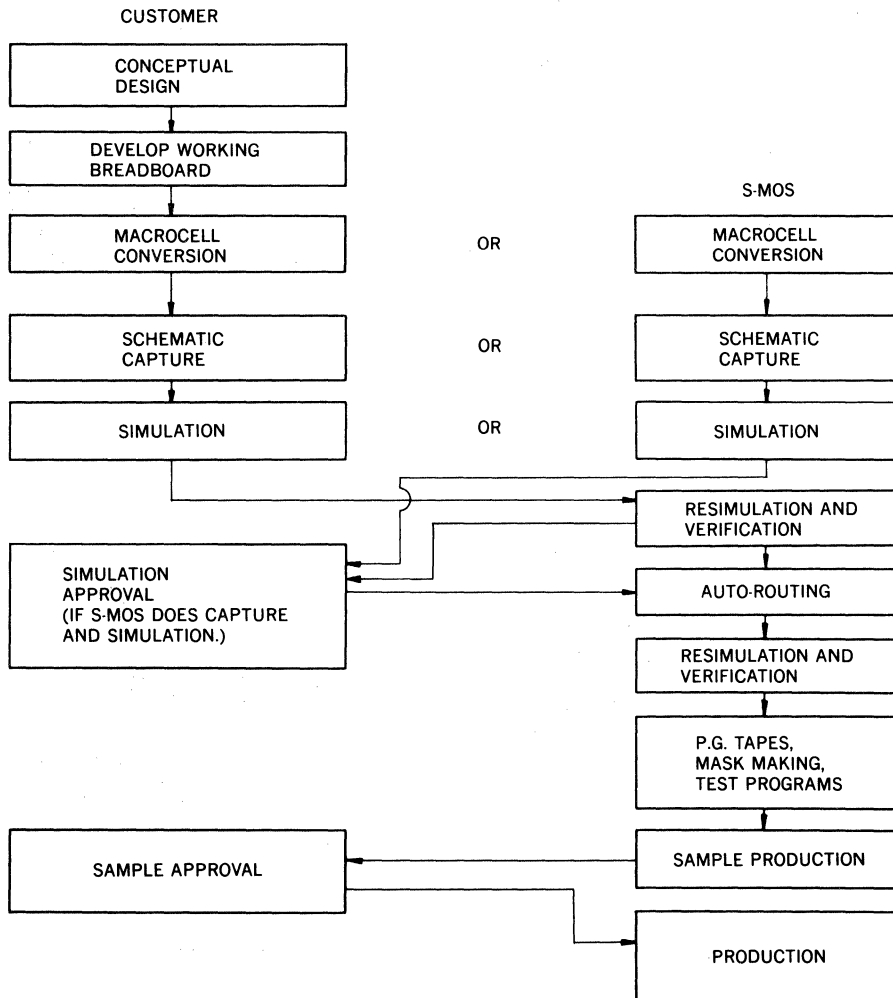
### $t_{pd}$ , $t_r$ , $t_f - C_L$



### Delay Time



■ GATE ARRAY DESIGN FLOW



# SLA8000 Series

## CMOS HIGH SPEED GATE ARRAY

- High Speed Silicon Gate CMOS Technology
- TTL and CMOS I/O Compatible
- High Output Drive Capability
- Gate Densities From 5,304 to 38,550 Gates  
(Sea of Gates)

### DESCRIPTION

The SLA8000 Series is a super-high-speed, densely-packaged master slice CMOS gate array (sea of gates). The SLA8000 Series comes in seven models. They can accommodate up to 16K usable gates to meet a variety of logical design requirements in special processor and controller applications.

### FEATURES

- Super-high speed:  $t_{pd}$  (typ) = 0.8ns/gate
- High performance applicable to LSTTL application area
- 24mA (Max) current available with 3 I/O cell in parallel
- Input cells and Bi-directional cells are provided with pull-up/pull-down resistor
- SRAM, ROM cells library are available
- Mega-cells capability
- Gate densities from 5,304 to 38,550 gates
- Actual ability for routing: 40 to 50% of total gates.

### SLA8000 SERIES

Parameter		Series						
		SLA827S	SLA847S	SLA872S	SLA890S	SLA8B3S	SLA8F0S	SLA8J3S
Gates (2-input NAND)		5,304	9,416	14,336	18,300	22,680	30,000	38,550
Technology		SILICON GATE CMOS 2 LAYER METALLIZATION, SEA OF GATES						
I/O level		TTL, CMOS						
Delay time	Internal gate <sup>*1</sup>	0.8ns (Typ)						
	Input buffer <sup>*1,*2</sup>	1.4ns (Typ)						
	Output buffer <sup>*2</sup>	3.5ns (Typ) $C_L = 15pF$						
Total ports for I/O		82	108	136	152	168	194	222
Total ports for Power/GND (Max)		4	4	4	4	4	4	4
Output mode		Normal, Open-drain, 3-state, Bi-directional						

\*1 Typical fanout of 2, 1mm of interconnect

\*2 Standard I/O cell.

### ■ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.3 to 7.0	V
Input voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Storage temperature	T <sub>stg</sub>	-65 to 150	°C

### ■RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>	—	4.75	5.00	5.25	V
Operating temperature	T <sub>opr</sub>	—	0	—	70	°C

### ■ELECTRICAL CHARACTERISTICS

(V<sub>DD</sub> = 5V ± 5%, T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply current	I <sub>DD</sub>	Stand-by	—	2	—	μA
High level output voltage	V <sub>OH</sub>	V <sub>DD</sub> = 4.75V I <sub>OH</sub> = -6mA	2.4	—	—	V
Low level output voltage	V <sub>OL</sub>	V <sub>DD</sub> = 4.75V I <sub>OL</sub> = 6mA	—	—	0.4	V
High level input voltage	V <sub>IH</sub>	V <sub>DD</sub> = 5.25V	2.0	—	—	V
Low level input voltage	V <sub>IL</sub>	V <sub>DD</sub> = 4.75V	—	—	0.8	V
Input leakage current	I <sub>LI</sub>	—	-1	—	1	μA

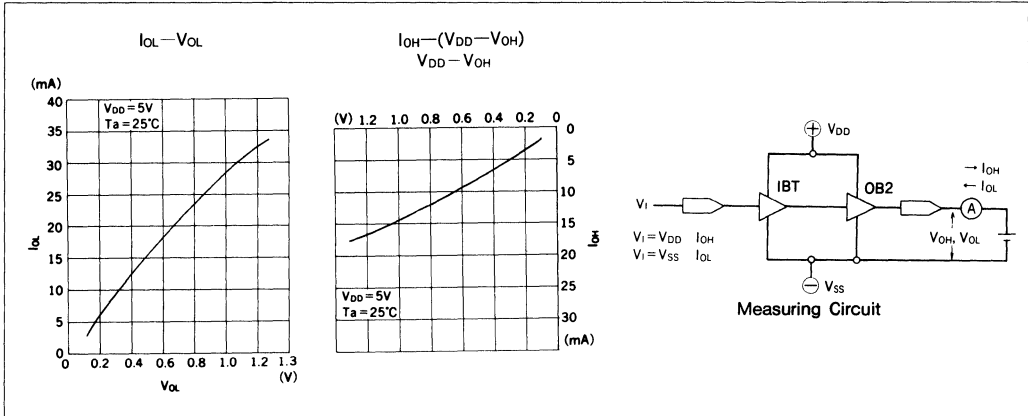
### ■PACKAGE LIST

Type	Pin No.	Package Name	SLA827S	SLA847S	SLA872S	SLA890S	SLA8B3S	SLA8F0S	SLA8J3S
Plastic DIP	28pin	C28	○	○	□				
	40pin	C40	○	□	□				
	42pin	C42	○	○	□				
Plastic shrink DIP	64pin	S64	○	○	○	○	○		
	44pin	F44-2	○	○	□	□	□		
Plastic QFP	60pin	F60-2	□	○	○	○	○		
	60pin	F60-5	○	○	○	□	□		
	64pin	F64-5	□	□	□	□	□		
	80pin	F80-5	○	○	○	○	○		
	100pin	F100-5	○	○	○	○	○	□	
	128pin	F128-8			□	□	○	○	□
	144pin	F144-8			□	□	○	○	○
	160pin	F160-8					○	○	○
	196pin	F196-9					□	□	□
	230pin	F230-9						□	□
	Plastic PGA	89pin	G89	□	□	□	□	□	
132pin		G132	□	□	□	□	□		
176pin		G176					□	□	□
208pin		G208						□	□
240pin		G240					□	□	□
PLCC	44pin	J44	○	○	○	○	○		
	68pin	J68	○	○	○	○	○		
	84pin	J84	○		○	○	○	○	
	132pin	J132							□
Ceramic PGA	132pin	P132	□	○	○	○	○	○	
	176pin	P176					□	□	□
	208pin	P208						□	□

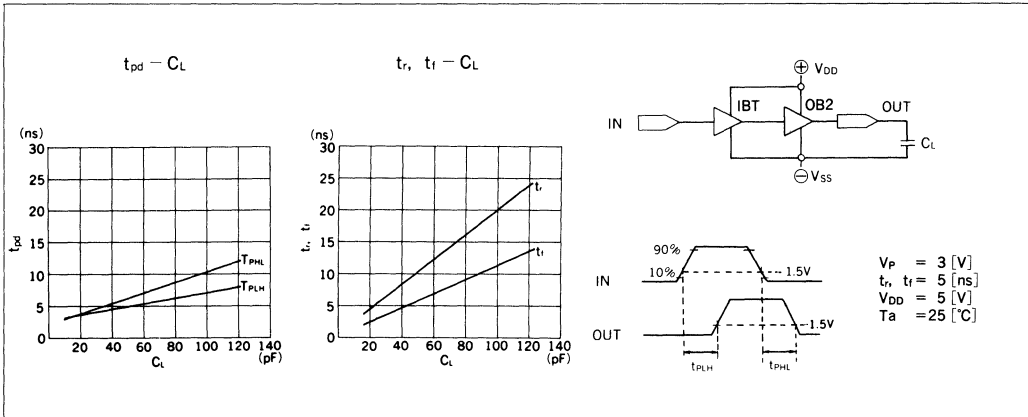
○ : Available    □ : Under development

## PERFORMANCE CURVES

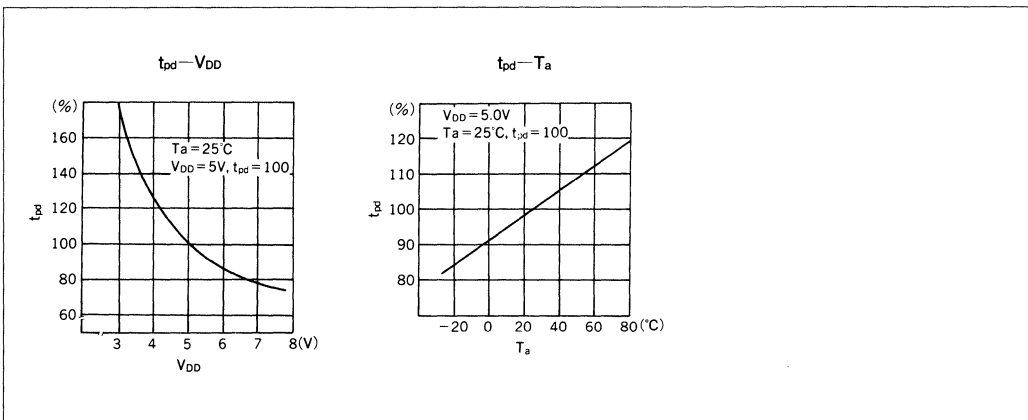
### Output Current



### $t_{pd}$ , $t_r$ , $t_f - C_L$

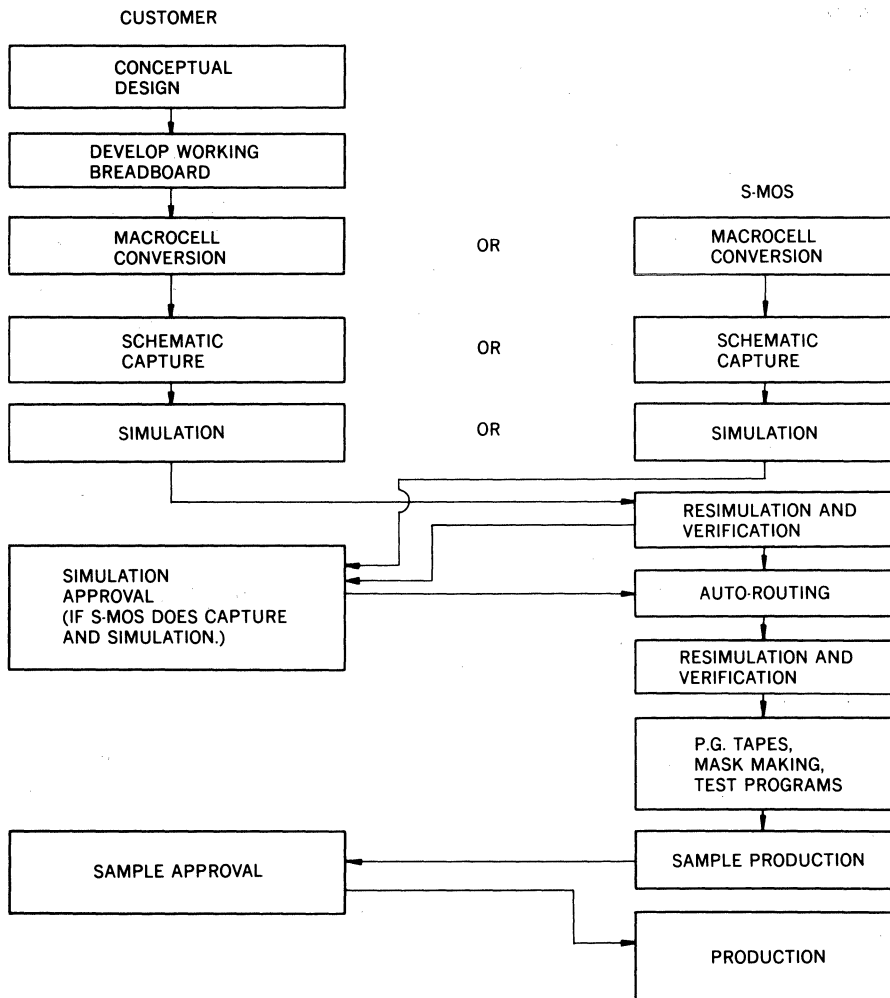


### Delay Time





■ GATE ARRAY DESIGN FLOW



# SSC1000 Series

## CMOS STANDARD CELL

- Gate Densities Up To 12,000 Gates
- A Large Cell Library
- Minimal Delay Time Variance for Consistent Performance

### DESCRIPTION

The SSC1000 Standard Cell Series consists of 20 basic master chips. A system utilizing up to 12,000 gates can be implemented on a single chip.

This family is fabricated using our advanced 1.8 micron dual layer metal CMOS process which results in very low power and very high speed performance.

The functions of the cell library are compatible with those of the SLA Gate Array Series and easy conversion from SLA6000 Series Gate Array design is possible.

The minimal delay time variance between the internal cells simplifies the design stage, and allows the speed to be as high as the TTL74S Series.

### FEATURES

- Usable for designs up to 12,000 gate complexity
- Very high speed (Typical delay time : 1.4ns)
- Cell functions compatible with the SLA gate array series
- Cell functions correspond to TTL74 Series
- Minimal delay time variance between cells
- I/O compatible with TTL or CMOS
- I/O high switching speed
- High output drive
- Low voltage operation at  $V_{DD}=2.4V$  possible
- SRAM, ROM cells are available

### SSC1000 SERIES

Series		SSC1010 to SSC1200
Parameter		
Gates (2-input NAND)		12,000 gates (Max)
Technology		SILICON GATE CMOS 2 LAYER METALLIZATION
I/O level		TTL, CMOS
Delay time	Internal gate	1.4ns (2-input NAND F.O.=2, I=2mm)
	Input buffer	3 to 4 ns (standard)
	Output buffer	4 to 6 ns $C_L=30pF$ (standard)
Total ports for I/O		192 (Max)
Input mode		TTL, CMOS, Pull-up, Schmidt (Buffer & Inverter)
Output mode		Normal, Open-drain, 3-state, Bi-directional $I_{OL}=4mA, 6mA, 14mA$

### ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V, T<sub>a</sub> = 25°C)

Parameter	Symbol	Rated	Unit
Supply voltage	V <sub>DD</sub>	-0.3 to 7.0	V
Input voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output current/pin	I <sub>O</sub>	±10*	mA
Power dissipation	P <sub>D</sub>	250	mW
Supply current	I <sub>DD</sub> /I <sub>SS</sub>	50	mA
Storage temperature	T <sub>stg</sub>	-65 to 150	°C

\*Apply 4mA, 6mA DRIVER

### ■ RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	TTL Input level			CMOS Input level			Low voltage operating			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
Supply voltage	V <sub>DD</sub>	4.75	5.0	5.25	4.5	5.0	5.5	2.4	—	5.5	V
Input voltage	V <sub>I</sub>	V <sub>SS</sub>	—	V <sub>DD</sub>	V <sub>SS</sub>	—	V <sub>DD</sub>	V <sub>SS</sub>	—	V <sub>DD</sub>	V
Operating temperature	T <sub>opr</sub>	0	—	70	-20	—	80	-20	—	85	°C

\*f<sub>MAX</sub> = 1MHz at low voltage operation

### ■ ELECTRICAL CHARACTERISTICS

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply current	I <sub>DDs</sub>	Standby	—	—	10	μA
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = 2, 4, 8mA * V <sub>DD</sub> = 4.75V	V <sub>DD</sub> - 0.4	—	—	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 4, 6, 14mA * V <sub>DD</sub> = 4.75V	—	—	V <sub>SS</sub> + 0.4	V
High level input voltage (TTL)	V <sub>IH1</sub>	V <sub>DD</sub> = 5.25V	2.0	—	—	V
Low level input voltage (TTL)	V <sub>IL1</sub>	V <sub>DD</sub> = 4.75V	—	—	0.8	V
High level input voltage (CMOS)	V <sub>IH2</sub>	V <sub>DD</sub> = 5.5V	3.5	—	—	V
Low level input voltage (CMOS)	V <sub>IL2</sub>	V <sub>DD</sub> = 4.5V	—	—	1.0	V
Input leakage current	I <sub>LI</sub>		-1	—	1	μA

\*selective

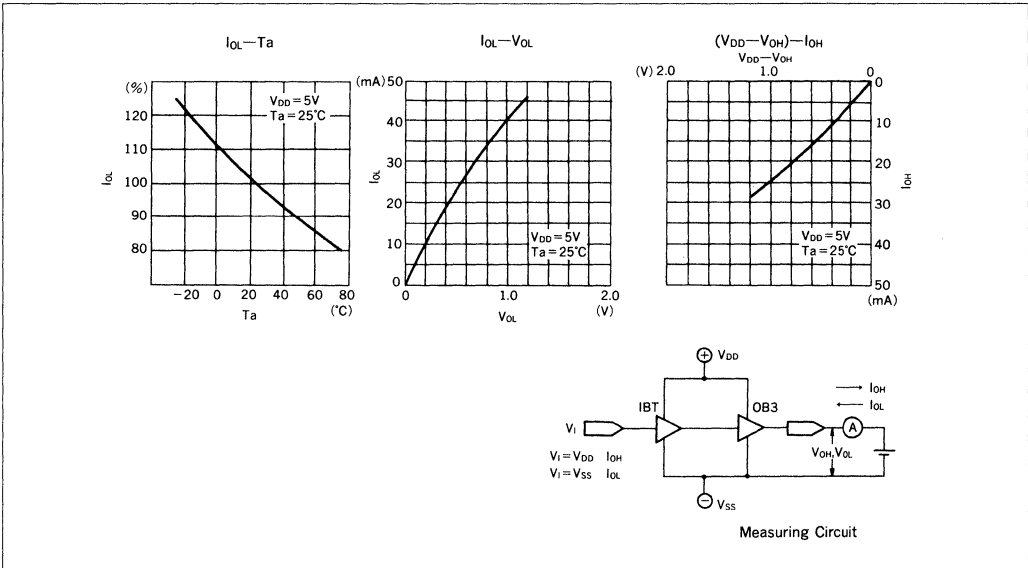
### ■ PACKAGE LIST

Series			40	44	48	60	64	72	80	84	92	100	112	120	124	132	148	160	172	180	188	192			
PADS			SSC107	SSC108	SSC109	SSC104	SSC105	SSC106	SSC107	SSC108	SSC109	SSC110	SSC111	SSC112	SSC113	SSC114	SSC115	SSC116	SSC117	SSC118	SSC119	SSC120			
Type	Pins	Name																							
Plastic DIP	16	C16	○	○																					
	18	C18	○	○																					
	24	C24	○	○	○	□	○	○	○	○	○	○													
	28	C28			○	○									○	○									
	40	C40			○	○	□					○	○												
Plastic QFP	60	F60				○	○	○	○	○	○	○	○	○	○	○	○								
	80	F80				○	○	○	○	○	○	○	○	○	○	○	○								
	100	F100-5									○	□	□	□	□	□	□								
	128	F128-8											○	□	□	□	□	○	□	○					
	144	F144-8													□	□	□	□	□	□	○	□	○	○	
160	F160-8																	○	○	○	□	○	○		
Plastic SOP	28	M28	○	○	○	○	○	○																	
PGA	64	P64												□	□	□	□	□							
	72	P72																□	□						
	88	P88						□	□	□								□	□						
	96	P96																□	□						
	120	P120																□	□						
132	P132																□	□							
PLCC	44	J44		○	○	○	○	○	○	○	○	○	○	○	○	○	○								
	68	J68			○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○					
	84	J84				○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	

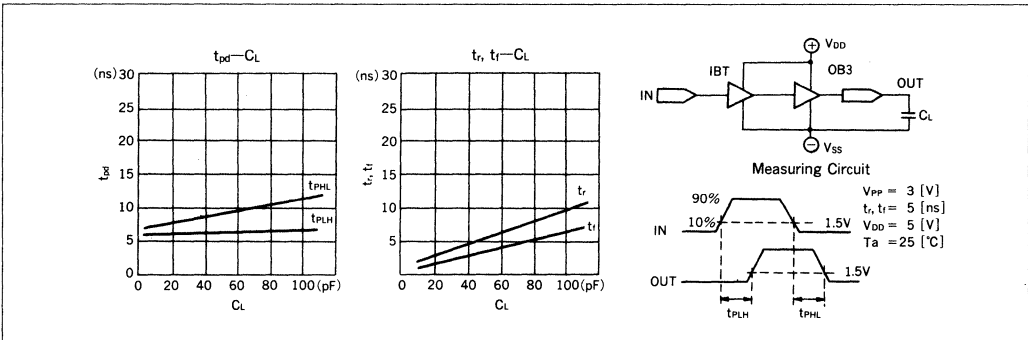
○ : Available □ : Under development

## CHARACTERISTICS CURVES

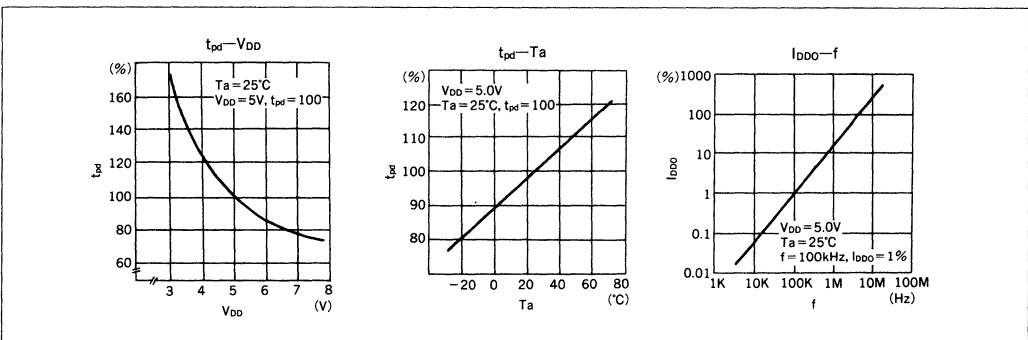
### Output Current



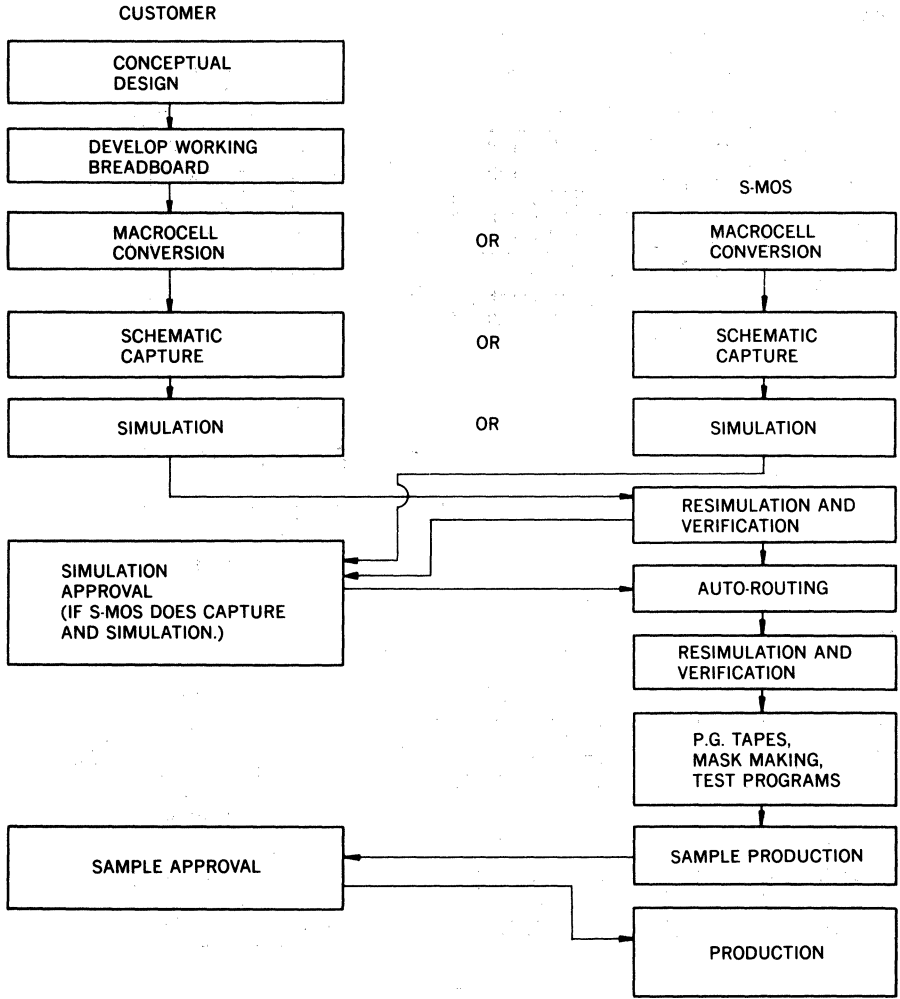
### $t_{pd}$ , $t_r$ , $t_f - C_L$

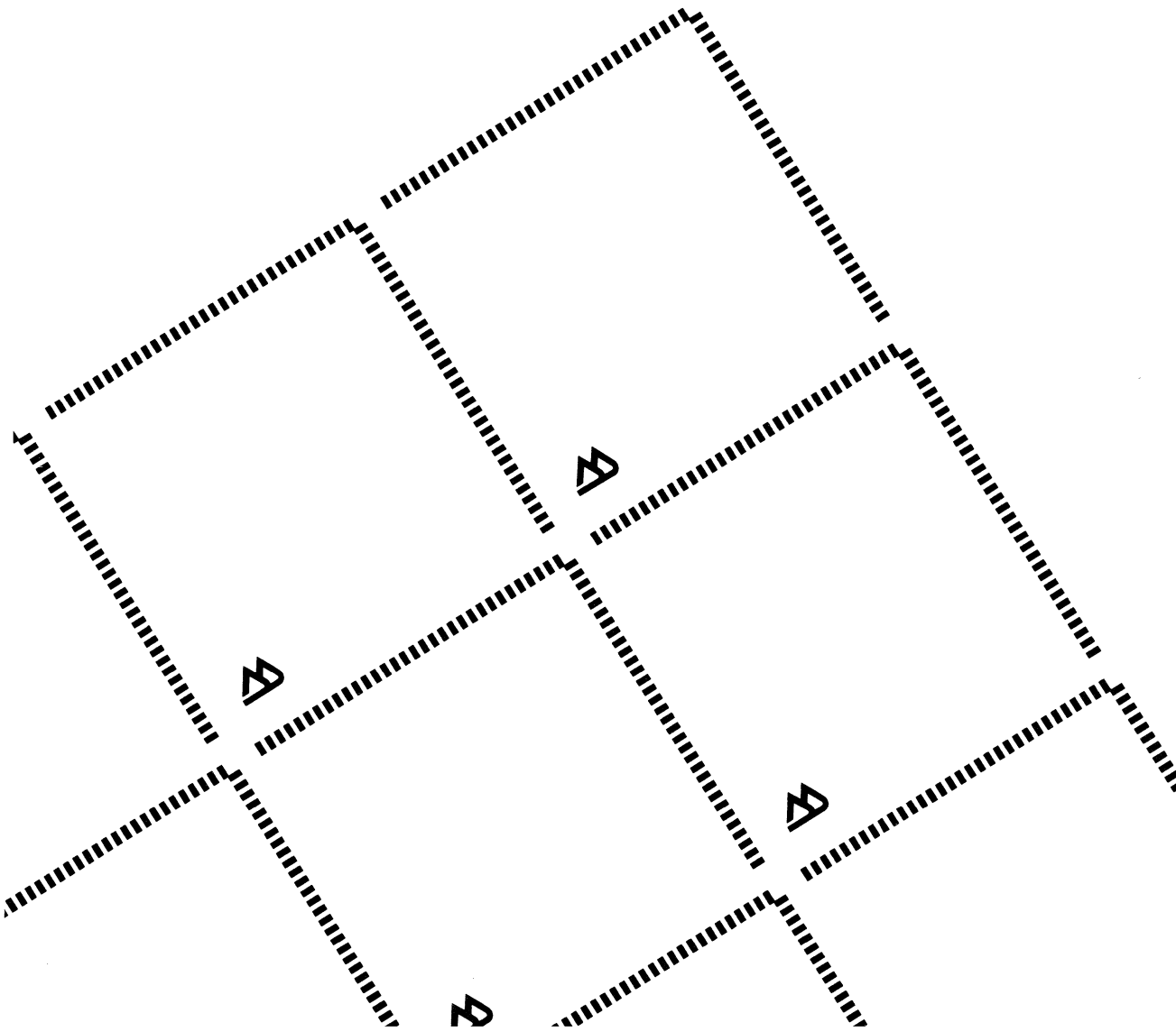


### Delay Time



■ GATE ARRAY DESIGN FLOW







# SED1180F/SED1181F

## CMOS DOT MATRIX HIGH DUTY LCD DRIVER

- 64-bit High Voltage Resistant Output
- 1/64 to 1/128 in Display Duty
- COMS High Voltage Resistant Process

### DESCRIPTION

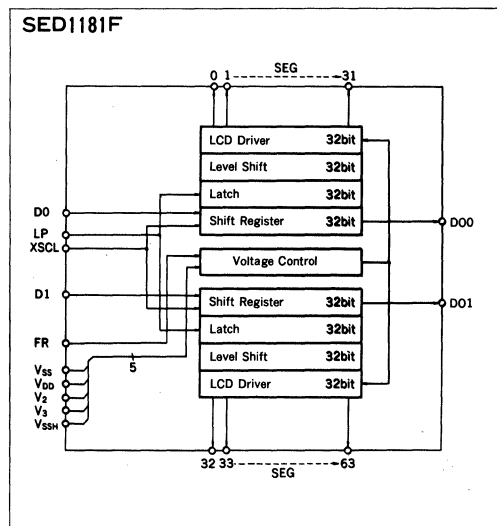
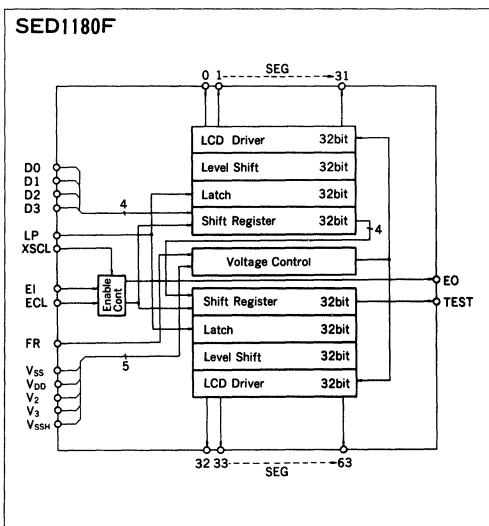
The SED1180F and SED1181F are LCD Segment drivers which are used in conjunction with the SED1190F and SED1191F (LCD common drivers).

They can drive a large dot-matrix LCD display with a duty ratio of 1/64 or higher.

### FEATURES

- Display duty ..... 1/64 to 1/128
- 64-bit high voltage resistant output, LCD driver (Segment driver)
- Rightward shift suitable for a 1/64-duty panel
- Allows cascade-connection. Dasy-chain connection of enable pins can be used to minimize power consumption. (SED1180F only)
- Power supply for the logic .....  $-5V \pm 10\%$
- CMOS high-voltage-resistant process ..... 25V (Max)
- SED1180F ..... 4-bit bus data transfer
- SED1181F ..... Independent serial data input for each 32 segment
- Package ..... 80-pin QFP (plastic)

### BLOCK DIAGRAM





## ■ PIN DESCRIPTION

### SED1180F

Pin Name	Functions
SEG0 to 63	Outputs to Segment pins of LCD Output level changes at each latch pulse LP falling-edge.
XSCL	Shift clock for displayed data Falling-edge trigger
LP	Latch pulse for displayed data Falling-edge trigger
FR	LCD display frame signal
EI	Enable input ; enabled on "H", disabled on "L"
ECL	A clock pulse for propagation of enable signals Falling-edge trigger
EO	Enable output In cascade connection, EO of nth driver is connected to EI of (n+1)-th driver.
D0 to D3	4-bit display data input
TEST	Outputs shifted data input from D3
V <sub>DD</sub> , V <sub>SS</sub>	Power supply for the logic, V <sub>DD</sub> : 0V (GND), V <sub>SS</sub> : -5.0V
V <sub>2</sub> , V <sub>3</sub> , V <sub>SSH</sub>	Power supply for driving LCD, V <sub>DD</sub> >V <sub>2</sub> >V <sub>3</sub> >V <sub>SSH</sub>

### SED1181F

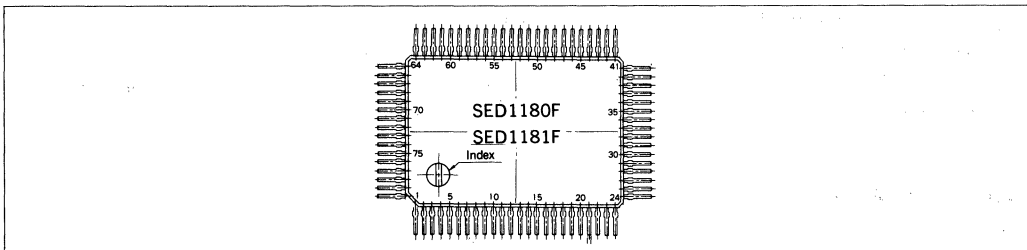
Pin Name	Functions
SEG0 to 63	Outputs to Segment pins of LCD Output level changes at each latch pulse LP falling-edge
XSCL	Shift clock for displayed data Falling-edge trigger
LP	Latch pulse for displayed data Falling-edge trigger
FR	LCD display frame signal
D00	Outputs serial display data input from D0.
DO1	Outputs serial display data input from D1.
D0, D1	Input 2-bit serial display data (Data read at a XSCL falling-edge)
V <sub>DD</sub> , V <sub>SS</sub>	Power supply for the logic, V <sub>DD</sub> : 0V (GND), V <sub>SS</sub> : -5.0V
V <sub>2</sub> , V <sub>3</sub> , V <sub>SSH</sub>	Power supply for driving LCD, V <sub>DD</sub> >V <sub>2</sub> >V <sub>3</sub> >V <sub>SSH</sub>

Note :

D0 : serial display data corresponds to SEG0 to SEG31.

D1 : serial display data corresponds to SEG32 to SEG63.

## ■ PIN CONFIGURATION



### SED1180F

No.	NAME	No.	NAME	No.	NAME	No.	NAME
1	SEG27	21	SEG 7	41	SEG36	61	SEG56
2	SEG26	22	SEG 6	42	SEG37	62	SEG57
3	SEG25	23	SEG 5	43	SEG38	63	SEG58
4	SEG24	24	SEG 4	44	SEG39	64	SEG59
5	SEG23	25	SEG 3	45	SEG40	65	SEG60
6	SEG22	26	SEG 2	46	SEG41	66	SEG61
7	SEG21	27	SEG 1	47	SEG42	67	SEG62
8	SEG20	28	SEG 0	48	SEG43	68	SEG63
9	SEG19	29	EO	49	SEG44	69	V <sub>SSH</sub>
10	SEG18	30	D3	50	SEG45	70	V <sub>2</sub>
11	SEG17	31	D2	51	SEG46	71	V <sub>3</sub>
12	SEG16	32	D1	52	SEG47	72	V <sub>SS</sub>
13	SEG15	33	D0	53	SEG48	73	V <sub>DD</sub>
14	SEG14	34	XSCL	54	SEG49	74	TEST
15	SEG13	35	LP	55	SEG50	75	EI
16	SEG12	36	FR	56	SEG51	76	ECL
17	SEG11	37	SEG32	57	SEG52	77	SEG31
18	SEG10	38	SEG33	58	SEG53	78	SEG30
19	SEG 9	39	SEG34	59	SEG54	79	SEG29
20	SEG 8	40	SEG35	60	SEG55	80	SEG28

### SED1181F

No.	NAME	No.	NAME	No.	NAME	No.	NAME
1	SEG27	21	SEG 7	41	SEG36	61	SEG56
2	SEG26	22	SEG 6	42	SEG37	62	SEG57
3	SEG25	23	SEG 5	43	SEG38	63	SEG58
4	SEG24	24	SEG 4	44	SEG39	64	SEG59
5	SEG23	25	SEG 3	45	SEG40	65	SEG60
6	SEG22	26	SEG 2	46	SEG41	66	SEG61
7	SEG21	27	SEG 1	47	SEG42	67	SEG62
8	SEG20	28	SEG 0	48	SEG43	68	SEG63
9	SEG19	29	D00	49	SEG44	69	V <sub>SSH</sub>
10	SEG18	30	NC	50	SEG45	70	V <sub>2</sub>
11	SEG17	31	NC	51	SEG46	71	V <sub>3</sub>
12	SEG16	32	D1	52	SEG47	72	V <sub>SS</sub>
13	SEG15	33	D0	53	SEG48	73	V <sub>DD</sub>
14	SEG14	34	XSCL	54	SEG49	74	DO1
15	SEG13	35	LP	55	SEG50	75	NC
16	SEG12	36	FR	56	SEG51	76	NC
17	SEG11	37	SEG32	57	SEG52	77	SEG31
18	SEG10	38	SEG33	58	SEG53	78	SEG30
19	SEG 9	39	SEG34	59	SEG54	79	SEG29
20	SEG 8	40	SEG35	60	SEG55	80	SEG28

## ■ ABSOLUTE MAXIMUM RATINGS

( $V_{DD}=0V$ )

Parameter	Symbol	Ratings	Unit
Supply voltage (1)	$V_{SS}$	-7.0 to 0.3	V
Supply voltage (2)	$V_{SSH}$	-28.0 to 0.3	V
	$V_2, V_3$		
Input voltage	$V_I$	$V_{SS}-0.3$ to 0.3	V
Operating temperature	$T_{opr}$	-20 to 75	°C
Storage temperature	$T_{stg}$	-65 to 150	°C
Soldering temperature and time	$T_{sol}$	260°C · 10s (at lead)	—

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

( $V_{DD}=0V, V_{SS}=-5V \pm 10\%, T_a=-20$  to  $75^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit		
Supply voltage (1)	$V_{SS}$		-5.5	-5.0	-4.5	V		
Supply voltage (2)	$V_2$		$V_{SSH}$	—	$V_{DD}$	V		
	$V_3$		$V_{SSH}$	—	$V_{DD}$	V		
	$V_{SSH}$	Recommended $V_{SSH}$	-25.0	—	-14.0	V		
		Operable $V_{SSH}$ *	-25.0	—	-5.0	V		
High level input voltage	$V_{IH}$		0.2 $V_{SS}$	—	$V_{DD}+0.3$	V		
Low level input voltage	$V_{IL}$		$V_{SS}-0.3$	—	0.8 $V_{SS}$	V		
High level output voltage	$V_{OH}$	$I_{OH} = -0.6mA$	-0.4	—	—	V		
Low level output voltage	$V_{OL}$	$I_{OL} = 0.6mA$	—	—	$V_{SS}+0.4$	V		
Input leak current	$I_{LI}$	$0V \leq V_I \leq V_{SS}$	—	0.05	2.0	$\mu A$		
Output leak current	$I_{LO}$	$0V \leq V_O \leq V_{SS}$	—	0.05	5.0	$\mu A$		
Shift clock	XSCL		—	—	6.0	MHz		
Frame signal	FR		—	1/60	—	s		
Input capacitance	$C_I$	$T_a = 25^\circ C$	—	5.0	8.0	pF		
Segment output on resistance	$R_{SEG}$	$V_{OH} = V_{DD} - 0.5V$ $V_{OL} = V_{SSH} + 0.5V$ SEG /bit	$V_{SSH} = -20.0V$	—	1.9	2.9	k $\Omega$	
			$V_{SSH} = -14.0V$	—	2.4	3.9		
			$V_{SSH} = -9.0V$	—	3.6	7.0		
			$V_{SSH} = -5.0V$	—	11.5	500.0		
Quiescent current	$I_Q$	$V_{SSH} = -25V, V_{SS} = -5.5V$ $V_I = V_{DD}$	—	0.05	30	$\mu A$		
Operating current for the logic	$I_{SSO}$	SED 1180	FR cycle = 16.7ms ECL cycle = 13 $\mu s$	$V_{SS} = -5.0V$ $V_{IH} = V_{DD}, V_{IL} = V_{SS}$ LP cycle = 130 $\mu s$ XSCL = 1.5MHz (duty50%)	—	90	200	$\mu A$
		SED 1181	FR cycle = 130 $\mu s$ (duty50%)	All data input reversed bit by bit. All output pins are opened.	—	850	1200	
Operating current for LCD	$I_{SSHO}$	SED 1180	FR cycle = 16.7ms ECL cycle = 13 $\mu s$	$V_{SS} = -4.5V, V_2 = -4.0V$ $V_3 = -16.0V, V_{SSH} = -20.0V$ $V_{IH} = V_{DD}, V_{IL} = V_{SS}$ LP cycle = 130 $\mu s$ XSCL = 1.5MHz (duty50%)	—	40	80	$\mu A$
		SED 1181	FR cycle = 130 $\mu s$ (duty50%)	All data input reversed bit by bit. All output pins are opened.	—	70	100	

\* Operable  $V_{SSH}$  indicates its functionally operable range although the driver output ON resistance becomes higher than with recommended  $V_{SSH}$ .

To determine the voltage, we recommend to test the driver with a liquid crystal panel.

●AC Electrical Characteristics

( $V_{DD}=0V$ ,  $V_{SS}=-5.0V \pm 10\%$ ,  $T_a=-20$  to  $75^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Shift clock cycle	$t_{CLC}$		166	—	—	ns
Shift clock "H" width	$t_{WCLH}$		63	—	—	ns
Shift clock "L" width	$t_{WCLL}$		63	—	—	ns
Data setup time	$t_{DS}$		50	—	—	ns
Data hold time	$t_{DH}$		30	—	—	ns
Enable clock "H" width	$t_{WECH}$	*3	100	—	—	ns
Enable clock "L" width	$t_{WECL}$	*3	100	—	—	ns
Enable data setup time	$t_{EDS}$	*3	50	—	—	ns
Enable data hold time	$t_{EDH}$	*3	20	—	—	ns
Enable clock delay time	$t_{EDR}$	*3	-10	—	—	ns
Enable clock setup time	$t_{ECS}$	*3	70	—	—	ns
Latch pulse "H" width	$t_{WLPH}$	*1	110	—	—	ns
Latch pulse "L" width	$t_{WLPL}$		220	—	—	ns
Latch timing	$t_{LT}$		100	—	—	ns
Latch hold time	$t_{LH}$		0	—	—	ns
Latch pulse data setup time	$t_{LDS}$	*2, *3	140	—	—	ns
Latch pulse data hold time	$t_{LDH}$	*2, *3	50	—	—	ns
Permissible frame signal delay	$t_{DFR}$		-500	—	500	ns
Input signal rise time	$t_r$		—	—	*4	
Input signal fall time	$t_f$		—	—	*4	
Enable output delay	$t_{PD}$	*3	20	—	150	ns
Serial data output delay	$t_{PO}$		20	—	150	ns

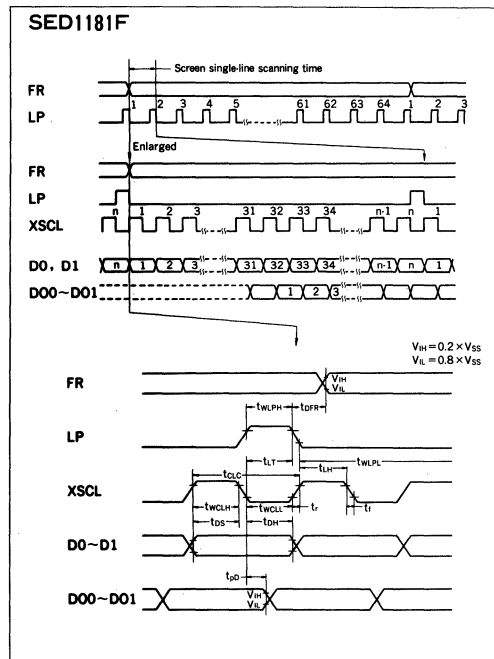
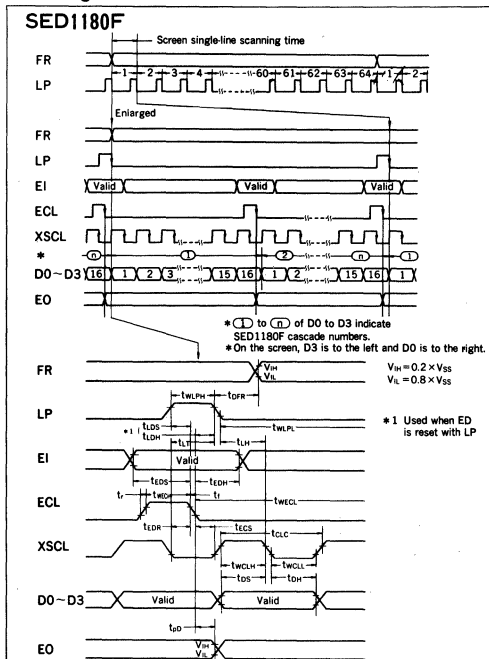
\*1  $t_{WLPH}=160ns$  (Min) when LP is used as EI data.

\*2  $t_{WLPH}=250ns$  (Min) when EO output is reset with LP. ( $t_r=t_f=25ns$ )

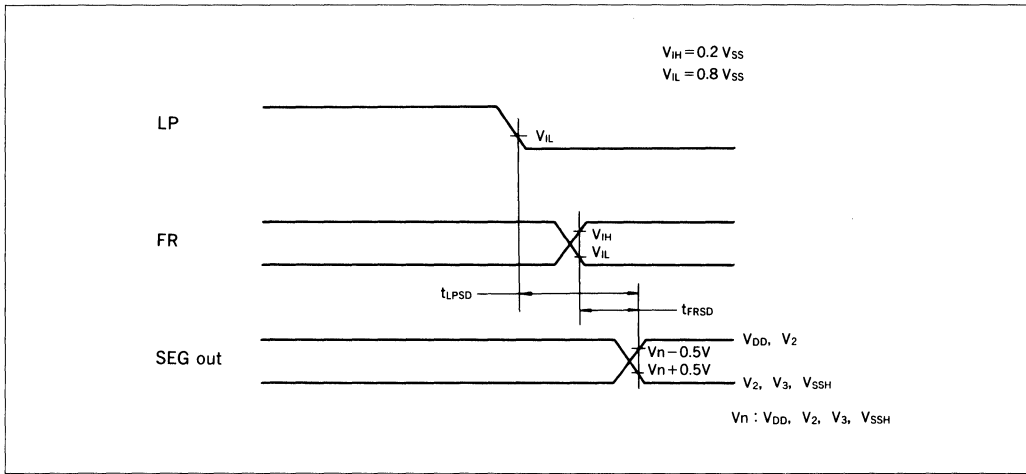
\*3 Applicable to SED1180F only.

\*4  $t_r, t_f < (t_{CLC} - t_{WCLH} - t_{WCLL})/2$ , where  $t_r, t_f \leq 50ns$ .

●Timing Chart



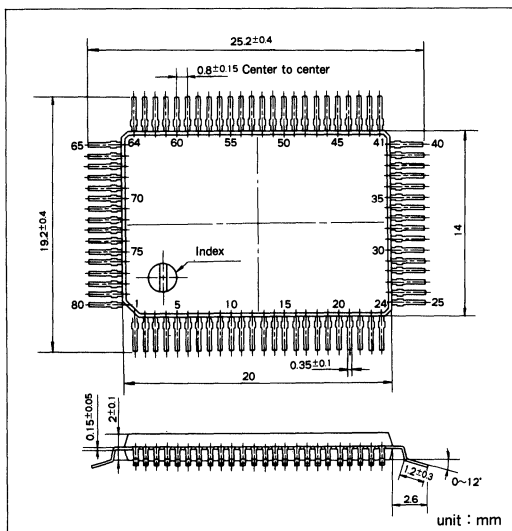
### ●SEG Output Signal Timing Characteristics



( $V_{DD} = 0V$ ,  $V_{SS} = -5V \pm 10\%$ ,  $T_a = -20$  to  $75^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
LP-SEG output delay time	$t_{LPSD}$	$V_{SSH} = -14.0$ to $-25.0V$ $C_L = 100pF$	—	—	4.5	$\mu s$
FR-SEG output delay time	$t_{FRSD}$		—	—	4.5	$\mu s$

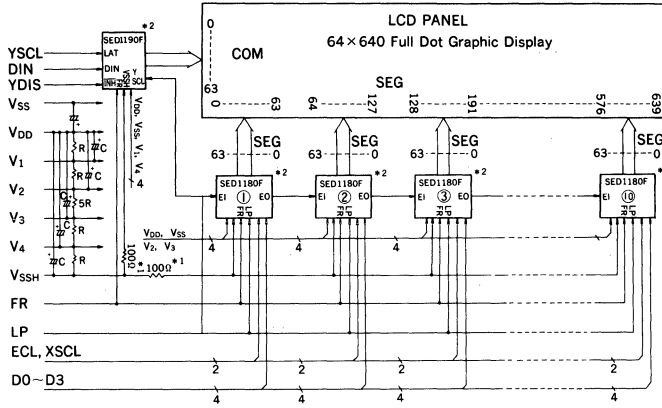
### ■PACKAGE DIMENSIONS



\* Drawing is applicable to SED1180F<sub>0A</sub>/SED1181F<sub>0B</sub>.  
 \* SED1180F<sub>5A</sub>/SED1181F<sub>5A</sub> are 2.7mm thick.

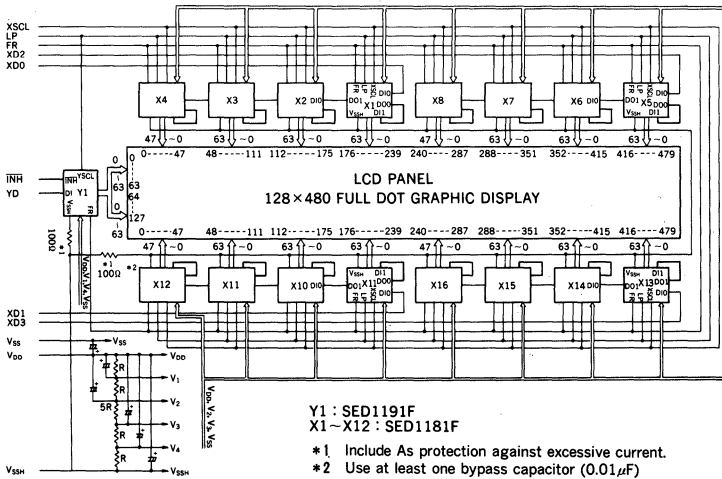
EXAMPLE OF APPLICATION

SED1180F (64×640 dot, 1/64 duty, 1/9 bias)



- \*1 Use to protect against excessive current.
- \*2 Use at least one bypass capacitor (0.01μF) Near V<sub>SS</sub> and V<sub>SSH</sub> of each driver LSI to improve noise immunity.

SED1181F (128×480 dot, 1/64 duty, 1/9 bias)



- Y1 : SED1191F
- X1~X12 : SED1181F
- \*1 Include As protection against excessive current.
- \*2 Use at least one bypass capacitor (0.01μF) Near V<sub>SS</sub> and V<sub>SSH</sub> of each driver LSI to improve noise immunity.

# SED1190F/SED1191F

## CMOS DOT MATRIX HIGH DUTY LCD DRIVER

- 64-bit High Voltage Resistant Output
- 1/64 to 1/128 in Display Duty
- CMOS High Voltage Resistant Process

### DESCRIPTION

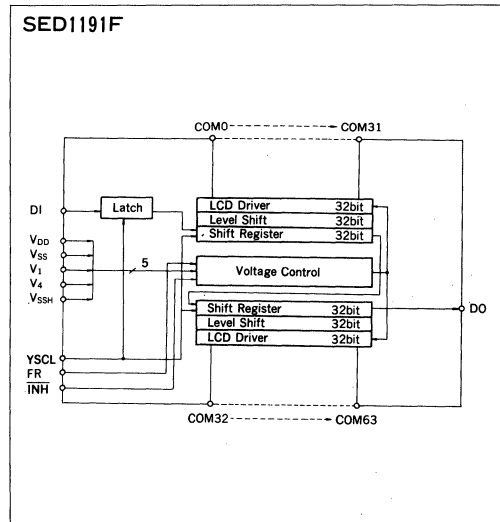
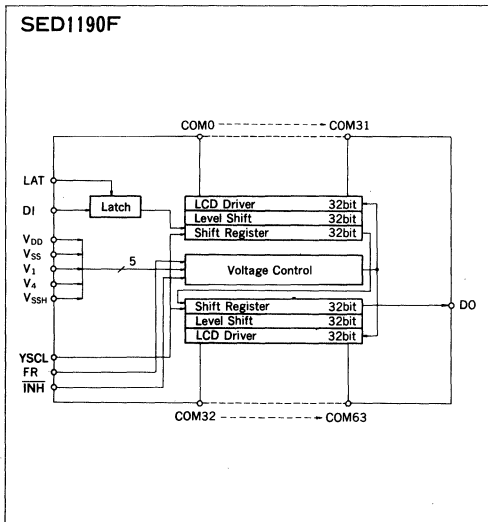
The SED1190F and SED1191F are LCD Common drivers which are used in conjunction with SED1180F and SED1181F (LCD Segment drivers).

They can drive a large dot-matrix LCD display with a duty ratio of 1/64 or higher.

### FEATURES

- Display duty .....1/64 to 1/128
- Provides inhibit function for instantaneous display blanking
- 64-bit high-voltage resistant output, LCD driver (Common driver)
- Rightward shift suitable for a 1/64-duty LCD panel
- Cascade-connection makes high duty drive possible
- Power supply for the logic .....5V ±10%
- CMOS high-voltage-resistant process .....25V (Max)
- Connectable to a general purpose LCD controller (SED1191F only)
- Provides for data read and data shift by a single clock
- Package .....80-pin QFP (plastic)

### BLOCK DIAGRAM



## PIN DESCRIPTION

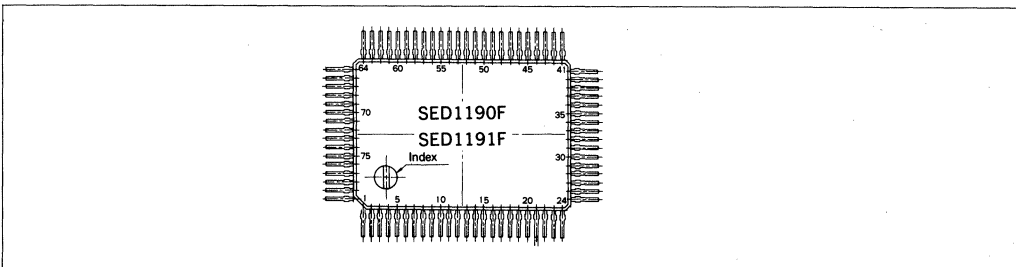
### SED1190F

Pin Name	Functions
COM0 to 63	Outputs to Common pins of LCD Output level changes at each shift clock YSCL falling-edge.
LAT	The latch pulse input for the shift data DI is pulled up internally. Normally used in the opened state.
YSCL	Serial data shift clock, Falling edge trigger
FR	LCD display frame signal
DI	Serial shift data input
INH	A control signal which turns all Common outputs to a non-selectable waveform. "L" active
DO	Serial shift data output Outputs serial data at shift clock falling-edge.
V <sub>DD</sub> , V <sub>SS</sub>	Power supply for the logic, V <sub>DD</sub> : 0V, V <sub>SS</sub> : -5.0V
V <sub>1</sub> , V <sub>4</sub> , V <sub>SSH</sub>	Power supply for driving LCD, V <sub>DD</sub> >V <sub>1</sub> >V <sub>4</sub> >V <sub>SSH</sub>

### SED1191F

Pin Name	Functions
COM0 to 63	Outputs to Common pins of LCD Output level changes at each shift clock YSCL falling-edge.
YSCL	Serial data shift clock, Falling edge trigger
FR	LCD display frame signal
DI	Serial shift data input Reads data at each YSCL rising edge.
INH	A control signal which turns all common outputs to a non-selectable waveform. "L" active
DO	Serial shift data output Outputs serial data in sync with shift clock falling-edge.
V <sub>DD</sub> , V <sub>SS</sub>	Power supply for the logic, V <sub>DD</sub> : 0V, V <sub>SS</sub> : -5.0V
V <sub>1</sub> , V <sub>4</sub> , V <sub>SSH</sub>	Power supply for driving LCD, V <sub>DD</sub> >V <sub>1</sub> >V <sub>4</sub> >V <sub>SSH</sub>

## PIN CONFIGURATION



### SED1190F

No.	NAME	No.	NAME	No.	NAME	No.	NAME
1	COM31	21	COM11	41	COM40	61	COM60
2	COM30	22	COM10	42	COM41	62	COM61
3	COM29	23	COM 9	43	COM42	63	COM62
4	COM28	24	COM 8	44	COM43	64	COM63
5	COM27	25	COM 7	45	COM44	65	DO
6	COM26	26	COM 6	46	COM45	66	V <sub>SSH</sub>
7	COM25	27	COM 5	47	COM46	67	V <sub>4</sub>
8	COM24	28	COM 4	48	COM47	68	NC
9	COM23	29	COM 3	49	COM48	69	NC
10	COM22	30	COM 2	50	COM49	70	NC
11	COM21	31	COM 1	51	COM50	71	NC
12	COM20	32	COM 0	52	COM51	72	V <sub>1</sub>
13	COM19	33	COM32	53	COM52	73	V <sub>SS</sub>
14	COM18	34	COM33	54	COM53	74	V <sub>DD</sub>
15	COM17	35	COM34	55	COM54	75	NC
16	COM16	36	COM35	56	COM55	76	DI
17	COM15	37	COM36	57	COM56	77	LAT
18	COM14	38	COM37	58	COM57	78	INH
19	COM13	39	COM38	59	COM58	79	FR
20	COM12	40	COM39	60	COM59	80	YSCL

### SED1191F

No.	NAME	No.	NAME	No.	NAME	No.	NAME
1	COM31	21	COM11	41	COM40	61	COM60
2	COM30	22	COM10	42	COM41	62	COM61
3	COM29	23	COM 9	43	COM42	63	COM62
4	COM28	24	COM 8	44	COM43	64	COM63
5	COM27	25	COM 7	45	COM44	65	DO
6	COM26	26	COM 6	46	COM45	66	V <sub>SSH</sub>
7	COM25	27	COM 5	47	COM46	67	V <sub>4</sub>
8	COM24	28	COM 4	48	COM47	68	NC
9	COM23	29	COM 3	49	COM48	69	NC
10	COM22	30	COM 2	50	COM49	70	NC
11	COM21	31	COM 1	51	COM50	71	NC
12	COM20	32	COM 0	52	COM51	72	V <sub>1</sub>
13	COM19	33	COM32	53	COM52	73	V <sub>SS</sub>
14	COM18	34	COM33	54	COM53	74	V <sub>DD</sub>
15	COM17	35	COM34	55	COM54	75	NC
16	COM16	36	COM35	56	COM55	76	DI
17	COM15	37	COM36	57	COM56	77	YSCL
18	COM14	38	COM37	58	COM57	78	INH
19	COM13	39	COM38	59	COM58	79	FR
20	COM12	40	COM39	60	COM59	80	NC

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>DD</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage (1)	V <sub>SS</sub>	-7.0 to 0.3	V
Supply voltage (2)	V <sub>SSH</sub>	-28.0 to 0.3	V
	V <sub>I</sub> , V <sub>4</sub>		
Input voltage	V <sub>I</sub>	V <sub>SS</sub> -0.3 to 0.3	V
Operating temperature	T <sub>opr</sub>	-20 to 75	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C · 10s (at lead)	—

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

(V<sub>DD</sub>=0V, V<sub>SS</sub>=-5V±10%, T<sub>a</sub>=-20 to 75°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit	
Supply voltage (1)	V <sub>SS</sub>		-5.5	-5.0	-4.5	V	
Supply voltage (2)	V <sub>I</sub>		V <sub>SSH</sub>	—	V <sub>DD</sub>	V	
	V <sub>4</sub>		V <sub>SSH</sub>	—	V <sub>DD</sub>	V	
	V <sub>SSH</sub>	Recommended V <sub>SSH</sub>	-25.0	—	-14.0	V	
Operable V <sub>SSH</sub> *		-25.0	—	-5.0	V		
High level input voltage	V <sub>IH</sub>		0.2V <sub>SS</sub>	—	V <sub>DD</sub> +0.3	V	
Low level input voltage	V <sub>IL</sub>		V <sub>SS</sub> -0.3	—	0.8V <sub>SS</sub>	V	
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> =-0.6mA	-0.4	—	—	V	
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> =0.6mA	—	—	V <sub>SS</sub> +0.4	V	
Input leak current	I <sub>LI</sub>	0V≧V <sub>I</sub> ≧V <sub>SS</sub>	—	0.05	2.0	μA	
Output leak current	I <sub>LO</sub>	0V≧V <sub>O</sub> ≧V <sub>SS</sub>	—	0.05	5.0	μA	
Shift clock	YSCL		—	—	2.5	MHz	
Frame signal	FR		—	1/60	—	s	
Input capacitance	C <sub>I</sub>	T <sub>a</sub> =25°C	—	5.0	8.0	pF	
Common output on resistance	R <sub>COM</sub>	V <sub>OH</sub> =V <sub>DD</sub> -0.5V V <sub>OL</sub> =V <sub>SSH</sub> -0.5V COM/bit	V <sub>SSH</sub> =-20.0V	—	0.8	1.0	kΩ
			V <sub>SSH</sub> =-14.0V	—	0.9	1.3	
			V <sub>SSH</sub> =-9.0V	—	1.3	2.0	
			V <sub>SSH</sub> =-5.0V	—	3.0	30.0	
Quiescent current	I <sub>Q</sub>	SED1190 V <sub>SSH</sub> =-25.0V	V <sub>SS</sub> =-5.5V	—	0.05	30	μA
		SED1191 V <sub>SSH</sub> =-25.0V	V <sub>I</sub> =V <sub>DD</sub>	—	—	—	
Operating current for the logic	I <sub>SSO</sub>	SED1190 FR cycle=16.7ms	V <sub>SS</sub> =-5.0V V <sub>IH</sub> =V <sub>DD</sub> , V <sub>IL</sub> =V <sub>SS</sub> YSCL cycle=130μs (duty 50%)	—	3.0	8.0	μA
		SED1191 FR cycle=130μs	All "H" output. Output terminals are opened at every data input of 1/128 duty.	—	850	1200	
Operating current for LCD	I <sub>SSHO</sub>	SED1190 FR cycle=16.7ms	V <sub>SS</sub> =-4.5V, V <sub>I</sub> =-2.0V V <sub>I</sub> =-18.0V, V <sub>SSH</sub> =-20.0V YSCL cycle=130μs (duty 50%)	—	3.0	8.0	μA
		SED1191 FR cycle=130μs	All "H" output. Output terminals are opened at every data input of 1/128 duty.	—	70	100	
Pull up MOS current (applicable to SED1190 only)	-I <sub>p</sub>	V <sub>SS</sub> =-5.0V, V <sub>IL</sub> =-5.0V Applicable to LAT input terminals	10.0	25.0	50.0	μA	

\* Operable V<sub>SSH</sub> indicates its functionally operable range although the driver output on resistance becomes higher than with recommended V<sub>SSH</sub>.  
To determine the voltage, we recommend to test the driver with a liquid crystal panel.



● AC Electrical Characteristics

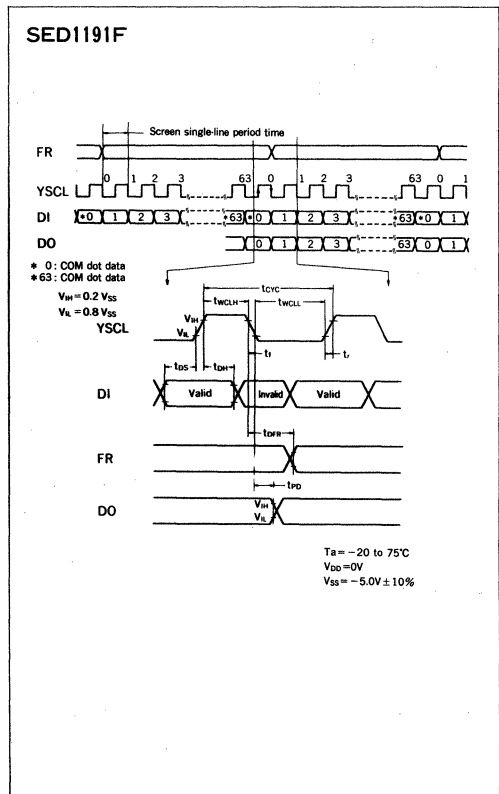
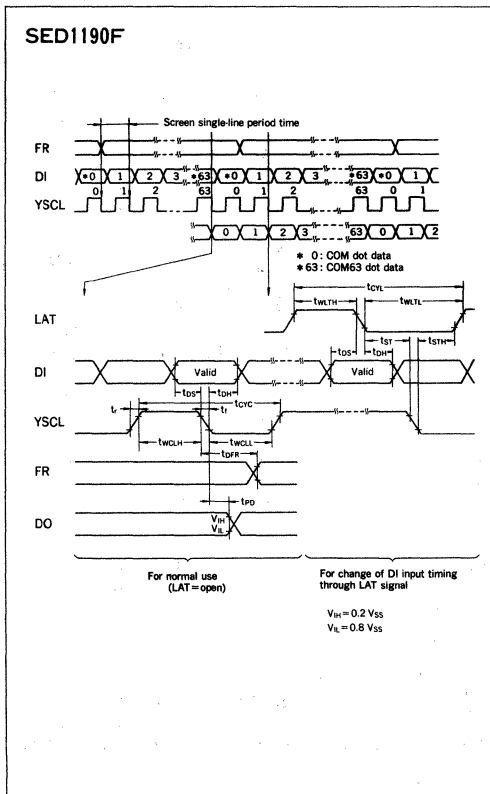
( $V_{DD}=0V$ ,  $V_{SS}=-5V \pm 10\%$ ,  $T_a=-20$  to  $75^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Latch pulse cycle time	$t_{CYL}$		400	—	—	ns
Latch pulse "H" width*1	$t_{WLTH}$		180	—	—	ns
Latch pulse "L" width*1	$t_{WLTl}$		180	—	—	ns
Shift lock cycle time	$t_{CYC}$		400	—	—	ns
Shift lock "H" width	$t_{WCLH}$		110	—	—	ns
Shift lock "L" width	$t_{WCLL}$		110(240)	—	—	ns
Data setup time	$t_{DS}$		100(70)	—	—	ns
Data hold time	$t_{DH}$		30	—	—	ns
Data shift timing*1	$t_{ST}$		0	—	—	ns
Data shift hold time*1	$t_{STH}$		125	—	—	ns
Permissible frame signal delay	$t_{DFR}$		-500	0	500	ns
Input signal rise time	$t_r$		—	—	*2	ns
Input signal fall time	$t_f$		—	—	*2	ns
Data output delay time	$t_{pD}$	$C_L=15pF$	30	—	170	ns

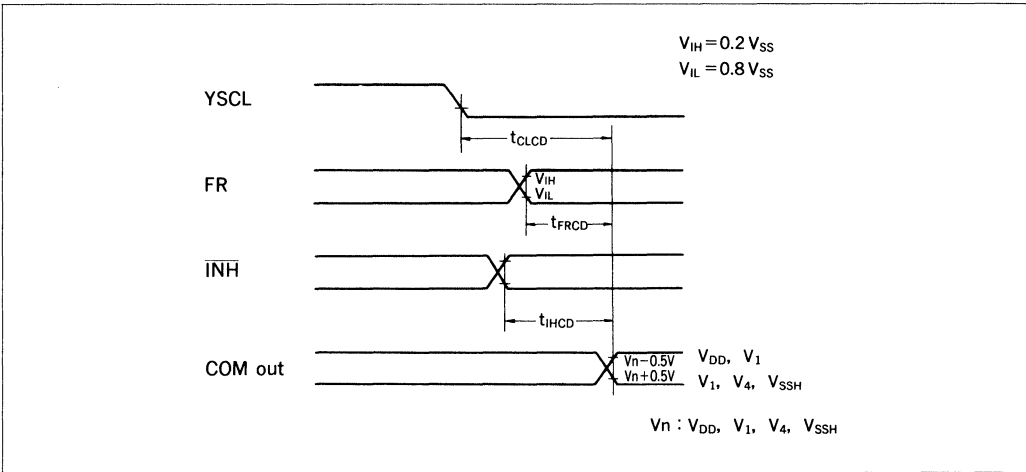
\*1 Applicable to SED1190F only. Values in parenthesis are for SED1191F.

\*2  $t_r, t_f=(t_{CYL}-t_{WLH}-t_{WLTl})/2$ , where  $t_r, t_f \leq 50ns$ .

● Timing Chart



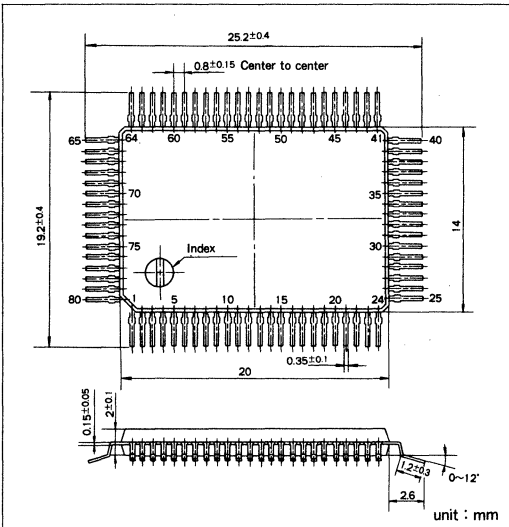
### ●COM Output Signal Timing Characteristics



( $V_{DD} = 0V$ ,  $V_{SS} = -5V \pm 10\%$ ,  $T_a = -20$  to  $75^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
YSCL-COM output delay time	$t_{CLCD}$	$V_{SSH} = -14.0$ to $-25.0V$ $C_L = 100pF$	—	—	3.0	$\mu S$
RF-COM output delay time	$t_{FRCD}$		—	—	3.0	$\mu S$
INH-COM output delay time	$t_{IHCD}$		—	—	3.0	$\mu S$

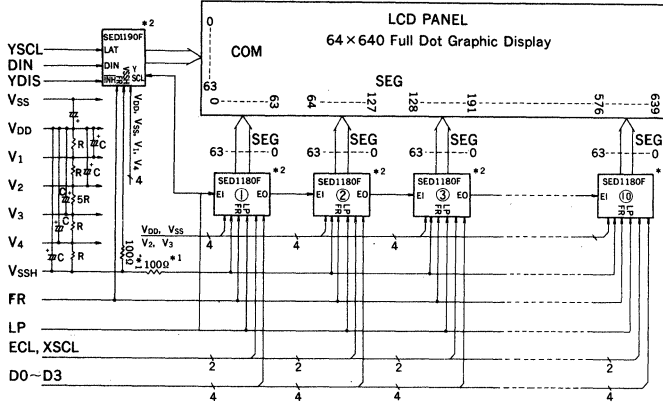
### ■PACKAGE DIMENSIONS



\*Drawing is applicable to SED1190F<sub>0A</sub>/SED1191F<sub>0B</sub>.  
 \*SED1190F<sub>6A</sub>/SED1191F<sub>6B</sub> are 2.7mm thick.

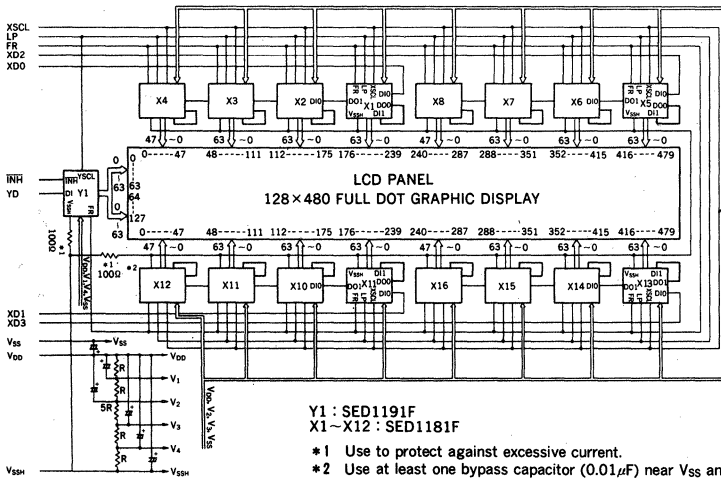
EXAMPLE OF APPLICATION

SED1190F (64×640 dots, 1/64 duty, 1/9 bias)



- \*1 Use to protect against excessive current.
- \*2 Use at least one bypass capacitor (0.01μF) near VSS and VSSH of each driver LSI to improve noise immunity.

SED1191F (128×480 dots, 1/64 duty, 1/9 bias)



- Y1 : SED1191F  
 X1~X12 : SED1181F
- \*1 Use to protect against excessive current.
  - \*2 Use at least one bypass capacitor (0.01μF) near VSS and VSSH of each driver LSI to improve noise immunity.

# SED1600F

## CMOS DOT MATRIX HIGH DUTY LCD DRIVER

- 80-bit High Voltage Resistant Output
- 1/100 to 1/300 in Display Duty
- CMOS High Voltage Resistant Process

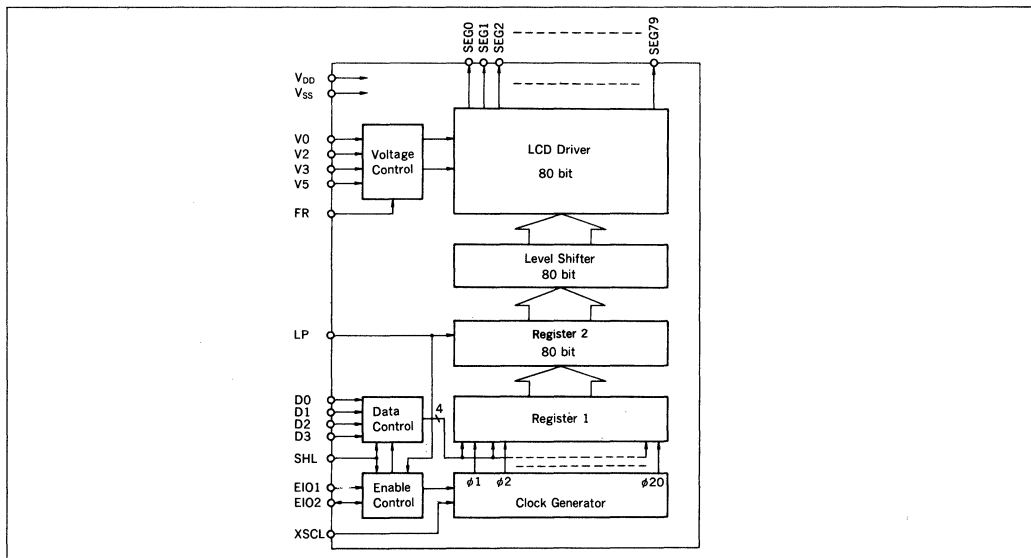
### DESCRIPTION

The SED1600F is an 80 output segment (column) driver, used to driver large-capacity dot matrix LCD panels with a duty ratio of 1/300 (from 1/100). It is used in conjunction with the SED1610F or SED1630F common (row) drivers. The SED1600F has a wide range of drive voltages. The maximum voltage  $V_0$  is isolated from  $V_{DD}$  to enable the application of any external LCD driving bias voltage from outside to the SED1600F. These unique features enable the SED1600F to operate with a wide variety of LCD panels. The SED1600F requires no enable signal to implement an enable chain technology which provides low power dissipation. This offers simpler interface with the LCD controller SED1330F/SED1341F or a microprocessor.

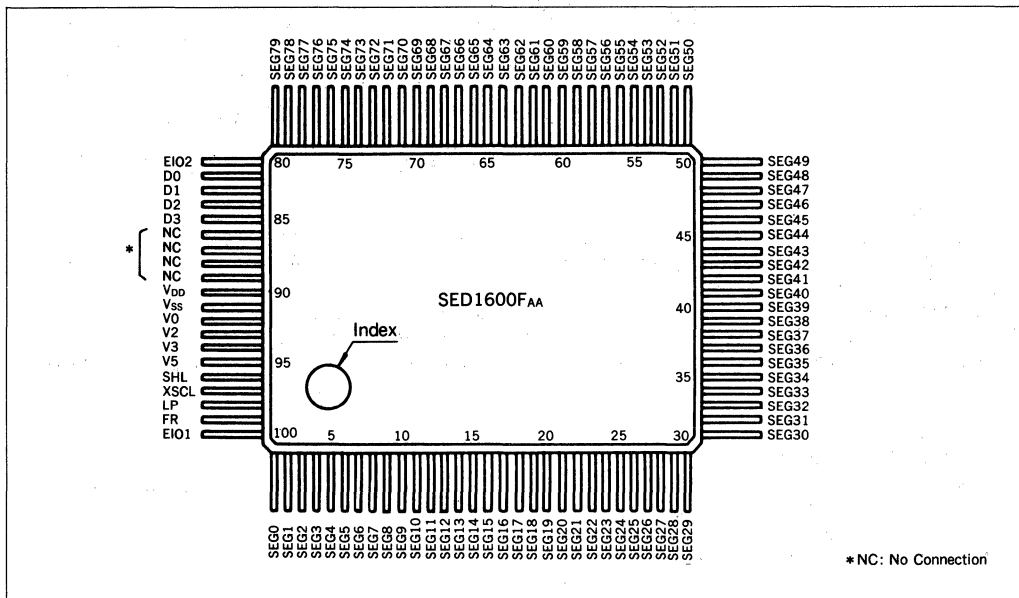
### FEATURES

- 80 LCD driving outputs
- Display capacity .....  $640 \times 200 \times 3$  dots when combined with SED1610F (SED1630F)
- Wide range of LCD driving voltages ..... 12 to 28V  
(Absolute maximum voltage ..... 30V)
- High-speed, low-power data transfer by 4-bit bus enable chain technology  
Shift clock ..... 6MHz Max
- Enable auto-transfer function to allow cascade connection and low power dissipation (requiring no enable signal to be furnished by a controller)
- Output shift direction pin selectable
- Ability to adjust offset bias of LCD source from  $V_{DD}$
- Power supply for the logic .....  $-5V \pm 10\%$
- Si gate CMOS process
- Package ..... 100-pin QFP (plastic)

### BLOCK DIAGRAM



## PIN CONFIGURATION



## PIN DESCRIPTION

Pin name	I/O	Functions																																																												
SEG0 to SEG79	O	LCD driving segment (column) outputs. Each output changes at the falling edge of LP.																																																												
D0 to D3	I	Display data inputs.																																																												
XSCL	I	Shift clock of display data (falling edge trigger).																																																												
LP	I	Latch pulse of display data (falling edge trigger).																																																												
EIO1, EIO2	I/O	Enable I/O, which is controlled by SHL input. Output is reset by LP, and automatically falls when 80 bits of data are taken in.																																																												
SHL	I	Shift direction selection and EIO pin I/O control. When data (a, b, c, d) (e, f, g, h).....(w, x, y, z) are input to pins (D3, D2, D1, D0) respectively, the following relation is established between the data and segment outputs: <table border="1" style="margin-left: 20px;"> <thead> <tr> <th rowspan="2">SHL</th> <th colspan="8">SEG</th> <th colspan="4">EIO</th> </tr> <tr> <th>79</th> <th>78</th> <th>77</th> <th>76</th> <th>75</th> <th>74</th> <th>73</th> <th>72</th> <th>.....</th> <th>3</th> <th>2</th> <th>1</th> <th>0</th> <th>1</th> <th>2</th> </tr> </thead> <tbody> <tr> <td>L</td> <td>a</td> <td>b</td> <td>c</td> <td>d</td> <td>e</td> <td>f</td> <td>g</td> <td>h</td> <td>.....</td> <td>w</td> <td>x</td> <td>y</td> <td>z</td> <td>Output</td> <td>Input</td> </tr> <tr> <td>H</td> <td>z</td> <td>y</td> <td>x</td> <td>w</td> <td>v</td> <td>u</td> <td>t</td> <td>s</td> <td>.....</td> <td>d</td> <td>c</td> <td>b</td> <td>a</td> <td>Input</td> <td>Output</td> </tr> </tbody> </table>	SHL	SEG								EIO				79	78	77	76	75	74	73	72	.....	3	2	1	0	1	2	L	a	b	c	d	e	f	g	h	.....	w	x	y	z	Output	Input	H	z	y	x	w	v	u	t	s	.....	d	c	b	a	Input	Output
SHL	SEG								EIO																																																					
	79	78	77	76	75	74	73	72	.....	3	2	1	0	1	2																																															
L	a	b	c	d	e	f	g	h	.....	w	x	y	z	Output	Input																																															
H	z	y	x	w	v	u	t	s	.....	d	c	b	a	Input	Output																																															
FR	I	AC signal of LCD driving outputs.																																																												
V <sub>DD</sub> , V <sub>SS</sub>	Power supplies	Logic circuit power. V <sub>DD</sub> : 0V (GND) V <sub>SS</sub> : -5.0V																																																												
V <sub>0</sub> , V <sub>2</sub> , V <sub>3</sub> , V <sub>5</sub>	Power supplies	LCD driving power. V <sub>5</sub> : -12 to -28V V <sub>DD</sub> ≥ V <sub>0</sub> ≥ V <sub>2</sub> > V <sub>3</sub> ≥ V <sub>5</sub>																																																												

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>DD</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage (1)	V <sub>SS</sub>	-7.0 to +0.3	V
Supply voltage (2)	V5	-30.0 to +0.3	V
Supply voltage (2)	V0, V2, V3*	V5 - 0.3 to +0.3	V
Input voltage (1)	V <sub>I</sub>	V <sub>SS</sub> - 0.3 to +0.3	V
Output voltage (1)	V <sub>O</sub>	V <sub>SS</sub> - 0.3 to +0.3	V
Output current (1)	I <sub>O</sub>	20	mA
Output current (2)	I <sub>OSEG</sub>	20	mA
Allowable power dissipation	P <sub>D</sub>	300	mW
Operating temperature	T <sub>opr</sub>	-20 to +75	°C
Storage temperature	T <sub>stg</sub>	-65 to +150	°C
Soldering temperature*time	T <sub>sol</sub>	260°C, 10s (at lead)	—

\*V0, V2 and V3 must always satisfy the condition: V<sub>DD</sub> ≥ V0 ≥ V2 ≥ V3 ≥ V5.

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

(Unless otherwise specified, V<sub>DD</sub> = V0 = 0V, V<sub>SS</sub> = -5.0V ± 10%, and Ta = -20 to 75°C)

Parameter	Symbol	Conditions	Pin	Min	Typ	Max	Unit		
Operating voltage (1)	V <sub>SS</sub>		V <sub>SS</sub>	-5.5	-5.0	-4.5	V		
Recommended operating voltage Minimum operating voltage	V5		V5	-28.0	—	-12.0 -8.0	V		
Operating voltage (2)	—	Recommended value	V0	-2.5	—	0	V		
Operating voltage (3)	V2	Recommended value	V2	3/9·V5	—	V0	V		
Operating voltage (4)	V3	Recommended value	V3	V5	—	6/9·V5	V		
"H" input voltage	V <sub>IH</sub>		EIO1, EIO2, XSCL, LP, D0 to D3, FR, SHL	0.2V <sub>SS</sub>	—	—	V		
"L" input voltage	V <sub>IL</sub>			—	—	0.8V <sub>SS</sub>	V		
"H" output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -0.6mA	EIO1, EIO2	-0.4	—	—	V		
"L" output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 0.6mA		—	—	V <sub>SS</sub> + 0.4	V		
Input leakage current	I <sub>LI</sub>	V <sub>SS</sub> ≤ V <sub>I</sub> ≤ 0V	D0 to D3, XSCL, LP, SHL, FR	—	—	2.0	μA		
	I <sub>LI/O</sub>	V <sub>SS</sub> ≤ V <sub>I</sub> ≤ 0V	EIO1, EIO2	—	—	5.0	μA		
Stand-by current	I <sub>DDs</sub>	V5 = -12.0 to -28.0V V <sub>IH</sub> = V <sub>DD</sub> , V <sub>IL</sub> = V <sub>SS</sub>	V <sub>DD</sub>	—	—	25	μA		
Output resistance	R <sub>SEG</sub>	ΔV <sub>on</sub>   = 0.5V	V5	-20.0V	SEG0 to SEG79	—	1.5	3.5	kΩ
				-14.0V		—	2.0	4.5	
				-8.0V		—	3.0	8.0	
Current dissipation (1)	I <sub>SS01</sub>	V <sub>SS</sub> = -5.0V, V <sub>IH</sub> = V <sub>DD</sub> , V <sub>IL</sub> = V <sub>SS</sub> , f <sub>XSCL</sub> = 1.92MHz f <sub>LP</sub> = 12kHz, Frame period = 60Hz Input data: Inverted bit by bit No-load	V <sub>SS</sub>	—	120	500	μA		
Current dissipation (2)	I <sub>SS02</sub>	V <sub>SS</sub> = -5.0V, V2 = -4.0V V3 = -16.0V, V5 = -20.0V All other conditions are same as I <sub>SS01</sub> .	V5	—	20	100	μA		
Input capacitance	C <sub>I</sub>	Ta = 25°C	D0 to D3, XSCL, LP, FR, SHL	—	—	8.0	pF		
	C <sub>I/O</sub>		EIO1, EIO2	—	—	15.0	pF		

● AC Electrical Characteristics

(V<sub>SS</sub> = -5.0 ± 10%, T<sub>a</sub> = -20 to 75°C)

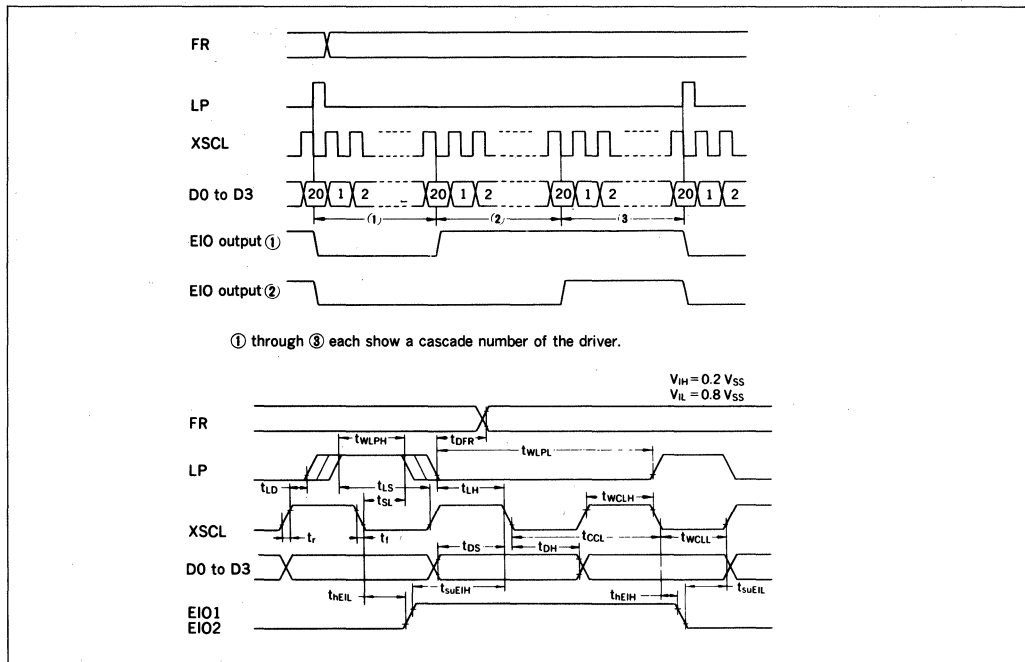
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
XSCL period	t <sub>CCL</sub>	t <sub>r</sub> , t <sub>f</sub> ≤ 10ns	166	—	—	ns
XSCL "H" pulse width	t <sub>WCLH</sub>		70	—	—	ns
XSCL "L" pulse width	t <sub>WCLL</sub>		70	—	—	ns
Data setup time	t <sub>DS</sub>		60	—	—	ns
Data hold time	t <sub>DH</sub>		40	—	—	ns
XSCL-rise to LP-rise time	t <sub>LD</sub>		0	—	—	ns
XSCL-fall to LP-fall time	t <sub>SL</sub>		70	—	—	ns
LP-rise to XSCL-rise time	t <sub>LS</sub>		70	—	—	ns
LP-fall to XSCL-fall time	t <sub>LH</sub>		70	—	—	ns
LP "H" pulse width	t <sub>WLPH</sub>		70	—	—	ns
LP "L" pulse width	t <sub>WLPL</sub>		230	—	—	ns
Alloable FR delay time	t <sub>DFR</sub>		-500	—	500	ns
Enable "H" setup time	t <sub>SUEIH</sub>		40	—	—	ns
Enable "H" hold time	t <sub>HEIH</sub>		0	—	—	ns
Enable "L" setup time	t <sub>SUEIL</sub>		0	—	—	ns
Enable "L" hold time	t <sub>HEIL</sub>		0	—	—	ns
Input signal rise time	t <sub>r</sub>		—	—	50*	ns
Input signal fall time	t <sub>f</sub>		—	—	50*	ns

\*The specifications for t<sub>r</sub> and t<sub>f</sub> are provided to prevent a malfunction which may occur when noise is mixed with a slow-down signal. To assure high-speed XSCL, both t<sub>r</sub> and t<sub>f</sub> must satisfy the following relation:

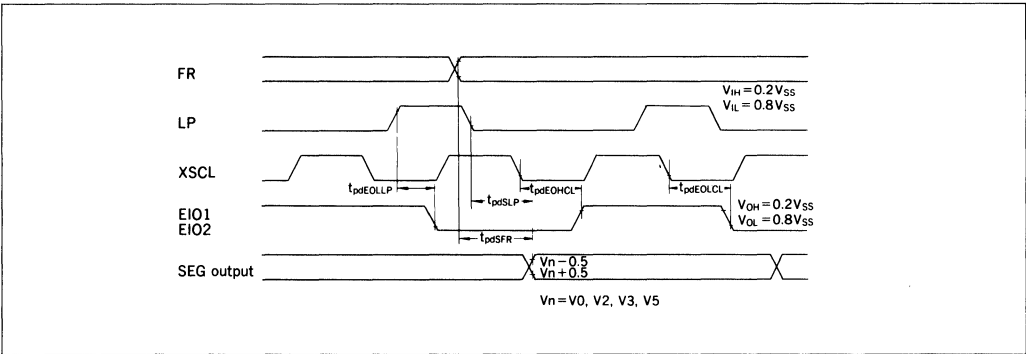
$$t_r, t_f < \frac{t_{CCL} - (t_{WCLH} + t_{WCLL})}{2}$$

● Timing Chart

○ Input Timing



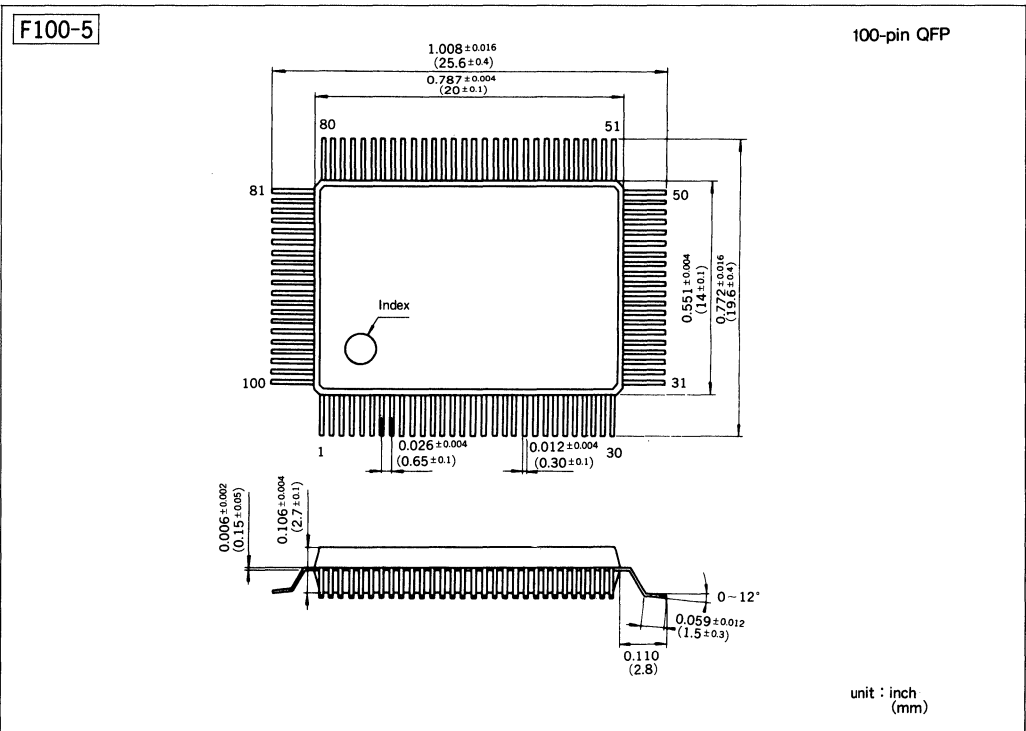
## ○ Output Timing



( $V_{SS} = -5.0 \pm 10\%$ ,  $T_a = -20$  to  $75^\circ\text{C}$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
(LP-rise to disable) time	$t_{pdiEOLLP}$	XSCL = "L"	—	—	70	ns
(XSCL-fall to disable) time	$t_{pdiEOLCL}$	LP = "H"	—	—	70	ns
(XSCL-fall to enable) time	$t_{pdiEOHCL}$		—	—	100	ns
(LP-fall to SEG output) time	$t_{pdiSLP}$	$V_5 = -12.0$ to $-28.0\text{V}$	—	—	4.5	$\mu\text{s}$
(FR to SEG output) delay time	$t_{pdiSFR}$	$C_L = 100\text{pF}$	—	—	4.5	$\mu\text{s}$

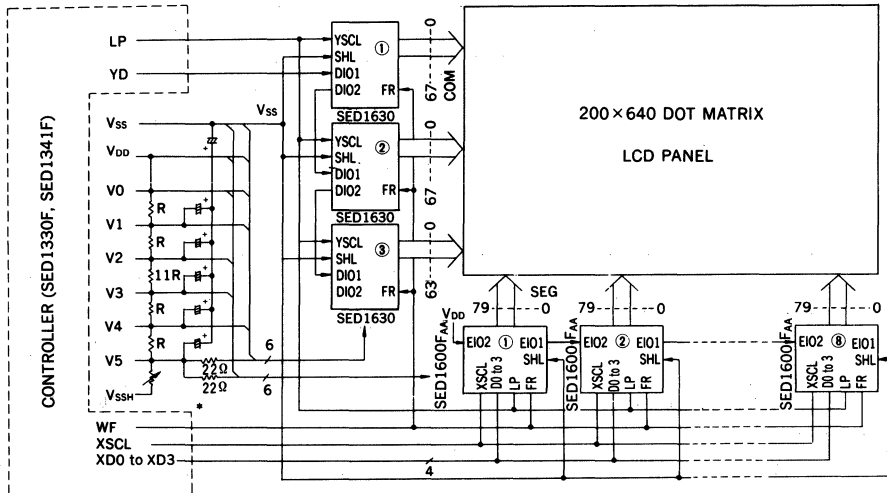
## ■ PACKAGE DIMENSIONS





■EXAMPLE OF APPLICATION (SED1600FAA)

for 200×640 DOT MATRIX LCD



\*Be sure to connect a current limiter resistor. Also, connect decoupling capacitors (0.01uF) near pins Vss and V5 of each LSI for noise protection.

# SED1610F

## CMOS DOT MATRIX HIGH DUTY LCD DRIVER

- 86-bit High Voltage Resistant Output
- Max 1/200 in Display Duty
- CMOS High Voltage Resistant Process

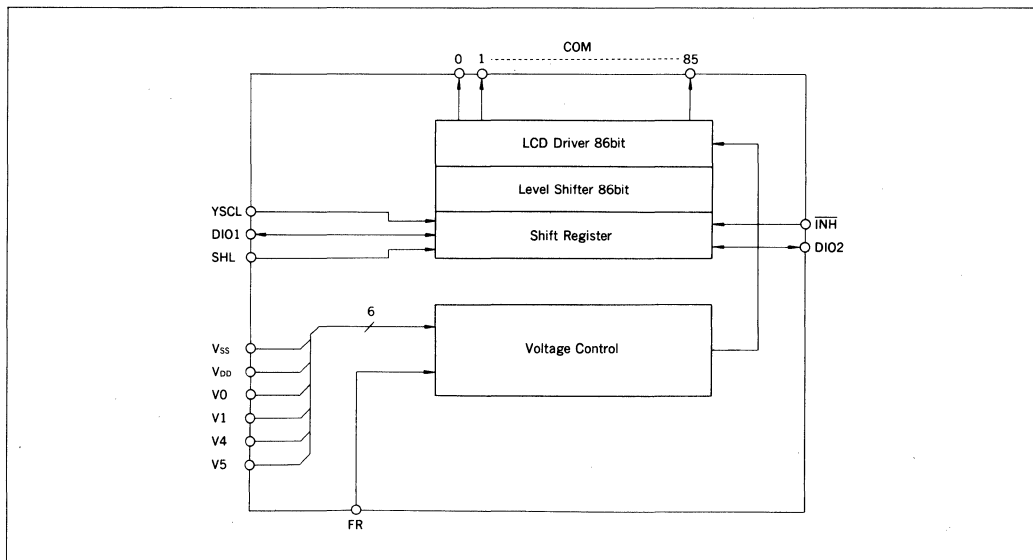
### DESCRIPTION

The SED1610F is an 86 output common (row) driver, used to driver large-capacity dot matrix LCD panels with a duty ratio of up to 1/200. It is used in conjunction with the SED1600F. The SED1610F has a wide range of drive voltages. The maximum voltage  $V_0$  is isolated from  $V_{DD}$  to enable the application of any external LCD driving bias voltage from outside to the SED1610F. These unique features enable the SED1610F to operate with a wide variety of LCD panels.

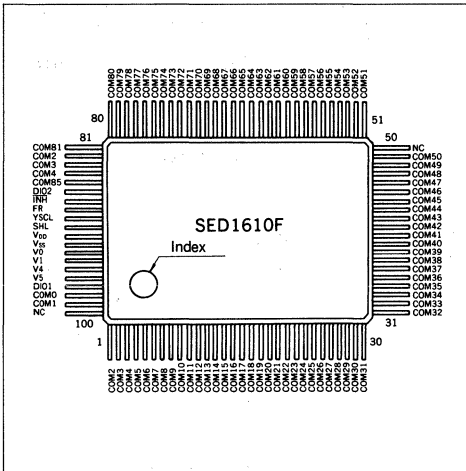
### FEATURES

- 86 LCD driving outputs
- Display capacity .....640 × 200 × 3 dots when combined with SED1600F
- Wide range of LCD driving voltages .....12 to 28V  
 (Absolte maximum voltage.....30V)  
 (Display duty ratio..... $1 / \{2 \times (n + 1)\}$ , where  $n = 1, 2, \dots$  positive integer)
- Output shift direction pin selectable
- Momentary display blanking by inhibit function
- Power supply for the logic.....5V ± 10%
- Ability to adjust offset bias of LCD source from  $V_{DD}$
- Silicon gate CMOS process
- Package.....100-pin QFP (plastic)

### BLOCK DIAGRAM



## PIN CONFIGURATION



## PIN DESCRIPTION

Pin name	Functions													
COM0 to COM85	LCD driving common (row) outputs. Each output changes at the falling edge of YSCL.													
INH	Controls all common outputs to nonselect level (V4 when FR=L, V1 when FR=H) (low active)													
YSCL	Shift clock of serial data (falling edge trigger).													
DIO1, DIO2	Serial transfer data I/O, which is controlled by SHL input. Output changes at falling edge of YSCL.													
SHL	Shift direction selection and DIO pin control.													
	<table border="1"> <thead> <tr> <th rowspan="2">SHL</th> <th rowspan="2">COM output shift direction</th> <th colspan="2">DIO</th> </tr> <tr> <th>1</th> <th>2</th> </tr> </thead> <tbody> <tr> <td>L</td> <td>85 ← 0</td> <td>Input</td> <td>Output</td> </tr> <tr> <td>H</td> <td>85 → 0</td> <td>Output</td> <td>Input</td> </tr> </tbody> </table>	SHL	COM output shift direction	DIO		1	2	L	85 ← 0	Input	Output	H	85 → 0	Output
SHL	COM output shift direction			DIO										
		1	2											
L	85 ← 0	Input	Output											
H	85 → 0	Output	Input											
FR	AC signal of LCD driving outputs.													
V <sub>DD</sub> , V <sub>SS</sub>	Logic circuit power. V <sub>DD</sub> : 0V (GND) V <sub>SS</sub> : -5.0V													
V0, V1, V4, V5	LCD driving power. V5: -12 to -28V V <sub>DD</sub> ≥ V0 > V1 > V4 > V5													

## ABSOLUTE MAXIMUM RATINGS

(V<sub>DD</sub>=0V)

Parameter	Symbol	Ratings	Unit	Parameter	Symbol	Ratings	Unit
Supply voltage (1)	V <sub>SS</sub>	-7.0 to +0.3	V	Output current (2)	I <sub>OSEG</sub>	20	mA
Supply voltage (2)	V5	-30.0 to +0.3	V	Operating temperature	T <sub>opr</sub>	-20 to +75	°C
Supply voltage (2)	V0, V1, V4	V5 - 0.3 to +0.3	V	Storage temperature	T <sub>stg</sub>	-65 to +150	°C
Input voltage (1)	V <sub>I</sub>	V <sub>SS</sub> - 0.3 to +0.3	V	Soldering temperature-time	T <sub>sol</sub>	260°C, 10s (at lead)	—
Output voltage (1)	V <sub>O</sub>	V <sub>SS</sub> - 0.3 to +0.3	V	Allowable power dissipation	P <sub>D</sub>	300	mW
Output current (1)	I <sub>O</sub>	20	mA				

## ELECTRICAL CHARACTERISTICS

### DC Electrical Characteristics

(Unless otherwise specified, V<sub>DD</sub>=V0=0V, V<sub>SS</sub>=-5.0V±10%, and Ta=-20 to 75°C)

Parameter	Symbol	Conditions	Pin	Min	Typ	Max	Unit	
Operating voltage (1)	V <sub>SS</sub>		V <sub>SS</sub>	-5.5	-5.0	-4.5	V	
Recommended operating voltage	V5		V5	-28.0	—	-12.0	V	
Minimum operating voltage						-8.0		
Operating voltage (2)	V0		V0	-2.5	—	0	V	
"H" input voltage	V <sub>IH</sub>		DIO1, DIO2, YSCL, FR, SHL, INH	0.2V <sub>SS</sub>	—	—	V	
"L" input voltage	V <sub>IL</sub>			—	—	0.8V <sub>SS</sub>	V	
"H" output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -0.6mA		-0.4	—	—	V	
"L" output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 0.6mA	DIO1, DIO2	—	—	V <sub>SS</sub> +0.4	V	
Input leakage current	I <sub>LI</sub>	V <sub>SS</sub> ≤ V <sub>I</sub> ≤ 0V	YSCL, SHL, INH, FR	—	—	2.0	μA	
	I <sub>LI/O</sub>	V <sub>SS</sub> ≤ V <sub>I</sub> ≤ 0V	DIO1, DIO2	—	—	5.0	μA	
Stand-by current	I <sub>DDs</sub>	V5 = -12.0 to -28.0V V <sub>IH</sub> = V <sub>DD</sub> , V <sub>IL</sub> = V <sub>SS</sub>	V <sub>DD</sub>	—	—	25	μA	
Output resistance	R <sub>SEG</sub>	ΔV <sub>on</sub>   = 0.5V	V5	-20.0V	—	1.1	1.8	KΩ
				-14.0V	—	1.2	2.0	
				-8.0V	—	2.0	4.0	

continued

Parameter	Symbol	Condition	Pin	Min	Typ	Max	Unit
Current dissipation (1)	$I_{SS01}$	$V_{SS} = -5.0V$ , $V_{IH} = V_{DD}$ , $V_{IL} = V_{SS}$ , $f_{YSCl} = 7.7KHz$ Frame period = 60Hz Input data: "H" every 1/128 duty No-load	$V_{SS}$	—	7	15.0	$\mu A$
Current dissipation (2)	$I_{SS02}$	$V_{SS} = -5.0V$ , $V_1 = -2.0V$ $V_4 = -18.0V$ , $V_5 = -20.0V$ All other conditions are same as $I_{SS01}$	$V_5$	—	7	15.0	$\mu A$
Input capacitance	$C_I$	$T_a = 25^\circ C$	YSCl, SHL, INH, FR	—	—	8.0	pF
	$C_{I/O}$		DIO1, DIO2	—	—	15.0	pF

### ● AC Characteristics

#### ○ Input Timing

( $V_{SS} = -5.0V \pm 10\%$ ,  $T_a = -20$  to  $75^\circ C$ )

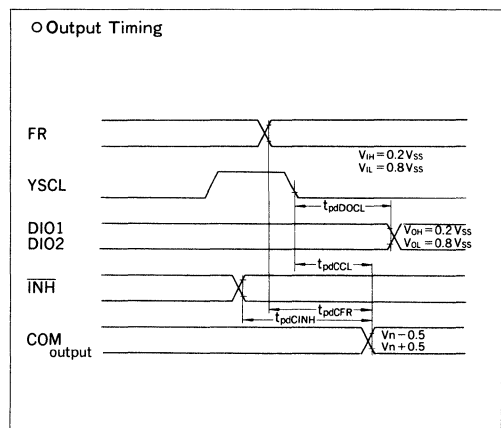
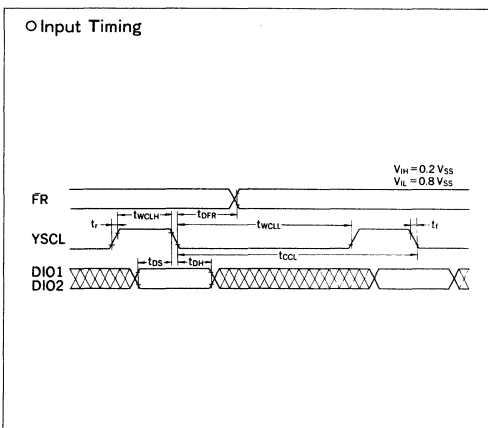
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
YSCl period	$t_{CCL}$		500	—	—	ns
YSCl "H" pulse width	$t_{WCLH}$		70	—	—	ns
YSCl "L" pulse width	$t_{WCLL}$		330	—	—	ns
Data setup time	$t_{DS}$		100	—	—	ns
Data hold time	$t_{DH}$		10	—	—	ns
Allowable FR delay time	$t_{DFR}$		-500	—	500	ns
Input signal rise time	$t_r$		—	—	50	ns
Input signal fall time	$t_f$		—	—	50	ns

#### ○ Output Timing

( $V_{SS} = -5.0V \pm 10\%$ ,  $T_a = -20$  to  $75^\circ C$ )

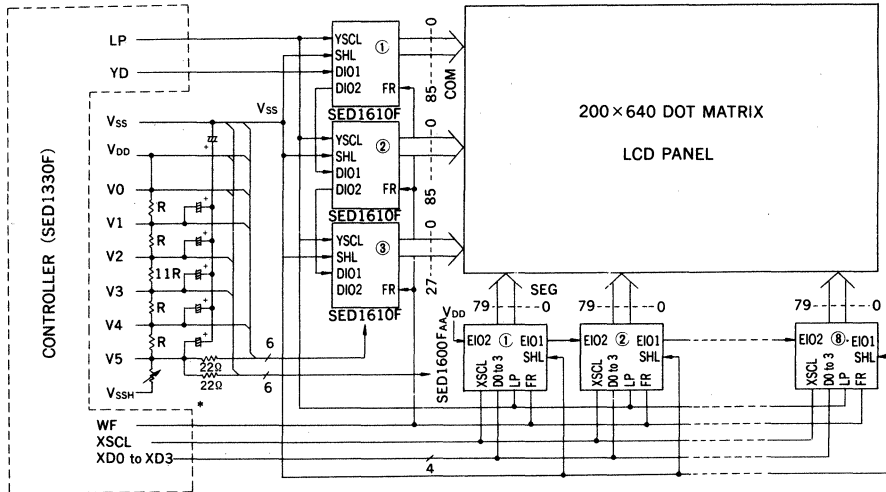
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
(YSCl-fall to DIO) Delay time	$t_{pdDOCL}$	$C_L = 15pF$	30	—	300	ns
(YSCl-fall to COM output) Delay time	$t_{pdCCL}$	$V_5 = -12.0$ to $-28.0V$ $C_L = 100pF$	—	—	3.0	$\mu s$
(INH to COM output) Delay time	$t_{pdCINH}$		—	—	3.0	$\mu s$
(FR to COM output) Delay time	$t_{pdCFR}$		—	—	3.0	$\mu s$

### ● Timing Chart



## EXAMPLE OF APPLICATION

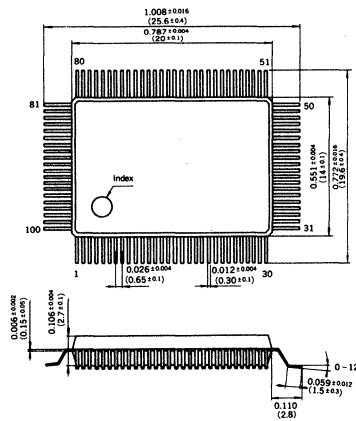
for 200×640 DOT MATRIX LCD



\*Be sure to connect a current limiter resistor. Also, connect decoupling capacitors (0.01 $\mu$ F) near pins Vss and V5 of each LSI for noise protection.

## PACKAGE DIMENSIONS

F100-5



100-pin QFP

unit : inch  
(mm)

# SED1200F<sub>OB</sub>

## CMOS DOT MATRIX LCD CONTROLLER DRIVER

- 1/8 or 1/16 Duty Cycle Dot Matrix Drive
- 20 Character Simultaneous Display
- Built in Character Generator ROM and RAM

### ■ DESCRIPTION

The SED1200F<sub>OB</sub> is a dot matrix LCD controller/driver with a built in CG (character generator).

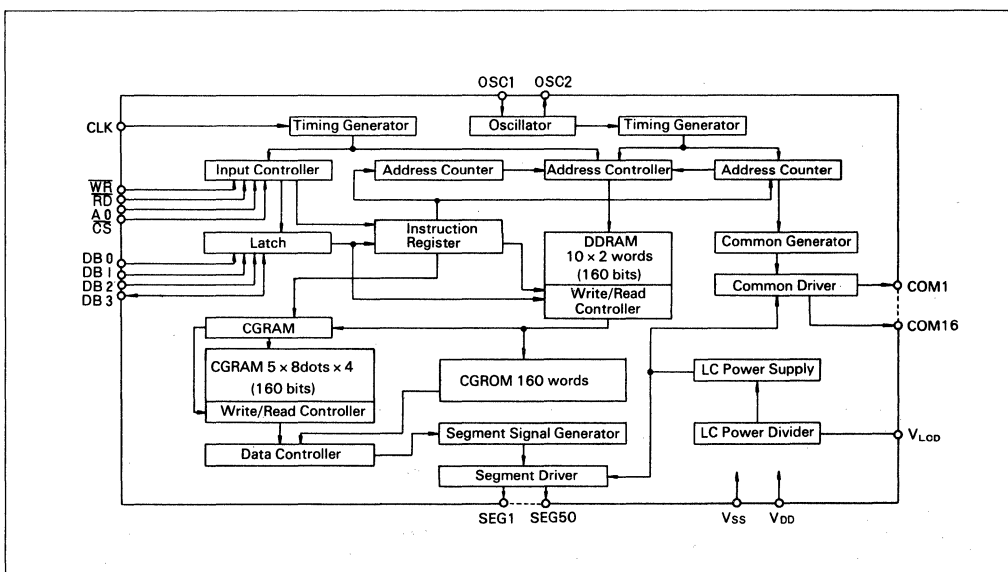
The circuit consists of a CG ROM which contains 160 different characters, 4 words CG RAM, 20 words display data RAM and logic functions to operate a 20 character display. Additional characters may be used by writing CG data to the 4 words CG RAM.

The device also contains the resistor array for the LCD power supply. The SED1200F<sub>OB</sub> is fabricated Silicon Gate CMOS process and features very low power dissipation. This makes the device very desirable for applications in hand held, portable and other battery powered instruments.

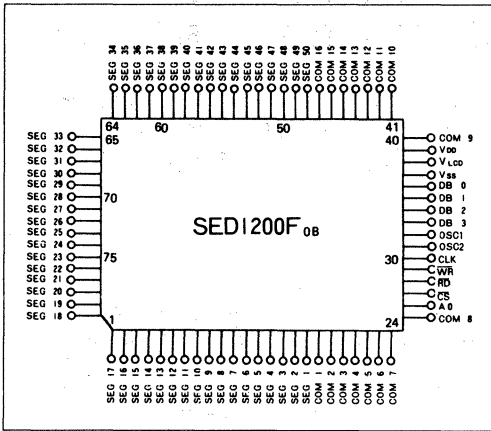
### ■ FEATURES

- 1/8 or 1/16 Duty cycle dot matrix drive
- 20 Character simultaneous display
- Built in character generator ROM and RAM
- Built in CR oscillator
- Built in resistor array for LCD power supply.
- Compatible with 4 or 8 bit microprocessors
- TTL Compatible
- 5 × 7 + Cursor line or 5 × 8 character font
- Package.....80-pin QFP (plastic)

### ■ BLOCK DIAGRAM



## ■ PIN CONFIGURATION



## ■ PIN DESCRIPTION

Pin No.	Pin Name	I/O	Functions
18 to 25 40 to 47	COM1 to COM16	O	LCD Common output
17 to 1 80 to 48	SEG1 to SEG50	O	LCD Segment output
27	CS	I	Chip select input (active "Low")
28	$\overline{RD}$	I	Read enable input (active "Low")
29	$\overline{WR}$	I	Write enable input (active "Low" to "High")
26	A0	I	"High"; Set character code, "Low"; Command
36 to 33	DB0 to DB3	I, I/O	Data input (except DB3; Data input/output)
30	CLK	I	Clock for command
32, 31	OSC1, OSC2	-	Connect oscillation resistor
39	VDD	-	Supply voltage (+5V) for logic
37	VSS	-	GND (0V)
38	VLCD	-	Supply voltage for LCD

## ■ ABSOLUTE MAXIMUM RATINGS

(VSS = 0V)

Parameter	Symbol	Rated	Unit
Supply voltage (1)	VDD	-0.3 to +7.0	V
Supply voltage (2)	VLCD	VDD - 7.0 to VDD + 0.3	V
Input voltage	Vi	-0.3 to VDD + 0.3	V
Output voltage	Vo	-0.3 to VDD + 0.3	V
Operating temperature	Topr	-10 to +70	°C
Storage temperature	Tstg	-65 to +150	°C

## ■ ELECTRICAL CHARACTERISTICS

### ● AC Characteristics (Read cycle)

(VDD = 5V ± 10%, VSS = 0V, Ta = -10 to +70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
A0 setup time to $\overline{RD}$	tAR		0	-	-	ns
CS setup time to RD	tCR		0	-	-	ns
Output delay time from $\overline{RD}$	tRD		-	-	250	ns
A0 hold time after $\overline{RD}$	tRA		20	-	-	ns
CS hold time after $\overline{RD}$	tRC		20	-	-	ns
Data hold time	tRH		10	-	-	ns
Read pulse width	tRP		350	-	-	ns
Input fall time	tHL		-	-	50	ns
Input rise time	tLH		-	-	50	ns

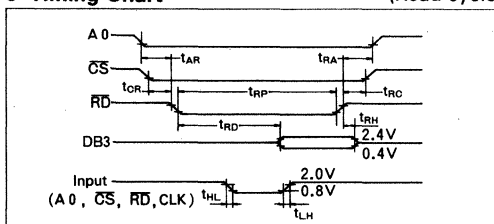
### ● AC Characteristics (Write cycle)

(VDD = 5V ± 10%, VSS = 0V, Ta = -10 to +70°C)

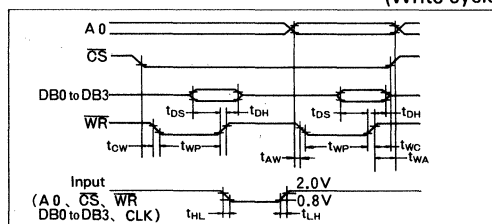
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
A0 setup time to $\overline{WR}$	tAW		0	-	-	ns
CS setup time to $\overline{WR}$	tCW		0	-	-	ns
Data setup time	tDS		120	-	-	ns
A0 hold time after $\overline{WR}$	tWA		20	-	-	ns
CS hold time after $\overline{WR}$	tWC		20	-	-	ns
Data hold time	tDH		20	-	-	ns
Write pulse width	tWP		200	-	-	ns
Input fall time	tHL		-	-	50	ns
Input rise time	tLH		-	-	50	ns

## ● Timing Chart

(Read cycle)



(Write cycle)



● DC Characteristics

(V<sub>SS</sub> = 0V, T<sub>a</sub> = -10 to +70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Logic operating voltage	V <sub>DD</sub>		4.5	5	5.5	V
LCD operating voltage	V <sub>LCD</sub>		V <sub>DD</sub> -5.5	-	V <sub>DD</sub> -4	V
Resistor for oscillator	R <sub>f</sub>	V <sub>DD</sub> = 5V, f <sub>osc</sub> = 100kHz	240	310	380	kΩ
Input voltage ; High (1)	V <sub>IH1</sub>	V <sub>DD</sub> = 4.5 to 5.5V * 1	2.0	-	V <sub>DD</sub>	V
Input voltage ; Low (1)	V <sub>IL1</sub>	V <sub>DD</sub> = 4.5 to 5.5V * 1	0	-	0.8	V
Input leakage current ; High	I <sub>LH</sub>	V <sub>DD</sub> = 5.5V, V <sub>IH</sub> = 5.5V * 2	-	-	1.0	μA
Input leakage current ; Low	I <sub>LI</sub>	V <sub>DD</sub> = 5.5V, V <sub>IL</sub> = 0V * 2	-	-	1.0	μA
Input voltage ; High (2)	V <sub>IH2</sub>	V <sub>DD</sub> = 4.5 to 5.5V * 3	0.8V <sub>DD</sub>	V <sub>DD</sub>	V <sub>DD</sub>	V
Input voltage ; Low (2)	V <sub>IL2</sub>	V <sub>DD</sub> = 4.5 to 5.5V * 3	0	0	0.2V <sub>DD</sub>	V
Output current ; High	I <sub>OH</sub>	V <sub>DD</sub> = 5V, V <sub>OH</sub> = 2.4V * 4	1.0	-	-	mA
Output current ; Low	I <sub>OL</sub>	V <sub>DD</sub> = 5V, V <sub>OL</sub> = 0.4V * 4	1.6	-	-	mA
Input pull up current	I <sub>PU</sub>	V <sub>IL</sub> = 0V, V <sub>DD</sub> = 5V * 5	3	10	30	μA
Resistor as power divider	R <sub>d</sub>		30	130	300	kΩ
Operating frequency (1)	f <sub>osc</sub>	V <sub>DD</sub> = 4.5 to 5.5V	-	100	300	kHz
Operating frequency (2)	CLK	V <sub>DD</sub> = 4.5 to 5.5V	-	-	3.2	MHz
Operating current	I <sub>DD</sub>	V <sub>DD</sub> = 5V, V <sub>LCD</sub> = 0V * 6 f <sub>osc</sub> = 100KHz, CLK = 1MHz	-	80	150	μA
Command execution time	t <sub>COMD</sub>		-	-	16/CLK (MHz)	μs
Common output current (1)	I <sub>OH</sub> V <sub>DDC</sub>	V <sub>DD</sub> = 4.5V V <sub>LCD</sub> = 1.0V 1/16 duty drive Voltage drop by 0.5V  When one terminal is measured, the others are open.	20	-	-	μA
Common output current (2)	I <sub>OL</sub> V <sub>LDC</sub>		20	-	-	μA
Common output current (3)	I <sub>OL</sub> V <sub>L1C</sub>		8	-	-	μA
Common output current (4)	I <sub>OL</sub> V <sub>L4C</sub>		8	-	-	μA
Segment output current (1)	I <sub>OL</sub> V <sub>DDs</sub>		12	-	-	μA
Segment output current (2)	I <sub>OL</sub> V <sub>LCDs</sub>		12	-	-	μA
Segment output current (3)	I <sub>OL</sub> V <sub>L2s</sub>		4	-	-	μA
Segment output current (4)	I <sub>OL</sub> V <sub>L3s</sub>		4	-	-	μA

- \* 1. Terminal:  $\overline{CS}$ ,  $\overline{RD}$ ,  $\overline{WR}$ , A0, DB0 to DB3, CLK
- \* 2. Terminal: CLK, OSC1, DB0 to DB3
- \* 3. Terminal: OSC1 (for external clock)

- \* 4. Terminal: DB3
- \* 5. Terminal:  $\overline{CS}$ ,  $\overline{RD}$ ,  $\overline{WR}$ , A0
- \* 6.  $\overline{CS} = \overline{RD} = \overline{WR} = A0 = 5.0V$ , (open output terminals)

■ DISPLAY COMMAND

Command Name	$\overline{CS}$	$\overline{WR}$	$\overline{RD}$	A0	1st input				2nd input				Note
					DB3 (D7)	DB2 (D6)	DB1 (D5)	DB0 (D4)	DB3 (D3)	DB2 (D2)	DB1 (D1)	DB0 (D0)	
SET CURSOR DIRECTION	0	0	1	0	0	0	0	0	0	1	0	D/I	D0 = 1: Decrement D0 = 0: Increment
CURSOR ADDRESS -1/+1	0	0	1	0	0	0	0	0	0	1	1	-1/+1	
CURSORFONT SELECT	0	0	1	0	0	0	0	0	1	0	0	A/U	D0 = 1: All dots blinking D0 = 0: Under line
CURSOR BLINK ON/OFF	0	0	1	0	0	0	0	0	1	0	1	ON/OFF	
DISPLAY ON/OFF	0	0	1	0	0	0	0	0	1	1	0	ON/OFF	D0 = 1: ON D0 = 0: OFF
CURSOR ON/OFF	0	0	1	0	0	0	0	0	1	1	1	ON/OFF	
SYSTEM RESET	0	0	1	0	0	0	0	1	0	0	0	0	Except data RAM and CGRAM D0 = 1: 2 line display (1/16 duty) D0 = 0: 1 line display (1/ 8 duty)
LINE SELECT	0	0	1	0	0	0	0	1	0	0	1	2/1	
SET CURSOR ADDRESS	0	0	1	0	1	0	(N figure - 1) B						
1st LINE													
2nd LINE	0	0	1	0	1	1	(N figure - 1) B						
SET CHARACTER CODE	0	0	1	1	(CHARACTER CODE)								
BUSY FLAG CHECK	0	1	0	0	BF	*	*	*	BF	*	*	*	D7(D3) = 1: Busy D7(D3) = 0: Not Busy
SET CGRAM ADDRESS	0	0	1	0	0	0	1	0	(Set lower address)				
SET CGRAM DATA	0	0	1	0	0	1	0	(Set CGRAM data)					

\* = High impedance

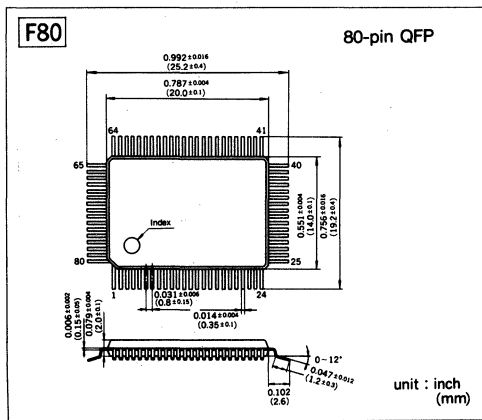
**Note:** Misoperation may be caused when any command other than that listed in the above table is inputted.



## CHARACTER CODE MAP (SED1200F08)

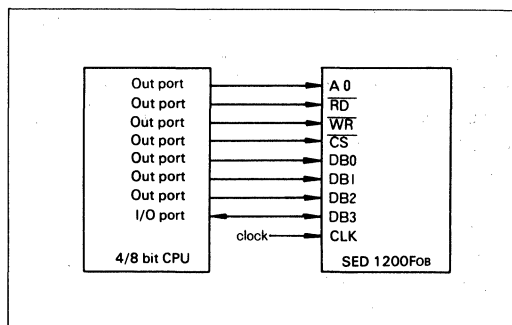
		Lower 4 bit (D4 to D7) of Character Code (Hexadecimal)															
		0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Upper 4 bit (D0 to D3) of Character Code (Hexadecimal)	0	CG RAM AREA 5 × 8 DOTS															
	2		!	"	#	\$	%	&	'	(	)	*	+	,	-	.	/
	3	0	1	2	3	4	5	6	7	8	9	:	;	<	=	>	?
	4	0	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	5	P	R	S	T	U	V	W	X	Y	Z	[	\	]	^	_	~
	6	'	a	b	c	d	e	f	g	h	i	j	k	l	m	n	o
	7	P	a	r	s	t	u	v	w	x	y	z	[	]	^	_	~
	A	S	T	R	X	-	+	P	O	A	B	C	D	E	F	G	H
	B	S	T	R	I	S	A	B	C	D	E	F	G	H	I	J	K
	C	K	L	M	N	O	P	Q	R	S	T	U	V	W	X	Y	Z
	D	+	-	^	_	~	!	"	#	\$	%	&	'	(	)	*	+

## PACKAGE DIMENSIONS



## APPLICATION FOR CPU

The SED1200F08 can connect to the address bus or the data bus directly or alternatively, a peripheral interface unit. An example is shown below.



# SED1210F<sub>0B</sub>

## CMOS DOT MATRIX LCD CONTROLLER DRIVER

- 1/8 or 1/16 Duty Cycle Dot Matrix Drive
- Built-in Character Generator ROM and RAM
- Maximum Simultaneous Display of 40 Characters  
(When Accompanied with SED1181F<sub>LA</sub>)

### DESCRIPTION

The SED1210F<sub>0B</sub> is a dot matrix LCD controller/driver with a built in CG (character generator).

The circuit consists of a CG ROM which contains 160 different characters, 4 characters CG RAM, 40 words display data RAM and logic functions to operate a 40 character display. Additional characters may be used by writing CG data to the 4 characters CG RAM.

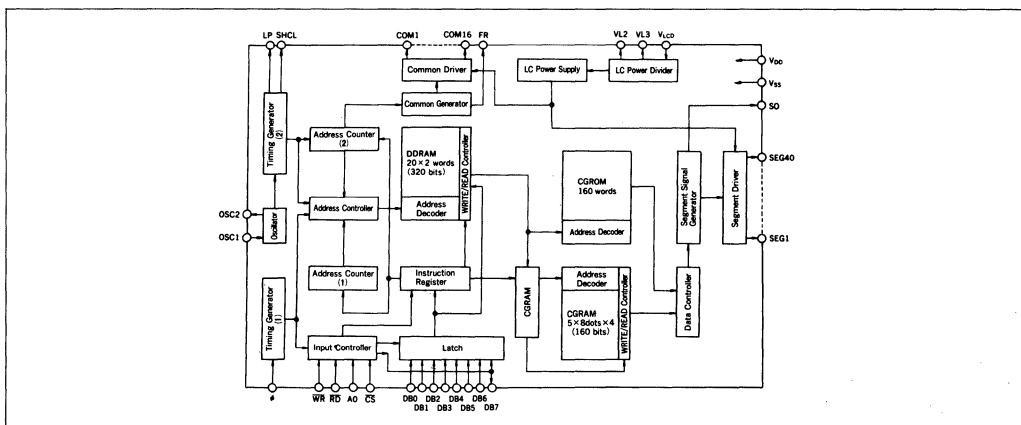
The device also contains the resistor array for the LCD power supply. The SED1210F<sub>0B</sub> is fabricated Silicon Gate CMOS process and features very low power dissipation. This makes the device very desirable for applications in hand held, portable and other battery powered instruments.

Since 1210F<sub>0B</sub> consists of 40 segment drivers and 16 common drivers on one chip, at most 16 characters are displayed. Accompanied with SED1181F<sub>LA</sub>, number of characters can be expanded to 40 characters at most.

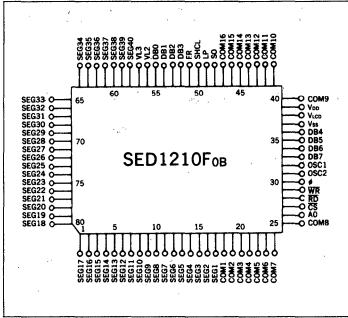
### FEATURES

- CMOS LSI
- Built in display data RAM .....40×8 bits : 40 characters (Max)
- Built in character generator ROM (160 different characters) and CGRAM (4 words)
- Built in CR oscillator circuit (External Resistance)
- Built in resistor array for LCD power supply
- Maximum display dimension .....20 characters×2 lines or 40 characters×1 line  
(with SED1181F<sub>LA</sub> accompanied)
- 1/8 or 1/16 duty cycle dot matrix drive (fixed by command)
- Capable of interfacing to 4 or 8 bit CPU
- 13 simple commands for operation
- 5×7 + Cursor line or 5×8 character font
- Cursor font .....Underline or all dots blinking
- Low power dissipation
- Single power supply .....2.5V to 5.5V (Logic)
- Package .....80-pin QFP (plastic)

### BLOCK DIAGRAM



## PIN CONFIGURATION



## PIN DESCRIPTION

Pin Name	Functions	No. of Pin	Pin Name	Functions	No. of Pin
COM1 to 16	LCD common output	16	SO	Serial output for Segment driver	1
SEG1 to 40	LCD segment output	40	LP	Latch output for Segment driver	1
CS	Chip select input (active "Low")	1	SHCL	Shift clock for Segment driver	1
RD	Read enable input (active "Low")	1	FR	Frame output for Segment driver	1
WR	Write enable input (active "Low" to "High")	1	VL2, VL3	Supply voltage for Segment driver	2
A0	"High"; Set character code "Low"; Command	1	VDD	Supply voltage (2.5V to 5.5V) for logic	1
DB0 to 7	Data input (except DB7; Data input/output)	8	VSS	GND (0V)	1
phi	Clock for command	1	VLCD	Supply voltage for LCD 3.5V $\pm$ VDD - VLCD $\pm$ 5.5V	1
OSC1, OSC2	Connect oscillation resistor between OSC1 and OSC2. OSC1 also can be external clock input.	2			

## ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V, T<sub>a</sub> = 25°C)

Parameter	Symbol	Ratings	Unit
Supply voltage (1)	V <sub>DD</sub>	-0.3 to 7.0	V
Supply voltage (2)	V <sub>LCD</sub>	V <sub>DD</sub> - 7.0 to V <sub>DD</sub> + 0.3	V
Input voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> + 0.3	V
Output voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> + 0.3	V
Operating temperature	T <sub>opr</sub>	-20 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C · 10s (at lead)	—

## ELECTRICAL CHARACTERISTICS

### DC Characteristics

(V<sub>SS</sub> = 0V, T<sub>a</sub> = -20 to 75°C)

Parameter	Symbol	Conditions	Terminal	Min	Typ	Max	Unit
Logic operating voltage	V <sub>DD</sub>		V <sub>DD</sub>	2.5	5.0	5.5	V
LCD operating voltage	V <sub>LCD</sub>		V <sub>LCD</sub>	V <sub>DD</sub> - 5.5	—	V <sub>DD</sub> - 3.5	V
Resistor for oscillator	R <sub>f</sub>	V <sub>DD</sub> = 5.0V, f <sub>OSC</sub> = 100kHz	OSC1	240	310	380	kΩ
Operating frequency (1) (of oscillation or external clock)	f <sub>OSC</sub>	V <sub>DD</sub> = 4.5 to 5.5V	OSC2	—	100	300	kHz
Operating frequency (2)	phi		phi	—	—	3.2	MHz
External clock duty			OSC1, phi	45	50	55	%
Input voltage; High (1)	V <sub>IH1</sub>		CS, RD WR, A0 DB0 to 7	2.0	—	V <sub>DD</sub>	V
Input voltage; Low (1)	V <sub>IL1</sub>			0	—	0.8	V
Input voltage; High (2)	V <sub>IH2</sub>		OSC1	0.8V <sub>DD</sub>	V <sub>DD</sub>	V <sub>DD</sub>	V
Input voltage; Low (2)	V <sub>IL2</sub>			0	0	0.2V <sub>DD</sub>	V
Input leakage current; High	I <sub>IH1</sub>	V <sub>DD</sub> = 5.5V, V <sub>IH</sub> = 5.5V	phi, OSC1	—	—	1.0	μA
Input leakage current; Low	I <sub>IL1</sub>	V <sub>DD</sub> = 5.5V, V <sub>IL</sub> = 0V	DB0 to 7	—	—	1.0	μA
Input pull up current	I <sub>Ipu</sub>	V <sub>DD</sub> = 5.0V, V <sub>IL</sub> = 0V	CS, RD WR, A0	3.0	10	30	μA
Output current; High	I <sub>OH1</sub>	V <sub>DD</sub> = 4.5 to 5.5V, V <sub>OH</sub> = 2.4V	DB7	1.0	—	—	mA
Output current; Low	I <sub>OL1</sub>	V <sub>DD</sub> = 4.5 to 5.5V, V <sub>OL</sub> = 0.4V		1.6	—	—	mA
Output current; High	I <sub>OH2</sub>	V <sub>DD</sub> = 4.5V, V <sub>OH</sub> = 4.0V	FR, LP	200	—	—	μA
Output current; Low	I <sub>OL2</sub>	V <sub>DD</sub> = 4.5V, V <sub>OL</sub> = 0.5V	XSC1 SO	200	—	—	μA
Common output current (1)	I <sub>OH</sub> V <sub>DDC</sub>	• V <sub>DD</sub> = 4.5V • V <sub>LCD</sub> = 1.0V • When resistance array is in low impedance • 1/16 duty drive • Voltage drop by 0.5V When one terminal is measured, the others are open.	COM1 to COM16	20	—	—	μA
Common output current (2)	I <sub>OL</sub> V <sub>LCD</sub>			20	—	—	μA
Common output current (3)	I <sub>OL</sub> V <sub>L1C</sub>			8	—	—	μA
Common output current (4)	I <sub>OL</sub> V <sub>L4C</sub>			8	—	—	μA
Segment output current (1)	I <sub>OH</sub> V <sub>DD</sub> S		12	—	—	μA	
Segment output current (2)	I <sub>OL</sub> V <sub>L</sub> CDS		12	—	—	μA	
Segment output current (3)	I <sub>OL</sub> V <sub>L</sub> 2S		4	—	—	μA	
Segment output current (4)	I <sub>OL</sub> V <sub>L</sub> 3S		4	—	—	μA	

## ● AC Characteristics

### ○ Read Cycle

( $V_{DD}=5V \pm 10\%$ ,  $T_a = -20$  to  $75^\circ C$ )

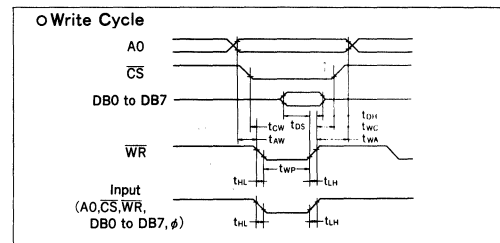
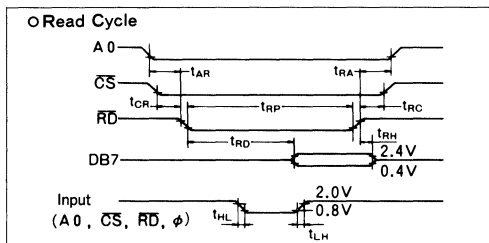
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
A0 setup time to $\overline{RD}$	$t_{AR}$		0	—	—	ns
$\overline{CS}$ setup time to $\overline{RD}$	$t_{CR}$		0	—	—	ns
Output delay time from $\overline{RD}$	$t_{RD}$	$C_L = 100pF$	—	—	250	ns
A0 hold time after $\overline{RD}$	$t_{RA}$		20	—	—	ns
$\overline{CS}$ hold time after $\overline{RD}$	$t_{RC}$		20	—	—	ns
Data hold time	$t_{RH}$		10	—	—	ns
Read pulse width	$t_{RP}$		350	—	—	ns
Input fall time	$t_{HL}$		—	—	50	ns
Input rise time	$t_{LH}$		—	—	50	ns

### ○ Write Cycle

( $V_{DD}=5V \pm 10\%$ ,  $T_a = -20$  to  $75^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Address allowance time	$t_{AW}$		0	—	—	ns
Chip select time	$t_{CW}$		0	—	—	ns
Data setup time	$t_{DS}$		120	—	—	ns
A0 hold time after $\overline{WR}$	$t_{WA}$		20	—	—	ns
$\overline{CS}$ hold time after $\overline{WR}$	$t_{WC}$		20	—	—	ns
Data hold time	$t_{DH}$		20	—	—	ns
Write pulse width	$t_{WP}$		200	—	—	ns
Input fall time	$t_{HL}$		—	—	50	ns
Input rise time	$t_{LH}$		—	—	50	ns

## ■ Timing Chart



## ■ DISPLAY COMMAND

Command Name	CS	WR	RD	A0	D7	D6	D5	D4	D3	D2	D1	D0	Note
SET CURSOR DIRECTION	0	0	1	0	0	0	0	0	0	1	0	D/I	D0=1: Decrement D0=0: Increment
CURSOR ADDRESS -1/+1	0	0	1	0	0	0	0	0	0	1	1	-1/+1	D0=1: -1 D0=0: +1
CURSOR FONT SELECT	0	0	1	0	0	0	0	0	1	0	0	A/U	D0=1: All dots blinking D0=0: Under line
CURSOR BLINK ON/OFF	0	0	1	0	0	0	0	0	1	0	1	ON/OFF	
DISPLAY ON/OFF	0	0	1	0	0	0	0	0	1	1	0	ON/OFF	D0=1 ON D0=0 OFF
CURSOR ON/OFF	0	0	1	0	0	0	0	0	1	1	1	ON/OFF	
SYSTEM RESET	0	0	1	0	0	0	0	1	0	0	0	0	Except data RAM and CGRAM
LINE SELECT	0	0	1	0	0	0	0	1	0	0	1	2/1	D0=1: 2 line display (1/16 duty) D0=0: 1 line display (1/8 duty)
SET CGRAM ADDRESS	0	0	1	0	0	0	1	0	A3	A2	A1	A0	Upper address is fixed to 0H
SET CGRAM DATA	0	0	1	0	0	1	0	D4	D3	D2	D1	D0	
SET CURSOR ADDRESS	0	0	1	0	1	2nd/1st	A5	A4	A3	A2	A1	A0	D6=1: N figure for second line D6=0: N figure for first line
SET CHARACTER CODE	0	0	1	1	D7	D6	D5	D4	D3	D2	D1	D0	
BUSY FLAG CHECK	0	1	0	0	BF	*	*	*	*	*	*	*	

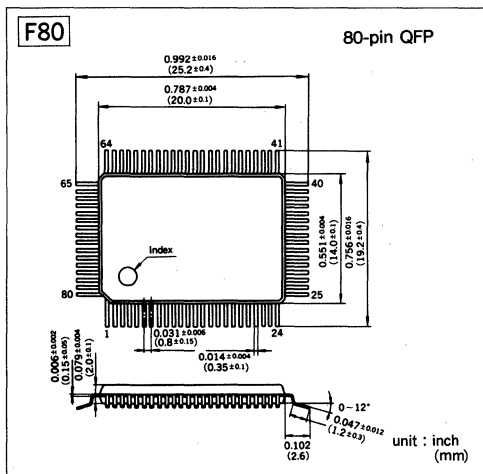
\* = High impedance

Note: Misoperation may be caused when any command other than that listed in the above table is inputted.

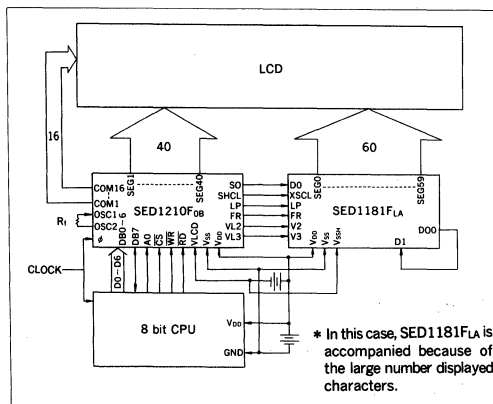
## CHARACTER CODE MAP (SED1210F08)

		Lower 4 bit (D4 to D7) of Character Code (Hexadecimal)															
		0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Upper 4 bit (D0 to D3) of Character Code (Hexadecimal)	0	CG RAM AREA 5 × 8 DOTS															
	2	!	"	#	\$	%	&	'	(	)	*	+	,	-	.	/	
	3	0	1	2	3	4	5	6	7	8	9	:	;	<	=	>	?
	4	@	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	5	P	Q	R	S	T	U	V	W	X	Y	Z	[	\	]	^	_
	6	'	a	b	c	d	e	f	g	h	i	j	k	l	m	n	o
	7	P	q	r	s	t	u	v	w	x	y	z	{		}	~	
	A	0	1	2	3	4	5	6	7	8	9	:	;	<	=	>	?
	B	0	1	2	3	4	5	6	7	8	9	:	;	<	=	>	?
	C	0	1	2	3	4	5	6	7	8	9	:	;	<	=	>	?
	D	0	1	2	3	4	5	6	7	8	9	:	;	<	=	>	?

## PACKAGE DIMENSIONS



## EXAMPLE OF APPLICATION (20 characters × 2 lines display)



SED1210F08 can connect to the address bus or the data bus directly or alternatively, a peripheral interface unit.

# SED1278F

## CMOS DOT MATRIX LCD CONTROLLER DRIVER

- 1/8, 1/11 or 1/16 Duty Cycle Dot Matrix Drive
- Built-in Character Generator ROM and RAM (ROM 240 characters, RAM 8 characters)
- Maximum Simultaneous Display of 80 Characters (When Accompanied with SED1181F<sub>LA</sub>)

### DESCRIPTION

The SED1278F is a dot matrix LCD controller/driver which is dedicated to character display. It is capable of displaying up to 80 characters under 4-bit/8-bit MPU control.

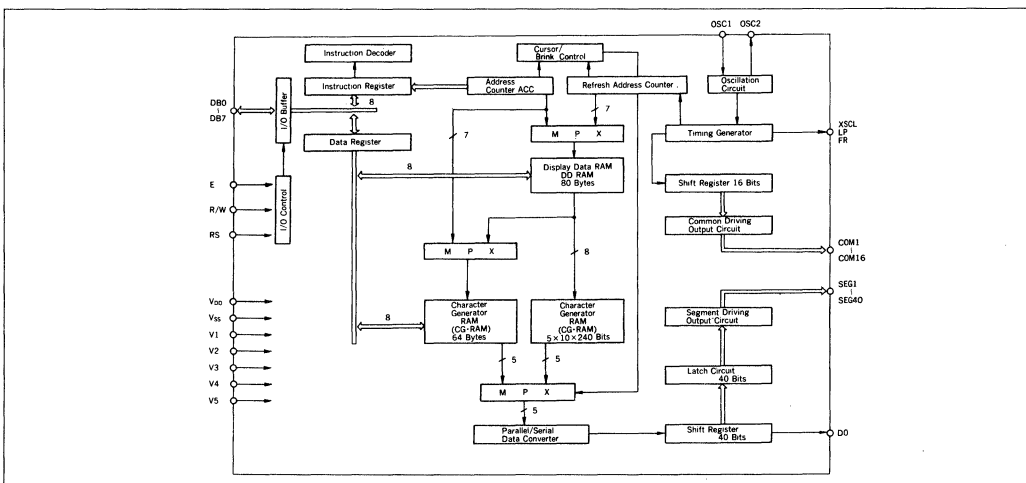
The built-in character generator ROM has an extended capacity of 240 different characters, each being generated in a 5×10 dots font compatible with a 1/11 duty. In addition, the SED1278F contains 64 bytes of character generator RAM in which the user can store 8 different characters, each consisting of 5×8 dots. These memory features offer high flexibility in character display.

The guaranteed minimum LCD driving voltage is 3V, and this makes the SED1278F suitable for driving low voltage LCDs.

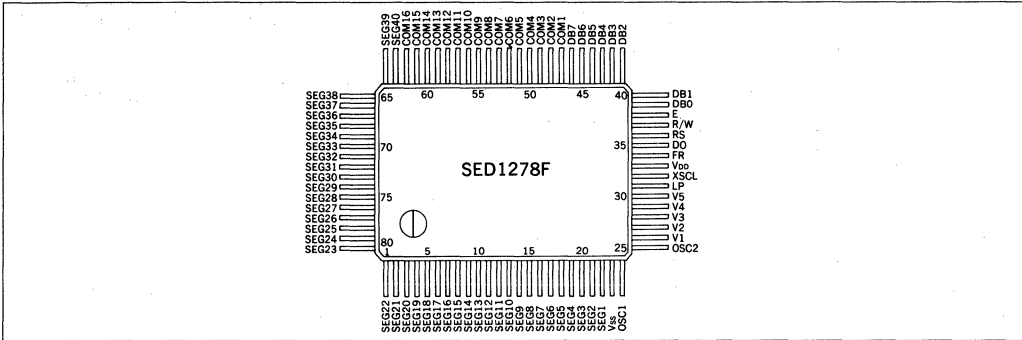
### FEATURES

- Display RAM.....80 bytes (80 characters)
- Character generator ROM.....240 characters (Able to 256 characters)
- Character generator RAM.....8 characters
- Built-in CR oscillator, Built-in power-on reset circuit
- Maximum display dimension.....80 characters×1 line, 40 characters×2 lines (When accompanied with SED1181F<sub>LA</sub>)
- 1/8, 1/11 or 1/16 duty cycle matrix drive (fixed by command)
- 2 flame AC wave-form drive
- High-speed bus interface with 4-bit/8-bit MPU
- Powerful display control instructions
- Character font.....5×7 dots+Cursor line (5×8 dots also possible)  
5×10 dots+Cursor line
- Single power supply.....5V±10% (Logic)
- Low LCD driving voltage.....V<sub>DD</sub> - V<sub>S</sub> ≥ 3.0V
- Package.....80-pin QFP (plastic)

### BLOCK DIAGRAM



## ■ PIN CONFIGURATION



## ■ PIN DESCRIPTION

Symbol	No. of signals	Functions
RS	1	Register select signal
R/W	1	Read/write select signal
E	1	Read/write execute signal
DB0 to DB7	8	Data bus
LP	1	Data latching pulse
XSC1	1	Data transfer clock
FR	1	LCD AC driving signal
DO	1	Serial data
COM1 to COM16	16	Common outputs COM9 to COM16 : non-select for 1/8 duty COM12 to COM16 : non-select for 1/11 duty
SEG1 to SEG40	40	Segment outputs
V1 to V5	5	LCD driving power ( $V5 \geq V_{SS}$ )
V <sub>DD</sub>	1	+5V
V <sub>SS</sub>	1	0V (GND)
OSC1	2	Used to connect resistor (typ. 91K-ohms) for oscillation ; OSC1 is for external clock input.
OSC2		

*1	RS	R/W	E	Operation
	0	0		Instruction write cycle
	0	1	1	Busy flag read cycle Address counter read cycle
	1	0		DD RAM or CG RAM data write cycle
	1	1	1	DD RAM or CG RAM data read cycle

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V, T<sub>a</sub>=25°C)

Parameter	Symbol	Ratings	Unit
Supply voltage (1)	V <sub>DD</sub>	-0.3 to 7.0	V
Supply voltage (2)	V1 to V5	-0.3 to V <sub>DD</sub> +0.3	V
Input voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Power dissipation	P <sub>D</sub>	300	mW
Operating temperature	T <sub>opr</sub>	-20 to 75	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C•10s (at lead)	—

Note) The following condition must always hold true : V<sub>DD</sub> ≥ V1 ≥ V2 ≥ V3 ≥ V4 ≥ V5

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Characteristics

( $V_{DD}=5.0V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a = -20$  to  $75^\circ C$ )

Parameter	Symbol	Conditions	Applicable Pin	Min	Typ	Max	Unit
"H" level input voltage (1)	$V_{IH1}$		DB0~DB7	2.0	—	$V_{DD}$	V
"L" level input voltage (1)	$V_{IL1}$		RS, R/W, E	$V_{SS}$	—	0.8	V
"H" level input voltage (2)	$V_{IH2}$		OSC1	$V_{DD} - 1.0$	—	$V_{DD}$	V
"L" level input voltage (2)	$V_{IL2}$			$V_{SS}$	—	1.0	V
"H" level output voltage (1)	$V_{OH1}$	$I_{OH} = -0.205mA$	DB0~DB7	2.4	—	—	V
"L" level output voltage (1)	$V_{OL1}$	$I_{OL} = 1.6mA$		—	—	0.4	V
"H" level output voltage (2)	$V_{OH2}$	$I_{OH} = -0.04mA$	XSCL LP DO	$0.9V_{DD}$	—	—	V
"L" level output voltage (2)	$V_{OL2}$	$I_{OL} = 0.04mA$		—	—	$0.1V_{DD}$	V
Driver-on resistor (COM)	$R_{COM}$	$ V_{COM} - V_n  = 0.5V$	COM1~16	—	2	10	$k\Omega$
Driver-on resistor (SEG)	$R_{SEG}$	$ V_{SEG} - V_n  = 0.5V$	SEG1~40	—	2.5	10	$k\Omega$
I/O leakage current	$I_{IL}$	$V_I = 0$ to $V_{DD}$		—	—	1	$\mu A$
Pull-up MOS current	$-I_P$	$V_{DD} = 5V$		50	125	250	$\mu A$
Supply current	$I_{op}$	Rf oscillation, external clock $V_{DD} = 5V$ , $f_{osc} = f_{CP} = 270kHz$	$V_{DD}$	—	0.5	0.8	mA
External clock operation							
External clock operating frequency	$f_{EXTCL}$			125	250	350	kHz
External clock duty	Duty			45	50	55	%
External clock rise time	$tr_{EXTCL}$			—	—	0.2	$\mu s$
External clock fall time	$tf_{EXTCL}$			—	—	0.2	$\mu s$
Internal clock operation (Rf oscillation)							
Internal clock oscillation frequency	$f_{OSC}$	$R_f = 91k\Omega \pm 2\%$		190	270	350	kHz
LCD driving voltage	$V_{LCD}$	$V_{DD} - V_5$		3.0	—	$V_{DD}$	V

### ● AC Characteristics

#### ○ Read Cycle

( $V_{DD}=5.0V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a = -20$  to  $75^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Enable cycle time	$t_{cycE}$		500	—	—	ns
Enable "H" level pulse width	$t_{WEH}$		220	—	—	ns
Enable rise/fall time	$t_{rE}$ , $t_{fE}$		—	—	25	ns
RS, R/W setup time	$t_{AS}$		40	—	—	ns
RS, R/W address hold time	$t_{AH}$		10	—	—	ns
Read data output delay	$t_{RD}$	$C_L = 100pF$	—	—	120	ns
Read data hold time	$t_{DHR}$		20	—	—	ns

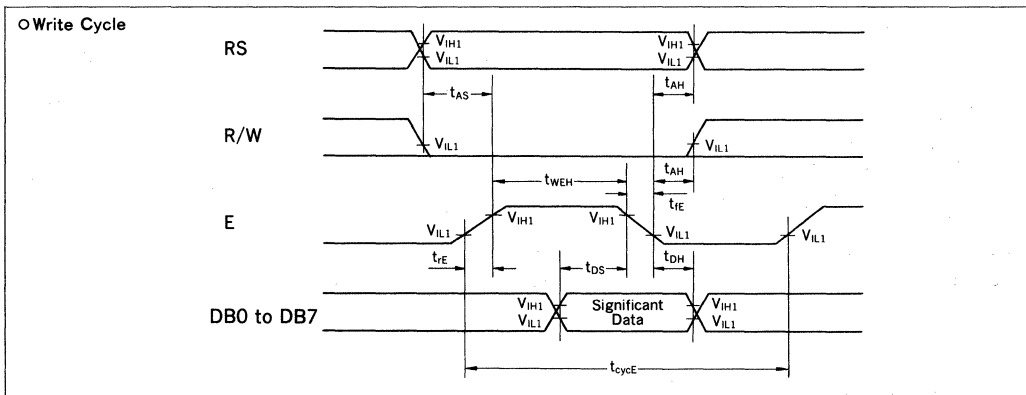
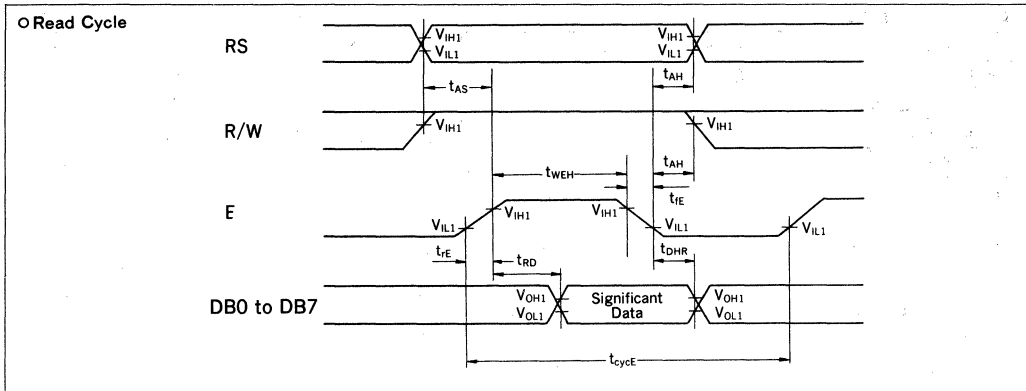
#### ○ Write Cycle

( $V_{DD}=5.0V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a = -20$  to  $75^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Enable cycle time	$t_{cycE}$		500	—	—	ns
Enable "H" level pulse width	$t_{WEH}$		220	—	—	ns
Enable rise/fall time	$t_{rE}$ , $t_{fE}$		—	—	25	ns
RS, R/W setup time	$t_{AS}$		40	—	—	ns
RS, R/W address hold time	$t_{AH}$		10	—	—	ns
Data setup time	$t_{DS}$		60	—	—	ns
Write data hold time	$t_{DH}$		10	—	—	ns



## ● Timing Chart

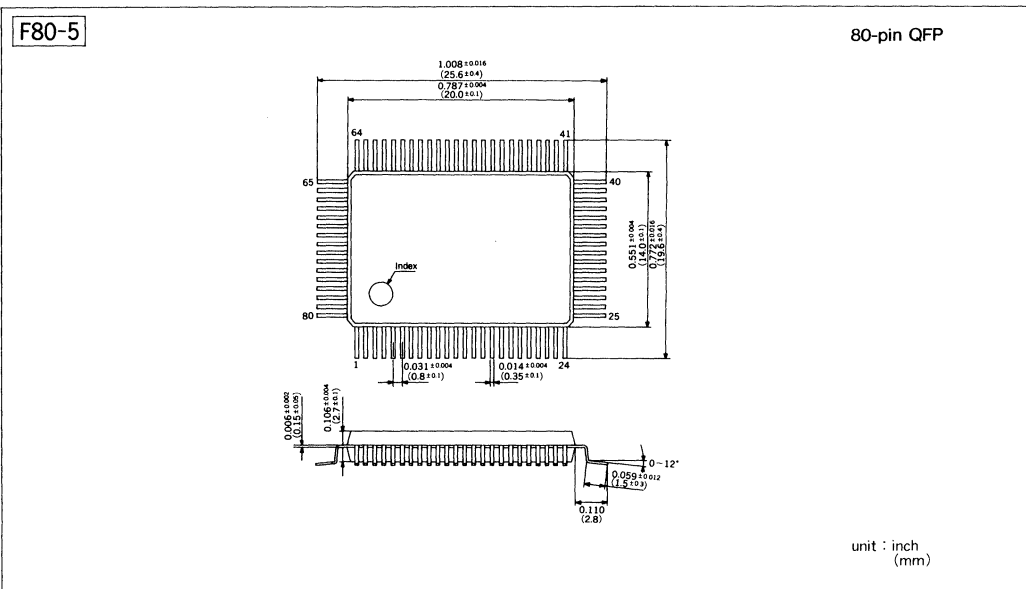


## ■ DISPLAY COMMAND

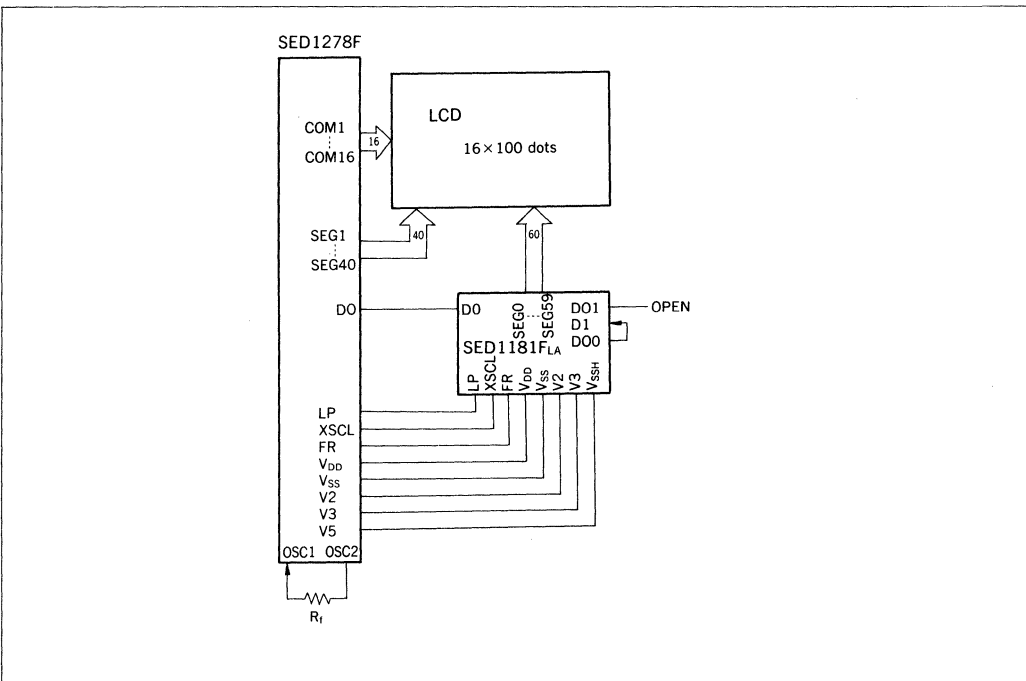
COMMAND	RS	R/W	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0	Note
CLEAR DISPLAY	0	0	0	0	0	0	0	0	0	1	
CURSOR HOME	0	0	0	0	0	0	0	0	1	*	
ENTRY MODE SET	0	0	0	0	0	0	0	1	I/D	S	DB1=1: Increment, DB1=0: Decrement DB0=1: The display is shifted. DB0=0: The display is not shifted.
DISPLAY ON/OFF	0	0	0	0	0	0	1	D	C	B	DB2=1: Display on DB2=0: Display off DB1=1: Cursor on DB1=0: Cursor off DB0=1: Brinking on DB0=0: Brinking off
CURSOR/DISPLAY SHIFT	0	0	0	0	0	1	S/C	R/L	*	*	DB3=1: Shifts display one character DB2=1: Right shift, DB2=0: Left shift
SYSTEM SET	0	0	0	0	1	DL	N	F	*	*	DB4=1: 8 bits, DB4=0: 4 bits DB3=1: 2 lines display (1/16 duty), DB3=0: 1 line display (DB2=1: 5×10 dots, 1/11 duty) (DB2=0: 5×7 dots, 1/8 duty)
SET CGRAM ADDRESS	0	0	0	1	ACG					The address length that can be set is 64 addresses.	
SET DDRAM ADDRESS	0	0	1	ADD					The address length that can be set is 80 addresses.		
READ BUSY FLAG/ ADDRESS COUNTER	0	1	BF	AC					DB7=1: Busy (instruction not accepted) DB7=0: Ready (instruction accepted)		
WRITE DATA	1	0	Write Data								
READ DATA	1	1	Read Data								

\*Don't care

■ PACKAGE DIMENSIONS



■ EXAMPLE OF APPLICATION (2 lines × 20 characters)



SED1278F is usually connected to 8-bit MPU via I/O ports.

■ CHARACTER CODE MAP (SED1278F0A)

		Higher 4bit (D4 to D7) of Character Code (Hexadecimal)																
		0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	
Lower 4bit (D0 to D3) of Character Code (Hexadecimal)	0	CG RAM (1)			0	0	P	`	P					-	9	E	0	p
	1	CG RAM (2)	!	1	A	Q	a	4					▣	7	†	4	ä	q
	2	CG RAM (3)	"	2	B	R	b	r					Γ	ι	ψ	×	ε	θ
	3	CG RAM (4)	#	3	C	S	c	s					┘	ウ	〒	E	ε	∞
	4	CG RAM (5)	\$	4	D	T	d	t					\	ι	†	†	μ	o
	5	CG RAM (6)	%	5	E	U	e	u					•	オ	†	1	ε	ü
	6	CG RAM (7)	&	6	F	V	f	v					ヲ	カ	ニ	ヨ	ρ	Σ
	7	CG RAM (8)	'	7	G	W	g	w					フ	†	7	7	g	π
	8	CG RAM (1)	(	8	H	X	h	x					イ	ウ	*	リ	ル	ア
	9	CG RAM (2)	)	9	I	Y	i	y					5	†	レ	レ	'	γ
	A	CG RAM (3)	*	:	J	Z	j	z					ε	コ	レ	V	j	†
	B	CG RAM (4)	+	;	K	[	k	[					*	ウ	レ	コ	*	ア
	C	CG RAM (5)	,	<	L	¥	l	l					ト	3	フ	フ	†	ア
	D	CG RAM (6)	-	=	M	^	m	^					ユ	ズ	レ	レ	レ	レ
	E	CG RAM (7)	.	>	N	^	n	^					α	レ	レ	レ	レ	レ
	F	CG RAM (8)	/	?	O	_	o	+					ウ	ウ	7	7	°	◻

\* Character codes (00H-0FH) of SED1278F are assigned to the area of character generator RAM (CG RAM).  
 The CG ROM of the SED1278F is masked; if you wish to have your own CG ROM, consult Seiko Epson Marketing Department for conversion of the masked ROM.

# SED1500F Series

## CMOS DOT MATRIX LCD DRIVER

● Duty 1/7–1/16 LCD Driver

● Single Chip LCD Driver (with Built in Display Data RAM)

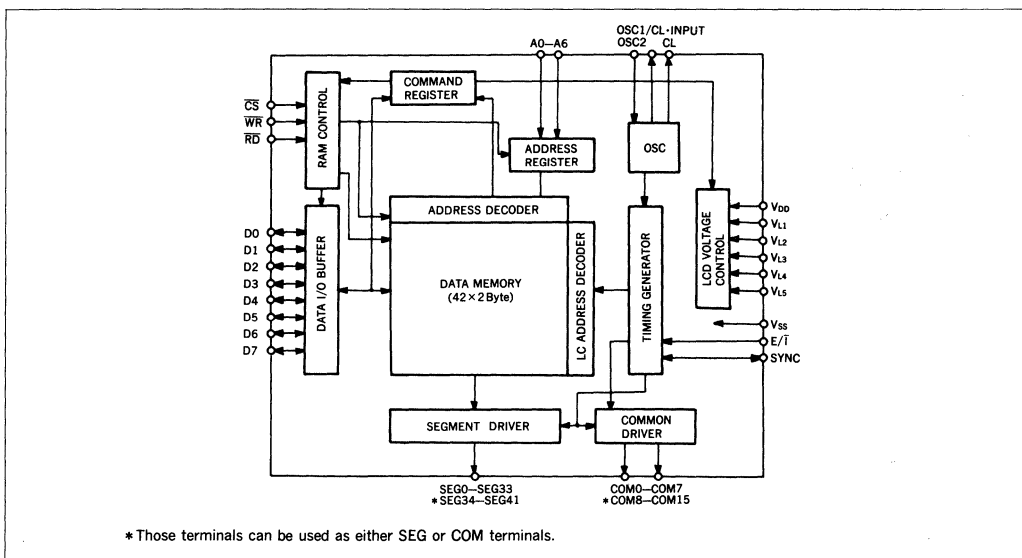
### DESCRIPTION

The SED1500F series is a dot matrix LCD driver CMOS LSI with the ability of alpha numeric and graphic display. Because of a built-in display data RAM, the necessary operation for drive is only writing of display data. Moreover, this LSI can be connected directly to the bus line of a 4 bits/8 bits microcomputer. Therefore the combinations of CMOS microcomputer and the SED1500F Series make it easier to systematize the handy instruments requiring low power dissipation.

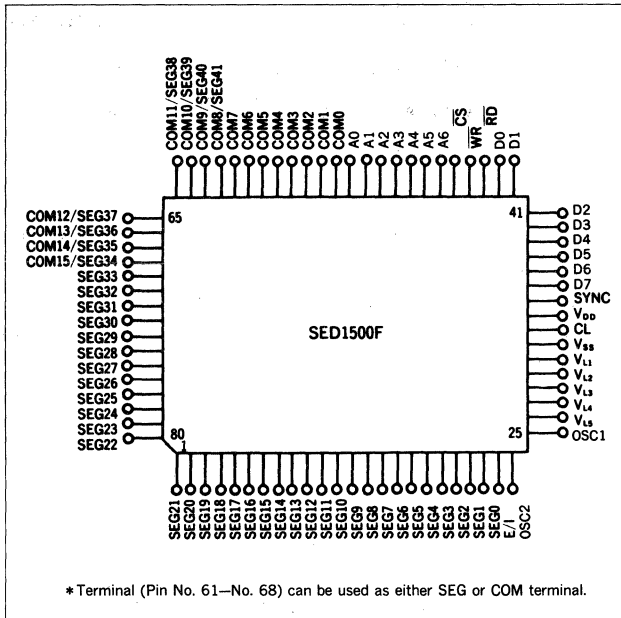
### FEATURES

- Built-in display data RAM
- Built-in driver for LCD segment and LCD common
- Dot drive capability : Common-single system 336 to 544 dots (per chip)
- Common-multi system 336 to 672 dots (per chip)
- Direct connection capability to the bus line of a 4 bits/8 bits microcomputer.
- Duty 1/7–1/16 setting capability (mask option)
- Built-in CR oscillation circuit (without resistor)
- Low power dissipation
- Package.....80-pin QFP (plastic)

### BLOCK DIAGRAM



## PIN CONFIGURATION



## PIN DESCRIPTION

A0 to A6	RAM Address
D0 to D7	Data Input/Output
$\overline{RD}$	Read Enable
$\overline{WR}$	Write Enable
OSC1, OSC2	Oscillation Circuit
$\overline{CS}$	Chip Select Input
CL	Clock Output
$E/\overline{T}$	Master/Slave Selection
SYNC	Slave Synchronous Input/Output
COM0 to COM15	LCD Common (Y) Drive Output
SEG0 to SEG41	LCD Segment (X) Drive Output
$V_{L1}$ to $V_{L5}$	LCD Drive Power Supply
$V_{DD}$	Power Supply (+)
$V_{SS}$	Logic Power Supply (-)

## ABSOLUTE MAXIMUM RATINGS

( $V_{DD}=0V$ )

Parameter	Symbol	Ratings	Unit
Supply voltage	$V_{SS}$	-7.0 to 0.3	V
	$V_{L1}$ to $V_{L5}$	-13.0 to 0.3	V
Input voltage	$V_I$	$V_{SS}-0.3$ to $V_{DD}+0.3$	V
Operating temperature	$T_{opr}$	-20 to 75	°C
Storage temperature	$T_{stg}$	-65 to 150	°C
Soldering temperature and time	$T_{sol}$	260°C, 10s (at lead)	—

## ELECTRICAL CHARACTERISTICS

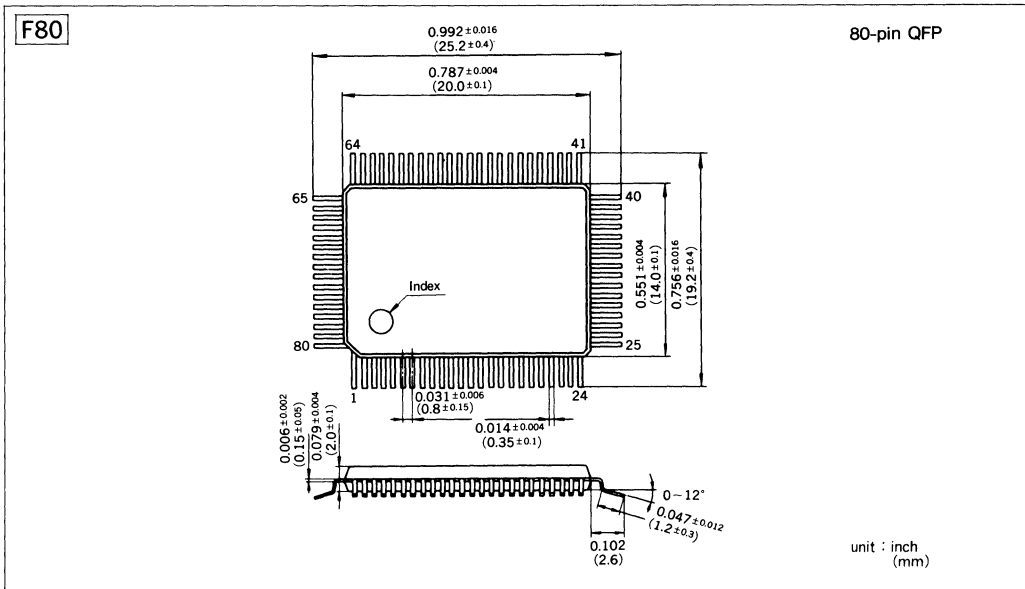
### DC Characteristics

( $V_{DD}=0V$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	$V_{SS}$		-4.5	*1	-5.5	V
Supply voltage	$V_{L5}$		-3.5	—	-10	V
Operating dissipation	$I_{OP1}$	$V_{SS} = -5.5V$ $\overline{CS} = H$ $V_{L5} = -10.0V$ $R_f = 1.0M\Omega$	—	60	100	$\mu A$
Oscillation start voltage	$V_{STA}$	$R_f = 1.0M\Omega$	—	—	-2.0	V
Oscillation stop voltage	$V_{STP}$	$R_f = 1.0M\Omega$	—	—	-2.0	V
Read cycle time	$t_{c(RD)}$	$V_{SS} = -5V$ $V_{IH} = V_{OH} = -2.0V$ $V_{IL} = V_{OL} = V_{SS} + 0.8V$ $C_L = 100pF + 1TTL$	1,000	—	—	ns
Write cycle time	$t_{c(WR)}$		1,000	—	—	ns
Access time	$t_a$		—	—	800	ns

\*1 In the case of operating voltage  $V_{SS}$  at  $V_{DD} - 3.0V$ , inquire of IC SALES DEPT.

## ■ PACKAGE DIMENSIONS



## ■ SED1500F SERIES

The capacity of the SED1500F series is varied as follows with a duty of LCD multiplex drive.

### ● Common-single series

### ● Common-multi series

\*1

Duty	Type	No. of COM output	No. of SEG output
1/7	SED1507F	7	42
1/8	SED1500F	8	42
1/10	SED1501F	10	40
1/11		11	39
1/12		12	38
1/13		13	37
1/14		14	36
1/15		15	35
1/16	SED1502F	16	34

Duty	Type	No. of COM output	No. of SEG output
1/8		4	42
1/9		5	42
1/10		5	42
1/11		6	42
1/12		6	42
1/13		7	42
1/14		7	42
1/15		8	42
1/16	SED1503F	8	42

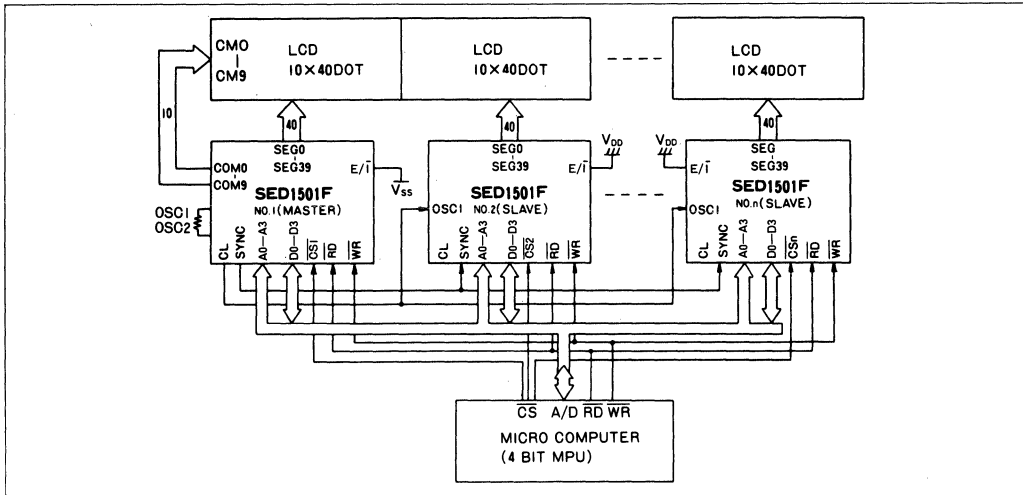
\*1 The driver is open-ended by the cascade connection.

\*2 Above-mentioned Duties are all realized by the mask option. Listed types are already available. As to other ones, please inquire of our IC Sales Dept.

■EXAMPLE OF APPLICATIONS (Connection among the SED1500F Series, LCD and MPU)

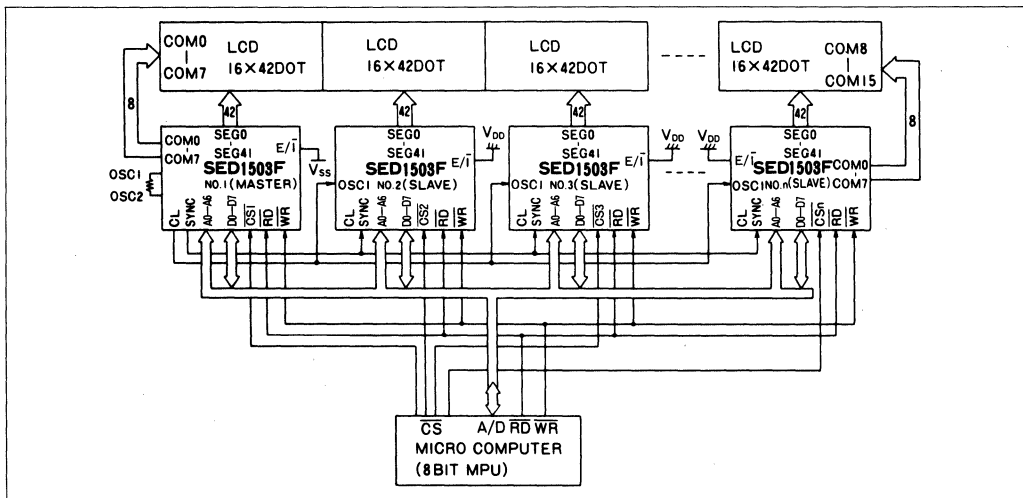
- An example of multichip composition by the common-single series.

Number of display dots =  $10 \times 40 \times n$   $n=1-10$  (in the case of SED1501F)



- An example of multichip composition by the common-multi series.

Number of display dots =  $16 \times 42 \times n$   $n=2-10$  (in the case of SED1503F)



# SED2020F<sub>0A</sub>/SED2020F<sub>0B</sub>

## CMOS VFD DRIVER

- High-voltage CMOS Driver (70V: 10mA/bit)
- Transfer Clock (4MHz Max)
- Shift Registers and Latch Circuits are Built-in

### DESCRIPTION

The SED2020F<sub>0A</sub> is a 20 bits (10 bits × 2) driver for vacuum fluorescent displays (VFD). The SED2020F<sub>0A</sub> is designed to drive both the anode and grid of the VFD. A cascade connection of multiple SED2020F<sub>0A</sub>s allows to expand characters and segments.

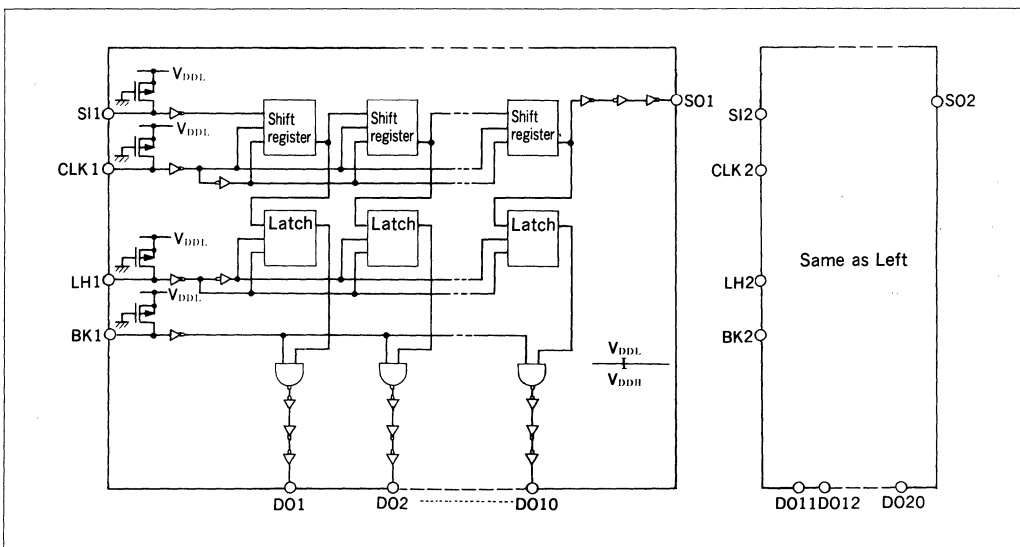
High voltage (70V Max) CMOS designed output circuit eliminates the external pull-down resistors to the output. The fast rise/fall time (1μs Max) enables a clear display which is free from afterglow.

The input circuit has a CMOS structure (logic level: 1.55V) with pull-up resistors, and can be directly driven by a standard logic IC such as TTL, LSTTL, CMOS, or HSCMOS.

### FEATURES

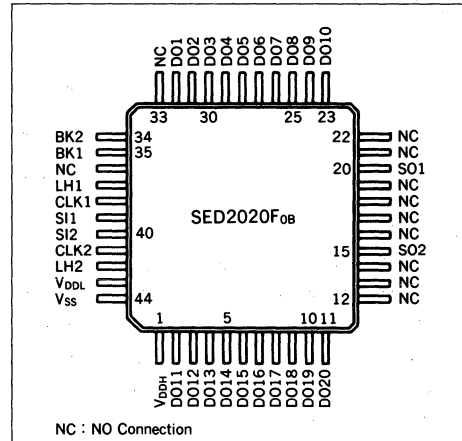
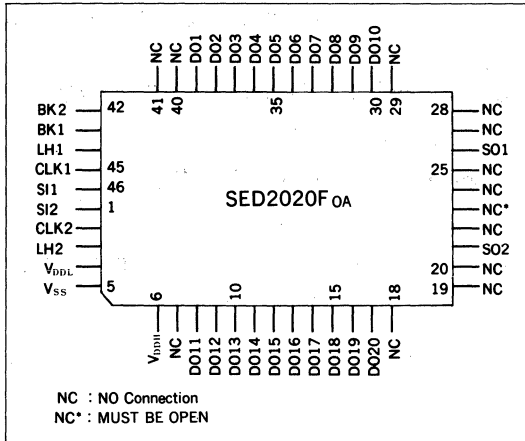
- High-voltage CMOS driver (70V: 10mA/bit)
- Anode/Grid driver for VFD
- On-chip serial input 10 bits shift register × 2 (20 bits in total)
- Transfer clock .....4MHz
- Logic supply voltage .....V<sub>DDL</sub> = 5V ±10%
- Package.....46-pin QFP (plastic)/44-pin QFP (plastic)

### BLOCK DIAGRAM





## PIN CONFIGURATION



## PIN DESCRIPTION

Symbol	Pin Name	Function
CLK1	Clock input	Data is read from SI during "L" of CLK; data shifts to SO at rising edge of CLK.
CLK2		
SI1	Data input	Serial data input to shift registers
SI2		
SO1	Data output	Serial data output from shift registers
SO2		
LH1	Latch clock input	Data of shift register are read during "H" of LH; data of shift register are latched at falling edge of the signal.
LH2		
BK1	Blanking	Entire display can be turned off during "H".
BK2		
DO	Driver output	High-voltage CMOS output
V <sub>SS</sub>	Power supply	GND (0V)
V <sub>DDL</sub>	Power supply	Supply for logic (5V)
V <sub>DDH</sub>	Power supply	Supply for driver (70V)

## ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V, T<sub>a</sub>= -10 to 70°C)

Parameter	Symbol	Ratings	Unit
Supply voltage (driver)	V <sub>DDH</sub>	-0.3 to 70	V
Supply voltage (logic)	V <sub>DDL</sub>	-0.3 to 7	V
Driver output voltage	V <sub>DO</sub>	V <sub>SS</sub> -0.3 to V <sub>DDH</sub> +0.3	V
Input/output voltage	V <sub>I/O</sub>	V <sub>SS</sub> -0.3 to V <sub>DDL</sub> +0.3	V
Driver high level output current	I <sub>OHDO</sub>	-15 to 0	mA
Driver low level output current	I <sub>OLDO</sub>	0 to 3	mA
Power dissipation	P <sub>D</sub>	0 to 250	mW
Operating temperature	T <sub>opr</sub>	-10 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

## RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage (driver)	V <sub>DDH</sub>		30	60	70	V
Supply voltage (logic)	V <sub>DDL</sub>		4.5	5.0	5.5	V
Input voltage	V <sub>I</sub>		0	—	V <sub>DDL</sub>	V
Input logic level	V <sub>LL</sub>	TTL input level	—	1.55	—	V
Driver High level output current	I <sub>OHD0</sub>	Grid output	—	-10	—	mA
		Anode output	—	-0.5	—	mA
Clock frequency	f <sub>clock</sub>	Cascade connection	0	—	4	MHz
Clock pulse width	t <sub>wclock</sub>		125	—	—	ns
Setup time	t <sub>setup</sub>		125	—	—	ns
Hold time	t <sub>hold</sub>		0	—	—	ns
Latch pulse width	t <sub>wlatch</sub>		250	—	—	ns

## ELECTRICAL CHARACTERISTICS

### DC Electrical Characteristics

(V<sub>DDL</sub> = 5V, V<sub>DDH</sub> = 60V, V<sub>SS</sub> = 0V, T<sub>a</sub> = 25°C)

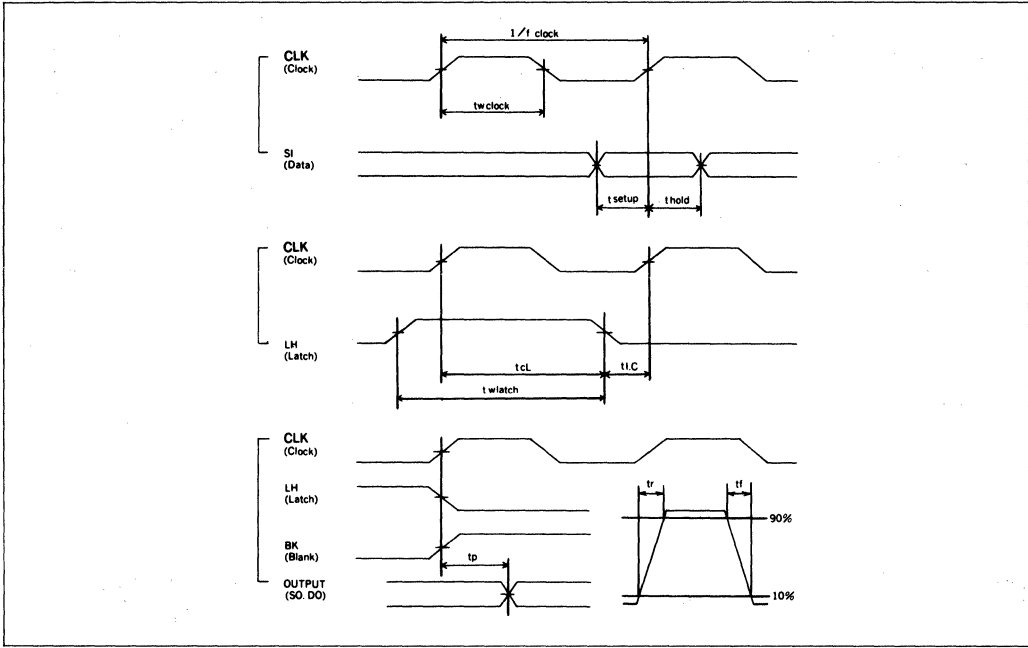
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
High level input voltage	V <sub>IH</sub>		2.4	—	V <sub>DDL</sub>	V
Low level input voltage	V <sub>IL</sub>		0	—	0.7	V
High level input current	I <sub>IH</sub>	V <sub>IH</sub> = 5.3V	—	33	100	μA
Low level input current	I <sub>IL</sub>	V <sub>IL</sub> = 0V	-160	-100	—	μA
High level output current	I <sub>OH</sub> (SO)	V <sub>OH</sub> = 4.6V	—	-1.4	-0.44	mA
Low level output current	I <sub>OL</sub> (SO)	V <sub>OL</sub> = 0.4V	1.6	2.1	—	mA
Supply current (V <sub>DDL</sub> )	I <sub>DDL</sub>	f <sub>clock</sub> = 4MHz	—	—	5	mA
Supply current (V <sub>DDH</sub> )	I <sub>DDH</sub>	At all drivers output "H"	—	—	2.0	mA
Driver high level output current	I <sub>OHD0</sub>	V <sub>OHD0</sub> = 55V at output "H"	—	—	-10	mA
Driver low level output current	I <sub>OLD0</sub>	V <sub>OLD0</sub> = 5V at output "L"	1	—	—	mA

### AC Electrical Characteristics

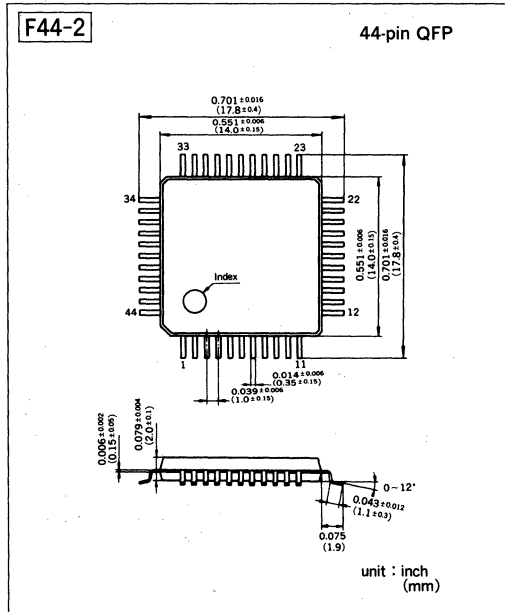
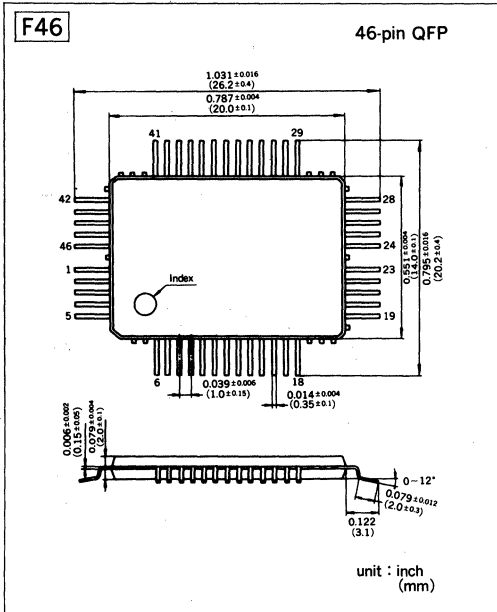
(V<sub>DDL</sub> = 5V, V<sub>DDH</sub> = 60V, V<sub>SS</sub> = 0V, T<sub>a</sub> = 25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Clock-latch delay time	t <sub>CL</sub>	1. Input signal conditions (1) Amplitude: 0–5V (2) Rise/fall time should be 15ns or less.	125	—	—	ns
Latch-clock delay time	t <sub>LC</sub>		0	—	—	ns
Output(SO) rise time	t <sub>r</sub> (SO)	(3) Measuring voltage should be 2.5V.	—	—	50	ns
Output(SO) fall time	t <sub>f</sub> (SO)		—	—	50	ns
Clock(SO) delay time	t <sub>p</sub> (SO)	2. Output signal conditions (1) Standard loads are: 13pF, 10MΩ (2) Measuring voltage should be 2.5V or 1/2 of the amplitude.	—	—	125	ns
Output(DO) rise time	t <sub>r</sub> (DO)		—	—	1	μs
Output(DO) fall time	t <sub>f</sub> (DO)		—	—	1	μs
BK-DO transfer time	t <sub>p</sub> (DO)		—	—	2	μs

# Timing Chart

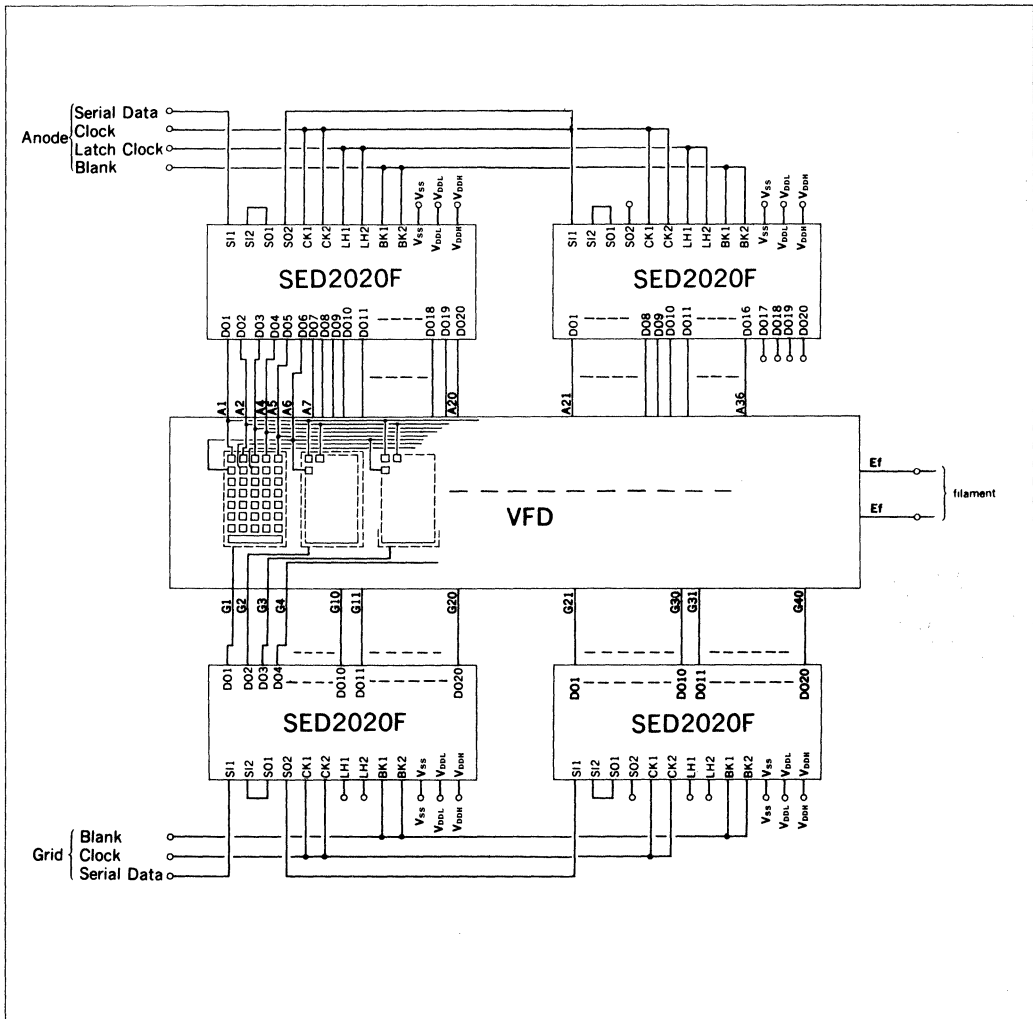


# PACKAGE DIMENSIONS

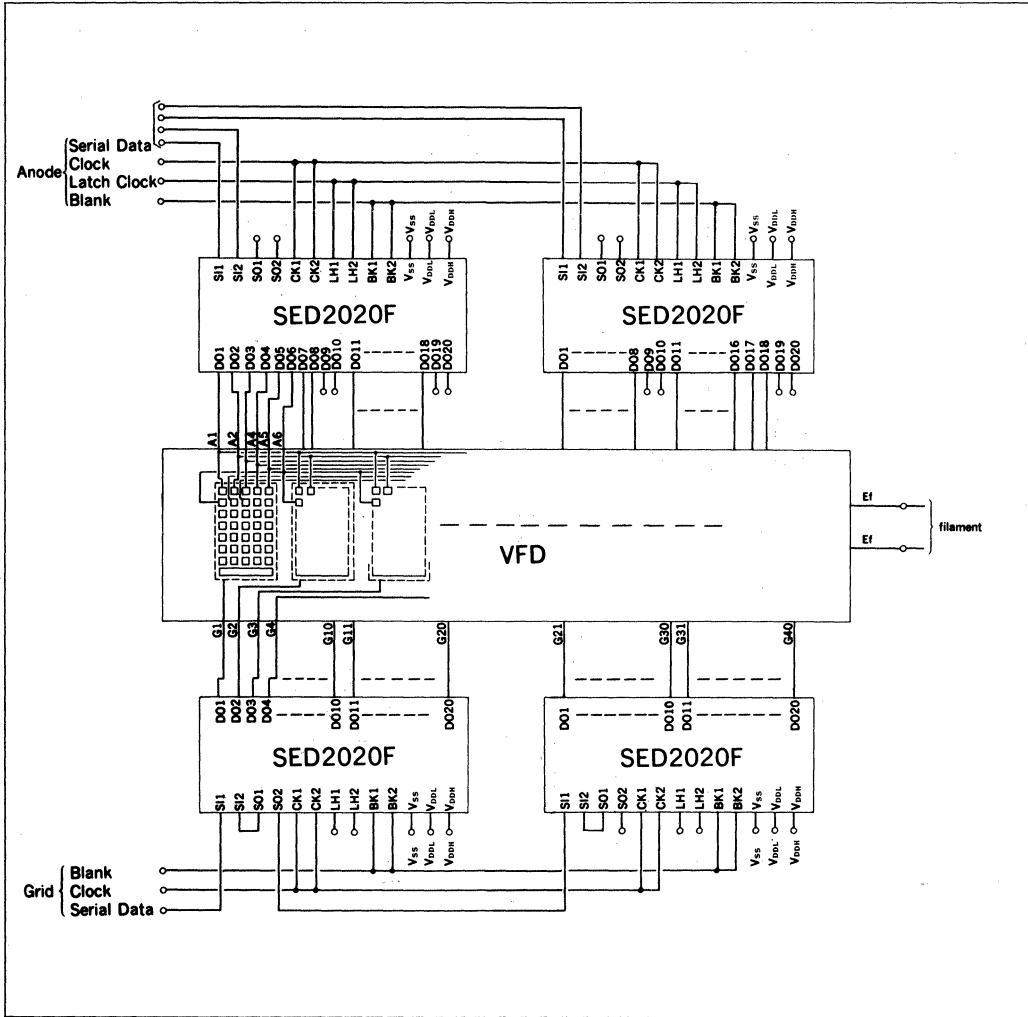


■ TYPICAL CONNECTIONS

- Example of connecting SED2020F's to VFD (1)
- <1 bit serial>



● Example of connecting  
 SED2020F's to VFD (2)  
 <4bits serial>



# SED2032F<sub>0B</sub>

## CMOS VFD DRIVER

- High-voltage CMOS Driver (70V: 10mA/bit)
- Transfer Clock (4MHz Max)
- Shift Registers and Latch Circuits are Built-in

### DESCRIPTION

The SED2032F<sub>0B</sub> is a 32 bits (16 bits × 2) driver for vacuum fluorescent displays (VFD). The SED2032F<sub>0B</sub> is designed to drive both the anode and grid of the VFD. A cascade connection of multiple SED2032F<sub>0B</sub> allows to expand characters and segments.

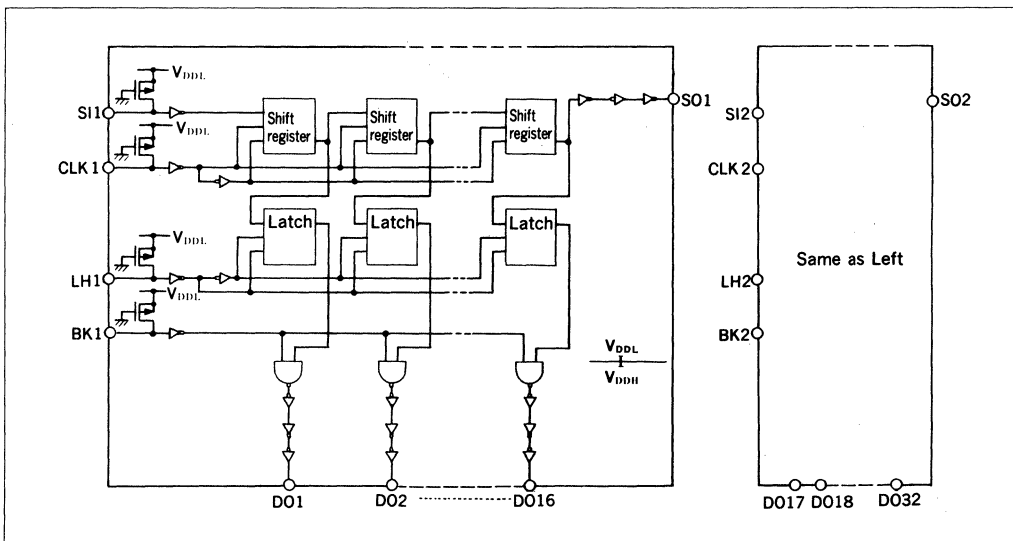
High voltage (70V Max) CMOS designed output circuit eliminates the external pull-down resistors to the output. The fast rise/fall time (1μs Max) enables a clear display which is free from afterglow.

The input circuit has a CMOS structure (logic level: 1.55V) with pull-up resistors, and can be directly driven by a standard logic IC such as TTL, LSTTL, CMOS, or HSCMOS.

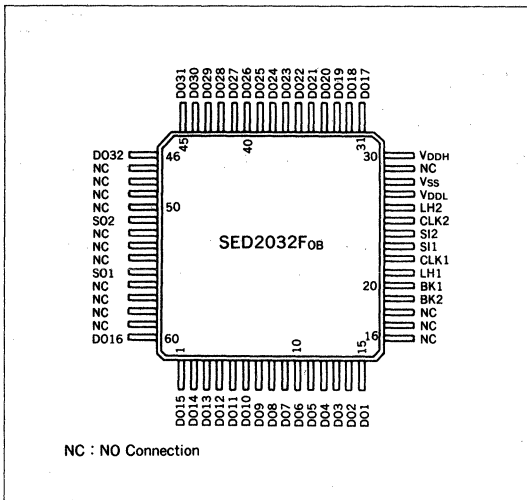
### FEATURES

- High-voltage CMOS driver (70V: 10mA/bit)
- Anode/Grid driver for VFD
- On-chip serial input 16 bits shift register × 2 (32 bits in total)
- Transfer clock .....4MHz
- Logic supply voltage .....V<sub>DDL</sub> = 5V ±10%
- Package.....60-pin QFP (plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

Pin No.	Symbol	Pin Name	Functions
22	CLK1	Clock input	Data is read from SI during "L" of CLK; data shifts to SO at rising edge of CLK.
25	CLK2		
23	SI1	Data input	Serial data input to shift registers
24	SI2	Data input	
51	SO1	Data output	Serial data output from shift registers
55	SO2	Data output	
21	LH1	Latch clock input	Data of shift register are read during "H" of LH; data of shift register are latched at falling edge of the signal.
26	LH2		
20	BK1	Blanking	Entire display can be turned off during "H"
19	BK2		
15 to 1, 60 31 to 46	DO	Driver output	High-voltage CMOS output
28	V <sub>SS</sub>	Power supply	GND (0V)
27	V <sub>DDL</sub>	Power supply	Supply for logic (5V)
30	V <sub>DDH</sub>	Power supply	Supply for driver (70V)

### ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V, T<sub>a</sub> = -10 to 70°C)

Parameter	Symbol	Ratings	Unit
Supply voltage (driver)	V <sub>DDH</sub>	-0.3 to 70	V
Supply voltage (logic)	V <sub>DDL</sub>	-0.3 to 7	V
Driver output voltage	V <sub>DO</sub>	V <sub>SS</sub> - 0.3 to V <sub>DDH</sub> + 0.3	V
Input/output voltage	V <sub>I/O</sub>	V <sub>SS</sub> - 0.3 to V <sub>DDL</sub> + 0.3	V
Driver high level output current	I <sub>OHD0</sub>	-15 to 0	mA
Driver low level output current	I <sub>OLD0</sub>	0 to 3	mA
Power dissipation	P <sub>D</sub>	0 to 250	mW
Operating temperature	T <sub>opr</sub>	-10 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

### RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage (driver)	V <sub>DDH</sub>		30	60	70	V
Supply voltage (logic)	V <sub>DDL</sub>		4.5	5.0	5.5	V
Input voltage	V <sub>i</sub>		0	—	V <sub>DDL</sub>	V
Input logic level	V <sub>LL</sub>	TTL input level	—	1.55	—	V
Driver High level output current	I <sub>OHD0</sub>	Grid output	—	-10	—	mA
		Anode output	—	-0.5	—	mA
Clock frequency	f <sub>clock</sub>	Cascade connection	0	—	4	MHz
Clock pulse width	t <sub>wclock</sub>		125	—	—	ns
Setup time	t <sub>setup</sub>		125	—	—	ns
Hold time	t <sub>hold</sub>		0	—	—	ns
Latch pulse width	t <sub>wlatch</sub>		250	—	—	ns

## ELECTRICAL CHARACTERISTICS

### DC Electrical Characteristics

( $V_{DDL}=5V$ ,  $V_{SS}=0V$ ,  $V_{DDH}=60V$ ,  $T_a=25^\circ C$ )

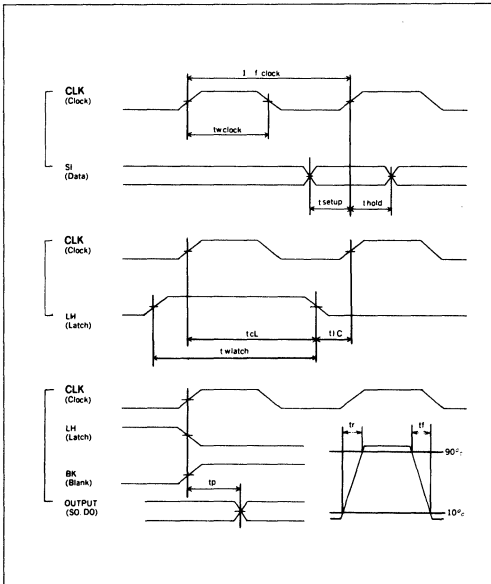
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
High level input voltage	$V_{IH}$		2.4	—	$V_{DDL}$	V
Low level input voltage	$V_{IL}$		0	—	0.7	V
High level input current	$I_{IH}$	$V_{IH}=5.3V$	—	33	100	$\mu A$
Low level input current	$I_{IL}$	$V_{IL}=0V$	-160	-100	—	$\mu A$
High level output current	$I_{OH}(SO)$	$V_{OH}=4.6V$	—	-1.4	-0.44	mA
Low level output current	$I_{OL}(SO)$	$V_{OL}=0.4V$	1.6	2.1	—	mA
Supply current ( $V_{DDL}$ )	$I_{DDL}$	f clock=4MHz	—	—	5	mA
Supply current ( $V_{DDH}$ )	$I_{DDH}$	At all drivers output "H"	—	—	3	mA
Driver high level output current	$I_{OHDO}$	$V_{OHDO}=55V$ at output "H"	—	—	-10	mA
Driver low level output current	$I_{OLD0}$	$V_{OLD0}=5V$ at output "L"	1	—	—	mA

### AC Electrical Characteristics

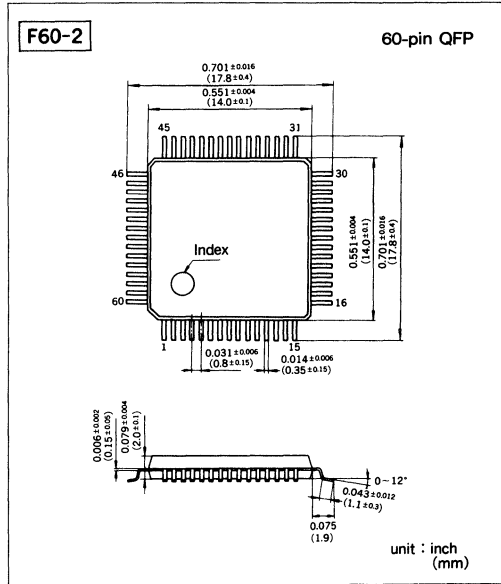
( $V_{DDL}=5V$ ,  $V_{SS}=0V$ ,  $V_{DDH}=60V$ ,  $T_a=25^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Clock-latch delay time	$t_{CL}$	1. Input signal conditions (1) Amplitude: 0-5V (2) Rise/fall time should be 15ns or less. (3) Measuring voltage should be 2.5V.	125	—	—	ns
Latch-clock delay time	$t_{LC}$		0	—	—	ns
Output(SO) rise time	$t_r(SO)$	2. Output signal conditions (1) Standard loads are : 13pF, 10M $\Omega$ (2) Measuring voltage should be 2.5V or 1/2 of the amplitude.	—	—	50	ns
Output(SO) fall time	$t_f(SO)$		—	—	50	ns
Clock(SO) delay time	$t_p(SO)$		—	—	125	ns
Output(DO) rise time	$t_r(DO)$		—	—	1	$\mu s$
Output(DO) fall time	$t_f(DO)$		—	—	1	$\mu s$
BK-DO transfer time	$t_p(DO)$		—	—	2	$\mu s$

### Timing Chart



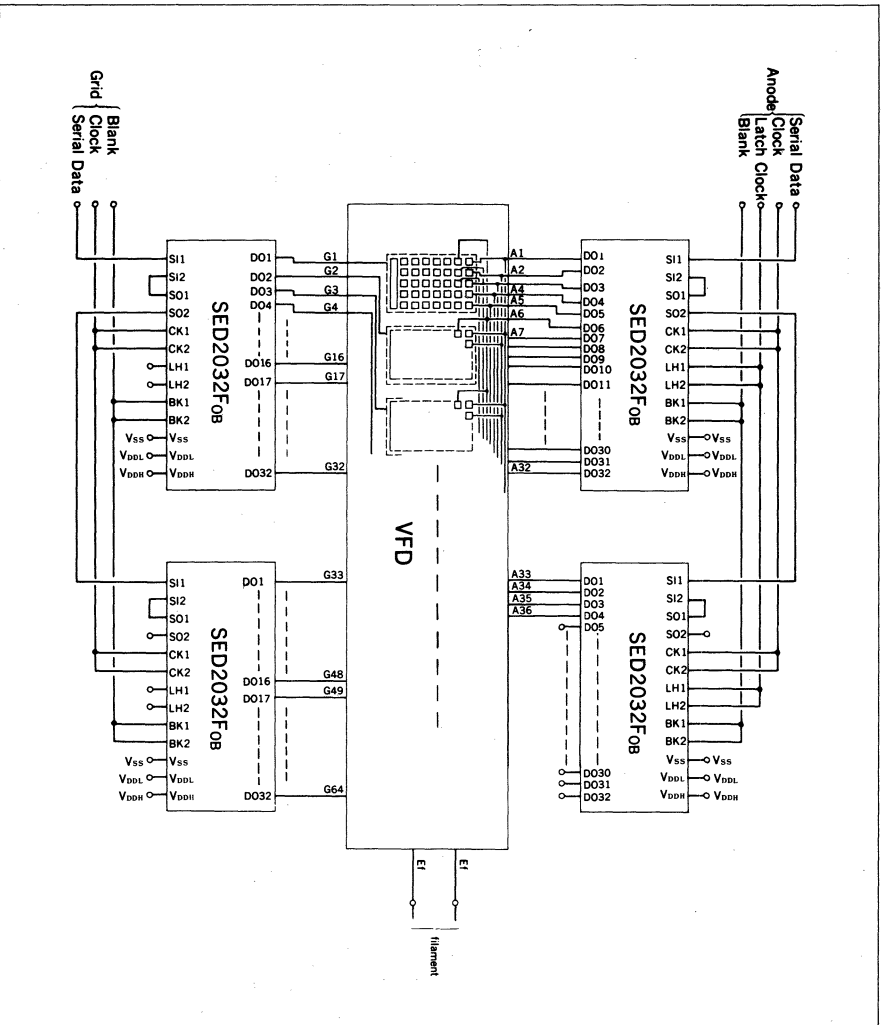
### PACKAGE DIMENSIONS





## TYPICAL CONNECTIONS

- Example of connecting SED2032F's to VFD
- <1 bit serial>



The SED2032F can be efficiently used as dot matrix LCD driver.

# SED5031C<sub>OC</sub>

## CMOS 12 BIT THERMAL HEAD DRIVER

- Built in 12bit static shift register
- 12bit latch circuits
- Output control circuits and built in 12bit driver

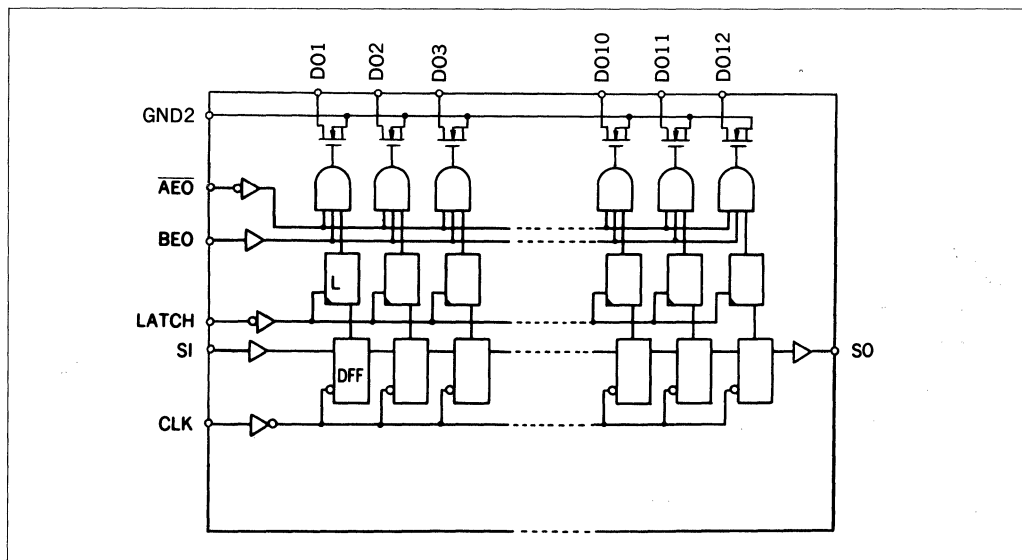
### DESCRIPTION

The SED5031C<sub>OC</sub> is a low power CMOS 12bit thermal head driver. It contains a 12bit high speed shift register, 12bit latch, output control circuit and 12bit driver with a drive capability of 28V/150mA allowing direct connection with thermal heads.

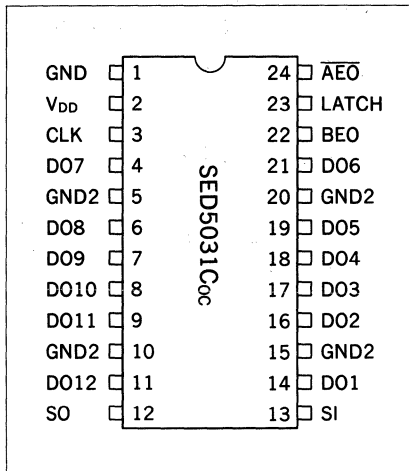
### FEATURES

- Built in 12bit static shift register
- Built in 12bit latch
- Built in output control circuit and 12bit driver
- High supply voltage for driver .....28V (Max)
- High output current .....150mA (Max)
- Low supply current .....0.3mA/2MHz (Typ)
- High speed operation .....7MHz (Max)
- Si gate CMOS process
- Package.....24-pin DIP (plastic)

### BLOCK DIAGRAM



### ■ PIN CONFIGURATION



### ■ PIN DESCRIPTION

Pin No.	Pin Name	Function
CLK	3	Clock input for static shift register.
SI	13	Serial data input to shift register.
SO	12	Serial data output from shift register.
LATCH	23	Latch signal input. Data in the shift register is latched when this signal goes low.
$\overline{AEO}$	24	Output enable A. Latched data is enabled for output to the driver when this signal is low. DO terminals are in the high impedance state when this signal is high.
BEO	22	Output enable B. Latched data is enabled for output when this signal is high. DO terminals are in the high impedance state when this signal is low.
DO <sub>n</sub>	14, 16~19, 21 4, 6~9, 11	Parallel data output terminals. (Open drain NMOS transistor output)
V <sub>DD</sub>	2	Power supply (+5V)
GND	1	Signal ground for input : 0V
GND2	5, 10, 15, 20	Ground for driver output terminals : 0V

### ■ ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Voltage supplied to driver	B <sub>VDO</sub>	28	V
Driver output current	I <sub>OLDO</sub>	150	mA
Input voltage	V <sub>I</sub>	-0.5 to V <sub>DD</sub> +0.5	V
Input current	I <sub>I</sub>	-20 to 20	mA
Output voltage	V <sub>O</sub>	-0.5 to V <sub>DD</sub> +0.5	V
Power dissipation	P <sub>D</sub>	0.65 (Ta=80°C)	W
Operating temperature	T <sub>opr</sub>	-10 to 80	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

### ■ RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
Input voltage	V <sub>I</sub>		0	—	V <sub>DD</sub>	V
Output high voltage DO <sub>n</sub>	V <sub>OHDO</sub>		0	12	24	V
Driver output current	I <sub>OLDO</sub>		—	120	150	mA
Clock frequency	f <sub>CLK1</sub>		—	2	7	MHz
	f <sub>CLK2</sub> *	*for cascade connection	—	2	5	MHz
Clock pulse width	t <sub>WCLK</sub>		70	—	—	ns
Setup time SI-CLK	t <sub>setup</sub>		50	—	—	ns
Setup time CLK-LATCH	t <sub>CL</sub>		100	—	—	ns
Hold time SI-CLK	t <sub>hold</sub>		10	—	—	ns
Latch pulse width	t <sub>WLATCH</sub>		50	—	—	ns

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

( $V_{DD}=5V$ ,  $T_a=25^\circ C$ )

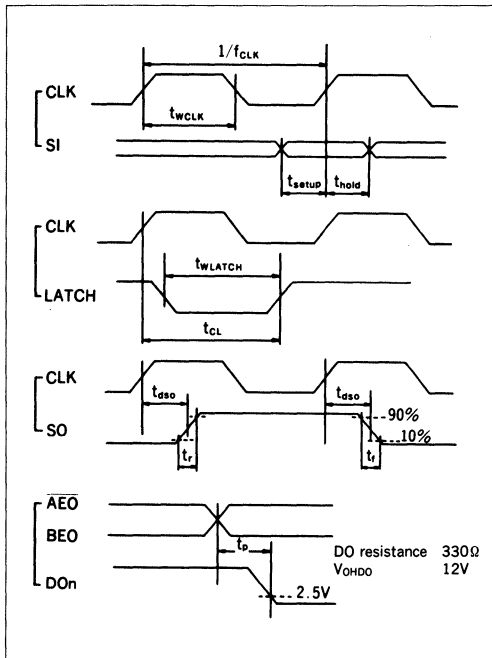
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input high voltage	$V_{IH}$		3.5	—	5.0	V
Input low voltage	$V_{IL}$		0	—	1.5	V
Input high current	$I_{IH}$	$V_{IH}=5.3V$	—	—	0.5	$\mu A$
Input low current	$I_{IL}$	$V_{IL}=-0.3V$	—	—	0.5	$\mu A$
Output high voltage (SO)	$V_{OH\ SO}$	$V_{DD}=4.5V$	4.45	—	—	V
Output low voltage (SO)	$V_{OL\ SO}$	$V_{DD}=4.5V$	—	—	0.05	V
Output high current (SO)	$I_{OH\ SO}$	$V_{OH}=4.2V$	0.5	2.5	—	mA
Output low current (SO)	$I_{OL\ SO}$	$V_{OL}=0.4V$	0.5	1.5	—	mA
Driver output voltage (DO <sub>n</sub> )	$V_{OL\ DO}$	$I_{OL\ DO}=120mA$	—	0.7	1.0	V
Driver output current (DO <sub>n</sub> )	$I_{OL\ DO}$	$V_{OL\ DO}=1.0V$	120	160	—	mA
$V_{DD}$ supply current	$I_{DD}$	$V_{DD}=5.5V$ , $f_{CLK}=5MHz$	—	1.5	5	mA
Output leakage	$I_{LO}$	$V_{DD}=4.5V$ , $V_{OH}=24V$	—	—	50	$\mu A$

### ● AC Electrical Characteristics

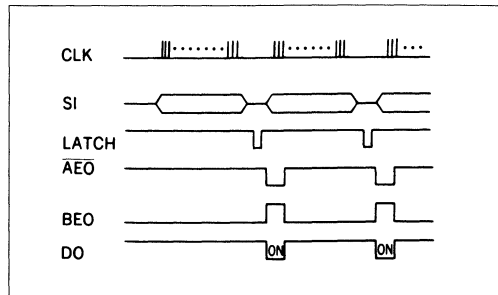
( $V_{DD}=5V$ ,  $T_a=80^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Output rise time	$t_r$	$C_L=13pF$	—	20	35	ns
Output fall time	$t_f$		—	20	35	ns
Output (SO) delay time	$t_{d\ so}$		—	70	120	ns
Low level propagation time	$t_p$		—	0.2	1	$\mu s$

### ● Timing Chart

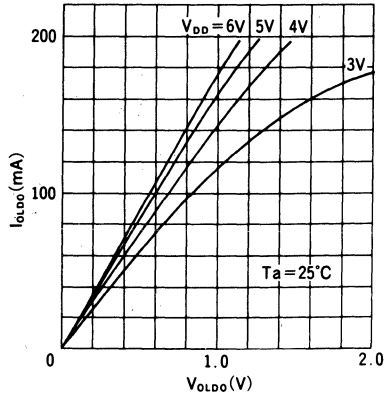


### ● Signal Sequence

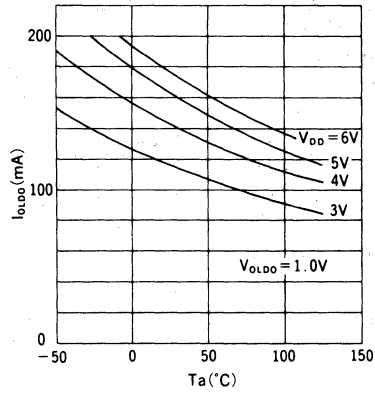


## ■ PERFORMANCE CURVES

Driver output current ( $I_{OLDO}$ )—Driver output voltage ( $V_{OLDO}$ )



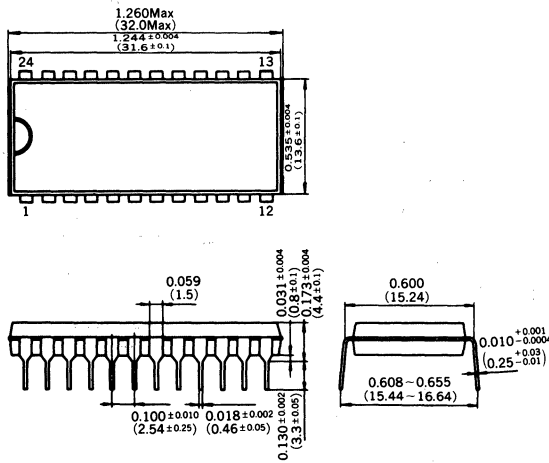
Driver output current ( $I_{OLDO}$ )—Ambient temperature ( $T_a$ )



## ■ PACKAGE DIMENSIONS

C24

24-pin DIP



unit : inch  
(mm)

# SED1330F

## CMOS GRAPHIC LCD CONTROLLER

- For Large-scale LCD
- Few External Circuits
- Virtual Screen Display RAM
- Enhanced Control Function

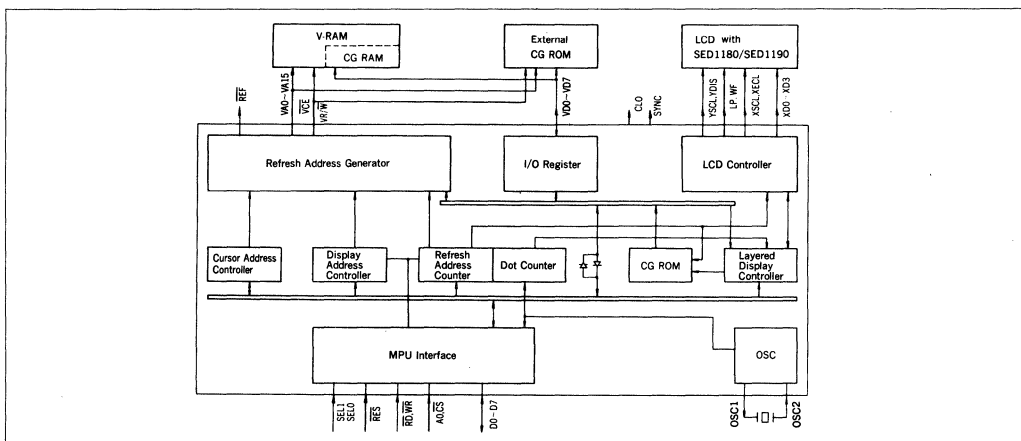
### DESCRIPTION

The SED1330F is a Graphic and Character display controller for large-scale dot matrix liquid crystal displays. The external frame buffer stores the character code and/or bit image data from a microprocessor. The data is periodically read out and outputted as the converted bit image data for the display. The SED1330F's enhanced control functions allow layered displays of the character and graphic screens, flexible scrolling and division of the display. The built-in external memory timing circuit, LCD module control circuit and high speed character generator make it easier to design an LCD control block requiring few external circuits.

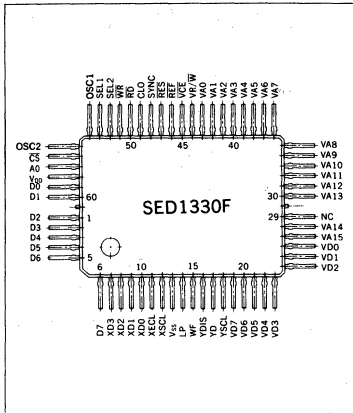
### FEATURES

- Automatic cursor shift function ..... 4 directions, up, down, right and left
- Flexible scrolling function ..... Free scrolling of the display window of character/graphic screen  
Smooth scrolling to right and left
- 3 modes of display ..... Character mode, Graphic mode, 2-screen layered mode
- Display dots ..... Character mode : 80 characters x 32 lines plus layered graphic screen  
Graphic mode : 256 x 640 dots x 3 screen
- Frame buffer memory space ..... 64K bytes
- Built-in Character Generator ..... 160 characters (5 x 7 dot matrix, mask programmable)
- External Character Generators ..... CGRAM : 64 characters (8 x 16 dot matrix)  
CGROM : 256 characters (8 x 16 dot matrix)
- LCD drive duty ratio ..... Static to 1/256 duty (programmable)
- 80 series or 68 series MPU interface (selectable)
- Low supply current ..... Operation : 5mA (Typ), Standby : 0.05 $\mu$ A (Typ)
- Single power supply ..... 5V  $\pm$  10%
- Package ..... 60 pin QFP (Plastic)

### BLOCK DIAGRAM



## PIN CONFIGURATION



## PIN DESCRIPTION

Pin Name	Pin No.	Functions	Pin Name	Pin No.	Functions
OSC1	54	Oscillator terminal (Input)	VA0 to VA15	27, 28, 29 to 42	VRAM address bus
OSC2	55	Oscillator terminal (Output)	VD0 to VD7	19 to 26	VRAM data bus
V <sub>DD</sub>	58	Power supply (+5V)	VR/W	44	VRAM R/W signal
V <sub>SS</sub>	13	Power supply (GND)	VCE	45	Memory control signal
SEL1,2	53, 52	MPU interface format selection	REF	46	Refresh signal for DRAM
D0 to D7	59, 60, 1 to 6	Data bus	XD0 to XD3	7-10	Dot data output bus to X driver
A0	57	Data type selection	XSCL	12	Dot data shift clock for X driver
RD	50	80 series Read strobe signal 88 series "E" clock	XECL	11	Chip enable shift clock for X driver
WR	51	80 Series Write strobe signal 88 series R/W signal	LP	14	Dot data latch pulse
CS	56	Chip select	WF	15	Frame signal
RES	47	Reset	YSCL	18	Scan data shift clock for Y driver
SYNC	48	I/O pin for synchronization signal	YD	17	Scan data output
CLO	49	Synchronized clock input for slave GLC	YDIS	16	Power down signal when display OFF

## ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.3 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5 to V <sub>DD</sub> + 0.5	V
Power dissipation	P <sub>D</sub>	0.3	W
Operating temperature	T <sub>opr</sub>	-20 to 75	°C
Storage temperature	T <sub>stg</sub>	-60 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

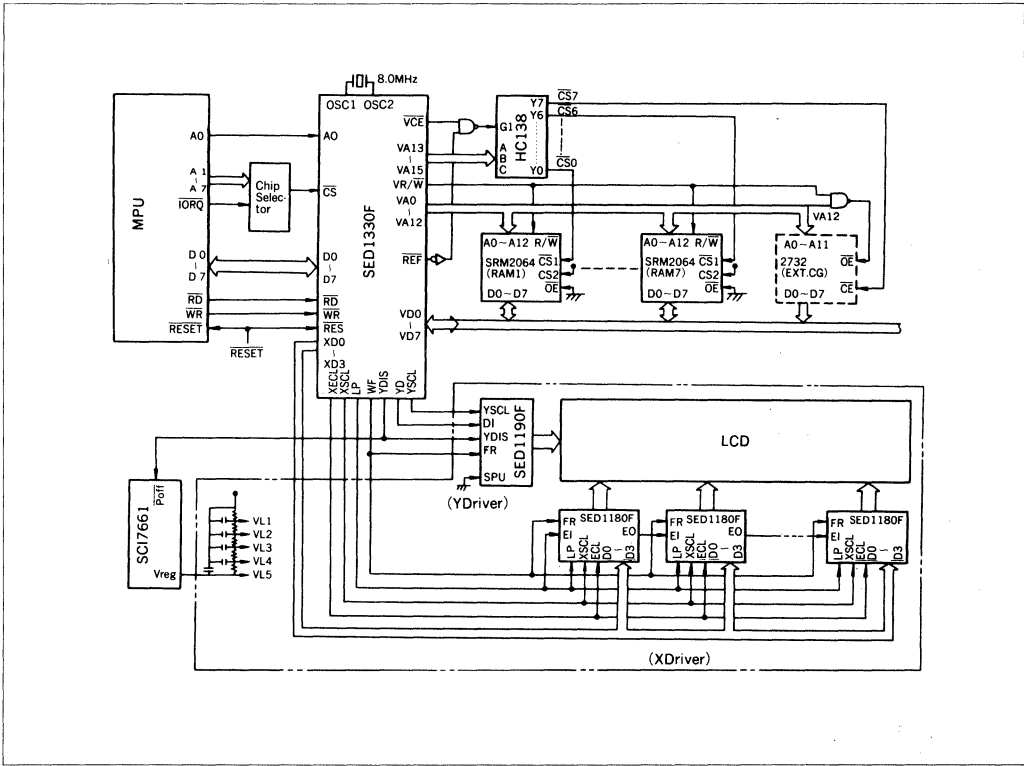
## ELECTRICAL CHARACTERISTICS

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = -20 to 75°C)

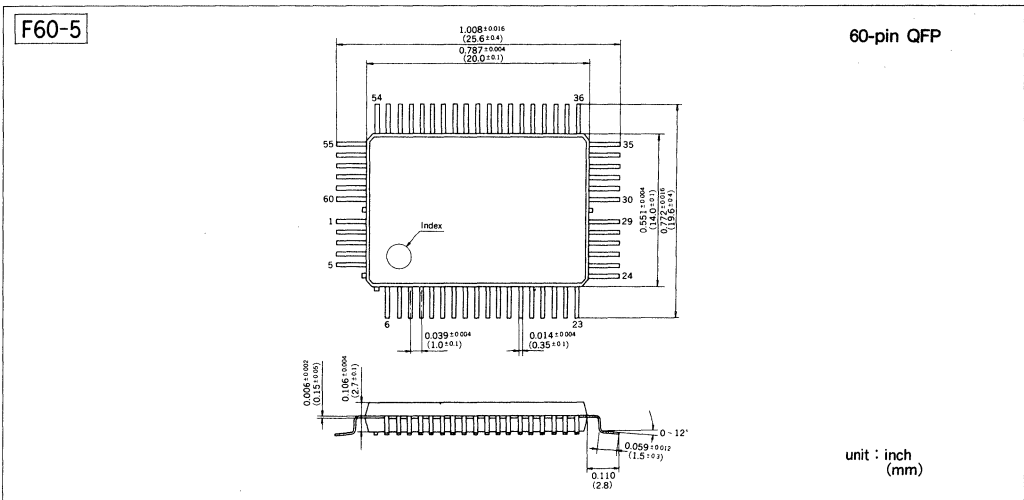
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Operating voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
Register data retention voltage	V <sub>DH</sub>		2.0	—	6.0	V
T T L	High level input voltage	D0 to D7, A0, CS, RD, WR, VD0 to VD7, IOH = -5.0mA, IOL = 5.0mA, VR/W, VCE, REF	2.2	—	V <sub>DD</sub> + 0.3	V
	Low level input voltage		-0.3	—	0.8	V
	High level output voltage		2.4	—	—	V
	Low level output voltage		—	—	0.4	V
C M O S	High level input voltage	IOH = 1.6mA, IOL = -1.6mA, SEL1, 2, SYNC, YD, XD0 to XD3, XSCL, XECL, LP, FR, YSCL, YDIS, OSC1, OSC2	0.8V <sub>DD</sub>	—	—	V
	Low level input voltage		—	—	0.2V <sub>DD</sub>	V
	High level output voltage		V <sub>DD</sub> - 0.4	—	—	V
	Low level output voltage		—	—	0.4	V
T T L	Positive trigger threshold voltage	RES *	0.5V <sub>DD</sub>	0.7V <sub>DD</sub>	0.8V <sub>DD</sub>	V
	Negative trigger threshold voltage		0.2V <sub>DD</sub>	0.3V <sub>DD</sub>	0.5V <sub>DD</sub>	V
Input leakage current	I <sub>LI</sub>	V <sub>I</sub> = V <sub>DD</sub> or V <sub>SS</sub>	—	0.05	2.0	μA
Output leakage current	I <sub>LO</sub>		—	0.10	5.0	μA
Average operating current	I <sub>DDA</sub>	f <sub>osc</sub> = 6.0MHz, No load (No external V-RAM)	—	5.0	6.5	mA
Standby current	I <sub>DDS</sub>	OSC1 = CS = V <sub>DD</sub>	—	0.05	20	μA
Oscillation frequency	f <sub>osc</sub>	AT X'tal OSC1, OSC2	1.0	—	10.0	MHz
External clock frequency	f <sub>CLK</sub>		—	—	10.0	MHz
Feed back resistance	R <sub>f</sub>		0.5	1.0	7.0	MΩ

\* RES input pulse should be longer than 1.0ms.  
V<sub>LS</sub> should be OFF when RES is "L".

■EXAMPLE OF APPLICATION



■PACKAGE DIMENSIONS





■ CHARACTER CODE TABLE (BUILT-IN CHARACTER GENERATOR)

		Lower 4 bit (D0 to D3) of Character Code (Hexadecimal)															
		0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Higher 4 bit (D4 to D7) of Character Code (Hexadecimal)	2		!	"	#	\$	%	&	'	(	)	*	+	,	-	.	/
	3	0	1	2	3	4	5	6	7	8	9	:	;	<	=	>	?
	4	@	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
	5	P	Q	R	S	T	U	V	W	X	Y	Z	[	¥	]	^	_
	6	'	a	b	c	d	e	f	g	h	i	j	k	l	m	n	o
	7	P	q	r	s	t	u	v	w	x	y	z	{		}	*	*
	A		。	「	」	・	ヲ	アイ	ウ	エ	オ	カ	ユ	ヨ	ツ		
	B	一	ア	イ	ウ	エ	オ	カ	キ	ク	ケ	コ	サ	シ	ス	セ	ソ
	C	タ	チ	ツ	テ	ト	ナ	ニ	ヌ	ネ	ノ	ハ	ヒ	フ	ヘ	ホ	マ
	D	ミ	ム	メ	モ	カ	ユ	ヨ	ラ	リ	ル	ロ	ワ	ヅ	ヅ	。	。
	1																

Note: ▨ means all dots of 6 x 8 matrix are on.

# SED1351F

## CMOS GRAPHIC LCD CONTROLLER

- Operation Under the Control of 8Bits or 16Bits MPU
- Cycle Steal Mode for MPU's Access to VRAM
- Maximum Display Capacity 1,024 × 512 Dots (524,288 Dots)

### DESCRIPTION

The SED1351F is a high-duty dot matrix graphic display LCD controller. It can interface with an 8bits or 16bits MPU having a READY ( $\overline{\text{WAIT}}$ ) input pin. Cycle steal mode is used to have the MPU access the VRAM so that the display is not disturbed. The SED1351F contains circuits that control all data and addresses for cycle steal operations and requires no external data/address control circuit. Furthermore, the device has a chip select output pin for VRAM. This makes it possible to directly connect up to eight 64K SRAMs or two 256K SRAMs to the SED1351F without using an external decoder.

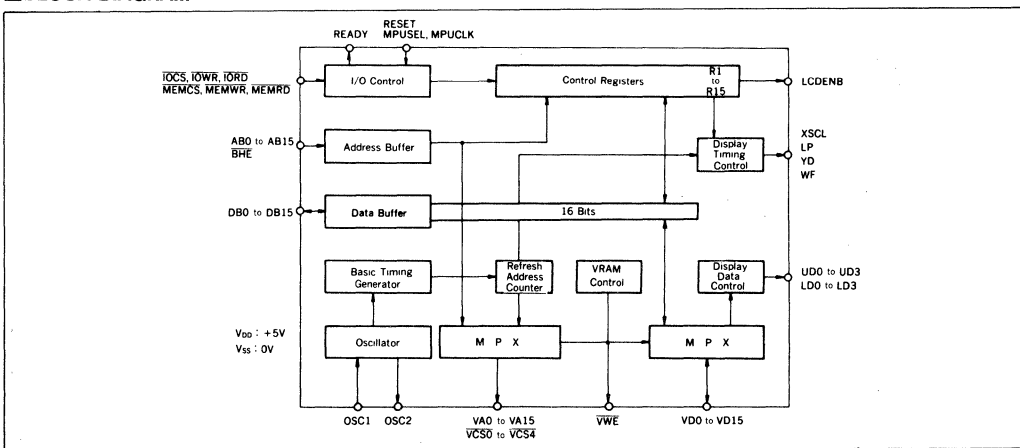
The VRAM addresses are mapped in the MPU memory space. This feature enables the MPU to directly address any display data for efficient data manipulation especially when the user is drawing a picture.

The SED1351F is available with two display modes to choose from, binary mode (on/off only) and gray mode (on/off and two gray steps). Use of the full 64K bytes capacity of VRAM makes it possible to display a maximum of 524,288 dots in the binary mode and 262,144 dots in the gray mode.

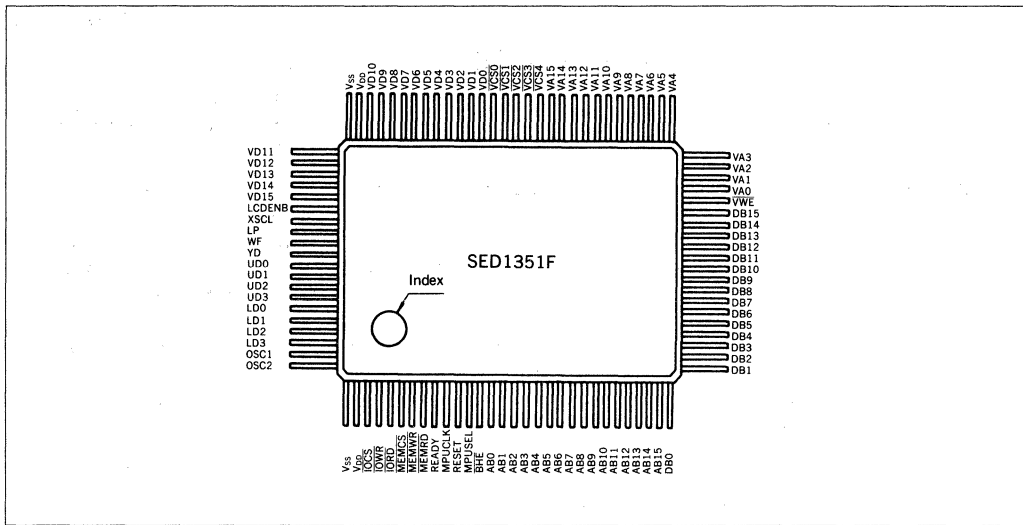
### FEATURES

- VRAM capacity .....64K bytes (Mapping : MPU memory space)
- LCD display modes .....Binary (ON/OFF only)  
Gray (ON/OFF + two gray steps)
- LCD panel .....1-screen configuration (4bits or 8bits data transfer)  
2-screen configuration (4bits data transfer for each display)
- Maximum number of horizontal .....256 characters  
2,048 dots (Binary display mode) / 1,024 dots (Gray display mode)
- Maximum number of vertical lines .....1,024 lines (1-screen drive) / 2,048 lines (2-screen drive)
- Panel division/OR function .....Either to be selected in 1-screen drive mode
- Interface with MPU through use of READY ( $\overline{\text{WAIT}}$ ) signal
- Capability of using virtual display panel
- Smooth vertical scrolling
- Chip select output for VRAM
- Single power supply .....5V ± 10%
- Package .....100pin QFP (Plastic)

### BLOCK DIAGRAM



## PIN CONFIGURATION



## PIN DESCRIPTION

Pin Name	Pin No.	Functions	Pin Name	Pin No.	Functions
DB0 to DB15	30 to 45	MPU data bus	VCS0 to VCS4	67 to 63	VRAM chip select
AB0 to AB15	14 to 29	MPU address bus	VWE	46	VRAM write enable signal output
BHE	13	Bus high enable	UD0 to UD3	91 to 94	Upper panel dot data
IOCS	3	Control register chip select	LD0/UD4 to LD3/UD7	95 to 98	Lower/upper panel dot data
IOWR	4	Control register write enable signal input	XSC1	87	Dot data shift clock
IORD	5	Control register read enable signal input	LP	88	Dot data latch pulse
MEMCS	6	VRAM control chip select	WF	89	Frame signal (LCD AC signal)
MEMWR	7	VRAM control write enable signal input	YD	90	Scan data output
MEMRD	8	VRAM control read enable signal input	LCDENB	86	LCD control signal
READY	9	Ready (wait) signal	OSC1	99	Oscillator terminal (Input)
MPUCLK	10	MPU clock	OSC2	100	Oscillator terminal (Output)
MPUSEL	12	MPU selection (16bits/8bits)	VDD	2	Supply voltage (+5V)
RESET	11	Reset signal	Vss	1	GND
VD0 to VD15	68 to 78 81 to 85	VRAM data bus			
VA0 to VA12	47 to 59	VRAM address bus			
VA13/VCS7 to VA15/VCS5	60 to 62	VRAM address/chip select			

## ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	V <sub>SS</sub> - 0.3 to 7.0	V
Input voltage	V <sub>I</sub>	V <sub>SS</sub> - 0.3 to V <sub>DD</sub> + 0.3	V
Output voltage	V <sub>O</sub>	V <sub>SS</sub> - 0.3 to V <sub>DD</sub> + 0.3	V
Output current/pin	I <sub>O</sub>	±10	mA
Power dissipation	P <sub>D</sub>	200	mW
Supply current	I <sub>DD</sub> /I <sub>SS</sub>	±40	mA
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
Input voltage	V <sub>I</sub>		V <sub>SS</sub>	—	V <sub>DD</sub>	V
Operating temperature	T <sub>opr</sub>		-20	—	75	°C

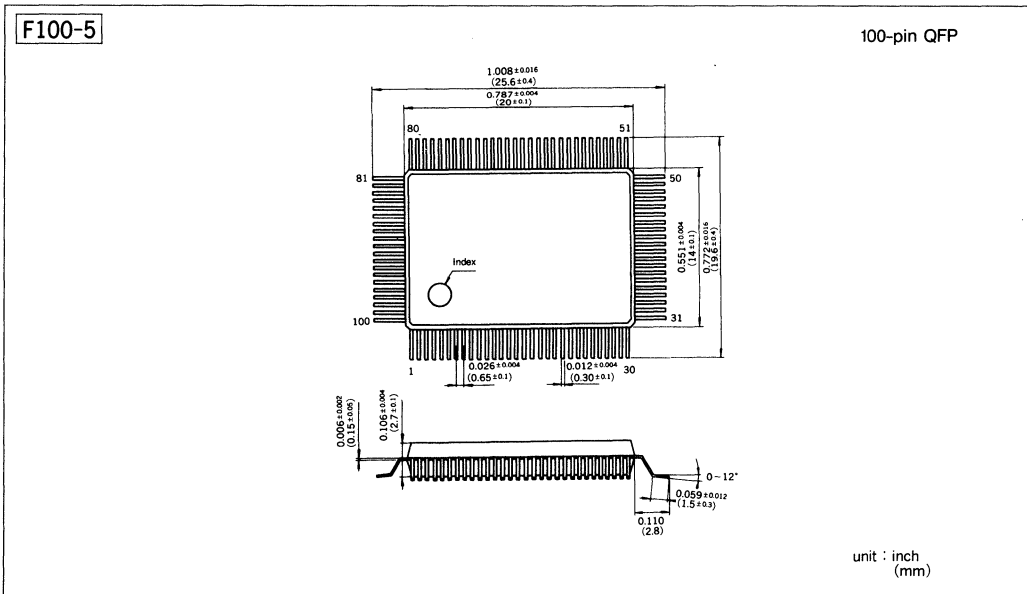
ELECTRICAL CHARACTERISTICS

DC Characteristics

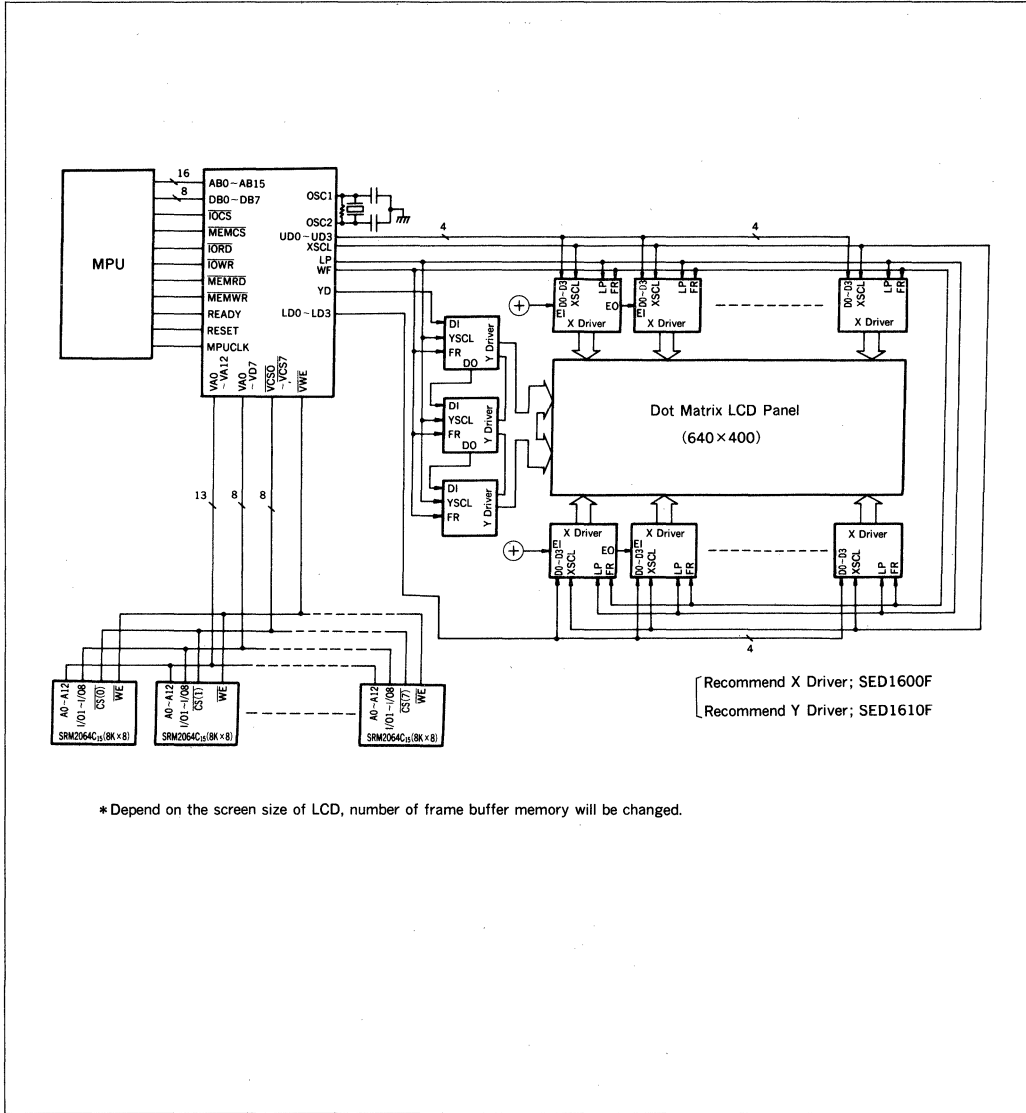
(Ta = -20°C to 75°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Static current	I <sub>DDS</sub>	V <sub>IN</sub> = V <sub>DD</sub> , V <sub>SS</sub> I <sub>OH</sub> = I <sub>OL</sub> = 0	—	—	100	μA
Input leakage current	I <sub>LI</sub>	V <sub>DD</sub> = 5.5V V <sub>IH</sub> = V <sub>DD</sub> V <sub>IL</sub> = V <sub>SS</sub>	-10	—	10	μA
High level input voltage 1	V <sub>IH1</sub>	V <sub>DD</sub> = 5.5V	3.5	—	—	V
Low level input voltage 1	V <sub>IL1</sub>	V <sub>DD</sub> = 4.5V	—	—	1.0	V
High level input voltage 2	V <sub>IH2</sub>	V <sub>DD</sub> = 5.5V	2.0	—	—	V
Low level input voltage 2	V <sub>IL2</sub>	V <sub>DD</sub> = 4.5V	—	—	0.8	V
High level input voltage 3	V <sub>T+</sub>	V <sub>DD</sub> = 5.5V	—	—	4.0	V
Low level input voltage 3	V <sub>T-</sub>	V <sub>DD</sub> = 4.5V	0.8	—	—	V
Hysteresis voltage	V <sub>H</sub>	V <sub>DD</sub> = 5V	0.3	—	—	V
High level output voltage 1	V <sub>OH1</sub>	V <sub>DD</sub> = 4.5V I <sub>OH</sub> = -2mA	V <sub>DD</sub> - 0.4	—	—	V
Low level output voltage 1	V <sub>OL1</sub>	I <sub>OL</sub> = 6mA	—	—	V <sub>SS</sub> + 0.4	V
High level output voltage 2	V <sub>OH2</sub>	V <sub>DD</sub> = 4.5V I <sub>OH</sub> = -50μA	V <sub>DD</sub> - 0.4	—	—	V
Low level output voltage 2	V <sub>OL2</sub>	I <sub>OL</sub> = 50μA	—	—	V <sub>SS</sub> + 0.4	V

PACKAGE DIMENSIONS



■EXAMPLE OF APPLICATION (When using an 8bits MPU)



# SED1341F<sub>OC</sub>

## CMOS VIDEO-LCD INTERFACE (VLI)

- Video/LCD Signal Converter LSI
- Simplified Screen Alignment
- Internal Oscillator for LCD Display Operation (Independent of Video Signal)

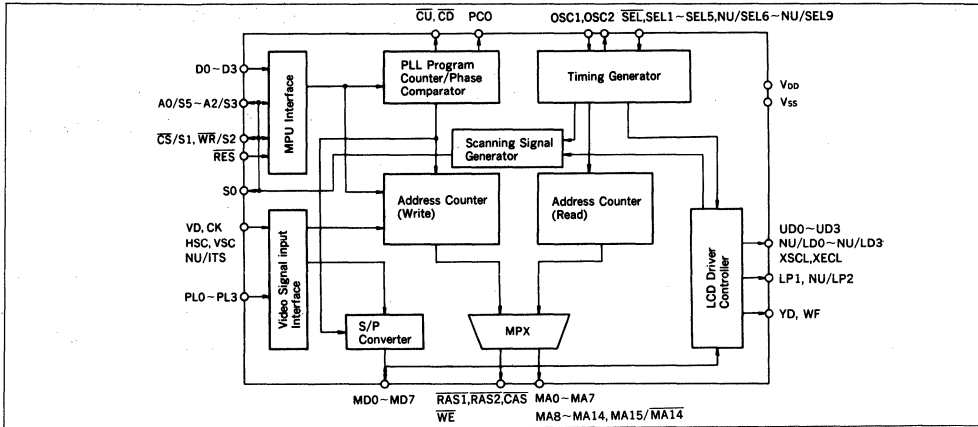
### ■ DESCRIPTION

The SED1341F VLI (Video-LCD Interface) converts a split composite video signal used to drive CRT displays into a data format necessary to drive dot-matrix liquid crystal displays. With the addition of a sync signal/data separator composite signals can also be processed, making it possible to replace a CRT display (without brightness gradation) with a liquid crystal display panel, needing no special software or hardware. A frame buffer allows the VLI to accurately match the higher frequency video signals to the lower frequency operation of the LCD unit. In addition, the VLI has a screen alignment function for fine adjustment. These functions make it easy to create an LCD terminal that is plug-compatible with CRT display connectors.

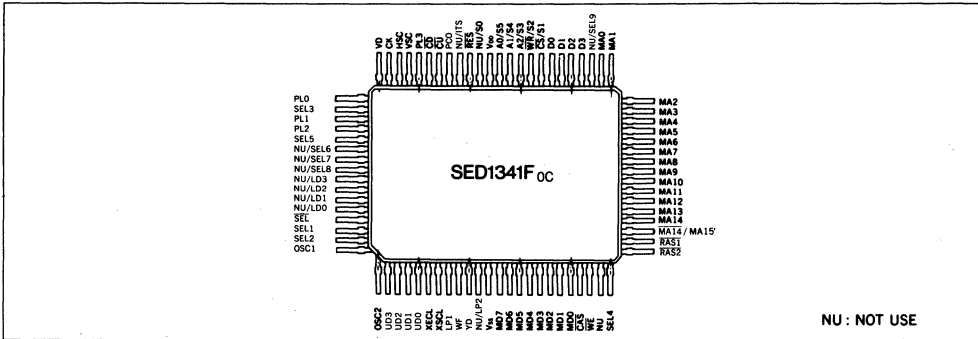
### ■ FEATURES

- Makes LCD monitor plug-compatible with CRT connectors
- Screen size : 640×200 dots, 640×350 dots, 640×400 dots, 640×480 dots
- LCD Interface
  - Internal oscillator enables setting of frame frequency to match LCD unit  $f_{OSC}=11.2\text{MHz (Max)}$
  - Duty ratio ..... 1/100, 1/200, 1/400, 1/175, 1/350, 1/102, 1/202, 1/402, 1/177, 1/352, 1/104, 1/208, 1/416, 1/183, 1/366, 1/240, 1/480, 1/242, 1/482, 1/248, 1/496
  - Scan mode ..... 1-screen drive, 2-screen drive
  - X-driver interface ..... 4-bit bus, 4-bit×2 bus, 8-bit bus, Enable-chain type
  - LCD drive method ..... 2-frame AC
- Video signal interface ..... Horizontal scan frequency : 15.69kHz (Typ), 24.83kHz (Typ)
  - TTL-compatible separate signal input
    - Video data, horizontal sync signal, vertical sync signal, dot clock
  - Internal PLL (Phase lock loop circuit) program counter (1/706~1/961), Internal phase comparator
    - Dot clock generation via PLL : 14.32MHz (Typ), 21.05MHz (Typ),  $f_{CK}=34\text{MHz (Max)}$
  - Screen alignment fine adjustment ..... Register program method via 4-bit bus
- Direct control of 64K DRAM/SRAM, 256K SRAM for frame buffer memory (40K×8 bits Max)
- Pin compatible with SED1341F<sub>0A,0B</sub>
- Single power supply .....  $5V \pm 5\%$
- Package ..... 80-pin QFP (plastic)

## ■BLOCK DIAGRAM



## ■PIN CONFIGURATION



## ■PIN DESCRIPTION

Pin Name	Pin No.	Functions
V <sub>DD</sub>	53	Supply voltage (+5V)
V <sub>SS</sub>	12	GND
OSC1	80	Oscillator terminal (Input)
OSC2	1	Oscillator terminal (Output)
UD0 to UD3, NU/LD0 to NU/LD3	5 to 2, 76 to 73	X driver data bus output
XECL	6	X driver enable shift clock output
XSCL	7	X driver shift clock output
LP1, NU/LP2	8, 11	Latch pulse output
WF	9	AC wave form output for the LCD
YD	10	Row scanning start data output for Y driver
VD	64	Video data input
CK	63	Dot clock input
HSC	62	Horizontal sync signal input
VSC	61	Vertical sync signal input
NU/ITS	56	ITS (Half tone) signal input
MA0 to MA14, MA14/MA15	42 to 28, 27	Address bus output to frame buffer memory
MD0 to MD7	20 to 13	Data bus I/O to frame buffer memory
RAST, RAS2	26, 25	Row address strobe signal output
CAS	21	Column address strobe signal output
WE	22	Write enable signal output

Pin Name	Pin No.	Functions	
D0 to D3	47 to 44	Data input for screen position register	
		SEL5 = "L"	SEL5 = "H"
NU/S0	54	NU	Scan signal output for digital switch
A0/S5 to A2/S3	52 to 50	Address bus input	Scan signal output for digital switch
$\overline{CS}/S1$	48	Chip select signal input	Scan signal output for digital switch
$\overline{WR}/S2$	49	Write signal input	Scan signal output for digital switch
RES	55	Reset signal input	
SEL	77	When SEL is "L", SEL6 to SEL9, ITS are enabled	
SEL1	78	Drive mode select input (1-screen drive/2-screen drive)	
SEL2	79	SCREEN SIZE select input > 640 × 200, 640 × 350, 640 × 400, 640 × 480	
SEL3	66	SCREEN SIZE select input >	
SEL4	24	Frame buffer memory select input (SRAM/DRAM)	
SEL5	69	Screen alignment method select input (SW/MPU)	
NU/SEL6	70	Select input for Vertical back porch (invalid/valid)	
NU/SEL7	71	Timing select input for Latch pulse output (edge/level)	
NU/SEL8	72	X driver interface select input (4 bit bus/4 bit × 2 bus, 8 bit bus)	
NU/SEL9	73	Line select input for back porch (8, 16 lines/2, 4 lines)	
PL0 to PL3	65,67,68,60	Polarity select input for video signal	
PCO	57	Program counter output in PLL Section	
C $\overline{U}$ , C $\overline{D}$	58, 59	Phase comparator output in PLL Section (connect to charge pump)	

\*If terminal No.77 (SEL) is set to the "H" level, terminal No.70 to No.72 and No.56 become the NU terminal, and all the inputs of SEL6 to SEL8 are considered as "H" level.  
For this reason, the pins are compatible with those in SED1341F<sub>0A</sub>.

#### ■ ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Ratings	Unit
Supply voltage*	V <sub>DD</sub>	-0.3 to 7.0	V
Input voltage*	V <sub>I</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output voltage*	V <sub>O</sub>	-0.3 to V <sub>DD</sub> +0.3	V
I/O voltage*	V <sub>I/O</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output current	I <sub>O</sub>	-10 to 10	mA
Power dissipation	P <sub>D</sub>	250	mW
Operating temperature	T <sub>opr</sub>	0 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

\* V<sub>SS</sub> = 0V

#### ■ RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.75	5.00	5.25	V
Supply voltage	V <sub>SS</sub>		—	0	—	V



## ELECTRICAL CHARACTERISTICS

### DC Characteristics

( $T_a = 0$  to  $70^\circ\text{C}$ ,  $V_{DD} = 5V \pm 5\%$ ,  $V_{SS} = 0V$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Oscillation frequency	$f_{OSC}$	$f_{CK} = 14.3\text{MHz}$ $f_{CK} = 21\text{MHz}$	$f_{CK}/3.6$	4.5 9	11.2 and $f_{CK}/2.28$	MHz
Average operating current consumption	$I_{OPR}$	$f_{CK} = 32\text{MHz}$ , $f_{OSC} = 11\text{MHz}$	—	—	40	mA
High level input voltage 1	$V_{IH1}$	*1	2.0	—	$V_{DD} + 0.3$	V
Low level input voltage 1	$V_{IL1}$		-0.3	—	0.8	V
High level input voltage 2	$V_{IH2}$	*2	4.0	—	$V_{DD} + 0.3$	V
Low level input voltage 2	$V_{IL2}$		-0.3	—	0.8	V
High level input voltage 3	$V_{IH3}$	*3	3.0	—	$V_{DD} + 0.3$	V
Low level input voltage 3	$V_{IL3}$		-0.3	—	0.6	V
High level output voltage	$V_{OH}$	$I_{OH} = -2\text{mA}$ *4	4.35	—	—	V
Low level output voltage	$V_{OL}$	$I_{OL} = 6\text{mA}$ *4	—	—	0.4	V
Input current leakage	$I_{LI}$	$V_I = 0V$ to $V_{DD}$	-1	—	1	$\mu\text{A}$
I/O current leakage	$I_{LI/O}$	$V_{I/O} = 0V$ to $V_{DD}$	-1	—	1	$\mu\text{A}$

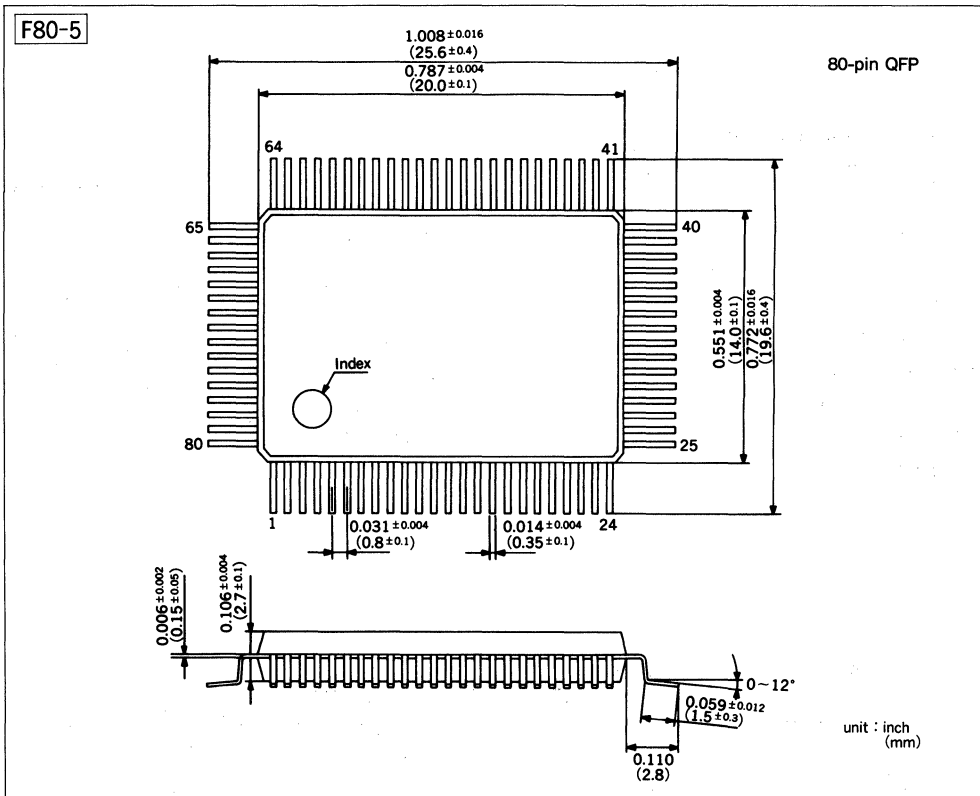
\*1 Terminal : VD, CK, HSC, VSC, NU/ITS, MD0 to MD7, A0 to A2, CS, WR, NU/SEL9

\*3 Terminal : RES

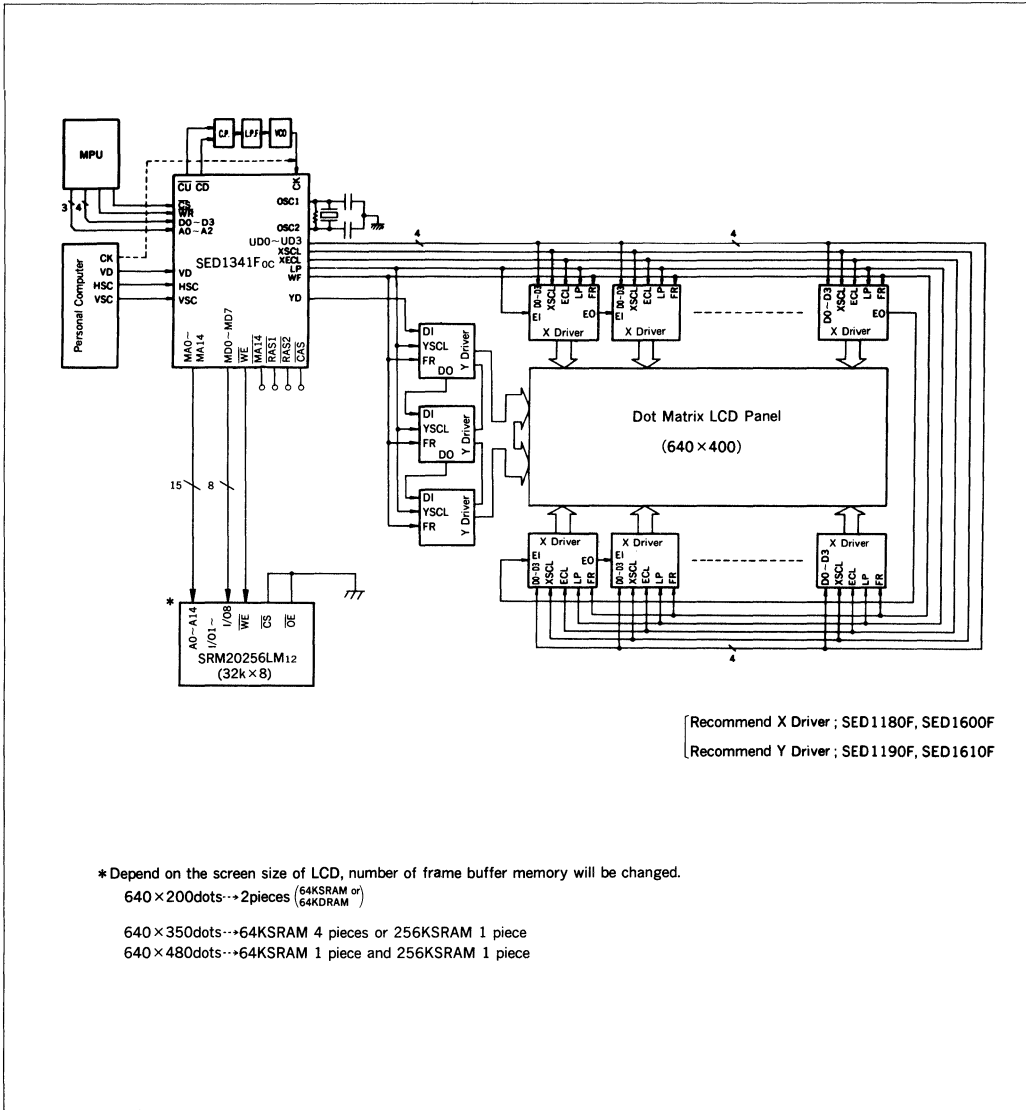
\*2 Terminal : SEL, SEL1 to SEL5, PL0 to PL3, NU/SEL6 to NU/SEL8, D0 to D3

\*4 Terminal : (except OSC2 pin)

## PACKAGE DIMENSIONS



## EXAMPLE OF APPLICATION



Recommend X Driver ; SED1180F, SED1600F  
 Recommend Y Driver ; SED1190F, SED1610F

\* Depend on the screen size of LCD, number of frame buffer memory will be changed.

640 x 200 dots --> 2 pieces (64KSRAM or 64KDRAM)

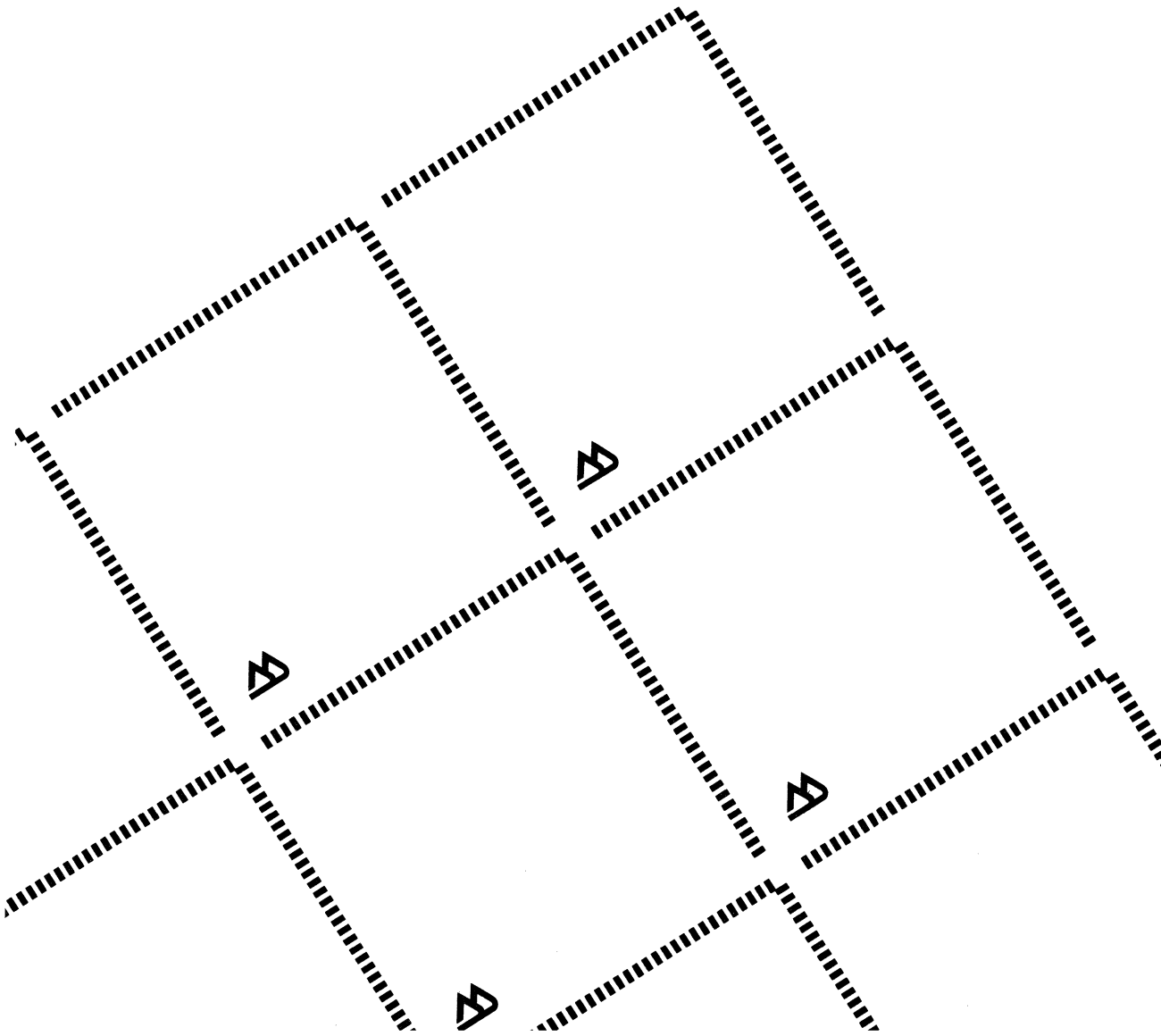
640 x 350 dots --> 64KSRAM 4 pieces or 256KSRAM 1 piece

640 x 480 dots --> 64KSRAM 1 piece and 256KSRAM 1 piece



F. TELECOMMUNICATION PRODUCTS

1988/1989 CMOS  
DATA BOOK





# STC9430C Series

## CMOS 300bps FSK SINGLE CHIP MODEM

- High Data Quality
- Low Supply Current
- 5V Single Power Supply

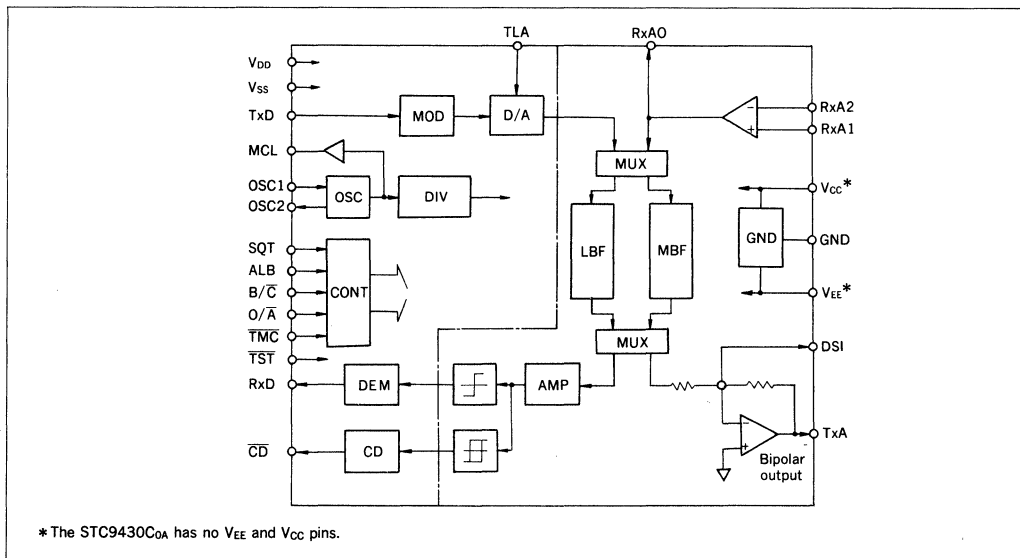
### DESCRIPTION

The STC9430C Series LSI is a CMOS 300bps FSK full-duplex modem operating on a single 5V supply. It provides all functions needed for a modem compatible with the Bell 103J specifications and the CCITT recommendations. The STC9430C also incorporates a power-saving function and a transmit-receive buffer amplifier which can be configured adaptively to any line interface the user desires. These excellent features offer a high-performance solution to home security, telemetering terminal, and other modem applications.

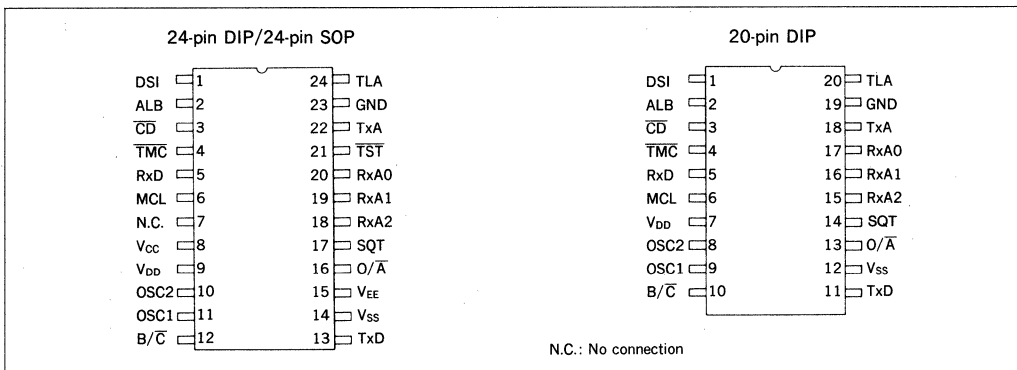
### FEATURES

- 0-300bps FSK full duplex modem ..... Bell 103J, CCITT V.21
- Built-in line interface ..... Built-in buffer amplifier for hybrid circuit.  
(Outputs bipolar signals.)
- Full duplex band pass filter ..... Built-in leap frog SCF
- High data quality ..... Bit error rate (Receive level  $-30\text{dBm}$ )  
Bell mode :  $1 \times 10^{-5}\text{Max}$  ( $S/N \geq 6\text{dB}$ )  
CCITT mode :  $1 \times 10^{-5}\text{Max}$  ( $S/N \geq 5\text{dB}$ )
- Low supply current ..... Operation : 75mW (Typ)  
Stand-by : 10 $\mu$ W (Max)
- Supply voltage ..... 5V single power supply
- Digital I/O level ..... TTL compatible
- Built-in oscillation circuit ..... 3.579545MHz : Externally connected X'tal & capacitor
- Test function ..... Built-in Analog loop back test mode
- Package ..... 20-pin DIP (plastic)/24-pin DIP (plastic)/24-pin SOP (plastic)

### BLOCK DIAGRAM



## PIN CONFIGURATION



## PIN DESCRIPTION

Pin name	Pin No.		I/O	Functions
	20 pin	24 pin		
DSI	1	1	I	[Transmit Buffer Amplifier Inverted Signal] Receives DTMF (Dual Tone Multi-Frequency) and other external signals.
ALB	2	2	I <sub>1</sub>	[Analog Loop-Back] When this signal goes high, the send output turns to a receive input and the system enters the LSI self-test mode. If both ALB and SQT go high, the power-saving mode results.
CD	3	3	O	[Carrier Detect] This signal goes low when a specified level of energy is detected within the receive frequency band.
TMC	4	4	I <sub>1</sub>	[Timer Select] Selects a carrier detection timer response time. Short : High level    Long : Low level
RxD	5	5	O	[Receive Data] Outputs demodulated output. Mark : High level    Space : Low level
MCL	6	6	O	[Master Clock] Outputs the master clock (3.579545MHz) for supply to a tone dialer or other external circuits
V <sub>CC</sub>	—	8	—	[V <sub>CC</sub> Power] +5V (24 pin type : Analog, positive)
V <sub>DD</sub>	7	9	—	[V <sub>DD</sub> Power] +5V (24 pin type : Digital, positive) (20 pin type : Analog/digital, positive)
OSC2	8	10	O	[Oscillation Output] A crystal oscillator (3.579545MHz) and, an oscillation capacitor are connected to this pin.
OSC1	9	11	I	[Oscillation Output] A crystal oscillator (3.579545MHz) and an oscillation capacitor are connected to this pin (If external oscillation is used, it enters through this pin.)
B/ $\bar{C}$	10	12	I <sub>1</sub>	[Bell/CCITT Select] Selects the Bell or CCITT mode. Bell : High level    CCITT : Low level
TxD	11	13	I <sub>1</sub>	[Send Data] Receives send data. Mark : High level    Space : Low level
V <sub>SS</sub>	12	14	—	[V <sub>SS</sub> Power] 0V (24 pin type : Digital, negative) (20 pin type : Analog/digital, negative)

(Continue)

The input pin has an on-chip pull-up resistor. If not used, however, it should preferably be fixed to V<sub>DD</sub> level for protection against noise.

Pin name	Pin No.		I/O	Functions
	20 pin	24 pin		
V <sub>EE</sub>	—	15	—	[V <sub>EE</sub> Power] 0V (24 pin type : Analog, negative)
O/ $\bar{A}$	13	16	I <sub>1</sub>	[Originate/Answer Mode Select] Originate mode : High level    Answer mode : Low level
SQT	14	17	I <sub>1</sub>	[Transmit Carrier Squelch] Controls send carrier on/off. Off : High level    On : Low level
RxA2	15	18	I	[Receive Buffer Amplifier Inverted Signal]
RxA1	16	19	I	[Receive Buffer Amplifier Non-inverted Signal]
RxA0	17	20	O	[Receive Buffer Amplifier Output]
$\bar{TST}$	—	21	I <sub>1</sub>	[LSI Test Signal]
TxA	18	22	O	[Transmit Buffer Amplifier Signal] Outputs bipolar signals.
GND	19	23	O	[Signal Ground Output] Outputs the intermediate potential of an analog signal. (V <sub>GND</sub> =1/2 V <sub>CC</sub> )
TLA	20	24	I	[Transmit Level Control]

I<sub>1</sub> The input pin has an on-chip pull-up resistor. If not used, however, it should be fixed to the V<sub>DD</sub> level for protection against noise.

### ■STC9430C SERIES

Name	Package	
	Pin	Type
STC9430C <sub>0A</sub>	20	DIP (plastic)
STC9435C <sub>0A</sub>	24	DIP (plastic)
STC9435M <sub>0A</sub>	24	SOP (plastic)

### ■ABSOLUTE MAXIMUM RATINGS

(V<sub>EE</sub>\*1=V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	Digital	V <sub>DD</sub>	0 to 7
	Analog	V <sub>CC</sub> *1	0 to 7
Input voltage	Digital	V <sub>ID</sub> *2	V <sub>SS</sub> -0.3 to V <sub>DD</sub> +0.3
	Analog	V <sub>IA</sub> *3	V <sub>EE</sub> -0.3 to V <sub>CC</sub> +0.3
Power dissipation	P <sub>D</sub>	500	mW
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

\*1 The STC9430C<sub>0A</sub> has no V<sub>EE</sub> and V<sub>CC</sub> pins.

\*2 ALB, TMC, OSC1, B/C, TxD, O/A, SQT,  $\bar{TST}$ , TLA

\*3 DSI, RxA1, RxA2

### ■RECOMMENDED OPERATING CONDITIONS

(V<sub>EE</sub>\*1=V<sub>SS</sub>=0V, f<sub>OSC</sub>=3.579545MHz)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	Digital	V <sub>DD</sub>	—	4.5	5.0	5.5
	Analog	V <sub>CC</sub> *1	—	4.5	5.0	5.5
Input voltage	Digital	V <sub>ID</sub> *2	—	V <sub>SS</sub>	—	V <sub>DD</sub>
	Analog	V <sub>IA</sub> *3	—	V <sub>EE</sub>	—	V <sub>CC</sub>
Operating temperature	T <sub>opr</sub>	—	-10	25	70	°C
Osc. frequency offset	$\Delta f_{OSC}$	X'tal/Ext. clock	-0.1	0	+0.1	%

\*1 The STC9430C<sub>0A</sub> has no V<sub>EE</sub> and V<sub>CC</sub> pins.

\*2 ALB, TMC, OSC1, B/C, TxD, O/A, SQT,  $\bar{TST}$ , TLA

\*3 DSI, RxA1, RxA2



## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

( $V_{CC}^*1 = V_{DD} = 5V$ ,  $V_{EE}^*1 = V_{SS} = 0V$ ,  $T_a = 25^\circ C$ )

Parameter	Symbol	Conditions		Min	Typ	Max	Unit	
Average operating current	$I_{DDA}$	ALB	STC9430C0A	—	15	30	mA	
		or SQT = "L"	STC9435C0A	Digital	—	5	10	mA
			STC9435M0A	Analog	—	10	20	mA
Stand-by current	$I_{DDs}$	ALB	STC9430C0A	—	—	2	$\mu A$	
		= SQT = "H"	STC9435C0A	Digital	—	—	1	$\mu A$
			STC9435M0A	Analog	—	—	1	$\mu A$
High level input voltage (1)	$V_{IH1}$	Digital input except OSC1		2.4	—	$V_{DD}$	V	
Low level input voltage (1)	$V_{IL1}$	Digital input except OSC1		$V_{SS}$	—	0.8	V	
High level input current	$I_{IH}$	Digital input except OSC1		—	—	1	$\mu A$	
Low level input current	$I_{IL}$	Digital input except OSC1		5	10	30	$\mu A$	
High level input voltage (2)	$V_{IH2}$	OSC1 Ext. clock input condition		4.0	—	$V_{DD}$	V	
Low level input voltage (2)	$V_{IL2}$			$V_{SS}$	—	1.0	V	
Input frequency	$f_{IN}^{*2}$			—0.1	( $f_{osc}$ )	+0.1	%	
Clock duty	$T_1/T_0$			35	50	65	%	
High level output current (1)	$I_{OH1}$	$V_{OH} = 4.5V$	$\overline{CD}$ , RxD	4	6.5	—	mA	
Low level output current (1)	$I_{OL1}$	$V_{OL} = 0.5V$		6	11.5	—	mA	
High level output current (2)	$I_{OH2}$	$V_{OH} = 4.5V$	MCL	2	3.5	—	mA	
Low level output current (2)	$I_{OL2}$	$V_{OL} = 0.5V$		3.5	5.5	—	mA	
Analog output impedance	$Z_{RxA0}$	$V_{SG} - 1.2 \leq V_{RxA0}(V) \leq V_{SG} + 1.2$		4	—	—	k $\Omega$	
	$Z_{TxA}$	$V_{SG} - 1.2 \leq V_{TxA}(V) \leq V_{SG} + 1.2$		1.1	—	—	k $\Omega$	
	$Z_{SG}$	$-0.2 \leq \Delta V_{SG}^{*3} \leq +0.2$		3	—	—	k $\Omega$	
Receive buffer input impedance	$Z_{RxA1}$	RxA0 open, $f = 0Hz$		5	—	—	M $\Omega$	
	$Z_{RxA2}$	RxA0 open, $f = 0Hz$		5	—	—	M $\Omega$	
Transmit buffer feedback resistance	$R_{FB}$	SQT = "H", ALB = "L"		20	25	30	k $\Omega$	
TLA input leakage current	$I_{TLA}$	$V_{TLA} = V_{SS}$		20	30	45	mA	
		$V_{TLA} = V_{DD}$		50	80	140		

\*1 The STC9430C0A has no  $V_{EE}$  and  $V_{CC}$  pins.

\*2  $f_{osc} = 3.579545MHz$

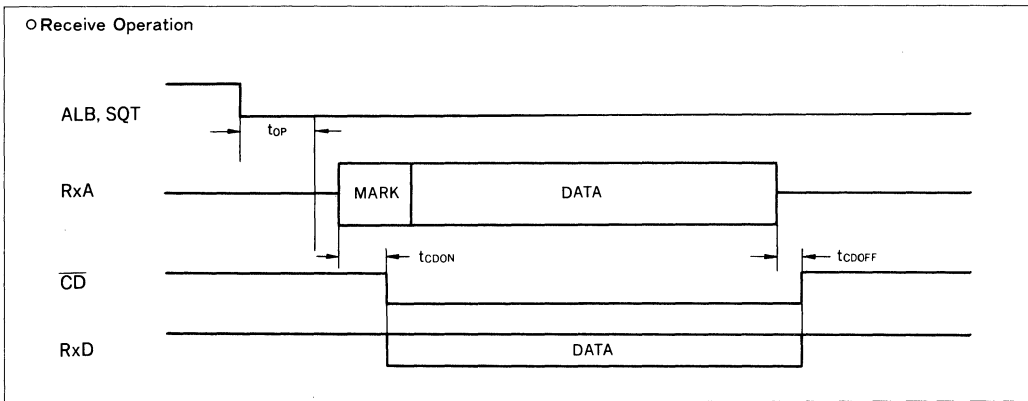
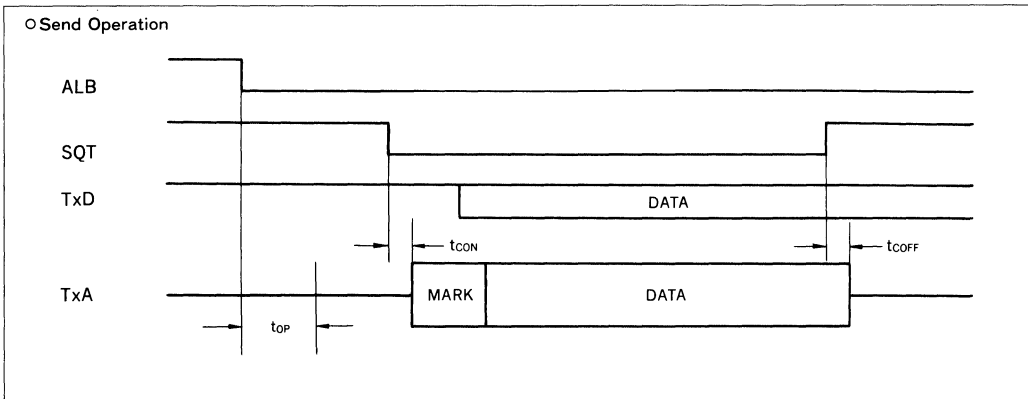
\*3 Output impedance calculation conditions.

### ● AC Electrical Characteristics

( $f_{osc} = 3.579545MHz$ ,  $T_a = 25^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit	
After cancel stand-by, operation time	$t_{OP}$	Transmit & Receive	—	60	100	ms	
Carrier on time	$t_{CON}$	SQT = "H" → "L"	—	3	5	ms	
Carrier off time	$t_{COFF}$	SQT = "L" → "H"	—	—	1	ms	
Carrier detect response time	$t_{CDON}$	OFF → ON	TMC = "H"	4	15	26	ms
			TMC = "L"	410	435	460	
	$t_{CDOFF}$	ON → OFF	—	28	36	44	ms

## ●Timing Chart



## ●Analog Electrical Characteristics

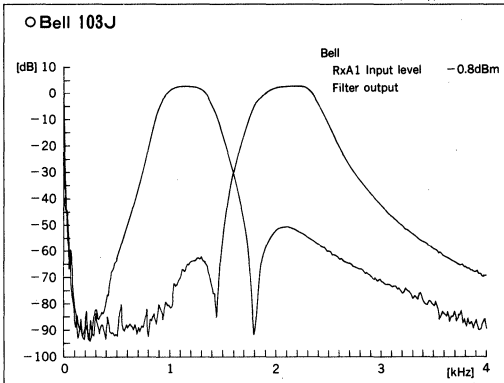
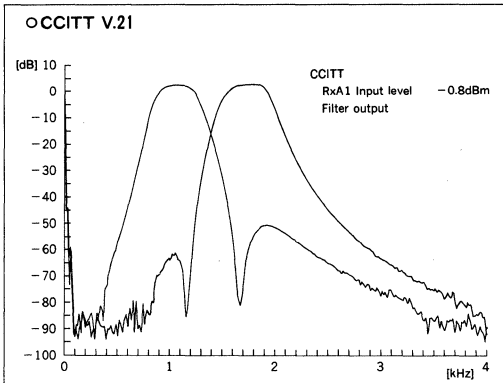
( $V_{CC}^{*1} = V_{DD} = 5V$ ,  $V_{EE}^{*1} = V_{SS} = 0V$ ,  $T_a = 25^{\circ}C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit	
TX signal output level	$P_T$	TxA open, $R_{TLA} = \infty \Omega$	-13	-12	-11	dBm	
		TxA open, $R_{TLA} = 0\Omega$	-1	0	+1		
RX signal level	$D_R$	Receive buffer amp. gain 0dB	-40	—	0	dBm	
Carrier detect level	$L_{ON}$	OFF→ON: On level	—	-43	-42	dBm	
	$L_{OFF}$	ON→OFF: Off level	-48	-46	—		
	$L_H$	Hysteresis	2	3	4	dB	
Center frequency	$f_0^{*2}$	CCITT V.21	Low Band	—	1,080	—	Hz
			High Band	—	1,750	—	
		Bell 103J	Low Band	—	1,170	—	
			High Band	—	2,125	—	
Pass bandwidth	$f_{BWL}^{*2}$	CCITT V.21	Low Band $f_0$	—	$\pm 150$	—	Hz
			High Band $f_0$	—	$\pm 150$	—	
		Bell 103J	Low Band $f_0$	—	$\pm 150$	—	
			High Band $f_0$	—	$\pm 150$	—	

\*1 The STC9430C0A has no  $V_{EE}$  and  $V_{CC}$  pins.

\*2  $f_{osc} = 3.579545MHz$

## ● Filter Characteristics



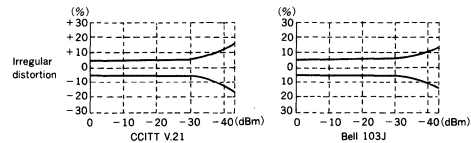
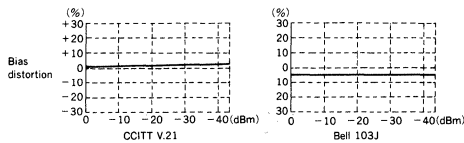
## ● Data Quality

( $V_{CC}^{*1} = V_{DD} = 5V$ ,  $V_{EE}^{*1} = V_{SS} = 0V$ ,  $T_a = 25^\circ C$ )

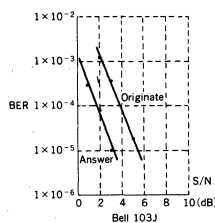
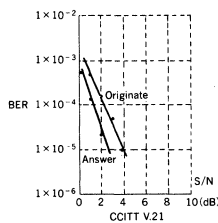
Parameter		Symbol	Conditions	Min	Typ	Max	Unit
Code distortion	Bias distortion	$D_B$	at ALB	0	—	$\pm 4$	%
			Receive level: $-40dBm$	0	—	$\pm 4$	
	Irregular distortion	$D_J$	at ALB	—	—	$\pm 6$	%
			Receive level: $-40dBm$	—	—	$\pm 12$	
Bit error rate		BER	CCITT V.21: S/N = 5dB	—	—	$1 \times 10^{-5}$	—
			Bell 103J: S/N = 6dB	—	—	$1 \times 10^{-5}$	

\*1 The STC9430<sub>0A</sub> has no  $V_{EE}$  and  $V_{CC}$  pins.

### ○ Dependence of code distortion on receive input level

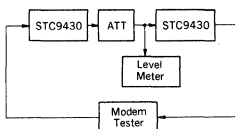


### ○ Bit error rate (Receive level: $-30dBm$ )

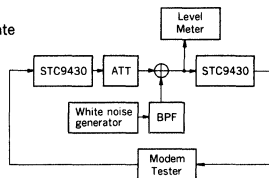


### [Accuracy of data measuring circuit]

#### ○ Code distortion

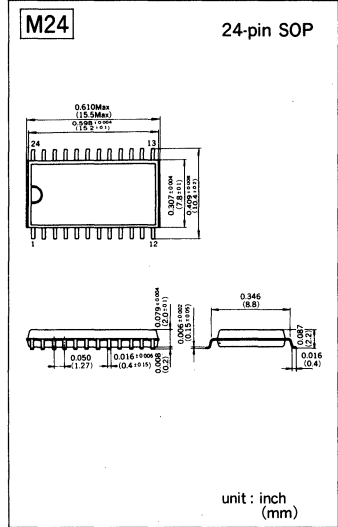
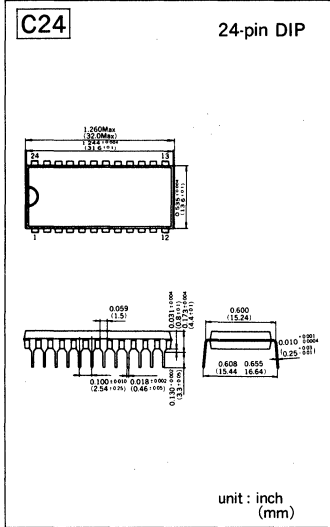
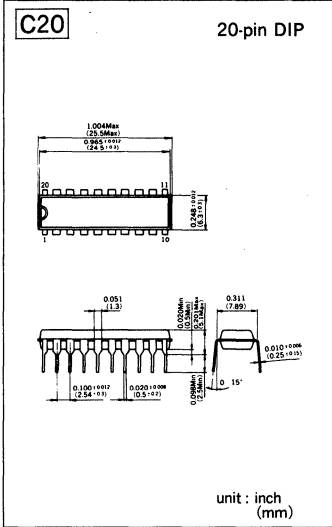


#### ○ Bit error rate





■ PACKAGE DIMENSIONS



# STC9492C Series

## CMOS 1,200bps PSK SINGLE CHIP MODEM

- Compatible with Bell212A (High speed)/CCITT V.22
- Tone Generator Incorporated
- Call Progress Tone Detection Function Provided

### DESCRIPTION

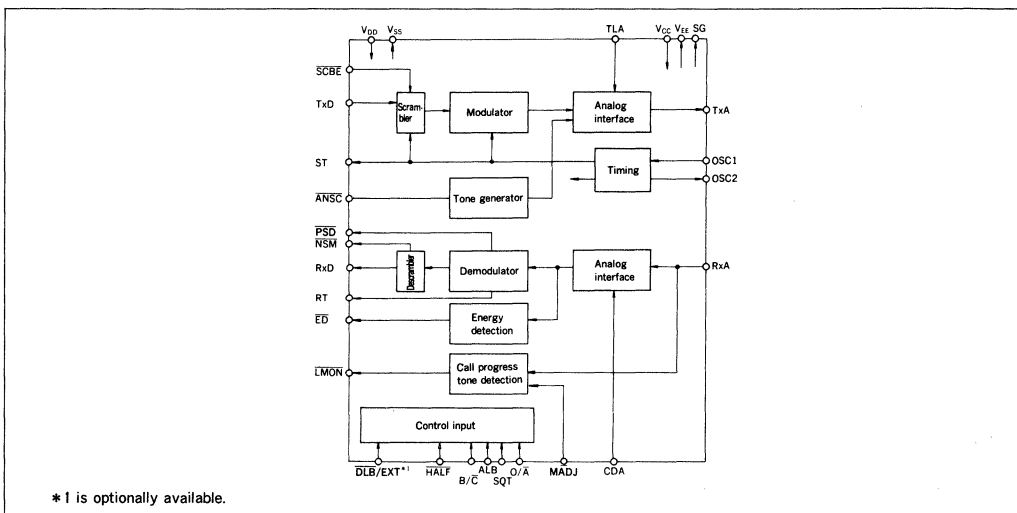
The STC9492C Series is a Bell 212A (high speed)/CCITT V.22 compatible, single chip, 1,200 bps CMOS LSI for a PSK MODEM. The built-in additional functions include answer and guard tones generation functions and a call progress tone detection function.

The high quality switched capacitor circuits and the adaptive equalizing algorithm are adopted in the signal processing, so that they realize highly reliable data quality.

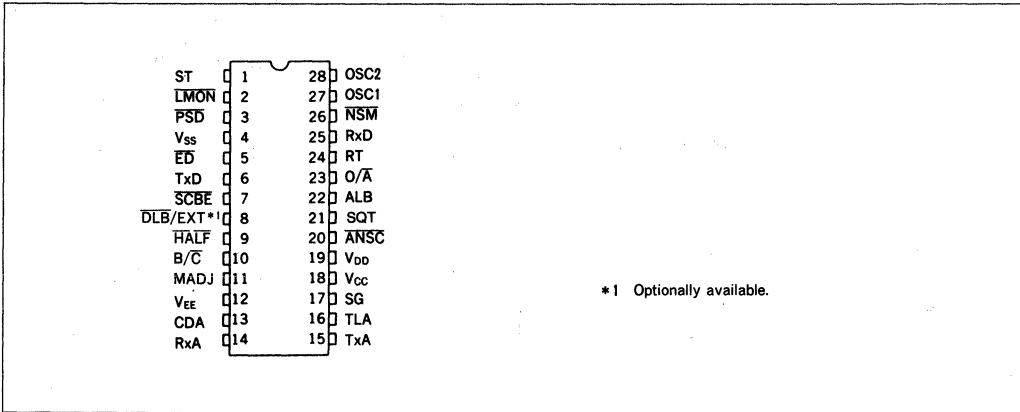
### FEATURES

- Compatible with Bell 212A (high speed), CCITT V.22
- Built-in Tone Generator (2,225Hz/2,100Hz/1,800Hz)
- Call Progress Tone Detector On Chip
- Adaptive Equalizer On Chip
- 4.032MHz Crystal Oscillation ..... Quartz oscillator and capacitors externally connected
- Test Function ..... Analog Loop-back Test  
Digital Remote Loop-back Test
- Low Power Consumption ..... Operation : 120mW (Typ)  
Power down : 10 $\mu$ W (Max)
- Input/Output Interface ..... CMOS level
- Single Power Supply ..... 5V  $\pm$  10%
- Package ..... 28-pin DIP (plastic)/28-pin SOP (plastic)

### BLOCK DIAGRAM



## ■ PIN CONFIGURATION (This also applies to DIP and SOP.)



## ■ PIN DESCRIPTION

Pin Name	Pin No.	I/O	Functions
ST	1	O	[Transmit timing output] Outputs a transmit timing signal synchronized with the internal operation.
LMON	2	O	[Call progress tone detection output] Detects call progress tones generated during line connection, and outputs their energy envelope.
PSD	3	O	[PSK signal detection output] When detects the PSK carrier in a receive signal, this produces low level.
V <sub>SS</sub>	4	—	[V <sub>SS</sub> supply for the digital section] 0V
ED	5	O	[Carrier detection output] When detects the appointed energy within receive band, this produces low level.
TxD	6	I* *1	[Transmit data input] Inputs transmit data for PSK modulation. Mark : High level    Space : Low level
SCBE	7	I*	[Scrambler control input] The low level input enables the scrambler active. This should be high level for transmitting non-scrambled data.
DLB	8 *2	I*	[Digital remote loop-back test input] The low level input sets a remote digital loop. RxD produces mark continuously during this test mode.
EXT		I*	[External transmit timing input] The external transmit timing can be input to this terminal. Tolerance : within $\pm 0.01\%$ of data transmit speed
HALF	9	I*	[1,200bps/600bps selection input] Selects the transmit speed. 1,200bps : High level    600bps : Low level
B/C	10	I*	[Bell/CCITT mode selection input] Controls answer tone or guard tone connected with Bell/CCITT mode. Bell : High level    CCITT : Low level
MADJ	11	I	[Call progress tone detection level adjust] The call progress tone detection level can be adjusted by supplied voltage. When unused, this should be connected to SG, V <sub>CC</sub> or V <sub>EE</sub> .
V <sub>EE</sub>	12	—	[V <sub>EE</sub> supply for the analog section] 0V

\*1 I\* has a built-in pull-up resistor.

\*2 Optional selection

Pin Name	Pin No.	I/O	Functions
CDA	13	I/O	[Carrier detection level adjust] Can adjust a carrier detection level by potential difference with SG. (when opened, produces $\approx V_{SG} + 1.0V$ )
RxA	14	I	[Receive analog input] Inputs the receive analog signal.
TxA	15	O	[Transmit analog output] Outputs the transmit analog signal.
TLA	16	I/O	[Transmit level adjust] Can adjust a transmit signal output level by potential difference with SG. (When opened, produces $\approx V_{SG} + 1.0V$ )
SG	17	O	[Signal ground] Outputs a reference potential of an analog signal. (When opened, produces $\approx 2.5V$ )
V <sub>CC</sub>	18	—	[V <sub>CC</sub> supply for the analog section] +5V
V <sub>DD</sub>	19	—	[V <sub>DD</sub> supply for the digital section] +5V
$\overline{ANS}$	20	I* *1	[Answer tone control input] The low level input enables answer tone generation during SQT is high level.
SQT	21	I*	[Squelch transmitter] The high level input squelches the carrier transmitting.
ALB	22	I*	[Analog loop-back test input] The high level input leads to connection of modulated output to demodulated input, so that enables the analog loop-back test. Both ALB and SQT are made high, the power-down mode is established.
O/ $\overline{A}$	23	I*	[Originate or Answer mode selection input] Originate mode : High level    Answer mode : Low level
RT	24	O	[Receive timing output] Outputs a receive timing signal.
RxD	25	O	[Receive data output] Outputs the PSK demodulated serial data. This produces high level continuously when $\overline{PSD}$ is high level or $\overline{DLB}$ is low level. Mark : High level    Space : Low level
$\overline{NSM}$	26	O	[Non-scrambled mark detection output] Outputs low level when 64 or more continuous mark signals are detected in the input of the descrambler.
OSC1	27	I	[Oscillation input/output] Connects a 4.032MHz crystal oscillator and capacitors.
OSC2	28	O	

\*1 I\* has a built-in pull-up resistor.

#### ■STC9492C SERIES

Name	Optional Selection (#8 pin)	Package
STC9492C <sub>ID</sub>	$\overline{DLB}$	28-pin DIP
STC9492M <sub>ID</sub>		28-pin SOP
STC9492C <sub>IE</sub>	EXT	28-pin DIP
STC9492M <sub>IE</sub>		28-pin SOP



## ■ ABSOLUTE MAXIMUM RATINGS

Parameter		Symbol	Ratings	Unit
Supply voltage		$V_{CC}$	7	V
		$V_{DD}$	7	V
Input voltage	Analog input	$V_{IA}^{*1}$	$V_{EE}-0.3$ to $V_{CC}+0.3$	V
	Digital input	$V_{ID}^{*2}$	$V_{SS}-0.3$ to $V_{DD}+0.3$	V
Power dissipation		$P_D$	500	mW
Storage temperature		$T_{stg}$	-65 to 150	°C
Soldering temperature and time		$T_{sol}$	260°C, 10s (at lead)	—

\*1……TLA, CDA, RxA, MADJ

\*2……OSC1, TxD, SQT, ALB, O/A, ANSC, SCBE, HALF, DLB, B/C, EXT

## ■ RECOMMENDED OPERATING CONDITIONS

( $f_{osc}=4.032\text{MHz}$ ,  $V_{SS}=V_{EE}=0\text{V}$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage for analog section	$V_{CC}$	—	4.75	5.0	5.25	V
Supply voltage for digital section	$V_{DD}$	—	4.75	5.0	5.25	V
Analog input voltage	$V_{IA}$	—	$V_{EE}$	—	$V_{CC}$	V
Digital input voltage	$V_{ID}$	—	$V_{SS}$	—	$V_{DD}$	V
Operating temperature	$T_{opr}$	—	-10	25	70	°C
Oscillating frequency tolerance	$\Delta f_{osc}$	Crystal/External clock	-0.01	0	+0.01	%

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

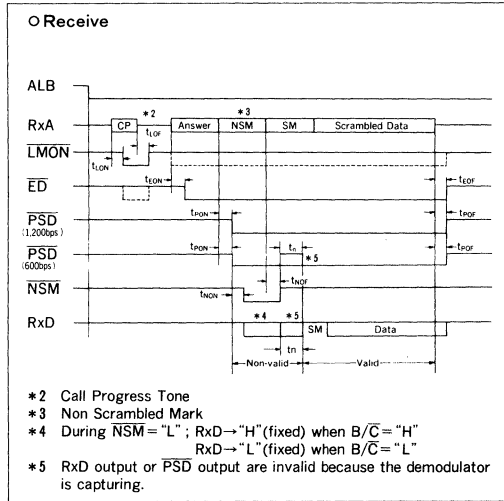
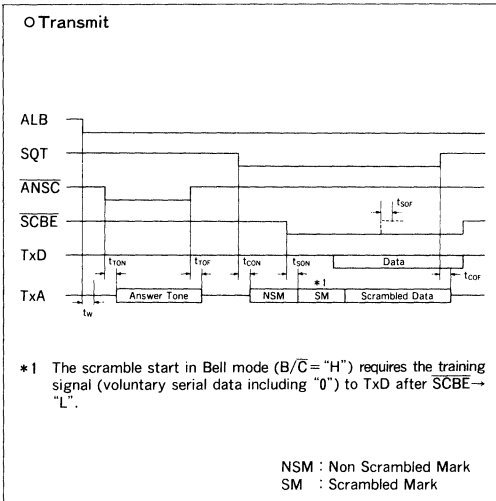
( $V_{DD}=5.0\text{V}$ ,  $V_{SS}=V_{EE}=0\text{V}$ ,  $T_a=25^\circ\text{C}$ )

Parameter		Symbol	Conditions	Min	Typ	Max	Unit
Digital section operating current	Operating	$I_{DDO}$	SQT or ALB = "L"	—	3	5	mA
	Power-down	$I_{DDs}$	SQT = ALB = "H"	—	—	1	$\mu\text{A}$
High level input voltage	$V_{IH}$	*1		3.5	—	$V_{DD}$	V
Low level input voltage	$V_{IL}$			$V_{SS}$	—	1.5	V
High level input current	$I_{IH}$	*1		—	—	1	$\mu\text{A}$
Low level input current	$I_{IL}$			5	10	30	$\mu\text{A}$
High level output current	$I_{OH}$		$V_{OH}=4.5\text{V}^{*2}$	—	3.5	—	mA
Low level output current	$I_{OL}$		$V_{OL}=0.5\text{V}^{*2}$	—	3.5	—	mA
Analog section operating current	Operating	$I_{CCO}$	SQT or ALB = "L"	—	20	30	mA
	Power-down	$I_{CCs}$	SQT = ALB = "H"	—	—	1	$\mu\text{A}$
Output DC impedance		$Z_{SG}$	SG	—	70	150	$\Omega$
		$Z_{TxA}$	TxA	—	150	250	$\Omega$
Reference voltage generator output impedance		$Z_{TLA}$	$V_{TLA}-V_{SG}\geq 1.0\text{V}$	20	—	500	k $\Omega$
		$Z_{CDA}$	$V_{CDA}-V_{SG}\geq 1.0\text{V}$	20	—	500	k $\Omega$
Input DC impedance		$Z_{RxA}$	RxA	5	—	—	M $\Omega$
		$Z_{MADJ}$	MADJ	5	—	—	M $\Omega$

\*1 Digital input terminal except for OSC1. (pull-up resistor is built-in)

\*2 ST, LMON, PSD, ED, RT, RxD, NSM

## ● AC Electrical Characteristics



### ○ Transmitter

( $f_{osc} = 4.032\text{MHz}$ ,  $V_{DD} = V_{CC} = 5.0\text{V}$ ,  $T_a = 25^\circ\text{C}$ )

Delay time	Trigger signal	Symbol	Min	Typ	Max	Unit
Power-on	ALB or SQT → "L"	$t_w$	—	50	100	ms
Answer tone transmit	SQT = "H", ANSC → "L"	$t_{TON}$	—	—	2	ms
Answer tone stop	SQT = "H", ANSC → "H"	$t_{TOF}$	—	—	2	ms
Carrier transmit	SQT → "L"	$t_{CON}$	—	—	2	ms
Carrier stop	ANSC = "H", SQT → "H"	$t_{COF}$	—	—	2	ms
Scrambler start	SQT = "L", SCBE → "L"	$t_{SON}$	—	—	70 *6	ms
Scrambler stop	SQT = "L", SCBE → "H"	$t_{SOF}$	—	—	10	ms

\*6 In case of CCITT mode, 1,200 bps

### ○ Receiver

( $f_{osc} = 4.032\text{MHz}$ ,  $V_{DD} = V_{CC} = 5.0\text{V}$ ,  $T_a = 25^\circ\text{C}$ )

Delay time	Input signal	Symbol	Min	Typ	Max	Unit
Call progress tone detection time	Call progress tone	$t_{LON}$	—	—	150	ms
		$t_{LOF}$	—	—	150	ms
Carrier detection time	Signal within receive band	$t_{EON}$	—	—	20	ms
		$t_{EOF}$	—	40	70	ms
PSK energy detection time	Phase shifted signal (600 baud)	$t_{PON}$	—	200	300	ms
		$t_{POF}$	—	—	100	ms
Non-scrambled mark detection time	Non-scrambled mark	$t_{NON}$	—	—	60	ms
		$t_{NOF}$	—	—	10	ms
Settling time	Scrambled data	$t_n$	—	—	600	ms

## ● Analog Characteristics

### ○ Transmitter

( $V_{CC}=5.0V$ ,  $T_a=25^\circ C$ , TLA is opened)

Parameter	Symbol	Condition	Min	Typ	Max	Unit
Tone frequency	$f_r$	Bell Answer tone	2,205	2,225	2,245	Hz
		CCITT Answer tone	2,090	2,100	2,110	
		CCITT Guard tone	1,790	1,800	1,810	
Transmit level	P	Answer tone	-12.0	-10.5	-9.0	dBm
		PSK carrier	-13.5	-12.0	-10.5	
Unexpected transmit level	$P_E$	$f=4$ to 8kHz	—	—	P-20	dBm
		$f=8$ to 12kHz	—	—	P-40	
		$f \geq 12$ kHz	—	—	P-60	

### ○ Receiver

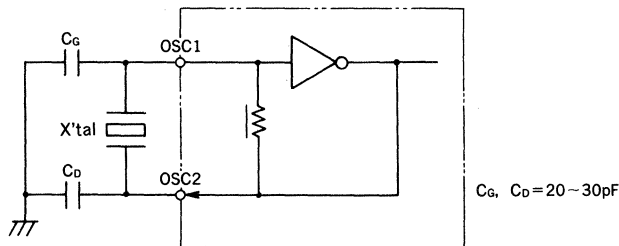
( $V_{CC}=5.0V$ ,  $T_a=25^\circ C$ , CDA is opened)

Parameter	Symbol	Condition	Min	Typ	Max	Unit
Allowable input range	DR	at RxA	-40	—	-5	dBm
Carrier detection level	$L_{ON}$	OFF→ON (On level)	-43	—	—	dBm
	$L_{OFF}$	ON→OFF (Off level)	—	—	-48	dBm
	$L_H$	Hysteresis width	1	2	—	dB
Call progress tone detection level	$L_D$	$V_{EE} \leq V_{MADJ} \leq V_{CC}$	—	—	-32	dBm
	$L_{AR}$	$L_D(\text{Max}) - L_D(\text{Min})$	10	—	—	dB

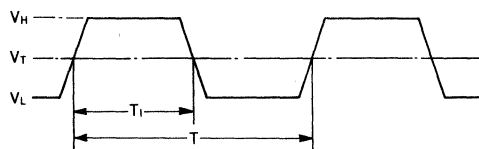
## ■ FUNCTIONS

### ● Oscillating Circuit

○ Crystal quartz oscillation



○ External clock into OSC1



Parameter	Symbol	Condition	Tolerance
Amplitude	$V_H$	$\geq V_{DD} - 1.0V$	—
	$V_L$	$\leq V_{SS} + 1.0V$	—
Frequency	$1/T$	4.032MHz	$\pm 0.01\%$
Duty	$T_1/T$	50%	$\pm 15\%$

## ● Operation Mode

ALB	SQT	Mode
High level	Low level	Normal mode (transmission enable)
	High level	Transmission disable mode
Low level	Low level	Analog loop-back test mode
	High level	Power-down mode

### ○ Power-down mode

During both ALB and SQT are high level, oscillation stops and operating current is to be below  $2\mu\text{A}$ .

### ○ Analog loop-back test mode

In the analog loop-back test mode, the functional test (including LSI) should be easily done, because transmission data into TxD are sent to the demodulator through the modulator automatically and appear from RxD again.

During this mode, transmit buffer so operates that test signal can be monitored, and, input signal into RxD is ignored by the demodulator but call progress tone can be detected.

### ○ Transmission disable mode

In this mode, the transmitter stops its operation but the receiver operates.

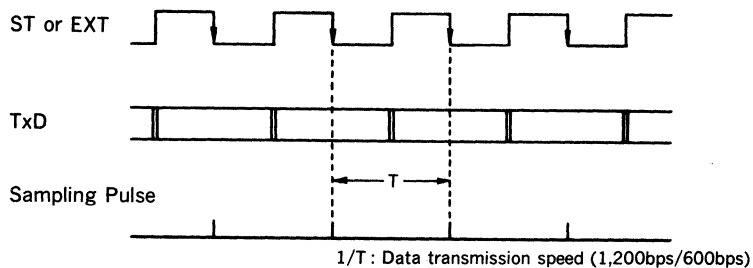
And the answer tone should be transmitted by  $\overline{\text{ANSC}}$  being low level.

### ○ Normal mode

Both the transmitter and the receiver become active, the PSK modulated signal which has a center frequency of 1,200Hz or 2,400Hz (depend on  $\text{O}/\overline{\text{A}}$  input) can be transmitted, and a  $1,800\pm 10\text{Hz}$  guard tone can be transmitted when  $\overline{\text{ANSC}} = \text{"L"}$  and CCITT answer mode are selected.

## ● Transmitter

### ○ Relation between input data and transmit timing signal



In case of using an external transmit timing (EXT), the frequency tolerance of EXT should be less than  $\pm 0.01\%$  of data transmission speed.

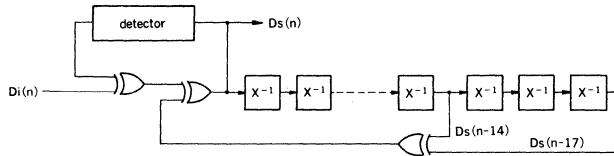
○ Scrambler

[Scrambler control]

Transmit data	SCBE	Algorithm
Scrambled	Low level	$D_s(n) = D_i(n) + D_s(n-14) + D_s(n-17)$
Non-scrambled	High level	$D_s(n) = D_i(n)$

- $D_i(n)$  ; Input data (TxD)
- $D_s(n-k)$  ; Scrambler output (k is output data of k times before)
- + ; Logical addition (mod 2)

[Construction]



- $x^{-1}$  ; 1 bit delay circuit
- detector ; In the CCITT mode ( $B/\overline{C} = "L"$ ), if it detects 64 or more continuous mark data in the output of the scrambler, this inverts the polarity of the following input data. In the Bell mode ( $B/\overline{C} = "H"$ ), the detector output becomes invalid, so that the training signal (voluntary serial data including "0") are required into TxD to start the scrambler.

○ Modulation

[Base-band modulation]

- 4-phase differential modulation

1,200bps	600bps	Phase shift (deg)
0 0	0	+ 90
0 1	—	+ 0
1 1	1	+270
1 0	—	+180

- Roll off characteristic .....75% cosine roll off

[Transmit carrier frequency]

Originate mode .....1,200Hz ± 0.01%

Answer mode .....2,400Hz ± 0.01%

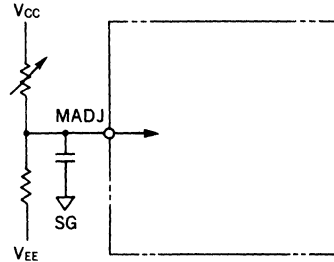
○ Tone Generator

Name	SQT	ANSC	O/A	B/C	Frequency
Answer tone	"H"	"L"	—	"L"	2,100Hz ± 10Hz
				"H"	2,225Hz ± 20Hz
Guard tone	"L"	"H"	"L"	"L"	1,800Hz ± 10Hz

● Receiver

○ Call progress tone detection

The definitions of the call progress tone are different in each country, so that an appropriate detection level can be adjusted by some external voltage through the MADJ terminal.



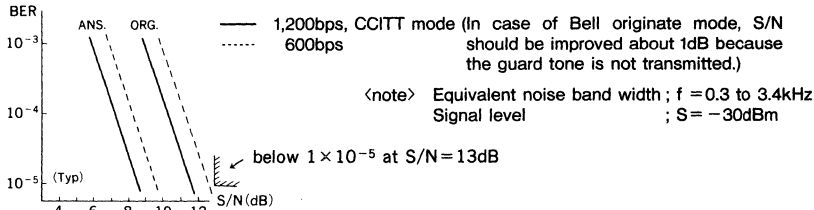
○ Demodulation

[Demodulated carrier frequency]

Mode	O/ $\bar{A}$	Carrier frequency	Tolerance
Originate	H	2,400Hz	$\pm 0.01\%$
Answer	L	1,200Hz	$\pm 0.01\%$

[Data reliability]

• Bit error rate (BER)



• Allowable range of the factor which makes the line characteristic worse

Factor	Symbol	Range	Unit
Frequency offset	$\Delta f$	$\pm 7$	Hz
Phase jitter	$\theta_j$	$\pm 20$	deg

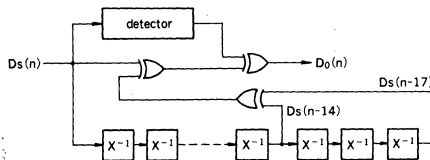
○ Descrambler

[Algorithm]

$$D_o(n) = D_s(n) + D_s(n-14) + D_s(n-17)$$

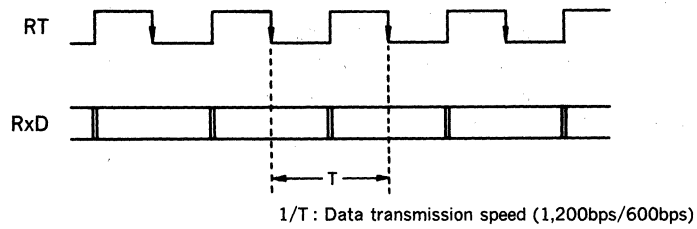
- $D_o(n)$  ; Output data (Rx/D)
- $D_s(n-k)$  ; Descrambler input (k is input data of k times before)
- + ; Logical addition (mod 2)

[Construction]



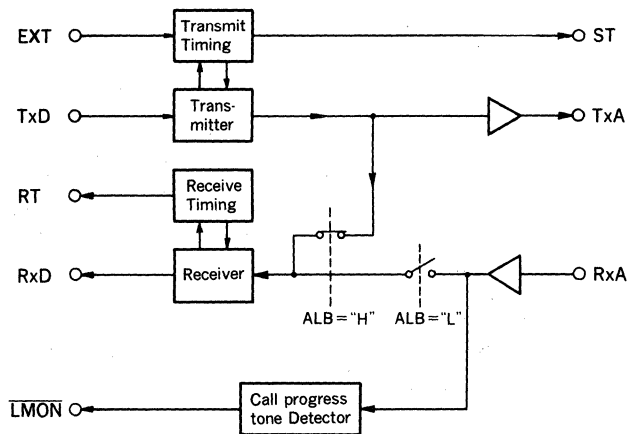
- $x^{-1}$  : 1 bit delay circuit
- detector : In the CCITT mode ( $B/\bar{C} = "L"$ ), if it detects 64 or more continuous mark data in the input of the descrambler, this inverts the polarity of the following output data and outputs low level to NSM.  
 In the Bell mode ( $B/\bar{C} = "H"$ ), the detector output is invalid for the descrambler, but valid for the  $\bar{NSM}$  output.

○ Relation between output data (RxD) and receive timing output (RT)

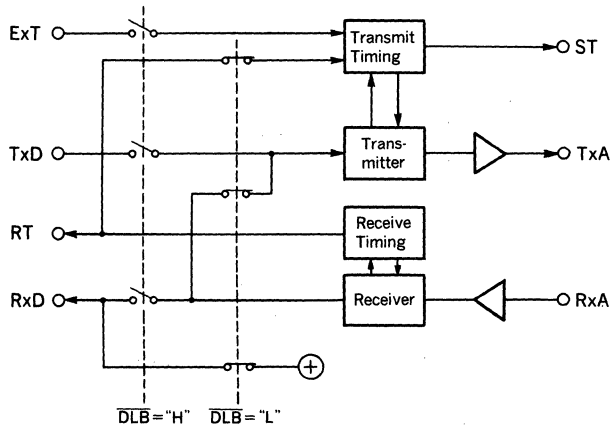


■ TEST FUNCTIONS

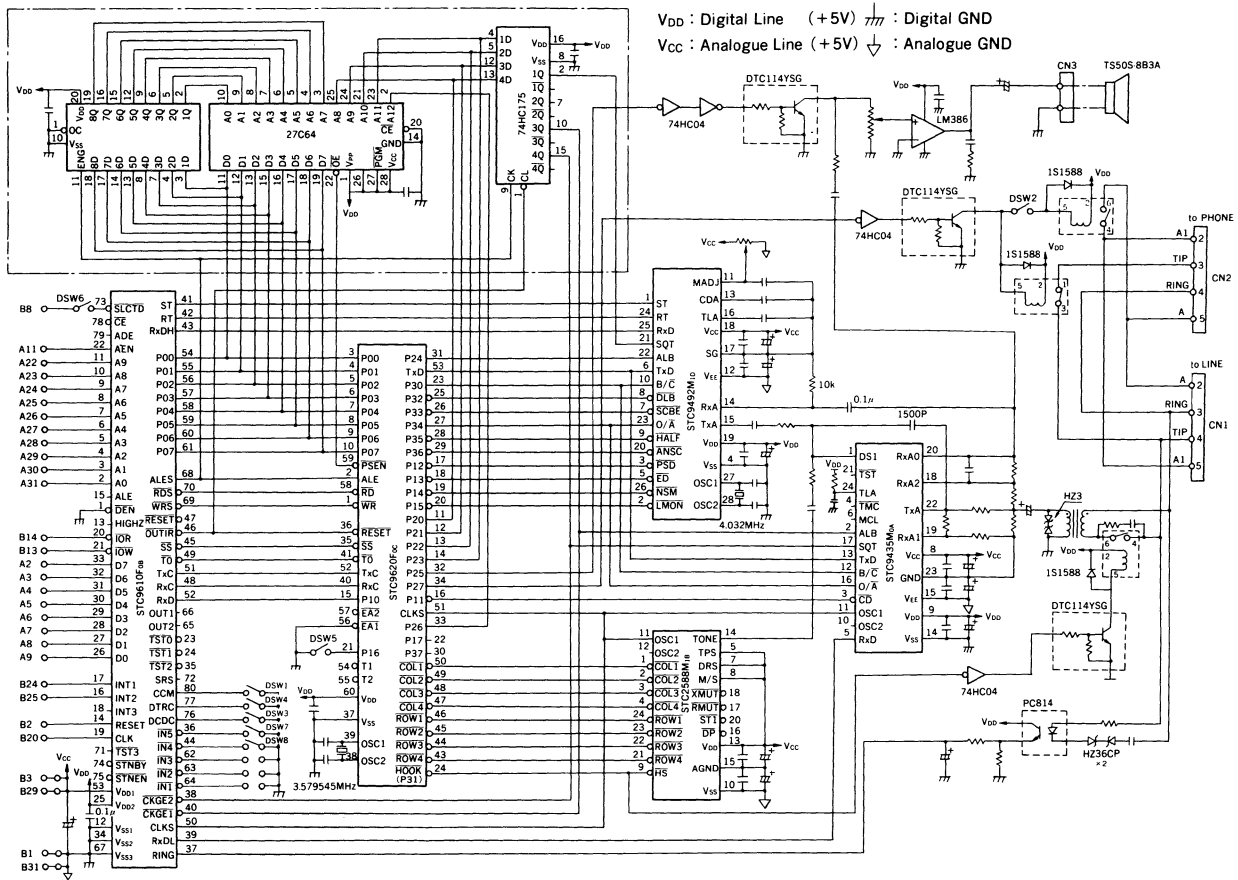
● Analog loop-back test



● Digital remote loop-back test

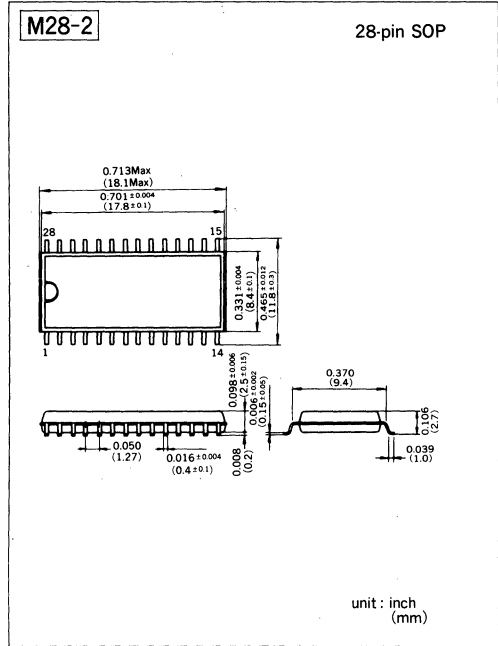
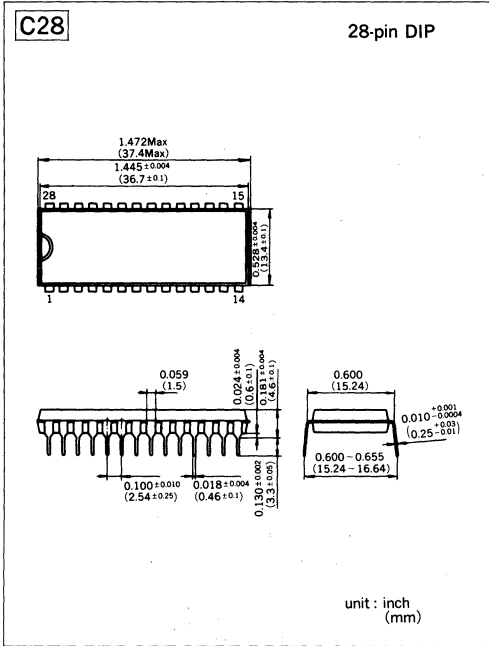


**EXAMPLE OF APPLICATIONS**  
**● Circuit for Intelligent MODEM card**





■ PACKAGE DIMENSIONS



# STC9610F<sub>0B</sub>

## CMOS ASYNCHRONOUS COMMUNICATION INTERFACE

- 8250 A/B Function Compatible
- Abundant Addressing Modes
- 300/110 bps Baud-rate Generator Incorporated

### DESCRIPTION

The STC9610F<sub>0B</sub> is an interface LSI with the protocol controller and the 8086 group host CPU, and supports the serial data I/O function at the asynchronous communication, as an external data memory of the protocol controller.

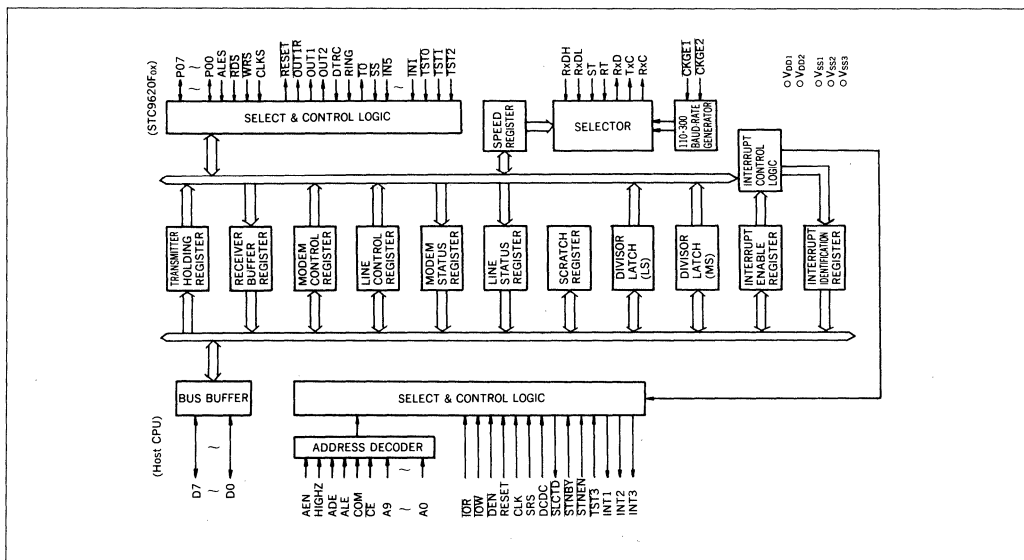
The host CPU interface is function compatible with the asynchronous communication adaptor 8250A/B, and especially the STC9610F<sub>0B</sub> has all interface functions for the system-bus of the IBM<sup>®</sup> PC-XT/AT.

### FEATURES

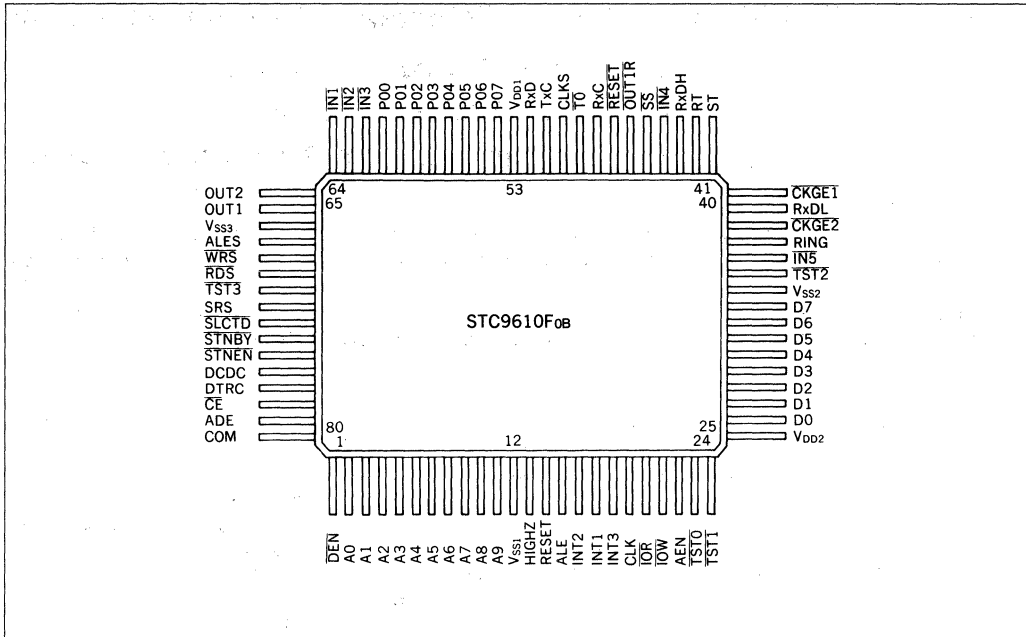
- Host CPU interface ..... Function compatible with the asynchronous communication adaptor 8250A/B.  
 Address control register : 8 bits×16  
 Abundant addressing mode : Address decoding function  
 Address data separating function  
 Can be controlled by an external address decoder.
- Protocol controller interface ..... Address control register : 8 bits×8
- Built-in 300/110 bps baud-rate generator (Protocol controller clock = 3.579545MHz)  
 Transmit clock : baud-rate×1  
 Receive clock : baud-rate×8
- Built-in expansive input function for the protocol controller (5 inputs)
- Built-in stand-by control function for the protocol controller
- Single power supply ..... 5V
- Package ..... 80-pin QFP (plastic)

IBM<sup>®</sup> PC-XT/AT is the registered trademark of International Business Machines Inc.

### BLOCK DIAGRAM



## PIN CONFIGURATION



## PIN DESCRIPTION

Pin name	Pin No.	I/O	Functions
$\overline{\text{DEN}}$	1	I	Inputs a signal which indicates that the bus data are valid, when the host system-bus is a multiplex bus. In this case, $\overline{\text{DEN}}=\text{L}$ makes the $\overline{\text{IOR}}$ and $\overline{\text{IOW}}$ active. Should be fixed to low level, when not used.
A0—A9	2—11	I	Input the addresses of the host CPU.
$V_{\text{SS1}}$	12	—	$V_{\text{SS}}$ power supply : 0V
$V_{\text{SS2}}$	34		
$V_{\text{SS3}}$	67		
HIGHZ	13	I*	Can be used when the decoded result of the high-ranking addresses (A10—A15) of the host CPU should be utilized. HIGHZ=L causes that the addresses are not decoded. Should be opened or fixed to high level, when not used.
RESET	14	I	Inputs the host reset signal. The high level input clears all registers (except for the Transmitter holding register, the Receiver buffer register and the Divisor latch register) and the control logic. And, it leads the following state ; (INT1, INT2)→high impedance (INT3, OUT1, OUT2)→low level
ALE	15	I*	Inputs the address latch timing signal ALE, when the host system-bus is a multiplex bus. Should be opened or fixed to high level, when not used.

Note ; I is a floating input so that it should always be given high level or low level.

I\* has a built-in pull-up resistor.

Pin name	Pin No.	I/O	Functions
INT2	16	O	3 state output Outputs an interrupt signal which is enabled in the case of COM=H and OUT2=1, to the host CPU. (The OUT2 is a bit3 of the MODEM control register.) Outputs the high impedance state in the case of COM=L or OUT2=0. Connects to the IRQ3 pin when the host CPU is the IBM® PC.
INT1	17	O	3 state output Outputs an interrupt signal which is enabled in the case of COM=L and OUT2=1, to the host CPU. (The OUT2 is a bit3 of the MODEM control register.) Outputs the high impedance state in the case of COM=H or OUT2=0. Connects to the IRQ4 pin when the host CPU is the IBM® PC.
INT3	18	O	Outputs an interrupt signal to the host CPU. Should be used when the OUT2 is not utilized as an enable register for the interrupt line.
CLK	19	I	Inputs the host system clock.
$\overline{\text{IOR}}$	20	I	Inputs the host read signal.
$\overline{\text{IOW}}$	21	I	Inputs the host write signal.
AEN	22	I	Inputs a signal which indicates that the DMA controller is using the bus. AEN=H causes that the addresses from being decoded. Should be fixed to low level, when not used.
$\overline{\text{TST0}}$	23	I*	LSI test inputs. Should be opened normally.
$\overline{\text{TST1}}$	24		
$\overline{\text{TST2}}$	35		
$\overline{\text{TST3}}$	71		
V <sub>DD2</sub>	25	—	V <sub>DD</sub> power supply : +5V
V <sub>DD1</sub>	53		
D0—D7	26—33	I/O	3 state I/O terminals Connect to the data-bus of the host CPU.
$\overline{\text{IN5}}$ $\overline{\text{IN4}}$ $\overline{\text{IN3—IN1}}$	36 44 62—64	I*	Can be used as the expansive input ports for the protocol controller.
RING	37	I	Inputs the ringing detection signal. ringing : high level    not ringing : low level
$\overline{\text{CKGE2}}$	38	I	Enable the built-in baud-rate generator. The baud-rate generator is halted in the case of $\overline{\text{CKGE1}} = \overline{\text{CKGE2}} = \text{H}$ , and operates when either of these pins is low level.
$\overline{\text{CKGE1}}$	40		
RxDL	39	I	Inputs the receive data of a low speed MODEM. Outputs the input signal into the RxDL to the RxD at the low speed mode.*1
ST	41	I	Inputs the transmit timing clock of a synchronous MODEM. Outputs the input signal into the ST to the TxC at the high speed mode.*1
RT	42	I	Inputs the receive timing clock of a synchronous MODEM. Outputs the input signal into the RT to the RxC at the high speed mode.*1
RxDH	43	I	Inputs the receive data of a high speed MODEM. Outputs the input signal into the RxDH to the RxD at the high speed mode.*1

Note ; I is a floating input so that it should always be given high level or low level.

I\* has a built-in pull-up resistor.

IBM® PC is the registered trademark of International Business Machines.

\*1...Control register 2 (CR2) bit7=1 makes the high speed mode, and the bit7=0 makes low speed mode.

Pin name	Pin No.	I/O	Functions
$\overline{SS}$	45	I	<p>These 4 terminals are used to construct a system which lets the protocol controller have the stand-by mode.</p> <p>When this function is not utilized, the <math>\overline{SS}</math> should be fixed to low level or high level and <math>\overline{T0}</math>, <math>\overline{STNBY}</math> and <math>\overline{STNEN}</math> should be opened.</p> <p><math>\overline{STNBY}</math> ; Inputs the stand-by control signal.</p> <p><math>\overline{STNEN}</math> ; Inputs the clock signal for writing into the <math>\overline{STNBY}</math> register.</p> <p>The value into the <math>\overline{STNBY}</math> is written into the bit0 of the Control register 3 (CR3), at the rising edge of the <math>\overline{STNEN}</math>.</p> <p>normal operation : bit0 = 1 stand-by mode : bit0 = 0</p> <p><math>\overline{T0}</math> ; Outputs the interrupt signal for cancelling the stand-by mode.</p> <p>Outputs low level at the time when bit0 of CR3 changes from 0 to 1 . Returns to high level when the protocol controller reads the Control register 1 (CR1) after this state.</p> <p><math>\overline{SS}</math> ; Inputs the inhibit signal for cancelling the stand-by mode.</p> <p>When the <math>\overline{SS}</math> is low level, it does not output low level to the <math>\overline{T0}</math>, even though the bit0 of CR3 changes from 0 to 1.</p>
$\overline{T0}$	49	O	
$\overline{STNBY}$	74	I*	
$\overline{STNEN}$	75	I*	
$\overline{OUT1R}$	46	O	<p>Outputs a reset signal to the protocol controller.</p> <p>Outputs low level in the case of RESET = H or OUT1 = 1. (The OUT1 is the bit2 of MODEM control register.) Should be used when the software-reset is utilized together with the hardware-reset.</p>
RESET	47	O	<p>Outputs a reset signal to the protocol controller.</p> <p>Outputs an inverted level of the RESET input.</p> <p>Should be used when only the hardware-reset is utilized.</p>
RxC	48	O	<p>Outputs the RT input at the high speed mode.</p> <p>Outputs the receive timing clock generated from the built-in baud-rate generator at the low speed mode.*1</p>
CLKS	50	I	<p>Inputs the protocol controller clock. Should be input a 3.579545MHz clock when the built-in baud-rate generator is utilized.</p>
TxC	51	O	<p>Outputs the ST input at the high speed mode.*1</p> <p>Outputs the transmit timing clock generated from the built-in baud-rate generator at the low speed mode.*1</p>
RxD	52	O	<p>Outputs the RxDH input at the high speed mode.*1</p> <p>Outputs the RxDL input at the low speed mode.*1</p>
P07—P00	54—61	I/O	<p>Connects the address-data bus of protocol controller.</p>
OUT2	65	O	<p>Outputs the value of the OUT2 (bit3 of the MODEM control register).</p>
OUT1	66	O	<p>Outputs the value of the OUT1 (bit2 of the MODEM control register).</p>
ALES	68	I	<p>Inputs the address latch timing signal of the protocol controller.</p>
$\overline{WRS}$	69	I	<p>Inputs the write signal of the protocol controller.</p>
$\overline{RDS}$	70	I	<p>Inputs the read signal of the protocol controller.</p>
SRS	72	I*	<p>Selects the register of address 7(A2 = A1 = A0 = 1) controlled by the host CPU to be a Scratch register or a Speed indicator register.</p> <p>Scratch register : high level Speed indicator : low level</p>
$\overline{SLCTD}$	73	O	<p>Becomes necessary when the system (includes this STC9610F0A) is used into the half-slot of the IBM® PC-XT.</p> <p>Outputs the <math>\overline{IOR}</math> input according that the host CPU reads the register.</p>

Note ; I is a floating input so that it should always be given high level or low level.

I\* has a built-in pull-up resistor.

\*1...Control register 2(CR2) bit7=1 makes high speed mode and the bit7=0 makes low speed mode.

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Pin name	Pin No.	I/O	Functions
DCDC	76	I*	Controls the bit7 of MODEM status register read by the host CPU. The bit7 is a data carrier detection (DCD), and is utilized to inform that the protocol controller is detecting the receive carrier, to the host CPU. At DCDC=L ; The bit7 outputs the DCD value set by the protocol controller. At DCDC=H ; The bit7 outputs always 1 regardless of the value set by the protocol controller.
DTRC	77	I*	Controls the bit6 of Control register 3 (CR3) read by the protocol controller. The bit6 is a data terminal ready (DTR), and is utilized to inform that the host CPU is in the transmit enable state to the protocol controller. At DTRC=L ; The bit6 outputs the DTR value set by the host CPU. At DTRC=H ; The bit6 outputs always 1 regardless of the value set by the host CPU.
$\overline{\text{CE}}$	78	I*	Inputs the decoded result when the external address decoder is utilized. (Low active) In this case, the host CPU can utilize the register designated by A2, A1 and A0 during CE=L.
ADE	79	I*	Inputs an enable signal for the internal address decoder. Should be opened or fixed to high level when the internal address decoder is utilized. When the internal address decoder is not utilized, the ADE should be low level and the A9—A3 should be 1 or 0.
COM	80	I*	Inputs a signal to designate the decoded address of address decoder, and to select the terminal for the interruption output. At COM=L ; Decoded address=3F8—3FF (H) Interruption output=INT1 (The INT2 becomes high impedance.) At COM=H ; Decoded address=2F8—2FF (H) Interruption output=INT2 (The INT1 becomes high impedance.)

Note ; I\* has a built-in pull-up resistor.

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS1</sub> = V<sub>SS2</sub> = V<sub>SS3</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub> *1	-0.3 to 7.0	V
Input voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> +0.3*1	V
Output voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> +0.3*1	V
Output current	I <sub>O</sub>	±10*2	mA
Power dissipation	P <sub>D</sub>	100	mW
Power supply current	I <sub>DD</sub> /I <sub>SS</sub>	±40*2	mA
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

\*1 V<sub>DD</sub> = V<sub>DD1</sub> or V<sub>DD2</sub>

\*2 The sign + or - shows the current flow direction.  
(+...inflow direction, -...outflow direction)

## ■ RECOMMENDED OPERATING CONDITIONS

(V<sub>SS1</sub> = V<sub>SS2</sub> = V<sub>SS3</sub> = 0V)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
Input voltage	V <sub>I</sub>		V <sub>SS</sub> *1	—	V <sub>DD</sub> *2	V
Operating temperature	T <sub>a</sub>		0	—	70	°C

\*1 V<sub>SS</sub> = V<sub>SS1</sub>, V<sub>SS2</sub> or V<sub>SS3</sub>

\*2 V<sub>DD</sub> = V<sub>DD1</sub> or V<sub>DD2</sub>

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Characteristics

(V<sub>DD</sub> = V<sub>DD1</sub> or V<sub>DD2</sub>, V<sub>SS</sub> = V<sub>SS1</sub>, V<sub>SS2</sub> or V<sub>SS3</sub> = 0V, T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Standby supply current	I <sub>DDs</sub>	V <sub>I</sub> = V <sub>DD</sub> or V <sub>SS</sub> , I <sub>OH</sub> = I <sub>OL</sub> = 0	—	—	10	μA
Input leakage current	I <sub>LI</sub>	V <sub>DD</sub> = 5.5V, V <sub>IH</sub> = V <sub>DD</sub> , V <sub>IL</sub> = V <sub>SS</sub> *1	-1	0	1	μA
High level input voltage	V <sub>IH1</sub>	V <sub>DD</sub> = 5.5V*2	2.2	—	—	V
	V <sub>IH2</sub>	V <sub>DD</sub> = 5.5V, $\overline{SS}$	3.5	—	—	
Low level input voltage	V <sub>IL1</sub>	V <sub>DD</sub> = 4.5V*2	—	—	0.6	V
	V <sub>IL2</sub>	V <sub>DD</sub> = 4.5V, $\overline{SS}$	—	—	1.0	
High level trigger voltage	V <sub>T+</sub>	V <sub>DD</sub> = 5.5V, RESET, RING	—	—	4.0	V
Low level trigger voltage	V <sub>T-</sub>	V <sub>DD</sub> = 4.5V, RESET, RING	0.8	—	—	V
Pull-up resistor	R <sub>PL</sub>	V <sub>DD</sub> = 5.0V*3	100	—	900	kΩ
High level output voltage	V <sub>OH</sub>	V <sub>DD</sub> = 4.5V, I <sub>OH</sub> = -2mA*4	V <sub>DD</sub> - 0.4	—	—	V
Low level output voltage	V <sub>OL</sub>	V <sub>DD</sub> = 4.5V, I <sub>OL</sub> = 6mA*4	—	—	0.4	V
Off-state leak current	I <sub>OZ</sub>	V <sub>DD</sub> = 5.5V, V <sub>OH</sub> = V <sub>DD</sub> , V <sub>OL</sub> = V <sub>SS</sub> *5	-1	0	1	μA

\*1 All input terminals which have no pull-up resistor.

[DEN, AO-A9, RESET, CLK, TOR, IOW, AEN, (DO-D7), RING,  $\overline{CKGE2}$ , RxDL,  $\overline{CKGE1}$ , ST, RT, RxDH,  $\overline{SS}$ , CLKS, (P00-P07), ALES, WRS, RDS]

\*2 All input terminals except for the schmidt inputs (RESET, RING) and the  $\overline{SS}$ .

\*3 Input terminals with the pull-up resistors.

[HIGHZ, ALE, TST0, TST1, TST2, IN5, IN4, IN3, IN2, IN1,  $\overline{TST3}$ , SRS,  $\overline{STNBY}$ ,  $\overline{STNEN}$ , DCDC, DTRC,  $\overline{CE}$ , ADE, COM]

\*4 All output terminals including the 3 state output.

\*5 3 state output terminals. [INT2, INT1, (DO-D7), (P00-P07)]

●AC Characteristics and Timing Chart

○Interface With The Protocol Controller

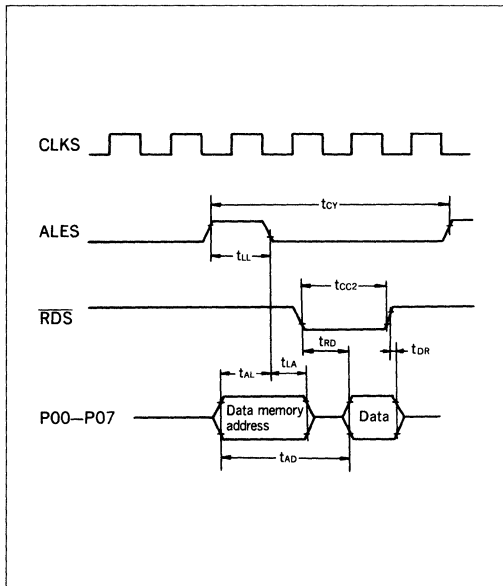
(1) AC Characteristics

( $V_{DD} = 5V \pm 10\%$ ,  $V_{SS} = 0V$ ,  $f_{CLKS} = 3.579545MHz$ ,  $T_a = 0$  to  $70^\circ C$ )

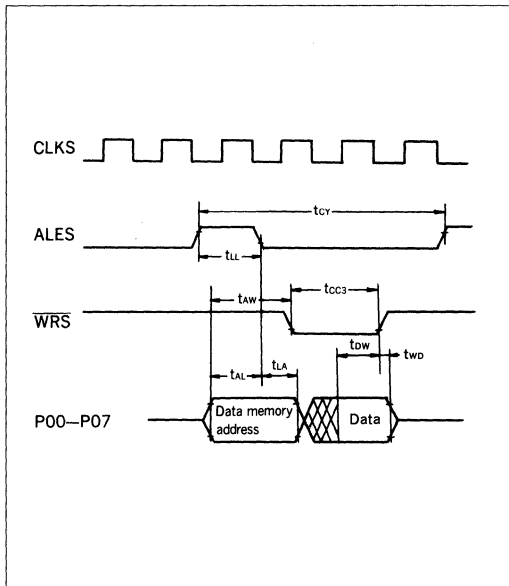
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Cycle time	$t_{CY}$		—	1.117	—	$\mu s$
Pulse width of ALES	$t_{LL}$		200	—	—	ns
Address set-up time	$t_{AL}$		100	—	—	ns
Address hold time	$t_{LA}$		50	—	—	ns
Pulse width of $\overline{RDS}$	$t_{CC2}$		300	—	—	ns
Pulse width of $\overline{WRS}$	$t_{CC3}$		300	—	—	ns
Delay time of data input	$t_{RD}$		—	—	150	ns
Read data hold time	$t_{DR}$		0	—	100	ns
Write data set-up time	$t_{DW}$		250	—	—	ns
Write data hold time	$t_{WD}$		5	—	—	ns
$\overline{WRS}$ delay time	$t_{AW}$		200	—	—	ns
Delay time of data input	$t_{AD}$		—	—	450	ns

(2) Timing Chart

○Data output cycle to the protocol controller



○Data input cycle from the protocol controller





## ○Interface With The Host CPU

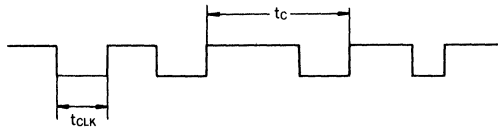
### (1) AC Characteristics

( $V_{SS1}=V_{SS2}=V_{SS3}=0V$ ,  $V_{DD1}=V_{DD2}=5V \pm 10\%$ ,  $T_a=0$  to  $70^\circ C$ )

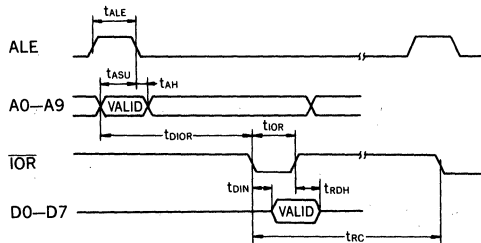
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Pulse width of ALE	$t_{ALE}$		90	—	—	ns
Address set-up time	$t_{ASU}$		90	—	—	ns
Address hold time	$t_{AH}$		0	—	—	ns
Delay time of $\overline{IOR}$	$t_{DIOR}$		80	—	—	ns
Pulse width of $\overline{IOR}$	$t_{IOR}$		175	—	350	ns
Delay time of data-in	$t_{DIN}$		—	—	175	ns
Read data hold time	$t_{RDH}$		100	—	—	ns
Read cycle time	$t_{RC}$		755	—	—	ns
Delay time of $\overline{IOW}$	$t_{DIOW}$		80	—	—	ns
Pulse width of $\overline{IOW}$	$t_{IOW}$		175	—	350	ns
Write data set-up time	$t_{WSU}$		90	—	—	ns
Write data hold time	$t_{WDH}$		60	—	—	ns
Write cycle time	$t_{WC}$		755	—	—	ns
Pulse width of CLK	$t_{CLK}$		20	—	350	ns
CLK period	$t_c$		—	—	400	ns

### (2) Timing Chart

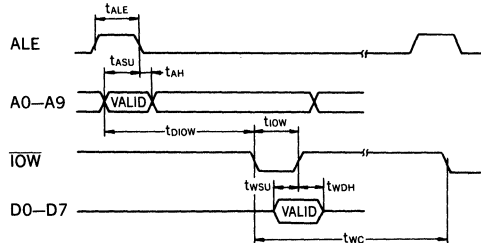
○ Clock input into the CLK



○ Read cycle



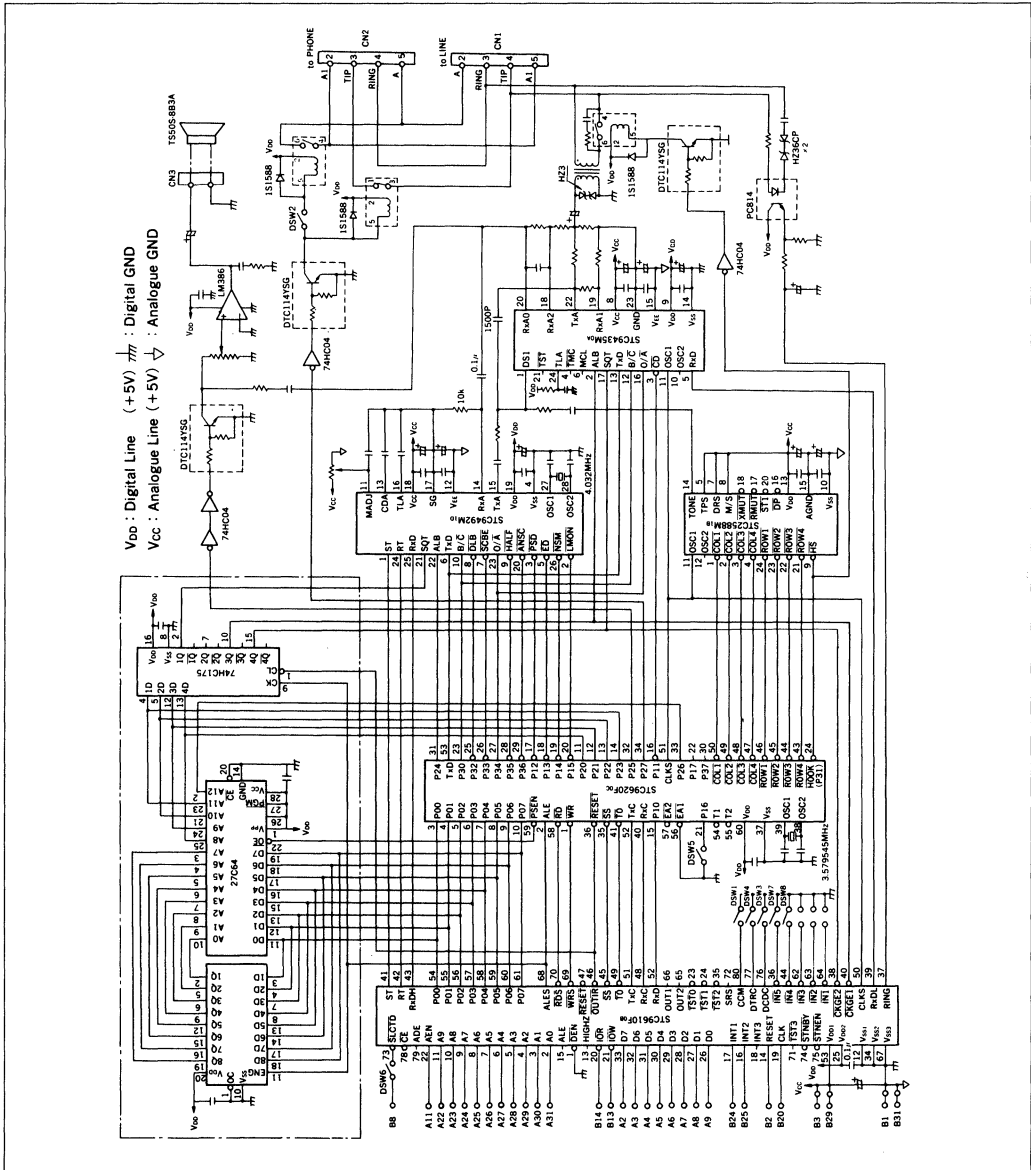
○ Write cycle



## EXAMPLE OF APPLICATIONS

This schema shows an example of the system-bus interface type intelligent MODEM, combining the STC 9610F<sub>0B</sub> with the following LSIs ;

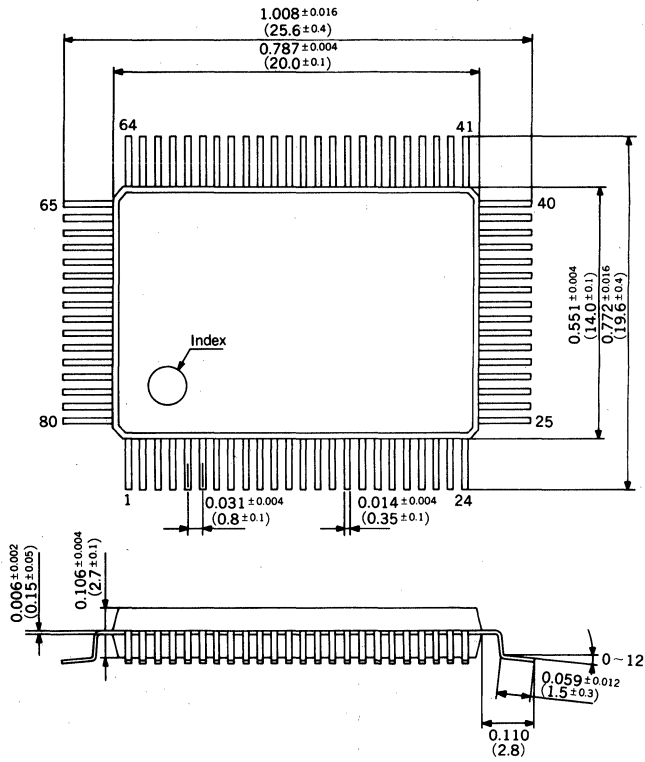
- Protocol controller .....STC9620F Series
- High speed MODEM (1,200bps PSK) .....STC9492M Series
- Low speed MODEM (300bps FSK) .....STC9435M Series
- DTMF dialer .....STC2588M Series



PACKAGE DIMENSIONS

F80-5

80-pin QFP



unit : inch  
(mm)

# STC9620F Series

## CMOS COMMUNICATION PROTOCOL CONTROLLER

- Compatible with "AT Command" System
- Ports for Interface with Modem and Host CPU
- On-chip Data Parallel/Serial Conversion Circuit

### DESCRIPTION

The STC9620F series asynchronous Communication Protocol Controller runs on a host CPU via an external data memory (registers) and controls a modem LSI or dialer to provide an intelligent communication function. The protocol controller is stored in the program memory of the STC9620F, and can be changed as required to support a specific communication protocol.

In order for the user to understand the functions of the STC9620F series more realistically, this document focuses on the STC9620F<sub>0B</sub> that provides programmed intelligent functions compatible with the "AT Command" system.

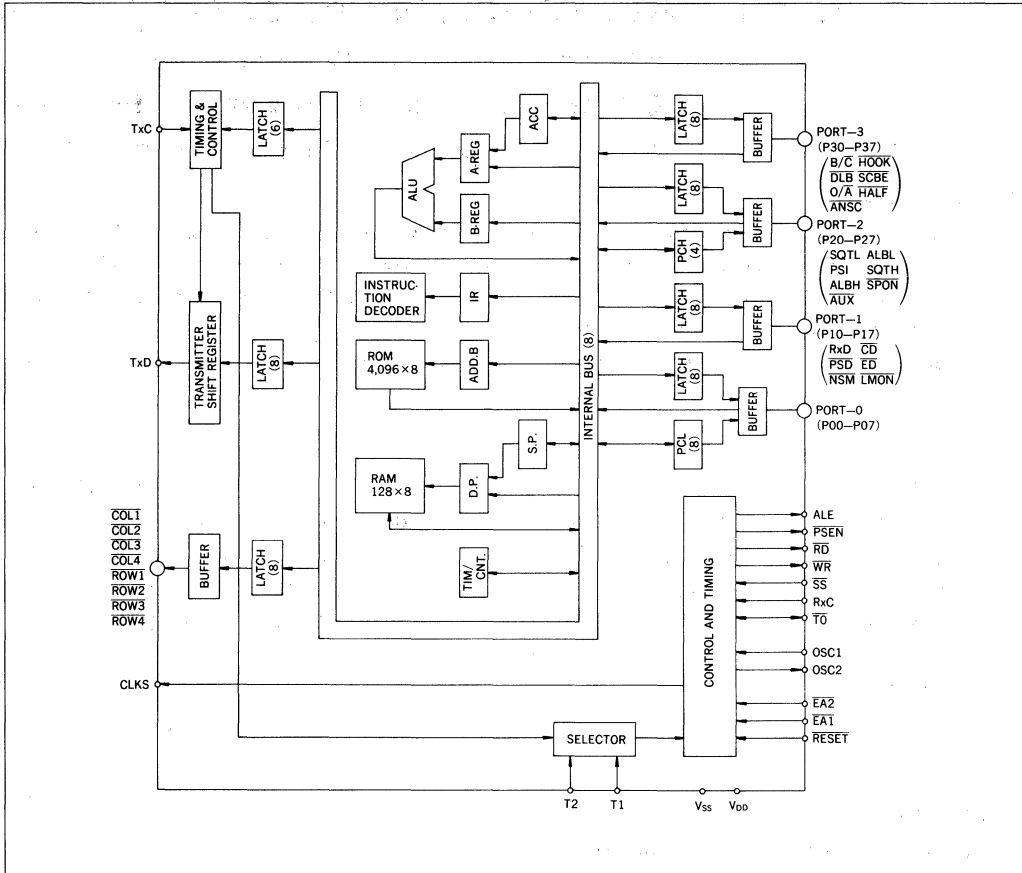
The STC9620F<sub>0B</sub> contains a parallel/serial data conversion circuit. The STC9620F<sub>0B</sub> enables the designer to easily configure a system bus interface based intelligent modem when combined with :

1,200 bps PSK full-duplex modem LSI	STC9492C <sub>ID</sub> (STC9492M <sub>ID</sub> )
300 bps FSK full-duplex modem LSI	STC9424C <sub>0A</sub> (STC9424M <sub>0A</sub> )
DTMF dialer	STC2588C <sub>1B</sub> (STC2588M <sub>1B</sub> )
System bus interface LSI (external data memory)	STC9610F <sub>0A</sub>

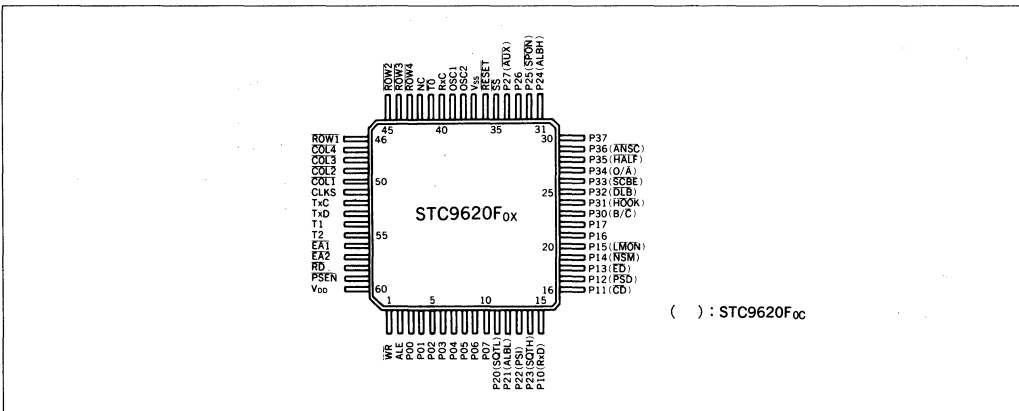
### FEATURES

- Compatible with "AT Command" system
- Can be used with Bell 212A/103 or CCITT V.22/(V.21) protocol (V.21 optional)
- On-chip asynchronous (start-stop synchronous) communication parallel/serial data conversion
- Interface with host CPU ..... Programmable registers
  - External data memory : 8 × 8 bits
- Modem control interface ..... Function assignment I/O ports
  - Data : Format : Asynchronous serial  
(Start-stop synchronous)
  - Length : 7 or 8 bits
  - Parity : None, even, odd, mark, space
  - Stop bit length : 1 or 2 bits
  - Break signal : Generation/detection function
- Power supply ..... Single 5V
- Package ..... 60-pin QFP (plastic)

## ■ BLOCK DIAGRAM



## ■ PIN CONFIGURATION



## ■PIN DESCRIPTION

Pin name	Pin No.	I/O	Functions
WR	1	O*1	Provides a timing signal for writing data to external data memory.
ALE	2	O*1	The address of external data memory or external program memory is latched at the falling edge of the output provided at this pin.
P00—P07	3—10	I/O*2	I/O ports for external data memory or external program memory. Each of these pins provides the address of external data memory synchronously with the ALE signal, then reads or writes data synchronously with the RD or WR signal. Also, it provides the low-order 8 bits of the address of external program memory synchronously with the ALE signal, then fetches the addressed instruction synchronously with the PSEN signal.
P20—P23 P24—P27	11—14 31—34	O*2/3	Output only ports used to control the modem. The P20—P23 provide the high-order 4 bits of the address of external program memory when it is connected.
[SQT]	[11]		[Controls the squelch transmitter (SQT) pin of STC9430 Series.]
[ALBL]	[12]		[Controls the analog loopback test (ALB) pin of STC9430C Series.]
[PSI]	[13]		[Controls the power save control (PSI) pin of STC9430C Series.]
[SQTH]	[14]		[Controls the squelch transmitter (SQT) pin of STC9492C1D.]
[ALBH]	[31]		[Controls the analog loopback test (ALB) pin of STC9492C1D.]
[SPON]	[32]		[Turns on/off the speaker to monitor DTMF tone or send/receive signal. Speaker ON...low level Speaker OFF...high level]
	[33]		[For STC9620F08, this pin must be opened as the device does not use P26.]
[AUX]	[34]		[Provides an output for driving the relay which determines whether the modem or handset is to be connected to the telephone line. Modem connected...low level Handset connected...high level]
P10—P17	15—22	I*2	Input only ports to control the modem.
[RxD]	[15]		[STC9430C Series or STC9492C1D receive data (RxD) input]
[CD]	[16]		[STC9430C Series carrier detection signal (CD) input]
[PSD]	[17]		[STC9492C1D PSK energy detection signal (PSD) input]
[ED]	[18]		[STC9492C1D carrier detection signal (ED) input]
[NSM]	[19]		[STC9492C1D non-scramble mark detection signal (NSM) input]
[LMON]	[20]		[STC9492C1D call progress tone detection signal (LMON) input]
	[21] [22]		[For STC9620F08, these pins must be opened as the device does not use P16/P17.]
P30—P37	23—30	O*2	Output only ports for modem control.
[B/C]	[23]		[Controls the Bell/CCITT (B/C) pin of STC9492C1D.]
[HOOK]	[24]		[Controls the hook switch (HS) pin of STC2588C1B. Also drives the relay which is used to select on-hook or off-hook for the telephone circuit. Off-hook...low level On-hook...high level]
[DLB]	[25]		[Controls the digital remote loopback test (DLB) pin of STC9492C1D.]
[SCBE]	[26]		[Controls the scramble control (SCBE) pin of STC9492C1D.]
[O/A]	[27]		[Controls the originate/answer mode select (O/A) pin of STC9430C Series or STC9492C1D.]
[HALF]	[28]		[Controls the 1,200/600 bps data transfer speed select (HALF) pin of STC9492C1D.]
[ANSC]	[29]		[Controls the answer tone send control (ANSC) pin of STC9492C1D.]
	[30]		[For STC9620F08, this pin must be opened as the device does not use P37.]
SS	35	I	This signal is used to execute one instruction after another. The pin contains a pull-up resistor (about 100k-ohms), and pulled down (about 10k-ohms) when the device is in stop mode. [For STC9620F08, the SS pin must be opened as the device does not use it.]
RESET	36	I	Resets the internal CPU into stand-by mode. (A pull-up resistor is incorporated.) Stand-by mode...low level Normal run mode...high level In stand-by mode, the set-up of each function is as follows: <ul style="list-style-type: none"> <li>• Program counter set to "0"</li> <li>• Stack pointer set to "0"</li> <li>• Program memory area set to addresses 0 through 2047</li> <li>• Ports P0—P3 set to entry mode</li> <li>• Pin T0 set to entry mode</li> <li>• External interrupts disabled</li> <li>• Internal interrupts disabled</li> <li>• Pin TxD set to "1"</li> <li>• Timer/counter off</li> </ul>

Remarks: The descriptions enclosed in [ ] give functions of the STC9620F08.

Pin name	Pin No.	I/O	Functions															
V <sub>SS</sub>	37	—	Power supply, 0V															
OSC2	38	O	A crystal oscillator (3.579545MHz) is connected between the two pins and capacitors (C <sub>a</sub> , C <sub>b</sub> ) between each of the pins and the power supply pin to make reference signal sources.															
OSC1	39	I																
RxC	40	I	Receive clock is entered at this pin. (A pull-up resistor is incorporated.) Data is read from P10 [RxD] synchronously with the falling edge of the receive clock entered.															
T <sub>0</sub>	41	I	This pin receives the stand-by clear signal. (A pull-up resistor is incorporated.) If at least 2 cycles of low level are applied to this pin with an external interrupt enabled, an interrupt occurs to clear the stand-by mode. [For STC9620F <sub>08</sub> , the T <sub>0</sub> pin must be opened as the device does not use it.]															
NC	42	—	As this pin is used for special operation verification, it must be held open.															
ROW4—ROW1	43—46	O	Controls key entry for the DTMF dialer. A combination of these outputs enables access to keys 0—9, *, and #. [Controls the STC2588C <sub>1B</sub> key input (ROW4—ROW1, COL4—COL1) pins.]															
COL4—COL1	47—50																	
CLKS	51	O	System clock output. In normal run mode, a system clock of 3.579545MHz (the oscillation circuit frequency) is output via the buffer. [The system clock is supplied as the reference signal source for STC9424C <sub>0A</sub> , STC2588C <sub>1B</sub> or STC9610F <sub>0A</sub> .]															
TxC	52	I	Transmit clock input. The TxD pin provides transmit data which becomes stable at the falling edge of the transmit clock entered to the TxC pin.															
TxD	53	O	Transmit data output. Transmit data written into the external data memory according to the format information stored by the host CPU is supplied in serial data form at the baud rate of the transmit clock entered to the TxC pin. [Transmit data is supplied to the STC9430C Series or STC9492C <sub>1D</sub> transmit data input (TxD) pin.]															
T1	54	I	Interrupt control signal input. (A pull-up resistor is incorporated.) When high level is applied to this pin, internal interrupt mode results and the input to pin T2 is nullified. For low level, external interrupt mode results and an interrupt signal entered to pin T2 becomes valid. [For STC9620F <sub>08</sub> , the T1 pin must be opened as the device does not use it.]															
T2	55	I	External interrupt signal input. (A pull-up resistor is incorporated.) In external interrupt mode, an external interrupt is enabled at the falling edge of the input to pin T2. [For STC9620F <sub>08</sub> , the T2 pin must be opened as the device does not use it.]															
EA1	56	I	A combination of these two pin inputs determines control mode. (Pull-up resistors are incorporated.)															
EA2	57																	
			<table border="1"> <thead> <tr> <th>EA2</th> <th>EA1</th> <th>Control mode</th> </tr> </thead> <tbody> <tr> <td>H</td> <td>H</td> <td>Normal run mode</td> </tr> <tr> <td>H</td> <td>L</td> <td>External program memory mode</td> </tr> <tr> <td>L</td> <td>H</td> <td>Internal program memory data read mode</td> </tr> <tr> <td>L</td> <td>L</td> <td>Internal program memory addressing mode</td> </tr> </tbody> </table>	EA2	EA1	Control mode	H	H	Normal run mode	H	L	External program memory mode	L	H	Internal program memory data read mode	L	L	Internal program memory addressing mode
EA2	EA1	Control mode																
H	H	Normal run mode																
H	L	External program memory mode																
L	H	Internal program memory data read mode																
L	L	Internal program memory addressing mode																
RD	58	O	Provides a timing signal at which data is read from external data memory.															
PSEN	59	O	Provides a timing signal at which an instruction is taken from external program memory.															
V <sub>DD</sub>	60	—	Power supply, +5V															

Remarks : The descriptions enclosed in [ ] give functions of the STC9620F<sub>08</sub>.

Notes \*1 Each control signal holds high level when the device is in the stand-by mode or stop mode, or when the program halts in a single step mode.

\*2 In the stand-by mode (system reset), all of P00—P07, P10—P17, P20—P27 and P30—P37 work as input ports.

\*3 With external program memory used, no data can be derived from P20—P23.

## ■ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Power supply voltage	V <sub>DD</sub>	-0.3 to 7.0	V
Input voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Power Dissipation	P <sub>D</sub>	0.5	W
Operating temperature	T <sub>opr</sub>	-10 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

## ■RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub>=0V, f<sub>OSC</sub>=3.579545MHz, Ta=-10 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Operating voltage	V <sub>DD</sub>		4.5	5	5.5	V
Operating frequency	f <sub>OSC</sub>	V <sub>DD</sub> =5V±10%	50	—	4,000	kHz

## ■ELECTRICAL CHARACTERISTICS

### ●DC Characteristics

(V<sub>DD</sub>=5V±10%, V<sub>SS</sub>=0V, f<sub>OSC</sub>=3.579545MHz, Ta=-10 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Low level input voltage	V <sub>IL</sub>		0	—	0.8	V
High level input voltage	V <sub>IH1</sub>	Except for RESET, SS, OSC1	2.0	—	V <sub>DD</sub>	V
	V <sub>IH2</sub>	RESET, SS, OSC1	V <sub>DD</sub> -1	—	V <sub>DD</sub>	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> =2.0mA	—	—	0.45	V
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> =-1.0mA	2.4	—	—	V
Input current	I <sub>ILP1</sub>	V <sub>ILP1</sub> =V <sub>SS</sub> , Input terminal with pull-up	-250	-100	-30	μA
	I <sub>ILL</sub>	V <sub>ILL</sub> =V <sub>SS</sub> , Latch input terminal	-3	0	3	
	I <sub>ILP2</sub>	V <sub>ILP2</sub> =V <sub>SS</sub> , SS	RUN	-125	-50	
STOP			-3	0	3	
Input leakage current	I <sub>LI1</sub>	V <sub>LI1</sub> =V <sub>DD</sub> , Except for SS	-3	0	3	μA
	I <sub>LI2</sub>	SS terminal open	-3	0	3	
Output leakage current (at High-impedance)	I <sub>LOP</sub>	V <sub>LOP</sub> =V <sub>SS</sub> , I/O port with pull-up	-250	-100	-30	μA
	I <sub>LOL</sub>	V <sub>LOL</sub> =V <sub>SS</sub> , I/O port with latch	-3	0	3	
	I <sub>LOH</sub>	V <sub>LOH</sub> =V <sub>DD</sub> , Output terminal	-3	0	3	
Standby supply current	I <sub>DDS</sub>	t <sub>CY</sub> =1μs, Stand-by or stop mode	—	—	20	μA
Operating supply current	I <sub>DDO</sub>	t <sub>CY</sub> =1μs, RUN mode	—	6	20	mA
Data retention voltage	V <sub>DDR</sub>	STOP mode. Without sudden fluctuation of voltage	3.0	—	—	V

### ●AC Characteristics

(V<sub>DD</sub>=5V±10%, V<sub>SS</sub>=0V, f<sub>OSC</sub>=3.579545MHz, Ta=-10 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Cycle time	t <sub>CY</sub>		—	1.117	—	μs
ALE pulse width	t <sub>LL</sub>		200	—	—	ns
Address set up time	t <sub>AL</sub>		100	—	—	ns
Address hold time	t <sub>LA</sub>		50	—	—	ns
PSEN pulse width	t <sub>CC1</sub>		300	—	—	ns
RD pulse width	t <sub>CC2</sub>		300	—	—	ns
WR pulse width	t <sub>CC3</sub>		300	—	—	ns
Data-in delay time	t <sub>RD</sub>		—	—	150	ns
Read data hold time	t <sub>DR</sub>		0	—	100	ns



Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Write data set up time	$t_{DW}$		250	—	—	ns
Write data hold time	$t_{WD}$		5	—	—	ns
WR delay time	$t_{AW}$		200	—	—	ns
Data-in delay time	$t_{AD}$		—	—	450	ns

Note 1 : The load capacitance of the control pins (ALE,  $\overline{PSEN}$ ,  $\overline{RD}$  and  $\overline{WR}$ ) is 80pF.

Note 2 : The load capacitance of port P0 is 150pF.

Note 3 : AC data measuring conditions

Input :  $V_{IH}=2.4V$ ,  $V_{IL}=0.6V$

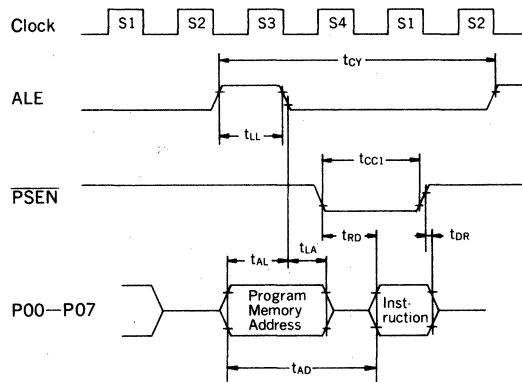
Timing check voltage : Input..... $V_{IH}=2.2V$ ,  $V_{IL}=0.8V$

Output..... $V_{OH}=2.2V$ ,  $V_{OL}=0.8V$

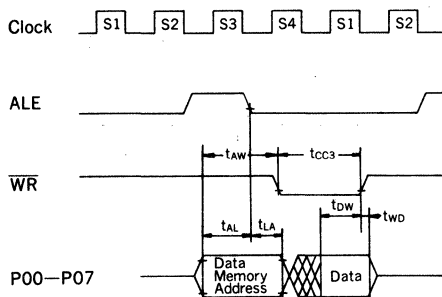
Output load capacitance : Control pins.....80pF  
Data pins.....150pF

### ●Timing Chart

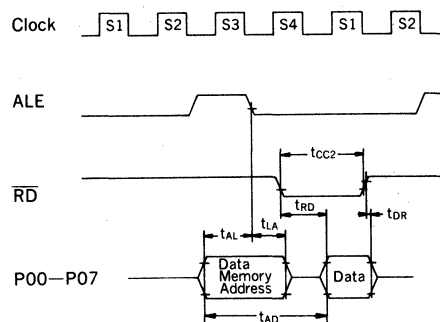
#### ○ External Program Memory Fetch Cycle



#### ○ External Data Memory Write Cycle

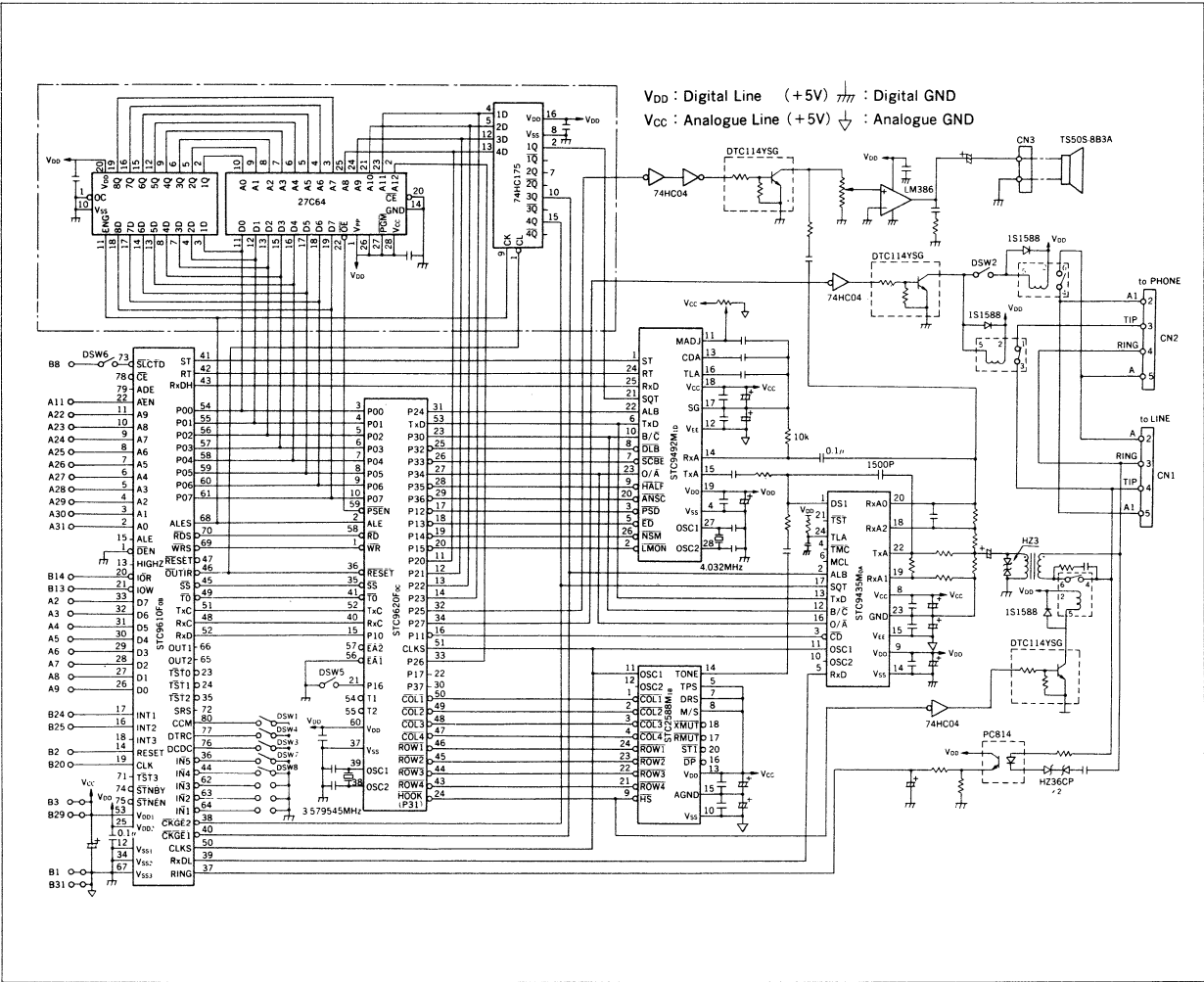


#### ○ External Data Memory Read Cycle



### EXAMPLE OF APPLICATIONS

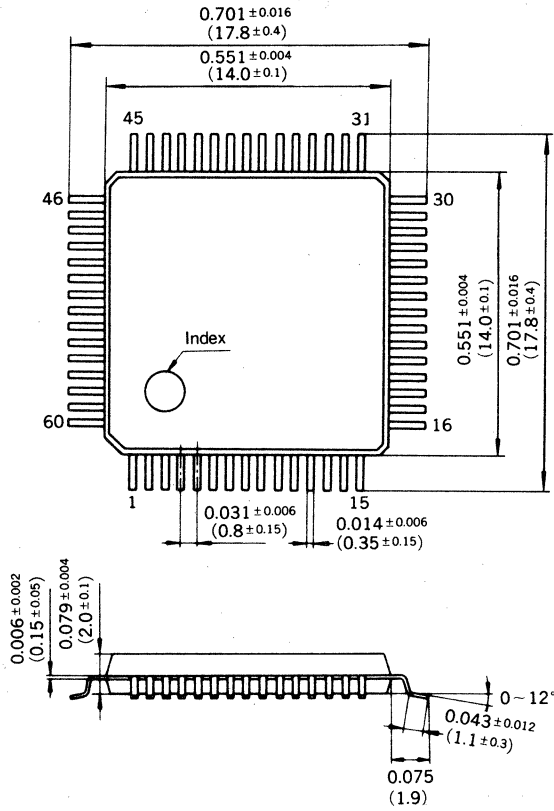
The configuration shown below is a system bus interface based intelligent modem which uses an STC9620F08 in combination with four chips : STC9610F08, STC9492C0D (STC9492M1D), STC9435C0A (STC9435M0A) and STC2588C1B (STC2588M1B).



■ PACKAGE DIMENSIONS

F60-2

60-pin QFP



unit : inch  
(mm)

# STC9630C<sub>0A</sub>/M<sub>0A</sub>

## CMOS ASYNC-SYNC CONVERTER

- Compatible with Bell 212A/CCITT V.22
- Selectable Character Length 8/9/10/11 Bits
- Low Supply Current

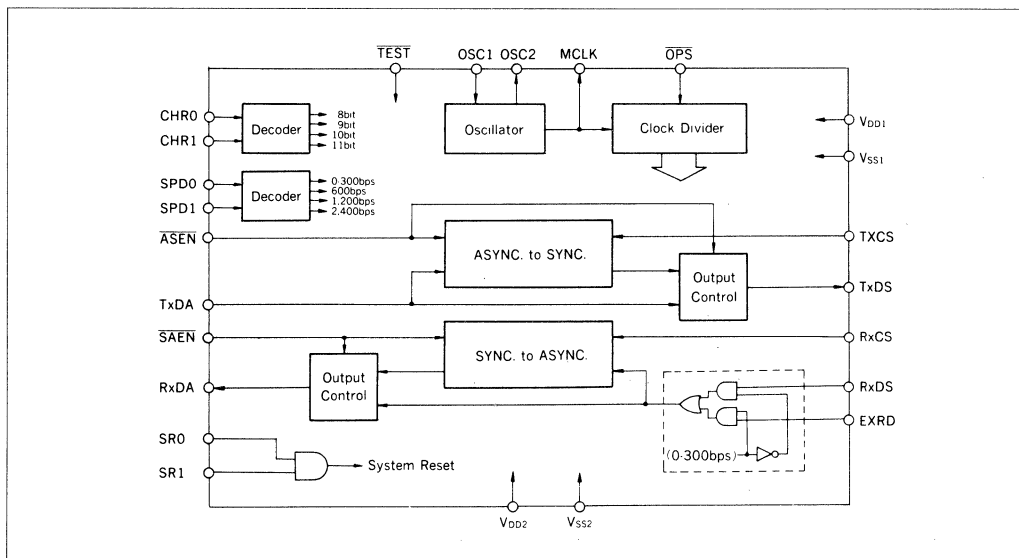
### DESCRIPTION

The STC9630C<sub>0A</sub>/M<sub>0A</sub> LSI converts data for serial transfer between a data circuit terminating equipment (DCE) and a data terminal equipment (DTE) in either transparent mode or async/sync conversion mode.

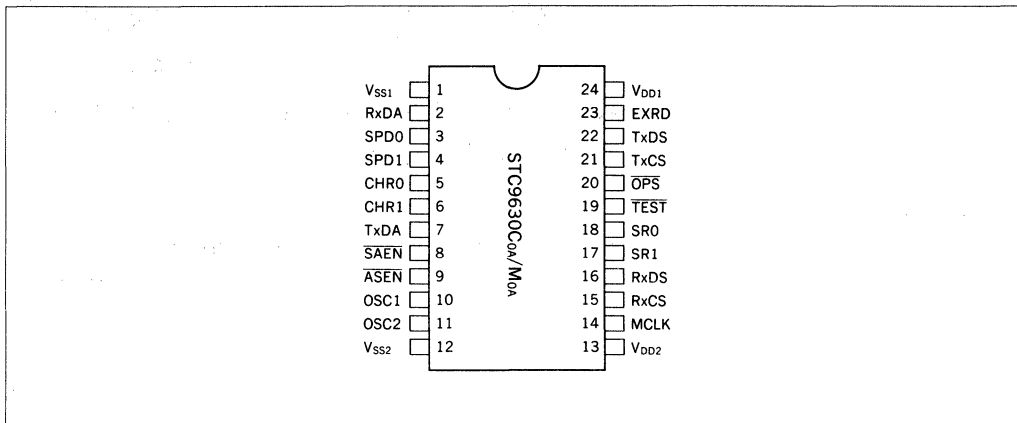
### FEATURES

- Full duplex data transfer (compatible with Bell 212A and CCITT V.22)
- Async/Sync, Sync/Async conversion
- Character length : 8/9/10/11 bits
- Built-in crystal oscillation circuit .....4.032MHz (X'tal, R<sub>F</sub>, C<sub>G</sub>, C<sub>D</sub> externally connected)
- Low supply current .....Operation : 5mA (Typ)  
Stand-by : 1 $\mu$ A (Max)
- Digital I/O level .....TTL compatible
- Single power supply .....5V
- Package .....24-pin DIP (plastic)/24-pin SOP (plastic)

### BLOCK DIAGRAM



■ PIN CONFIGURATION (This also applied to DIP and SOP.)



■ PIN DESCRIPTION

Pin Name	Pin No.	I/O	Functions
V <sub>SS1</sub>	1	—	— power (GND)
RxDA	2	O	Receive start-stop sync data output (to DTE)
SPD0	3	I*	Data speed selection Speed 0-300 600 1,200 2,400 (bps) SPD0 0 1 0 1 SPD1 0 0 1 1
SPD1	4	I*	
CHR0	5	I*	Word length selection Character length 8 9 10 11 (bits) CHR0 0 1 0 1 CHR1 0 0 1 1
CHR1	6	I*	
TxDA	7	I*	Transmit start-stop sync data input (from DTE)
SAEN	8	I*	Sync → Async conversion enable
ASEN	9	I*	Async → Sync conversion enable
OSC1	10	I	Oscillation pins (4.032MHz X'tal, R <sub>F</sub> , C <sub>G</sub> , C <sub>D</sub> externally connected)
OSC2	11	O	
V <sub>SS2</sub>	12	—	— power (GND)
V <sub>DD2</sub>	13	—	+ power (+5V)
MCLK	14	O	4.032MHz output pin
RxCS	15	I*	Receive sync clock input (from DCE)
RxDs	16	I*	Receive sync data input (from DCE)
SR1	17	I*	System reset (When using STC9492, connect this pin to SQT.)
SR0	18	I*	System reset (When using STC9492, connect this pin to ALB.)
TEST	19	I*	LSI test pin (normally set at NC)
OPS	20	I*	Option speed selection Basic..... 1 Extended..... 0
TxCS	21	I*	Transmit sync clock input (from DTE)
TxDs	22	O	Transmit sync data output (to DCE)
EXRD	23	I*	Nonsimultaneous data input 0-300 bps
V <sub>DD1</sub>	24	—	+ power (+5V)

Note) The input pin (I\*) contains a pull-up resistor.

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.3 to 7.0	V
Input voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> + 0.3	V
Output voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> + 0.3	V
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

## ■ RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.75	5.00	5.25	V
Operating temperature	T <sub>opr</sub>		0	—	70	°C

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

(V<sub>DD</sub> = 5.0V, V<sub>SS</sub> = 0V, T<sub>a</sub> = 25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Operating current	I <sub>DDO</sub>	Operating (C <sub>L</sub> ≤ 20pF)	3	5	10	mA
	I <sub>DDS</sub>	Stand-by except OSC1, OSC2	—	—	1	μA
High level input voltage	V <sub>IH</sub>	V <sub>DD</sub> = 5.25V	2.0	—	—	V
Low level input voltage	V <sub>IL</sub>	V <sub>DD</sub> = 4.75V	—	—	0.8	V
High level input current	I <sub>IH</sub>	except OSC1	-1	—	1	μA
Low level input current	I <sub>IL</sub>	except OSC1	-50	-12.5	-5	μA
High level output voltage	V <sub>OH</sub>	V <sub>DD</sub> = 4.75V, I <sub>OH</sub> = -6mA	2.4	—	—	V
Low level output voltage	V <sub>OL</sub>	V <sub>DD</sub> = 4.75V, I <sub>OL</sub> = 6mA	—	—	0.4	V

### ● AC Electrical Characteristics

(V<sub>DD</sub> = 5.0V, V<sub>SS</sub> = 0V, T<sub>a</sub> = 25°C, f<sub>osc</sub> = 4.032MHz, SPD0 = Low, SPD1 = High)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
TxDA Baud rate *2	f <sub>TxDA</sub>	A <sub>SEN</sub> = Low, O <sub>PS</sub> = High	1,170 (-2.5%)	1,200	1,212 (+1.0%)	bps
		A <sub>SEN</sub> = Low, O <sub>PS</sub> = Low	1,170 (-2.5%)	1,200	1,227 (+2.3%)	bps
RxDA Baud rate *2	f <sub>RxDA</sub>	A <sub>SEN</sub> = Low, O <sub>PS</sub> = High	—	1,219	—	Hz
		A <sub>SEN</sub> = Low, O <sub>PS</sub> = Low	—	1,219	*1	bps
MCLK Output frequency	f <sub>MCLK</sub>	V <sub>DD</sub> = 5.0V, V <sub>SS</sub> = 0V	—	4.032	—	MHz

\*1 In the option speed mode (O<sub>PS</sub> low), 12.5% (maximum) of stop bits may be deleted to allow an overspeed (+2.3%) on the transmit side.

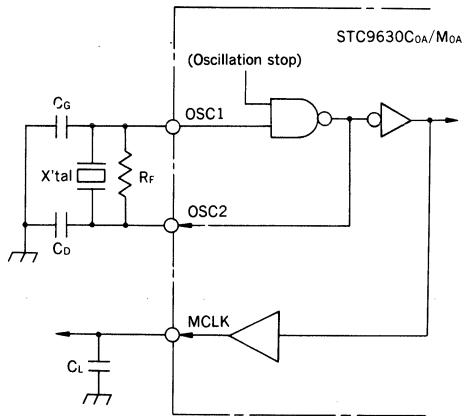
\*2 If the speed is set at 600 bps or 2,400 bps, the transfer rate is one half or twice the listed value.

## FUNCTIONS

### ● Oscillation Circuit

#### ○ Crystal quartz oscillation

A crystal oscillator (4.032MHz), a feedback resistor ( $R_F$ ) and two capacitors ( $C_G$ ,  $C_D$ ) are connected to the oscillation pins (OSC1, OSC2).

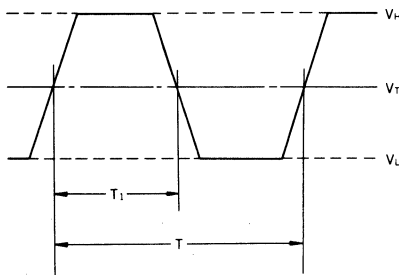


X'tal : 4.032MHz  
 $R_F$  : 470k $\Omega$  (Typ)  
 $C_G$ ,  $C_D$  : 20 to 30pF  
 $C_L$  : 50pF (Max)

When both SR0 and SR1 go high or both SPD0 and SPD1 go low, the oscillation cycle stops and the MCLK pin is fixed to high level.

#### ○ External clock into OSC1

In supplying a 4.032MHz clock pulse from an external circuit to the OSC1 pin, make sure that the MCLK output fulfills the AC characteristics shown in Figure.

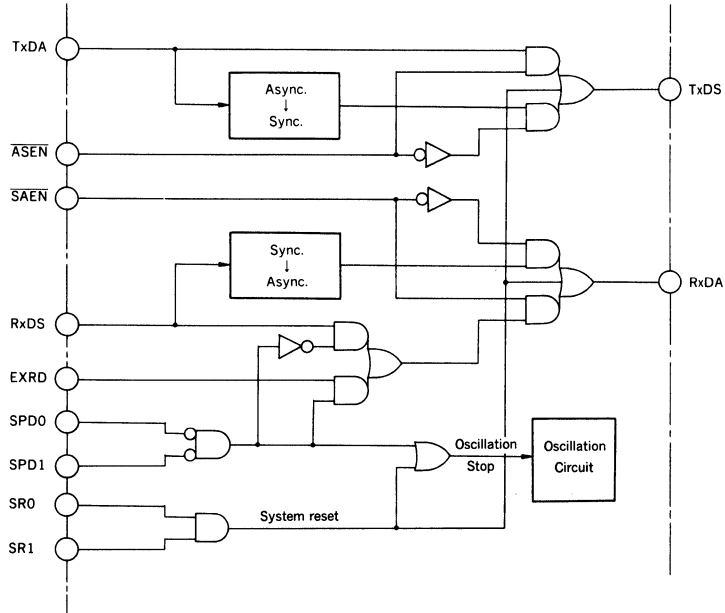


High level input voltage  $V_H \geq V_{DD} - 1.0V$   
 Low level input voltage  $V_L \leq V_{SS} + 1.0V$   
 Input frequency  $1/T = 4.032MHz \pm 0.01\%$   
 Clock duty  $T_1/T = 50 \pm 15\%$

(at  $V_T = \frac{1}{2} V_{DD}$ )

## I/O CONTROL FUNCTION

The STC9630C<sub>0A</sub>/M<sub>0A</sub> I/O control circuit provides the transmit/receive circuits with the output data listed in the table below with each I/O pin set as shown in the figure below.



Operating mode	Terminal set						Output data		Oscillator
	SR0	SR1	ASEN	SAEN	SPD0	SPD1	TxDS	RxDA	
System reset	"H"	"H"	*1	*1	*1	*1	"H"	"H"	Stop
Unlocked data transfer	*2	*2	*1	*1	"L"	"L"	TxDA	EXRD	
Sync data transfer	*2	*2	"H"	"H"	*3	*3	TxDA	RxDS	Operation
Async data transfer	*2	*2	"L"	"L"	*3	*3	A→S	S→A	

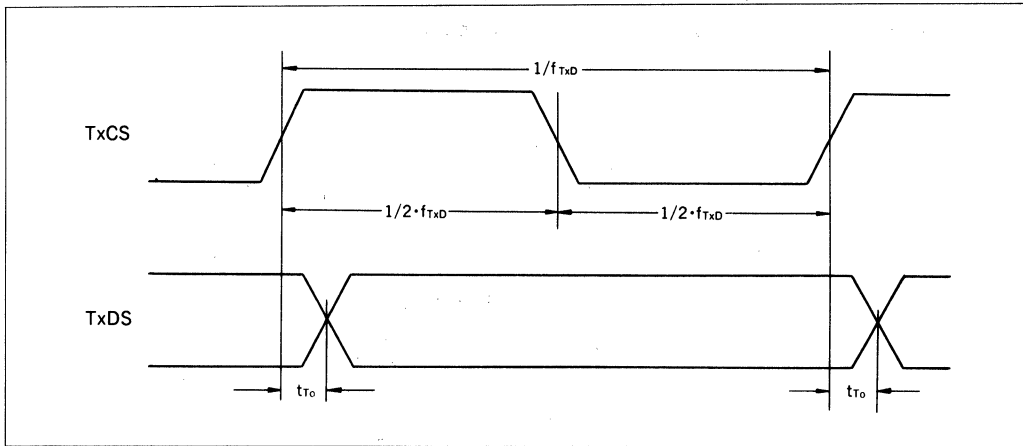
- \*1 Don't care
- \*2 Other than (H, H)
- \*3 Other than (L, L)

Note) ASEN and SAEN can be individually controlled.

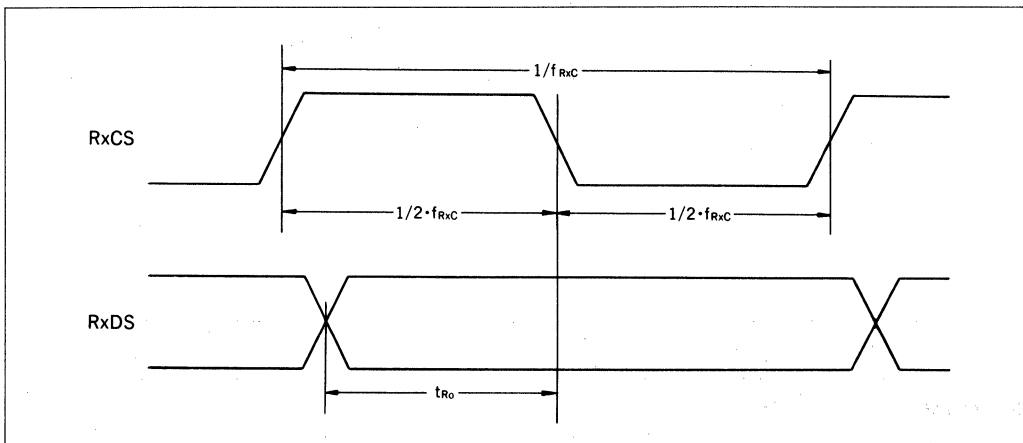


■TIMING CHART

●Transmit Sync Data Timing Chart



●Receive Sync Data Timing Chart

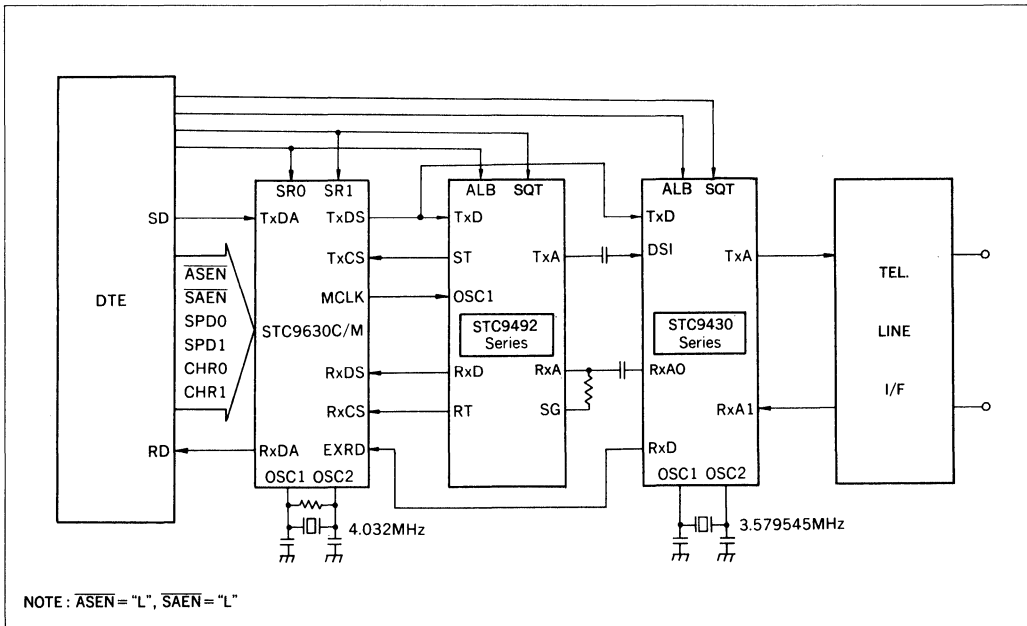


( $V_{DD}=4.75V$ ,  $T_a=25^{\circ}C$ )

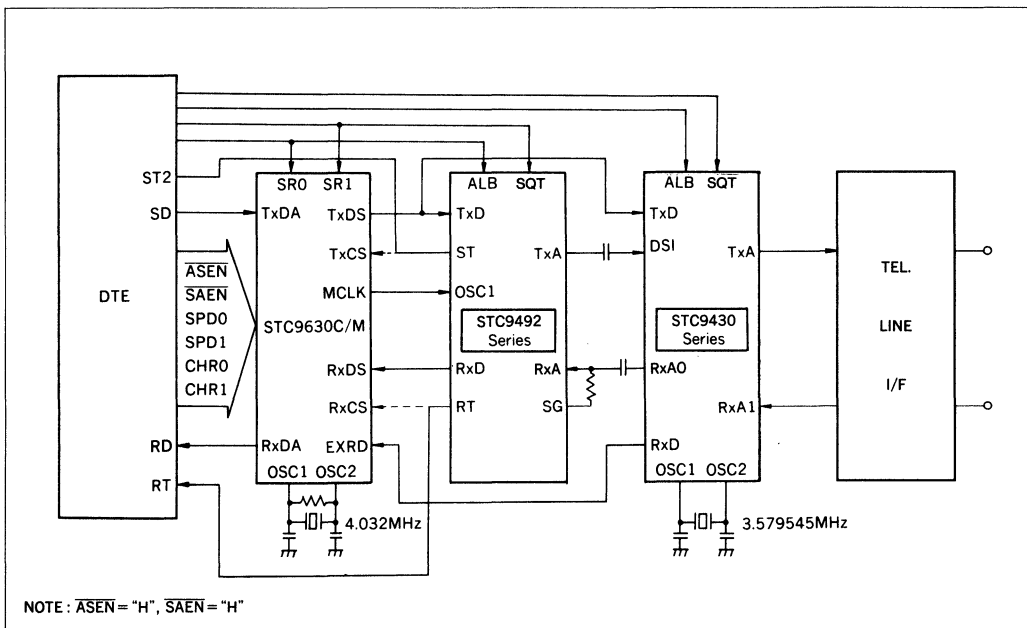
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Transmit data delay time	$t_{TO}$	Sync data enable	—	—	100	ns
Receive data set up time	$t_{RO}$	Sync data enable	50	—	—	ns

■EXAMPLE OF APPLICATIONS

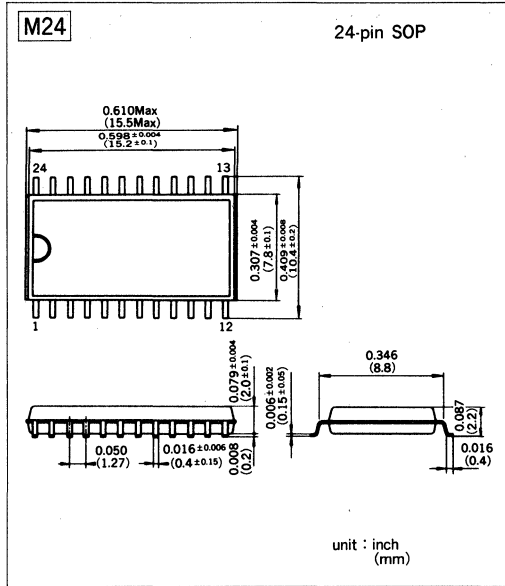
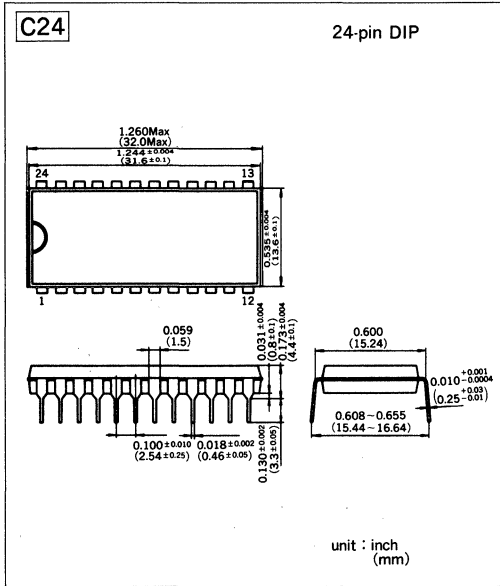
●Transfer of data between sync modem and async terminal



●Transfer of data between sync modem and async terminal



■ PACKAGE DIMENSIONS



# STC9120C/M

## CMOS 1,200 bps MSK MODEM

- Minimum External Parts Required
- 1200 bps for Full-duplex or Half-duplex System
- Low Supply Current
- On-chip Carrier Detector

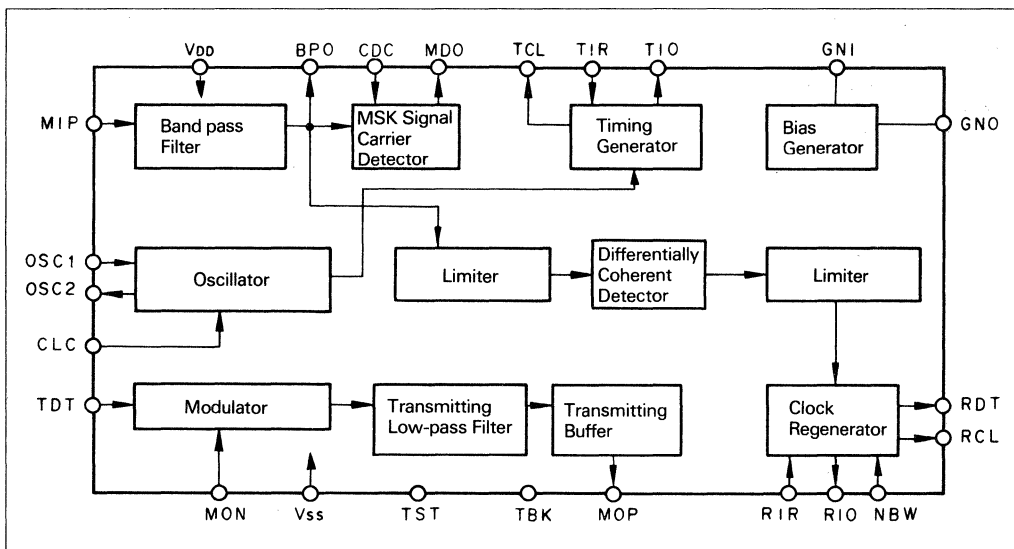
### ■ DESCRIPTION

The STC9120C/M is a single chip CMOS 1200 bps MSK MODEM for full-duplex or half-duplex radio communication equipment. The modulator provides a low-distortion sinusoidal output and a sync clock output. A receiving low-pass filter, a differentially coherent detector and a clock regenerator makes up the demodulator incorporating a MSK signal carrier detector, the STC9120C/M offers a high-performance MSK MODEM with a minimum of external parts.

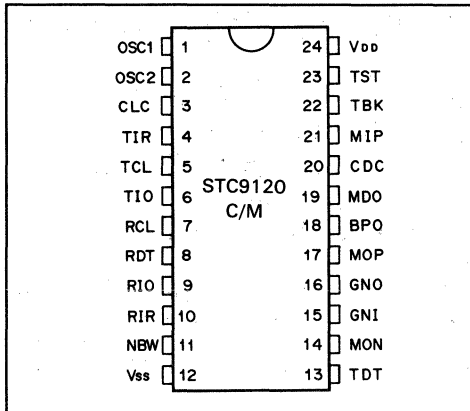
### ■ FEATURES

- 1200 bps full-duplex/half-duplex MSK MODEM
- Low supply current
- 5.5296 MHz crystal oscillator, or external 5.5296 MHz clock input
- Minimized external parts
- Built-in MSK signal carrier detect circuit
- TTL compatible input/output (except for terminals OSC1, OSC2, CLC, TBK and TST)
- Transmitting/receiving filter based on SCF (Switched Capacitor Filter) technology
- Little group delay distortion at the pass band
- Single power supply (+5V)
- Package.... STC9120C 24-pin DIP(plastic)  
STC9120M 24-pin SOP(plastic)

### ■ BLOCK DIAGRAM



## ■ PIN CONFIGURATION (common to DIP and SOP)



## ■ PIN DESCRIPTION

Pin name	Pin No.	Functions
OSC1	1	5.5296 MHz (CLC = "L") or 2.7648 MHz (CLC = "H") crystal oscillator circuit or external clock input terminal.
OSC2	2	Crystal oscillator output terminal
CLC*1	3	Input terminal for oscillator frequency division control (with pull-down resistor)
TIR*2	4	Input terminal that resets the 1-bit data transmit interruption flip-flop (without pull-down resistor)
TCL	5	Transmit data sync clock signal output terminal
TIO	6	Output terminal for the 1-bit data transmit interruption flip-flop
RCL	7	Output terminal of sync clock signals regenerated from demodulated data

RDT	8	Output terminal of demodulated receive data
RIO	9	Output terminal for the 1-bit data receive interruption flip-flop
RIR*2	10	Input terminal that resets the 1-bit data receive interruption flip-flop (without pull-down resistor)
NBW*2	11	Input terminal that controls selection of DPLL circuit lock-in range (narrow/wide) (without pull-down resistor) Narrow..... high level Wide..... low level
Vss	12	Supply voltage (0V)
TDT*2	13	Input terminal of NRZ signals to be transmitted (without pull-down resistor)
MON*2	14	Input terminal for MSK signal transmit control (without pull-down resistor)
GNI	15	Input terminal of intermediate point reference voltage for power supply
GNO	16	Output terminal of intermediate point reference voltage for built-in operational amplifier
MOP	17	MSK signal output terminal
BPO	18	Receiving band low-pass filter output monitor terminal (normally non-connected)
MDO	19	MSK signal carrier detector output terminal
CDC	20	Input terminal for application of offset voltage to set MSK signal carrier detection threshold value (with C-R connected externally)
MIP	21	MSK signal input terminal
TBK*1	22	Function test terminal (normally non-connected; with pull-down resistor)
TST*1	23	Function test terminal (normally non-connected; with pull-down resistor)
VDD	24	Supply voltage (+5V)

\*1 These input terminals are pulled down with a resistor, typically 500 k $\Omega$ . It is recommended that they are directly pulled down to VDD' not left open, when they are not used, regarding to noise effect.

\*2 These input terminals are input gate floating type. When not used, they must be directly pulled down to Vss' not left open.

## ■ ABSOLUTE MAXIMUM RATINGS

(Vss = 0V, Ta = 25°C)

Parameter	Symbol	Ratings	Unit
Supply voltage	VDD	-0.3 to 8.0	V
Input voltage*	Vi	-0.3 to VDD +0.3	V
Output voltage	Vo	-0.3 to VDD +0.3	V
Power dissipation	Pd (Max)	500	mW
Operating temperature	Topr	-25 to 70	°C
Storage temperature	Tstg	-65 to 150	°C
Soldering temperature and time	Tsol	260°C, 10 s (at lead)	-

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Characteristics

(VDD = 5.0V, VSS = 0V and Ta = 25°C unless otherwise specified)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit	
Supply voltage	VDD		4.5	5.0	5.5	V	
Supply current	IDD	fosc = 5.5296 MHz	-	6	12	mA	
"L" level input voltage	VIL1	OSC1	VSS	-	VSS + 0.3	V	
"H" level input voltage	VIH1		VDD - 0.3	-	VDD	V	
Input frequency	FI1		-	5.5296	-	MHz	
Input current	Ii1	VIH1 = 5V	-	0.5	-	μA	
"L" level input voltage	VIL2	CLC, TBK, TST	VSS	-	VSS + 0.3	V	
"H" level input voltage	VIH2		VDD - 0.3	-	VDD	V	
Pull-down resistance	R12		200	500	1250	kΩ	
"L" level input voltage	VIL3	NBW, RIR*3, RIE*3 TDT,	0	-	0.8	V	
"H" level input voltage	VIH3	MON	2.4	-	VDD	V	
Input impedance	R14	MIP	70	120	190	kΩ	
Input signal voltage	V14	Sinewave input	-	1.0	2.0*4	VP-P	
"L" level output voltage	VOL1	RCL, RDT RIO, MDO	IoL1 = 2.6mA	VSS	-	0.5	V
"H" level output voltage	VOH1	TCL, TIO	IoH1 = -0.2 mA	4.6	-	VDD	V
Mark output voltage	VOM	Load resistance: Min 10 kΩ		0.9	1.0	1.1	VP-P
Space signal output voltage	VOS				0.9	1.0	1.1

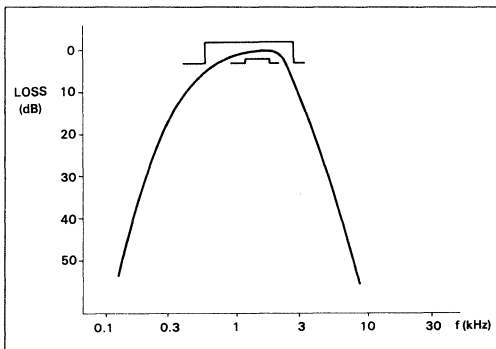
\*3 The reset pulse width must be at least 1 μs.

\*4 The maximum input level should be adjusted not so as to happen a malfunction.

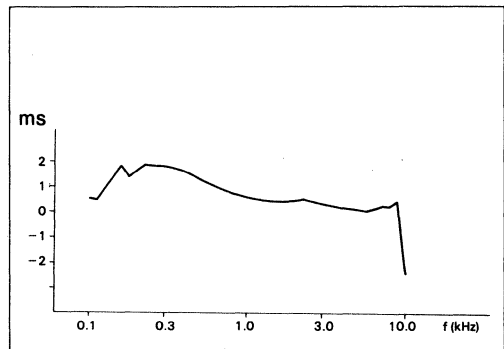
### ● Filter Specifications

(VDD = 5.0V, VSS = 0V and Ta = 25°C unless otherwise specified)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
3 dB band width (Low Band)	FCL1	Receiving band-pass filter	600	700	800	Hz
3 dB band width (High Band)	FCH1	Butterworth	2000	2400	2800	Hz
Insertion loss	LB1	10 order	-2	0	2	dB
3 dB band width (High Band)	Fc2	Transmitting low band-pass	4250	5000	5750	Hz
Insertion loss	LB2	filter Butterworth 5 order	-2	0	2	dB
3 dB band width (High Band)	Fc3	Receiving low band-pass filter	1000	1200	1400	Hz
Insertion loss	LB3	Butterworth 3 order	-2	0	2	dB



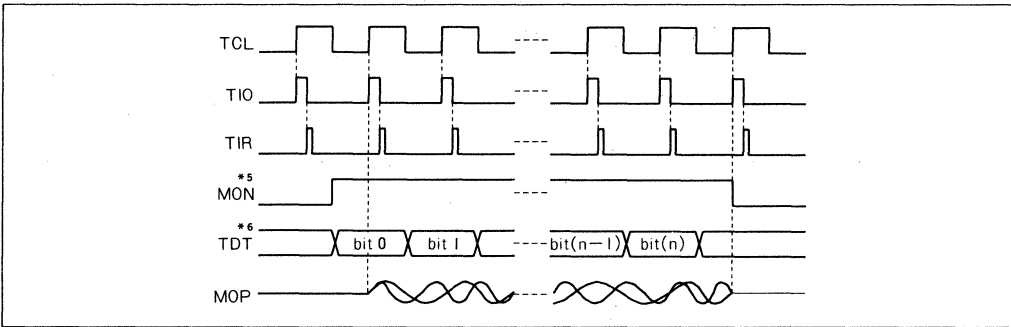
Band Pass Filter Frequency Characteristics



Band Pass Filter Group Delay Characteristics

## ■ DATA INPUT/OUTPUT TIMING CHART

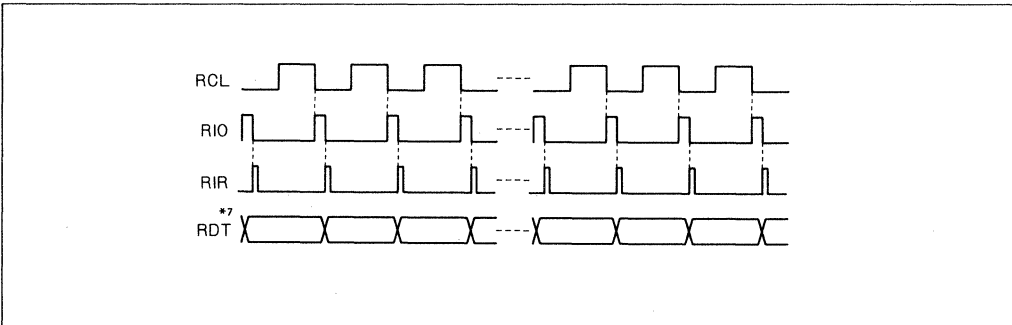
### ● Data Transmit Timing Chart



\*5 When data transmission starts, MON must go to "H" level within about 833  $\mu$ s following the leading edge of the TCL. When the data transmission ends, MON must go to "L" level at the leading edge of the next TCL following the transmission of the last bit of MOP.

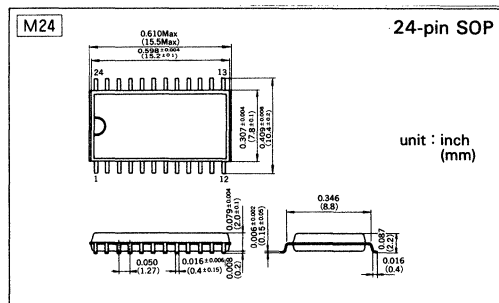
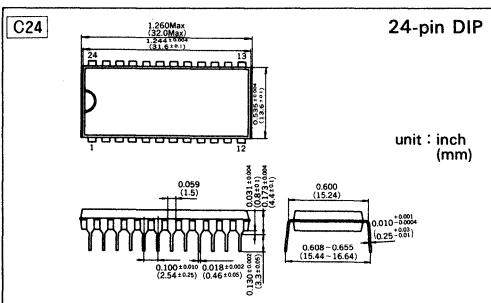
\*6 For TDT, data must be set within about 833  $\mu$ s after the occurrence of an interrupt.

### ● Data Receive Timing Chart



\*7 RDT must be read within about 833  $\mu$ s following the leading edge of RCL.

## ■ PACKAGE DIMENSIONS



# STC2530C Series

## CMOS TONE/PULSE DIALER WITH LCD DRIVER

Preliminary

- DTMF/Pulse Output Switch
- 10 Digit LCD Driver
- Ten 18-digit Repertory Memories and 24-digit Redial Memory

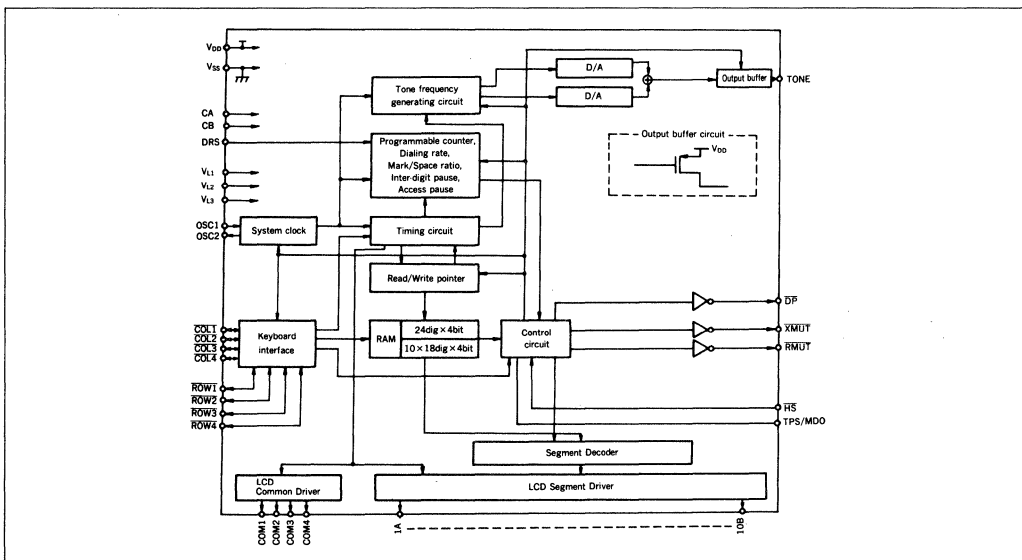
### DESCRIPTION

The STC2530C series is CMOS LSI which is provided with a memory and LCD display driver for telephone numbers, and can selectively output either dual tone multi-frequency (DTMF) signals or a dialing pulse (DP) train. The LSI contains the DA conversion system used in a conventional tone dialer by connecting the minimum necessary interface circuit, the dialing pulse can also drive a telephone line.

### FEATURES

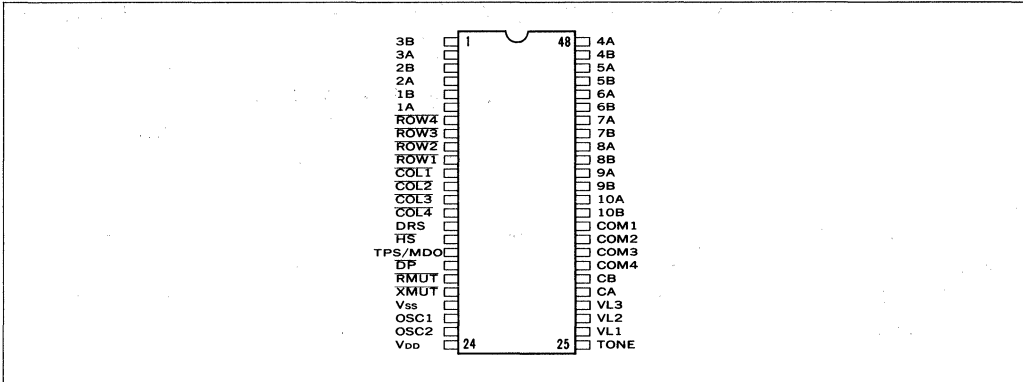
- Low-voltage operation and low power dissipation due to CMOS process.
- A built-in 10 digit LCD drivers for telephone numbers. (V-3V, 1/4duty)
- A built-in Ten 18-digit repertory memories and 24-digit redial memory.
- A built-in DA conversion system makes possible a DTMF signal.
- 0.6sec Hooking (Flash) can be accessed directly by Flash key.
- This LSI can be connected to a standard 2 of 8 keyboard.
- The built-in signal generator requires 3.58MHz TV crystal oscillator.
- Package.....48 pin DIP (plastic)

### BLOCK DIAGRAM





## ■ PIN CONFIGURATION



## ■ STC2530C Series

Type	Write to repartory memory	Tone/pulse output selection	Dial pulse mark/space
STC2531C <sub>0A</sub>	OFF-Hook	Key	33.3/66.6
STC2531C <sub>0B</sub>			40/60
STC2532C <sub>0A</sub>	ON-Hook	Key	33.3/66.6
STC2532C <sub>0B</sub>			40/60
STC2533C <sub>0A</sub>	OFF-Hook	External pin	33.3/66.6
STC2533C <sub>0B</sub>			40/60
STC2534C <sub>0A</sub>	ON-Hook	External pin	33.3/66.6
STC2534C <sub>0B</sub>			40/60

## ■ PIN DESCRIPTION

Pin Name	Pin No.	Function
ROW1 to ROW4	7 to 10	[Scanning input/output of matrix keyboard]
COL1 to COL4	11 to 14	
TPS/MDO	17	[DTMF/DP mode select input] / [DTMF/DP mode signal output]
DRS	15	[Pulse rate select input in DP mode]
HS	16	[Hook switch]
V <sub>SS</sub>	21	[Power supply terminal (-)]
OSC1	22	[3.579545MHz crystal oscillator terminal]
OSC2	23	
V <sub>DD</sub>	24	[Power supply terminal (+)]
TONE	25	[DTMF signal output]
DP	18	[Dialing pulse output]
RMUT	19	[Receiver mute output]
XMUT	20	[Transmitter mute output]
VL1	26	[Doubler & Tripler capacitor]
VL2	27	
VL3	28	
CA	29	
CB	30	
COM1 to COM4	31 to 34	[Common Driver output]
1A to 10A 1B to 10B	1 to 6 35 to 48	[Segment Driver output]

## ■ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Power supply voltage	V <sub>DD</sub>	-0.3 to 7.5	V
Input voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Operating temperature	T <sub>opr</sub>	-20 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

## ■ELECTRICAL CHARACTERISTICS

### ●DC Characteristics

(V<sub>SS</sub>=0V, T<sub>a</sub>=25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Operating voltage	V <sub>DD</sub>	DP mode	1.5	—	6.0	V
		DTMF mode	2.5	—	6.0	
Data retention voltage	V <sub>DDR</sub>	Stand-by mode	1.0	—	6.0	V
Average operating current	I <sub>DDA</sub>	V <sub>DD</sub> =3.0V, T <sub>a</sub> =25°C Key input stand-by status	—	—	200	μA
		H <sub>S</sub> =V <sub>SS</sub> DP, TONE, RMUT and XMUT not loaded In DP mode dial pulse being output	—	—	400	μA
		In DTMF mode DTMF signal being output	—	—	1.5	mA
LCD operating voltage	V <sub>L2</sub>	V <sub>L1</sub> >V <sub>L2</sub> >V <sub>L3</sub>	—	V <sub>DD</sub> -2×V <sub>L1</sub>	—	V
	V <sub>L3</sub>		—	V <sub>DD</sub> -3×V <sub>L1</sub>	—	

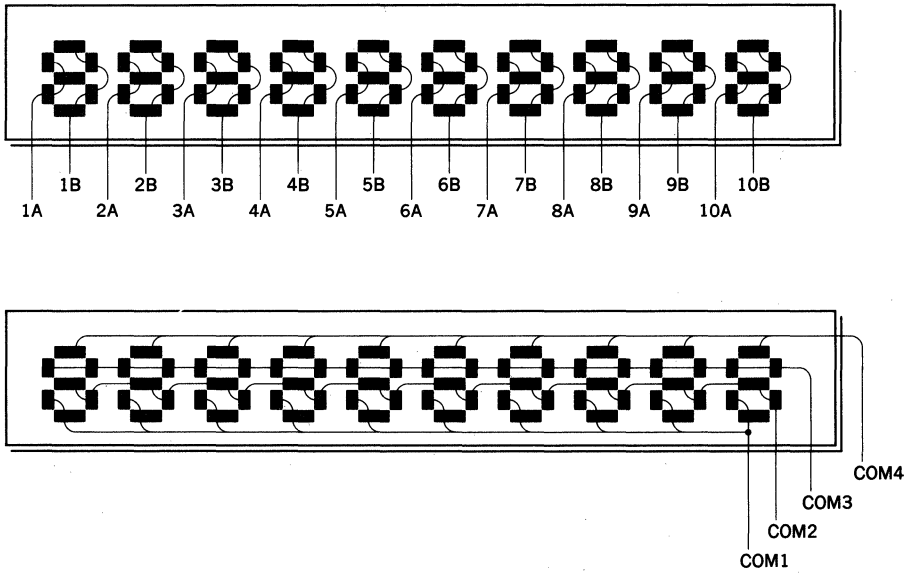
### ●AC Characteristics

(V<sub>SS</sub>=0V, T<sub>a</sub>=25°C, f<sub>osc</sub>=3.579545MHz)

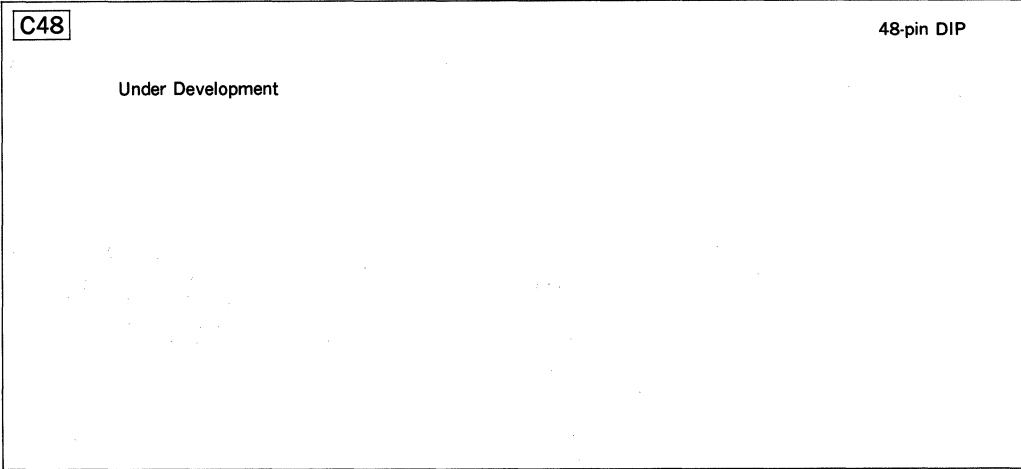
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Dial pulse rate	—	DRS=V <sub>DD</sub>	—	19.42	—	pps
	—	DRS=V <sub>SS</sub>	—	9.71	—	
Inter digit pause	t <sub>IDP1</sub>	DP mode	Dial rate =19.42pps	—	463.4	ms
			Dial rate =9.71pps	—	823.9 (617.9)*	
	t <sub>IDP2</sub>	DTMF mode auto dialing	—	—	112.9 (61.4)*	
DTMF make time	t <sub>TM</sub>	DTMF mode auto dialing	93.1	—	—	ms
Oscillator frequency	f <sub>osc</sub>		—	3.579545	—	MHz
Tone output voltage	V <sub>tone</sub>	COL	V <sub>DD</sub> =2.5V to 6.0V	—	-11.7	dBm
		ROW		—	-14.2	
Tone distortion	%DIS	V <sub>DD</sub> =3.5V	—	—	10	%
Hooking (flash)	t <sub>HK</sub>		—	617.5 (82.0)*	—	ms

Note: \*Mask option

■ LCD PATTERN LAYOUT



■ PACKAGE DIMENSIONS



# STC2560C

## CMOS PULSE DIALER

- Low Voltage Operation (Min 1.25V)
- 20-digit Memory for Redial
- Pin Compatible to AMI S2560A

### DESCRIPTION

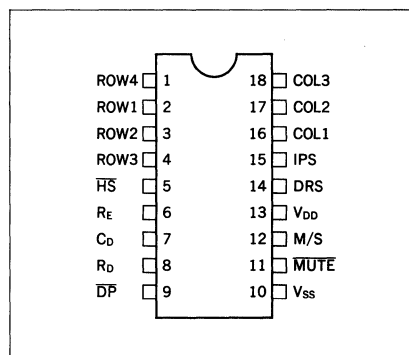
The STC2560C Pulse Dialer is a CMOS IC that converts push-button inputs to a series of pulses suitable for telephone dialing. It requires no independent external power supply but can be driven on the power supplied from telephone lines.

The STC2560C has two output terminals: one for the transmission of dial pulses and the other for providing signals to mute the receiver during the dial pulsing.

### FEATURES

- Directly operation from the telephone lines
- Low power CMOS process. (1.25V to 3.5V)
- Inexpensive RC oscillator built-in
- Mark/space ratio selectable
- Dial rate selectable
- 20-digit memory for Redial by "#" key

### PIN CONFIGURATION



### PIN DESCRIPTION

Pin Name	Pin No.	Functions									
Keyboard ROW1 to ROW4 COL1 to COL3	1 to 4 16 to 18	4×3 matrix input terminals on keyboard. Selected depending on whether ROW and COL reach V <sub>DD</sub> or connect with each other. Input is detected through chattering killer. The keyboard scan begins when a key is pressed and starts the oscillator.									
HS (Hook Switch)	5	Input terminal which detects that the telephone set has become active when the handset is hooked off. "OFF-HOOK" corresponds to V <sub>SS</sub> condition.									
R <sub>E</sub> , C <sub>D</sub> , R <sub>D</sub>	6 to 8	Terminals for oscillation.									
DP (Dial Pulse Out)	9	Dial pulse output terminal									
V <sub>DD</sub> (Power Supply) V <sub>SS</sub> (Power Supply)	13 10	Power terminals. The device is designed to operate from 1.25V to 3.5V									
MUTE (Mute Out)	11	Output terminal to prevent handset noise from entering the line during dialing.									
M/S (Mark/Space)	12	Terminal for selecting a mark/space ratio. <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th>Input Logic Level</th> <th>Mark</th> <th>Space</th> </tr> </thead> <tbody> <tr> <td>V<sub>DD</sub></td> <td>40</td> <td>60</td> </tr> <tr> <td>V<sub>SS</sub></td> <td>100/3</td> <td>200/3</td> </tr> </tbody> </table>	Input Logic Level	Mark	Space	V <sub>DD</sub>	40	60	V <sub>SS</sub>	100/3	200/3
Input Logic Level	Mark	Space									
V <sub>DD</sub>	40	60									
V <sub>SS</sub>	100/3	200/3									
DRS (Dial Rate Select)	14	Terminal for selecting a dial pulse rate. <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th>Input Logic Level</th> <th>Dial Pulse Rate</th> </tr> </thead> <tbody> <tr> <td>V<sub>DD</sub></td> <td>20pps</td> </tr> <tr> <td>V<sub>SS</sub></td> <td>10pps</td> </tr> </tbody> </table>	Input Logic Level	Dial Pulse Rate	V <sub>DD</sub>	20pps	V <sub>SS</sub>	10pps			
Input Logic Level	Dial Pulse Rate										
V <sub>DD</sub>	20pps										
V <sub>SS</sub>	10pps										
IPS (Inter-digit Pause Select)	15	Terminal for selecting a dial pulse pause time between digits. <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th>Input Logic Level</th> <th>DR 20pps</th> <th>DR 10pps</th> </tr> </thead> <tbody> <tr> <td>V<sub>DD</sub></td> <td>470ms</td> <td>620ms</td> </tr> <tr> <td>V<sub>SS</sub></td> <td>400ms</td> <td>800ms</td> </tr> </tbody> </table>	Input Logic Level	DR 20pps	DR 10pps	V <sub>DD</sub>	470ms	620ms	V <sub>SS</sub>	400ms	800ms
Input Logic Level	DR 20pps	DR 10pps									
V <sub>DD</sub>	470ms	620ms									
V <sub>SS</sub>	400ms	800ms									

## ■ ABSOLUTE MAXIMUM RATINGS

( $V_{SS}=0V$ )

Parameter	Symbol	Min	Max	Unit
Supply voltage	$V_{DD}$	-0.3	5.0	V
Operating temperature	$T_{opr}$	-30	70	°C
Storage temperature	$T_{stg}$	-55	125	°C
Input voltage	$V_I$	$V_{SS}-0.3$	$V_{DD}+0.3$	V

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Characteristics

( $V_{SS}=0V, T_a = -30$  to  $70^\circ C$ )

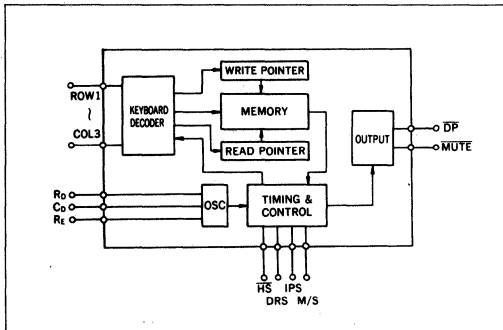
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	$V_{DD}$		1.25	—	3.5	V
Operating current	$I_{OP}$	$V_{OP}=3.5V$	—	—	200	$\mu A$
Data retention voltage	$V_{DR}$		1.0	—	—	V
Data retention current	$I_{DR}$	$V_{DR}=1.0V$	—	—	0.75	$\mu A$
DP sink current	$I_{PL}$	$V_{OP}=3.5V, V_O=0.4V$	1.0	—	—	mA
DP source current	$I_{PH}$	$V_{OP}=3.5V, V_O=2.5V$	1.0	—	—	mA
Mute sink current	$I_{ML}$	$V_{OP}=3.5V, V_O=0.4V$	1.0	—	—	mA
Mute source current	$I_{MH}$	$V_{OP}=3.5V, V_O=2.5V$	1.0	—	—	mA
Logic "1"	$V_H$		80% of $V_{OP}$	—	—	V
Logic "0"	$V_L$		—	—	20% of $V_{OP}$	V

### ● AC Characteristics

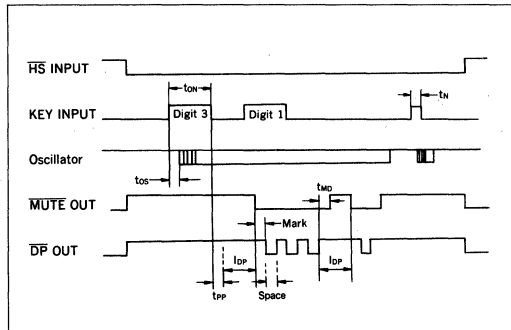
( $f_{osc}=2.4kHz$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Pre-pause	$t_{PP}$		4.58	6.25	7.92	ms
Time for valid key entry	$t_{ON}$		28.34	—	—	ms
Oscillator start up time	$t_{OS}$		—	—	1.0	ms
Mute delay	$t_{MD}$		—	9.17	—	ms
Approval noise pulse width	$t_N$		—	—	13.3	ms

## ■ BLOCK DIAGRAM



## ● Timing Chart



# STC2565C

## CMOS PULSE DIALER

- Low Voltage Operation
- 20-digit Memory for Redial
- Crystal Oscillation (32.768 KHz)

### ■ DESCRIPTION

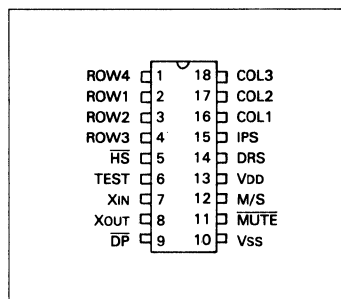
The STC2565C Pulse Dialer is a CMOS IC that converts push-button inputs to a serial pulses of telephone dialing. It requires no independent external power supply but can be driven on the power supplied from telephone lines.

The STC2565C has same functions and pin configuration as the STC2560C except the oscillation circuit.

### ■ FEATURES

- Directly Operation from the telephone lines
- Low power CMOS process. (1.3V to 3.5V)
- High accuracy crystal oscillation (32.768 KHz)
- Mark/space ratio selectable
- Dial rate selectable
- 20-digit memory for Redial by “#” key

### ■ PIN CONFIGURATION



### ■ PIN DESCRIPTION

Pin Name	Pin No.	Functions									
Keyboard ROW1 to ROW4 COL1 to COL3	1to4 16to18	4 x 3 matrix input terminals on keyboard. Selected depending on whether ROW and COL reach VDD or connect with each other. Input chatter – protection circuit is built – in. The keyboard scan begins when a key is pressed and starts the oscillator.									
HS (Hook Switch)	5	Input terminal which detects that the telephone set has become active when the handset is hooked off. "OFF-HOOK" corresponds to VSS condition.									
TEST	6	Test terminal for IC testing (Pull – downed to VSS internally)									
XIN, XOUT	7,8	Terminals for oscillation. (Connect only a crystal between 2 terminals)									
DP (Dial Pulse Out)	9	Dial pulse output terminal									
VDD (Power Supply) VSS (Power Supply)	13 10	Power terminals. The device is designed to operate from 1.3V to 3.5V									
MUTE (Mute Out)	11	Output terminal to prevent handset noise from entering the line during dialing.									
M/S (Mark/Space)	12	Terminal for selecting a mark/space ratio. <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th>Input Logic Level</th> <th>Mark</th> <th>Space</th> </tr> </thead> <tbody> <tr> <td>VDD</td> <td>40</td> <td>60</td> </tr> <tr> <td>VSS</td> <td>100/3</td> <td>200/3</td> </tr> </tbody> </table>	Input Logic Level	Mark	Space	VDD	40	60	VSS	100/3	200/3
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VDD	40	60									
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Input Logic Level	Dial Pulse Rate										
VDD	19.50 pps										
VSS	9.75 pps										
IPS (Inter-digit Pause Select)	15	Terminal for selecting a dial pulse pause time between digits. <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th>Input Logic Level</th> <th>DR 19.50 pps</th> <th>DR 9.75 pps</th> </tr> </thead> <tbody> <tr> <td>VDD</td> <td>410.16 ms</td> <td>820.31 ms</td> </tr> <tr> <td>VSS</td> <td>481.93 ms</td> <td>635.74 ms</td> </tr> </tbody> </table>	Input Logic Level	DR 19.50 pps	DR 9.75 pps	VDD	410.16 ms	820.31 ms	VSS	481.93 ms	635.74 ms
Input Logic Level	DR 19.50 pps	DR 9.75 pps									
VDD	410.16 ms	820.31 ms									
VSS	481.93 ms	635.74 ms									

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Min	Max	Unit
Supply Voltage	V <sub>DD</sub>	-0.3	5.0	V
Operating Temperature	T <sub>opr</sub>	-30	70	°C
Storage Temperature	T <sub>stg</sub>	-55	125	°C
Input Voltage	V <sub>I</sub>	V <sub>SS</sub> -0.3	V <sub>DD</sub> +0.3	V

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Characteristics

(V<sub>SS</sub>=0V, T<sub>a</sub>=-30°C to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply Voltage	V <sub>DD</sub>	T <sub>OP</sub> = 0 to 70°C	1.30	-	3.50	V
		T <sub>OP</sub> = -30 to 0°C	1.50	-	3.50	
Operating Current	I <sub>OP</sub>	V <sub>OP</sub> = 1.8V, T <sub>OP</sub> = 25°C	-	2.00	5.00	μA
Data Retention Voltage	V <sub>DR</sub>		1.00	-	-	V
Data Retention Current	I <sub>DR</sub>	V <sub>OP</sub> = 1.0V	-	-	0.75	μA
DP Sink Current	I <sub>PL</sub>	V <sub>OP</sub> = 3.5V, V <sub>O</sub> = 0.4V	1.00	-	-	mA
DP Source Current	I <sub>PH</sub>	V <sub>OP</sub> = 3.5V, V <sub>O</sub> = 2.5V	1.00	-	-	mA
		V <sub>OP</sub> = 1.5V, V <sub>O</sub> = 1.0V	130	-	-	
Mute Sink Current	I <sub>ML</sub>	V <sub>OP</sub> = 3.5V, V <sub>O</sub> = 0.4V	1.00	-	-	mA
Mute Source Current	I <sub>MH</sub>	V <sub>OP</sub> = 3.5V, V <sub>O</sub> = 2.5V	1.00	-	-	mA
		V <sub>OP</sub> = 1.5V, V <sub>O</sub> = 1.0V	130	-	-	

### ● AC Characteristics

(f<sub>osc</sub> = 32.768 kHz)

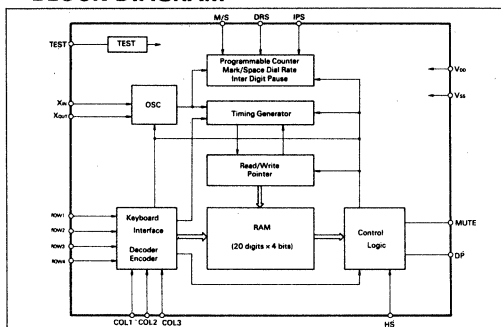
Symbol	Parameter : Conditions	Min	Typ	Max	Unit
t <sub>ON</sub>	Time for Valid Key Entry	29.06	-	-	msec
t <sub>OFF</sub>	Time for Valid Key Down	1.72	-	-	msec
t <sub>PP</sub>	Pre-Pause	4.70	6.41	8.12	msec
t <sub>MD</sub>	Mute Delay	-	9.40	-	msec
t <sub>N</sub>	Approval Noise Pulse Width	-	-	13.64	msec

### ● Oscillation Characteristics

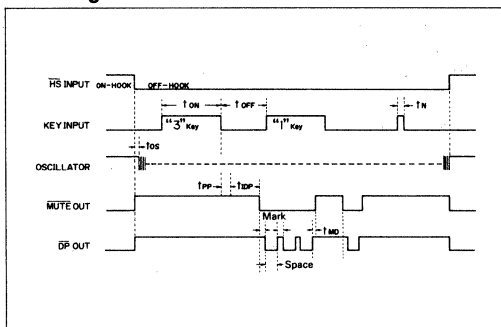
(T<sub>a</sub> = -30°C to 70°C)

Symbol	Parameter : Conditions	Min	Typ	Max	Unit	
f <sub>o</sub>	Frequency of Oscillation	-0.05	32768 Hz	+0.05	%	
V <sub>STA</sub>	Oscillator Start up Voltage	T = -30 to 0°C	-	-	1.50	V
		T = 0 to 70°C	-	-	1.30	
V <sub>STP</sub>	Oscillator Stop Voltage	T = -30 to 0°C	-	-	1.30	V
		T = 0 to 70°C	-	-	1.10	
t <sub>OS</sub>	Oscillator Start up Time C <sub>I</sub> ≤ 40KΩ, T = -20 to 70°C	-	200	600	msec	
Δf/f <sub>o</sub>	1.2V ≤ V <sub>DD</sub> ≤ 3.5V	-	-	100	PPm	

## ■ BLOCK DIAGRAM



## ● Timing Chart



# STC2570C Series

## CMOS REPERTORY DIALER

- Low Voltage Driving, Low Supply Current
- Twenty 18-digit Repertory Memories on Chip
- Last Number Redial (22-digit) Memory on Chip

### DESCRIPTION

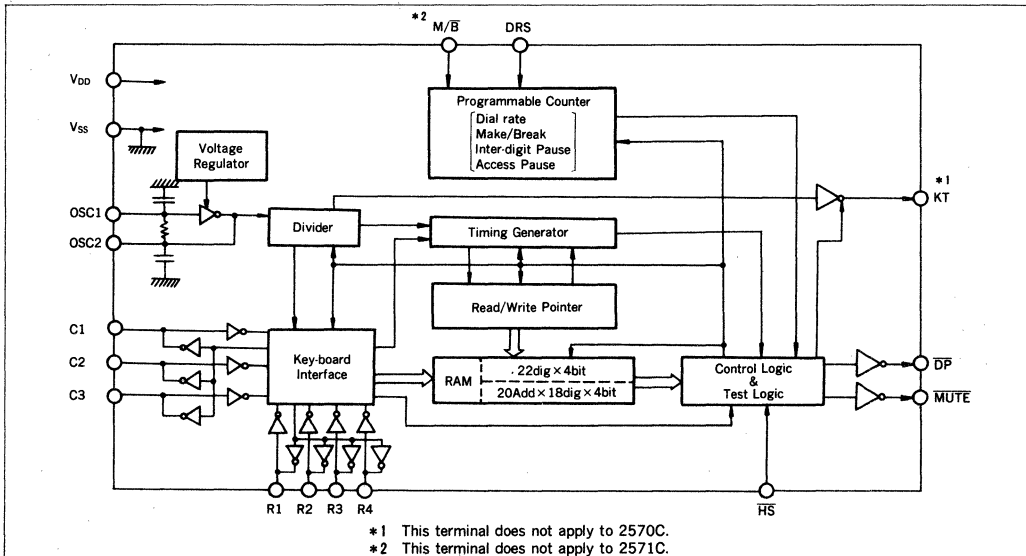
STC2570C Series is CMOS LSI for conversion between push button and dial pulse. It has built-in memories which memorize telephone numbers as abbreviated dial numbers. In addition to the basic movement as repertory dialer, there are some optional mechanisms to be selected by mask conversion for better use.

### FEATURES

- Low voltage CMOS process, Low supply current
- Twenty 18-digit number memories plus last number redial (22-digit) memory on chip
- Selection of dialing rates (10 pps/20 pps)
- Four types of dialing ..... normal dialing, redialing, repertory dialing, and mixed dialing
- Able to inhibit dialing
- Selection of make and break (1/2 or 2/3)\*1
- Built in call disconnect mechanism\*1
- Manual pause for access pause (HALT)\*1
- Auto pause for access pause (3.59 sec)\*2
- Built-in Hooking mechanism (Hooking time 0.5 sec)\*2
- Built-in sound generator for key operation confirmation\*2
- Built-in crystal oscillation circuit, External connection between crystal oscillator (f<sub>0</sub>-32.768kHz) only
- Interface with standard 2 of 7 key board
- Package.....16-pin DIP (plastic)

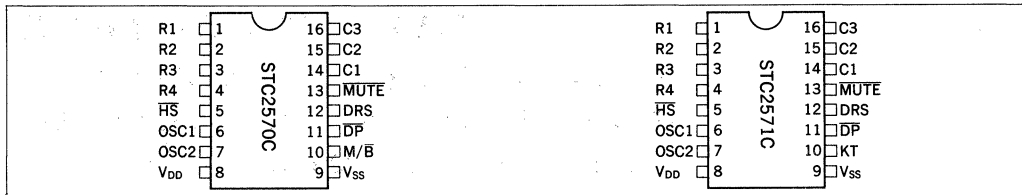
\*1 For STC2570C only  
 \*2 For STC2571C only

### BLOCK DIAGRAM





## PIN CONFIGURATION



## PIN DESCRIPTION

Pin Name	Pin No.	Functions
C1—C3 R1—R4	14—16 1—4	I/O pins for scanning the 2-of-7 matrix keyboard. A key is selected when V <sub>DD</sub> level is applied to both the appropriate COL and ROW pins.
HS	5	Input pin for detecting the status of the hook switch (OFF-hook: V <sub>SS</sub> level). If HS=V <sub>DD</sub> level (ON-hook), only writing to the repertory memory is enabled. If HS=V <sub>SS</sub> level (OFF-hook), a dial pulse is generated when an appropriate key is pressed. Since this input pin is a floating type, it must always be supplied with either V <sub>DD</sub> level or V <sub>SS</sub> level.
OSC1	6	Only a 32.768kHz crystal oscillator is connected between these two pins to form a crystal oscillation circuit (the reference signal source).
OSC2	7	
V <sub>DD</sub>	8	Power pin (+)
V <sub>SS</sub>	9	Power pin (-)
M/B*1	10	Keying confirmation tone output pin. It generates a confirmation tone only when a valid key is pressed (except during a hooking operation). Confirmation tone duration: 26.49msec    Confirmation tone frequency: 910.22Hz During absence of confirmation tone: high impedance output.
KT*2	10	Dial pulse make/break ratio select pin. V <sub>SS</sub> level: 100/3 or 200/3    V <sub>DD</sub> level: 40/60 Since this input pin is a floating type, it must always be supplied with either V <sub>DD</sub> level or V <sub>SS</sub> level.
DP	11	Dial pulse output pin, which generates V <sub>SS</sub> level during an ON-hook or call-disconnect, or during an OFF-hook with no call. It outputs V <sub>DD</sub> level during a make, and V <sub>SS</sub> level during a break.
DRS	12	Dial pulse rate select pin. V <sub>SS</sub> level: 10pps (9.752pps) V <sub>DD</sub> level: 20pps (19.505pps) Since this pin is a floating type, it must always be supplied with either V <sub>DD</sub> level or V <sub>SS</sub> level. The inter-digit pause is fixed for each dial rate: IDP=615.2msec at DR=10pps IDP=461.4msec at DR=20pps
MUTE	13	Mute output pin, which generates V <sub>SS</sub> level during an ON-hook or call-disconnect and V <sub>DD</sub> level during an OFF-hook with no call. It outputs V <sub>SS</sub> level while dial pulses are being sent. (Not intermittent between digits)

\*1 For STC2570C only

\*2 For STC2571C only

## STC2570C SERIES

Series Name	Functions
STC2570C <sub>0A</sub>	<ul style="list-style-type: none"> <li>• Make/break (1/2 or 2/3) selectable</li> <li>• On-chip call disconnect function</li> <li>• Manual access pause</li> </ul> IDP=615.2msec at DR=10pps IDP=461.4msec at DR=20pps
STC2571C <sub>0A</sub>	
STC2570C <sub>0B</sub>	<ul style="list-style-type: none"> <li>• Make/break (1/2 or 2/3) selectable</li> <li>• On-chip call disconnect function</li> <li>• Manual access pause</li> </ul> IDP=820.3msec at DR=10pps IDP=410.2msec at DR=20pps
STC2571C <sub>0B</sub>	

## ■ ABSOLUTE MAXIMUM RATINGS

( $V_{SS}=0V$ ,  $T_a=25^\circ C$ )

Parameter	Symbol	Ratings	Unit
Supply voltage	$V_{DD}$	-0.3 to 7.5	V
Input voltage	$V_I$	$V_{SS}-0.3$ to $V_{DD}+0.3$	V
Output voltage	$V_O$	$V_{SS}-0.3$ to $V_{DD}+0.3$	V
Operating temperature	$T_{opr}$	-25 to 70	$^\circ C$
Storage temperature	$T_{stg}$	-65 to 150	$^\circ C$
Soldering temperature and time	$T_{sol}$	260 $^\circ C$ , 10s (at lead)	—

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

( $f_{osc}=32.768kHz$ ,  $T_a=25^\circ C$ ,  $V_{SS}=0V$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	$V_{DD}$	—	1.3	—	6.0	V
Data retention voltage	$V_{DDR}$	$\overline{HS}=V_{DD}$	1.0	—	—	V
Average operating current	$I_{DDA}$	$V_{DD}=1.8V$ C1—C3, R1—R4, $\overline{DP}$ , MUTE = open	—	2	5	$\mu A$
		$V_{DD}=2.4V$ $\overline{HS}$ , M/B, DRS = $V_{DD}$	—	2.5	—	
High level input voltage	$V_{IH}$	C1—C3, R1—R4 $\overline{HS}$ , M/B, DRS	$0.8V_{DD}$	—	$V_{DD}$	V
Low level input voltage	$V_{IL}$	C1—C3, R1—R4 $\overline{HS}$ , M/B, DRS	$V_{SS}$	—	$0.2V_{DD}$	V
High level input current (1)	$I_{IH1}$	$\overline{HS}$ , M/B, DRS $V_{DD}=6.0V$ , $V_{IH1}=V_{DD}$	—	—	0.1	$\mu A$
Low level input current (1)	$I_{IL1}$	$\overline{HS}$ , M/B, DRS $V_{DD}=6.0V$ , $V_{IL1}=V_{SS}$	—	—	0.1	$\mu A$
High level input current (2)	$I_{IH2}$	C1—C3, R1—R4, $V_{DD}=2.4V$ , $V_{IH2}=V_{DD}$	—	4.5	10	$\mu A$
Low level input current (2)	$I_{IL2}$	C1—C3, R1—R4, $V_{DD}=2.4V$ , $V_{IL2}=V_{SS}$	90	200	—	$\mu A$
High level output current	$I_{OH}$	$\overline{DP}$ , MUTE $V_{DD}=2.4V$ , $V_{OH}=2.0V$	0.45	1.4	—	mA
Low level output current	$I_{OL}$	$\overline{DP}$ , MUTE $V_{DD}=2.4V$ , $V_{OL}=0.8V$	1.0	5	—	mA

### ●AC Electrical Characteristics

(Common to STC2570C and STC2571C)

( $f_{osc}=32.768kHz$ ,  $T_a=25^{\circ}C$ ,  $V_{SS}=0V$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Key input ON time	$T_{on}$	Excl. chattering time	21.0	—	—	msec
Key input OFF time	$T_{off}$	Excl. chattering time	3.42	—	—	msec
Allowable noise pulse width of key input pin	$T_n$	Width of one noise pulse	—	—	15.38	msec
Key judgement time	$T_{kj1}$	Normal dialing	33.73	33.75	33.77	msec
	$T_{kj2}$	Redialing or repertory dialing	26.90	26.92	26.94	
	$T_{kj3}$	Access pause cancelled	24.77	25.63	26.49	
	$T_{kj4}$	Writing to repertory memory	10.37	25.63	40.90	
Mute delay time	$T_{md}$	— *1	—	9.83	—	msec
Redial memory write time	$T_{mw}$	— *1	—	0.85	—	msec
Rate of data transfer to repertory memory	$T_{dt}$	— *1	—	3.42	—	msec/digit
Dial pulse transfer rate	DR	DRS= $V_{SS}$ *1	—	9.752	—	pps
		DRS= $V_{DD}$ *1	—	19.505	—	
Inter-digit pause	IDP	DRS= $V_{SS}$ (10pps) *1	—	615.2 <sup>*2</sup> /820.3 <sup>*3</sup>	—	msec
		DRS= $V_{DD}$ (20pps) *1	—	461.4 <sup>*2</sup> /410.2 <sup>*3</sup>	—	
Oscillation start time	$T_{os}$	$V_{DD}=1.8V$ , $CI \leq 40k\Omega$	—	500	—	msec
Voltage deviation of oscillation frequency	$\Delta f/f$	$V_{DD}=1.3$ to $2.0V$	-6	—	+6	ppm/0.1V
		$V_{DD}=2.0$ to $6.0V$	-10	—	+10	ppm/V

(STC2570C only)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Time difference between two keys when pressed at a time	$T_{dk1}$	When call disconnected (*, #)	—	—	8.54	msec
Dial pulse make/break ratio	M/B	$M/\bar{B}=V_{SS}$ *1	—	1/2	—	—
		$M/\bar{B}=V_{DD}$ *1	—	2/3	—	

(STC2571C only)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Dial pulse make/break ratio	M/B	— *1	—	1/2	—	—
Hooking time	$T_{hk}$	— *1	—	499.02	—	msec
Auto access pause	$T_{ap}$	— *1	—	3.589	—	sec
Keying confirmation tone ON time	$T_{kt}$	Valid key input *1	—	26.49	—	msec
Keying confirmation tone frequency	$f_{kt}$	Valid key input *1	—	910.22	—	Hz

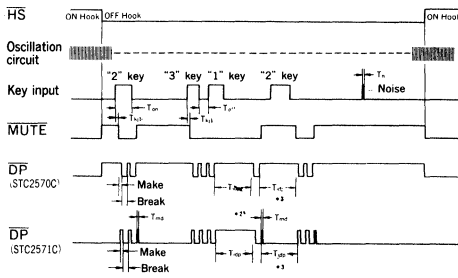
\*1 All specifications take constant values logically.  
The deviation is only a change of the oscillation frequency.

\*2 STC2570C<sub>0A</sub> and STC2571C<sub>0A</sub>

\*3 STC2570C<sub>0B</sub> and STC2571C<sub>0B</sub>

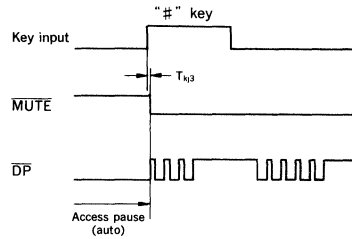
## ● Timing Chart

### ○ Normal dialing (DP mode) \*2, \*3



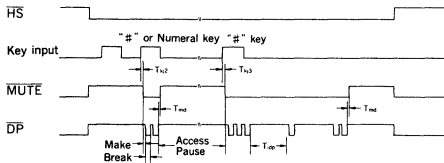
- \*2 If a key is pressed earlier than the transmission of a dial pulse, the MUTE continues on until all dial pulses corresponding to the buffered key input data have been transmitted.
- \*3 The inter-digit pause stays valid even if a key is pressed immediately after the last dial pulse has been transmitted. As system assumes that dial pulses are being transmitted during the inter-digit pause, entry of the '\*' key is ignored.

### ○ Access pause (auto pause)\*4, \*5 STC2571C



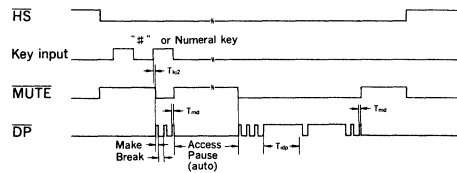
- \*4 Even in the normal dialing mode, pressing the '#' key causes an auto pause. The timing diagram for this operation is the same as in the redialing or repertory dialing.
- \*5 Clearing the auto pause (common to normal dialing, redialing and repertory dialing)

### ○ Redialing or repertory dialing \*6 STC2570C



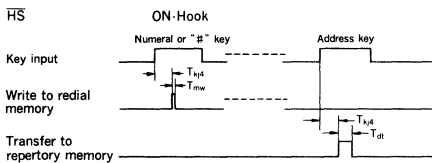
- \*6 During mixed dialing (e.g., redialing+normal, or repertory+normal), the inter-digit pause stays valid even if a key is pressed immediately after the last dial pulse of redialing or repertory dialing has been transmitted. As system assumes that dial pulses are being transmitted during the inter-digit pause, entry of any key is ignored.

### ○ Redialing or repertory dialing \*7 STC2571C



- \*7 During mixed dialing (e.g., redialing+normal, or repertory+normal), the inter-digit pause stays valid even if a key is pressed immediately after the last dial pulse of redialing or repertory dialing has been transmitted. As system assumes that dial pulses are being transmitted during the inter-digit pause, entry of any key is ignored.

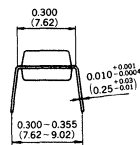
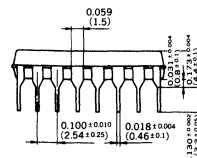
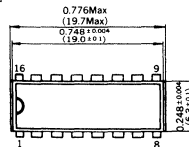
### ○ Registration to repertory memory STC2570C/STC2571C



## ■ PACKAGE DIMENSIONS

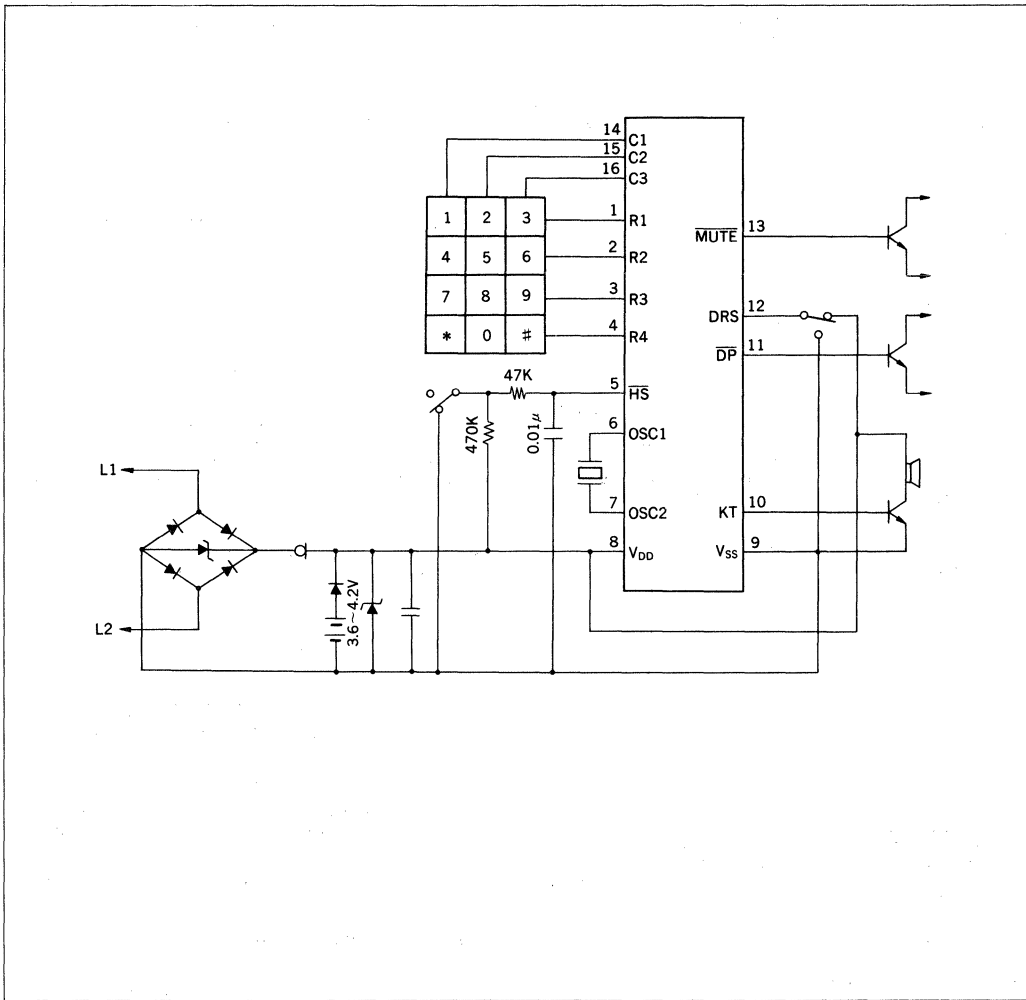
C16

16-pin DIP



unit : inch  
(mm)

■EXAMPLE OF APPLICATION



# STC2580C<sub>0c</sub> Series

## CMOS TONE/PULSE DIALER

- DTMF/Pulse Output Switch
- Low Distortion
- Ten 18-digit Repertory Memoies and 24-digit Redial Memory

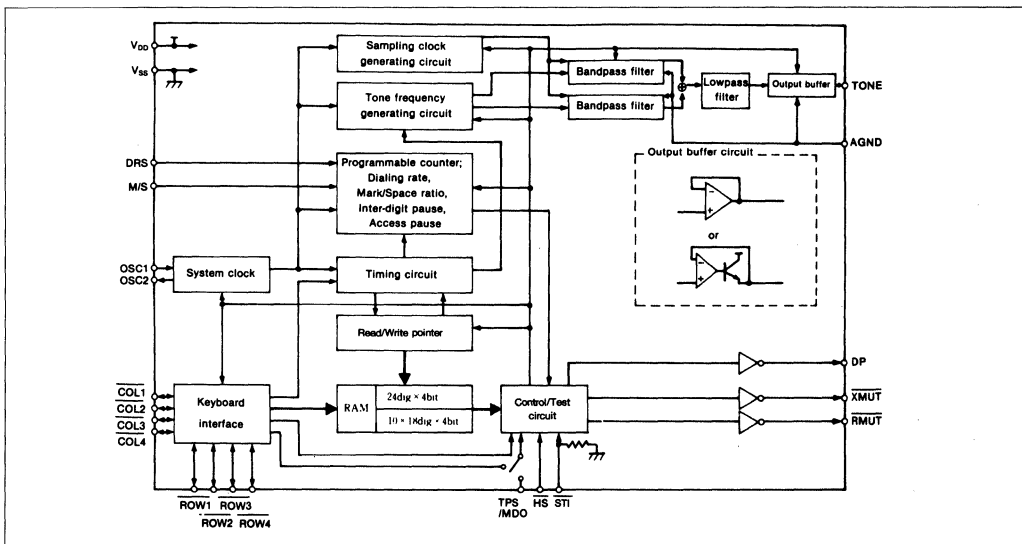
### DESCRIPTION

The STC2580C<sub>0c</sub> series is a CMOS LSI which is provided with a memory for telephone numbers, and can selectively output either dual tone multi-frequency (DTMF) signals or a dialing pulse (DP) train. The LSI contains Band Pass Filters (BPF) and smoothing filter by switched capacitor filter (SCF) technology, so that the DTMF output has less distortion than the DA conversion system used in a conventional tone dialer. It also incorporates an emitter-follower NPN transistor, enabling the DTMF output to directly drive a telephone line. By connecting the minimum necessary interface circuit, the dialing pulse output can also drive a telephone line.

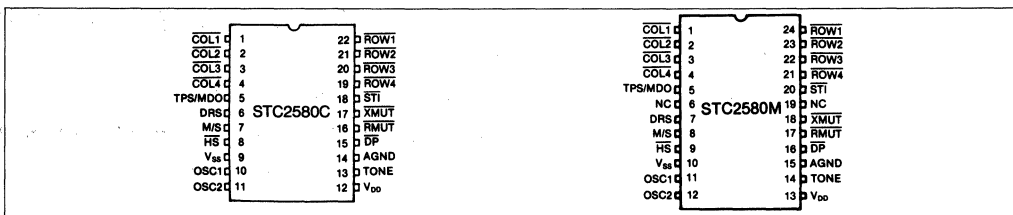
### FEATURES

- Low-voltage operation and low power dissipation due to CMOS process.
- A built-in SCF-type BPF makes possible a DTMF signal with low THD (typically 2.5% at 5 V) without the use of external filters.
- The LSI contains redialing memory for a 24-digit numbers and repertory memory for ten 18-digit numbers which can be used in either the tone or pulse mode.
- DP mode : Permits selection of dialing pulse rate (10/20 pps) and mark/space ratio (40/60, 33.3/66.6). (The inter-digit pause is fixed for each dialing rate .....617.9 ms for 10 pps or 463.4 ms for 20 pps.)
- DTMF mode ..... Make=93.1 ms and inter-digit pause=61.4 ms.
- When sending to an external line, the access pause can be set to auto pause (3.97s) using the pause key. This function can also be canceled during sending.
- This LSI can be connected to a standard 2 of 8 keyboard.
- The built-in reference signal generator requires only an inexpensive and easily-obtainable 3.58 MHz crystal oscillator for the TV color burst signal.
- Package ..... 22-pin DIP (plastic) / 24-pin SOP (plastic)

### BLOCK DIAGRAM



## PIN CONFIGURATION



## PIN DESCRIPTION

Pin name	Pin No.		Functions
	STC2580C	STC2580M	
ROW4-ROW1	19—22	21—24	[Scanning input/output of matrix keyboard] Keys are selected by short-circuiting ROW and COL.
COL1-COL4	1—4	1—4	
TPS*/MDO	5	5	[TPS : DTMF/DP mode select input] (for STC2585C to STC2588C) In this case, [T/P] on the keypad is an invalid input. [MDO : DTMF/DP mode display output] (for STC2581C to STC2584C) Outputs whether the DTMF or DP mode has been selected using [T/P] key.
DRS* <sup>1</sup>	6	7	[Pulse rate select input in DP mode] Ignores input switching performed during a pulse output (including auto dialing) as well as inputs made in the DTMF mode. The inter-digit pause is fixed for each pulse rate.
M/S* <sup>1</sup>	7	8	[Pulse mark/space ratio in DP mode] Like DRS, this pin ignores inputs made during a pulse output or in the DTMF mode. OFF-Hook : V <sub>SS</sub> level
HS* <sup>1</sup>	8	9	[Hook switch] Determines the ON/OFF status of the hook switch.
V <sub>SS</sub>	9	10	[Power supply terminal (-)]
CSC1	10	11	These pins are connected across the terminals of a 3.579545 MHz crystal oscillator which is used for the reference signal generator.
OSC2	11	12	
V <sub>DD</sub>	12	13	[Power supply terminal (+)]
TONE	13	14	[DTMF signal output] This pin enables either an NPN emitter-follower output or a CMOS OP-Amp output to be selected.
AGND	14	15	[Grounding point output of analog circuit (SCF section)] By connecting a capacitor to this point, the level is stabilized.
DP	15	16	[Dialing pulse output] While the dialing pulse is not output, the output level is V <sub>SS</sub> during ON-Hook and V <sub>DD</sub> during OFF-Hook.
RMUT	16	17	[Receiver mute output] This output is valid in the DP mode. In the DTMF mode, muting is not applied. The level of this pin is : DP mode : During mute or ON-Hook → V <sub>SS</sub> level DTMF mode : During ON-Hook → V <sub>SS</sub> level ; During OFF-Hook → V <sub>DD</sub> level.
X MUT	17	18	[Transmitter mute output] Mute signal for transmitter usable in both the DP mode and the DTMF mode. During mute or ON-Hook status → V <sub>SS</sub> level
STI* <sup>2</sup>	18	20	[Single tone generating mode select] The single tone generating mode is selected by applying the V <sub>DD</sub> level. To generate a single tone for COL1, COL2, or COL3, press two or three keys in the corresponding column simultaneously, and to generate a single tone for ROW1, ROW2, ROW3, or ROW4, press the two keys of COL1 and COL2 in the corresponding row simultaneously.
NC	6, 19		[No connection]

\*1 Because DRS, M/S, HS, and TPS are open pins, be sure to apply V<sub>DD</sub> or V<sub>SS</sub> from outside the LSI.

\*2 Pin STI is connected to a built-in pull-down resistor which puts the LSI in the single tone inhibit mode during normal use, even when the pin is open. To provide noise immunity, however, it is recommended that this pin be fixed at V<sub>SS</sub> level externally.

## STC2580C<sub>OC</sub> SERIES

Type* <sup>1</sup>	Write to repertory memory	DTMF output* <sup>2</sup>	Tone/pulse output selection	Type* <sup>1</sup>	Write to repertory memory	DTMF output* <sup>2</sup>	Tone/pulse output selection
STC2581C <sub>OC</sub>	OFF Hook	Bip	Key	STC2585C <sub>OC</sub>	OFF Hook	Bip	External pin
STC2582C <sub>OC</sub>	ON Hook	Bip	Key	STC2586C <sub>OC</sub>	ON Hook	Bip	External pin
STC2583C <sub>OC</sub>	OFF Hook	CMOS	Key	STC2587C <sub>OC</sub>	OFF Hook	CMOS	External pin
STC2584C <sub>OC</sub>	ON Hook	CMOS	Key	STC2588C <sub>OC</sub>	ON Hook	CMOS	External pin

\*1 This LSI can also be provided in a mini-flat package. In this case, C becomes M (e.g. STC2581M). The characteristics are same as those of the DIP type.

\*2 This is the CMOS OP-Amp output or Bipolar emitter-follower output.

## ■ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Power supply voltage	V <sub>DD</sub>	-0.3 to 7.5	V
Input voltage	V <sub>I</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Operating temperature	T <sub>opr</sub>	-20 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

## ■ELECTRICAL CHARACTERISTICS

### ●DC Characteristics

(V<sub>SS</sub>=0V, T<sub>a</sub> = -20 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Operating voltage	V <sub>DD</sub>	DP mode	1.5	—	6.0	V
		DTMF mode	2.5	—	6.0	
Data retention voltage	V <sub>DDR</sub>	$\overline{HS} = V_{DD}$	1.0	—	6.0	V
Average operating current	I <sub>DDA</sub>	V <sub>DD</sub> =5.0V $\overline{HS} = V_{SS}$ Key input stand-by status	—	—	800	μA
		DP, TONE, RMUT, XMUT and MDO not loaded in DP mode dial pulse being output	—	—	1.0	mA
		in DTMF mode DTMF signal being output	—	—	8.0	mA
Data retention current	I <sub>DDR</sub>	V <sub>DD</sub> =1.0V, $\overline{HS} = V_{DD}$ , $\overline{STI} = V_{SS}$ , TPS=DRS=M/S= V <sub>DD</sub> or V <sub>SS</sub>	—	—	0.75	μA
High level input voltage	V <sub>IH</sub>	TPS, DRS, M/S, $\overline{HS}$ , $\overline{STI}$	V <sub>DD</sub> -0.4	—	V <sub>DD</sub>	V
Low level input voltage	V <sub>IL</sub>	TPS, DRS, M/S, $\overline{HS}$ , $\overline{STI}$	V <sub>SS</sub>	—	V <sub>SS</sub> +0.4	V
High level input voltage (1)	I <sub>IH1</sub>	TPS, DRS, M/S, $\overline{HS}$ , V <sub>DD</sub> = 5.0V, V <sub>IH1</sub> =V <sub>DD</sub>	—	—	0.1	μA
High level input voltage (2)	I <sub>IH2</sub>	STI, V <sub>DD</sub> =5.0V, V <sub>IH2</sub> =V <sub>DD</sub>	—	—	300	μA
Low level input current	I <sub>IL1</sub>	TPS, DRS, M/S, $\overline{HS}$ , $\overline{STI}$ , V <sub>DD</sub> = 5.0V, V <sub>IL1</sub> =V <sub>SS</sub>	—	—	0.1	μA
Low level input current	I <sub>IL2</sub>	$\overline{COLT} - \overline{COL4}$ , ROW1—ROW4, V <sub>DD</sub> =5.0V, V <sub>IL2</sub> =V <sub>SS</sub>	10	23	50	μA
High level output current (Source)	I <sub>OH1</sub>	DP, XMUT, RMUT, MDO V <sub>DD</sub> =5.0V, V <sub>OH1</sub> =4.0V	4.0	—	—	mA
Low level output current (Sink)	I <sub>OL2</sub>	DP, XMUT, RMUT, MDO V <sub>DD</sub> =5.0V, V <sub>OL2</sub> =0.5V	4.0	—	—	mA



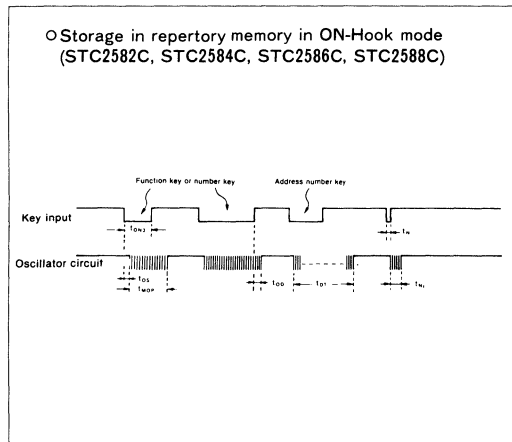
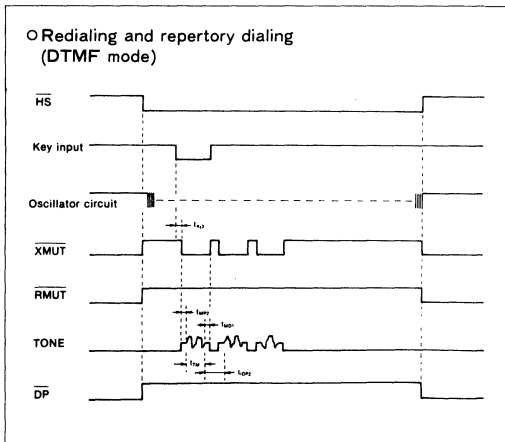
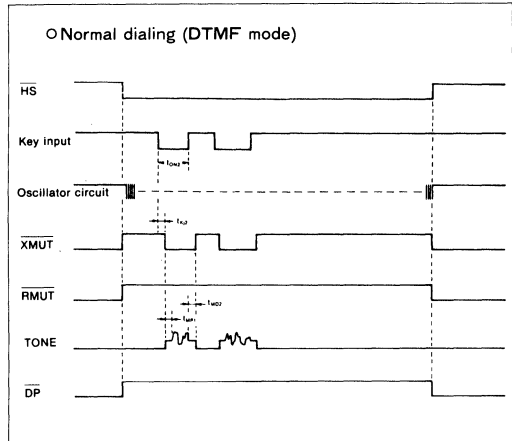
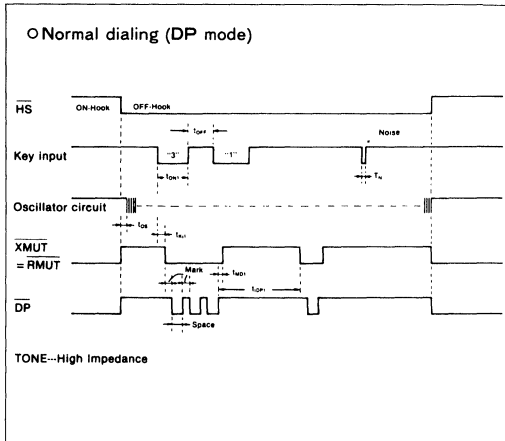
●AC Characteristics

(V<sub>SS</sub>=0V, Ta=25°C, f<sub>osc</sub>=3.579545MHz)

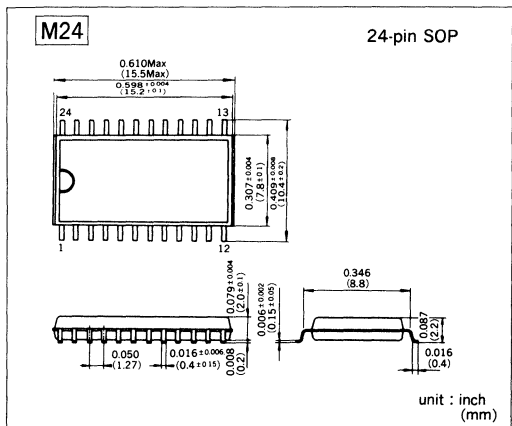
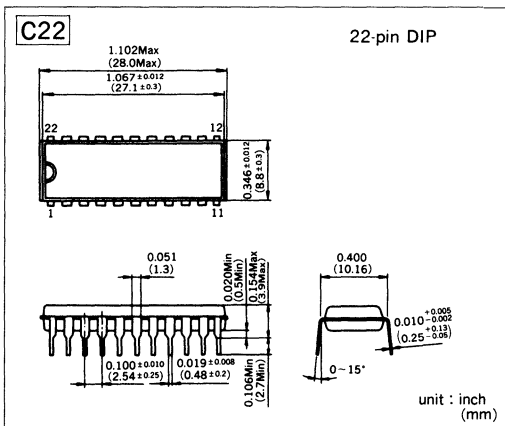
Parameter	Symbol	Conditions	Min	Typ	Max	Unit	
Key input ON effective period	t <sub>ON1</sub> *1	DP and DTMF mode non-normal dialing	Excluding chattering	15.45	—	—	ms
	t <sub>ON2</sub> *2	DTMF mode normal dialing		77.24	—	—	
Key input OFF effective period	t <sub>OFF</sub>	Excluding chattering	1.72	—	—	ms	
Pulse width of allowable noise at input terminal	t <sub>N</sub>		—	—	14.37	ms	
Oscillator start-up time	t <sub>OS</sub>	V <sub>DD</sub> =5.0V CI<100Ω	—	—	2.0	ms	
Key judgement time	t <sub>KJ1</sub>	DP mode normal dialing	30.25	30.90	31.97	ms	
	t <sub>KJ2</sub>	DTMF mode normal dialing	17.37	18.02	19.10		
	t <sub>KJ3</sub>	DP/DTMF mode auto dialing*3	19.95	20.60	21.67		
Pre-mute time	t <sub>MP1</sub>	DTMF mode normal dialing	—	9.01	—	ms	
	t <sub>MP2</sub>	DTMF mode auto dialing	—	9.87	—		
Mute delay time	t <sub>MD1</sub>	DP and DTMF mode auto dialing	—	9.87	—	ms	
	t <sub>MD2</sub>	DTMF mode normal dialing	9.22	9.33	9.44		
Dial pulse mark/space	—	M/S=V <sub>DD</sub>	—	40/60	—	—	
	—	M/S=V <sub>SS</sub>	—	33.3/66.6	—		
Dial pulse rate	—	DRS=V <sub>DD</sub>	—	19.42	—	pps	
	—	DRS=V <sub>SS</sub>	—	9.71	—		
Inter-digit pause	t <sub>IDP1</sub>	DP mode	Dial rate=19.42pps	—	463.4	—	ms
			Dial rate=9.71pps	—	617.9	—	
	t <sub>IDP2</sub>	DTMF mode auto dialing	—	61.36	—		
DTMF make time	t <sub>TM</sub>	DTMF mode auto dialing	—	93.12	—	ms	
Auto access pause	t <sub>AP</sub>		—	3.965	—	s	
Oscillator frequency	f <sub>OSC</sub>		—	3.579545	—	MHz	
Oscillator frequency/voltage variance	Δf/f	V <sub>DD</sub> =1.5 to 6.0V	—	—	30	ppm/v	
Tone output voltage (single tone)	V <sub>TONE</sub>	COL	V <sub>DD</sub> =5.0V	—	-10	—	dBm
		ROW	Operational amplifier load=10 Kohms ; Bipolar transistor load=120 ohms	—	-11	—	
COL-ROW tone output voltage ratio**4	d <sub>BCR</sub>	V <sub>DD</sub> =3.0 to 6.0V	—	—	2	dB	
Tone distortion	% <sub>DIS</sub>	V <sub>DD</sub> =2.5V	—	—	7.0	%	
Tone output frequency	f <sub>R1</sub>	ROW1	—	699.13	—	Hz	
	f <sub>R2</sub>	ROW2	—	766.17	—		
	f <sub>R3</sub>	ROW3	—	847.43	—		
	f <sub>R4</sub>	ROW4	—	947.97	—		
	f <sub>C1</sub>	COL1	—	1215.88	—		
	f <sub>C2</sub>	COL2	—	1331.68	—		
	f <sub>C3</sub>	COL3	—	1471.85	—		
Minimum assured key detection time	t <sub>MOP</sub>	t <sub>ON1</sub> <t <sub>MOP</sub> Excluding chattering	42.91	44.63	46.35	ms	

- \*1 Key input ON effective time  
When writing data to the repertory memory while in ON-Hook status (STC2582C, STC2584C, STC2586C, and STC2588C), it is necessary to add the oscillator starting time to the effective time t<sub>ON3</sub>. t<sub>ON3</sub>=t<sub>ON1</sub>+t<sub>OS</sub> (no key chattering)
- \*2 Key input ON effective time (DTMF mode normal dialing)  
This is the key read time+mute time+NTT engineering reference signal sending time of 50 ms.
- \*3 Auto dialing  
Indicates redialing and repertory dialing.
- \*4 COL-ROW tone output voltage ratio  
The output gain of COL is higher than that of ROW.

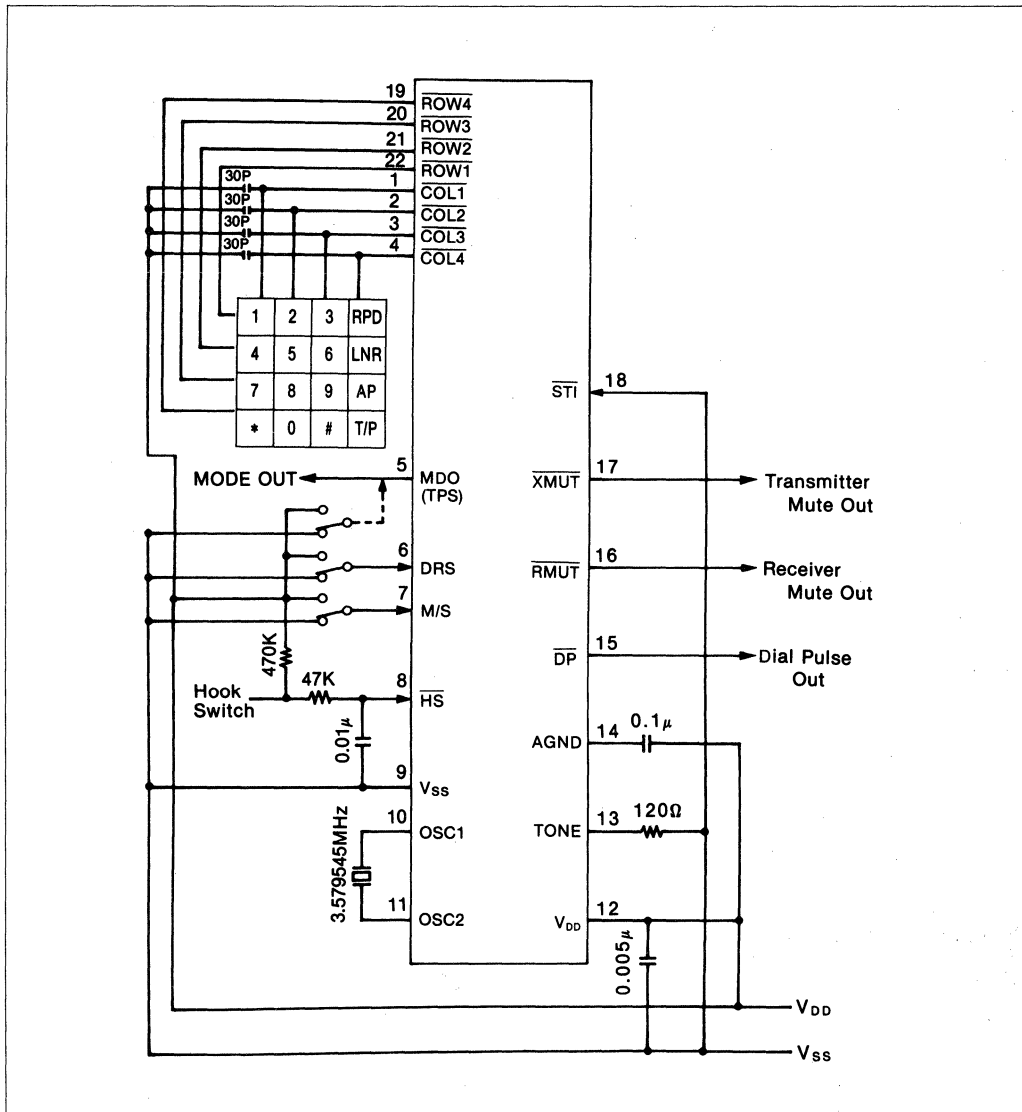
## ●Timing Chart



## ■PACKAGE DIMENSIONS

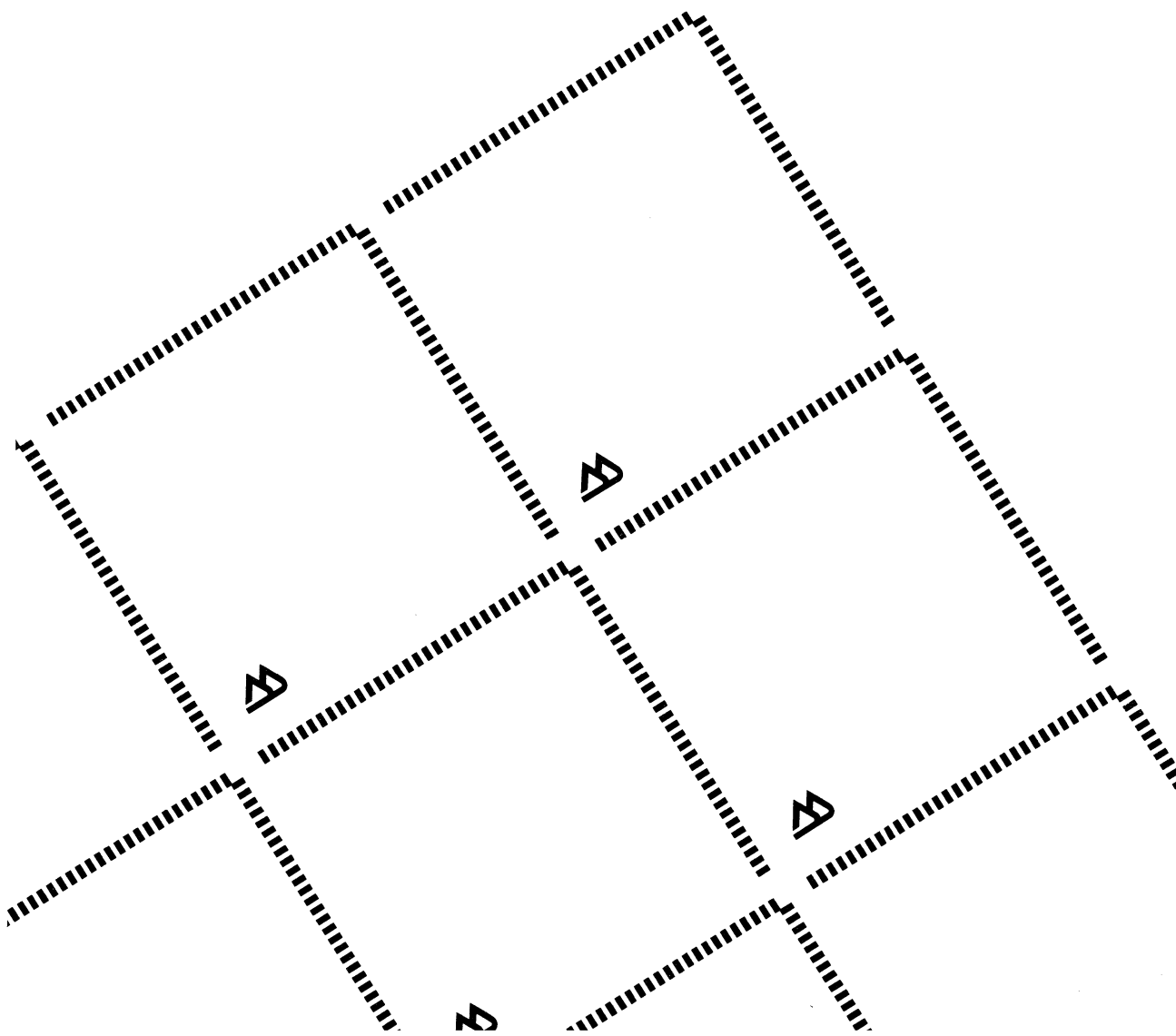


EXAMPLE OF APPLICATIONS



G. MELODY ICs

1988/1989 CMOS  
DATA BOOK





▷ MELODY IC TABLE\*

Type No.	Maximum Number of Tunes (Number of note)	Tune Selection		Accompaniment	Preamplifier(internal)	BUSY END Signal	Dynamic SP	Transducer		External CR	Envelope		Oscillation	Tune mode		Power Supply			pin (DIP)	Package	Note
		Binary Code	Serial Trigger					Magnetic	Piezo		Digital Envelope	CR self		External Clock	Level hold	One-shot	Stop	1.5V			
7910 series #	2 (128)	○	—	—	○	—	—	—	—	○	—	—	—	—	—	○	○	—	16	•High quality tone •Dynamic SP Drive •Dynamic SP Drive (External)	
7920 series	1 (64)	—	—	—	○	—	—	—	—	—	—	☆	☆	—	—	○	○	—	8		
7930 series	1 (64)	—	—	—	○	—	—	—	—	—	—	☆	☆	—	—	○	○	—	14		
SVM7940 Series	8	—	○	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	16	•Multi melody type •High impedance transducer drive	
SVM7941	(512)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7942	(512)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7943	(512)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7944	(512)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7945	(512)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7946	(512)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7950 Series	1	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	16	•High impedance transducer drive	
SVM7951	(64)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7952	(64)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7953	(64)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7954	(64)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7955	(64)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7956	(64)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7960 Series	4	○	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	16	•High quality tone •Dynamic SP Drive •1.5V/5V	
SVM7961	(127)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7962	(127)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7963	(127)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7964	(127)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7965	(127)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7966	(127)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7970 Series	8 (640)	—	○	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	18	•Multi melody type •High quality tone •Dynamic SP Drive •1.5V/5V	
SVM7971	(640)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7972	(640)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7973	(640)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7974	(640)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7975	(640)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7976	(640)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7990 Series	8	—	○	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	16	•Multi melody type •Dynamic SP Drive	
SVM7991	(512)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7992	(512)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7993	(512)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7994	(512)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7995	(512)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7996	(512)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7900 Series #	1 (64)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	8	•High impedance transducer drive *4 OSC. resistor is built in (Mask option)	
SVM7901	(64)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7902	(64)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		
SVM7903	(64)	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—		

☆Mask option

# Ongoing user service product

(Continue)

\*Minimum melody IC order is 100,000 pieces. Please consult S-MOS for specific availability.

Type No.	Maximum Number of Tunes (Number of notes)	Binary Code	Tune Selection	Serial Trigger	Accompaniment	Preamplifier(Internal)	BUSY END Signal	Dynamic SP	Transducer		External CR	Envelope		Oscillation	Tune mode		Power Supply	Package	Note	
									Magnetic	Piezo		Digital Envelope	CR self		Level hold	One-shot				Stop
SVM7800 Series	SVM7800	1 (63)	-	-	-	-	-	○	○	-	-	○	○	-	○	-	○	-	8	<ul style="list-style-type: none"> <li>•High impedance transducer drive</li> <li>•5 Level hold or one shot pin selection</li> </ul>
	SVM7801											○	○							
	SVM7802											○	○							
	SVM7803											○	○							
	SVM7804											○	○							
	SVM7805											○	○							
	SVM7806											○	○							
	SVM7807											○	○							
	SVM7808											○	○							
SVM7809	○	○																		
SVM7820 Series	SVM7820	1 (63)	-	-	-	-	-	○	○	-	-	○	○	-	○	-	○	-	-	<ul style="list-style-type: none"> <li>•LED drive</li> <li>•High impedance transducer drive</li> <li>•7 Level hold or one shot pin selection</li> </ul>
	SVM7821											○	○							
	SVM7822											○	○							
	SVM7823											○	○							
	SVM7824											○	○							
	SVM7825											○	○							
	SVM7826											○	○							
	SVM7827											○	○							
	SVM7828											○	○							
SVM7829	○	○																		
SVM7860 Series	SVM7860	1 (127)	-	○	-	-	○	-	-	○	-	○	○	-	○	-	○	-	8	<ul style="list-style-type: none"> <li>•High quality tone</li> <li>•Dynamic SP Drive (External)</li> </ul>
	SVM7861											○	○							

☆ Mask option

## ▷ STANDARD MELODY LIST

Code No.	Song Title	Code No.	Song Title	Code No.	Song Title
7910C	Holdilidia	☆7943COE	Romance de amor	☆7993COc	Mountain Musician
7910E	Two Minuets		O sole mio	7993CO <sub>n</sub>	Westminster
7910G	Dark eyebrows		Die Lorelei		A maiden's prayer
	Melodia A		The cuckoos waltz		For Elise
	Melodia B		Old folk at home		Romance de amor
7910I	Home on the range	☆7943COs	Spring		Amaryllis
	Green Sleeves		Hymne a Lamour		Symphony # 40 (Mozart)
7910K	lullaby (two songs)		La Mer		Dark eyebrows
7910N	Musunde Hiraita		Farandolles	7993DAc	De camptown races
	Cho-cho		Yesterday		Yellow Rose of Texas-Dixie Land
* 7910O	Westminster (two tunes)		L'eau Vive		Stars and Stripes forever-Anchors Aweigh
* 7910P	Westminster (accompaniment)		O Tannenbaum		She wore a yellow ribbon-Twinkle twinkle little star
7910Q	Wiegenlied (Brahms)		Symphony # 40 (Mozart)		London Bridge is falling down-Mountain musician
	Rock a bye Baby	☆7943CO <sub>n</sub>	Hymne a lamour		Row row row a boat-It's a small world
7910CE	Nocturne		Santa lucia	7993DAE	Home sweet home-Wiegenlied
	Minuet		Hey Jude		<small>Rudolph, The red nosed reindeer-Santa Claus is coming to town</small>
7910T	Jingle Bells		L'eau Vive		We wish you a Merry X'mas-Frosty the snow man
7910CF	For Elise		Romance de amor		Jingle Bells-Silent Night
	A maiden's prayer		Yesterday		Joy to the world-The First Noel
7910CG	Romance de Amor		Happy birthday to you		O christmas tree-Hark the herald Angels sing
	Petrouchka		Wedding march		O tannenbaum-Oh little town of Bethlehem
★ 7910CH	Westminster	7942DA <sub>n</sub>	Jingle Bells	7902CO <sub>A</sub>	X'mas song medley. Red nosed reindeer. O Tannenbaum Jingle bells.
	Ave Maria		Joy to the world		Happy birthday
★ 7910CM	Westminster		O Tannenbaum	⊗7903CO <sub>B</sub>	Wedding March
	Whittington		We wish you a Merry X'mas	⊗7903CO <sub>C</sub>	Happy birthday
7910CN	Holdilidia		Silent Night	★7903CO <sub>E</sub>	Hymne a lamour
	Home on the range		The First Noel	☆7903CO <sub>H</sub>	The Alphabet Song
7910CP	Silent lake-side		Frosty the snow man	☆7903CO <sub>J</sub>	Rock a bye Baby
	Mountain Musician		Rudolph the red nosed reindeer	☆7903CO <sub>K</sub>	Old Macdonald Had a Farm
7910CQ	Mary's little lamb			⊗7903CO <sub>S</sub>	Mountain Musician
	De camptown races	7950CO <sub>B</sub>	Les filles mortes	★7903CO <sub>Y</sub>	Jingle Bells
7910CR	Lorelei	7950CO <sub>D</sub>	Blue bell of Scotland	★7903CA <sub>A</sub>	Love me tender
	Landler tanz	7950CO <sub>F</sub>	Yodel	★7903CA <sub>B</sub>	Love Story
7910CS	Amaryllis	7950CO <sub>H</sub>	Cantate # 147 (Bach)	★7903CA <sub>C</sub>	Wedding March
	Symphony # 40 (Mozart)	☆7951CO <sub>C</sub>	Mexican hat dance	★7903CA <sub>E</sub>	Congratulations
7910CU	Jingle Bells	☆7951CO <sub>D</sub>	Cantate # 147 (Bach)	★7903CA <sub>H</sub>	Silent Night
	Silent night	7952CO <sub>G</sub>	Cantate # 147 (Bach)	★7903CA <sub>L</sub>	Saint go'in march'in in
7910CV	Joy to the world	7954CA <sub>R</sub>	Green Sleeves	★7903CA <sub>N</sub>	Jingle bells, Red nosed reindeer, Joy to the world.
	The first noel	☆7955CO <sub>J</sub>	O sole mio	★7903CA <sub>P</sub>	Music box dancer
7910CW	O Tannenbaum	☆7955CO <sub>L</sub>	Happy birthday to you	★7903CA <sub>R</sub>	Wedding march (Long version)
	Frosty the snow man	☆7955CO <sub>X</sub>	Saint go'in march'in in	★7903CA <sub>S</sub>	Let me call you my Sweet heart
		☆7955CO <sub>Y</sub>	Music box dancer	☆7903CA <sub>B</sub>	Jingle Bells.
		☆7955CA <sub>F</sub>	Mountain Musician	☆7903CA <sub>BB</sub>	Silent Night
		☆7955CA <sub>N</sub>	Jingle Bells	☆7903CA <sub>BN</sub>	Hymne a lamour
		☆7955CA <sub>BC</sub>	Wedding March	★7903CA <sub>BP</sub>	Mother of mine
7920A	The cuckoos waltz			☆7903CA <sub>BQ</sub>	Happy birthday
7920B	Home sweet home			☆7903CA <sub>BR</sub>	Music box dancer
7920C	Jingle Bells			☆7903CA <sub>BS</sub>	Wedding March
★ 7920M	Wedding march			☆7903CA <sub>BT</sub>	Jingle Bells, Red Nosed Reindeer, Joy to the world
★ 7920Q	Victory Song			☆7903CA <sub>BY</sub>	For Elise
7920AH	Wiegenlied (Brahms)			7902DC <sub>F</sub>	Christmas song medley
		7962CO <sub>A</sub>	Green Sleeves	★7903DC <sub>K</sub>	Easter Paradise
			Home on the range	7902DC <sub>S</sub>	Rock A bye baby
			Ding Dong	★7903DC <sub>T</sub>	Santa Claus is coming to town
			Two Minuets	★7903DC <sub>V</sub>	The First Noel
7930B	Home sweet home			★7903DC <sub>Y</sub>	When you wish up on a star
7930C	Holdilidia			★7903DE <sub>A</sub>	You light up my life
7930D	Lorelei			★7903DE <sub>B</sub>	Wargner's Wedding March
★ 7930E	Westminster			7902DEC	Christmas Medley
7930GA	Yurikago no uta			☆7903DE <sub>H</sub>	Congratulation
7930GB	Jingle Bells				
7930GC	We wish you a merry X'mas				
7930GD	Rudolph, the red-nosed Reindeer				
7930GE	For Elise				
7942CO <sub>T</sub>	Holdilidia				
	Minuet (Bach)				
	Green Sleeves				
	Symphony # 40 (Mozart)				
	Home on the range				
	Silent lake-side				
	Mountain Musician				
	Happy birthday to you				
	Green Sleeves				
	De camptown races				
	For Elise				
☆7943CO <sub>E</sub>		7992CO <sub>A</sub>	X'mas song medley (8 tunes)		
		☆7993CO <sub>C</sub>	Green Sleeves		
			De camptown races		
			For Elise		
			Romance de amor		
			O sole mio		
			Lorelei		
			The cuckoos waltz		

\* Type 7910P will be used as accompaniment with type 7910O.  
 Note: 7910 Series and SVM7900 Series are ongoing user service products.

☆ One shot mode. (A type)  
 ★ One shot mode (B type)

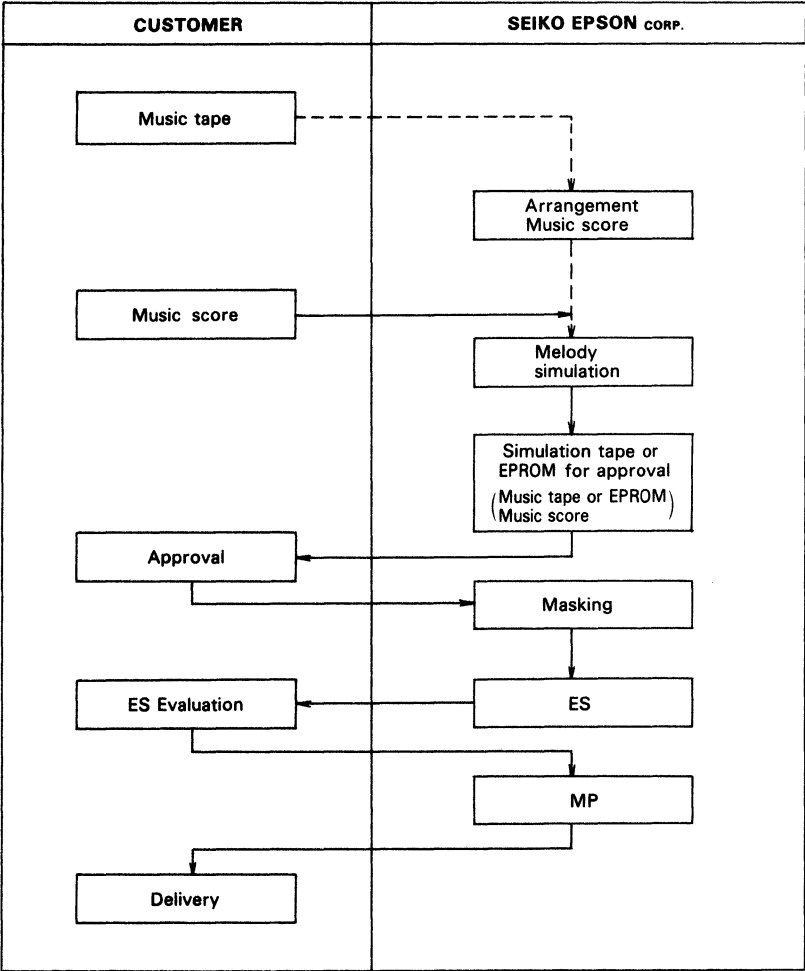
⊗, ⊕ OSC, resistor is not included on IC



▷ STANDARD MELODY LIST

Code No	Song Title	Code No	Song Title	Code No	Song Title
7800Cs	Silent Night	7820Sb	Jingle Bells Medley		
7800Ct	Rock a Bye Baby	7820Sc	Music Box Dancer		
7800Cv	If You Love Me	7820Se	Jingle Bells		
7800Cy	Brahms' Lullaby	7820Sf	Silver Bells		
7800Ea	Love Story	7820Sg	It's a Small World		
7800Eb	Happy Birthday to You	7820Sh	Over The Rainbow		
7800Ec	Jingle Bells	7820Sj	Easter Parade / Peter Cottontail		
7800En	Old Macdonald				
7800Ep	Twinkle Twinkle Little Star				
7800Eq	Romance D'amor				
7800Er	White Christmas				
7800Es	Wedding March (Wagner)				
7800Et	Wedding March (Mendelssohn)				
7800Ev	You are my Sunshine				
7800Fb	O Tannenbanm / Silent Night				
7800Fc	Silver Bells				
7800Ff	Aure Lee				
7800Fg	Let me call you my sweet heart				
7800Fl	Mary Had a Little Lamb				
7800Fp	Jesus Loves Me				
7800Ft	Yesterday				
7800Fv	Music Box Dancer				
7800Fy	My Way				
7800Ga	Easter Parade / Peter Cottontail				
7800Gb	Love Me Tender / Let Me Call You My Sweet	7860Sb	Nocturne		
7802Fe	For Elise	7860Sc	Minuet		
		7860Se	Home on the Range		
		7860Sf	Green Sleeves		
		7860Sg	The Entertainer		
		7860Sh	Lorelei		
		7860Sk	For Elise		
		7860Ec	Tableaux d'une Exposition(Promenade)		
		7860Ee	Je te Veux		
		7860Ef	The Jewels of the Madonna		
		7860Eg	When I'm Sixty-four		
		7860Eh	Minuet (Boccherini)		

**MELODY IC DESIGN FLOW**



QUESTION NO. 10

1. The following information is available for the year ended 31st December 2018:

	Rs.
Share Capital	100,000
Reserves	20,000
Trade Receivables	15,000
Trade Payables	10,000
Inventory	5,000
Fixed Assets	50,000
Current Assets	10,000
Current Liabilities	10,000
Long Term Debt	20,000

2. The following information is available for the year ended 31st December 2019:

	Rs.
Share Capital	100,000
Reserves	25,000
Trade Receivables	18,000
Trade Payables	12,000
Inventory	6,000
Fixed Assets	55,000
Current Assets	12,000
Current Liabilities	12,000
Long Term Debt	22,000

3. The following information is available for the year ended 31st December 2020:

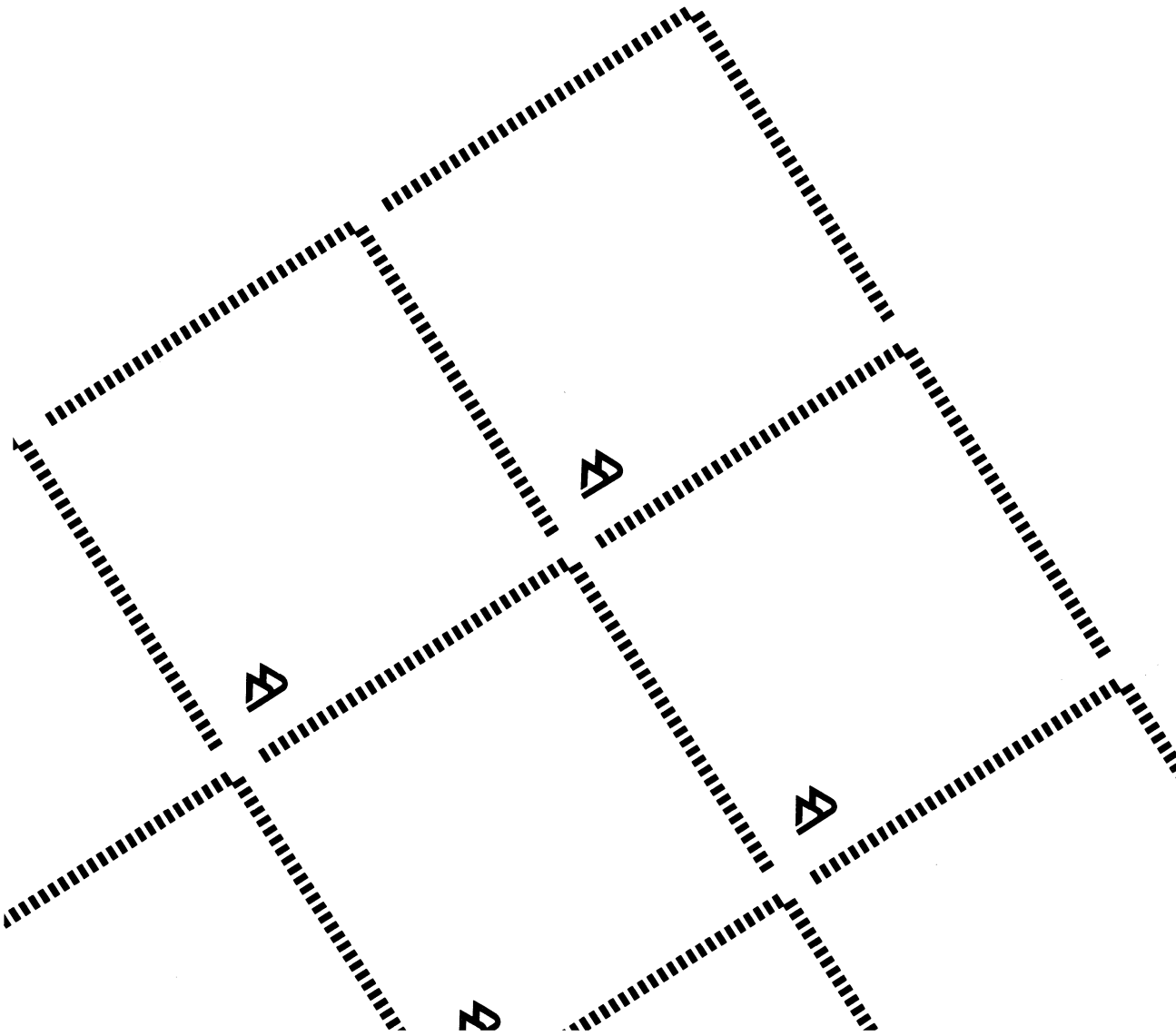
	Rs.
Share Capital	100,000
Reserves	30,000
Trade Receivables	20,000
Trade Payables	15,000
Inventory	7,000
Fixed Assets	60,000
Current Assets	15,000
Current Liabilities	15,000
Long Term Debt	25,000

4. The following information is available for the year ended 31st December 2021:

	Rs.
Share Capital	100,000
Reserves	35,000
Trade Receivables	22,000
Trade Payables	18,000
Inventory	8,000
Fixed Assets	65,000
Current Assets	18,000
Current Liabilities	18,000
Long Term Debt	28,000

H. SUB-ASSEMBLIES

1988/1989 CMOS  
DATA BOOK





# SHB2112B<sub>1A/1B</sub>

## CMOS 1M-BIT HYBRID STATIC RAM

- Low Supply Current
- Access Time 100ns
- 131,072 Words × 8 Bits Asynchronous

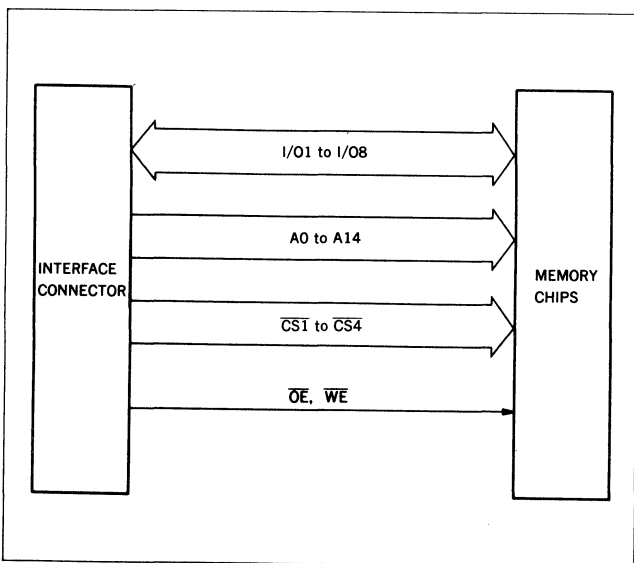
### DESCRIPTION

The SHB2112B<sub>1A/1B</sub> is a 131,072-word × 8-bit hybrid LSI module with four 256K SRAM (SRM20256LM). With low power consumption, the module can be used with applications which require a battery back-up. Since it is a static device, it does not require a clock or refresh circuitry. The I/O control provides 3-state output, for data bus connection. These features provide solutions for a wide variety of applications, including microcomputers and other peripheral equipments.

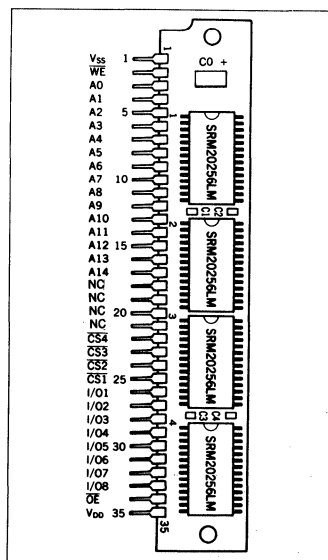
### FEATURES

- Hybrid CMOS LSI
- 131,072-word × 8-bit memory density
- Mounting 4 pcs. of 256K static RAM (SRM20256LM<sub>10</sub>)
- Access time 100ns Max.
- Single power supply-5volt
- Printed-circuit-board (PCB) size 17.5mm × 101.6mm × 4.77mm (except pins)
- PCB .....SHB 2112B<sub>1A</sub> 35-pin SIP (Single inline package)
- SHB 2112B<sub>1B</sub> 35-pin SIM (Single inline module)

### BLOCK DIAGRAM



### PIN CONFIGURATION



## PIN DESCRIPTION

Pin name	Pin No.	Functions
V <sub>SS</sub>	1	Grounding pin. This GND is common in signal.
WE	2	<Write Enable> Data write signal line (negative logic). Data is written to the memory module at the positive edge of WE. When WE is "H", this module is read operation.
A0 to A14	3 to 17	<Address Input> 15-bit address input pin. (Positive logic)
NC	18 to 21	<No connection>
CS1 CS2 CS3 CS4	25 24 23 22	<Chip Select> These signal line (negative active) are module select line. These line should be selected each one at read and write operation. Each CS is available for each 32kB RAM. That is to say, 128kB is divide by 4 CS signal. EX. Data will be valid to read and write when CS1 is "L" and CS2 to CS4 are "H". If CS1 to CS4 are "H", this module is non-selected mode (I <sub>DD</sub> is stand-by mode)
I/O1 to I/O8	26 to 33	<Data I/O> Inputs or outputs 8-bit of data. This pin provides an input with WE low and an output with WE high. Also, it has low impedance with OE low and high impedance with OE high.
OE	34	<Output Enable> Data read signal line (negative logic) from equipment to the memory module. As Data I/O terminals are hi-impedance when OE = "H", the contention of data memory output bus can be avoided.
V <sub>DD</sub>	35	Positive power supply pin. (5V ± 10%) Normally, 5V is supplied.

(V<sub>SS</sub> = 0V)

## ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5* to 7.0	V
I/O voltage	V <sub>I/O</sub>	-0.5* to V <sub>DD</sub> + 0.3	V
Operating temperature	T <sub>opr</sub>	0 to 70	°C
Storage temperature	T <sub>stg</sub>	-40 to 100	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (Lead only)	—

\* V<sub>I</sub>, V<sub>I/O</sub> (Min.) = -1.0V at pulse width less than 50ns

## DC RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub> = 0V, T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
	V <sub>SS</sub>		0	0	0	V
Input voltage	V <sub>IH</sub>		2.4	—	V <sub>DD</sub> + 0.3	V
	V <sub>IL</sub>		-0.3*	0	0.8	V

\* V<sub>IL</sub> (Min.) = -1.0V at pulse width less than 50ns

## ELECTRICAL CHARACTERISTICS

### DC Electrical Characteristics

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ*	Max	Unit
Input leakage current	I <sub>LI</sub>	V <sub>I</sub> = 0 to V <sub>DD</sub>	-2	—	2	μA
Stand-by supply current	I <sub>DDS</sub>	CS1 to CS4 = V <sub>IH</sub> Non-selected	—	6	12	mA
	I <sub>DDSI</sub>	CS1 to CS4 ≥ V <sub>DD</sub> - 0.2V, V <sub>I</sub> = V <sub>DD</sub> - 0.2V or 0.2V	—	—	400	μA
Average operating current	I <sub>DDA</sub>	V <sub>I</sub> = V <sub>IL</sub> , V <sub>IH</sub> I <sub>I/O</sub> = 0mA t <sub>cy</sub> = Min	—	60	75	mA
Output leakage current	I <sub>LO</sub>	CS1 to CS4 = V <sub>IH</sub> or WE = V <sub>IL</sub> or OE = V <sub>IH</sub> V <sub>I/O</sub> = 0 to V <sub>DD</sub>	-2	—	2	μA
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -1.0mA	2.4	—	—	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2.1mA	—	—	0.4	V

\* T<sub>a</sub> = 25°C, V<sub>DD</sub> = 5.0V

### Terminal Capacitance

(f = 1MHz, T<sub>a</sub> = 25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input capacitance	C <sub>I</sub>		—	—	50	pF
Input/output capacitance	C <sub>I/O</sub>		—	—	50	pF

## ● AC Electrical Characteristics

### ○ Read cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=0$  to  $70^\circ C$ )

Parameter	Symbol	Conditions	Min	Max	Unit
Read cycle time	$t_{RC}$		100	—	ns
Address access time	$t_{ACC}$		—	100	ns
$\overline{CS}$ access time	$t_{ACS}^{*3}$	*1	—	100	ns
$\overline{OE}$ access time	$t_{OE}$		—	55	ns
$\overline{CS}$ output set time	$t_{CLZ}^{*3}$		10	—	ns
$\overline{CS}$ output floating time	$t_{CHZ}^{*3}$	*2	—	40	ns
$\overline{OE}$ output set time	$t_{OLZ}$	*1	5	—	ns
$\overline{OE}$ output floating time	$t_{OHZ}$	*2	—	40	ns
Output hold time	$t_{OH}$	*1	10	—	ns

### ○ Write cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=0$  to  $70^\circ C$ )

Parameter	Symbol	Conditions	Min	Max	Unit
Write cycle time	$t_{WC}$		100	—	ns
Chip select time	$t_{CW}^{*3}$		90	—	ns
Address valid time	$t_{AV}$		90	—	ns
Address setup time	$t_{AS}$	*1	0	—	ns
Write pulse width	$t_{WP}$		75	—	ns
Address hold time	$t_{WR}$		0	—	ns
Input data setup time	$t_{DW}$		45	—	ns
Input data hold time	$t_{DH}$		0	—	ns
$\overline{WE}$ output floating time	$t_{WHZ}$	*2	—	40	ns
$\overline{WE}$ output setup time	$t_{OW}$	*1	10	—	ns

#### \*1 Test Conditions

1. Input pulse level: 0.6V to 2.4V
2.  $t_r = t_f = 10ns$
3. Input and output timing reference levels: 1.5V
4. Output load:  $C_L = 100pF$

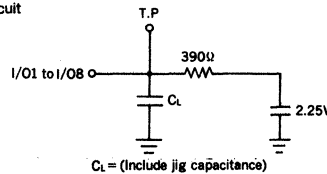
5. Output load:  $C_L = 100pF$  (Include scope & jig capacitance)

6. Circuit

\*3  $\overline{CS1}$  to  $\overline{CS4}$

#### \*2 $t_{CHZ}$ , $t_{OHZ}$ , $t_{WHZ}$ Test Conditions

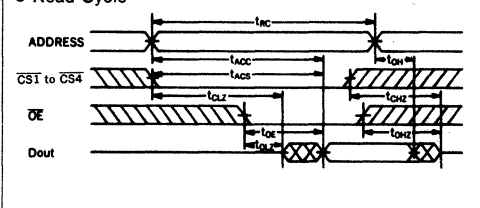
1. Input pulse level: 0.6V to 2.4V
2.  $t_r = t_f = 10ns$
3. Input timing reference levels: 1.5V
4. Output timing reference levels:  $\pm 200V$  (the level displaced from stable output voltage level)



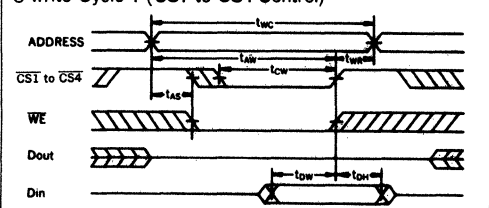
$C_L =$  (include jig capacitance)

## ● Timing Chart

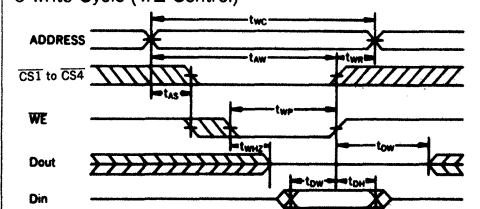
### ○ Read Cycle \*1



### ○ Write Cycle 1 ( $\overline{CS1}$ to $\overline{CS4}$ Control) \*2



### ○ Write Cycle ( $\overline{WE}$ Control) \*3



\*1 During read cycle time,  $\overline{WE}$  should be high.

\*2 During write cycle that is controlled by  $\overline{CS1}$  to  $\overline{CS4}$ , the output buffer changes to high impedance.  $\overline{CS1}$  to  $\overline{CS4}$  should be selected each one at read and write operation.

\*3 During write cycle that is controlled by  $\overline{WE}$ , the output buffer changes to high impedance. ( $\overline{OE} = "H"$ )



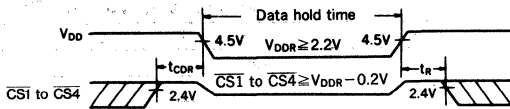
■ DATA RETENTION CHARACTERISTICS WITH LOW VOLTAGE POWER SUPPLY

V<sub>SS</sub>=0V, T<sub>a</sub>=0 to 70°C

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Data retention supply voltage	V <sub>DDR</sub>	CS1 to CS4 ≥ V <sub>DDR</sub> - 0.2V	2.2	—	5.5	V
Data retention current	I <sub>DDR</sub>	V <sub>DDR</sub> = 3.0V, CS1 to CS4 ≥ V <sub>DDR</sub> - 0.2V V <sub>I</sub> = V <sub>DDR</sub> - 0.2V or 0.2V	—	—	200	μA
Chip select data hold time	t <sub>CDR</sub>		0	—	—	ns
Operating recovery time	t <sub>R</sub>		t <sub>RC</sub> *	—	—	ns

\*t<sub>RC</sub> = Read cycle time

Data retention timing (CS1 to CS4 Control)



NOTE : When retaining data in stand-by mode the supply voltage can be lowered within a certain range.  
The read or write cycle are disabled when the supply voltage is low.

■ FUNCTION

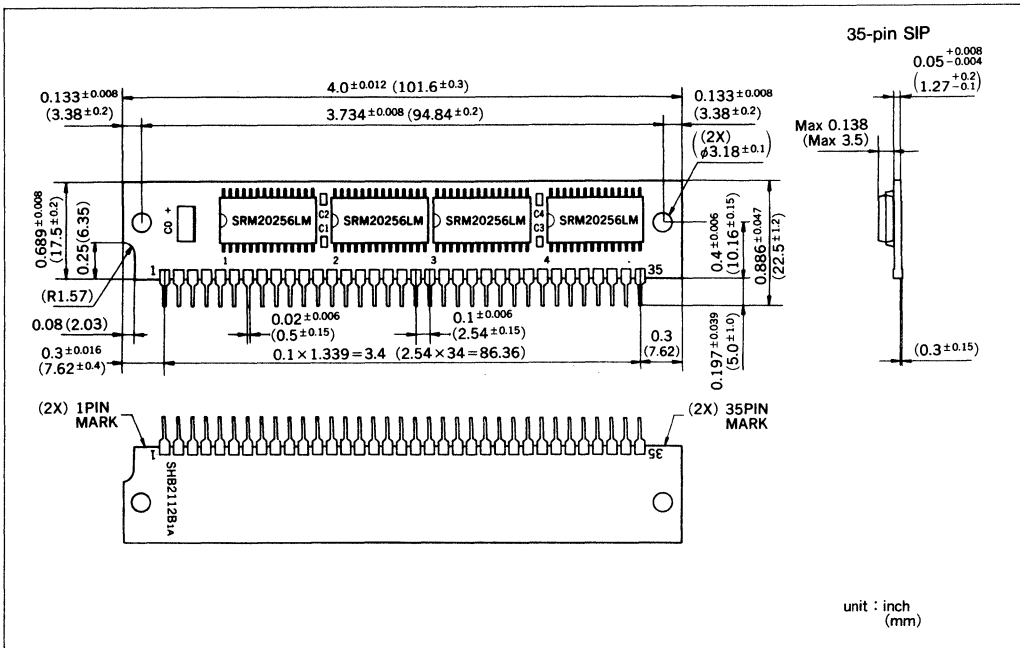
● Truth Table

CS1 to CS4 *	OE	WE	A0 to A14	DATA I/O	MODE	I <sub>DD</sub>
H	X	X	X	Hi-Z	Not selected	I <sub>DD</sub> , I <sub>DD</sub> S1, I <sub>DD</sub> R
Stable *	X	L	Stable	Data in	Write	I <sub>DD</sub> A
Stable *	L	H	Stable	Data out	Read	I <sub>DD</sub> A
Stable *	H	H	Stable	Hi-Z	Output disable	I <sub>DD</sub> A

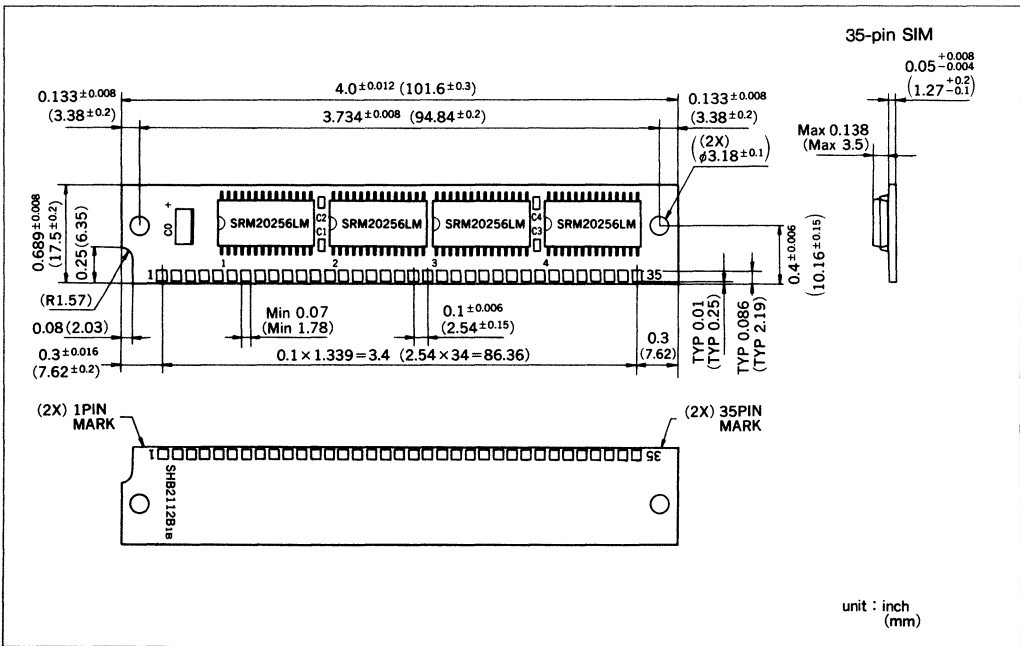
X : "H" or "L"

\* : These lines should be selected each one at read and write operation.

■ PACKAGE DIMENSIONS



SHB 2112B<sub>1A</sub>



SHB 2112B<sub>1B</sub>

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**■ CHARACTERISTICS CURVES**

Under measurement

# SHB2212B<sub>1A/1B</sub>

## CMOS 1M-BIT HYBRID STATIC RAM

- Low Supply Current
- Access Time 120ns
- 131,072 Words × 8 Bits Asynchronous
- Included Decoder

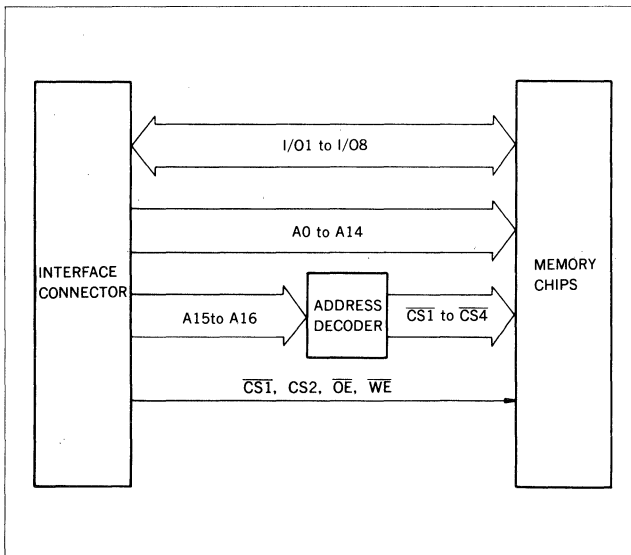
### DESCRIPTION

The SHB2212B<sub>1A/1B</sub> is a 131,072-word × 8-bit hybrid LSI module with four 256K SRAM (SRM20256LM) and a 3-8Line decoder. With low power consumption, the module can be used with applications which require a battery back-up. Since it is a static device, it does not requires a clock or refresh circuitry. The I/O control provides 3-state output, for data bus connection. These features provide solutions for a wide variety of applications, including microcomputers and other peripheral equipments.

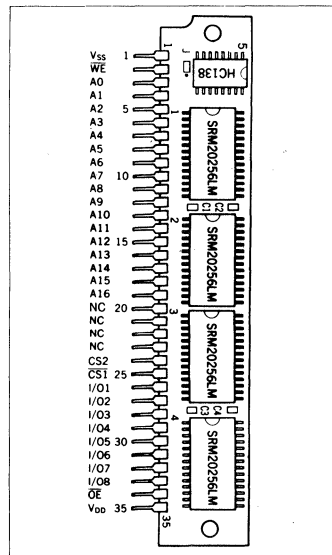
### FEATURES

- Hybrid CMOS LSI (with address decoder)
- 131,072-word × 8-bit memory density
- Mounting 4 pcs. of 256K static RAM (SRM20256LM<sub>10</sub>)
- 3-8 line decoder
- Access time 120ns (Max.)
- Single power supply-5volt
- 3-State output, with wired-or capability
- Printed-circuit-board (PCB) size 17.5mm × 101.6mm × 8.27mm (except pins)
- PCB .....SHB 2212B<sub>1A</sub> 35 pin SIP (Single inline package)  
SHB 2212B<sub>1B</sub> 35 pin SIM (Single inline module)

### BLOCK DIAGRAM



### PIN CONFIGURATION



## PIN DESCRIPTION

Pin name	Pin No.	Functions
V <sub>SS</sub>	1	Grounding pin. This GND is common in signal.
WE	2	<Write Enable> Data write signal line (negative logic). Data is written to the memory module at the positive edge of WE. When WE is "H", this module is read operation.
A0 to A16	3 to 19	<Address Input> 17-bit address input pin. (Positive logic)
NC	20 to 23	<No Connection>
CST	25	<Chip Select>
CS2	24	Memory module select signal line. Data is valid to read and write when CST is "L" (negative logic) and CS2 is "H" (positive logic). When CST is "H" or CS2 is "L" level, the module is in the non-selected mode. (I <sub>DD</sub> is standby mode.)
I/O1 to I/O8	26 to 33	<Data I/O> 8-bit bi-directional data signal bus. (Positive logic) This bus carries data for transfer between the equipment and the memory module.
OE	34	<Output Enable> Data read signal line (negative logic) from the equipment to the memory module. As Data I/O terminals are hi-impedance when CST="L", CS2="H", OE="H", the contention of data memory output bus can be avoided.
V <sub>DD</sub>	35	Positive power supply pin. (5V ± 10%) Normally, 5V is supplied.

## ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5* to 7.0	V
I/O voltage	V <sub>I/O</sub>	-0.5* to V <sub>DD</sub> + 0.3	V
Operating temperature	T <sub>opr</sub>	0 to 70	°C
Storage temperature	T <sub>stg</sub>	-40 to 100	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (Lead only)	—

\* V<sub>I</sub>, V<sub>I/O</sub> (Min.) = -1.0V at pulse width less than 50ns

## DC RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub> = 0V, Ta = 0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
	V <sub>SS</sub>		0	0	0	V
Input voltage	V <sub>IH</sub>		$\frac{3.85^{*2}}{2.4^{*3}}$	—	V <sub>DD</sub> + 0.3	V
	V <sub>IL</sub>		-0.3*1	0	0.8	V

\*1 V<sub>IL</sub> (Min.) = -1.0V at pulse width less than 50ns

\*2 A15, A16, CST, CS2 \*3 Others except A15, A16, CST, CS2

## ELECTRICAL CHARACTERISTICS

### DC Electrical Characteristics

(V<sub>DD</sub> = 5V ± 10%, V<sub>SS</sub> = 0V, Ta = 0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ*	Max	Unit
Input leakage current	I <sub>LI</sub>	V <sub>I</sub> = 0 to V <sub>DD</sub>	-2	—	2	μA
Stand-by supply current	I <sub>DDs</sub>	CST = V <sub>IH</sub> , CS2 = V <sub>IL</sub> Non-selected	—	—	7	mA
	I <sub>DDs1</sub>	CST = V <sub>DD</sub> - 0.2V, CS2 = 0.2V, V <sub>I</sub> = V <sub>DD</sub> - 0.2V or 0.2V	—	—	400	μA
Average operating current	I <sub>DDA</sub>	V <sub>I</sub> = V <sub>IL</sub> , V <sub>IH</sub> I <sub>I/O</sub> = 0mA t <sub>cyc</sub> = Min	—	65	80	mA
Output leakage current	I <sub>LO</sub>	CST = V <sub>IH</sub> or CS2 = V <sub>IL</sub> or WE = V <sub>IL</sub> or OE = V <sub>IH</sub> V <sub>I/O</sub> = 0 to V <sub>DD</sub>	-2	—	2	μA
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -1.0mA	2.4	—	—	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2.1mA	—	—	0.4	V

\* Ta = 25°C, V<sub>DD</sub> = 5.0V

### Terminal Capacitance

(f = 1MHz, Ta = 25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input capacitance	C <sub>I</sub>		—	—	50	pF
Input/output capacitance	C <sub>I/O</sub>		—	—	50	pF

## ● AC Electrical Characteristics

### ○ Read cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=0\text{to}70^\circ\text{C}$ )

Parameter	Symbol	Conditions	Min	Max	Unit
Read cycle time	$t_{RC}$		120	—	ns
Address access time	$t_{ACC}$		—	120	ns
$\overline{\text{CS1}}$ access time	$t_{ACS1}$	*1	—	120	ns
CS2 access time	$t_{ACS2}$		—	120	ns
$\overline{\text{OE}}$ access time	$t_{OE}$		—	65	ns
$\overline{\text{CS1}}$ output set time	$t_{CLZ1}$		10	—	ns
$\overline{\text{CS1}}$ output floating time	$t_{CHZ1}$	*2	—	65	ns
CS2 output set time	$t_{CLZ2}$	*1	10	—	ns
CS2 output floating time	$t_{CHZ2}$	*2	—	65	ns
$\overline{\text{OE}}$ output set time	$t_{OLZ}$	*1	5	—	ns
$\overline{\text{OE}}$ output floating time	$t_{OHZ}$	*2	—	65	ns
Output hold time	$t_{OH}$	*1	10	—	ns

### ○ Write cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=0\text{to}70^\circ\text{C}$ )

Parameter	Symbol	Conditions	Min	Max	Unit
Write cycle time	$t_{WC}$		120	—	ns
Chip select time ( $\overline{\text{CS1}}$ )	$t_{CW1}$		100	—	ns
Chip select time (CS2)	$t_{CW2}$		100	—	ns
Address valid time	$t_{AV}$		100	—	ns
Address setup time	$t_{AS}$	*1	10	—	ns
Write pulse width	$t_{WP}$		90	—	ns
Address hold time	$t_{WR}$		10	—	ns
Input data setup time	$t_{DW}$		60	—	ns
Input data hold time	$t_{DH}$		10	—	ns
$\overline{\text{WE}}$ output floating time	$t_{WHZ}$	*2	—	65	ns
$\overline{\text{WE}}$ output setup time	$t_{OW}$	*1	10	—	ns

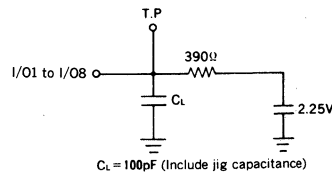
#### \*1 Test Conditions

- Input pulse level: 0.4V to 3.85V..... $\overline{\text{CS1}}$ , CS2, A15, A16  
0.6V to 2.4V .....Other except  $\overline{\text{CS1}}$ , CS2, A15, A16
- $t_r = t_f = 10\text{ns}$
- Input and output timing reference levels: 1.5V
- Output load:  $C_L = 100\text{pF}$

- Output load:  $C_L = 100\text{pF}$  (Include scope & jig capacitance)
- Circuit

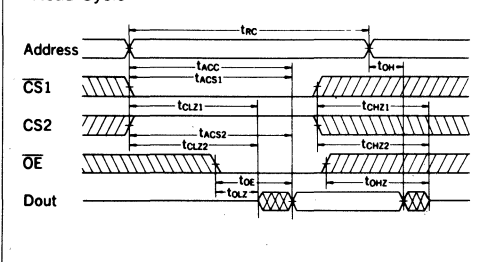
#### \*2 $t_{CHZ}$ , $t_{OHZ}$ , $t_{WHZ}$ Test Conditions

- Input pulse level: 0.4V to 3.85V..... $\overline{\text{CS1}}$ , CS2, A15, A16  
0.6V to 2.4V .....Other except  $\overline{\text{CS1}}$ , CS2, A15, A16
- $t_r = t_f = 10\text{ns}$
- Input and output timing reference levels: 1.5V
- Output timing reference levels:  $\pm 200\text{mV}$  (the level displaced from stable output voltage level)

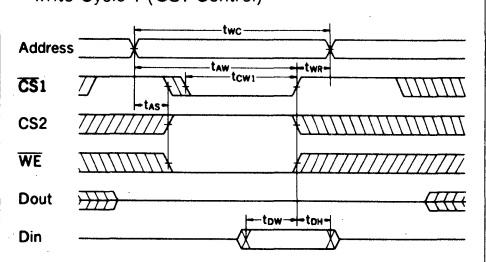


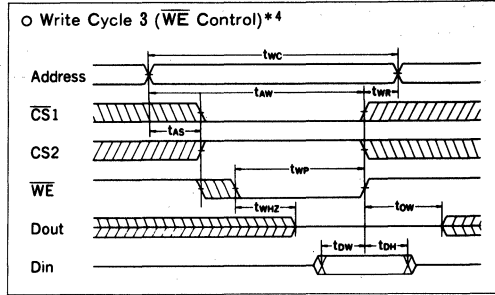
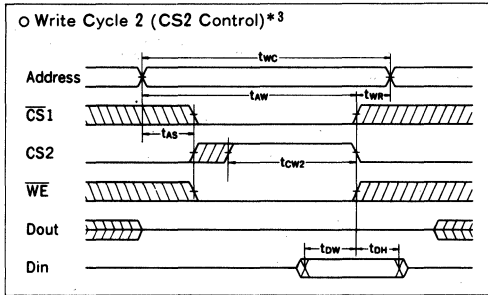
## ● Timing Chart

### ○ Read Cycle \*1



### ○ Write Cycle 1 ( $\overline{\text{CS1}}$ Control) \*2





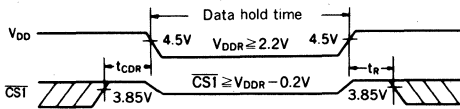
- \*1 During read cycle time,  $\overline{WE}$  should be high.
- \*2 During write cycle that is controlled by  $\overline{CS1}$ , the output buffer changes to high impedance.
- \*3 During write cycle that is controlled by  $\overline{CS2}$ , the output buffer changes to high impedance.
- \*4 During write cycle that is controlled by  $\overline{WE}$ , the output buffer changes to high impedance.  
(OE="H")

**DATA RETENTION CHARACTERISTICS WITH LOW VOLTAGE POWER SUPPLY** ( $V_{SS}=0V$ ,  $T_a=0$  to  $70^\circ C$ )

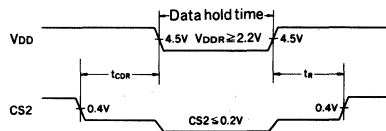
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Data retention supply voltage	$V_{DDR}$	$\overline{CS1} \geq V_{DDR} - 0.2V$ or $CS2 \leq 0.2V$	2.2	—	5.5	V
Data retention current	$I_{DDR}$	$V_{DDR} = 3V$ , $\overline{CS1} \geq V_{DDR} - 0.2V$ , or $CS2 \leq 0.2V$ , $V_i = V_{DDR} - 0.2V$ or $0.2V$	—	—	240	$\mu A$
Chip select data hold time	$t_{CDR}$		30	—	—	ns
Operating recovery time	$t_R$		$t_{RC}^*$	—	—	ns

\* $t_{RC}$  = Read cycle time

**Data retention timing ( $\overline{CS1}$  Control)**



**Data retention timing 2 (CS2 Control)**



NOTE : When retaining data in stand-by mode the supply voltage can be lowered within a certain range.  
The read or write cycle are disabled when the supply voltage is low.

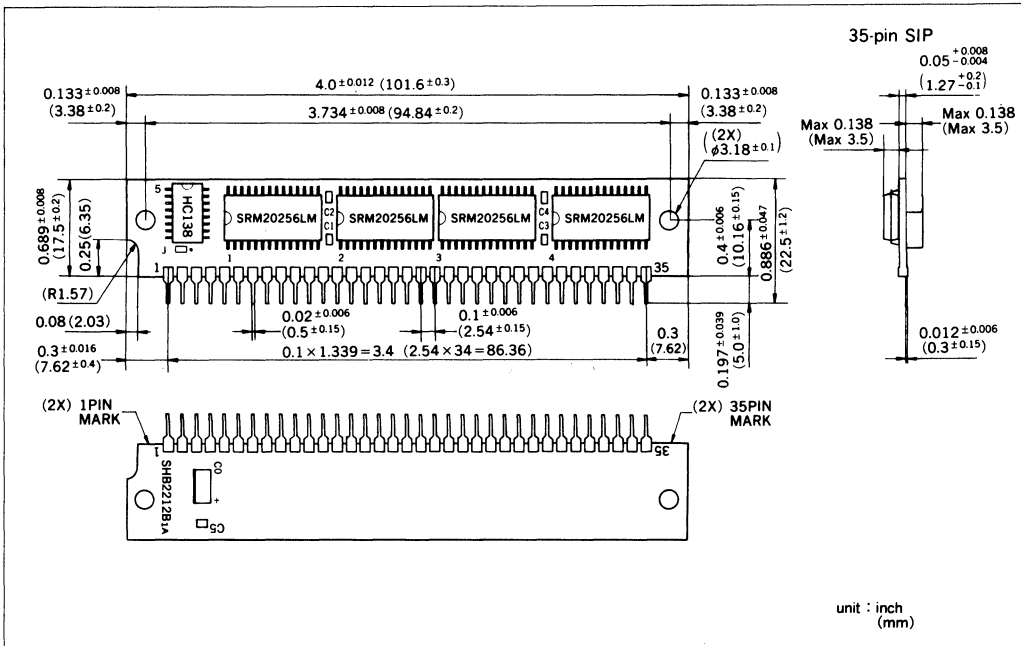
**FUNCTION**

**Truth Table**

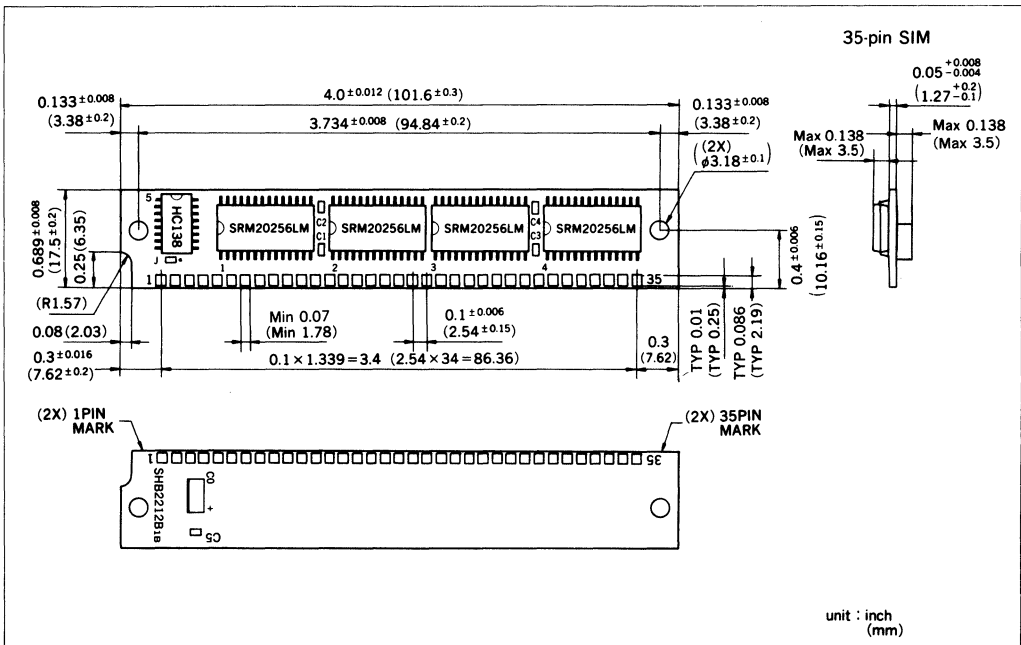
$\overline{CS1}$	CS2	$\overline{OE}$	$\overline{WE}$	A0 to A16	DATA I/O	MODE	$I_{DD}$
H	X	X	X	X	Hi-Z	Not selected	$I_{DDs}$ , $I_{DDs1}$ , $I_{DDR}$
X	L	X	X	X	Hi-Z	Not selected	$I_{DDs}$ , $I_{DDs1}$ , $I_{DDR}$
L	H	X	L	Stable	Data in	Write	$I_{DDA}$
L	H	L	H	Stable	Data out	Read	$I_{DDA}$
L	H	H	H	Stable	Hi-Z	Output disable	$I_{DDA}$

X : "H" or "L"

# PACKAGE DIMENSIONS



SHB2212B1A



SHB2212B1B



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**■ CHARACTERISTICS CURVES**

**Under measurement**

# SHB2125B<sub>0A/0B</sub>

## CMOS 2M-BIT HYBRID STATIC RAM

- Low Supply Current
- Access Time 120ns
- 262,144 Word × 8 Bits Asynchronous

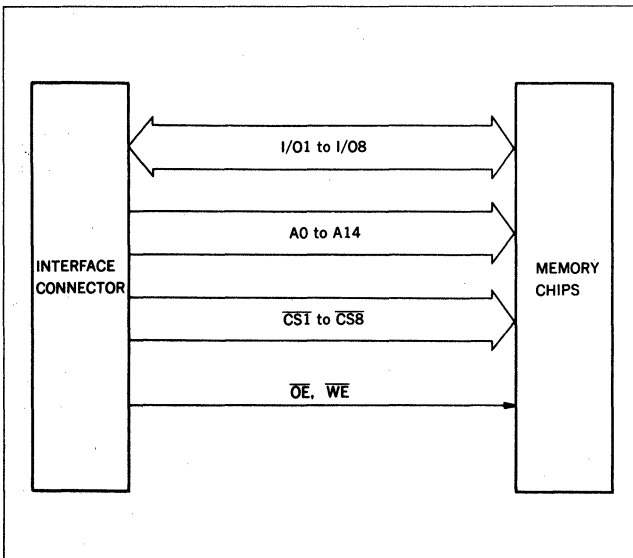
**DESCRIPTION**

The SHB2125B<sub>0A/0B</sub> is a 262,144-word × 8-bit hybrid LSI module with eight 256K SRAM (SRM20256LM). With low power consumption, the module can be used with applications which require a battery back-up. Since it is a static device, it does not require a clock or refresh circuitry. The I/O control provides 3-state output, for data bus connection. These features provide solutions for a wide variety of applications, including microcomputers and other peripheral equipments.

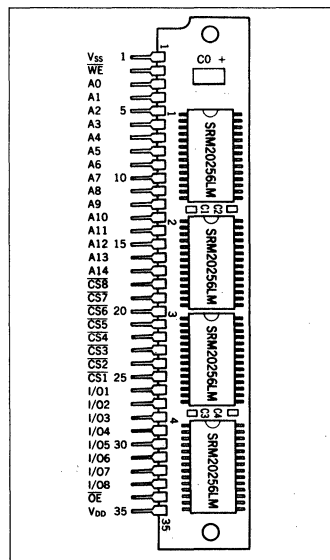
**FEATURES**

- Hybrid CMOS LSI
- 262,144-word × 8-bit memory density
- Mounting 8 pcs. of 256K static RAM (SRM20256LM<sub>12</sub>)
- Access time 120ns (Max)
- 3-State output, with wired-or capability
- Single power supply-5volt
- Printed-circuit-board (PCB) size 17.5mm × 101.6mm × 8.27mm (except pins)
- PCB .....SHB2125B<sub>0A</sub> 35 pin SIP (Single inline package)  
SHB2125B<sub>0B</sub> 35 pin SIM (Single inline module)

**BLOCK DIAGRAM**



**PIN CONFIGURATION**



## PIN DESCRIPTION

Pin name	Pin No.	Functions
V <sub>SS</sub>	1	Grounding pin. This GND is common in signal.
WE	2	<Write Enable> Data write signal line (negative logic). Data is written to the memory module at the positive edge of WE. When WE is "H", this module is read operation.
A0 to A14	3 to 17	<Address Input> 15-bit address input pin. (Positive logic)
CS1	25	<Chip Select> These signal line (negative active) are module select line. These line should be selected each one at read and write operation. Each CS is available for each 32kB RAM. That is to say, 256kB is divide by 8 CS signal. EX. Data will be valid to read and write when CS1 is "L" and CS2 to CS8 are "H". If CS1 to CS8 are "H", this module is non-selected mode (I <sub>DD</sub> is stand-by mode)
CS2	24	
...	...	
CS8	18	
I/O1 to I/O8	26 to 33	<Data I/O> Inputs or outputs 8-bit of data. This pin provides an input with WE low and an output with WE high. Also, it has low impedance with OE low and high impedance with OE high.
OE	34	<Output Enable> Data read signal line (negative logic) from equipment to the memory module. As Data I/O terminals are hi-impedance when OE = "H", the contention of data memory output bus can be avoided.
V <sub>DD</sub>	35	Positive power supply pin. (5V±10%) Normally, 5V is supplied.

## ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5* to 7.0	V
I/O voltage	V <sub>I/O</sub>	-0.5* to V <sub>DD</sub> +0.3	V
Operating temperature	T <sub>opr</sub>	0 to 70	°C
Storage temperature	T <sub>stg</sub>	-40 to 100	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (Lead only)	—

\* V<sub>I</sub>, V<sub>I/O</sub> (Min.) = -1.0V at pulse width less than 50ns

## DC RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub> = 0V, T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
	V <sub>SS</sub>		0	0	0	V
Input voltage	V <sub>IH</sub>		2.4	—	V <sub>DD</sub> +0.3	V
	V <sub>IL</sub>		-0.3*	0	0.8	V

\* V<sub>IL</sub> (Min.) = -1.0V at pulse width less than 50ns

## ELECTRICAL CHARACTERISTICS

### DC Electrical Characteristics

(V<sub>DD</sub> = 5V±10%, V<sub>SS</sub> = 0V, T<sub>a</sub> = 0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ*	Max	Unit
Input leakage current	I <sub>LI</sub>	V <sub>I</sub> = 0 to V <sub>DD</sub>	-2	—	2	μA
Stand-by supply current	I <sub>DDS</sub>	CS1 to CS8 = V <sub>IH</sub> , Non-selected	—	12	24	mA
	I <sub>DDSI</sub>	CS1 to CS8 = V <sub>DD</sub> -0.2V, V <sub>I</sub> = V <sub>DD</sub> -0.2V or 0.2V	—	—	800	μA
Average operating current	I <sub>DDA</sub>	V <sub>I</sub> = V <sub>IL</sub> , V <sub>IH</sub> I <sub>I/O</sub> = 0mA t <sub>cyc</sub> = Min	—	55	70	mA
Output leakage current	I <sub>LO</sub>	CS1 to CS8 = V <sub>IH</sub> or WE = V <sub>IL</sub> or OE = V <sub>IH</sub> , V <sub>I/O</sub> = 0 to V <sub>DD</sub>	-2	—	2	μA
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -1.0mA	2.4	—	—	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2.1mA	—	—	0.4	V

\* T<sub>a</sub> = 25°C, V<sub>DD</sub> = 5.0V

### Terminal Capacitance

(f = 1MHz, T<sub>a</sub> = 25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input capacitance	C <sub>I</sub>		—	—	80	pF
Input/output capacitance	C <sub>I/O</sub>		—	—	80	pF

● AC Electrical Characteristics

○ Read cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=0$  to  $70^\circ C$ )

Parameter	Symbol	Conditions	Min	Max	Unit
Read cycle time	$t_{RC}$	* 1	120	—	ns
Address access time	$t_{ACC}$		—	120	ns
CS access time	$t_{ACS}^{*3}$		—	120	ns
OE access time	$t_{OE}$		—	60	ns
CS output set time	$t_{CLZ}^{*3}$	* 2	10	—	ns
CS output floating time	$t_{CHZ}^{*3}$		—	45	ns
OE output set time	$t_{OLZ}$	* 1	5	—	ns
OE output floating time	$t_{OHZ}$	* 2	—	45	ns
Output hold time	$t_{OH}$	* 1	10	—	ns

○ Write cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=0$  to  $70^\circ C$ )

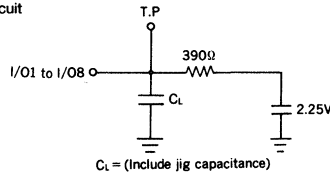
Parameter	Symbol	Conditions	Min	Max	Unit
Write cycle time	$t_{WC}$	* 1	120	—	ns
Chip select time	$t_{CW}^{*3}$		105	—	ns
Address valid time	$t_{AW}$		105	—	ns
Address setup time	$t_{AS}$		0	—	ns
Write pulse width	$t_{WP}$		80	—	ns
Address hold time	$t_{WR}$		0	—	ns
Input data setup time	$t_{DW}$		50	—	ns
Input data hold time	$t_{DH}$		0	—	ns
$\overline{WE}$ output floating time	$t_{WHZ}$	* 2	—	45	ns
$\overline{WE}$ output setup time	$t_{OW}$	* 1	10	—	ns

\* 1 Test Conditions

1. Input pulse level: 0.6V to 2.4V
2.  $t_r = t_f = 10ns$
3. Input and output timing reference levels: 1.5V
4. Output load:  $C_L = 100pF$

5. Output load:  $C_L = 100pF$  (Include scope & jig capacitance)

6. Circuit



$C_L =$  (Include jig capacitance)

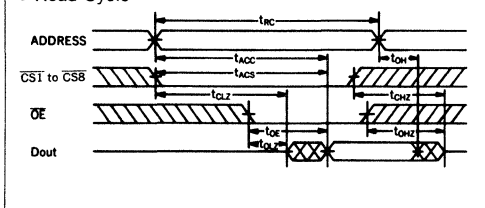
\* 3 CS1 to CS8

\* 2  $t_{CHZ}$ ,  $t_{OHZ}$ ,  $t_{WHZ}$  Test Conditions

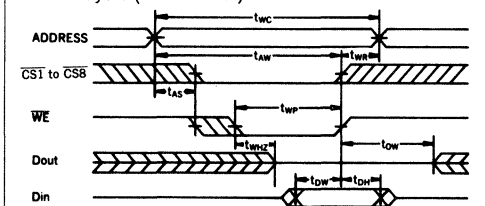
1. Input pulse level: 0.6V to 2.4V
2.  $t_r = t_f = 10ns$
3. Input timing reference levels: 1.5V
4. Output timing reference levels:  $\pm 200V$  (the level displaced from stable output voltage level)

● Timing Chart

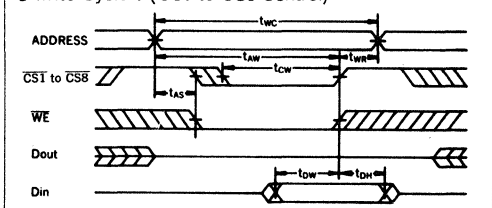
○ Read Cycle \* 1



○ Write Cycle ( $\overline{WE}$  Control) \* 3



○ Write Cycle 1 (CS1 to CS8 Control) \* 2



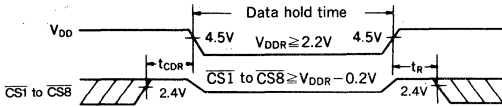
- \* 1 During read cycle time,  $\overline{WE}$  should be high.
- \* 2 During write cycle that is controlled by CS1 to CS8, the output buffer changes to high impedance. CS1 to CS8 should be selected each one at read and write operation.
- \* 3 During write cycle that is controlled by  $\overline{WE}$ , the output buffer changes to high impedance. ( $OE = "H"$ )

**DATA RETENTION CHARACTERISTICS WITH LOW VOLTAGE POWER SUPPLY** ( $V_{SS}=0V$ ,  $T_a=0$  to  $70^{\circ}C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Data retention supply voltage	$V_{DDR}$	$CS1$ to $CS8 \geq V_{DDR} - 0.2V$	2.2	—	5.5	V
Data retention current	$I_{DDR}$	$V_{DDR} = 3V$ , $CS1$ to $CS8 \geq V_{DDR} - 0.2V$ $V_i = V_{DDR} - 0.2V$ or $0.2V$	—	—	400	$\mu A$
Chip select data hold time	$t_{CDR}$		0	—	—	ns
Operating recovery time	$t_R$		$t_{RC}^*$	—	—	ns

\*  $t_{RC}$  = Read cycle time

**Data Retention timing 1** ( $CS1$  to  $CS8$  control)



NOTE: When retaining data in stand-by mode supply voltage can be lowered within a certain range.  
The read or write cycle are disabled when the supply voltage is low.

**FUNCTION**

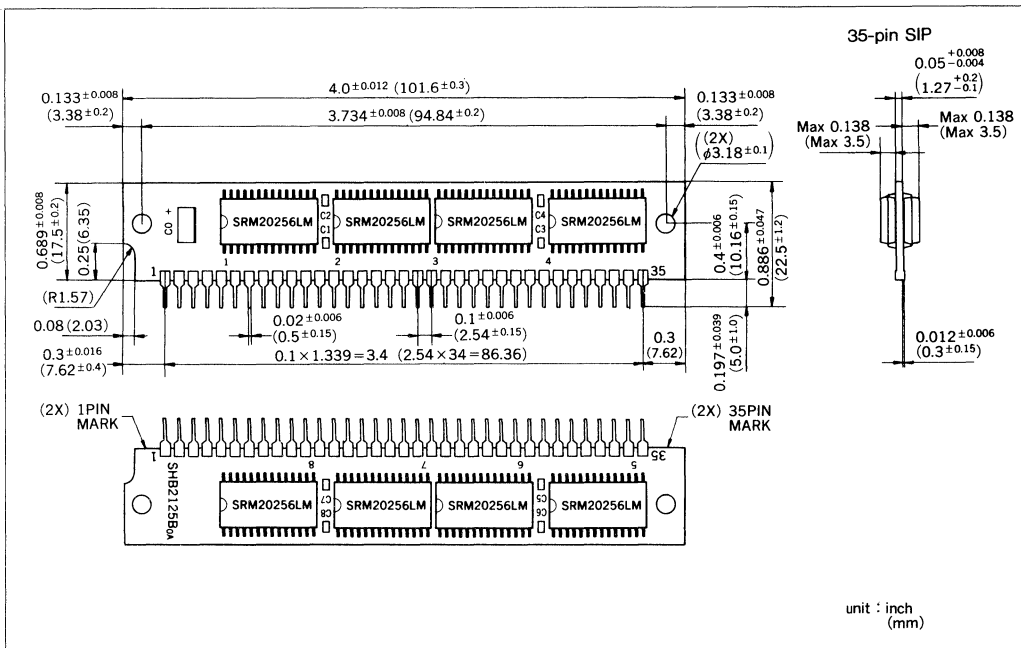
● **Truth Table**

$CS1$ to $CS8$ *	$\overline{OE}$	$\overline{WE}$	A0 to A14	DATA I/O	MODE	$I_{DD}$
H	x	x	x	Hi-Z	Not selected	$I_{DDs}$ $I_{DDs1}$ $I_{DDR}$
Stable *	x	L	Stable	Data in	Write	$I_{DDA}$
Stable *	L	H	Stable	Data out	Read	$I_{DDA}$
Stable *	H	H	Stable	Hi-Z	Output disable	$I_{DDA}$

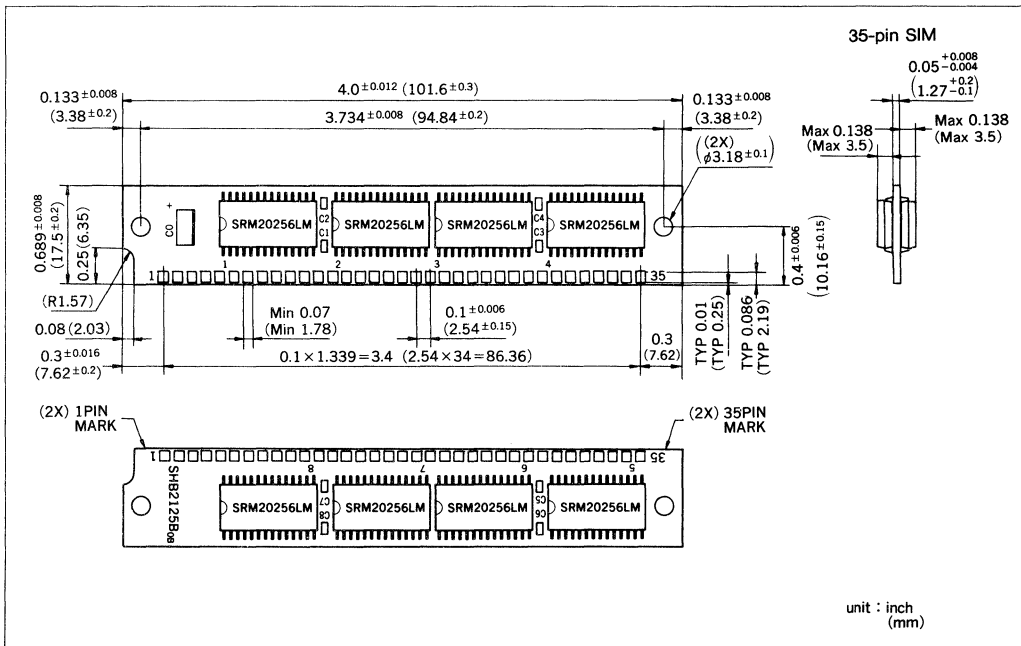
x: "H" or "L"

\*: These lines should be selected each one at read and write operation.

■ PACKAGE DIMENSIONS



SHB2125B0A



SHB2125B0B

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■ CHARACTERISTICS CURVES

Under measurement

# SHB2225B<sub>0A/0B</sub>

## CMOS 2M-BIT HYBRID STATIC RAM

- Low Supply Current
- Access Time 150ns
- 262,144 Words × 8 Bits Asynchronous
- Included Decoder

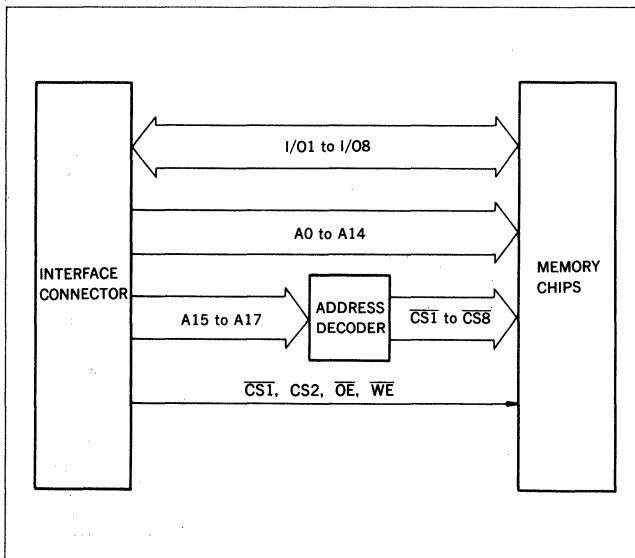
### DESCRIPTION

The SHB2225B<sub>0A/0B</sub> is a 262,144-word × 8-bit hybrid LSI module with eight 256K SRAM (SRM20256LM) and a 3-8Line decoder. With low power consumption, the module can be used with applications which require a battery back-up. Since it is a static device, it does not require a clock or refresh circuitry. The I/O control provides 3-state output, for data bus connection. These features provide solutions for a wide variety of applications, including microcomputers and other peripheral equipments.

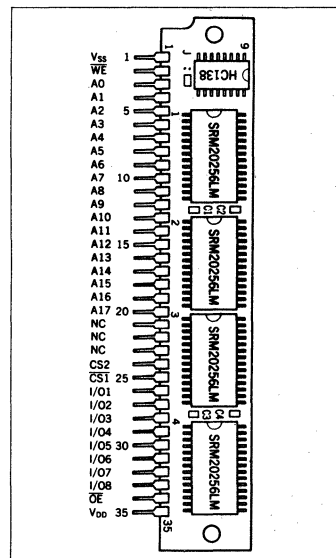
### FEATURES

- Hybrid CMOS LSI
- 262,144-word × 8-bit memory density
- Mounting 8 pcs. of 256K static RAM (SRM20256LM<sub>12</sub>)
- 3-8 line decoder
- Access time 150ns
- Single power supply-5volt
- 3-State output, with wired-or capability
- Printed-circuit-board (PCB) size 17.5mm × 101.6mm × 8.27mm (except pins)
- PCB .....SHB2225B<sub>0A</sub> 35 pin SIP (Single inline package)  
SHB2225B<sub>0B</sub> 35 pin SIM (Single inline module)

### BLOCK DIAGRAM



### PIN CONFIGURATION





## PIN DESCRIPTION

Pin name	Pin No.	Functions
V <sub>SS</sub>	1	Grounding pin. This GND is common in signal.
WE	2	<Write Enable> Data write signal line (negative logic). Data is written to the memory module at the positive edge of WE. When WE is "H", this module is read operation.
A0~A17	3 to 20	<Address Input> 18-bit address input pin. (Positive logic)
NC	21 to 29	<No Connection>
CS1	25	<Chip Select>
CS2	24	Memory module select signal line. Data is valid for read and write when CS1 is "L" (negative logic) and CS2 is "H" (positive logic). When CS1 is "H" or CS2 is "L" level, the module is in the non-selected mode. (I <sub>DD</sub> is stand-by mode.)
I/O1 to I/O8	26 to 33	<Data I/O> 8-bit bi-directional data signal bus. (Positive logic) This bus carries data for transfer between the equipment and the memory module.
OE	34	<Output Enable> Data read signal line (negative logic) from the equipment to the memory module. As Data I/O terminals are hi-impedance when CS1="L", CS2="H", OE="H", the contention of data memory output bus can be avoided.
V <sub>DD</sub>	35	Positive power supply pin. (5V±10%) Normally, 5V is supplied.

## ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub>=0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5* to 7.0	V
I/O voltage	V <sub>I/O</sub>	-0.5* to V <sub>DD</sub> +0.3	V
Operating temperature	T <sub>opr</sub>	0 to 70	°C
Storage temperature	T <sub>stg</sub>	-40 to 100	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (Lead only)	—

\* V<sub>L</sub> (Min.) = -1.0V at pulse width less than 50ns

## DC RECOMMENDED OPERATING CONDITIONS

(V<sub>SS</sub>=0V, Ta=0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
	V <sub>SS</sub>		0	0	0	V
Input voltage	V <sub>IH</sub>		3.85** 2.4**	—	V <sub>DD</sub> +0.3	V
	V <sub>IL</sub>		-0.3*1	0	0.8	V

\* 1 V<sub>L</sub> (Min.) = -1.0V at pulse width less than 50ns \*2 A15, A16, A17, CS1, CS2 \*3 Others except A15, A16, A17, CS1, CS2

## ELECTRICAL CHARACTERISTICS

### DC Electrical Characteristics

(V<sub>DD</sub>=5V±10%, V<sub>SS</sub>=0V, Ta=0 to 70°C)

Parameter	Symbol	Conditions	Min	Typ*	Max	Unit
Input leakage current	I <sub>LI</sub>	V <sub>I</sub> =0 to V <sub>DD</sub>	-2	—	2	μA
Stand-by supply current	I <sub>DDS</sub>	CS1=V <sub>IH</sub> , CS2=V <sub>IL</sub> Non-Selected	—	—	10	mA
	I <sub>DDSI</sub>	CS1≥V <sub>DD</sub> -0.2V, CS2≤0.2V, V <sub>I</sub> =V <sub>DD</sub> -0.2V or 0.2V	—	—	800	μA
Average operating current	I <sub>DDA</sub>	V <sub>I</sub> =V <sub>IL</sub> , V <sub>IH</sub> I <sub>I/O</sub> =0mA t <sub>cyc</sub> =Min	—	60	75	mA
Output leakage current	I <sub>LO</sub>	CS1=V <sub>IH</sub> or CS2=V <sub>IL</sub> or WE=V <sub>IL</sub> or OE=V <sub>IH</sub> V <sub>I/O</sub> =0 to V <sub>DD</sub>	-2	—	2	μA
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> =-1.0mA	2.4	—	—	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> =2.1mA	—	—	0.4	V

\* Ta=25°C, V<sub>DD</sub>=5.0V

### Terminal Capacitance

(f=1MHz, Ta=25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input capacitance	C <sub>I</sub>		—	—	80	pF
Input/output capacitance	C <sub>I/O</sub>		—	—	80	pF

## ● AC Electrical Characteristics

### ○ Read cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=0\text{to}70^\circ\text{C}$ )

Parameter	Symbol	Conditions	Min	Max	Unit	
Read cycle time	$t_{RC}$	*1	150	—	ns	
Address access time	$t_{ACC}$		—	150	ns	
CS1 access time	$t_{ACS1}$		—	150	ns	
CS2 access time	$t_{ACS2}$		—	150	ns	
OE access time	$t_{OE}$		—	70	ns	
CS1 output set time	$t_{CLZ1}$		10	—	ns	
CS1 output floating time	$t_{CHZ1}$		*2	—	70	ns
CS2 output set time	$t_{CLZ2}$		*1	10	—	ns
CS2 output floating time	$t_{CHZ2}$		*2	—	70	ns
OE output set time	$t_{OLZ}$		*1	5	—	ns
OE output floating time	$t_{OHZ}$	*2	—	70	ns	
Output hold time	$t_{OH}$	*1	10	—	ns	

### ○ Write cycle

( $V_{DD}=5V \pm 10\%$ ,  $V_{SS}=0V$ ,  $T_a=0\text{to}70^\circ\text{C}$ )

Parameter	Symbol	Conditions	Min	Max	Unit
Write cycle time	$t_{WC}$	*1	150	—	ns
Chip select time (CS1)	$t_{CW1}$		130	—	ns
Chip select time (CS2)	$t_{CW2}$		130	—	ns
Address valid time	$t_{AW}$		130	—	ns
Address setup time	$t_{AS}$		10	—	ns
Write pulse width	$t_{WP}$		100	—	ns
Address hold time	$t_{WR}$		10	—	ns
Input data setup time	$t_{DW}$		70	—	ns
Input data hold time	$t_{DH}$		10	—	ns
WE output floating time	$t_{WHZ}$		*2	—	70
WE output setup time	$t_{OW}$	*1	10	—	ns

#### \*1 Test Conditions

- Input pulse level: 0.4V to 3.85V ..... CS1, CS2, A15, A16, A17  
0.6V to 2.4V ..... Other except CS1, CS2, A15, A16, A17

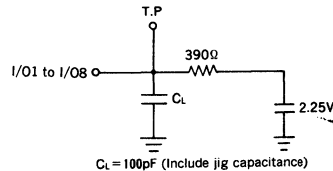
- $t_r = t_f = 10\text{ns}$
- Input and output timing reference levels: 1.5V
- Output load:  $C_L = 100\text{pF}$

#### \*2 $t_{CHZ}$ , $t_{OHZ}$ , $t_{WHZ}$ Test Conditions

- Input pulse level: 0.4V to 3.85V ..... CS1, CS2, A15, A16, A17  
0.6V to 2.4V ..... Other except CS1, CS2, A15, A16, A17
- $t_r = t_f = 10\text{ns}$
- Input and output timing reference levels: 1.5V
- Output timing reference levels:  $\pm 200\text{mV}$  (the level displaced from stable output voltage level)

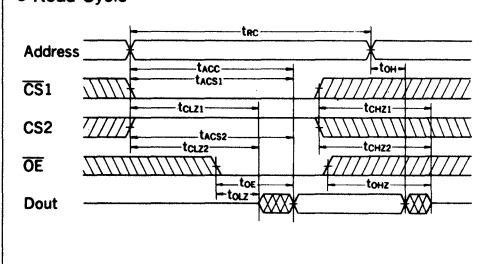
5. Output load:  $C_L = 100\text{pF}$  (Include scope & jig capacitance)

6. Circuit

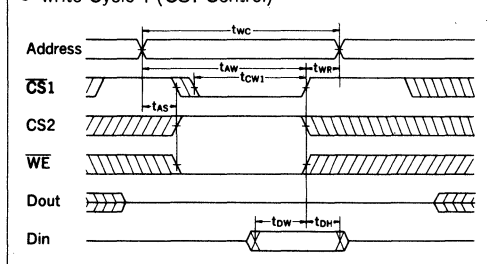


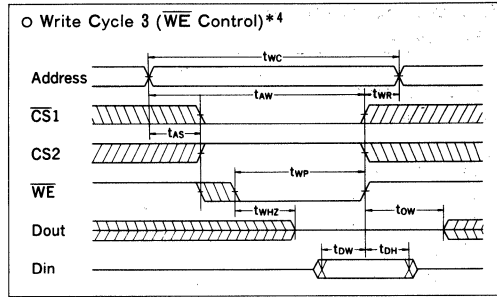
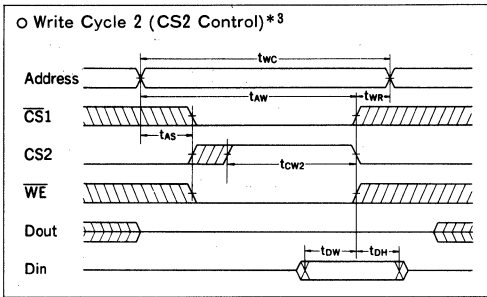
## ● Timing Chart

### ○ Read Cycle \*1



### ○ Write Cycle 1 (CS1 Control) \*2





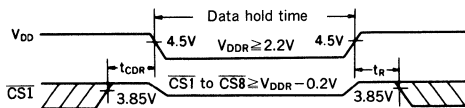
- \*1 During read cycle time,  $\overline{WE}$  should be high.
- \*2 During write cycle that is controlled by CS1, the output buffer changes to high impedance.
- \*3 During write cycle that is controlled by CS2, the output buffer changes to high impedance.
- \*4 During write cycle that is controlled by WE, the output buffer changes to high impedance. ( $\overline{OE} = "H"$ )

**DATA RETENTION CHARACTERISTICS WITH LOW VOLTAGE POWER SUPPLY** ( $V_{SS} = 0V$ ,  $T_a = 0$  to  $70^\circ C$ )

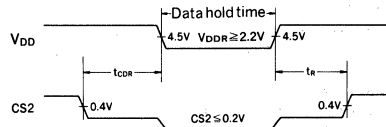
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Data retention supply voltage	$V_{DDR}$	$\overline{CS1} \geq V_{DDR} - 0.2V$ or $CS2 \leq 0.2V$	2.2	—	5.5	V
Data retention current	$I_{DDR}$	$V_{DDR} = 3V$ , $\overline{CS1} \geq V_{DDR} - 0.2V$ , or $CS2 \leq 0.2V$ , $V_I = V_{DDR} - 0.2V$ or $0.2V$	—	—	440	$\mu A$
Chip select data hold time	$t_{CDR}$		30	—	—	ns
Operating recovery time	$t_R$		$t_{RC}^*$	—	—	ns

\* $t_{RC}$  = Read cycle time

Data retention timing 1 ( $\overline{CS1}$  Control)



Data retention timing 2 (CS2 Control)



NOTE : When retaining data in stand-by mode the supply voltage can be lowered within a certain range. The read or write cycle are disabled when the supply voltage is low.

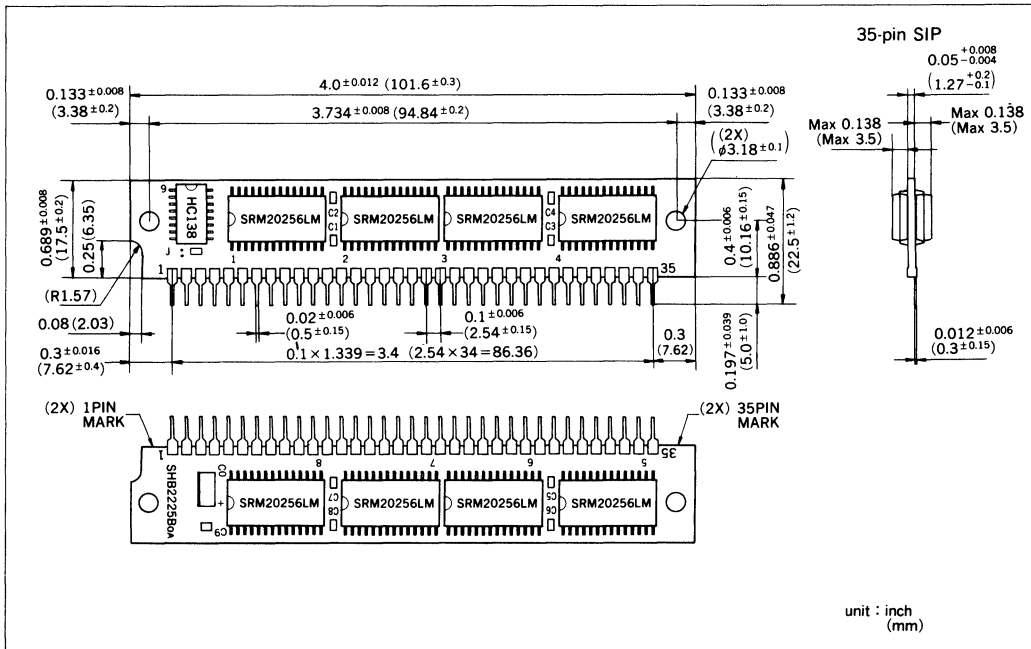
**FUNCTION**

● Truth Table

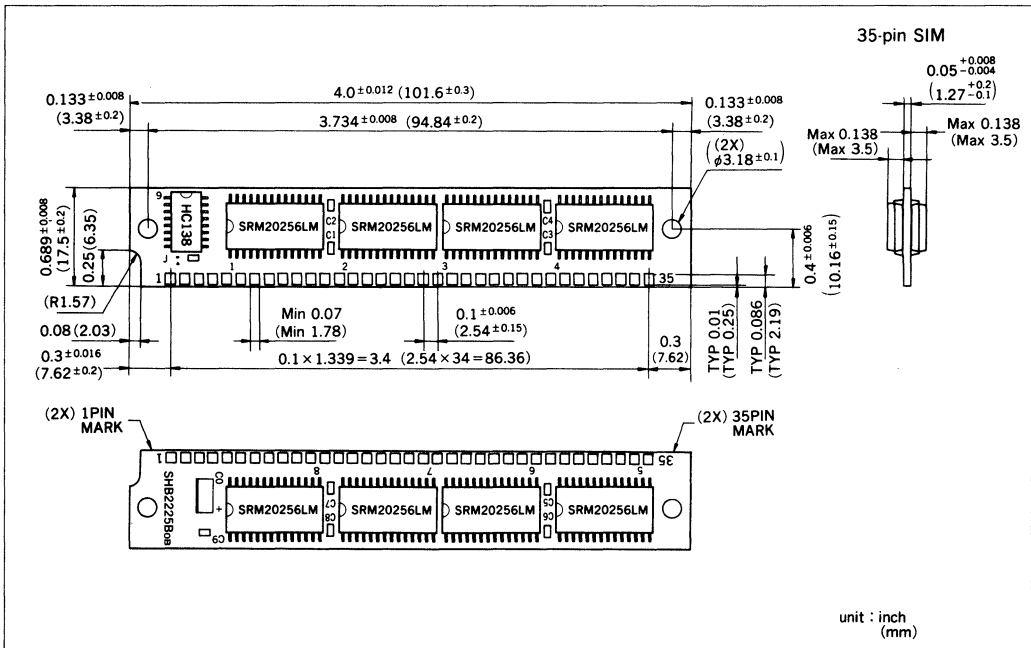
$\overline{CS1}$	CS2	$\overline{OE}$	$\overline{WE}$	A0 to A17	DATA I/O	MODE	$I_{DD}$
H	x	x	x	x	Hi-Z	Not selected	$I_{DDs}$ $I_{DDs1}$ $I_{DDR}$
x	L	x	x	x	Hi-Z	Not selected	$I_{DDs}$ $I_{DDs1}$ $I_{DDR}$
L	H	x	L	Stable	Data in	Write	$I_{DDA}$
L	H	L	H	Stable	Data out	Read	$I_{DDA}$
L	H	H	H	Stable	Hi-Z	Output disable	$I_{DDA}$

x : "H" or "L"

# PACKAGE DIMENSIONS



SHB2225B0A



SHB2225B0B

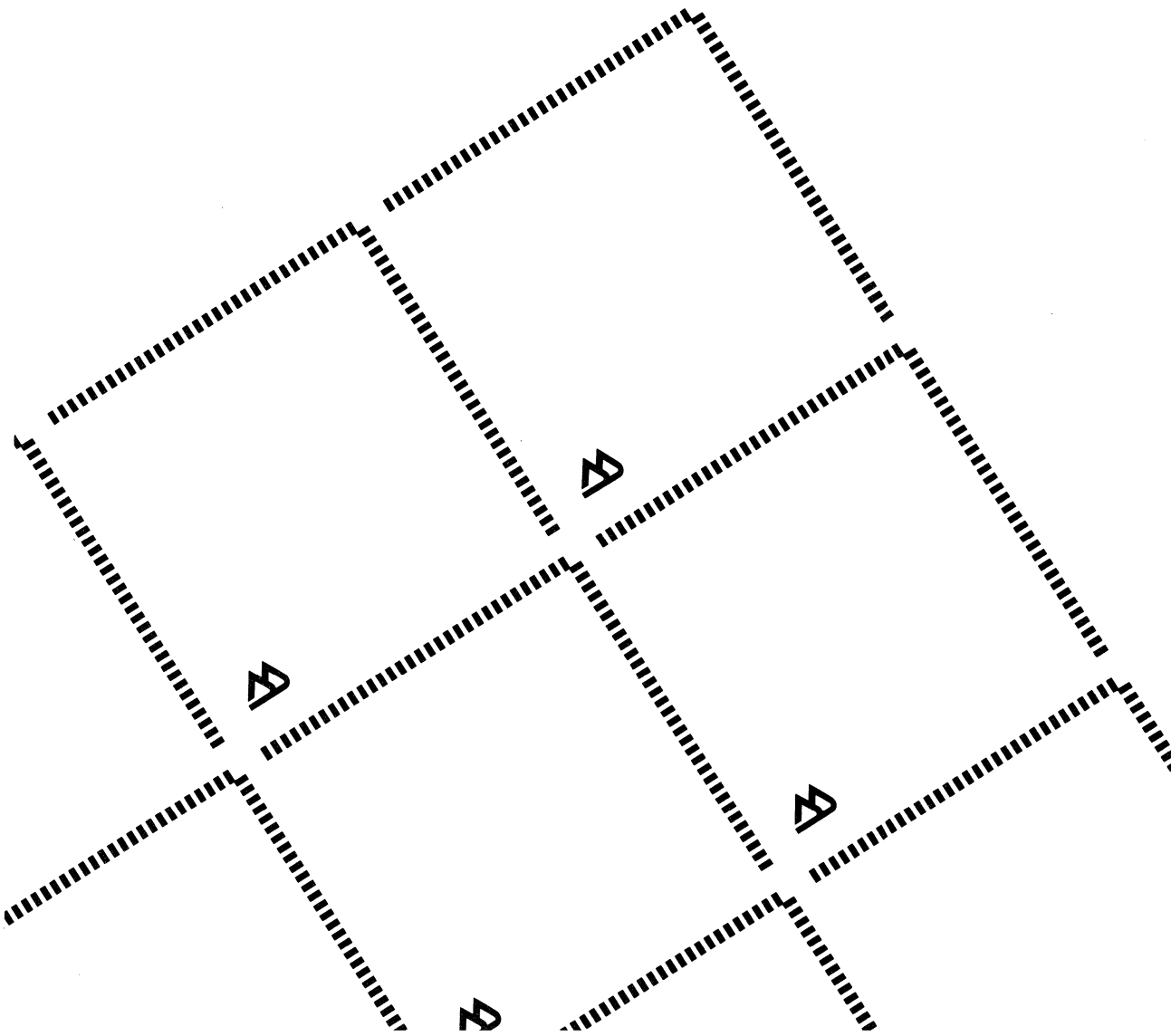
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**CHARACTERISTICS CURVES**

Under measurement

I. OTHER PRODUCTS

1988/1989 CMOS  
DATA BOOK





# SED9420C<sub>AC</sub>

## CMOS DATA SEPARATOR FOR FDD

- Built-in Terminals for Switching between 5 $\frac{1}{4}$ -inch and 8-inch Floppy Disks and between Double Density and Single Density
- For Filter Switching System Only

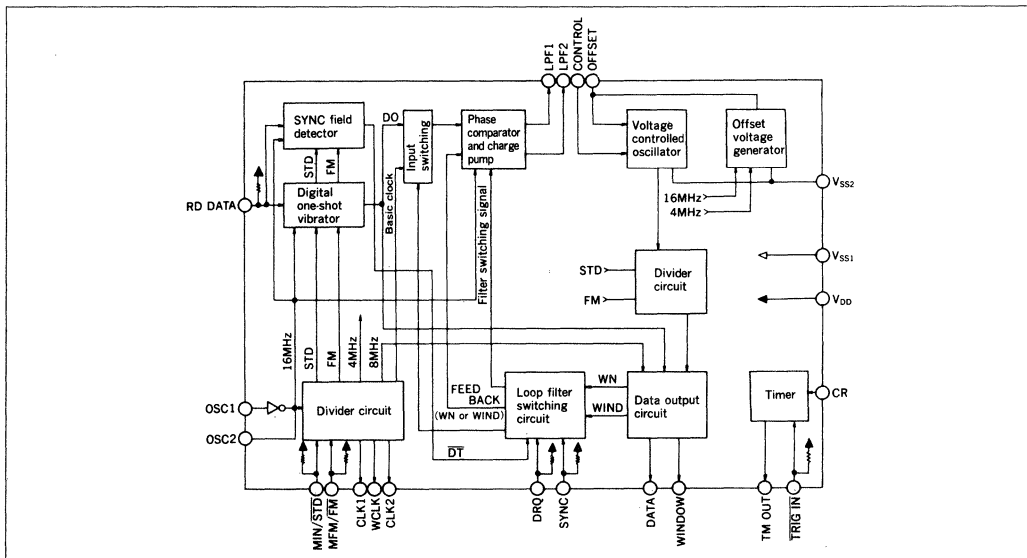
### DESCRIPTION

The SED9420C<sub>AC</sub> is a CMOS VFO data separator LSI for use in floppy disk interfaces. Equipped with its own SYNC field detection, loop filter switching, and timer functions, the IC allows construction of a one-chip VFO circuit with just a few external components. Floppy disk controllers which can be used with this IC are the  $\mu$ PD765,  $\mu$ PD765A, FD1791-02, FD1793-02, MB8876A, MB8877A.

### FEATURES

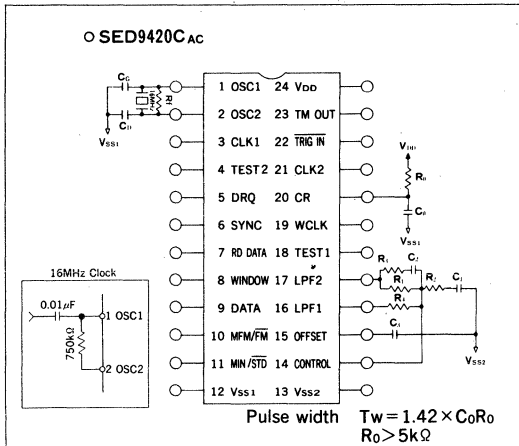
- Data separation function using the VFO system (a phase locked loop)
- Switchable between 8-inch and 5 $\frac{1}{4}$ -inch floppy disk drives (FDDs)
- Recording can be switched between double density and single density
- Requires no adjustment and few external circuits
- Compatible with the IBM Format
- Clock output for floppy disk controllers ..... to be connected with  $\mu$ PD765series, MB8877series or FD179Xseries
- Single 5V power supply
- TTL-compatible I/O pins (excluding OSC1 and OSC2)
- Built-in timer circuit (with external C-R)
- Package ..... 24-pin DIP (plastic)

### BLOCK DIAGRAM





## PIN CONFIGURATION AND AN EXAMPLE OF EXTERNAL CIRCUITS



[Reference value of external circuits]

FDD	$5\frac{1}{4}$ -inch/8-inch
R <sub>1</sub>	33kΩ
R <sub>2</sub>	2.4kΩ
R <sub>3</sub>	7.5kΩ
R <sub>4</sub>	100Ω
C <sub>1</sub>	0.01μF
C <sub>2</sub>	3,300pF
C <sub>3</sub>	0.01 to 0.1μF
C <sub>D</sub>	10pF
C <sub>G</sub>	10pF
R <sub>f</sub>	1 MΩ
f <sub>0</sub>	16MHz ± 0.5%

Accuracy of resistor ±5%, Accuracy of capacitor ±10%

## PIN DESCRIPTION

Pin Name	Pin No.	Function	Pin Name	Pin No.	Function
OSC1	1	(1) Gate input terminal for the inverted amplifier of the crystal oscillator circuit. (2) Clock input terminal when using an external 16MHz clock.	V <sub>SS1</sub>	12	Ground terminal for the digital system.
			V <sub>SS2</sub>	13	Ground terminal for the analog system. (VCO ground)
OSC2	2	Drain output terminal for the crystal oscillator circuit's inverted amplifier.	CONTROL	14	Input terminal for the VCO (voltage controlled oscillator) control voltage.
CLK1	3	FDC clock output terminal (for the μPD765) • f = 8MHz for 8-inch floppy disk • f = 4MHz for 5¼-inch floppy disk	OFFSET	15	Input terminal for offset voltage for VCO center frequency correction. An external capacitor tied to this pin generates offset voltage.
TEST2*	4	Test terminal for testing functions (with pull-up resistor)	LPF1	16	Terminal for connecting the PLL system's loop filter. Selected when sync field is detected for frequency lock-in.
DRQ*	5	Input signal for FDC data transfer signal (with pull-up resistor)	LPF2	17	Terminal for connecting the PLL system's loop filter. Selected when ID and DATA fields are detected after frequency lock-in.
SYNC*	6	FDC control signal input terminal for GAP area and SYNC area detection (with pull-up resistor).	TEST1	18	Test terminal for testing functions (ordinarily not connected).
RD DATA*	7	Input terminal for the read data signal from the floppy disk drive (FDD) (with pull-up resistor).	WCLK	19	Write clock for the μPD765 FDC. • 8-inch MFM: Interval T = 1 μs • 8-inch FM: Interval T = 2 μs • 5¼-inch MFM: Interval T = 2 μs • 5¼-inch FM: Interval T = 4 μs
WINDOW	8	Output terminal for the data window signal used to separate data pulses in the DATA signal from clock pulses.	CR	20	CR connection terminal for the timer circuit.
DATA	9	Output terminal for the read data signal produced from the RD DATA signal. Sent to the FDC together with the WINDOW signal, and is then separated into clock and data pulses.	CLK2	21	FDC clock output terminal (for the MB8877 and FD1791). • f = 2MHz for 8-inch floppy disk • f = 1MHz for 5¼-inch floppy disk
MFM/FM*	10	Terminal for switching between double density and single density (with pull-up resistor) HIGH selects double density (MFM), LOW selects single density (FM).	TRIG IN*	22	Trigger input terminal for the timer circuit (with pull-up resistor).
MIN/STD*	11	Terminal for switching between 5¼-inch and 8-inch floppy disks (with pull-up resistor). HIGH selects 5¼-inch floppies LOW selects 8-inch floppies.	TM OUT	23	Retriggerable oneshot timer output terminal (Timer for head-load timing or motor-on signal, etc.)
			V <sub>DD</sub>	24	+5V power supply terminal

NOTE: \*Input terminals with pull-up resistors are pulled up through a standard resistance of 100K ohms. Since susceptibility to noise is increased by leaving terminals open, it is recommended that terminals which are to be kept HIGH be connected directly to V<sub>DD</sub>.

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	V <sub>DD</sub>	-0.5 to 7.0	V
Input voltage	V <sub>I</sub>	-0.5 to V <sub>DD</sub> +0.3	V
Output voltage	V <sub>O</sub>		
Operating temperature	T <sub>opr</sub>	-10 to 60	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

## ■ ELECTRICAL CHARACTERISTICS

### ● DC Electrical Characteristics

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Operating supply voltage	V <sub>DD</sub>	—	4.75	5.0	5.25	V
High level input voltage	V <sub>IH</sub>	—	2.0	—	V <sub>DD</sub> +0.3	V
Low level input voltage	V <sub>IL</sub>	—	-0.3	—	0.8	V
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -200μA	2.4	—	V <sub>DD</sub>	V
Low level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2.0mA	0	—	0.4	V
High level input current*1	I <sub>IH1</sub>	V <sub>IH</sub> = V <sub>DD</sub>	—	—	2.0	μA
Low level input current*2	I <sub>IL1</sub>	V <sub>IL</sub> = V <sub>SS</sub> V <sub>DD</sub> = 5V	-100	-50	-10	μA
High level output current*3	I <sub>OH1</sub>	V <sub>OH</sub> = 2.4V	—	—	-200	μA
Low level output current*4	I <sub>OL1</sub>	V <sub>OL</sub> = 0.4V	2.0	—	—	mA
Current consumption	I <sub>DD</sub>	Output open, V <sub>DD</sub> = 5V, 16MHz oscillation	—	—	10	mA

\*1 HIGH input current for pins with pull-up resistors

\*2 LOW input current for pins with pull-up resistors

\*3 HIGH output current for driver output terminals

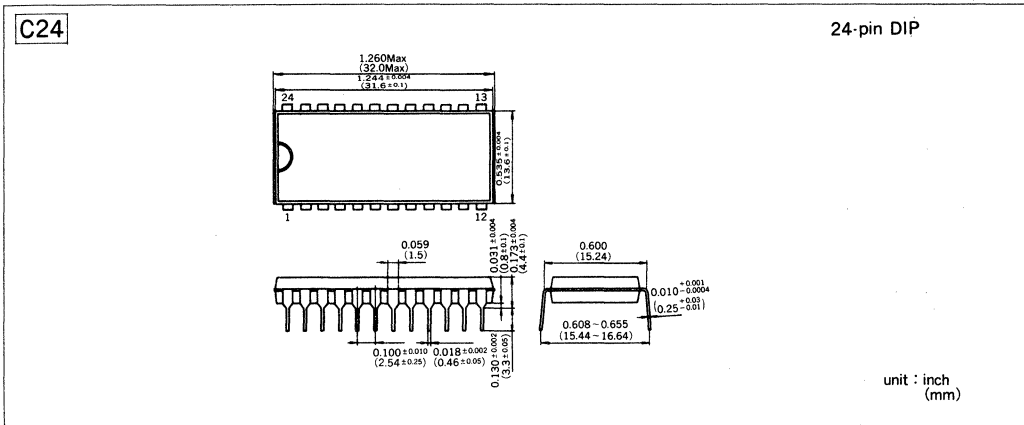
\*4 LOW output current for driver output terminals

### ● AC Electrical Characteristics

(Standard frequency ; f<sub>0</sub> = 16MHz)

Parameter	Symbol	Pin Name	Conditions	Min	Typ	Max	Unit
Frequency	f <sub>CLK1</sub>	CLK1	MIN/STD = Low	—	8.0	—	MHz
			MIN/STD = High	—	4.0	—	MHz
	f <sub>CLK2</sub>	CLK2	MIN/STD = Low	—	2.0	—	MHz
			MIN/STD = High	—	1.0	—	MHz
Cycle time and Window width	t <sub>CYWCL</sub> and t <sub>WHWIND</sub>	WCLK and WINDOW	MIN/STD = Low MFM/FM = Low	—	2	—	μs
			MIN/STD = High MFM/FM = Low	—	4	—	μs
	MIN/STD = Low MFM/FM = High		—	1	—	μs	
	MIN/STD = High MFM/FM = High		—	2	—	μs	
High level width	t <sub>WHDT</sub>	DATA	C <sub>L</sub> = 15pF	110	125	140	ns
High level width	t <sub>WHRD</sub>	RD DATA	—	150	—	—	ns
VCO Oscillation frequency	f <sub>VCO</sub>	—	CONTROL terminal = V <sub>DD</sub> /2 External capacitance (0.1μF) connected to OFFSET terminal	3.8	4.0	4.3	MHz
VCO control voltage coefficient	K <sub>V</sub>	—	V <sub>DD</sub> /2-CONTROL voltage  ≤ 0.5V	1.0	1.2	1.4	MHz/V
Supply voltage rise time	V <sub>R</sub>	—	Time for voltage to rise from 10% level to 90%	5	—	—	ms

PACKAGE DIMENSIONS



NOTE : The SED9420C<sub>AC</sub> cannot execute the Read Truck Command of MB8877 and FD179X.

NOTE : It is impossible to read 8-inch Media with SED9420C<sub>AC</sub> when the GAP DATA of 8-inch Media is written in (00)H.

# SCI7700Y Series / SCI7701Y Series

## CMOS VOLTAGE DETECTOR

Preliminary

- Voltage Detector
- Many Types
- Low Operating Supply Current

### DESCRIPTION

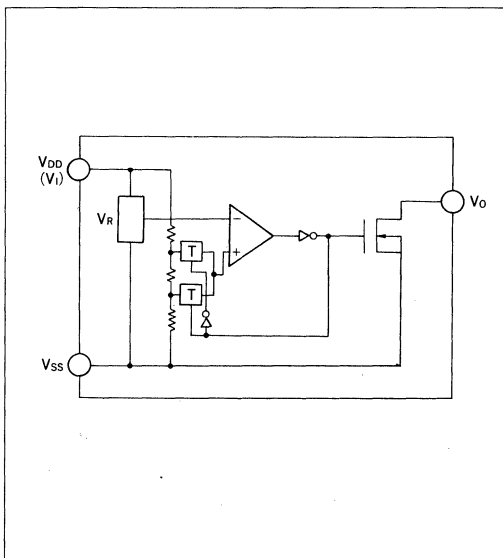
The SCI7700Y series/SCI7701Y series are a series of low-power precision voltage detectors, which do not require external adjustments. The SCI7700Y series/SCI7701Y series have such applications as battery-life detection, power supply fault monitoring, over/under-voltage protection and battery back-up switching. The SCI7700Y series is a n open-drain Nch output type and the SCI7701Y series is a CMOS output type. Both are available in SOT 89 (plastic) packages.

### FEATURES

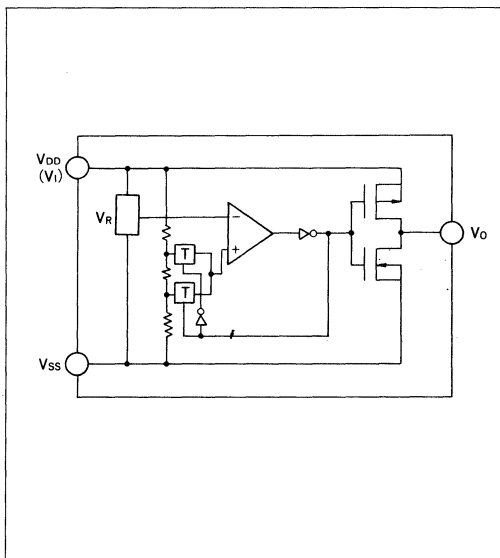
- Many types ..... See the next page.
- Low operating supply current ..... Typ 1.8 $\mu$ A (SCI7700Y<sub>NA</sub>, V<sub>DD</sub>=3.0V)
- Low range of operating voltage ..... Typ 1.2V (SCI7700Y<sub>NA</sub>)
- Temperature coefficient of detection voltage ..... Typ (detection voltage/reference voltage)  $\times$  0.1 (mV/ $^{\circ}$ C)
- Hysteresis difference ..... Typ detection voltage  $\times$  0.05V
- Package ..... SOT 89 (plastic)

### BLOCK DIAGRAM

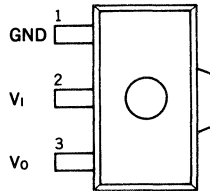
#### SCI7700Y Series



#### SCI7701Y Series



## PIN CONFIGURATION



## SCI7700Y series/SCI7701Y series

(Ta = 25°C)

Type No.	Output mode	Detection voltage (V)			Operating voltage (V)	Operating supply current (μA)
		Min	Typ	Max		
SCI7700Y <sub>VA</sub>	Open drain Nch	0.90	0.95	1.00	0.8 to 5.0	Typ 1.4 (V <sub>DD</sub> =1.5V)
SCI7700Y <sub>AA</sub>	Open drain Nch	1.00	1.05	1.10	0.9 to 5.0	Typ 1.4 (V <sub>DD</sub> =1.5V)
SCI7700Y <sub>BA</sub>	Open drain Nch	1.10	1.15	1.20	0.9 to 5.0	Typ 1.4 (V <sub>DD</sub> =1.5V)
SCI7700Y <sub>NA</sub>	Open drain Nch	1.85	1.90	1.95	1.2 to 10.0	Typ 1.8 (V <sub>DD</sub> =3.0V)
SCI7700Y <sub>TA</sub>	Open drain Nch	3.80	4.00	4.20	1.5 to 10.0	Typ 2.6 (V <sub>DD</sub> =6.0V)
SCI7701Y <sub>CA</sub>	CMOS	2.10	2.15	2.20	1.5 to 10.0	Typ 1.8 (V <sub>DD</sub> =3.0V)
SCI7701Y <sub>PA</sub>	CMOS	2.20	2.25	2.30	1.5 to 10.0	Typ 1.8 (V <sub>DD</sub> =3.0V)
SCI7701Y <sub>SA</sub>	CMOS	2.30	2.35	2.40	1.5 to 10.0	Typ 1.8 (V <sub>DD</sub> =3.0V)
SCI7701Y <sub>EA</sub>	CMOS	2.50	2.55	2.60	1.5 to 10.0	Typ 1.8 (V <sub>DD</sub> =3.0V)
SCI7701Y <sub>FA</sub>	CMOS	2.60	2.70	2.80	1.5 to 10.0	Typ 1.8 (V <sub>DD</sub> =3.0V)
SCI7701Y <sub>RA</sub>	CMOS	2.70	2.80	2.90	1.5 to 10.0	Typ 1.8 (V <sub>DD</sub> =3.0V)
SCI7701Y <sub>GA</sub>	CMOS	2.90	3.00	3.10	1.5 to 10.0	Typ 2.2 (V <sub>DD</sub> =4.5V)
SCI7701Y <sub>HA</sub>	CMOS	3.10	3.20	3.30	1.5 to 10.0	Typ 2.2 (V <sub>DD</sub> =4.5V)
SCI7701Y <sub>TA</sub>	CMOS	3.80	4.00	4.20	1.5 to 10.0	Typ 2.6 (V <sub>DD</sub> =6.0V)
SCI7701Y <sub>MA</sub>	CMOS	4.00	4.15	4.30	1.5 to 10.0	Typ 2.6 (V <sub>DD</sub> =6.0V)
SCI7701Y <sub>JA</sub>	CMOS	4.30	4.45	4.60	1.5 to 10.0	Typ 2.6 (V <sub>DD</sub> =6.0V)
SCI7701Y <sub>KA</sub>	CMOS	4.60	4.75	4.90	1.5 to 10.0	Typ 2.6 (V <sub>DD</sub> =6.0V)
SCI7701Y <sub>LA</sub>	CMOS	4.90	5.10	5.30	1.5 to 10.0	Typ 2.6 (V <sub>DD</sub> =6.0V)

## ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Ratings	Unit
Input voltage (supply voltage)	V <sub>DD</sub> (V <sub>I</sub> )-V <sub>SS</sub>	12	V
Output voltage	V <sub>O</sub>	V <sub>DD</sub> +0.3 to V <sub>SS</sub> -0.3	V
Output current	I <sub>O</sub>	50	mA
Power dissipation (Ta ≤ 25°C)	P <sub>D</sub>	400	mW
Operating temperature	T <sub>opr</sub>	-20 to 70	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	—

NOTE) Although this IC has electrostatic protection circuit, damage may still occur if very high electrostatic potentials are applied.

## ELECTRICAL CHARACTERISTICS

### SCI7700Y Series/SCI7701Y Series

Parameter	Symbol	Ratings	Min	Typ	Max	Unit
Detection voltage	$V_{DET}$	$T_a = 25^\circ\text{C}$	See the left page			V
Operating supply current	$I_{DDO}$	$V_{DD} = 1.5\text{V}, T_a = 25^\circ\text{C}$	—	1.4	3.0	$\mu\text{A}$
		$V_{DD} = 3.0\text{V}, T_a = 25^\circ\text{C}$	—	1.8	4.0	
		$V_{DD} = 4.5\text{V}, T_a = 25^\circ\text{C}$	—	2.2	5.0	
		$V_{DD} = 6.0\text{V}, T_a = 25^\circ\text{C}$	—	2.6	6.0	
Supply (Operating) voltage	$V_{DD} (V_i)$	$T_a = -20 \sim 70^\circ\text{C}$	See the left page			V
Hysteresis difference	$\Delta V_{DET}$	$T_a = -20 \sim 70^\circ\text{C}$	—	$V_{DET} \times 0.05^*$	—	V
Temperature coefficient of $V_{DET}$	$\frac{V_{DET}(T_a=70^\circ\text{C}) - V_{DET}(T_a=-20^\circ\text{C})}{90}$	$T_a = -20 \sim 70^\circ\text{C}$	Typ $(V_{DET}/V_R) \times 0.1$			$\text{mV}/^\circ\text{C}$

\*  $V_{DET} \times 0.04$  (Typ) about SCI7700Y<sub>TA</sub>/SCI7701Y<sub>TA</sub>/SCI7701Y<sub>MA</sub>/SCI7701Y<sub>JA</sub>/SCI7701Y<sub>KA</sub>/SCI7701Y<sub>LA</sub>

### SCI7700Y<sub>VA</sub>/SCI7700Y<sub>AA</sub>/SCI7700Y<sub>BA</sub>

Parameter	Symbol	Ratings	Min	Typ	Max	Unit
Output current	$I_o$ (Nch)	$V_{DD} = 0.85\text{V}, V_{DS} = 0.5\text{V}, T_a = 25^\circ\text{C}$	0.05	0.40	1.00	mA
		$V_{DD} = 0.95\text{V}, V_{DS} = 0.5\text{V}, T_a = 25^\circ\text{C}$	0.15	0.70	1.50	
		$V_{DD} = 1.05\text{V}, V_{DS} = 0.5\text{V}, T_a = 25^\circ\text{C}$	0.30	1.00	2.00	
Reference voltage supply	$V_R$	$T_a = 25^\circ\text{C}$	0.70	0.80	0.90	V

$V_{DS}$ : Voltage between drain and source

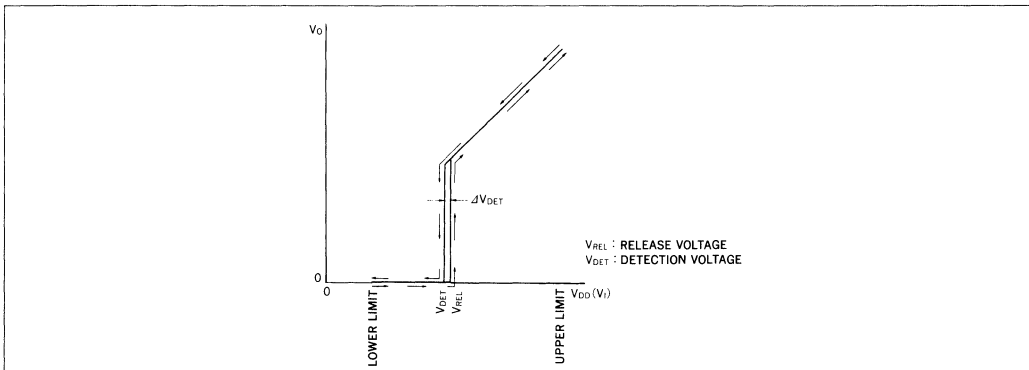
### SCI7700Y<sub>NA</sub>/SCI7700Y<sub>TA</sub>/SCI7701Y<sub>CA</sub>/SCI7701Y<sub>PA</sub>/SCI7701Y<sub>SA</sub>/SCI7701Y<sub>EA</sub>/SCI7701Y<sub>FA</sub>/SCI7701Y<sub>RA</sub>/ SCI7701Y<sub>GA</sub>/SCI7701Y<sub>HA</sub>/SCI7701Y<sub>TA</sub>/SCI7701Y<sub>MA</sub>/SCI7701Y<sub>JA</sub>/SCI7701Y<sub>KA</sub>/SCI7701Y<sub>LA</sub>

Parameter	Symbol	Ratings	Min	Typ	Max	Unit
Output current	$I_o$ (Nch)	$V_{DD} = 0.95\text{V}, V_{DS} = 0.5\text{V}, T_a = 25^\circ\text{C}$	0.03	0.15	0.50	mA
		$V_{DD} = 1.00\text{V}, V_{DS} = 0.5\text{V}, T_a = 25^\circ\text{C}$	0.05	0.22	0.60	
		$V_{DD} = 1.20\text{V}, V_{DS} = 0.5\text{V}, T_a = 25^\circ\text{C}$	0.30	0.70	1.50	
		$V_{DD} = 2.40\text{V}, V_{DS} = 0.5\text{V}, T_a = 25^\circ\text{C}$	1.40	2.00	2.30 *1	
		$V_{DD} = 3.60\text{V}, V_{DS} = 0.5\text{V}, T_a = 25^\circ\text{C}$	1.50	2.30	2.60 *2	
	$I_o$ (Pch)	$V_{DD} = 4.50\text{V}, V_{DS} = 2.1\text{V}, T_a = 25^\circ\text{C}$	1.7	2.0	2.3	
		$V_{DD} = 8.00\text{V}, V_{DS} = 2.1\text{V}, T_a = 25^\circ\text{C}$	2.8	3.1	3.8	
		Reference voltage supply	$V_R$	$T_a = 25^\circ\text{C}$	0.90	

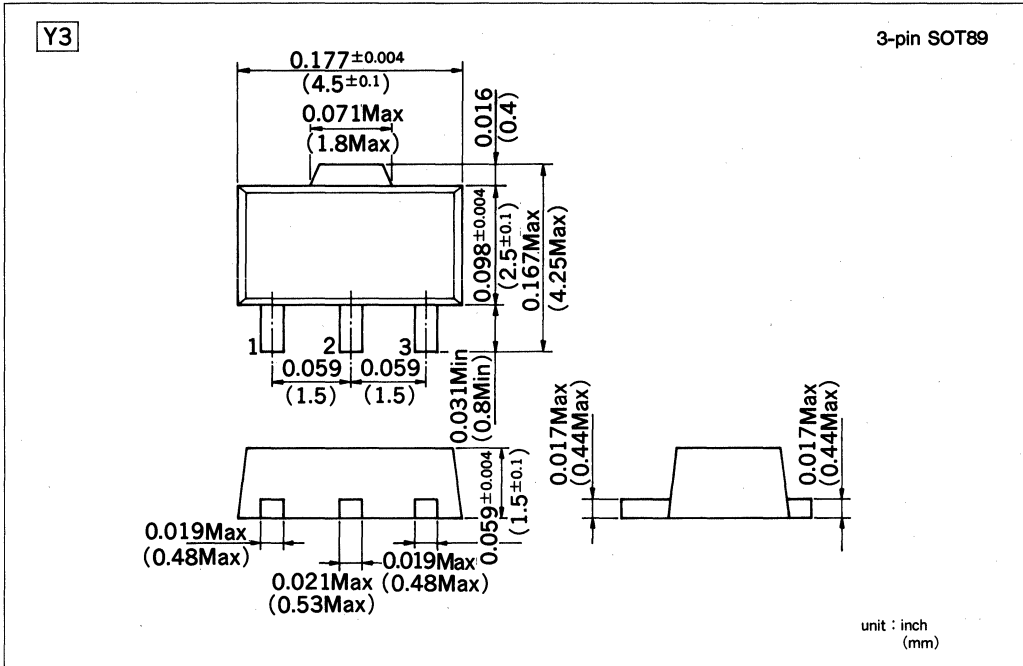
\*1: 3.30 mA about SCI7700Y<sub>TA</sub>, \*2: 4.00mA about SCI7700Y<sub>TA</sub>

$V_{DS}$ : Voltage between drain and source

### Performance Curves

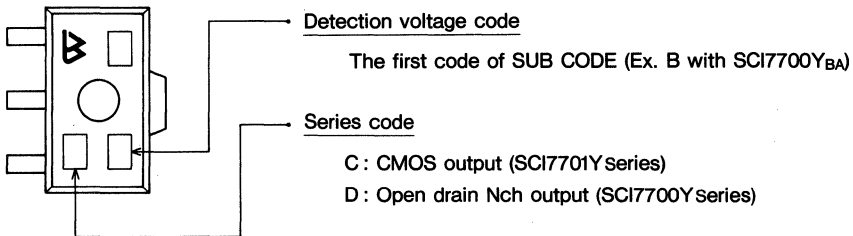


■ PACKAGE DIMENSIONS



■ MARKING

An abbreviation code is printed on SCI7700Y series/SCI7701Y series below, because its package size is very small.



# SCI7710Y Series / SCI7711Y Series

## CMOS VOLTAGE REGULATOR

Preliminary

- Voltage Regulator (Positive Output/Negative Output)
- Low Operating Supply Current

■ DESCRIPTION

SCI7710Yseries/SCI7711Yseries are fixed voltage regulators of a CMOS silicon gate process. The SCI7710Yseries/SCI7711Yseries are constructed of a reference voltage source, a differential amplifier and a resistor for setting voltage levels. The SCI7710Yseries are positive voltage regulators and the SCI7711Yseries are negative regulators. Both are available in SOT 89 (plastic) packages.

■ FEATURES

- Low operating supply current .....Typ 1.0 $\mu$ A (SCI7711Y<sub>DA</sub>)
- Small temperature coefficient of output voltage .....Typ 1.8mV/ $^{\circ}$ C (SCI7711Y<sub>DA</sub>)
- Wide range of operating voltage .....Max 15V
- Line regulation .....Typ 0.1%/V (SCI7711Y<sub>DA</sub>)
- Package .....SOT 89 (plastic)

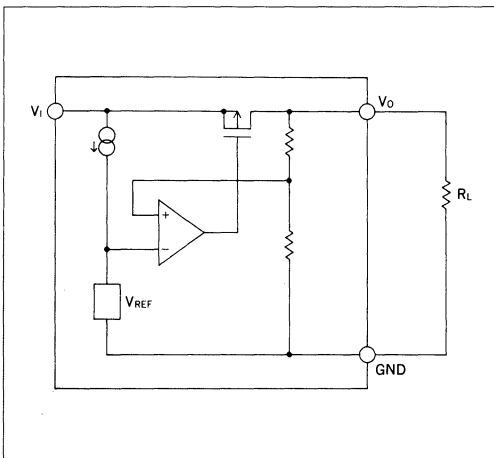
■ SCI7710Yseries/SCI7711Yseries

Type No.	Output voltage	Output current	Operating current	Input voltage	Absolute maximum input voltage
SCI7710Y <sub>BA</sub>	5V	Typ 50mA $V_I=7V$	Typ 2.4 $\mu$ A	15V	21V
SCI7710Y <sub>DA</sub>	3V	Typ 30mA $V_I=5V$	Typ 2.0 $\mu$ A	15V	21V
SCI7711Y <sub>BA</sub>	-5V	Typ 50mA $V_I=-7V$	Typ 1.4 $\mu$ A	-15V	-21V
SCI7711Y <sub>DA</sub>	-3V	Typ 30mA $V_I=-5V$	Typ 1.0 $\mu$ A	-15V	-21V

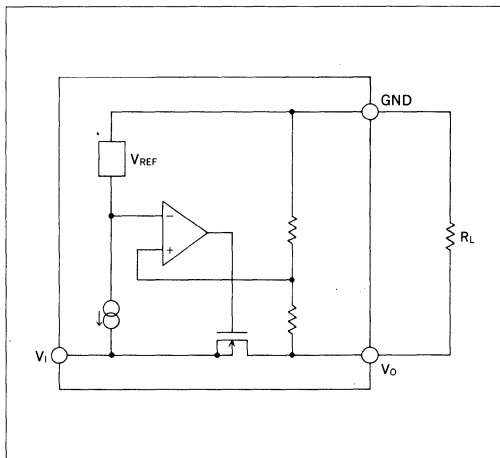
\*1.5V, 1.8V and 2.2V (output voltage) are under development.

■ BLOCK DIAGRAM

● SCI7710Y Series



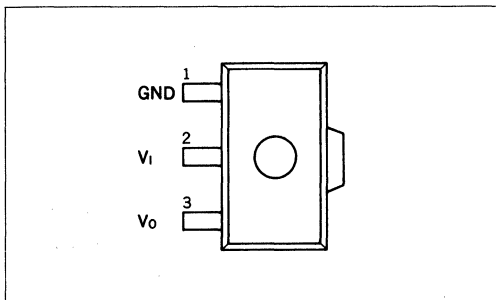
● SCI7711Y Series



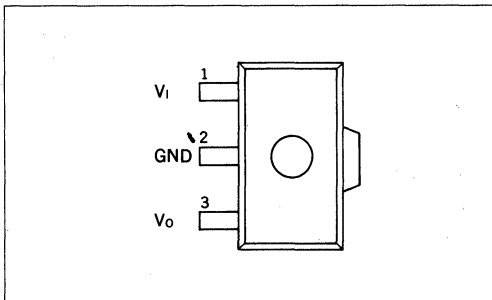


## ■ PIN CONFIGURATION

### ● SCI7710Y Series



### ● SCI7711Y Series



## ■ ABSOLUTE MAXIMUM RATINGS

### ● SCI7710Y Series

Parameter	Symbol	Ratings	Unit
Input voltage	$V_i$	21	V
Output current	$I_o$	100	mA
Output voltage	$V_o$	$V_i + 0.3$ to GND - 0.3	V
Power dissipation ( $T_a \leq 25^\circ\text{C}$ )	$P_D$	400	mW
Operating temperature	$T_{opr}$	-20 to 70	°C
Storage temperature	$T_{stg}$	-65 to 150	
Soldering temperature and time	$T_{sol}$	260°C, 10s (at lead)	—

### ● SCI7711Y Series

Parameter	Symbol	Ratings	Unit
Input voltage	$V_i$	-21	V
Output current	$I_o$	100	mA
Output voltage	$V_o$	GND + 0.3 to $V_i - 0.3$	V
Power dissipation ( $T_a \leq 25^\circ\text{C}$ )	$P_D$	400	mW
Operating temperature	$T_{opr}$	-20 to 70	°C
Storage temperature	$T_{stg}$	-65 to 150	
Soldering temperature and time	$T_{sol}$	260°C, 10s (at lead)	—

## ■ ELECTRICAL CHARACTERISTICS

### ● SCI7710Y<sub>BA</sub>

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input voltage	$V_i$	$T_a = -20$ to $70^\circ\text{C}$	—	—	15	V
Output voltage	$V_o$	$V_i = 7.0\text{V}, I_o = 10\text{mA}, T_a = 25^\circ\text{C}$	4.75	5.00	5.25	V
		$V_i = 6.0\text{V to } 15\text{V}, I_o = 10\text{mA}, T_a = -20$ to $70^\circ\text{C}$	4.50	—	5.50	
		$V_i = 7.2\text{V to } 15\text{V}, I_o = 50\text{mA}, T_a = -20$ to $70^\circ\text{C}$	4.50	—	5.50	
Voltage tolerance	$ V_i - V_o $	$V_i = 5.0\text{V}, I_o = 10\text{mA}, T_a = -20$ to $70^\circ\text{C}$	—	0.25	0.35	V
		$V_i = 5.0\text{V}, I_o = 50\text{mA}, T_a = -20$ to $70^\circ\text{C}$	—	1.35	1.70	
Line regulation	$\frac{ \Delta V_o }{ \Delta V_i \cdot V_o }$	$T_a = -20^\circ\text{C to } 70^\circ\text{C}$ (constant condition) $V_i = 6.0\text{V to } 15\text{V}, I_o = 1\text{mA to } 10\text{mA}$	—	0.18	—	%/V
Operating supply current	$I_{DDO}$	$V_i = 5.0\text{V to } 15\text{V}, T_a = 25^\circ\text{C}$	—	2.4	4.8	$\mu\text{A}$
Temperature coefficient of output voltage	$K_t$		—	-3.0	—	mV/°C
Load regulation	$\Delta V_o$	$V_i = 7\text{V}, 1\text{mA} \leq I_o \leq 50\text{mA}$	—	50	—	mV

●SCI7710Y<sub>DA</sub>

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input voltage	$V_I$	$T_a = -20 \text{ to } 70^\circ\text{C}$	—	—	15	V
Output voltage	$V_O$	$V_I = 5.0\text{V}, I_O = 10\text{mA}, T_a = 25^\circ\text{C}$	2.85	3.00	3.15	V
		$V_I = 4.0\text{V to } 15\text{V}, I_O = 10\text{mA}, T_a = -20 \text{ to } 70^\circ\text{C}$	2.70	—	3.30	
		$V_I = 5.0\text{V to } 15\text{V}, I_O = 30\text{mA}, T_a = -20 \text{ to } 70^\circ\text{C}$	2.70	—	3.30	
Voltage tolerance	$ V_I - V_O $	$V_I = 3.0\text{V}, I_O = 10\text{mA}, T_a = -20 \text{ to } 70^\circ\text{C}$	—	0.35	0.50	V
		$V_I = 3.0\text{V}, I_O = 30\text{mA}, T_a = -20 \text{ to } 70^\circ\text{C}$	—	1.20	1.70	
Line regulation	$\frac{ \Delta V_O }{ \Delta V_I \cdot V_O }$	$T_a = -20 \text{ to } 70^\circ\text{C}$ (constant condition) $V_I = 4.0\text{V to } 15\text{V}, I_O = 1\text{mA to } 10\text{mA}$	—	0.15	—	%/V
Operating supply current	$I_{DDO}$	$V_I = 3.0\text{V to } 15\text{V}, T_a = 25^\circ\text{C}$	—	2.0	4.5	$\mu\text{A}$
Temperature coefficient of output voltage	$K_t$		—	-1.8	—	$\text{mV}/^\circ\text{C}$
Load regulation	$\Delta V_O$	$V_I = 5\text{V}, 1\text{mA} \leq I_O \leq 30\text{mA}$	—	30	—	mV

●SCI7711Y<sub>BA</sub>

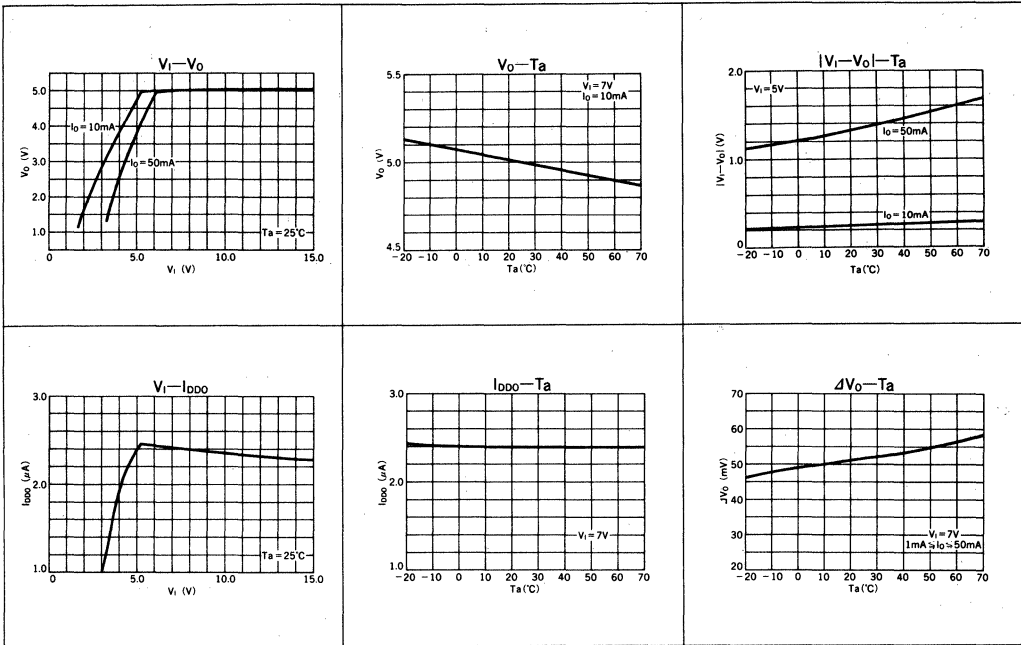
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input voltage	$V_I$	$T_a = -20 \text{ to } 70^\circ\text{C}$	-15	—	—	V
Output voltage	$V_O$	$V_I = -7.0\text{V}, I_O = 10\text{mA}, T_a = 25^\circ\text{C}$	-5.25	-5.00	-4.75	V
		$V_I = -5.7\text{V to } -15\text{V}, I_O = 10\text{mA}, T_a = -20 \text{ to } 70^\circ\text{C}$	-5.50	—	-4.50	
		$V_I = -6.5\text{V to } -15\text{V}, I_O = 50\text{mA}, T_a = -20 \text{ to } 70^\circ\text{C}$	-5.50	—	-4.50	
Voltage tolerance	$ V_I - V_O $	$V_I = -5.0\text{V}, I_O = 10\text{mA}, T_a = -20 \text{ to } 70^\circ\text{C}$	—	0.16	0.20	V
		$V_I = -5.0\text{V}, I_O = 50\text{mA}, T_a = -20 \text{ to } 70^\circ\text{C}$	—	0.80	1.00	
Line regulation	$\frac{ \Delta V_O }{ \Delta V_I \cdot V_O }$	$T_a = -20 \text{ to } 70^\circ\text{C}$ (constant condition) $V_I = -6.0\text{V to } -15\text{V}, I_O = 1\text{mA to } 10\text{mA}$	—	0.1	—	%/V
Operating supply current	$I_{DDO}$	$V_I = -5.0\text{V to } -15\text{V}, T_a = 25^\circ\text{C}$	—	1.4	2.0	$\mu\text{A}$
Temperature coefficient of output voltage	$K_t$		—	3.0	—	$\text{mV}/^\circ\text{C}$
Load regulation	$\Delta V_O$	$V_I = -7\text{V}, 1\text{mA} \leq I_O \leq 50\text{mA}$	—	50	—	mV

●SCI7711Y<sub>DA</sub>

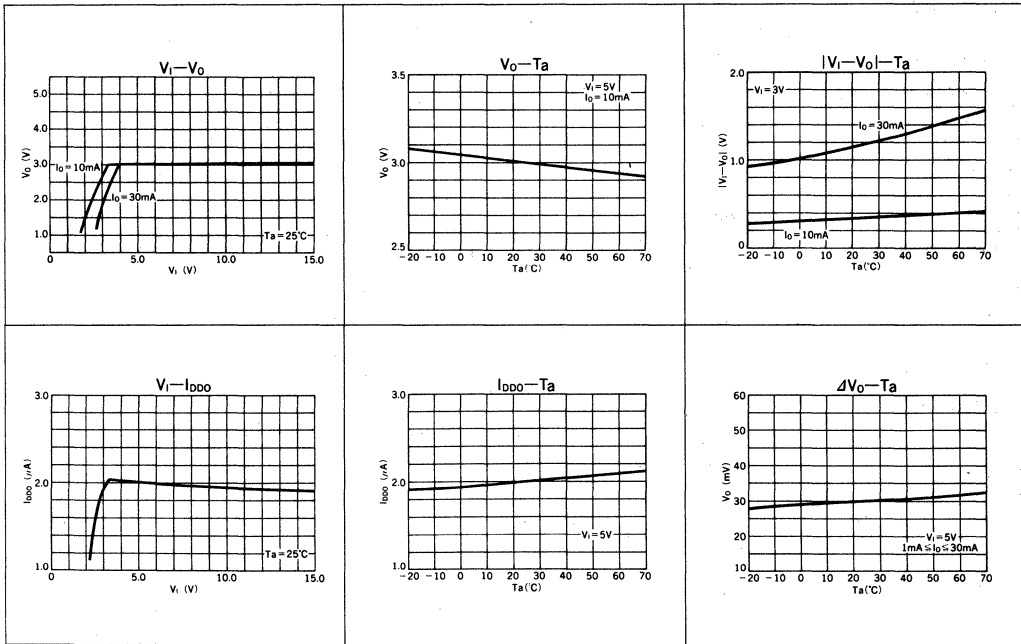
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input voltage	$V_I$	$T_a = -20 \text{ to } 70^\circ\text{C}$	-15	—	—	V
Output voltage	$V_O$	$V_I = -5.0\text{V}, I_O = 10\text{mA}, T_a = 25^\circ\text{C}$	-3.15	-3.00	-2.85	V
		$V_I = -3.7\text{V to } -15\text{V}, I_O = 10\text{mA}, T_a = -20 \text{ to } 70^\circ\text{C}$	-3.30	—	-2.70	
		$V_I = -4.5\text{V to } -15\text{V}, I_O = 30\text{mA}, T_a = -20 \text{ to } 70^\circ\text{C}$	-3.30	—	-2.70	
Voltage tolerance	$ V_I - V_O $	$V_I = -3.0\text{V}, I_O = 10\text{mA}, T_a = -20 \text{ to } 70^\circ\text{C}$	—	0.22	0.30	V
		$V_I = -3.0\text{V}, I_O = 30\text{mA}, T_a = -20 \text{ to } 70^\circ\text{C}$	—	0.70	1.00	
Line regulation	$\frac{ \Delta V_O }{ \Delta V_I \cdot V_O }$	$T_a = -20 \text{ to } 70^\circ\text{C}$ (constant condition) $V_I = -4.0\text{V to } -15\text{V}, I_O = 1\text{mA to } 10\text{mA}$	—	0.1	—	%/V
Operating supply current	$I_{DDO}$	$V_I = -3.0\text{V to } -15\text{V}, T_a = 25^\circ\text{C}$	—	1.0	1.5	$\mu\text{A}$
Temperature coefficient of output voltage	$K_t$		—	1.8	—	$\text{mV}/^\circ\text{C}$
Load regulation	$\Delta V_O$	$V_I = -5\text{V}, 1\text{mA} \leq I_O \leq 30\text{mA}$	—	30	—	mV

# CHARACTERISTICS CURVES

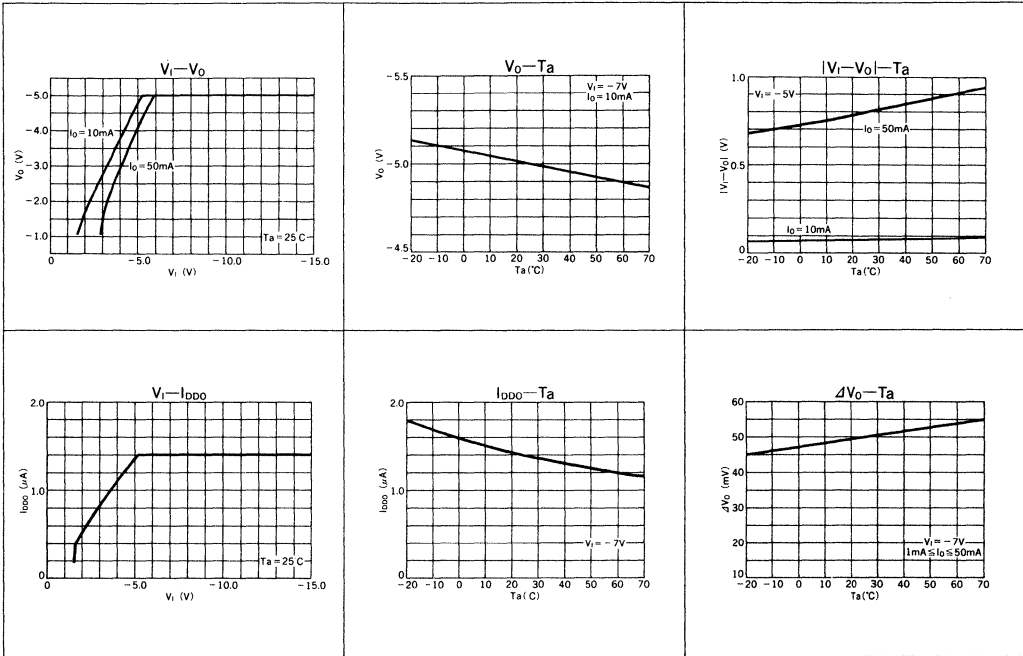
## SCI7710Y<sub>BA</sub>



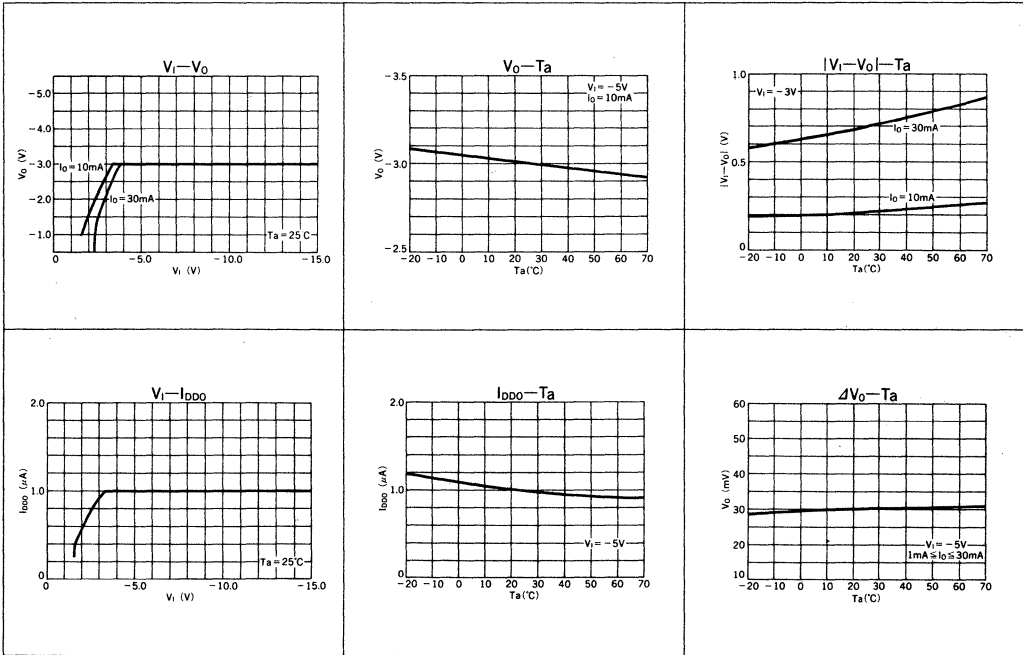
## SCI7710Y<sub>DA</sub>



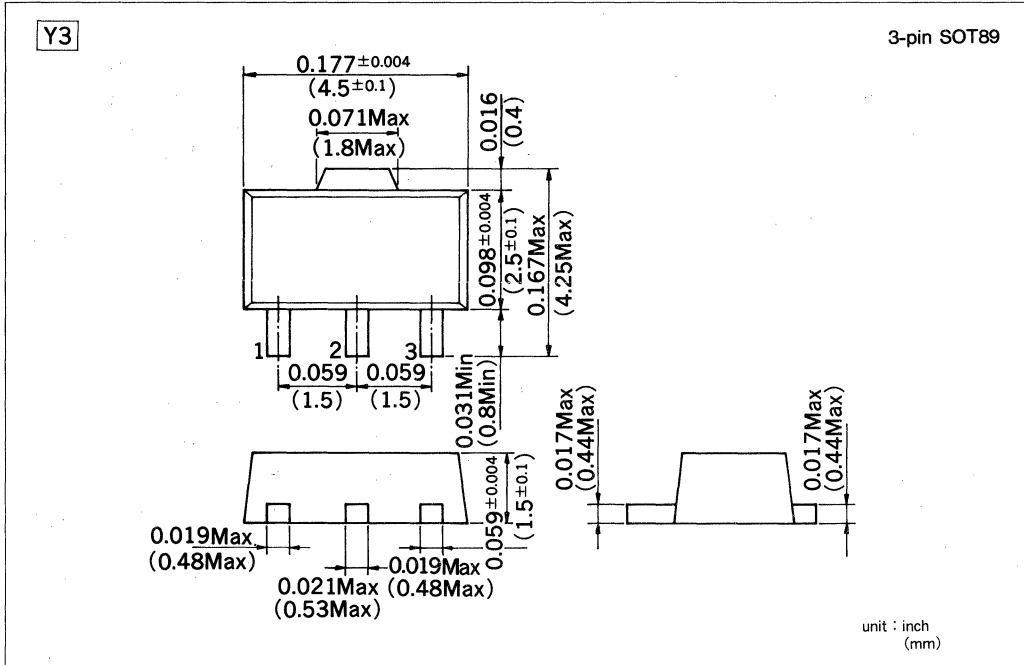
●SCI7711YBA



●SCI7711YDA

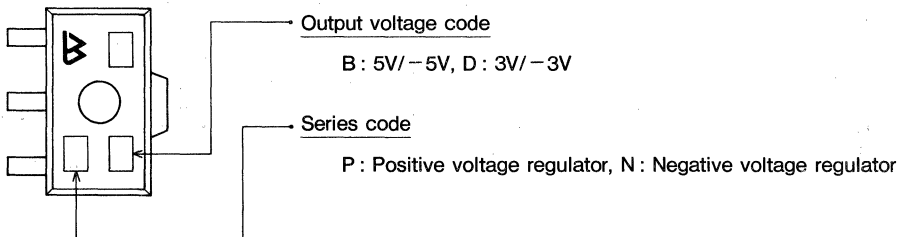


■ PACKAGE DIMENSIONS



■ MARKING

An abbreviation code is printed on SCI7710Yseries/SCI7711Yseries below, because its package size is very small.



# SCI7660C

## CMOS DC/DC CONVERTER

- 95% Typical Power Efficiency
- Doubled Output Voltage
- Voltage Conversion (Positive ↔ Negative)

### DESCRIPTION

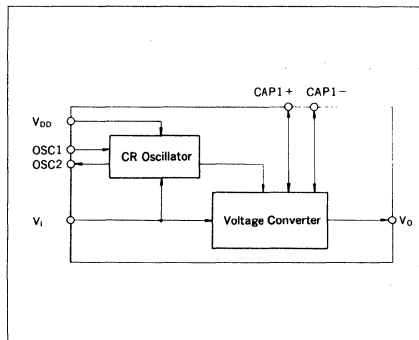
The SCI7660C CMOS DC/DC Converter features high operational performance with low power dissipation. The booster generates a doubled output voltage from the input.

It is possible to drive the LSI that need another power supply than main power supply. (LCD drivers·Analog LSI etc.) Its very low power requirement makes it ideal to supply handy equipments with power.

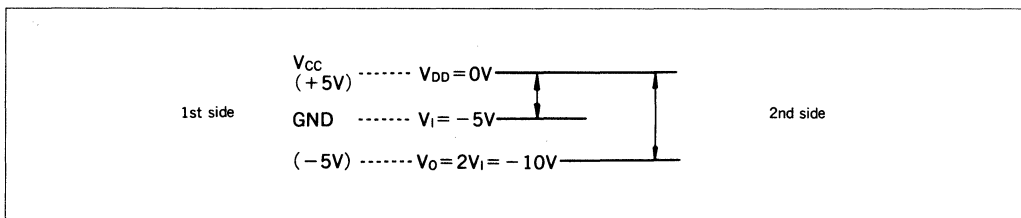
### FEATURES

- High performance with low power dissipation
- Simple conversion of  $V_{DD}(+5V)$  to  $-V_I(-5V)$ ,  $+2V_I(+10V)$
- Output current ..... 30mA Max ( $V_{DD}=5V$ )
- Power conversion efficiency ..... 95% Typ
- Cascade connection (two device connected  $V_{DD}=5V$ ,  $V_O = -10V$ )
- Low power ..... Ideal for dry cell battery
- On-chip CR oscillator
- Package ..... 8 pin DIP (plastic)

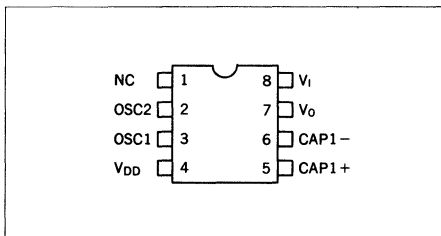
### BLOCK DIAGRAM



### VOLTAGE RELATIONS



### PIN CONFIGURATION



### PIN DESCRIPTION

Pin Name	Pin No.	Functions
OSC1	3	Oscillation resistor connection terminal
OSC2	2	
V <sub>DD</sub>	4	Power supply terminal (positive, system supply V <sub>cc</sub> )
CAP1 +	5	Terminal for connection of capacitor for booster (positive)
CAP1 -	6	Terminal for connection of capacitor for booster (negative)
V <sub>O</sub>	7	Output terminal at doubling
V <sub>I</sub>	8	Power supply terminal (negative, system supply GND)

### ■ ABSOLUTE MAXIMUM RATINGS

( $V_{DD}=0V$ ,  $T_a=25^\circ C$ )

Parameter	Symbol	Ratings	Unit
Input voltage	$V_I$	-10.0 to 0.5	V
Output voltage	$V_O$	-20.0 to $V_I$	V
Power dissipation	$P_D$	300	mW
Operating temperature	$T_{opr}$	-30 to 85	$^\circ C$
Storage temperature	$T_{stg}$	-65 to 150	$^\circ C$
Soldering temperature and time	$T_{sol}$	260 $^\circ C$ , 10s (at lead)	—

### ■ ELECTRICAL CHARACTERISTICS

( $V_{DD}=0V$ ,  $T_a=-30$  to  $85^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Input voltage	$V_I$		-8.0	—	-1.2	V
Output voltage	$V_O$		-16.0	—	—	V
Booster current consumption	$I_{opr}$	$R_L=\infty$ , $R_{OSC}=1M\Omega$ , $V_I=-5V$	—	40	70	$\mu A$
Stationary current	$I_Q$	$R_L=\infty$ , $V_I=-8V$	—	—	2.0	$\mu A$
Output impedance	$R_O$	$I_o=10mA$ , $V_I=-5V$	—	80	120	$\Omega$
Booster power conversion efficiency	$P_{eff}$	$I_o=5mA$ , $V_I=-5V$	90	95	—	%
Input leakage current	$I_{LI}$	OSC1 terminal, $V_I=-8V$	—	—	2.0	$\mu A$
Oscillation frequency	$f_{osc}$	$R_{OSC}=1M\Omega$ , $V_I=-5V$	16	20	24	kHz

### ■ RECOMMENDED OPERATING CONDITIONS

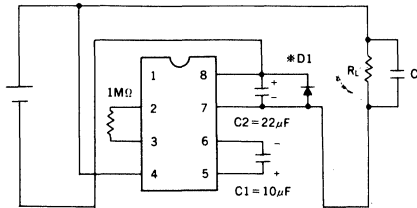
( $V_{DD}=0V$ ,  $T_a=-30$  to  $85^\circ C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Booster start voltage	$V_{STA1}$	$R_{OSC}=1M\Omega$ , $C_L/C_2 \leq 1/20$ *1 $C_2 \geq 10\mu F$ $T_a=-20$ to $85^\circ C$	—	—	-1.2	V
	$V_{STA2}$	$R_{OSC}=1M\Omega$	—	—	-2.2	V
Booster stop voltage	$V_{STP}$	$R_{OSC}=1M\Omega$	-1.2	—	—	V
Output load resistance	$R_L$		$R_L$ min *2	—	—	$\Omega$
Output current	$I_o$		—	—	30	mA
Oscillation frequency	$f_{osc}$		10	—	30	kHz
External resistance for oscillation	$R_{OSC}$		680	—	2000	k $\Omega$
Capacitor for booster	$C_1, C_2, C_3$		3.3	—	—	$\mu F$

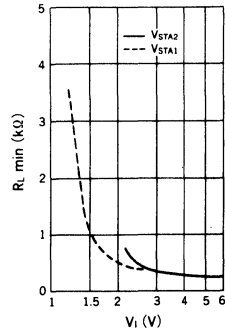
\*1 Recommended circuitry in low voltage operation is shown below.

\*2  $R_L$  min depends on input voltage as shown below.

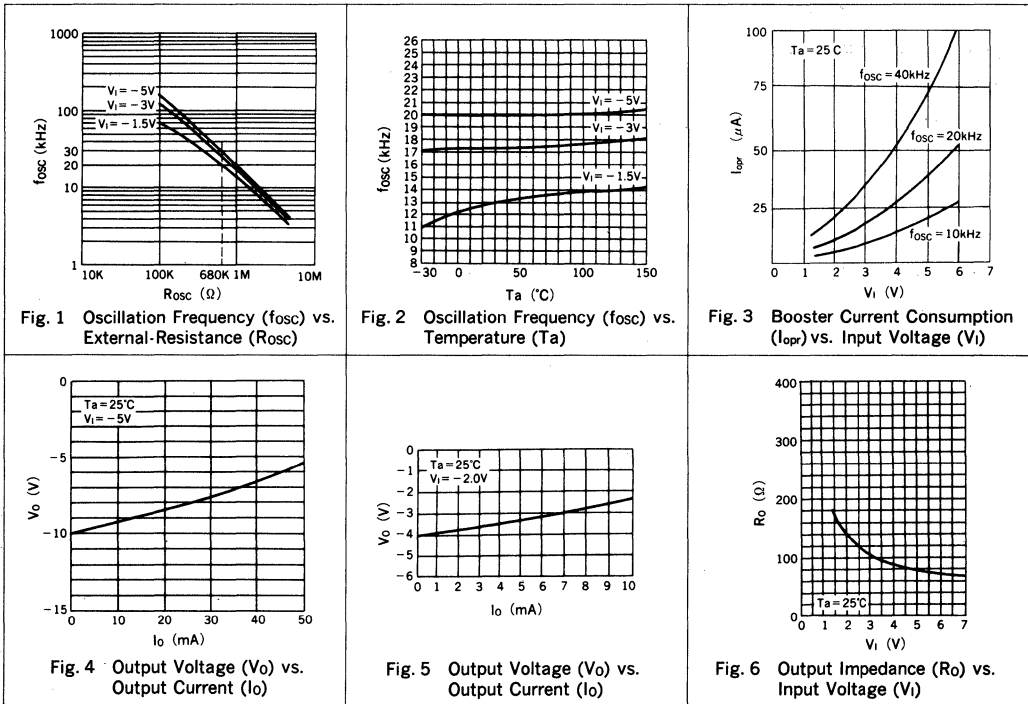
Recommended circuit in low voltage operation



\*D1 (VF(1F=1mA) ≤ 0.6V)



■ TYPICAL PERFORMANCE CHARACTERISTICS





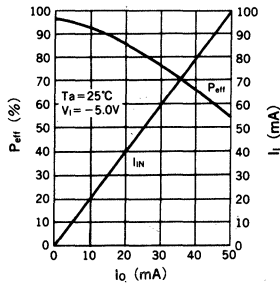


Fig. 7 Power Conversion Efficiency ( $P_{eff}$ )/Input Current ( $I_i$ ) vs. Output Current ( $I_o$ )

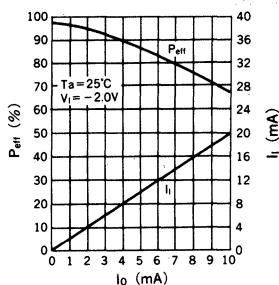


Fig. 8 Power Conversion Efficiency ( $P_{eff}$ )/Input Current ( $I_i$ ) vs. Output Current ( $I_o$ )

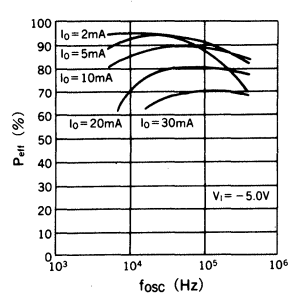


Fig. 9 Power Conversion Efficiency ( $P_{eff}$ ) vs. Oscillation Frequency ( $f_{osc}$ )

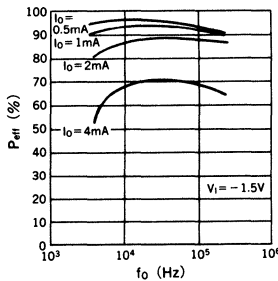
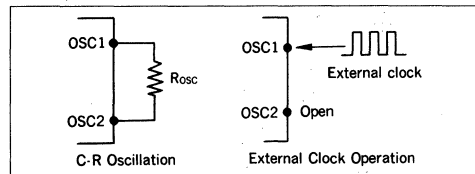


Fig. 10 Power Conversion Efficiency ( $P_{eff}$ ) vs. Oscillation Frequency ( $f_{osc}$ )

## ■ CIRCUIT DESCRIPTION

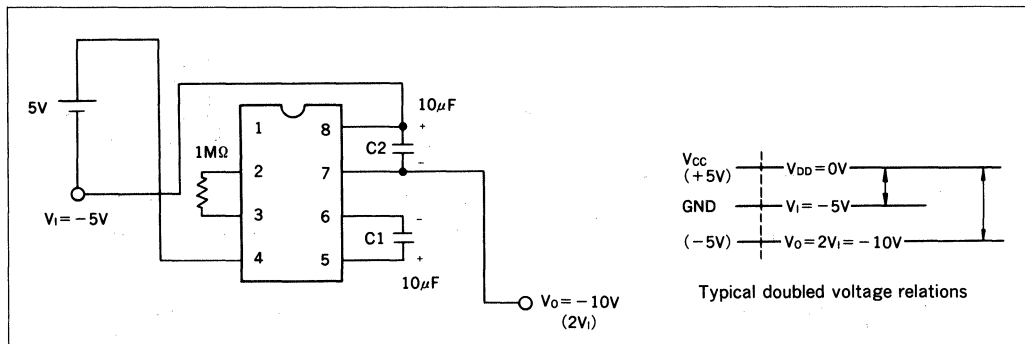
### ● C-R Oscillator

The SCI7660C contains a C-R oscillator for internal oscillation. It consists of an external resistor  $R_{osc}$  connected between the OSC1 pin and OSC2 pin.



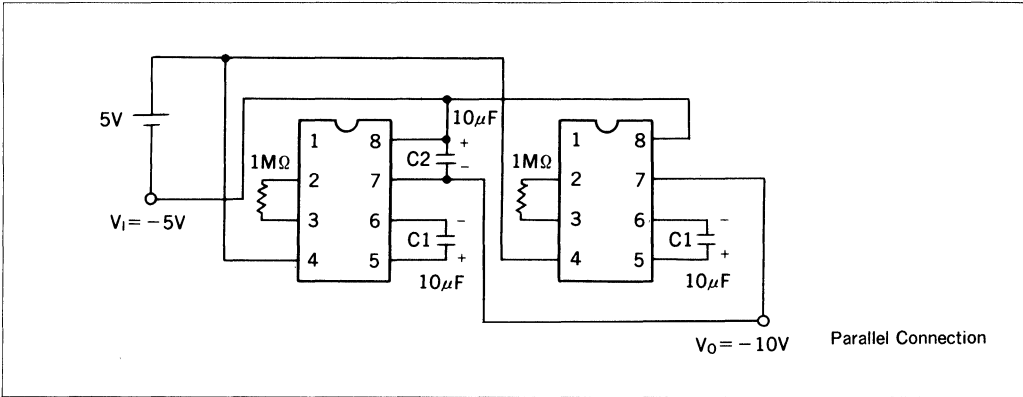
### ● Voltage Converters

The voltage converters double the input supply voltage ( $V_i$ ) using clocks generated by the C-R oscillator. A doubled voltage can be obtained with a booster capacitor between CAP+ and CAP-, and with an external smoothing capacitor between  $V_i$  and  $V_o$ .

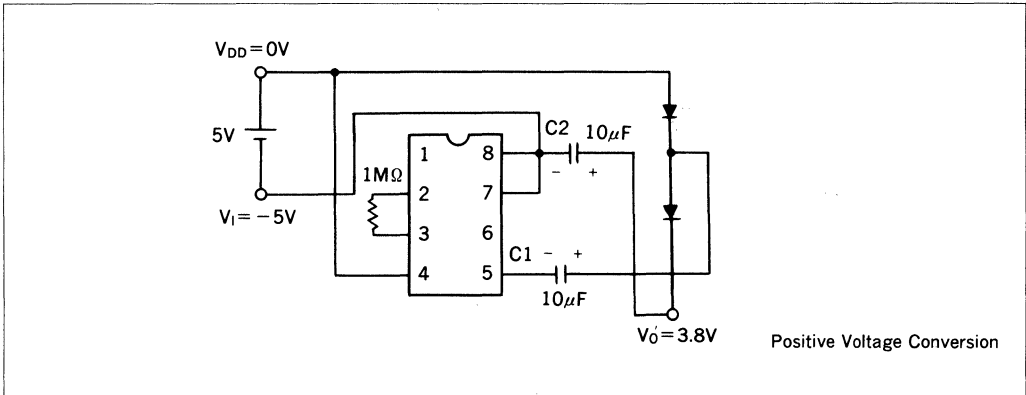


■ EXAMPLE OF APPLICATIONS

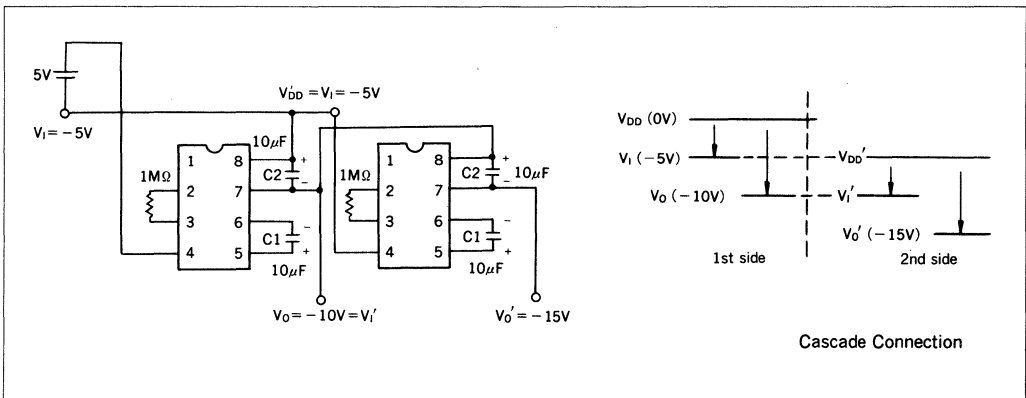
- **Parallel Connection** (Output impedance can be reduced by parallel connections.)



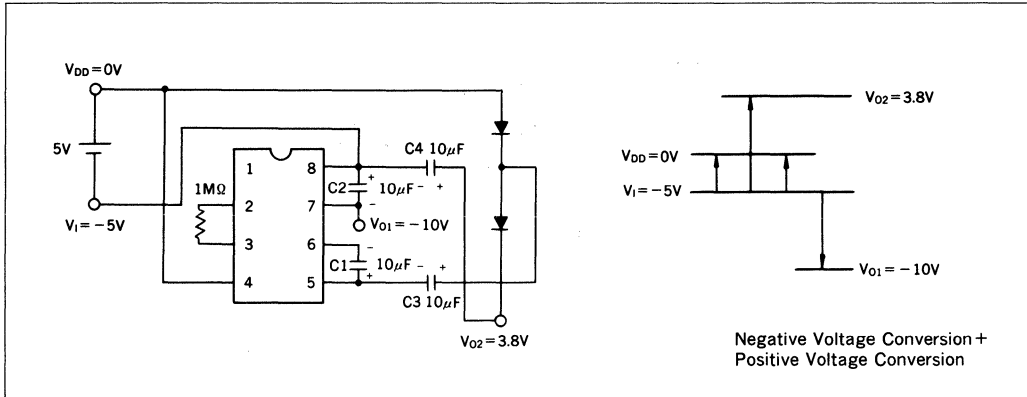
- **Positive Voltage Conversion** (Input voltage can be doubled toward the positive side with diode.)



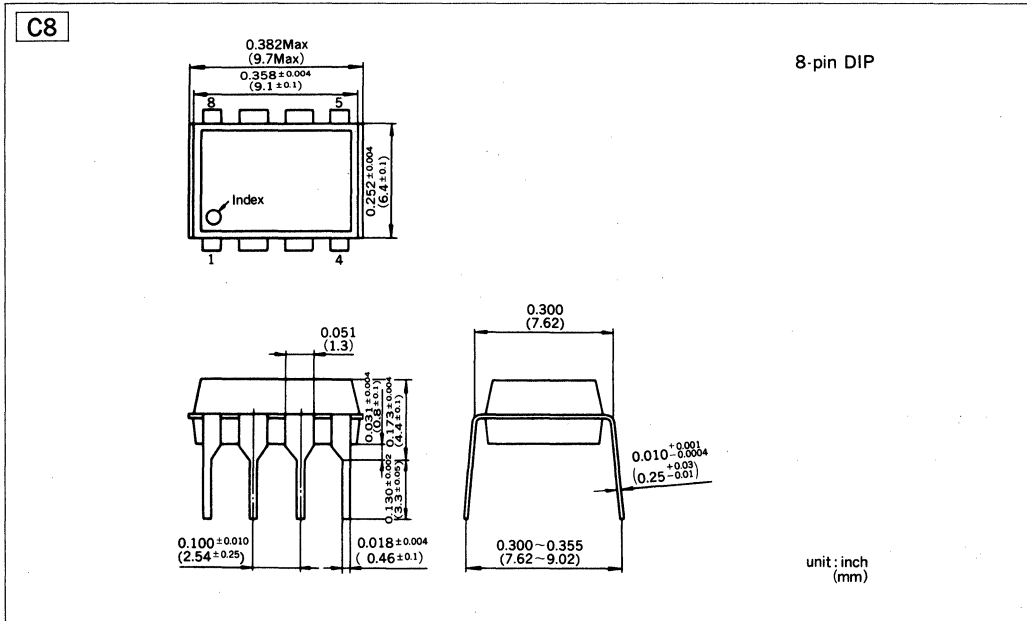
- **Cascade Connection** (Cascade connection of SCI7660 further increase the output voltage. Note, however, that the cascade connection increase the output impedance.)



● **Negative Voltage Conversion+Positive Voltage Conversion** (This circuit produces outputs of  $-10V$  and  $+3.8V$  from the  $-5V$  input by combination of voltage doubler circuit and positive voltage conversion circuit.)



■ **PACKAGE DIMENSIONS**



# SCI7661C/M

## CMOS DC/DC CONVERTER

- 95% Typical Power Efficiency
- Doubled/Tripled Output Voltage
- Internal Voltage Regulator

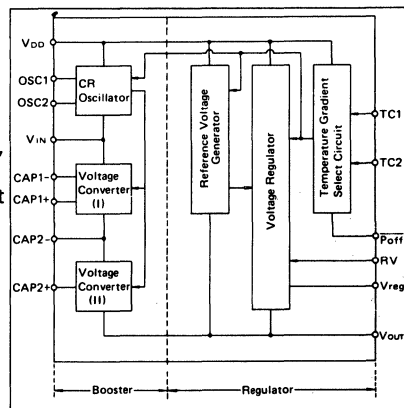
### DESCRIPTION

The SCI7661C CMOS DC/DC Converter features high operational performance with low power dissipation. It consists of two major parts: the booster circuitry and the regulator circuitry. The booster generates a doubled output voltage (-2.4V to -12V) or tripled output voltage (-3.6V to -18V) from the input (-1.2 to -6V). The regulator is capable of setting the output to any desired voltage. The regulated voltage can be given one of the three threshold temperature gradients.

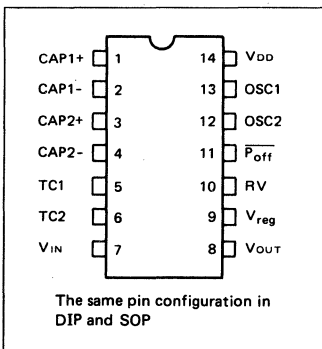
### FEATURES

- High performance with low power dissipation
- Simple conversion of  $V_{IN}$  (-5V) to  $|V_{IN}|$  (+5V),  $2|V_{IN}|$  (+10V),  $2V_{IN}$  (-10V) or  $3V_{IN}$  (-15V)
- On-chip output voltage regulator
- Power conversion efficiency – Typ95%
- Temperature gradient for LCD power supply – 0.1%/°C, 0.4%/°C or 0.6%/°C
- Power off by external signals – Stationary current at power off – Max 2μA
- Cascade connection – two device connected:  
 $V_{IN} = -5V$ ,  $V_{OUT} = -20V$
- On-chip C-R oscillator
- Package..... SCI7661C ..... 14-pin DIP (plastic)  
SCI7661M ..... 14-pinSOP(plastic)

### BLOCK DIAGRAM



### PIN CONFIGURATION



### PIN DESCRIPTION

Terminal	No.	Functions
CAP1+, CAP1-	1, 2	Terminal for connection of capacitor for doubler
CAP2+, CAP2-	3, 4	Terminal for connection of capacitor for tripler
TC1, TC2	5, 6	Temperature gradient selection terminal
VIN	7	Power supply terminal (negative, system supply GND)
VOUT	8	Output terminal at tripling
Vreg	9	Regulated voltage output terminal
RV	10	Regulated voltage control terminal
Poff	11	Vreg output ON/OFF control terminal
OSC2, OSC1	12, 13	Oscillation resistor connection terminal
VDD	14	Power supply terminal (positive system supply Vcc)

## ■ ABSOLUTE MAXIMUM RATINGS

(V<sub>DD</sub> = 0V)

Parameter	Symbol	Ratings		Unit	Remarks
		Min	Max		
Input supply voltage	V <sub>I</sub>	-20/N	0.5	V	N = 2: Doubler N = 3: Tripler
Input terminal voltage	V <sub>I</sub>	V <sub>IN</sub> -0.5	0.5	V	OSC1, P <sub>off</sub>
		V <sub>OUT</sub> -0.5	0.5	V	TC1, TC2, RV
Output voltage	V <sub>O</sub>	-20.0		V	
Allowable loss	P <sub>d</sub>		300	mW	
Operating temperature	T <sub>opr</sub>	-30	85	°C	Plastic package
Storage temperature	T <sub>stg</sub>	-55	150	°C	

## ■ ELECTRICAL CHARACTERISTICS

(V<sub>DD</sub> = 0V, V<sub>IN</sub> = -5V, T<sub>a</sub> = -30 to 85°C)

Parameter	Symbol	Ratings			Unit	Conditions
		Min	Typ	Max		
Input supply voltage	V <sub>I</sub>	-6.0		-1.2	V	
Output voltage	V <sub>O</sub>	-18.0			V	
	V <sub>reg</sub>	-18		-2.6	V	R <sub>L</sub> = ∞, R <sub>RV</sub> = 1MΩ, V <sub>O</sub> = -18V
Regulator operating voltage	V <sub>OUT</sub>	-18.0		-3.2	V	
Booster current consumption	I <sub>opr1</sub>		60	100	μA	R <sub>L</sub> = ∞, R <sub>osc</sub> = 1MΩ
Regulator current consumption	I <sub>opr2</sub>		5.0	12.0	μA	R <sub>L</sub> = ∞, R <sub>RV</sub> = 1MΩ V <sub>OUT</sub> = -15V
Stationary current	I <sub>Q</sub>			2.0	μA	TC2 = TC1 = V <sub>OUT</sub> , R <sub>L</sub> = ∞
Oscillation frequency	f <sub>osc</sub>	16	20	24	kHz	R <sub>osc</sub> = 1MΩ
Output impedance	R <sub>OUT</sub>		150	200	Ω	I <sub>OUT</sub> = 10mA
Booster power conversion efficiency	P <sub>eff</sub>	90	95		%	I <sub>OUT</sub> = 5mA
Regulated output voltage fluctuation	$\frac{\Delta V_{reg}}{\Delta V_{OUT} \cdot V_{reg}}$		0.2		%/V	-18V < V <sub>OUT</sub> < -8V, V <sub>reg</sub> = -8V, R <sub>L</sub> = ∞, T <sub>a</sub> = 25°C
Regulated output load fluctuation	$\frac{\Delta V_{reg}}{\Delta I_{OUT}}$		5		Ω	V <sub>OUT</sub> = -15V, V <sub>reg</sub> = -8V, T <sub>a</sub> = 25°C 0 < I <sub>OUT</sub> < 10mA, TC1 = V <sub>DD</sub> TC2 = V <sub>OUT</sub>
Regulated output saturation resistance	R <sub>SAT</sub>		8		Ω	R <sub>SAT</sub> = Δ(V <sub>reg</sub> - V <sub>OUT</sub> )/ΔI <sub>OUT</sub> 0 < I <sub>OUT</sub> < 10mA, R <sub>V</sub> = V <sub>DD</sub> , T <sub>a</sub> = 25°C
Reference voltage	VRV0	-2.3	-1.5	-1.0	V	TC2 = V <sub>OUT</sub> , TC1 = V <sub>DD</sub> , T <sub>a</sub> = 25°C
	VRV1	-1.7	-1.3	-1.1	V	TC2 = TC1 = V <sub>OUT</sub> , T <sub>a</sub> = 25°C
	VRV2	-1.1	-0.9	-0.8	V	TC2 = V <sub>DD</sub> , TC1 = V <sub>OUT</sub> , T <sub>a</sub> = 25°C
Temperature Gradient	CT0	-0.25	-0.1	-0.06	%/°C	$CT = \frac{ V_{reg}(50^\circ C) -  V_{reg}(0^\circ C) }{50^\circ C - 0^\circ C}$ $\times \frac{1}{ V_{reg}(25^\circ C) } \times 100$
	CT1	-0.5	-0.4	-0.3	%/°C	
	CT2	-0.7	-0.6	-0.5	%/°C	
Input leakage current	I <sub>L</sub>			2.0	μA	P <sub>off</sub> , TC1, TC2, OSC1, RV pins

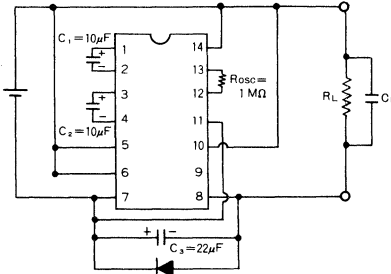
## RECOMMENDED OPERATING CONDITIONS

( $T_a = -30 \sim 85^\circ\text{C}$ )

Parameter	Symbol	Ratings		Unit	Remarks
		Min	Max		
Booster start voltage	$V_{STA1}$		-1.2	V	$R_{OSC} = 1\text{M}\Omega$ , $C_3 \geq 10\mu\text{F}$ *2 $CL/C_3 \leq 1/20$ , $T_a = -20$ to $85^\circ\text{C}$
	$V_{STA2}$		-2.2	V	
Booster stop voltage	$V_{STP}$	-1.2		V	$R_{OSC} = 1\text{M}\Omega$
Output load resistance	$R_L$	$R_L \text{ min}^*3$		$\Omega$	
Output load current	$I_{OUT}$		20	mA	
Oscillation frequency	$f_{OSC}$	10	30	kHz	
External resistance for oscillation	$R_{OSC}$	680	2000	$\text{k}\Omega$	
Capasitor for booster	$C_1, C_2, C_3$	3.3		$\mu\text{F}$	
Regulated output adjustable resistance	$R_{RV}$	100	1000	$\text{k}\Omega$	

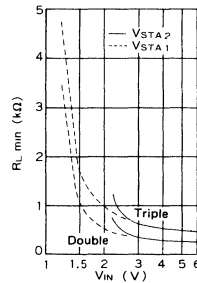
\*1  $V_{DD} = 0\text{V}$

\*2 Recommended circuitry in low voltage operation is shown below  
( $V_{IN} = -1.2\text{V} \sim -2.2\text{V}$ )



D, ( $V_f (I_f = 1\text{mA}) \leq 0.6\text{V}$ )

\*3  $R_L \text{ min}$  depends on input voltage as shown below.



## PERFORMANCE CURVES

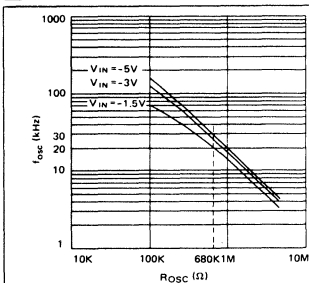


Fig. 1 Oscillation Frequency ( $f_{osc}$ ) vs. External Resistance ( $R_{osc}$ )

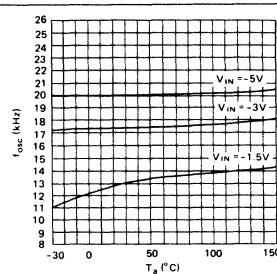


Fig. 2 Oscillation Frequency ( $f_{osc}$ ) vs. Temperature ( $T_a$ )

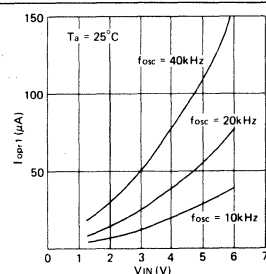


Fig. 3 Input Voltage ( $V_{IN}$ ) vs. Booster Current Consumption ( $I_{opr1}$ )

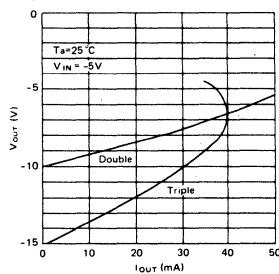


Fig. 4 Output Voltage ( $V_{out}$ ) vs. Output Current ( $I_{out}$ )

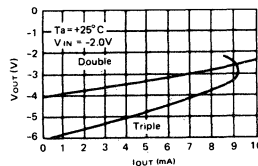


Fig. 5 Output Voltage ( $V_{out}$ ) vs. Output Current ( $I_{out}$ )

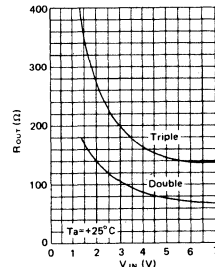
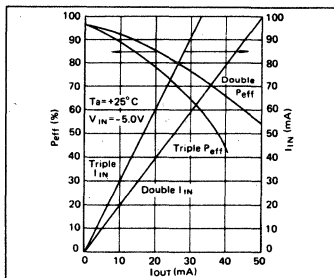
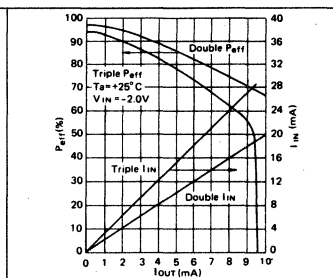


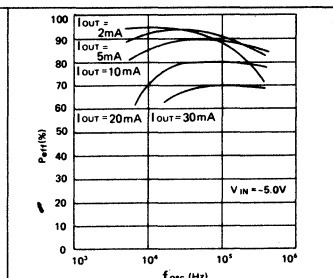
Fig. 6 Output Impedance ( $R_{out}$ ) vs. Input Voltage ( $V_{IN}$ )



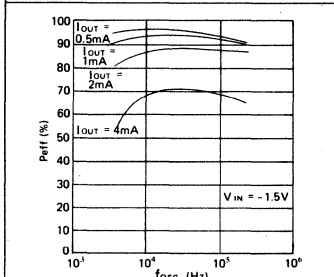
**Fig. 7 Power Conversion Efficiency (Peff)/Input Current (I<sub>in</sub>) vs. Output Current (I<sub>out</sub>)**



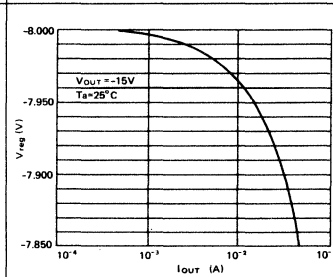
**Fig. 8 Power Conversion Efficiency (Peff)/Input Current (I<sub>in</sub>) vs. Output Current (I<sub>out</sub>)**



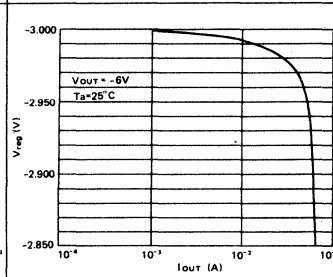
**Fig. 9 Power Conversion Efficiency (Peff) vs. Oscillation Frequency (fosc)**



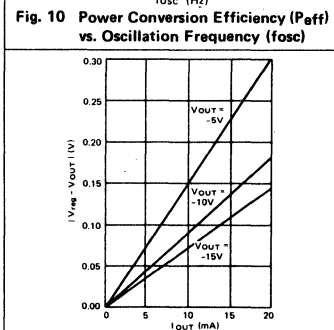
**Fig. 10 Power Conversion Efficiency (Peff) vs. Oscillation Frequency (fosc)**



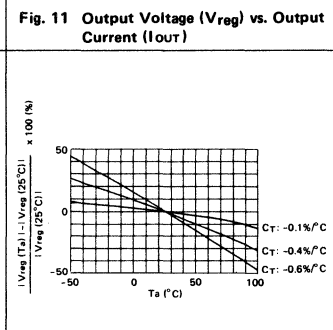
**Fig. 11 Output Voltage (V<sub>reg</sub>) vs. Output Current (I<sub>out</sub>)**



**Fig. 12 Output Voltage (V<sub>reg</sub>) vs. Output Current (I<sub>out</sub>)**



**Fig. 13 Regulated Output Saturation Resistance (RsAT) |V<sub>reg</sub> - V<sub>out</sub>| - I<sub>out</sub>**

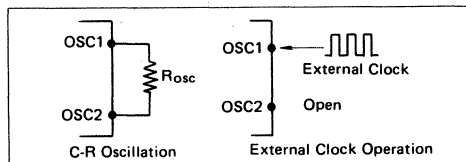


**Fig. 14 Output Voltage (V<sub>reg</sub>) vs. Temperature (T<sub>a</sub>)**

**■ CIRCUIT DESCRIPTION**

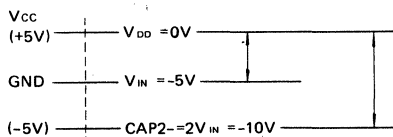
● **C-R Oscillator**

The SCI7661C contains a C-R oscillator for internal oscillation. It consists of an external resistor  $R_{osc}$  connected between the OSC1 pin and OSC2 pin.

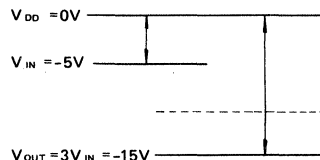


● **Voltage Converters**

The voltage converters double/triple the input supply voltage ( $V_{IN}$ ) using clocks generated by the C-R oscillator.



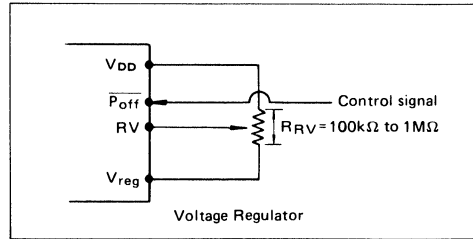
Typical Doubled Voltage Relations



Typical Tripled Voltage Relations

● **Reference Voltage Generator and Voltage Regulator**

The reference voltage generator produces reference voltage needed for operation of regulator circuit. The voltage regulator is used to regulate a boosted output voltage and its circuit contains a power-off function which uses signals from the system for on-off control of the  $V_{reg}$  output.



● **Temperature Gradient Selector Circuit**

The SCI7661C provides the  $V_{reg}$  output with a temperature gradient suitable for LCD driving.

● **Temperature Gradient Assignment**

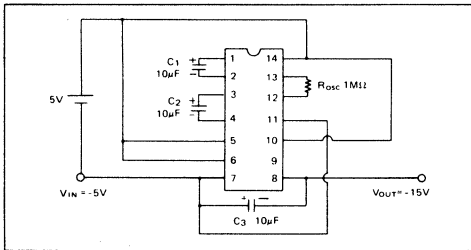
$\overline{P_{off}}$	TC2	TC1	Temp. Gradient	$V_{reg}$ Output	CR oscillation	Remarks
1 ( $V_{DD}$ )	L ( $V_{OUT}$ )	L ( $V_{OUT}$ )	-0.4%/°C	ON	ON	Cascade connection
1	L	H ( $V_{DD}$ )	-0.1%/°C	ON	ON	
1	H ( $V_{DD}$ )	L	-0.6%/°C	ON	ON	
1	H	H	-0.6%/°C	ON	OFF	
0 ( $V_{IN}$ )	L	L	—	OFF (Hi-Z)	OFF	Without regulation
0	L	H	—	OFF (Hi-Z)	OFF	
0	H	L	—	OFF (Hi-Z)	OFF	
0	H	H	—	OFF (Hi-Z)	ON	

NOTE: The potential at Low level is different between the  $\overline{P_{off}}$  pin and the TC1/TC2 pin.

■ **EXAMPLE OF APPLICATIONS**

● **Voltage Doubler and Tripler**

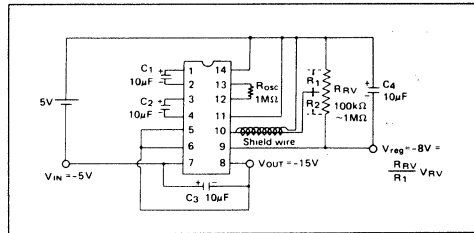
A doubled voltage can be obtained at  $V_{OUT}$  (CAP2-) by disconnecting capacitor  $C_2$  from the tripler configuration and shorting CAP2- (pin 4) and  $V_{OUT}$  (pin 8).



Voltage Tripler

● **Voltage Tripler + Regulator**

$V_{reg}$  output is given a temperature gradient, after boosted output  $V_{OUT}$  regulated. In this connection, both  $V_{OUT}$  and  $V_{reg}$  can be taken out at the same time.



Tripler + Regulator  
(-0.4%/°C selected as temperature gradient)

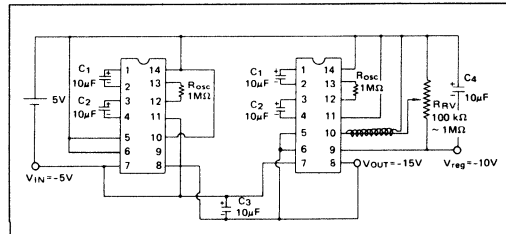
● **Parallel Connection**

Parallel connection of n circuits can reduce  $R_{out}$  to about  $1/n$ , that output impedance  $R_{out}$  can be reduced by connecting serial configuration. A single smoothing capacitor  $C_3$  can be used commonly for all parallelly connected circuit.

In parallelly connection, a regulated output can be obtained by applying the regulation circuit to only one of the n parallelly connected circuit.

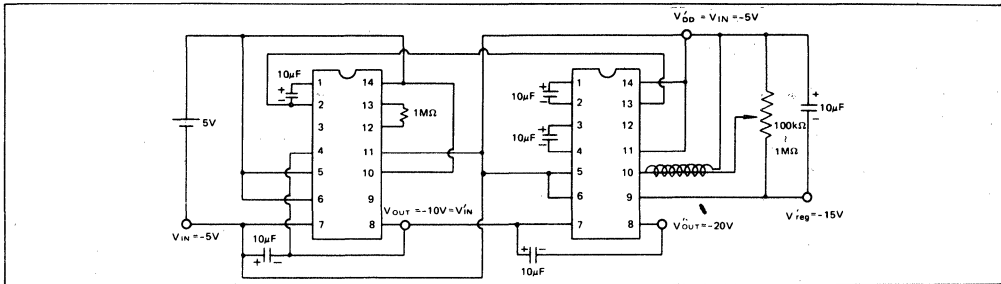
● **Cascade Connection**

Cascade connection of SCI7661C (by connecting  $V_{IN}$  and  $V_{OUT}$  of one stage to  $V_{DD}$  and  $V_{IN}$  respectively of the next stage) further increase the output voltage. Note, however, that the serial connection increases the output impedance.



Parallel Connection

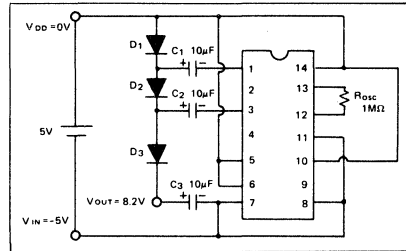




Serial Connection

● **Positive Voltage Conversion**

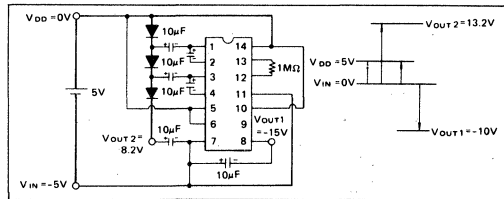
The input voltage can be doubled or tripled toward the positive side. (In the doubler configuration, capacitor C2 and diode D3 are disconnected and the diode D3 shorted at the both ends.) In this case, however, the output voltage decrease by  $V_F$  (forward voltage). For example  $V_{DD} = 0V$ ,  $V_{IN} = -5V$  and  $V_F = 0.6V$ , then  $V_{OUT} = 10V - 3 \times 0.6V = 8.2V$  (if doubled,  $5V - 2 \times 0.6V = 3.8V$ )



Positive Voltage Conversion D1, D2, D3: Shottky diodes with small  $V_F$  are recommended.

● **Negative Voltage Conversion + Positive Voltage Conversion**

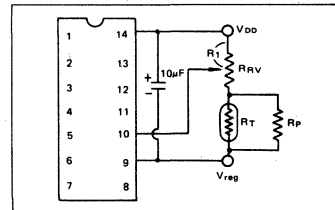
This circuit produces outputs of  $-15V$  and  $+8.2V$  from the  $-5V$  input. Note that this configuration causes higher output impedance than in a single function (negative or positive voltage converter).



Negative Voltage Conversion + Positive Voltage Conversion

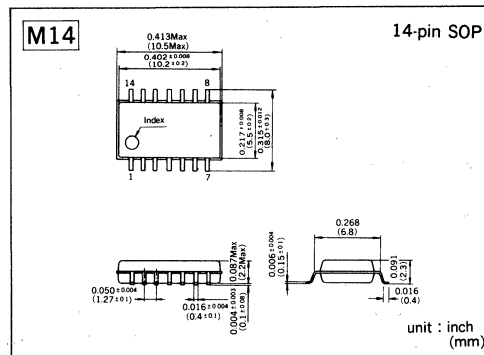
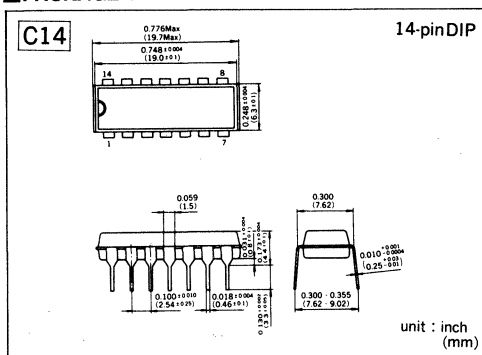
● **Changing the Temperature Gradient through Use of External Temperature Sensor (Thermistor)**

The SCI7661C has a temperature gradient selector circuit in its regulator. It selects any one of the three gradients:  $-0.1\%/^{\circ}C$ ,  $-0.4\%/^{\circ}C$  and  $-0.6\%/^{\circ}C$ . It is necessary that the temperature gradient can be changed to any other value by connecting a thermistor in series to the output voltage control resistor  $R_{RV}$ .



Example of Change of Temperature Gradient

■ **PACKAGE DIMENSIONS**



# SED3064F

## CMOS 8×8 ANALOG SWITCH ARRAY

- Low ON state resistance
- Built-in address decoder and control memory for switches

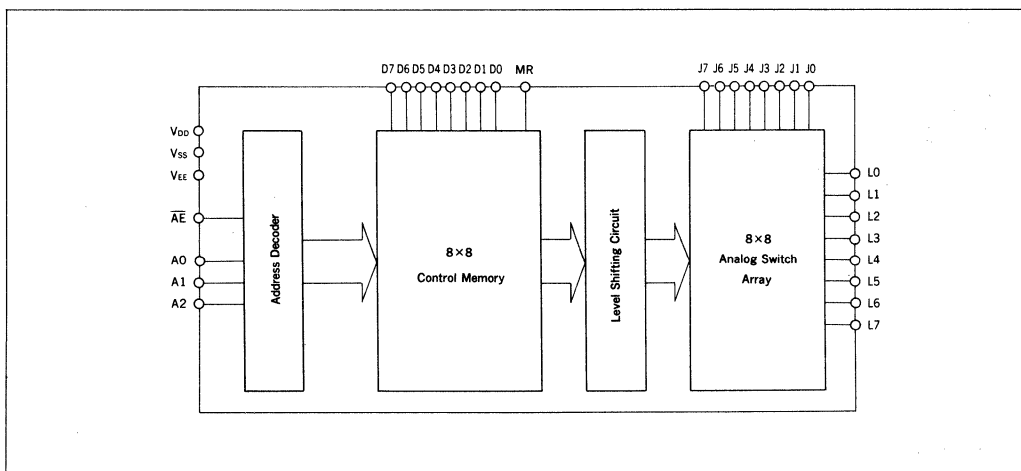
### DESCRIPTION

The SED3064F is a CMOS LSI 8×8 analog switch array incorporating a built-in address decoder and memory control for switches, moreover, with data reset mechanism for each switch. This circuit consists of 64 cross point switches in 8×8 array. Any one of the cross points can be selected, and can be turned on or off. Either analog or digital power supply is applied to the circuit depends on the DC voltage level of signals. Since the difference of "ON" resistance values between each switch on circuit is very small, change in (voltage) level for signals can be minimized.

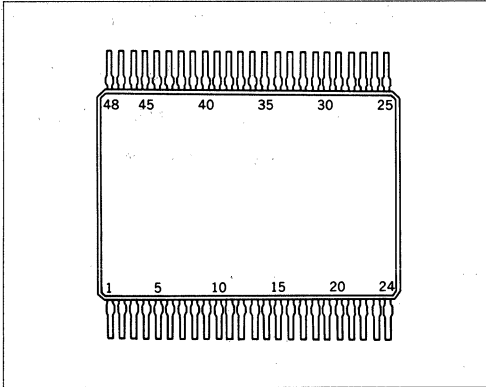
### FEATURES

- 8×8 analog switch array
- Low "ON" state resistance ..... 125Ω Max at  $V_{DD} - V_{EE} = 10V$
- Maximum rating voltage .....  $V_{DD} - V_{SS} = 7V$  (on any logic pin)  
 $V_{DD} - V_{EE} = 13V$   
 (On any junctor or line)
- Built-in address decoder and control memory
- Separated power supply for switch array and logic circuit.
- "ON" resistance allowance ..... 25Ω (Max)
- Package ..... 48-pin QFP (plastic)

### BLOCK DIAGRAM



## PIN CONFIGURATION



Pin No.	Symbol	Pin No.	Symbol	Pin No.	Symbol	Pin No.	Symbol
1	MR	13	D3	25	L3	37	NC
2	NC	14	D2	26	L2	38	NC
3	$\overline{AE}$	15	D1	27	L1	39	J4
4	$V_{EE}$	16	D0	28	L0	40	J5
5	NC	17	NC	29	NC	41	J6
6	NC	18	NC	30	NC	42	J7
7	D7	19	NC	31	NC	43	NC
8	D6	20	NC	32	NC	44	$V_{DD}$
9	D5	21	L7	33	J0	45	A0
10	D4	22	L6	34	J1	46	A1
11	NC	23	L5	35	J2	47	A2
12	NC	24	L4	36	J3	48	$V_{SS}$

## PIN DESCRIPTION

A0 to A2	Control memory address input
$\overline{AE}$	Control memory address enable input
MR	Master reset input
D0 to D7	Control memory data input
J0 to J7	Analog switch array input/output (junction)
L0 to L7	Analog switch array input/output (line)
$V_{DD}$	Positive analog/digital power supply
$V_{SS}$	Negative digital power supply
$V_{EE}$	Negative analog power supply
NC	No connection

## ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Ratings	Unit
Supply voltage	$V_{DD}-V_{SS}$	-0.3 to 7	V
	$V_{DD}-V_{EE}$	-0.3 to 16	V
	$V_{SS}-V_{EE}$	-0.3 to 16	V
Input voltage	$V_i$	$V_{SS}-0.3$ to $V_{DD}+0.3$ $V_{EE}-0.3$ to $V_{DD}+0.3$	V
Power dissipation	$P_D$	250	mW
Operating temperature	$T_{opr}$	-40 to 85	°C
Storage temperature	$T_{stg}$	-65 to 150	°C
Soldering temperature and time	$T_{sol}$	260°C, 10s (at lead)	—

## ELECTRICAL CHARACTERISTICS

### DC Electrical Characteristics

( $V_{DD}=5V$ ,  $V_{SS}=0V$ ,  $V_{EE}=-5V$ ,  $T_a=25^\circ C$  Unless Specified)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Supply voltage						
Digital	$V_{DD}-V_{SS}$		4.5	5	7	V
Analog	$V_{DD}-V_{EE}$		4.5	10	13	V
On state resistance	$R_{ON}$	$V_{Jn}-V_{Ln}=0.6V$ ( $n=0, \dots, 7$ )	—	90	125	$\Omega$
Difference in on state (resistance between any switches)	$\Delta R_{ON}$		—	—	25	$\Omega$
Input/Output off state leakage current	$I_{OFF}$		—	$\pm 0.02$	$\pm 100$	nA
Input voltage	$V_{IL}$		—	—	1.5	V
	$V_{IH}$		3.5	—	—	V
Quiescent device current	$I_Q$		—	0.1	10	$\mu A$

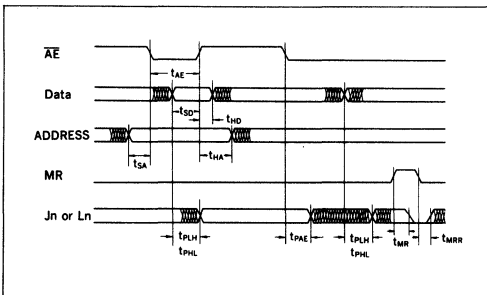
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Maximum current through cross point switch	$I_{Max}$		—	$\pm 8.0$	—	mA
Switch input capacitance	$C_{IL}$	$V_{in} = 0V$	—	100	—	pF
Switch output capacitance	$C_{OJ}$	$V_{in} = 0V$	—	110	—	pF
Feedthrough capacitance	$C_{IOS}$	$V_{in} = 0V$	—	0.2	—	pF
Digital input capacitance	$C_{IN}$	$V_{in} = 0V$	—	5	—	pF

### ●AC Electrical Characteristics

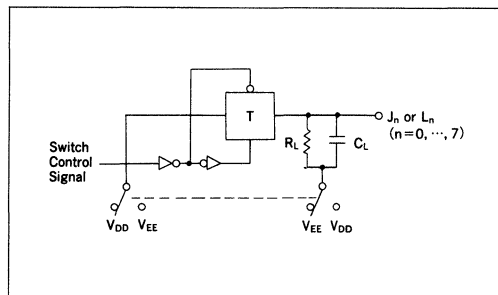
( $V_{DD} = 5V$ ,  $V_{SS} = 0V$ ,  $V_{EE} = -5V$ ,  $T_a = 25^\circ C$  Unless Specified)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit	
Sine wave response (Distortion)		$V_{is} = 5V (P-P)$ $R_L = 10k\Omega$ $f_{in} = 1kHz$	$V_{DD} - V_{SS} = 5V$ $V_{DD} - V_{EE} = 13V$	—	0.1	—	%
			$V_{DD} - V_{SS} = 5V$ $V_{DD} - V_{EE} = 10V$	—	0.2	—	
		$V_{DD} - V_{SS} = 5V$ $V_{DD} - V_{EE} = 5V$	—	1.0	—		
Maximum frequency response (Channel "ON" (Sine wave input))	$f_{Max}$ (I-O)	$V_{is} = 5V (P-P)$ $R_L = 1k\Omega$ ( $V_O/V_i$ ) dB = -3dB	—	40	—	MHz	
Feedthrough (Channel "OFF")		$V_{is} = 5V (P-P)$ $f_{in} = 1MHz$ $R_L = 1k\Omega$	—	-40	—	dB	
Crosstalk between any two channels		$f_{in} = 1MHz$ $f_{in} = 3.4kHz$ $R_L = 1k\Omega$	—	-40	—	dB	
			—	-90	—		
Propagation delay time signal input to signal output ( $J_n - L_n$ )	$t_{PS}$	Switch "ON" $C_L = 50pF$ $R_L = 10k\Omega$ $t_r = t_f = 20ns$ (input signal)	—	10	—	ns	
Turn "ON" propagation delay data input to signal output ( $D_n - J_n$ or $L_n$ )	$t_{PLH}$	$C_L = 50pF$ $R_L = 10k\Omega$ $t_r = t_f = 20ns$ (input signal)	—	120	400	ns	
	$t_{PHL}$						
Address enable to signal output ( $\overline{AE} - J_n$ or $L_n$ )	$t_{PAE}$	$C_L = 50pF$ $R_L = 10k\Omega$ $t_r = t_f = 20ns$ (input signal)	—	150	600	ns	
Minimum address enable pulse width	$t_{AE}$		—	30	80	ns	
Minimum set up time	Address to $\overline{AE}$	$t_{SA}$	0	50	80	ns	
	Data in to $\overline{AE}$	$t_{SD}$	0	50	80	ns	
Minimum hold time	Address to $\overline{AE}$	$t_{HA}$	0	50	80	ns	
	Data in to $\overline{AE}$	$t_{HD}$	0	50	80	ns	
Memory reset time	$t_{MR}$	$C_L = 50pF$ $R_L = 1k\Omega$	—	100	380	ns	
Memory reset recovery time	$t_{MRR}$	$C_L = 50pF$ $R_L = 1k\Omega$	—	200	380	ns	

### ●Timing Chart



### ●AC Electrical Measurement Circuit



## DESCRIPTION FOR MECHANISM

### Address Decoder

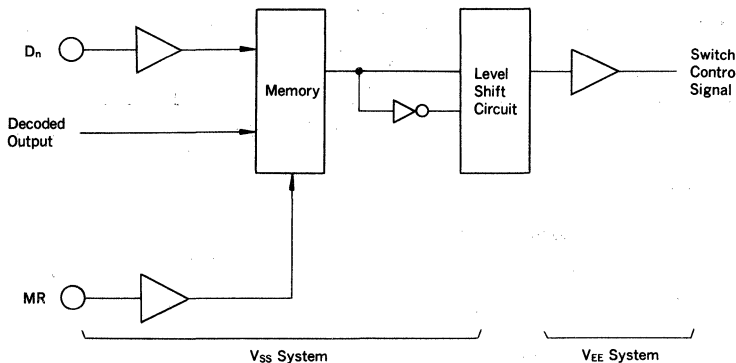
8 address lines are decoded by the combination of three ADDRESS (A0, A1, A2) inputs when the ADDRESS ENABLE ( $\overline{AE}$ ) is Low. The control memory is selected with the decoded output. All switches have corresponding control memory provided with data reset for each. A "1" written into a memory cell turns the corresponding crosspoint switch "ON" while a "0" causes the cross point to turn "OFF". Since the ADDRESS LINE ( $L_n$ ,  $n=0$  to 7) is corresponding to Analog Switch Array output. J0–L0 is turned on by selecting L0 ( $A0 = "L", A1 = "L", A2 = "L"$ ) for ADDRESS LINE, and also inputting "1" to D0 for INPUT DATA.

MR	$\overline{AE}$	ADDRESS			ADDRESS LINE	INPUT DATA								MEMORY CONTENT											
		A2	A1	A0		D7	D6	D5	D4	D3	D2	D1	D0	Q7	Q6	Q5	Q4	Q3	Q2	Q1	Q0				
H	X	X	X	X	all	X	X	X	X	X	X	X	X	X	X	X	L	L	L	L	L	L	L	L	L
L	H	X	X	X	none	X	X	X	X	X	X	X	X	X	X	X	NO CHANGE OF STATE								
L	L	L	L	L	L0	d7	d6	d5	d4	d3	d2	d1	d0	d7	d6	d5	d4	d3	d2	d1	d0				
L	L	L	L	H	L1																				
L	L	L	H	L	L2																				
L	L	L	H	H	L3																				
L	L	H	L	L	L4																				
L	L	H	L	H	L5																				
L	L	H	H	L	L6																				
L	L	H	H	H	L7																				

X: Don't care condition  
 di (i=0 to 7): Data (either "1" or "0")

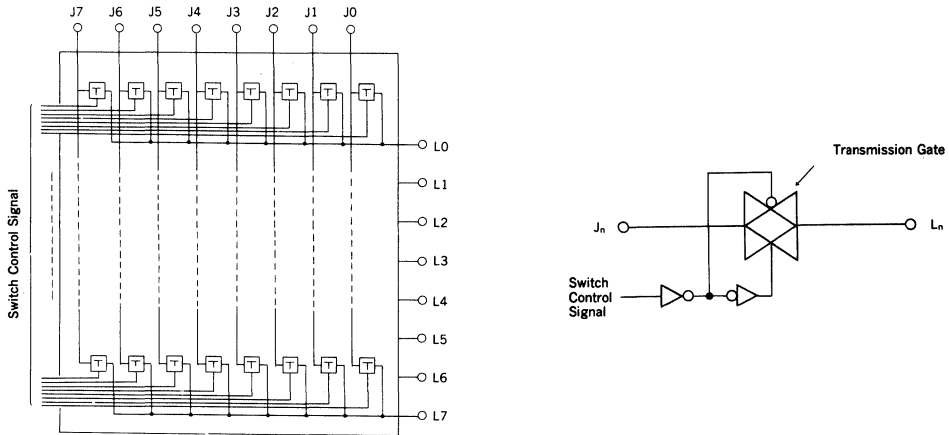
### Control Memory

When the previous decoded output is fixed to high level,  $D_n$  ( $n=0$  to 7) the INPUT DATA is read in. "1" written into INPUT DATA turns the corresponding crosspoint switch "ON" while "0" causes the crosspoint to turn "OFF". Since Control Memory provided with DATA RESET is corresponding to each switch one-to-one, it is possible to fix every switch to either "ON" or "OFF".



● Switch

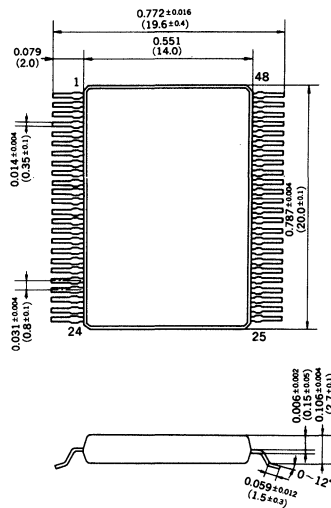
On chip 8×8 Analog Switch Array is controlled by the output of the previous control memory.



■ PACKAGE DIMENSIONS

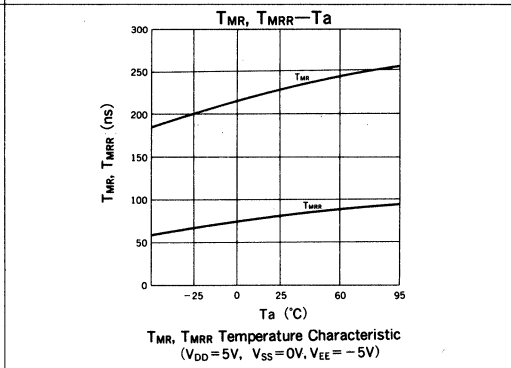
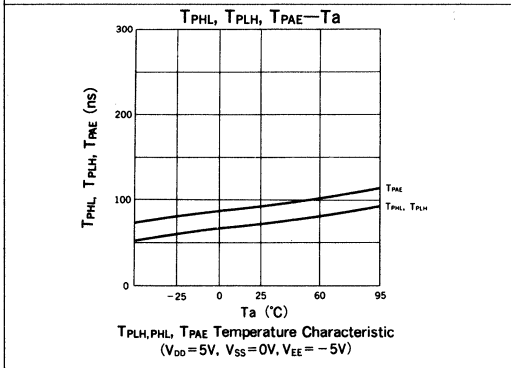
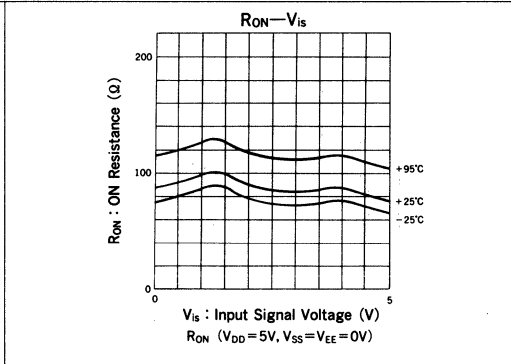
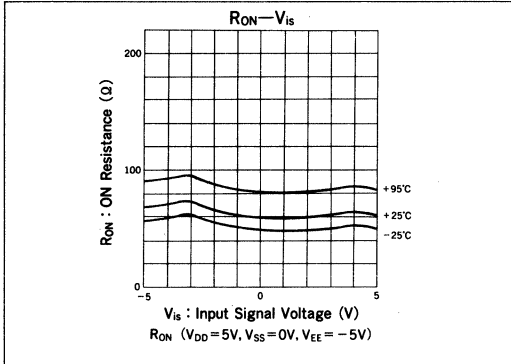
F48-5

48-pin QFP



unit : inch  
(mm)

**PERFORMANCE CURVES**



# SEA7000H

## MOS AREA IMAGE SENSOR

● **2/3-inch Size Solid State Imaging Device**

● **244 (Horizontal) × 244 (Vertical) Photo Sensor Incorporated**

### DESCRIPTION

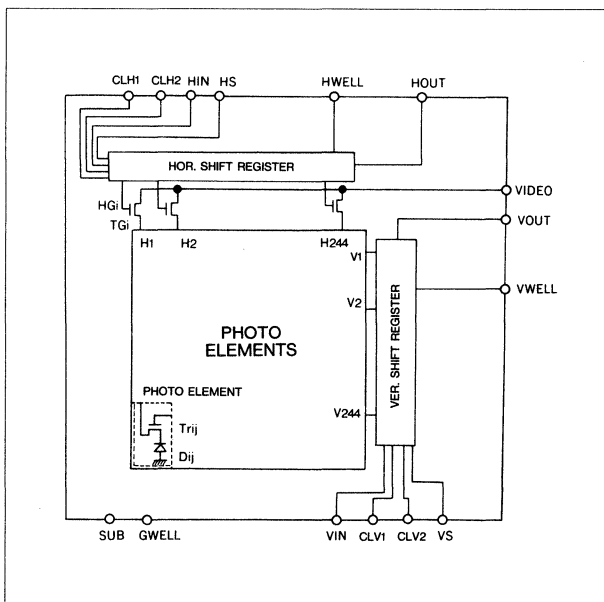
The SEA7000H is a MOS area image sensor designed for use with black-and-white video cameras. Implemented in unique technology, the sensor features suppressed blooming and low noise.

Because of the 2/3-inch size, the SEA7000H can be used with low-cost standard lenses. Combining it with a dedicated synchronization control LSI enables the user to easily build a compact video camera with high packaging density.

### FEATURES

- Photo elements.....244 (horizontal) × 244 (vertical)
- Resolution .....180 TV lines (horizontal)  
× 180 TV lines (vertical)
- Low voltage operation (7V) and low power consumption (70mW)
- Blooming suppressed by special technology
- Light-receiving area.....8.8 mm × 6.6 mm
- Peripheral circuits supported by dedicated synchronization control LSI
- Highly resistant to vibration and shock (operable under vibration)
- Package .....20-pin DIP (ceramic) with optical glass

### BLOCK DIAGRAM



### CIRCUIT CONFIGURATION

The SEA7000H consists of three blocks : photo element (photo diode cell) block, horizontal shift register block, and vertical shift register block.

#### ● Photo element block

244 selection lines V1 through V244 run horizontally and 244 signal lines H1 through H244 run vertically. A photo element consisting of a MOS transistor  $T_{rij}$  and a photo diode  $D_{ij}$  is located at each crossing point.

#### ● Horizontal shift register block

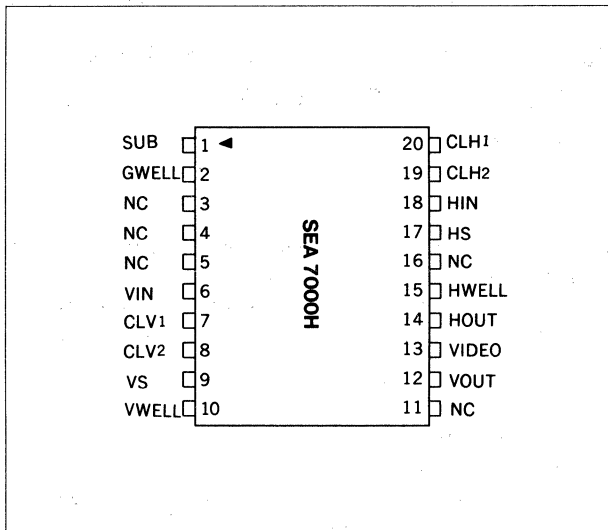
This block consists of 488 bit shift registers and MOS transistors  $T_{Gi}$  that are controlled with the output  $H_{Gi}$  of each bit as the gate signal.

#### ● Vertical shift register block

The vertical shift register block consists of 244 bit shift registers. The output of each bit becomes the scanning line  $V_j$ .



## ■ PIN CONFIGURATION



## ■ PIN DESCRIPTION

Pin No.	Terminal	Function
1	SUB	Board voltage
2	GWELL	Well voltage
6	VIN	Vertical S. R. input
7	CLV1	Vertical S. R. clock 1
8	CLV2	Vertical S. R. clock 2
9	VS	Vertical S. R. source
10	VWELL	Ground voltage (V)
12	VOUT	Shift register output
13	VIDEO	Video output
14	HOUT	Horizontal S. R. output
15	HWELL	Ground voltage (H)
17	HS	Horizontal S.R. source
18	HIN	Horizontal S.R. input
19	CLH2	Horizontal S.R. clock 2
20	CLH1	Horizontal S.R. clock 1
3, 4, 5, 11, 16	NC	No connection

## ■ ABSOLUTE MAXIMUM RATINGS

(VWELL = HWELL = 0V, Ta = 25°C)

Parameter	Symbol	Ratings	Unit
Terminal voltage (Horizontal S. R. input) *1	V <sub>H</sub>	-0.3 to 10	V
Terminal voltage (Vertical S. R. input) *2	V <sub>V</sub>	-0.3 to 10	V
Terminal voltage (Video bias)	V <sub>VIDEO</sub>	-0.3 to 10	V
Operating temperature	T <sub>opr</sub>	- 10 to 60	°C
Storage temperature	T <sub>stg</sub>	- 20 to 80	°C
Soldering temperature/time	T <sub>sol</sub>	260°C, 10s (lead only)	—

\*1 : HIN, CLH1, CLH2 \*2 : VIN, CLV1, CLV2

## ■ ELECTRICAL CHARACTERISTICS

### ● Recommended Operating Conditions

(VWELL = HWELL = 0V, Ta = 25°C)

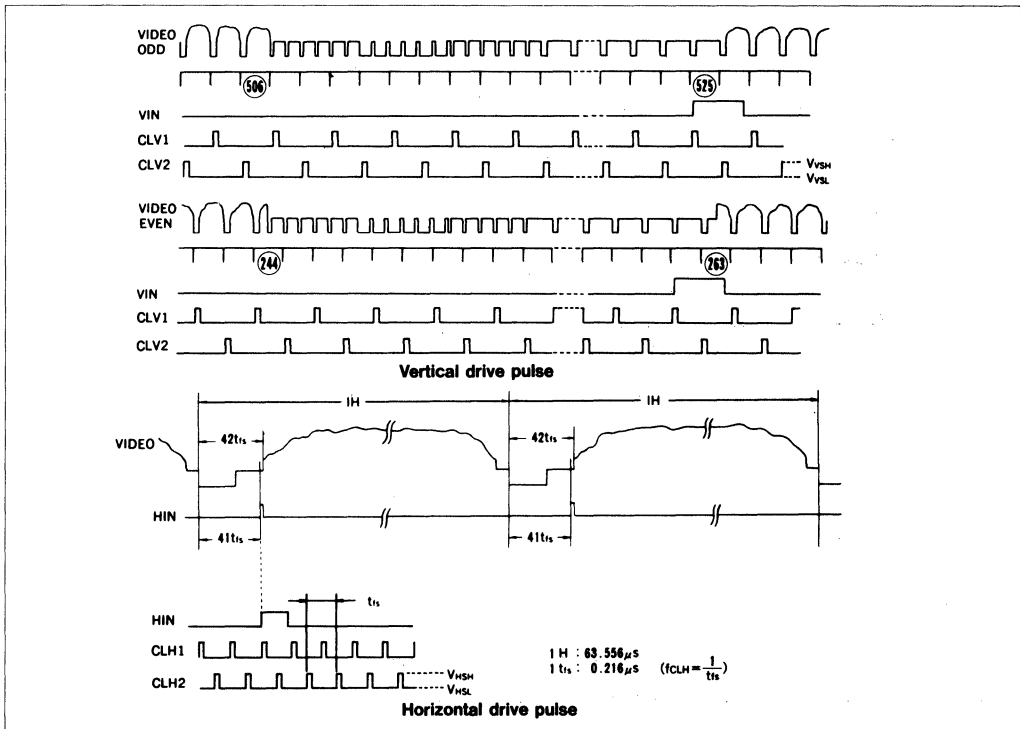
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Horizontal clock frequency	f <sub>CLH</sub>	V <sub>HSH</sub> = 7V	—	4.625	—	MHz
Vertical clock frequency	f <sub>CLV</sub>	V <sub>VSH</sub> = 7V	—	7.8	—	kHz
High level input voltage	V <sub>HSH</sub> , V <sub>VSH</sub>		—	7	—	V
Low level input voltage	V <sub>HSL</sub> , V <sub>VSL</sub>		—	0	—	V
GWELL voltage	V <sub>GWELL</sub>		—	0.8	—	V
SUB voltage	V <sub>SUB</sub>		—	7	—	V

### ● Opto-electrical Characteristics

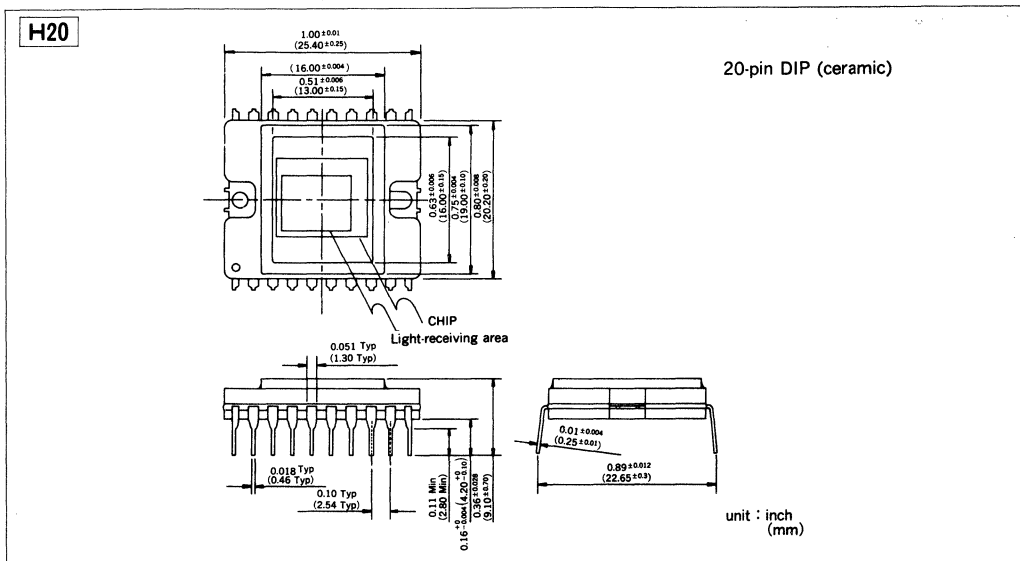
(VWELL = HWELL = 0V, Ta = 25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Saturated light quantity	L <sub>sat</sub>	V <sub>VIDEO</sub> = 3.0V	—	0.33	—	lx·sec
Sensitivity	S	V <sub>VIDEO</sub> = 3.0V	—	0.15	—	μA/lx
Horizontal resolution	R <sub>H</sub>		—	180	—	TVline
Vertical resolution	R <sub>V</sub>		—	180	—	TVline
Power consumption	P	F <sub>CLH</sub> = 4.625MHz, V <sub>HSH</sub> = V <sub>VSH</sub> = 7V	—	70	—	mW

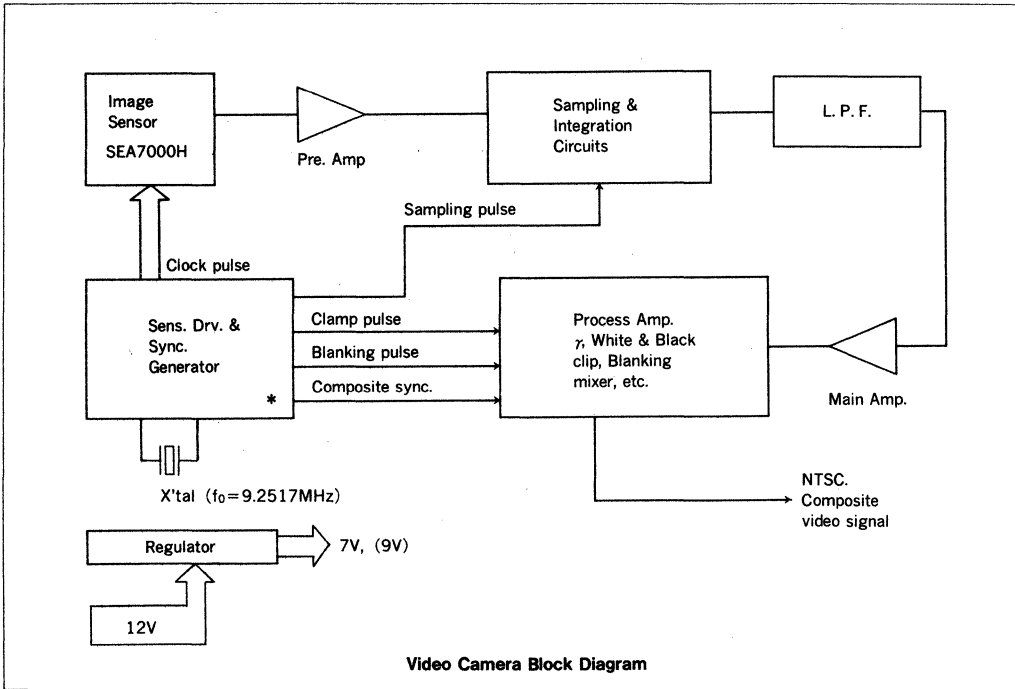
● Timing Chart



■ PACKAGE DIMENSIONS



■EXAMPLE OF APPLICATION (Peripheral Circuit Configuration)



\*:Sync. control LSI (flat plastic package) is available as a system support IC. (SED3081F<sub>2T</sub>)

**[Precaution to handle]**

1. The image sensor SEA7000H is a MOS LSI, so protect it against electrostatic breakdown. Never touch the sensor without grounding your body and the tools. Connect a resistance of about 1MΩ between the body and GND in series to ensure safety.
2. Do not touch the glass surface of the device. Wipe the surface, if soiled, with a clean applicator.
3. Take care not to drop the device, which has a glass cap.

# SEA7010H

## MOS AREA IMAGE SENSOR

- 8 mm Size Solid State Imaging Device
- 244 (Horizontal) × 244 (Vertical) Photo Sensor Incorporated

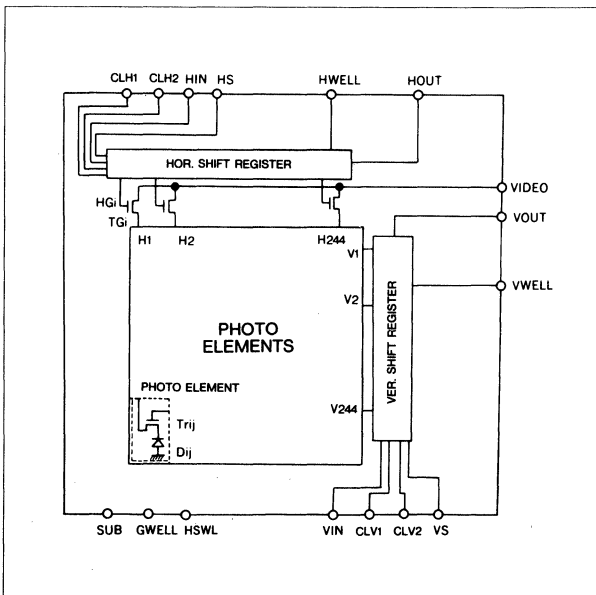
■ DESCRIPTION

The SEA7010H is a MOS area image sensor designed for use with black-and-white video cameras. Implemented in unique technology, the sensor features suppressed blooming and low noise. Because of its 8mm size, the SEA7010H can be used with low-cost standard lenses. Combining it with a dedicated synchronization control LSI enables the user to easily build a compact video camera with high packaging density.

■ FEATURES

- Photo elements.....244 (horizontal) × 244 (vertical)
- Resolution .....180 TV lines (horizontal) × 180 TV lines (vertical)
- Low voltage operation (7V) and low power consumption (50mW)
- Blooming suppressed by special technology
- Light-receiving area... 8 mm Size (5.3 mm × 4.0 mm)
- Peripheral circuits supported by dedicated synchronization control LSI
- Highly resistant to vibration and shock (operable under vibration)
- Package ..... 20-pin Shrink DIP (ceramic) with optical glass

■ BLOCK DIAGRAM



■ CIRCUIT CONFIGURATION

The SEA7010H consists of three blocks : photo element (photo diode cell) block, horizontal shift register block, and vertical shift register block.

● Photo element block

244 selection lines V1 through V244 run horizontally and 244 signal lines H1 through H244 run vertically. A photo element consisting of a MOS transistor Trij and a photo diode Dij is located at each crossing point.

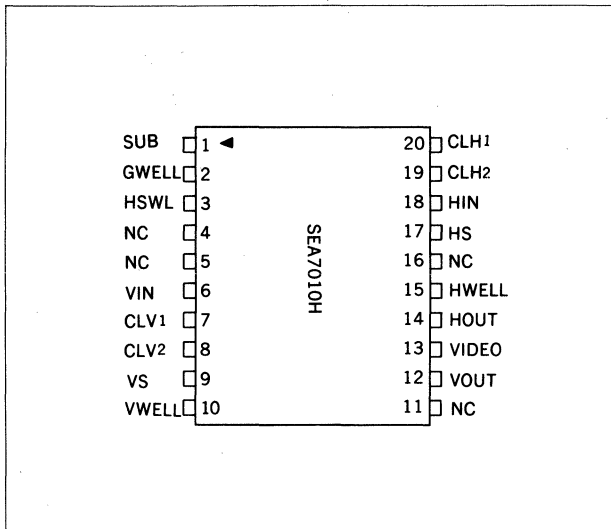
● Horizontal shift register block

This block consists of 488 bit shift registers and MOS transistors TGi that are controlled with the output HGi of each bit as the gate signal.

● Vertical shift register block

The vertical shift register block consists of 244 bit shift registers. The output of each bit becomes the scanning line Vj.

## ■ PIN CONFIGURATION



## ■ PIN DESCRIPTION

Pin No.	Terminal	Function
1	SUB	Board voltage
2	GWELL	Well voltage
3	HSWL	Reset pulse voltage
6	VIN	Vertical S.R. input
7	CLV1	Vertical S.R. clock 1
8	CLV2	Vertical S.R. clock 2
9	VS	Vertical S.R. source
10	VWELL	Ground voltage (V)
12	VOUT	Shift register output
13	VIDEO	Video output
14	HOUT	Horizontal S.R. output
15	HWELL	Reset pulse voltage
17	HS	Horizontal S.R. source
18	HIN	Horizontal S.R. input
19	CLH2	Horizontal S.R. clock 2
20	CLH1	Horizontal S.R. clock 1
4, 5, 11, 16	NC	No connection

## ■ ABSOLUTE MAXIMUM RATINGS

(VWELL = HWELL = 0V, Ta = 25°C)

Parameter	Symbol	Ratings	Unit
Terminal voltage (Horizontal S. R. input) *1	V <sub>H</sub>	-0.3 to 10	V
Terminal voltage (Vertical S. R. input) *2	V <sub>V</sub>	-0.3 to 10	V
Terminal voltage (Video bias)	V <sub>VIDEO</sub>	-0.3 to 10	V
Operating temperature	T <sub>opr</sub>	-10 to 60	°C
Storage temperature	T <sub>stg</sub>	-20 to 80	°C
Soldering temperature/time	T <sub>sol</sub>	260°C, 10s (lead only)	—

\*1: H<sub>IN</sub>, CLH1, CLH2 \*2: V<sub>IN</sub>, CLV1, CLV2

## ■ ELECTRICAL CHARACTERISTICS

### ● Recommended Operating Conditions

(VWELL = HWELL = 0V, Ta = 25°C)

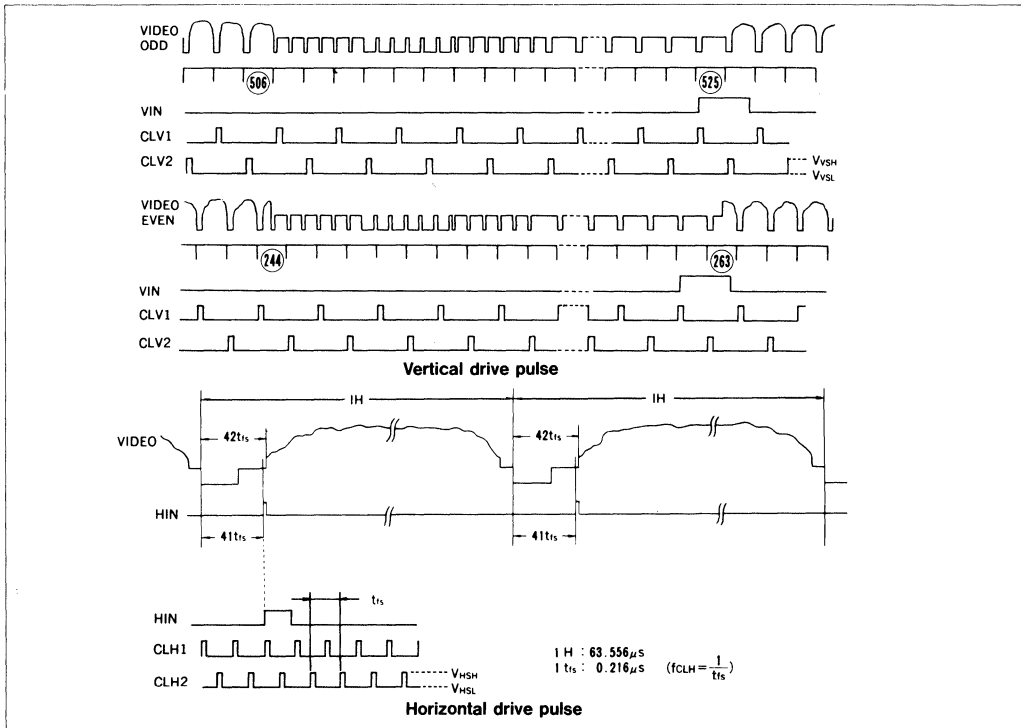
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Horizontal clock frequency	f <sub>CLH</sub>	V <sub>HSH</sub> = 7V	—	4.625	—	MHz
Vertical clock frequency	f <sub>CLV</sub>	V <sub>VSH</sub> = 7V	—	7.8	—	kHz
High level input voltage	V <sub>HSH</sub> , V <sub>VSH</sub>		6.5	7	7.5	V
Low level input voltage	V <sub>HSL</sub> , V <sub>VSL</sub>		0	0	0.1	V
GWELL voltage	V <sub>GWELL</sub>		0.6	0.8	1.0	V
SUB voltage	V <sub>SUB</sub>	V <sub>SUB</sub> ≥ V <sub>HSH</sub> , V <sub>VSH</sub>	6.5	7	7.5	V
Reset high level input voltage	V <sub>HWL</sub>		0.65	—	0.75	V
Reset low level input voltage	V <sub>LWL</sub>		0	—	0.05	V

### ● Opto-electrical Characteristics

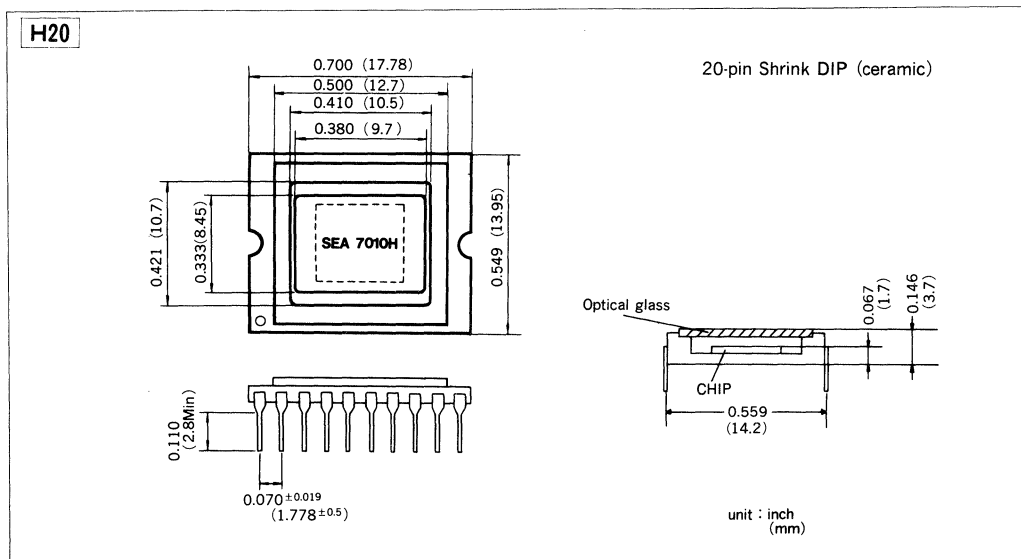
(VWELL = HWELL = 0V, Ta = 25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Saturated light quantity	L <sub>sat</sub>	V <sub>VIDEO</sub> = 3.0V	—	0.9	—	lx·sec
Sensitivity	S	V <sub>VIDEO</sub> = 3.0V	—	40	—	nA/lx
Horizontal resolution	R <sub>H</sub>		—	180	—	TVline
Vertical resolution	R <sub>V</sub>		—	180	—	TVline
Power consumption	P	F <sub>CLH</sub> = 4.625MHz, V <sub>HSH</sub> = V <sub>VSH</sub> = 7V	—	—	50	mW

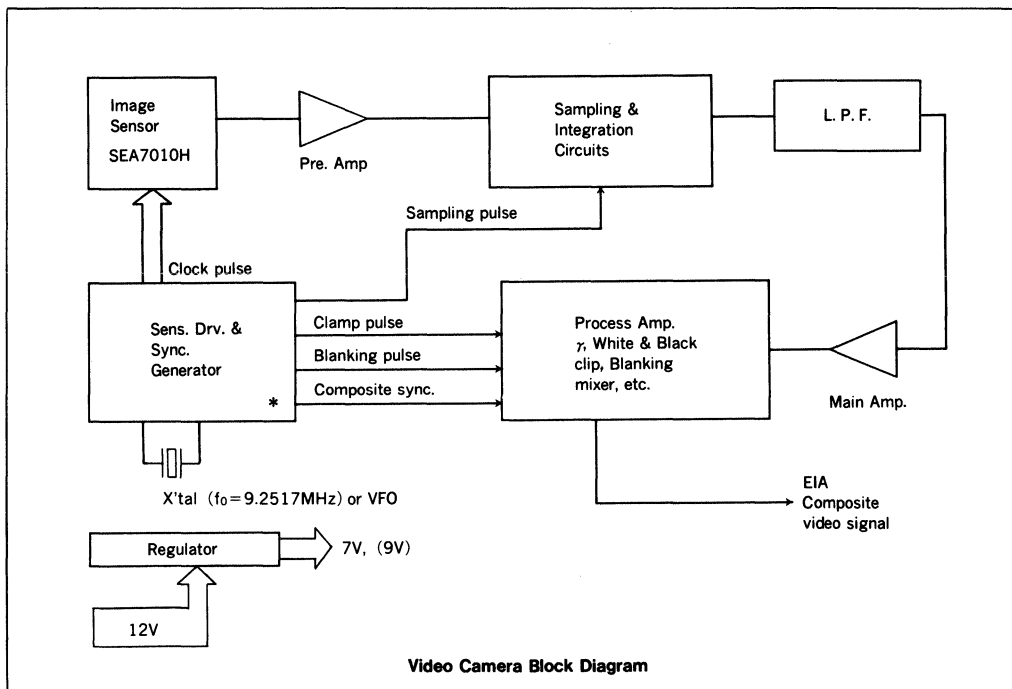
● Timing Chart



■ PACKAGE DIMENSIONS



■EXAMPLE OF APPLICATION (Peripheral Circuit Configuration)



Video Camera Block Diagram

\* Sync. control LSI (flat plastic package) is available as a system support IC. (SED3081F<sub>27</sub>)

[Precaution to handle]

1. The image sensor SEA7010H is a MOS LSI, so protect it against electrostatic breakdown. Never touch the sensor without grounding your body and the tools. Connect a resistance of about  $1\text{M}\Omega$  between the body and GND in series to ensure safety.
2. Do not touch the glass surface of the device. Wipe the surface, if soiled, with a clean applicator.
3. Take care not to drop the device, which has a glass cap.

# SEA7100H

## MOS AREA IMAGE SENSOR

- High Resolution
- 384 (Horizontal) × 485 (Vertical) Photo Sensors Incorporated
- 2/3-inch Size Solid State Imaging Device

### DESCRIPTION

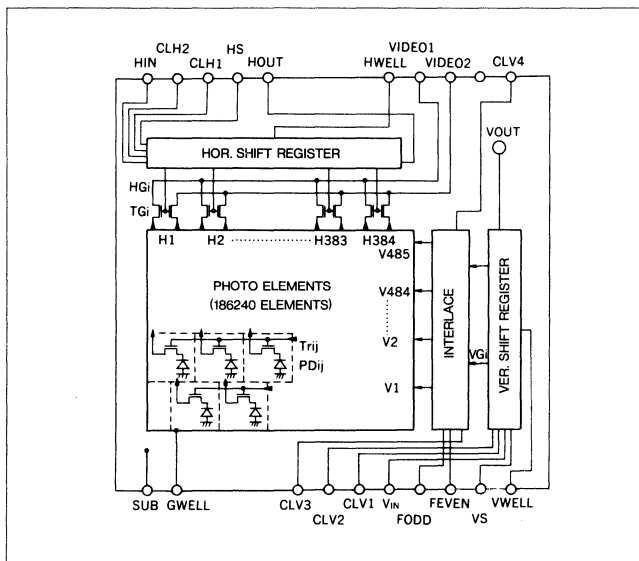
The SEA7100H is a high-density MOS area image sensor designed for use with black-and-white video cameras. Implemented in unique technology, the sensor features suppressed blooming and low noise.

Because of the 2/3-inch size, the SEA7100H can be used with low-cost standard lenses. Combining it with a dedicated synchronization control LSI enables the user to easily build a compact video camera with high packaging density.

### FEATURES

- Photo elements.....384(horizontal) × 485(vertical)
- Resolution.....450TV lines(horizontal) × 350 TV(vertical)
- Photo elements arranged in a checkered pattern, and two-line simultaneous reading which permits photo element interpolation
- Low voltage operation (7V) and low power consumption (70mW)
- Blooming suppressed by special technology
- Light-receiving area.....8.8mm × 6.6mm
- Peripheral circuits supported by dedicated synchronization control LSI
- Highly resistant to vibration and shock (operable under vibration)
- Package.....20-pin DIP(ceramic) with optical glass

### BLOCK DIAGRAM



### CIRCUIT CONFIGURATION

The SEA 7100H consists of three blocks : photo element (photo diode cell) block, horizontal shift register block, and vertical shift register block (including the interlace).

#### Photo element block

Photo elements are arranged in a checkered pattern : [384 elements horizontal] × [485 elements vertical] = [186240 elements]. 485 selection lines V1 through V485 run horizontally and 384 × 2 signal lines H1 through H384 (pair lines) run vertically. A photo element consisting of a MOS transistor  $Tr_{ij}$  and a photo diode  $D_{ij}$  is located at each crossing point.

#### Horizontal shift register block

This block consists of 768 bit shift registers and MOS transistors  $TG_i$  that are controlled with the output  $HG_i$  of each bit as the gate signal.

#### Vertical shift registers

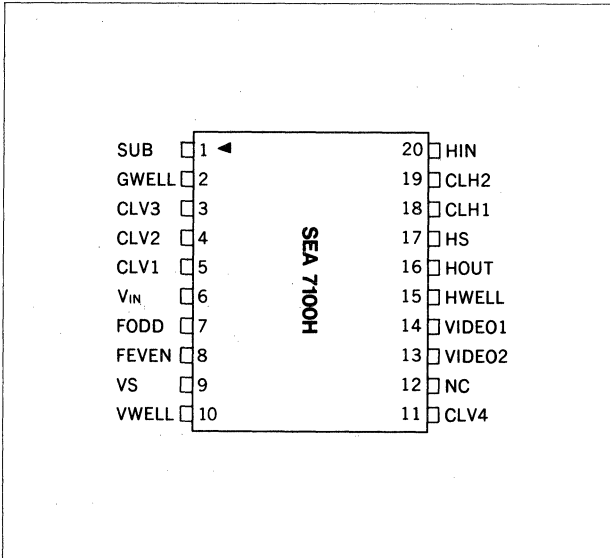
485 shift registers are provided. Output  $VG_j$  of each bit is supplied to the interlace part.

#### Interlace

This part receives vertical shift register output  $VG_j$ , and converts it for interlacing. This output is scanning line  $V_j$ .



## PIN CONFIGURATION



## PIN DESCRIPTION

Pin NO.	Pin name	Function
1	SUB	Board voltage
2	GWELL	Well voltage
3	CLV3	I.L. CLOCK 3
4	CLV2	Vertical S.R. clock 2
5	CLV1	Vertical S.R. clock 1
6	V <sub>IN</sub>	Vertical S.R. input
7	FODD	I.L. clock (odd field signal)
8	FEVEN	I.L. clock (even field signal)
9	VS	Vertical S.R. source
10	VWELL	Ground voltage (V)
11	CLV4	I.L. clock 4
12	NC	No connection
13	VIDEO2	Video output 2
14	VIDEO1	Video output 1
15	HWELL	Ground voltage (H)
16	HOUT	Horizontal S.R. output
17	HS	Horizontal S.R. source
18	CLH1	Horizontal S.R. clock 1
19	CLH2	Horizontal S.R. clock 2
20	HIN	Horizontal S.R. input

## ABSOLUTE MAXIMUM RATINGS

(V<sub>WELL</sub> = H<sub>WELL</sub> = 0V, T<sub>a</sub> = 25°C)

Parameter	Symbol	Ratings	Unit
Terminal voltage (Horizontal shift register)*1	V <sub>H</sub>	-0.3 to 10	V
Terminal voltage (Vertical shift register)*2	V <sub>V</sub>	-0.3 to 10	V
Terminal voltage (Video bias)	V <sub>VIDEO</sub>	-0.3 to 10	V
Operating temperature	T <sub>opr</sub>	-10 to 60	°C
Storage temperature	T <sub>stg</sub>	-20 to 80	°C
Soldering temperature/time	T <sub>sol</sub>	260°C, 10s (lead only)	—

\*1 : H<sub>IN</sub>, CLH1, CLH2 \*2 : V<sub>IN</sub>, CLV1, CLV2

## ELECTRICAL CHARACTERISTICS

### Recommended Operating Conditions

(V<sub>WELL</sub> = H<sub>WELL</sub> = 0V, T<sub>a</sub> = 25°C)

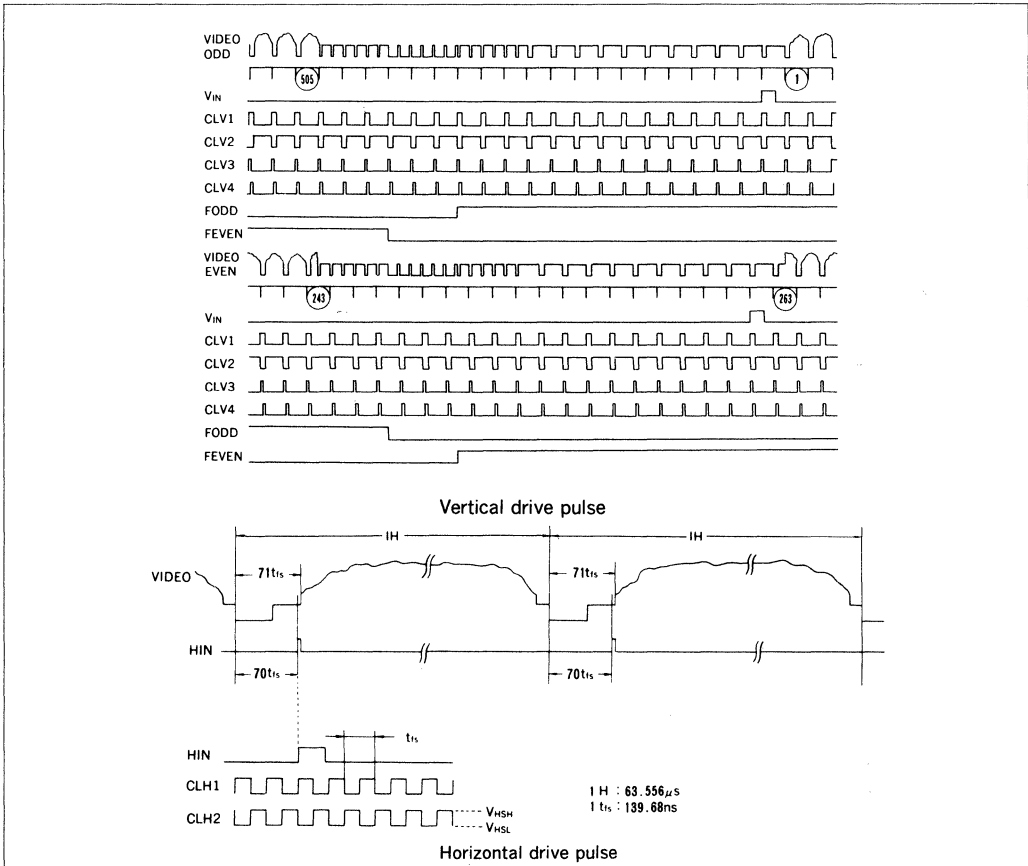
Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Horizontal clock frequency	f <sub>CLH</sub>	V <sub>HSH</sub> = 7V	—	7.16	—	MHz
Vertical clock frequency	f <sub>CLV</sub>	V <sub>VSH</sub> = 7V	—	15.74	—	kHz
High level input voltage	V <sub>HSH</sub> , V <sub>VSH</sub>		—	7	—	V
Low level input voltage	V <sub>HSL</sub> , V <sub>VSL</sub>		—	0	—	V
GWELL voltage	V <sub>GWELL</sub>		—	0.8	—	V
SUB voltage	V <sub>SUB</sub>		—	7	—	V

### Opto-electrical Characteristics

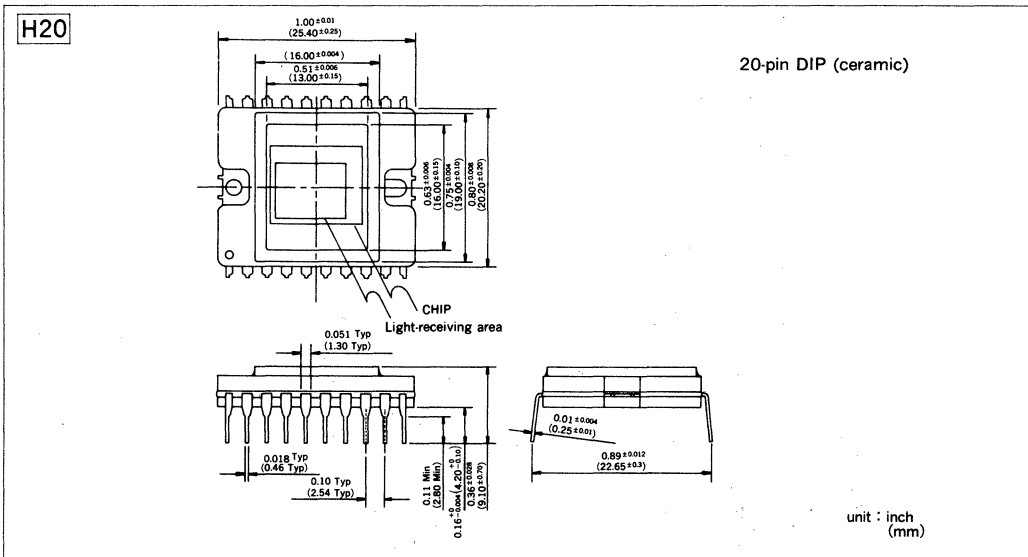
(V<sub>WELL</sub> = H<sub>WELL</sub> = 0V, T<sub>a</sub> = 25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Saturated light quantity	L <sub>sat</sub>	V <sub>VIDEO</sub> = 3.0V	—	1.3	—	lx·sec
Sensitivity	S	V <sub>VIDEO</sub> = 3.0V	—	15	—	nA/lx
Horizontal resolution	R <sub>H</sub>		—	450	—	TVline
Vertical resolution	R <sub>V</sub>		—	350	—	TVline
Power consumption	P	F <sub>CLH</sub> = 4.625MHz, V <sub>HSH</sub> = V <sub>VSH</sub> = 7V	—	70	—	mW

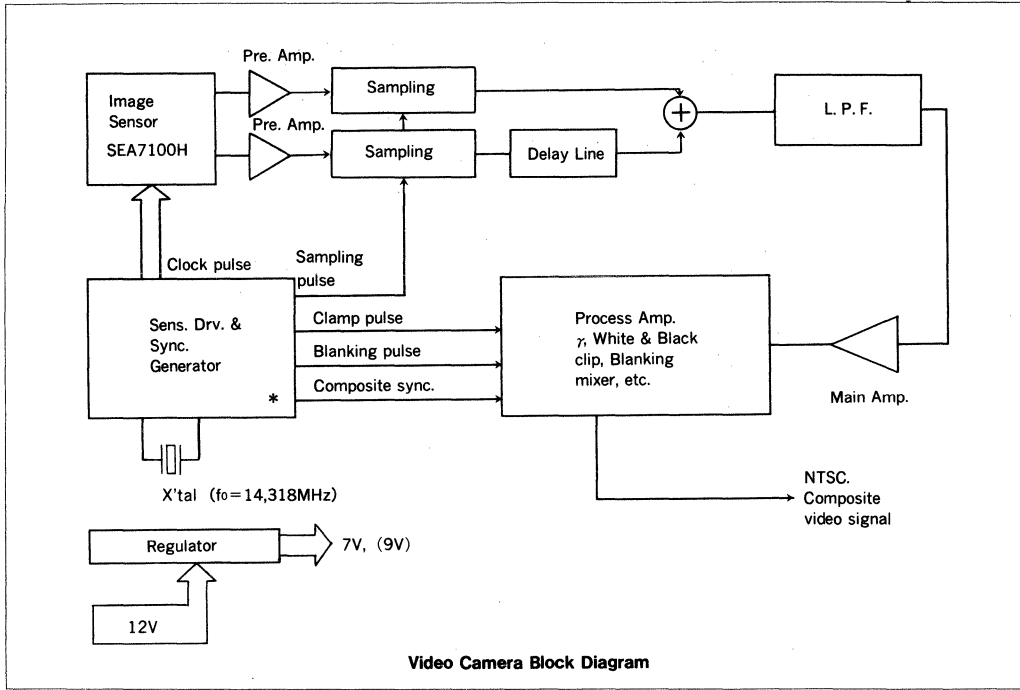
● Timing Chart



■ PACKAGE DIMENSIONS



## EXAMPLE OF APPLICATION (Peripheral Circuit Configuration)



Video Camera Block Diagram

\* Sync. control LSI (flat plastic package) is available as a system support IC. (SED3181F3A)

### [Precaution to handle]

1. The image sensor SEA7100H is a MOS LSI, so protect it against electrostatic breakdown. Never touch the sensor without grounding your body and the tools. Connect a resistance of about 1MΩ between the body and GND in series to ensure safety.
2. Do not touch the glass surface of the device. Wipe the surface, if soiled, with a clean applicator.
3. Take care not to drop the device, which has a glass cap.

# SEA7521H

## CCD LINE SENSOR

- 2,048 Bits Photo-element
- 14μm Pitch

### DESCRIPTION

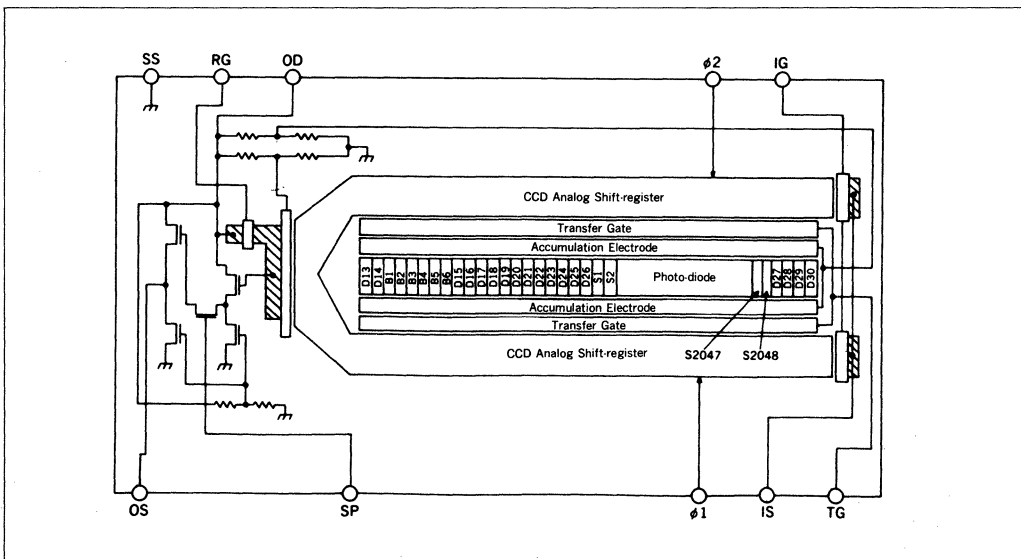
The SEA7521H is a 2,048 bits CCD line sensor which has a CCD analog shift register for reading image signals. It is possible to read a manuscript of B4 size (36.4cm×25.8cm) by 8 line/mm.

The SEA7521H is appropriate for facsimile, image scanner and industrial measurement/control system applications.

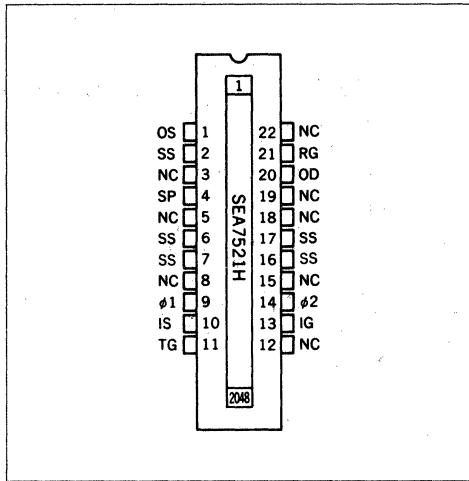
### FEATURES

- Photo element .....2,048 bits
- Element pitch .....14μm
- Data transmit frequency .....1MHz (Typ)
- Saturation voltage .....1.0 V (Typ)
- Saturated exposure value .....1.0 lx·sec (Typ)
- Photo response.....1.0 V/lx·sec (Typ)
- Improvement of blue response by using P/N photo diodes
- Elements exclusive to black level are incorporated
- Sample-hold circuits are incorporated for output signal
- 2 phases clock for CCD analog shift register
- Single power supply .....12V
- Package.....22-pin DIP (CERDIP) with optical glass

### BLOCK DIAGRAM



## PIN CONFIGURATION



## PIN DESCRIPTION

Pin No.	Pin Name	Function
1	OS	Source of output transistor
2	SS	Substrate (GND)
3	NC	non-connection
4	SP	Sample-hold
5	NC	non-connection
6	SS	Substrate (GND)
7	SS	Substrate (GND)
8	NC	non-connection
9	φ1	Clock (first phase)
10	IS	Input source (for testing)
11	TG	Transfer gate
12	NC	non-connection
13	IG	Input gate (for testing)
14	φ2	Clock (second phase)
15	NC	non-connection
16	SS	Substrate (GND)
17	SS	Substrate (GND)
18	NC	non-connection
19	NC	non-connection
20	OD	Drain of output transistor
21	RG	Reset gate
22	NC	non-connection

(The NC should be connected to the SS)

## ABSOLUTE MAXIMUM RATINGS

( $V_{SS}=0V$ )

Parameter	Symbol	Ratings	Unit	
Terminal voltage	φ1, φ2	$V_{\phi}$	-0.3 to 15	V
	TG	$V_{TG}$		
	RG	$V_{RG}$		
	SP	$V_{SP}$		
	OD	$V_{OD}$		
	IG	$V_{IG}$		
	IS	$V_{IS}$		
Operation temperature	$T_{opr}$	-25 to 60	°C	
Storage temperature	$T_{stg}$	-40 to 100	°C	
Soldering temperature/time	$T_{sol}$	260°C, 10s (at lead)	—	

## ELECTRICAL CHARACTERISTICS

### Recommended Operating Conditions

( $V_{SS}=0V$ ,  $T_a=25^{\circ}C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Transfer clock voltage	High level	$V_{\phi H}$	11	12	13	V
	Low level	$V_{\phi L}$	0	0.5	0.8	V
Transfer gate voltage	High level	$V_{TG H}$	11	12	13	V
	Low level	$V_{TG L}$	0	0.5	0.8	V
Reset gate voltage	High level	$V_{RG H}$	11	12	13	V
	Low level	$V_{RG L}$	0	0.5	0.8	V
Sample-hold gate voltage	High level	$V_{SP H}$	11	12	13	V
	Low level	$V_{SP L}$	0	0.5	0.8	V
Output Tr. drain voltage	$V_{OD}$		11.5	12	13	V
Input gate voltage	$V_{IG}$		0	0	1	V
Input source voltage	$V_{IS}$		11	12	13	V

Note; The SP should be connected to the OD when the sample-hold function is not used.

### ●Clock Characteristics

(Ta = 25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Transfer clock frequency	$f_{\phi}$		—	0.5	—	MHz
Reset gate clock frequency	$f_{RG}$		—	1	—	MHz
Input capacity of $\phi 1/\phi 2$	$C_{\phi}$		—	950	—	pF
Input capacity of TG	$C_{TG}$		—	150	—	pF
Input capacity of RG	$C_{RG}$		—	10	—	pF
Input capacity of SP	$C_{SP}$		—	10	—	pF

### ●Opto-electrical Characteristics

( $V_{\phi} = V_{TG} = V_{RG} = V_{SP} = V_{OD} = V_{IS} = 12V$ ,  $V_{IG} = 0V$ ,  $f_{\phi} = 0.5MHz$ , Optical accumulation time = 10ms, A light source of 2,856K colour temperature, Ta = 25°C)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Photo response	R	—	0.8	1.0	1.3	V/lx·sec
Unequalness of photo response	PRNU *1	50% of SE	—	—	±10	%
Unequalness of adjacent-photo response	PRNUN *2	—	—	—	±4	%
Saturated output voltage	$V_{SAT}$	—	0.8	1.0	—	V
Saturated exposure value	SE	—	—	1.0	—	lx·sec
Dark output voltage	$V_{DRK}$	—	—	1.1	5.0	mV
DC power consumption	PD	$V_{OD} = 13V$	—	20	40	mW
Total transfer efficiency	TTE	—	0.92	0.95	—	—
Output impedance	$Z_O$	—	—	0.9	1.5	kΩ
Dynamic range	DR	$V_{SAT}/V_{DRK}$	—	600	—	—

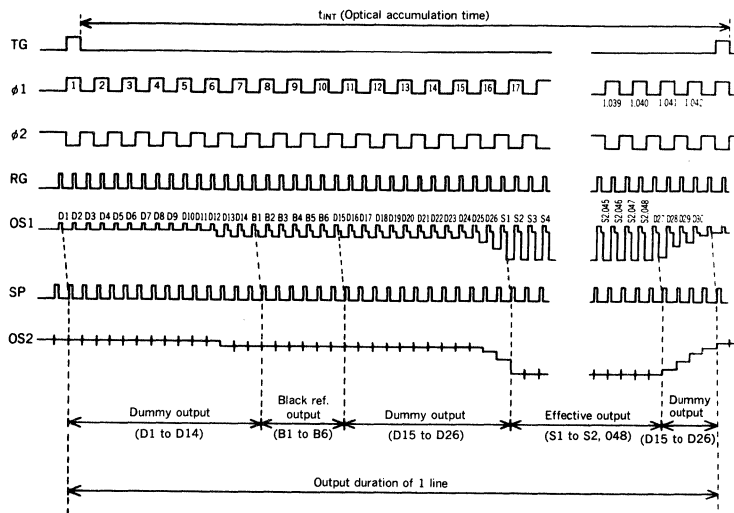
$$*1 \text{ PRNU} = \frac{V - \bar{V}}{\bar{V}} \times 100 \text{ [\%]}$$

$\bar{V}$ : Average output voltage of all photo-elements  
V: Output voltage of each photo-element

$$*2 \text{ PRNUN} = \frac{V - \bar{V}}{\bar{V}} \times 100 \text{ [\%]}$$

$\bar{V}$ : Average output voltage of adjacent 32 photo-elements  
V: Output voltage of each adjacent 32 photo elements

### ■TIMING CHART



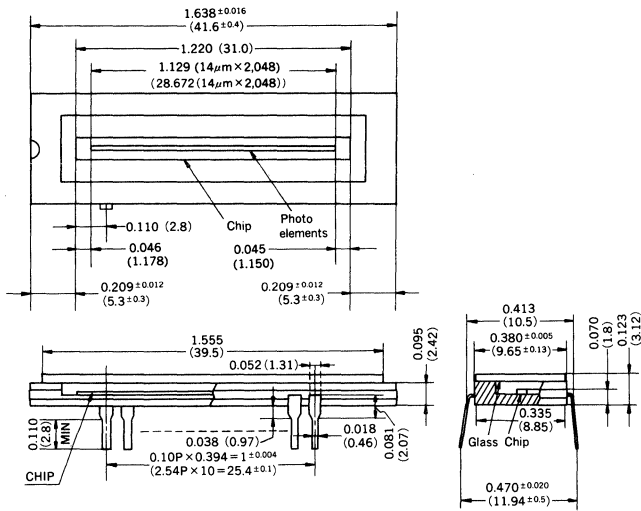
OS1: Output signal if the sample-and-hold function is not used.

OS2: Output signal if the sample-and-hold function is used.

The transfer clock ( $\phi 1/\phi 2$ ) should be given 1,042 times and more.

■ PACKAGE DIMENSIONS

22-pin DIP (CERDIP)



unit : inch  
(mm)

**[Precaution to handle]**

1. Handle the CCD line sensor carefully against electro-statics. Though SEA7521H is of such design as to be protected from electro-statics, some careless handling may cause the damage.
2. Wipe off the smear on the front glass with alcohol or the like. Otherwise, it will appear as a dark spot.
3. Use a visible radiation as the light incident to the device. Otherwise, the performance may not sometimes satisfy the specified characteristics.
4. Don't apply strong shocks to the device, which may cause the damage on the glass or other parts.

# SEA7551H

## CCD LINE SENSOR

- 5,000 Bits Photo-element
- 7 $\mu$ m Pitch

### DESCRIPTION

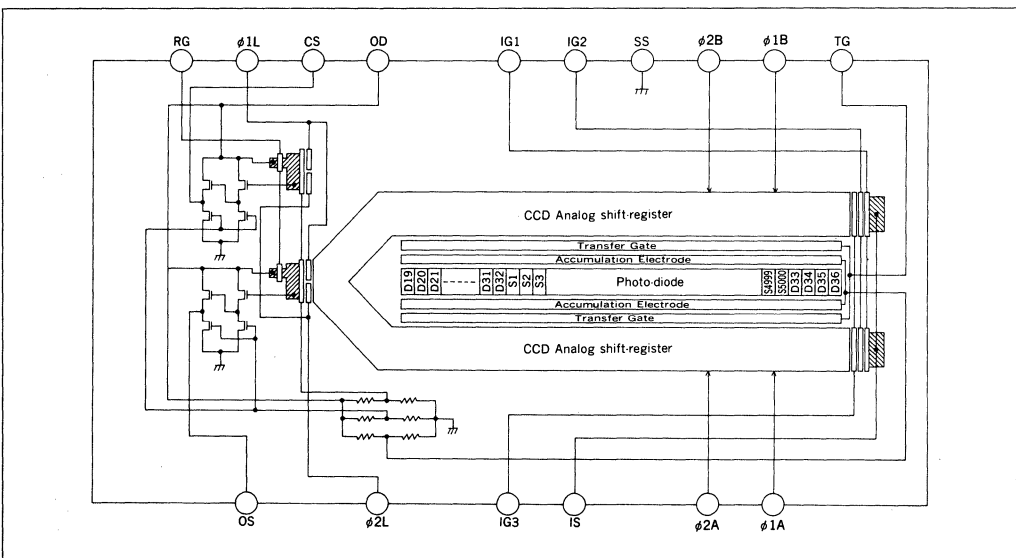
The SEA7551H is a 5,000 bits CCD line sensor which has a CCD analog shift register for reading image signals. It is possible to read a manuscript of A3 size (29.6cm $\times$ 42cm) by 16 line/mm.

The SEA7551H is appropriate for image scanners, digital copy, and industrial measurement/control systems applications.

### FEATURES

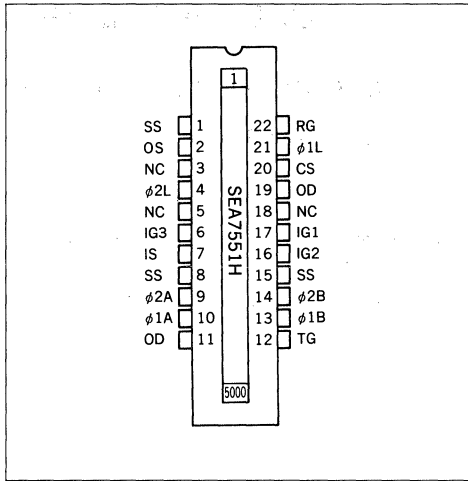
- Photo element ..... 5,000 bits
- Element pitch ..... 7 $\mu$ m
- Data transmit frequency ..... 0.5MHz (Typ)
- Saturation voltage ..... 0.6V (Typ)
- Saturated exposure value ..... 2.0lx $\cdot$ sec (Typ)
- Photo response ..... 0.3V/lx $\cdot$ sec (Typ)
- Improvement of blue response by using P/N photo diodes
- The signal output circuit has 2 step amplifiers, and it is enough output drive capability.
- The compensational output circuit is builded in, and it is easy to eliminate reset noise.
- 2 phases clock for CCD analog shift register
- Single power supply ..... 12V
- Package ..... 22-pin DIP (Ceramic) with optical glass

### BLOCK DIAGRAM





## PIN CONFIGURATION



## PIN DESCRIPTION

Pin No.	Pin Name	Function
1	SS	Substrate (GND)
2	OS	Source of output transistor
3	NC	No Connection
4	$\phi 2L$	Last gate clock (second phase)
5	NC	No Connection
6	IG3	Input gate 3 (for testing)
7	IS	Input source (for testing)
8	SS	Substrate (GND)
9	$\phi 2A$	Clock (second phase)
10	$\phi 1A$	Clock (first phase)
11	OD	Drain of output transistor
12	TG	Transfer gate
13	$\phi 1B$	Clock (first phase)
14	$\phi 2B$	Clock (second phase)
15	SS	Substrate (GND)
16	IG2	Input gate 2 (for testing)
17	IG1	Input gate 1 (for testing)
18	NC	No Connection
19	OD	Drain of output transistor
20	CS	Source of compensational output transistor
21	$\phi 1L$	Last gate clock (first phase)
22	RG	Reset Gate

(The NC should be connected to the SS)

## ABSOLUTE MAXIMUM RATINGS

( $V_{SS}=0V$ )

Parameter	Symbol	Ratings	Unit
Transfer clock voltage	$V_{\phi 1A}, V_{\phi 1B}, V_{\phi 1L}, V_{\phi 2A}, V_{\phi 2B}, V_{\phi 2L}$	-0.3 to 15	V
Transfer gate voltage	$V_{TG}$		
Reset gate voltage	$V_{RG}$		
Output tr. drain voltage	$V_{OD}$		
Input gate voltage	$V_{IG1}, V_{IG2}, V_{IG3}$		
Input source voltage	$V_{IS}$		
Operation temperature	$T_{opr}$	-25 to 60	$^{\circ}C$
Storage temperature	$T_{stg}$	-40 to 100	$^{\circ}C$
Soldering temperature/time	$T_{sol}$	260 $^{\circ}C$ , 10s (at lead)	—

## ELECTRICAL CHARACTERISTICS

### Recommended Operating Conditions

( $V_{SS}=0V, T_a=25^{\circ}C$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Transfer clock voltage	High level	$V_{\phi 1A}, V_{\phi 1B}, V_{\phi 1L}, V_{\phi 2A}, V_{\phi 2B}, V_{\phi 2L}$	11	12	13	V
	Low level	$V_{\phi 1A}, V_{\phi 1B}, V_{\phi 1L}, V_{\phi 2A}, V_{\phi 2B}, V_{\phi 2L}$	0	0.5	0.8	V
Transfer gate voltage	High level	$V_{TGH}$	11	12	13	V
	Low level	$V_{TGL}$	0	0.5	0.8	V
Reset gate voltage	High level	$V_{RGH}$	11	12	13	V
	Low level	$V_{RGL}$	0	0.5	0.8	V
Output Tr. drain voltage	$V_{OD}$		11.5	12	13	V
Input gate voltage	$V_{IG1}, V_{IG2}, V_{IG3}$		0	0	1	V
Input source voltage	$V_{IS}$		11	12	13	V

### ● Clock Characteristics

( $T_a = 25^\circ\text{C}$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Transfer clock frequency	$f_\phi$		—	0.5	—	MHz
Reset gate clock frequency	$f_{RG}$		—	1	—	MHz
Input capacity of $\phi_{1A}, \phi_{2A}, \phi_{1B}, \phi_{2B}$	$C_{\phi A,B}$		—	600	—	pF
Input capacity of $\phi_{1L}, \phi_{2L}$	$C_{\phi L}$		—	20	—	pF
Input capacity of TG	$C_{TG}$		—	150	—	pF
Input capacity of RG	$C_{RG}$		—	20	—	pF

### ● Opto-electrical Characteristics

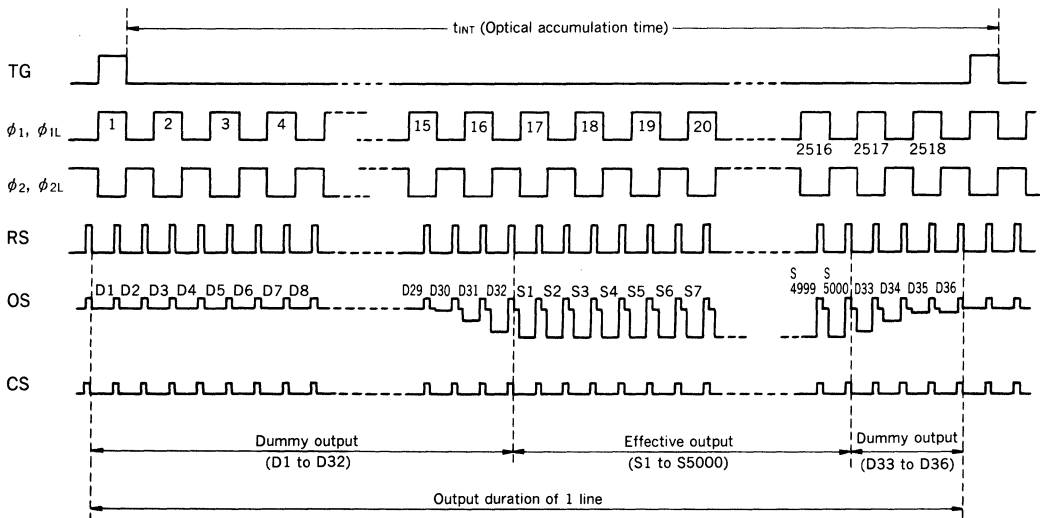
( $V_\phi = V_{TG} = V_{RG} = 12\text{V}$  pulse drive,  $V_{OD} = V_{IS} = 12\text{V}$ ,  $V_{IG} = 0\text{V}$ ,  $f_\phi = 0.5\text{MHz}$ , Optical accumulation time = 10ms, A light source of 2,856K colour temperature,  $T_a = 25^\circ\text{C}$ )

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Photo response	R	—	0.27	0.3	—	V/lx·sec
Unequalness of photo response	PRNU *1	50% of SE	—	—	$\pm 10$	%
Saturated output voltage	$V_{SAT}$	—	0.55	0.6	—	V
Saturated exposure value	SE	—	1.5	2.0	—	lx·sec
Dark output voltage	$V_{DRK}$	—	—	1.2	8	mV
DC power consumption	PD	$V_{OD} = 13\text{V}$	—	30	40	mW
Total transfer efficiency	TTE	—	0.90	0.95	—	—
Output impedance	$Z_O$	—	—	1	2	k $\Omega$
Dynamic range	DR	$V_{SAT}/V_{DRK}$	—	500	—	—
Output voltage-Compensational output voltage	$ V_{OS} - V_{CS} $	—	—	—	300	mV

$$*1 \text{ PRNU} = \frac{V - \bar{V}}{\bar{V}} \times 100 \text{ [%]}$$

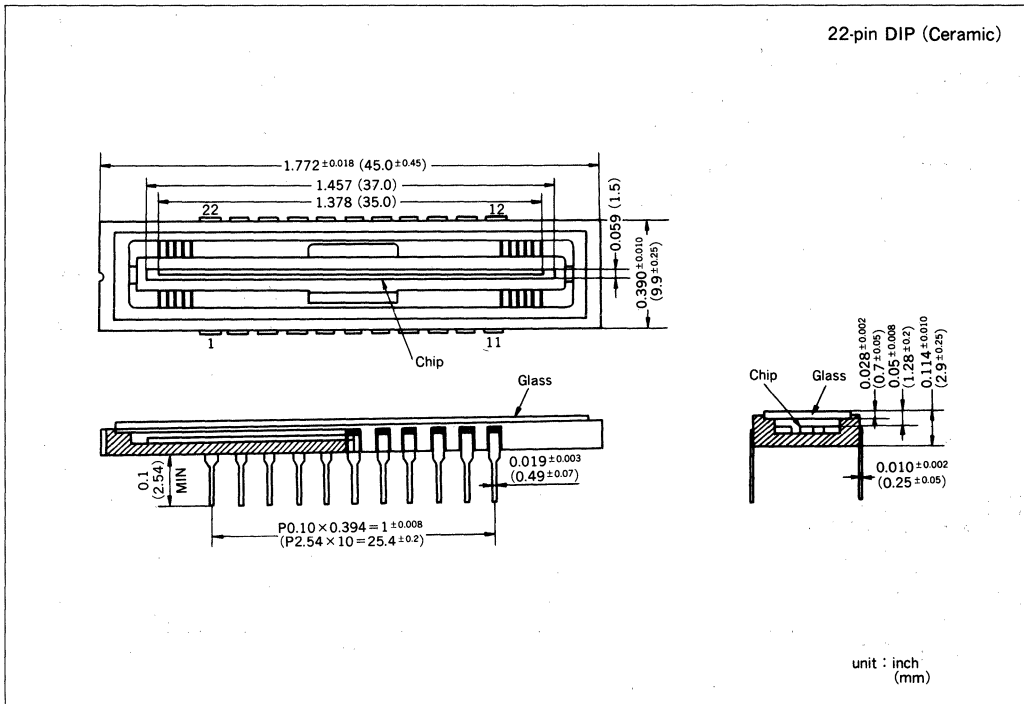
$\bar{V}$ : Average output voltage of all photo-elements  
 V: Output voltage of each photo-element

### ■ TIMING CHART



The transfer clock ( $\phi_1, \phi_2$ ) should be given 2,518 times and more.

## PACKAGE DIMENSIONS



### [Precaution to handle]

1. Handle the CCD line sensor carefully against electro-statics. Though SEA7551H is of such design as to be protected from electro-statics, some careless handling may cause the damage.
2. Wipe off the smear on the front glass with alcohol or the like. Otherwise, it will appear as a dark spot.
3. Use a visible radiation as the light incident to the device. Otherwise, the performance may not sometimes satisfy the specified characteristics.
4. Don't apply strong shocks to the device, which may cause the damage on the glass or other parts.



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