

SERIES 200

INTRODUCTION TO SERIES 200/OPERATING SYSTEM- MOD 2

SUBJECT:

General Description of the Series 200/Operating System - Mod 2, Third-Generation Operating System for Models 1200, 2200, and 4200.

SPECIAL INSTRUCTIONS:

This bulletin introduces the functional concepts, benefits, and components of the Series 200/Operating System - Mod 2. This prerequisite publication is the foundation for studying the Mod 2 Operating System programming and operating facilities. Appendix A is a publications guide for further study.

DATE: May 20, 1966

FILE NO. 122.0005.002J.0-393

*

8953
10566
Printed in U. S. A.

*When ordering this publication please specify
Title and Underscored portion of the File Number.

TABLE OF CONTENTS

		Page	
Section I	Introduction.....	1-1	
	The Operating System Approach.....	1-1	
	Operating System Design.....	1-1	
	Stacked-Job Processing and Program Modularity.....	1-2	
	Benefits of the Mod 2 Operating System.....	1-3	
	Ease of Programming.....	1-3	
	Ease of Operating.....	1-4	
	Ease of Maintenance and Expansion.....	1-5	
	Over-all Benefits.....	1-5	
	Section II	Functions of the Mod 2 Operating System.....	2-1
Job Control.....		2-1	
Communication and Real-Time Control.....		2-1	
Multiprogramming Control.....		2-1	
Interrupt Control.....		2-2	
Data Control.....		2-2	
File Access.....		2-2	
File Control.....		2-3	
Program Preparation and Maintenance.....		2-3	
Other Functions.....		2-4	
Summary of System Files.....		2-4	
System Operating File (SOF).....		2-4	
Go File (MGO).....		2-4	
Job File (MJB).....		2-4	
Standard Input Unit (SIU).....		2-4	
Standard Print Unit (SPR).....		2-4	
Standard Punch Unit (SPU).....		2-4	
Master History File (MHF).....		2-4	
Section III		Components of the Mod 2 Operating System.....	3-1
		Supervisory Components.....	3-1
	Resident Monitor J.....	3-1	
	Transitional Monitor J.....	3-2	
	Input/Output-File Controller J.....	3-2	
	Processing Components.....	3-3	
	Language Processors.....	3-3	
	Assembler J.....	3-3	
	COBOL Compiler J.....	3-4	
	Fortran Compiler J.....	3-4	
	Easytran J Transition Program.....	3-5	

Copyright 1966
 Honeywell Inc.
 Electronic Data Processing Division
 Wellesley Hills, Massachusetts 02181

TABLE OF CONTENTS (cont)

		Page
Section III (cont)	Linkage Loader J.....	3-6
	System Maintenance J.....	3-6
	Tape Sort J.....	3-7
	Mass Storage Sort J.....	3-7
	Utility Components.....	3-8
	Input/Output Editor J.....	3-8
	Storage Print J.....	3-8
	Tape Print J.....	3-8
Section IV	Minimum Equipment Requirements.....	4-1
Appendix A	Operating System - Mod 2 Publications.....	A-1

LIST OF ILLUSTRATIONS

Figure 1-1.	Turnaround Times for Batched-Job and Stacked-Job Processing.....	1-3
Figure A-1.	Mod 2 Operating System Publications Plan.....	A-2

SECTION I INTRODUCTION

THE OPERATING SYSTEM APPROACH

An operating system is an integrated set of interdependent programs providing the most efficient means for program development and operation. As the name implies, operating systems have evolved from the essential need to replace the human computer operator with a stored program. Human intervention wastes a tremendous amount of processing time due to the disparity in operating speeds between the hardware and its user. The first objective for a programmed computer operator is to eliminate human operations between successive program executions. Transition between programs involves clerical duties such as collecting the output produced by the previous program, submitting the next group of input data for processing, locating the next program, and loading it into memory.

Operating System Design

The embryo, and still the basic element, of today's operating systems is a programmed job scheduler, or monitor, which automates job-to-job transition. This routine resides permanently in core storage and responds to control specifications which determine the sequence of programs to be executed and the necessary peripheral equipment assignments. Merely by limiting the setup functions of a human operator, even such primitive operating systems can effectively reduce the idle time between program runs.

A second source of wasted processing time is console debugging. Therefore, primitive operating systems are augmented by standard dynamic dumping routines for use by all object programs. Entire batches of unrelated programs can then be executed in succession, removing both programmer and operator from the hardware interface. The logical extension of common debugging facilities is common input/output routines for all programs. By placing centralized input/output routines in core storage with the resident monitor, one approximation of a modern operating system is developed.

The effect of a resident monitor plus common input/output control and debugging facilities is standardization of both programming and operating procedures. The programmer and the operator are required to communicate with the operating system, rather than with the computer itself. A common set of operating procedures is superimposed on all programs running under control of the operating system. Independent programs use common routines and initiate input/output operations through logical directions issued to the centralized input/output control system.

Stacked-Job Processing and Program Modularity

One result of this standardization is the incorporation of the language processors into the operating system, which introduces two powerful and fundamental concepts; stacked-job processing and modular program structure.

Stacked-job processing is a refinement of the earlier batched-job approach. A job is a collection of related programs. Under batched-job processing, a single processing function, e. g., compilation, is applied to all jobs in the batch. While a group of jobs may be compiled in succession and then executed in succession, program generation is divorced from the execution of a batch of pregenerated programs. Under stacked-job processing, any number of processing functions such as compilation, maintenance, and execution may be successively applied to the same job. Thus, each job in the input stack is processed to completion before the next job is accepted. In batched-job processing, the elapsed time between the submission of a job and receipt of results (turnaroundtime) is equal to the total processing time for the entire batch which includes the job. In contrast, stacked-job processing dramatically reduces turnaround time for a given job by completely processing each job before the next.

As a simple example, consider the two jobs described below. Turnaround times for the two jobs are illustrated in Figure 1-1 for both a batched-job and a stacked-job situation.

<u>Job 1</u>	<u>Job 2</u>
Compile program A ... 20 time units	Compile program D ... 25 time units
Update program B. ... 5 time units	Compile program E ... 30 time units
Compile program B ... 10 time units	Execute program D ... 10 time units
Compile program C ... 15 time units	Execute program E ... 15 time units
Execute program A ... 10 time units	
Execute program B ... 5 time units	
Execute program C ... 5 time units	

Program development under the operating system achieves unprecedented flexibility with the introduction of the program module concept. A program module is the basic program unit in the operating system. Each module is created independently. Modules are relocatable and can be combined with other modules to fashion a variety of complete programs. These, in turn, may be built to run anywhere in core storage using any combination of modules. Also, all language processors in the operating system generate the identical type of relocatable modules. Hence, a complete program may be subdivided into program modules on the basis of physical size, functional breakdown, or the nature of the source language best suited for solving a portion of the total problem.

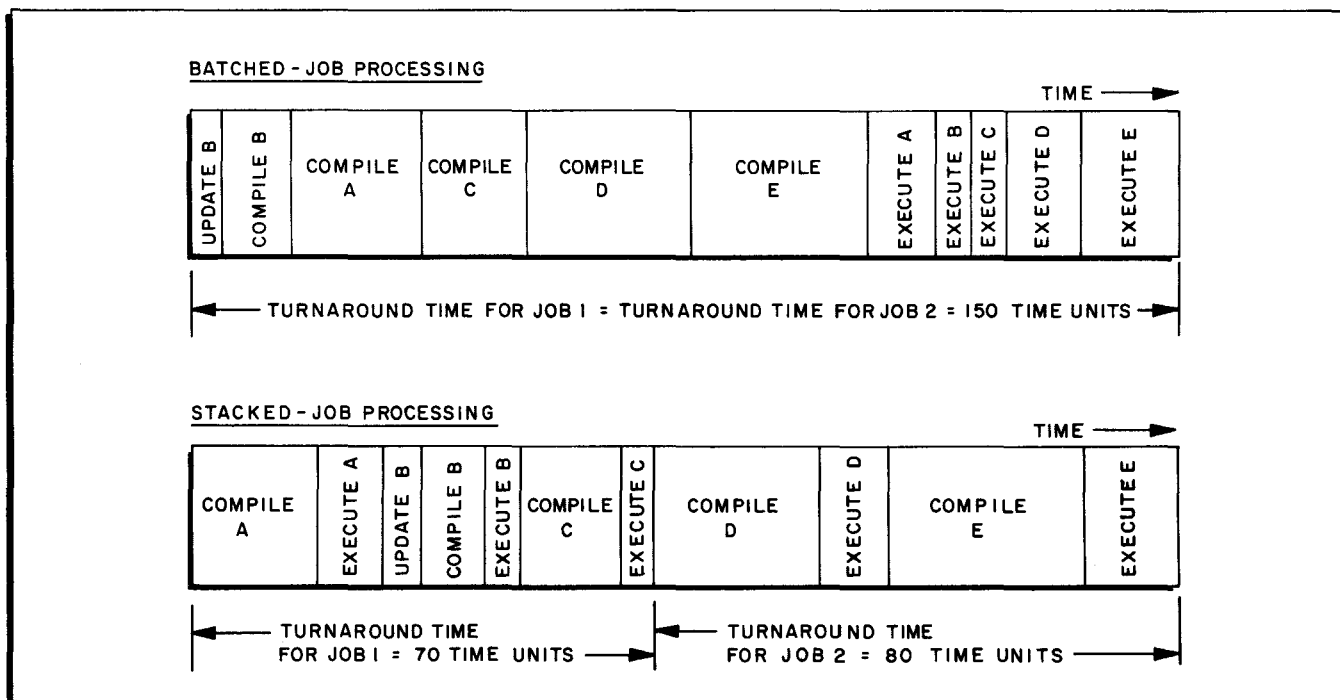


Figure 1-1. Turnaround Times for Batched-Job and Stacked-Job Processing

Honeywell has been intimately associated with this development of operating systems. Notable Honeywell milestones for the H-800/1800 systems were the Executive System in 1960 and the ADMIRAL Operating System in 1963. The development of Series 200/Operating Systems draws heavily on this experience in programming research and development. The Mod 2 Operating System encompasses the entire body of computer management tools for program development and maintenance, job and data control, and all service functions.

BENEFITS OF THE MOD 2 OPERATING SYSTEM

Ease of Programming

The relocatable program module is the common denominator of the Mod 2 Operating System. Because they are relocatable, all modules are essentially library routines which the Operating System can freely combine. Free communication between program modules is maintained through the standard interface of the operating system. All language processors generate the same basic building blocks (program modules). Thus a programmer is not limited to solving an entire problem in a single source language.

Responsibility for tedious and complex input/output programming is transferred from the user to the Operating System. Programmers need not be conversant with the programming characteristics of specific peripheral devices. Instead, they issue input/output macro instructions to the Operating System. In addition to managing physical device programming, the Mod 2

Operating System automatically frees the user from allocating buffers, checking file labels, blocking and unblocking records, and error-checking data transfer operations. Also, the Operating System ensures optimal use of the system facilities by maximizing the simultaneity of data flow and internal processing, a capability which is inherent in Series 200 hardware.

Managing the flow of data to and from peripheral devices is just part of the device independence provided by the data control functions of the Mod 2 Operating System. The Operating System also manages the logical data files themselves. Programmers designate both data files and associated peripheral devices by symbolic names. The names and properties of each data file are indexed in a symbolic catalog within the Operating System. Programmers may request data files by using only their symbolic names. The mechanics of locating and retrieving data files are the responsibility of the Operating System. The Operating System also controls space allocation and formatting on mass storage devices.

Finally, the standardized and automatic debugging facilities of the Mod 2 Operating System, coupled with the brief turnaround time per job, enhance the ease and efficiency of program check-out.

Ease of Operating

A single set of operating procedures is followed for user-written programs and components of the Operating System. Operators do not have to cope with the peculiarities of every program, a fact which simplifies operator training and increases the reliability of machine room operation. In the same fashion, man/machine communication is reduced to a standard dialogue between the operator and the Operating System. Most functions required for automatic job-to-job transition, like finding and loading the next program and assigning tapes, have been absorbed by the Mod 2 Operating System. Those manual procedures which could not be programmed into the Operating System, like mounting tape reels, are performed by the operator according to complete instructions issued by the Operating System.

In addition to automating job-to-job transition, the Operating System also administers internal hardware facilities, such as the interrupt system and storage protection. Thus, machine management is placed under control of the Operating System, minimizing and simplifying the role of the operator. Standardized operating procedures enhance the total flexibility of operation. Under the Mod 2 Operating System, the mode of operation is sensitive to the requirements of each application. Stacked-job processing, batched-job processing, and real-time processing are handled with equal facility.

Ease of Maintenance and Expansion

Both user programs and Honeywell-supplied components of the Mod 2 Operating System are easily modified because of their modular structure. A series of complex, time-consuming programs is required initially to generate some operating systems. However, the same single-phase component of the Mod 2 Operating System which is used to update the system files is also used to create a working version of the Operating System itself. System generation is both selective and efficient. A personalized operating system is tailored to each installation by incorporating only those system modules required by the user. System generation is rapid because file-access time in the Mod 2 Operating System is optimized by efficient blocking and by use of the read-backward feature of Honeywell magnetic tape units. A typical business-oriented version of the Mod 2 Operating System is generated in less than 15 minutes. System programs and user programs are easily updated without recompiling. For example, additional modules may be added to user programs to take advantage of newly acquired hardware. Additional modules may be added to the Operating System to provide further processing capabilities for growing applications. Also, the Operating System may be expanded by the inclusion of user-written components.

Over-all Benefits

From the perspective of the data processing manager, the convenience and modularity at each level of the Mod 2 Operating System are reflected and amplified in the over-all efficiency and reliability of the hardware/software complex. Standardized programming and operating procedures provide the most efficient path from initial formulation of a programming problem to final utilization of the solution. Use of the Mod 2 Operating System increases throughput as a result of total hardware utilization and reduced idle time. At the same time, the stacked-job capability provides complete software service with minimal turnaround time to all users of the Operating System. The flexible framework of the Mod 2 Operating System supports growth into applications such as total information and real-time systems. The magnitude and complexity of the functions performed by the Mod 2 Operating System simplify the jobs of programmer, operator, and manager. By furthering the independence of these personnel from the computer, the Mod 2 Operating System allows them to use it more effectively.

SECTION II

FUNCTIONS OF THE MOD 2 OPERATING SYSTEM

Mod 2 Operating System functions are described under the headings of job control, data control, program preparation and maintenance, and other functions.

JOB CONTROL

Before performing other job control functions, the Mod 2 Operating System reads and analyzes system control cards. A second job control function is loading programs into memory, including dependent programs and any nonresident portions of the Operating System required to carry out the control card requests. Peripheral devices are also assigned on the basis of control card specifications.

After loading each program into memory, the Operating System performs its monitoring function, which is the crux of job control. Monitoring consists of controlling the internal sequencing of dependent programs, i. e., all programs executed under control of the Mod 2 Operating System. At the proper instant in time, control is delegated to a dependent program or retrieved from it.

Another job control function is communication with the operator, advising him of the status of processing and requesting necessary operator actions.

Communication and Real-Time Control

Monitoring in a communication environment involves the control of message flow to and from the computer and message processing within the computer. The appropriate dependent programs which process communication data are located, loaded, and entered at the proper point. During communication processing, the status of communication lines and buffers is constantly monitored, and control is switched so that supervisory, input/output, and message processing functions are performed as required. Communication monitoring also includes the function of preventing memory violations by incoming data.

Multiprogramming Control

Monitoring in a multiprogramming environment consists of supervising the concurrent execution of two programs. One program is normally peripherally limited and is executed in upper memory. The second program runs in lower memory during the peripheral cycles of the upper-memory program. Multiprogramming monitoring functions include detecting the beginning and

end of input/output operations, switching the assignment of processor cycles, and maintaining the integrity of each program while the other program is active. Memory protection must often be enforced, especially when the lower-memory program is undergoing checkout.

Interrupt Control

Monitoring in all operating environments, including communication and multiprogramming, may entail handling hardware interrupts. In an interrupt situation, registers are stored and re-stored, control is passed to the proper routine, and area of memory are protected if necessary.

DATA CONTROL

Data control in the Mod 2 Operating System encompasses all functions related to the creation and maintenance of the data base. The data base of the Mod 2 Operating System is the entire collection of information which enters or leaves the computer main memory at any time. System programs, user programs, execution data, and groups of control information are equivalent members of the data base. The facilities available under data control provide efficient storage, flow, and retrieval of all data in the system. These facilities include two functions: file access and file control.

File Access

The principal file access function of the Mod 2 Operating System is the physical exchange of data between main memory and auxiliary storage or terminal equipment. Complete flexibility is provided for the transfer of data to and from unit record, magnetic tape, mass storage, and communication equipment. Several different access methods are available.

1. Sequential access. Physical or logical records are stored or retrieved serially. Data access may be initiated on demand by a dependent program or on an anticipatory basis by the Operating System.
2. Direct access. Physical or logical records are stored or retrieved randomly. The programmer specifies an actual physical address, the relative position of the record in the file, or the address at which a search for key match is to begin (if the records contain identifying keys). This access method also automatically controls the allocation of storage space for mass storage files.
3. Partitioned access. In the partitioned access method, sequential information is interspersed with special records containing keys and other data. The information contained in these special records is supplied by both the user and the Operating System. The partitioned access method is well suited for the efficient storage and retrieval of relatively short strings of sequential records.
4. Controlled sequential access. This access method uses a multilevel indexing scheme which optimizes space utilization and data access time. Physical or logical records are stored or retrieved either in a logical sequence defined by a key field or randomly by an individual key.

5. Communication access. The Mod 2 Operating System automatically sends and receives messages to and from remote terminals. Incoming messages are automatically placed in an input queue. Outgoing messages are automatically taken from an output queue. Dependent programs treat the queues like peripheral devices. Physical or logical communication records are stored or retrieved from the queues in a sequential fashion similar to the sequential access method.

The other file access functions are linked with the data transfer function. These other functions are automatic error detection and correction, automatic data buffering, automatic data blocking and unblocking, dynamic scheduling of input/output facilities, and overlapping of processing with input/output operations.

File Control

The file control function of the Mod 2 Operating System includes management of logical data files at a level which is independent of the physical characteristics of the files and their storage devices. The Operating System automatically allocates and partitions file storage space, providing efficient use of mass storage equipment. Mass storage data is automatically formatted for access by the methods described above. Storage allocation is complemented by automatic file protection.

All files are assigned symbolic names, and the Operating System maintains a symbolic file catalog. The catalog is constructed with several qualifying levels, so that each file is categorized by a symbolic description of its functions. Files may be requested by means of these symbolic descriptions, and the catalog provides the unique location from which the Operating System retrieves each file.

PROGRAM PREPARATION AND MAINTENANCE

The most familiar program preparation function of the Mod 2 Operating System is language processing. Programs written in compiler or assembly source language are translated to program modules in relocatable machine language. It is worth noting again that all relocatable program modules are identical, regardless of their original source language. The second program preparation function consists of building a complete program by selecting specified program modules, providing linkages between the modules, and assigning absolute memory addresses to the relocatable machine code.

The program maintenance functions include adding and deleting modules from all system files and correcting lines within specified modules. Maintenance may be carried out at the source-language, relocatable-code, or absolute-code level. The same maintenance functions are applied to both system and user programs. Thus program maintenance includes creating

and updating both the system program and user program files, as well as incorporating user-written modules into the Mod 2 Operating System.

OTHER FUNCTIONS

The Mod 2 Operating System provides automatic debugging facilities such as dynamic core and tape dumps.

The Operating System data editing and transcription functions include sorting and merging data in magnetic tape and mass storage files, and performing media-conversion operations.

SUMMARY OF SYSTEM FILES

System Operating File (SOF)

This file contains modules in absolute format, including all programs of the Mod 2 Operating System. It may also contain libraries of modules in relocatable machine language and symbolic source language. The file may exist on tape or mass storage.

Go File (MGO)

This file contains the output of the language processors, in the form of relocatable machine-language modules. It may exist on tape or mass storage.

Job File (MJB)

This file contains executable programs. The job file is created as a result of linking and assigning absolute addresses to relocatable program modules residing on the MGO, standard input unit (SIU), or relocatable library of the SOF. This file may exist on tape or mass storage.

Standard Input Unit (SIU)

A card file, or optionally a magnetic tape file, the SIU is the source of control information for the Operating System. The SIU may also supply the Operating System with source-language programs, execution data, and program modules in relocatable machine language.

Standard Print Unit (SPR)

This file is a possible destination for output of the Mod 2 Operating System. It may be produced on a printer or, optionally, on magnetic tape.

Standard Punch Unit (SPU)

This file is another possible destination for Operating System output. It may be produced on a card punch or, optionally, on magnetic tape.

Master History File (MHF)

This is a Honeywell-supplied tape file containing all elements of the Mod 2 Operating System in the form of source-language modules.

SECTION III

COMPONENTS OF THE MOD 2 OPERATING SYSTEM

The Mod 2 Operating System comprises supervisory components and processing components. The supervisory components are the Resident Monitor J, Transitional Monitor J, and Input/Output (I/O) - File Controller J. The processing components include the language processors, Linkage Loader J, System Maintenance J, utility programs, and tape and mass storage sort/merge programs. The supervisory components handle program control, communication, and data transfer operations which are essential for the execution of all other programs. Hence, the processing components, like user-written programs, are dependent programs. During Mod 2 operation, the Resident Monitor and part of the I/O-File Controller reside permanently in core storage and provide the interface through which all dependent programs are loaded and executed.

As mentioned, user-written processing programs may be integrated into the Mod 2 Operating System as easily as Honeywell-supplied programs. In addition, Honeywell-supplied components have own-coding provisions for the inclusion of user-written modifications.

SUPERVISORY COMPONENTS

Resident Monitor J

Resident Monitor J is the nerve center of the Mod 2 Operating System. It remains in memory throughout Mod 2 operation. To expedite processing of the job stream, the Resident Monitor employs a temporary nonresident assistant, Transitional Monitor J. The Resident Monitor reads system control cards, on which the user schedules all processing under the Mod 2 Operating System. Then the Resident Monitor loads the Transitional Monitor from the SOF. As explained below, one of the functions of the Transitional Monitor is to analyze the control cards and advise the Resident Monitor of required processing operations. Then the Resident Monitor loads specified absolute programs into memory from the Job File or the SOF.

After loading, the dependent programs are started and executed under control of Resident Monitor. In a multiprogramming or communication environment, the Resident Monitor, acting on interrupt signals and program demands, switches control to the appropriate dependent program. At the end of a program execution, the Resident Monitor reclaims control from the dependent program, ascertains whether or not the program terminated normally, performs operations required in the event of program failure, and recalls the Transitional Monitor to continue control card analysis.

The Resident Monitor also maintains a communication region and input/output tables. The communication region contains data and addresses which provide the information interface for both user-written programs and components of the Mod 2 Operating System. The input/output tables contain information describing the peripheral equipment configuration. Using the input/output tables, the Resident Monitor and the Transitional Monitor work as a team to assign peripheral equipment for each run.

Transitional Monitor J

Transitional Monitor J does not reside permanently in memory: it is loaded periodically by the Resident Monitor to handle the automatic transitions between programs within a job and between jobs in the input stack. The Transitional Monitor interprets the system control cards, indicates to the Resident Monitor the functions specified, locates programs to be loaded, and returns control to the appropriate portion of the Resident Monitor. Together with the Resident Monitor, the Transitional Monitor coordinates input/output assignments.

Input/Output-File Controller J

I/O-File Controller J performs the file access and file control functions described in Section II. Part of the I/O-File Controller remains in core storage with the Resident Monitor to handle file access. The resident routines of the I/O-File Controller execute all input/output operations for card equipment (card reader, card punch, card reader/punch), high-speed printers, console typewriter, magnetic tape units, mass memory transports, and communication equipment. These routines direct the dynamic allocation of read/write channels and control the simultaneity of internal computing and input/output operations. They also allocate data buffers, block and unblock tape records, check tape labels, and detect input/output errors. When errors cannot be automatically corrected, the I/O-File Controller furnishes the operator with an account of the error and directions for its correction. Own-code exits are provided for the incorporation of user's routines into the resident portion of the I/O-File Controller.

File access functions are requested by statements in the user's symbolic source programs. In assembly-language programs, file-description statements and macro instructions are directed to the I/O-File Controller. The macro language provides instructions for sequential, direct, partitioned, controlled-sequential, and communication access methods. When processed by Assembler J, the macro instructions are translated into machine-language links to the appropriate resident routine of the I/O-File Controller. In COBOL and Fortran programs, directions for the I/O-File Controller are implemented within the syntax of the compiler language itself. For example, a READ statement generates a machine-language link to the appropriate resident routine of the I/O-File Controller.

The part of the I/O-File Controller which manages data file control does not reside in memory but is loaded from the SOF when needed. These routines allocate and protect storage space for mass storage files. They also construct the symbolic file catalog. Both the amount and the nature of symbolic classification levels within the catalog are established by each user. The I/O-File Controller receives symbolic file designations from the user, consults the catalog to determine the physical identities and locations of the files, and retrieves the specified files.

PROCESSING COMPONENTS

Language Processors

The language processors in the Mod 2 Operating System comprise three source-language translators and a transition program for conversion of 1410/7010 Autocoder programs. The three source-language translators are AssemblerJ, COBOL Compiler J, and Fortran Compiler J. They provide alternate paths to the solution of a programming problem. An entire problem or each constituent module of a problem may be programmed in the most suitable and efficient source language. All the source-language translators generate relocatable machine-language program modules in the Go file. The relocatable modules are structurally identical building blocks; they may be combined into complete executable programs by the Linkage Loader component without regard to their original source language. The transition program, Easytran Symbolic Translator J, resolves hardware differences which are reflected in 1410/7010 Autocoder and its compatible superset, Mod 2 assembly language.

ASSEMBLER J

Assembler J translates a symbolic machine-oriented language. In assembly language, the programmer expresses machine operation codes and memory addresses using symbolic designations. In a typical assembly-language statement, the machine operation code is programmed by a fixed mnemonic abbreviation. References to memory addresses may be coded as symbolic names called labels. A label may identify the starting memory location of an instruction, a storage area, or a field containing data (an operand) to be operated upon by the hardware logic of the instruction. Labels are created by the programmer; mnemonics are an invariant property of the Assembler.

Each symbolic statement which abbreviates a machine function is translated to one equivalent machine instruction by Assembler J. Mnemonic operation codes are translated to octal codes, and a machine-language address is assigned to each symbolic label. Because the output program modules are relocatable, the Assembler assigns machine addresses relative to some base location.

Other types of assembly-language statements are not translated to a single machine instruction. These statements generate formatted data in memory, provide relocation information for Linkage Loader J, control the Assembler itself, or generate a block of machine-language instructions.

A statement which is not translated one-for-one but generates a sequence of machine instructions is called a macro instruction. A macro instruction contains certain parameters and references a routine which exists in a general form on the SOF. According to the parameters specified by the programmer, the Assembler adapts the generalized routine on the SOF to the purposes of the calling program and replaces the macro instruction with the specialized routine. Macro instructions may be used repeatedly to include a specialized sequence of instructions at several points in a program. Macro instructions and their associated routines may be defined by the user. The Mod 2 Operating System also provides a set of macro instructions and routines to facilitate the use of system components (e.g., the I/O-File Controller J).

On request, the Assembler produces a listing showing the symbolic source program and the corresponding assembled machine instructions and constants. Errors in the source program are flagged. A second optional listing provides a cross-reference of every label and its occurrences in the program.

COBOL COMPILER J

COBOL Compiler J translates source programs written in the business-oriented COBOL language. An industry standard, COBOL source language is patterned closely after the English language. COBOL J programs are constructed with paragraphs, sentences, and clauses. Verbs and statements in the COBOL vocabulary are tailored to commercial application and are independent of the hardware considerations for a specific computer. COBOL J translates each symbolic COBOL statement to several machine-language instructions. Thus, a business programmer using COBOL solves problems in his own language without regard to programming a physical computer. COBOL J generates a listing of the source and compiled programs. Diagnostic messages are issued for all source-program errors. Debugging is therefore carried out at the compiler-language level, preserving the machine independence of COBOL.

FORTRAN COMPILER J

Fortran Compiler J translates source programs written in Fortran language, which is designed for the scientific community. Scientific programmers code problems using a notation based on algebra. Equations are written to describe the algebraic processing for which the computer is programmed, the variables and constants operated upon, and the solutions to the computations. Programming to support the actual calculations, such as input/output and program

sequence control, is also described by machine-independent Fortran statements. Like the COBOL Compiler, Fortran J generates several machine-language instructions from each problem-oriented Fortran statement.

Fortran J language is a full implementation of proposed ASA Fortran, with powerful language extensions. Some of the significant extensions to ASA Fortran are the BEGIN TRACE and END TRACE debugging statements, mixed-mode arithmetic statements, the acceptance of Fortran II I/O statements, more flexible FORMAT statements, and data typing via IMPLICIT statements.

The program modularity of the Mod 2 Operating System is reflected in its Fortran language. The language is based upon a subprogram structure, under which relocatable machine-language subroutines may be incorporated into Fortran programs. The relocatable library on the SOF may include user-written subroutines as well as the mathematical subroutines supplied with the Fortran compiler.

A source-program listing with detailed error diagnostics is produced at each compilation.

EASYTRAN J TRANSITION PROGRAM

Included in Honeywell's liberator concept for elevating 1410/7010 users to Series 200 is compatibility with the Mod 2 Operating System in the areas of hardware, data files, software, and operating environments. The basic supervisory and processing functions of the Mod 2 Operating System include all those of the 1410/7010 Operating System. A few hardware dissimilarities between 1410/7010 and Series 200 are manifest in Mod 2 assembly language and its fully compatible subset, 1410/7010 Autocoder. At the assembly language level, the automatic transition program Easytran Symbolic Translator J resolves differences in addressing, indexing, and internal character codes.

Approximately ninety-five percent of all 1410/7010 Autocoder instructions are translated directly to Mod 2 assembly language. The remaining five percent are flagged, Easytran J applies a default translation, and programmer hand-tailoring is sometimes indicated. An average of only one out of five flagged instructions actually requires hand-tailoring; the others require only verification of the default translation.

Easytran J produces a listing which shows the correspondence between the original 1410/7010 Autocoder program and the modified Mod 2 assembly-language program. Converted programs are full-fledged components of the Mod 2 Operating System. They are translated by the Assembler, processed by the Linkage Loader, and executed under control of the Resident Monitor, and they may be updated through the facilities of System Maintenance.

Linkage Loader J

Linkage Loader J produces absolute machine-language programs for execution by selecting and combining relocatable program modules generated by the source-language translators. Complete programs may be built from any combination of program modules. In rendering a program executable, the Linkage Loader J assigns absolute addresses to the relocatable addresses in program modules and to the system linkage symbols, adjusting the relocatable modules to accommodate resident components of the Operating System.

The Linkage Loader resides on the SOF and is loaded and executed under control of the Resident Monitor. Control cards and programmed calls select the combination of program modules for relocation. The Linkage Loader processes program modules from any or all of these system files: the Go file, the relocatable library on the SOF, and the SIU. Each execution of the Linkage Loader creates the Job file of complete programs in absolute machine language. Programs on the Job file may be executed under control of the Resident Monitor or processed by System Maintenance J.

System Maintenance J

System Maintenance J creates, edits, and maintains the Master History file, the System Operating file, the Go file, and the Job file. For each installation, System Maintenance J initially generates a version of the Mod 2 Operating System. The modular design of the Mod 2 Operating System permits each user to select only those Operating System elements required for his application and to create custom-tailored MHF's, SOF's, and libraries. In addition to Honeywell-supplied elements, user-written components may be both introduced into the system files mentioned above and maintained by System Maintenance J.

System Maintenance J facilities may be applied to programs at the source-language, relocatable machine-language, and absolute machine-language levels. In addition, control card decks and even object data cards can be incorporated into a source library. Based on control card specifications supplied by the user, System Maintenance J can:

1. Delete a specified module from a source, relocatable, or absolute system file or library.
2. Add a specified module to a source, relocatable, or absolute system file or library.
3. Position a system file or library after a specified module.
4. Correct a specified source module by deleting, inserting, or replacing specified lines.

Combinations of these actions provide three System Maintenance J operating modes:

1. Creating a new system file or library by adding program units in a specified order.

2. Selecting a source module from a system file or library, producing a printed listing, and/or placing it on a stacked card-image tape for later system input. At the same time, line numbers of the module can be reassigned.
3. Updating a system file or library by copying an older version while deleting, replacing, or inserting specified modules.

System Maintenance J also provides directory listings of system files and libraries.

Tape Sort J

Tape Sort J is an efficient source of many individualized sorting and merging programs. Residing on the SOF, it consists of a group of relocatable modules which perform the actual sort/merge functions and a separate routine in absolute format called Sort Definition J. The Sort Definition program is loaded by the Resident Monitor and selects the relocatable sort/merge modules required to create the user's particular sorting program. Sort Definition J chooses relocatable modules according to information supplied by the user, such as whether the program will sort or merge fixed- or variable-length records, the number of pertinent key fields for the sort or merge, and the presence or absence of user-written modifications.

After the required modules are selected by Sort Definition J, the Linkage Loader is executed to combine the modules into a complete sort/merge program in absolute machine-language format. Complete sort/merge programs may be created once for all future processing, or they may be generated in each sorting run. If own-coding is included with the sort/merge modules, the user may employ special linkage symbols which are provided to reference locations within the Honeywell-supplied modules. Such symbols are also assigned absolute addresses by the Linkage Loader.

A complete sort/merge program generated by the Linkage Loader is entered into the Job file, from where it is loaded and executed under control of the Resident Monitor. At execution time, the complete sort/merge program adjusts itself to accommodate user control card specifications, such as whether to sort in ascending or descending order, whether to use the label-handling facilities of the resident I/O-File Controller J, and whether to write checkpoint records.

Mass Storage Sort J

Mass Storage Sort J performs sorting and merging functions on a file of fixed-length source items stored on a mass storage transport. In addition to data, the source items may contain up to 10 sorting keys. Mass Storage Sort J does not sort the actual source file but operates upon a group of sorting items which are created from the original source item. The input file of source items is preserved. The output of Mass Storage Sort J is an ordered file of these sorting items

which is stored in a work area of the Mass Memory Transport. Each sorting item contains the key fields of the source item, the address of the source item, and a selected portion of data extracted from the source item. Because extracted data is included in the output file, access to the original source items is often not necessary to process the sorted information. Depending on the number of sorting keys, the output sorting items may even contain all the data from the source items.

Mass Storage Sort J exists as a library routine in the Assembler macro library on the SOF. Mass Storage Sort J is specialized at assembly time for the types of files to be sorted and the equipment available. Parameters are entered at execution time to specify: the number of relevant sorting key fields; whether to sort in ascending order, descending order, or a mixed sequence; the selective inclusion or deletion of certain input items; and the presence or absence of user own-coding.

Utility Components

Utility components provide program testing and media preparation services. The utility components reside on the SOF and are loaded and executed under control of the Resident Monitor.

INPUT/OUTPUT EDITOR J

Input/Output Editor J performs two functions:

1. Converting input data from punched cards to magnetic tape (for use as the SIU).
2. Printing and/or punching output data from magnetic tape (the SPR or SPU).

In an off-line environment, the Input/Output Editor may perform these functions simultaneously on any Series 200 processor operating under the Basic Programming System or Mod 1 Operating System. These functions may also be performed concurrently with the execution of a dependent program under the Mod 2 Operating System.

STORAGE PRINT J

Storage Print J is executed in response to a user's control cards. According to specifications on the control cards, the Storage Print program edits and writes on the SPR the contents of any selected areas of memory. The addresses of system symbols, the contents of index registers, and special messages also appear on the printed listing.

TAPE PRINT J

Tape Print J dumps the contents of any portion of a magnetic tape reel. According to control cards, any number of entire files or a specified number of fixed- or variable-length records within a file are written on the SPR. Record counts, character counts, and special messages are also printed.

SECTION IV
MINIMUM EQUIPMENT REQUIREMENTS

The minimum hardware required for the Mod 2 Operating System is:

- A Series 200 Model 1200, 2200, or 4200 processor with 49,192 characters of core storage and the Optional Instruction Feature (0191).
- 5 Type 204B Magnetic Tape Units and tape control equipped with the IBM Format Feature (050) and the IBM Code Compatibility Feature (051).
 - OR 3 Type 204B Magnetic Tape Units and 1 Mass Storage Transport
- 1 Type 223 or 214-2 Card Reader and control
 - OR 1 additional magnetic tape unit
- 1 Type 222 Printer with 132 print positions and control
 - OR 1 additional magnetic tape unit
- 1 Type 220-3 Console Typewriter

APPENDIX A
OPERATING SYSTEM - MOD 2 PUBLICATIONS

The publication plan for the Series 200 Operating System - Mod 2 is illustrated schematically in Figure A-1. The solid lines connecting the boxes that contain publication titles indicate prerequisite reading, while the broken lines indicate recommended reading. This bulletin, which is prerequisite to all the others shown, is at the left-hand side of the diagram. In order to determine what publications contain the information necessary to use a particular operating system component, follow the solid line from the box denoting this bulletin to the box denoting the publication which describes the component in question. Thus, Introduction to Operating System - Mod 2, Study Guide: Operating System Mod 2, and Monitors and Linkage Loader J are prerequisites for Tape Sort J, Input/Output - File Controller J and its prerequisite, Assembler J, are recommended reading relevant to Tape Sort J.

The following paragraphs summarize the purpose and contents of the Operating System - Mod 2 publications.

Study Guide: Operating System - Mod 2 - This manual continues from the overview of Introduction to Operating System - Mod 2 to explain the Operating System in depth. It describes the functions of the individual operating system components in greater detail and provides all of the introductory "how-to" information necessary to tie the system together from a user's point of view.

Operating System - Mod 2 Operating Procedures - The operators' manual describing how to run Operating System - Mod 2. Provides step-by-step operating instructions, describes control card configurations and deck arrangements, defines operating system console messages, and indicates the operator actions required to respond to messages.

Liberation Guide - A description of the procedures for processing 1410/7010 programs and files under the Mod 2 - Operating System.

Monitors and Linkage Loader J - A detailed description of Resident Monitor J, Transitional Monitor J, and Linkage Loader J, describing the interfaces among these components and the other operating system elements. Includes descriptions of the linkage coding required to reference Resident Monitor subroutines, the console messages produced by the Monitor, and the console typeins accepted.

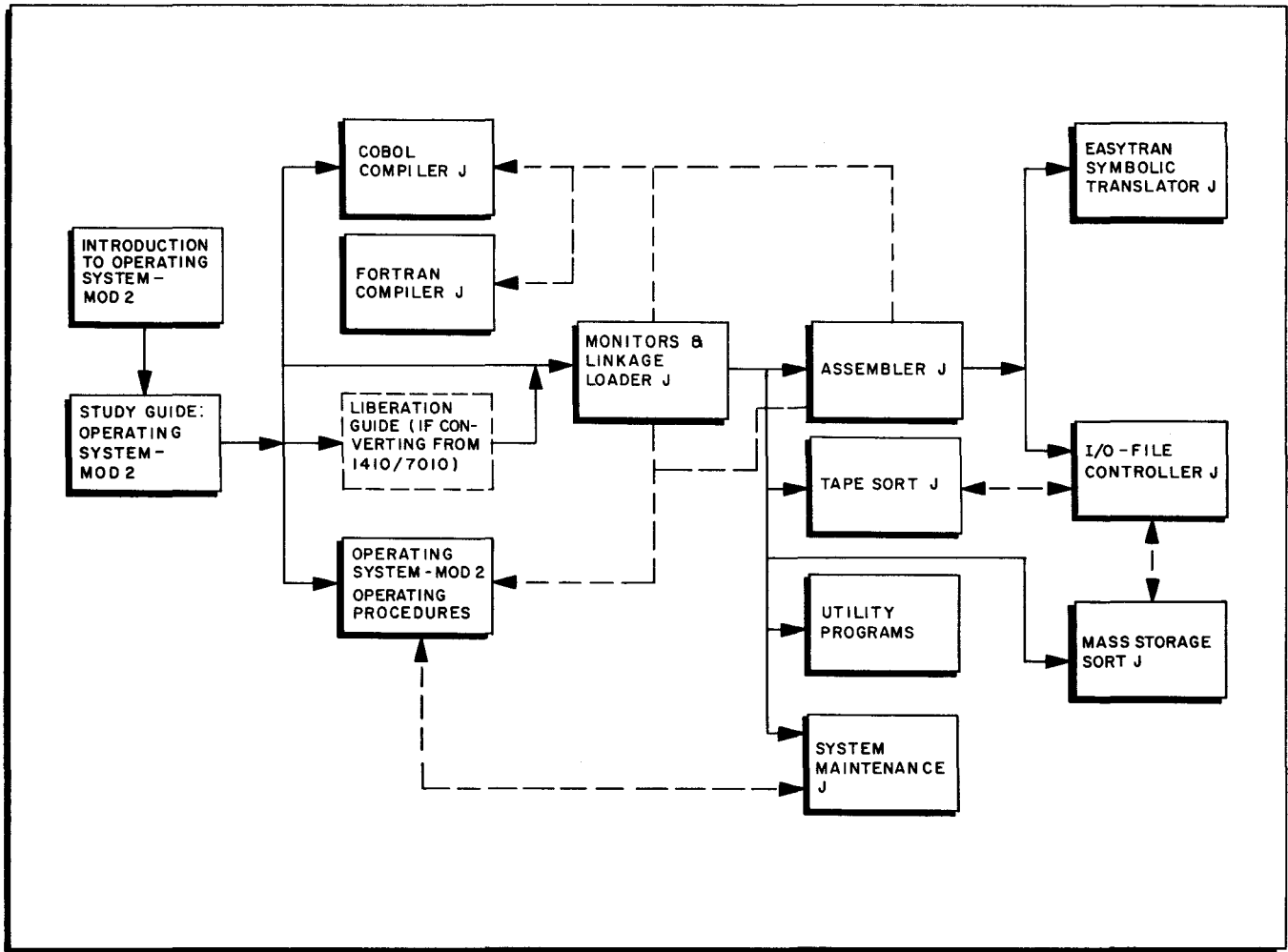


Figure A-1. Mod 2 Operating System Publications Plan

Input/Output - File Controller J - A detailed description of the program which provides the file access and file control functions described in Section II of this bulletin. Describes the file definition and macro statements used with I/O - File Controller J and tells how to exercise user own-coding options.

Language Processors

Each of these three manuals describes in detail the preparation of symbolic programs for input to one of the Operating System - Mod 2 language processors. Each manual includes a description of the arrangement of source-language card decks.

Assembler J

COBOL Compiler J

Fortran Compiler J

Easytran Symbolic Translator J - Describes the program for automatically translating 1410/7010 Autocoder programs into Operating System - Mod 2 Assembler J programs. This publication describes the few translation considerations and provides instructions for using the translator. In addition, hand-tailoring instructions are explained where required.

System Maintenance J - Contains detailed functional descriptions of System Maintenance J and the procedures for creating, editing, and maintaining system files. Includes a description of the control cards used to direct the operation of this program.

Tape Sort J - Contains a detailed functional description of Tape Sort J and instructions for Sort Definition and the resulting sort/merge programs. Includes information on control cards, console messages, timing, and the exercise of user own-coding options.

Mass Storage Sort J - Describes the functions of Mass Storage Sort J, the structures of input and output files, and the macro instructions and parameters for initially specializing the routine. Includes information on control cards for modifying Mass Storage Sort J at execution time, console messages, timing, and own-coding.

Utility Programs - Contains detailed functional descriptions of Input/Output Editor J, Storage Print J, and Tape Print J. Includes information about the requisite control cards and the console messages which are produced.

COMPUTER-GENERATED INDEX

ACCESS
 FILE ACCESS, 2-2

APPROACH
 OPERATING SYSTEM APPROACH, 1-1

ASSEMBLER J, 3-3

BATCHED-JOB
 TURNAROUND TIMES FOR BATCHED-JOB AND STACKED-JOB
 PROCESSING, 1-3

BENEFITS
 " OF THE MOD 2 OPERATING SYSTEM, 1-3
 OVER-ALL BENEFITS, 1-5

COBOL COMPILER J, 3-4

COMMUNICATION AND REAL-TIME CONTROL, 2-1

COMPILER
 COBOL COMPILER J, 3-4
 FORTRAN COMPILER J, 3-4

COMPONENTS
 " OF THE MOD 2 OPERATING SYSTEM, 3-1
 PROCESSING COMPONENTS, 3-3
 SUPERVISORY COMPONENTS, 3-1
 UTILITY COMPONENTS, 3-8

CONTROL
 DATA CONTROL, 2-2
 FILE CONTROL, 2-3
 INTERRUPT CONTROL, 2-2
 JOB CONTROL, 2-1
 MULTIPROGRAMMING CONTROL, 2-1
 REAL-TIME CONTROL,
 COMMUNICATION AND REAL-TIME CONTROL, 2-1

CONTROLLER
 INPUT/OUTPUT-FILE CONTROLLER J, 3-2

DATA CONTROL, 2-2

DESIGN
 OPERATING SYSTEM DESIGN, 1-1

EASYTRAN J TRANSITION PROGRAM, 3-5

EDITOR
 INPUT/OUTPUT EDITOR J, 3-6

EQUIPMENT REQUIREMENTS
 MINIMUM EQUIPMENT REQUIREMENTS, 4-1

EXPANSION
 EASE OF MAINTENANCE AND EXPANSION, 1-5

FILE
 " ACCESS, 2-2
 " CONTROL, 2-3
 GO FILE (MGO), 2-4
 JOB FILE (MJB), 2-4
 MASTER HISTORY FILE (MHF), 2-4
 SYSTEM FILES,
 SUMMARY OF SYSTEM FILES, 2-4
 SYSTEM OPERATING FILE (SOF), 2-4

FORTRAN COMPILER J, 3-4

FUNCTIONS
 " OF THE MOD 2 OPERATING SYSTEM, 2-1
 OTHER FUNCTIONS, 2-4

GO FILE (MGO), 2-4

HISTORY FILE
 MASTER HISTORY FILE (MHF), 2-4

INPUT UNIT
 STANDARD INPUT UNIT (SIU), 2-4

INPUT/OUTPUT EDITOR J, 3-6

INPUT/OUTPUT-FILE CONTROLLER J, 3-2

INTERRUPT CONTROL, 2-2

INTRODUCTION, 1-1

JOB
 " CONTROL, 2-1
 " FILE (MJB), 2-4

LANGUAGE PROCESSORS, 3-3

LINKAGE LOADER J, 3-6

LOADER
 LINKAGE LOADER J, 3-6

MAINTENANCE
 EASE OF MAINTENANCE AND EXPANSION, 1-5
 PROGRAM PREPARATION AND MAINTENANCE, 2-3
 SYSTEM MAINTENANCE J, 3-6

MASS STORAGE SORT J, 3-7

MASTER HISTORY FILE (MHF), 2-4

MGO
 GO FILE (MGO), 2-4

MHF
 MASTER HISTORY FILE (MHF), 2-4

MINIMUM EQUIPMENT REQUIREMENTS, 4-1

MJB
 JOB FILE (MJB), 2-4

MOD
 BENEFITS OF THE MOD 2 OPERATING SYSTEM, 1-3
 COMPONENTS OF THE MOD 2 OPERATING SYSTEM, 3-1
 FUNCTIONS OF THE MOD 2 OPERATING SYSTEM, 2-1
 (CONT.)

MOD (CONT.)
 OPERATING SYSTEM - MOD 2 PUBLICATIONS, A-1
 " 2 OPERATING SYSTEM PUBLICATIONS PLAN, A-2

MODULARITY
 PROGRAM MODULARITY,
 STACKED-JOB PROCESSING AND PROGRAM MODULARITY,
 1-2

MONITOR
 RESIDENT MONITOR J, 3-1
 TRANSITIONAL MONITOR J, 3-2

MULTIPROGRAMMING CONTROL, 2-1

OPERATING
 EASE OF OPERATING, 1-4
 " FILE,
 SYSTEM OPERATING FILE (SOF), 2-4
 " SYSTEM,
 BENEFITS OF THE MOD 2 OPERATING SYSTEM, 1-3
 COMPONENTS OF THE MOD 2 OPERATING SYSTEM, 3-1
 FUNCTIONS OF THE MOD 2 OPERATING SYSTEM, 2-1
 OPERATING SYSTEM - MOD 2 PUBLICATIONS, A-1
 " SYSTEM APPROACH, 1-1
 " SYSTEM DESIGN, 1-1
 " SYSTEM PUBLICATIONS PLAN,
 MOD 2 OPERATING SYSTEM PUBLICATIONS PLAN, A-2

PLAN
 OPERATING SYSTEM PUBLICATIONS PLAN,
 MOD 2 OPERATING SYSTEM PUBLICATIONS PLAN, A-2

PREPARATION
 PROGRAM PREPARATION AND MAINTENANCE, 2-3

PRINT
 STORAGE PRINT J, 3-8
 TAPE PRINT J, 3-8
 " UNIT,
 STANDARD PRINT UNIT (SPR), 2-4

PROCESSING
 " COMPONENTS, 3-3
 STACKED-JOB PROCESSING,
 TURNAROUND TIMES FOR BATCHED-JOB AND STACKED-JOB
 PROCESSING, 1-3
 STACKED-JOB PROCESSING AND PROGRAM MODULARITY, 1-2

PROCESSORS
 LANGUAGE PROCESSORS, 3-3

PROGRAM
 " MODULARITY,
 STACKED-JOB PROCESSING AND PROGRAM MODULARITY,
 1-2
 " PREPARATION AND MAINTENANCE, 2-3
 TRANSITION PROGRAM,
 EASYTRAN J TRANSITION PROGRAM, 3-5

PROGRAMMING
 EASE OF PROGRAMMING, 1-3

PUBLICATIONS
 OPERATING SYSTEM - MOD 2 PUBLICATIONS, A-1
 " PLAN,
 MOD 2 OPERATING SYSTEM PUBLICATIONS PLAN, A-2

PUNCH UNIT
 STANDARD PUNCH UNIT (SPU), 2-4

REAL-TIME CONTROL
 COMMUNICATION AND REAL-TIME CONTROL, 2-1

REQUIREMENTS
 MINIMUM EQUIPMENT REQUIREMENTS, 4-1

RESIDENT MONITOR J, 3-1

SIU
 STANDARD INPUT UNIT (SIU), 2-4

SOF
 SYSTEM OPERATING FILE (SOF), 2-4

SORT
 MASS STORAGE SORT J, 3-7
 TAPE SORT J, 3-7

SPR
 STANDARD PRINT UNIT (SPR), 2-4

SPU
 STANDARD PUNCH UNIT (SPU), 2-4

STACKED-JOB PROCESSING
 " AND PROGRAM MODULARITY, 1-2
 TURNAROUND TIMES FOR BATCHED-JOB AND STACKED-JOB
 PROCESSING, 1-3

STANDARD
 " INPUT UNIT (SIU), 2-4
 " PRINT UNIT (SPR), 2-4
 " PUNCH UNIT (SPU), 2-4

STORAGE
 " PRINT J, 3-8
 " SORT,
 MASS STORAGE SORT J, 3-7

SUMMARY OF SYSTEM FILES, 2-4

SUPERVISORY COMPONENTS, 3-1

SYSTEM (CONT.)

COMPUTER-GENERATED INDEX

SYSTEM

- " APPROACH,
OPERATING SYSTEM APPROACH, 1-1
- " DESIGN,
OPERATING SYSTEM DESIGN, 1-1
- " FILES,
SUMMARY OF SYSTEM FILES, 2-4
- " MAINTENANCE J, 3-6
- " OPERATING FILE (SOF), 2-4
- OPERATING SYSTEM,
BENEFITS OF THE MOD 2 OPERATING SYSTEM, 1-3
COMPONENTS OF THE MOD 2 OPERATING SYSTEM, 3-1
FUNCTIONS OF THE MOD 2 OPERATING SYSTEM, 2-1
OPERATING SYSTEM - MOD 2 PUBLICATIONS, A-1
- " PUBLICATIONS PLAN,
MOD 2 OPERATING SYSTEM PUBLICATIONS PLAN, A-2

TAPE

- " PRINT J, 3-8
- " SORT J, 3-7

TIMES

- TURNAROUND TIMES FOR BATCHED-JOB AND STACKED-JOB
PROCESSING, 1-3

TRANSITION PROGRAM

- EASYTRAN J TRANSITION PROGRAM, 3-5
- TRANSITIONAL MONITOR J, 3-2
- TURNAROUND TIMES FOR BATCHED-JOB AND STACKED-JOB
PROCESSING, 1-3

UNIT

- STANDARD INPUT UNIT (SIU), 2-4
- STANDARD PRINT UNIT (SPR), 2-4
- STANDARD PUNCH UNIT (SPU), 2-4
- UTILITY COMPONENTS, 3-8

HONEYWELL EDP TECHNICAL PUBLICATIONS
USERS' REMARKS FORM

TITLE: SERIES 200
INTRODUCTION TO SERIES
200/OPERATING SYSTEM - MOD 2
SOFTWARE BULLETIN

DATED: MAY, 1966
FILE NO: 122.0005.002J.0-393

ERRORS NOTED:

Fold

SUGGESTIONS FOR IMPROVEMENT:

Fold

FROM: NAME _____
COMPANY _____
TITLE _____
ADDRESS _____

DATE _____

Cut Along Line

BUSINESS REPLY MAIL

No postage stamp necessary if mailed in the United States

POSTAGE WILL BE PAID BY

HONEYWELL

ELECTRONIC DATA PROCESSING DIVISION

60 WALNUT STREET

WELLESLEY HILLS, MASS. 02181

ATT'N: TECHNICAL COMMUNICATIONS DEPARTMENT

FIRST CLASS
PERMIT NO. 39531
WELLESLEY HILLS
MASS.

Cut Along Line

Honeywell
ELECTRONIC DATA PROCESSING